Determinants Geometric Properties of Determinant Additional Properties of Determinant Algorithm Formulas

# Lecture 15: Determinants MAT2040 Linear Algebra

Before studying Ax through the lens of mappings (transformations) — in other words studying  $x \mapsto Ax$  — we will first study a quantity that is known as *the determinant* of A, denoted by det A or

$$\begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix}$$

The determinant is only defined for square matrices! For the next two or three lectures all the matrices will be square  $n \times n$  matrices.

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

Determinant of A: one number to summarize A

Determinant of A: one number to summarize A

Motivation is the volume of the geometric object the edges of which come from the rows of A (parallelepiped).

(Note that "volume" is length in 1 dimension, "area" in 2 dimensions, and some people prefer "hypervolume" for dimensions 4 and larger.)

Note that the volume of a geometric object is zero if the object is "flat" in the space it lives in.

(A line piece has a nonzero length in 1 dimensions, but an area of 0; a 2-dimensional geometric object has a nonzero area in 2 dimensions, but a volume of 0 in 3 dimensions, etc.)

Note that the volume of a geometric object is zero if the object is "flat" in the space it lives in.

(A line piece has a nonzero length in 1 dimensions, but an area of 0; a 2-dimensional geometric object has a nonzero area in 2 dimensions, but a volume of 0 in 3 dimensions, etc.)

So if the geometric object has a dimension less than n, the determinant will be zero.

Note that the volume of a geometric object is zero if the object is "flat" in the space it lives in.

(A line piece has a nonzero length in 1 dimensions, but an area of 0; a 2-dimensional geometric object has a nonzero area in 2 dimensions, but a volume of 0 in 3 dimensions, etc.)

So if the geometric object has a dimension less than n, the determinant will be zero.

In matrix lingo we can say that in this case the row space of A has dimension less than n.

Note that the volume of a geometric object is zero if the object is "flat" in the space it lives in.

(A line piece has a nonzero length in 1 dimensions, but an area of 0; a 2-dimensional geometric object has a nonzero area in 2 dimensions, but a volume of 0 in 3 dimensions, etc.)

So if the geometric object has a dimension less than n, the determinant will be zero.

In matrix lingo we can say that in this case the row space of A has dimension less than n.

For a square matrix this is equivalent to saying that *A* is not invertible!

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

▶ Determinant of a matrix is 0 if and only if A is not invertible.

- Determinant of a matrix is 0 if and only if A is not invertible.
- ▶ It can actually be used to find the solution to  $A\mathbf{x} = \mathbf{b}$  and to find  $A^{-1}$ . (But we already have methods that are computationally more efficient!)

- Determinant of a matrix is 0 if and only if A is not invertible.
- ▶ It can actually be used to find the solution to  $A\mathbf{x} = \mathbf{b}$  and to find  $A^{-1}$ . (But we already have methods that are computationally more efficient!)
- lt shows the sensitivity of solutions to  $A\mathbf{x} = \mathbf{b}$  to changes in  $\mathbf{b}$  (i.e., how much does  $\mathbf{x}$  change if  $\mathbf{b}$  changes to  $\mathbf{b}'$ ).

- ▶ Determinant of a matrix is 0 if and only if A is not invertible.
- ▶ It can actually be used to find the solution to  $A\mathbf{x} = \mathbf{b}$  and to find  $A^{-1}$ . (But we already have methods that are computationally more efficient!)
- ▶ It shows the sensitivity of solutions to  $A\mathbf{x} = \mathbf{b}$  to changes in  $\mathbf{b}$  (i.e., how much does  $\mathbf{x}$  change if  $\mathbf{b}$  changes to  $\mathbf{b}'$ ).

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

We will now work towards a way to calculate the determinant of a matrix.

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

We will now work towards a way to calculate the determinant of a matrix. We will also derive two formulas for the determinant of a matrix in terms of its entries.

We will now work towards a way to calculate the determinant of a matrix. We will also derive two formulas for the determinant of a matrix in terms of its entries.

(The algorithm to calculate the determinant with be more efficient than directly calculating the determinant from the formulas.)

We will now work towards a way to calculate the determinant of a matrix. We will also derive two formulas for the determinant of a matrix in terms of its entries.

(The algorithm to calculate the determinant with be more efficient than directly calculating the determinant from the formulas.)

Our starting point for defining the determinant will be the *geometric properties* of the determinant.

1.  $\det I = 1$ .

- 1.  $\det I = 1$ .
- 2.  $\det A = 0$  if A has two rows that are the same.

- 1.  $\det I = 1$ .
- 2.  $\det A = 0$  if A has two rows that are the same.
- If we change one row of A

   (a) by multiplying the row by some constant t call the new matrix B, we have

- 1.  $\det I = 1$ .
- 2.  $\det A = 0$  if A has two rows that are the same.
- 3. If we change **one row of** A
  - (a) by multiplying the row by some constant t call the new matrix B, we have

$$\det B = t \det A$$
.

- 1.  $\det I = 1$ .
- 2.  $\det A = 0$  if A has two rows that are the same.
- 3. If we change **one row of** A
  - (a) by multiplying the row by some constant t call the new matrix B, we have

$$\det B = t \det A$$
.

(b) by changing row  $\vec{a}_i$  to  $\vec{b}_i$  — call the new matrix B, we have

- 1.  $\det I = 1$ .
- 2.  $\det A = 0$  if A has two rows that are the same.
- 3. If we change **one row of** A
  - (a) by multiplying the row by some constant t call the new matrix B, we have

$$\det B = t \det A$$
.

(b) by changing row  $\vec{a}_i$  to  $\vec{b}_i$  — call the new matrix B, we have

$$\det B = \det A + \det A'$$

where A' is the matrix A where row i is replaced by  $\vec{\mathbf{b}}_i - \vec{\mathbf{a}}_i$ .



Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

Note that in property 3, we change **exactly one** row of A!

Note that in property 3, we change exactly one row of A!

It turns out that the determinant is fully defined (determined) by the three previous properties. Note that in property 3, we change **exactly one** row of A!

It turns out that the determinant is fully defined (determined) by the three previous properties.

Let's see what other properties we can find so that we can find a formula or way of computing the determinant of a matrix.

If A has a row of all zeros, then  $\det A = 0$ .

If A has a row of all zeros, then  $\det A = 0$ .

### Property 5

The determinant of a diagonal matrix is equal to the product of its diagonal entries.

If A has a row of all zeros, then  $\det A = 0$ .

#### Property 5

The determinant of a diagonal matrix is equal to the product of its diagonal entries.

#### Property 6

Subtracting t times row i from row j does not change the determinant.

If A has a row of all zeros, then  $\det A = 0$ .

### Property 5

The determinant of a diagonal matrix is equal to the product of its diagonal entries.

#### Property 6

Subtracting t times row i from row j does not change the determinant.

#### Property 7

If A is triangular, then  $\det A = \text{product of diagonal entries}$ .

So we almost have a method to calculate det A!

If we can transform A into triangular form using only the elementary row operation that subtracts multiples of one row from another, the determinant does not change (property 6).

The determinant of a triangular matrix is the product of the diagonal entries (property 7).

So we almost have a method to calculate det A!

If we can transform A into triangular form using only the elementary row operation that subtracts multiples of one row from another, the determinant does not change (property 6).

The determinant of a triangular matrix is the product of the diagonal entries (property 7).

Let's do an example before we try to find out what happens to the determinant when rows are exchanged.

#### Example 15.2

Find  $\begin{vmatrix} a & b \\ c & d \end{vmatrix}$  where  $a \neq 0$ , and check geometrically that this equals the area of the parallelogram with sides  $(0,0) \rightarrow (a,b)$  and  $(0,0) \rightarrow (c,d)$ .

Determinants Geometric Properties of Determinant Additional Properties of Determinant Algorithm Formulas

#### Property 8

If B is the matrix A with rows i and j exchanged then

 $\det B =$ 

If B is the matrix A with rows i and j exchanged then

$$\det B = - \det A$$
.

We can conclude that the following is an algorithm to compute  $\det A$ :

- 1. Use elementary row operations except the scaling operation, to transform *A* into row echelon form. Keep track of the number of row interchanges, say *r*.
- 2.  $\det A = (-1)^r$  product of the diagonal entries of row echelon form.

$$\begin{array}{c|cccc} \mathsf{Example} \ 15.3 \\ \mathsf{Find} & 5 & 9 & 17 \\ 1 & 2 & 0 \\ -5 & -11 & 3 \\ \end{array} .$$

Note that our intuition of getting a volume was not quite correct: we got a volume that could also be negative.

The absolute value of the determinant of A, however, exactly equals the volume of the parallelepiped defined by the rows of A.

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

You may be (should be) wondering whether the determinant is well defined: is the number of row interchanges to get the rows in a certain order always odd or always even (no matter which ones and which order you choose)?

Suppose you have a matrix, and you want to move row 1 to row  $\pi(1)$ , row 2 to row  $\pi(2)$ , etc., row n to row  $\pi(n)$ , using row interchanges, where  $\pi$  is a *permutation*.

#### Fact 15.4

The number of row interchanges you have to do has the same parity as the number of pairs that are out of order in  $\pi$ .

### Corollary 15.5

Let P be a permutation matrix.

 $\det P = (-1)^{\# \ of \ pairs \ of \ rows \ that \ are \ out \ of \ order \ compared \ to \ l}$  .

Example 15.6

What is 
$$\begin{vmatrix}
0 & 1 & 0 & 0 \\
1 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{vmatrix}$$
?

How many pairs of rows are out of order?

What is 
$$\begin{vmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{vmatrix}$$
?

How many pairs of rows are out of order?

#### Definition 15.7

The **sign of a permutation**  $\pi$  of size n is the determinant of the  $n \times n$  permutation matrix that corresponds to  $\pi$ :

$$\mathsf{sign}(\pi) = \left| egin{array}{c} e^{T}_{\pi(1)} \ e^{T}_{\pi(2)} \ e^{T}_{\pi(3)} \ dots \ e^{T}_{\pi(n)} \end{array} 
ight|.$$

# Property 9

If A has a column of all zeros then

$$\det A = 0$$
.

We will now focus on getting a formula for  $\det A$  (as well as derive some more properties).

Let's split up every row into rows that just contain one nonzero entry.

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$

by property 3(a)

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$
 by property 3(a)
$$= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix}$$
 by property 3(a)

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$
 by property 3(a) 
$$= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix}$$
 by property 3(a) 
$$= 0 + ad + (-1) \begin{vmatrix} c & 0 \\ 0 & b \end{vmatrix} + 0$$
 by properties 9, 7, 8 and 9, respectively

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$
 by property 3(a)
$$= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix}$$
 by property 3(a)
$$= 0 + ad + (-1) \begin{vmatrix} c & 0 \\ 0 & b \end{vmatrix} + 0$$
 by properties 9, 8 and 9, respect by property 7.

by property 3(a)

by properties 9, 7, 8 and 9, respectively by property 7.

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

Determinants
Geometric Properties of Determinant
Additional Properties of Determinant
Algorithm
Formulas

We can do the same for  $n \times n$  matrices — we get matrices, but most of the matrices we get have determinant 0 (because they have an all zero column).

We can do the same for  $n \times n$  matrices — we get  $\lfloor n^n \rfloor$  matrices, but most of the matrices we get have determinant 0 (because they have an all zero column).

We can do the same for  $n \times n$  matrices — we get  $\lfloor n^n \rfloor$  matrices, but most of the matrices we get have determinant 0 (because they have an all zero column).

How many matrices will there be that do not have an all zero column?

# Formula (Leibniz formula)

$$\det A = \sum_{\substack{\pi \text{ is a permutation of } 1, 2, \dots, n}} sign(\pi) a_{1\pi(1)} a_{2\pi(2)} \cdots a_{n\pi(n)}.$$

## Formula (Leibniz formula)

$$\det A = \sum_{\substack{\pi \text{ is a permutation of } 1, 2, \dots, n}} sign(\pi) a_{1\pi(1)} a_{2\pi(2)} \cdots a_{n\pi(n)}.$$

Argh! So many terms!

### Formula (Leibniz formula)

$$\det A = \sum_{\substack{\pi \text{ is a permutation of } 1, 2, \dots, n}} sign(\pi) a_{1\pi(1)} a_{2\pi(2)} \cdots a_{n\pi(n)}.$$

Argh! So many terms!

What if we group terms — for instance starting with all terms involving  $a_{11}$ ?

There is a term that includes  $a_{11}$  for every permutation where  $\pi(1) = 1$ .

There is a term that includes  $a_{11}$  for every permutation where  $\pi(1) = 1$ .

The sum of all terms that include  $a_{11}$  in Leibniz Formula can be written as

$$a_{11}$$
 
$$\sum_{\pi \text{ is a permutation of } 1,2,\ldots,n \text{ where } \pi(1)=1} \operatorname{sign}(\pi) a_{2\pi(2)} \cdots a_{n\pi(n)}$$

There is a term that includes  $a_{11}$  for every permutation where  $\pi(1) = 1$ .

The sum of all terms that include  $a_{11}$  in Leibniz Formula can be written as

$$a_{11}$$
 
$$\sum_{\pi \text{ is a permutation of } 1,2,\ldots,n \text{ where } \pi(1)=1$$
 
$$= a_{11} \det M_{11}$$
 sign $(\pi)a_{2\pi(2)}\cdots a_{n\pi(n)}$ 

where  $M_{11}$  is the matrix A with row 1 and column 1 deleted.