19) Convolutional Neural Networks: Padding, Strides, Max-Pooling

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Reference

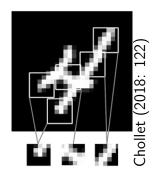
Chollet (2018): Ch 5.1

https://www.manning.com/books/deep-learningwith-python

https://github.com/fchollet/deep-learning-withpython-notebooks/blob/master/5.1-introductionto-convnets.ipynb

Densely Connected vs Convolution Layer

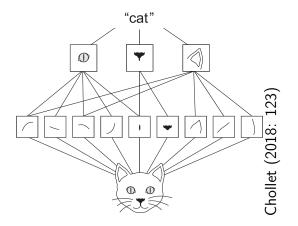
Global vs Local Patterns



3D tensors (feature maps) = (28, 28, 1)Spatial Axes (Height and Width) = 28x28 pixels Depth Axis (Channels) =1 (levels of gray)

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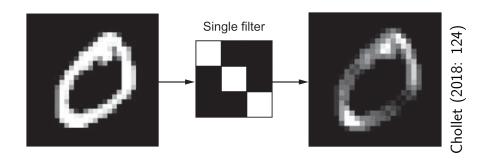
Spatial Hierarchies of Patterns



Depth is a parameter of the layer, and no longer stand for specific colors

Filters encode concepts: eyes, face

Feature Map of Size (28, 28, 1)

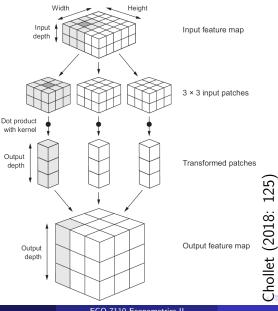


Size of the patches: 3×3

Depth of the output feature map: 32

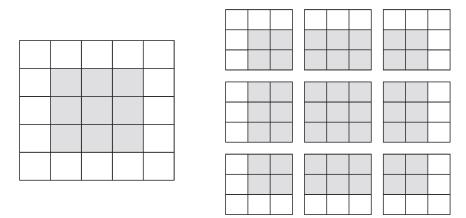
Outputs a Feature Map of Size (26, 26, 32)

How Convolution Works?



3×3 Patches in a 5×5 Input Feature Map

Border Effect: $5x5 \rightarrow 3x3$



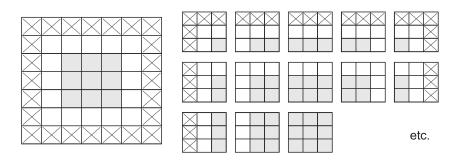
Chollet (2018: 126)

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Padding a 5×5 input to extract 25 3×3 patches

In Conv2D layers:

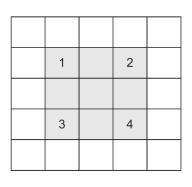
padding = "valid": means no padding



Chollet (2018: 126)

3×3 Convolution Patches with 2×2 Strides

Stride: Distance between two Successive Windows



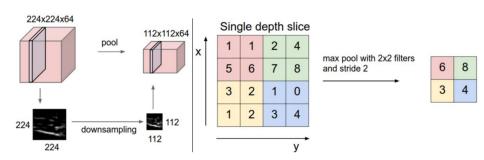
	1		

3	

	4	

Chollet (2018: 126)

Max-pooling Operation



Source: Stanford's CS231n github

from keras import layers from keras import models

model.summary()

```
Laver (type)
                             Output Shape
                                                        Param #
conv2d 1 (Conv2D)
                             (None, 26, 26, 32)
                                                        320
max pooling2d 1 (MaxPooling2 (None, 13, 13, 32)
                                                        0
conv2d 2 (Conv2D)
                             (None, 11, 11, 64)
                                                        18496
max pooling2d 2 (MaxPooling2 (None, 5, 5, 64)
                                                        0
conv2d 3 (Conv2D)
                                                        36928
                              (None, 3, 3, 64)
```

(output_channels)*(input_channels*window_size + 1)

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 26, 26, 32)	320
max_pooling2d_1 (MaxPooling2	(None, 13, 13, 32)	0
conv2d_2 (Conv2D)	(None, 11, 11, 64)	18496
max_pooling2d_2 (MaxPooling2	(None, 5, 5, 64)	0
conv2d_3 (Conv2D)	(None, 3, 3, 64)	36928

Total params: 55,744 Trainable params: 55,744 Non-trainable params: 0

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MNIST Digits

```
model.add(layers.Flatten())
model.add(layers.Dense(64, activation='relu'))
model.add(layers.Dense(10, activation='softmax'))
from keras.datasets import mnist
from keras.utils import to categorical
(train images, train labels), (test images,
                 test labels) = mnist.load data()
train images = train images.reshape((60000, 28, 28, 1))
train images = train images.astype('float32') / 255
test images = test images.reshape((10000, 28, 28, 1))
test images = test images.astype('float32') / 255
train labels = to categorical(train labels)
test labels = to categorical(test labels)
```

```
model.compile(optimizer='rmsprop',
  loss='categorical_crossentropy', metrics=['accuracy'])
model.fit(train_images, train_labels, epochs=5, batch_size=64)
```

```
Epoch 1/5
60000/60000 [============ ] - 8s - loss: 0.1766 - acc: 0.9440
Epoch 2/5
60000/60000 [===========] - 7s - loss: 0.0462 - acc: 0.9855
Epoch 3/5
60000/60000 [============] - 7s - loss: 0.0322 - acc: 0.9902
Epoch 4/5
60000/60000 [============ ] - 7s - loss: 0.0241 - acc: 0.9926
Epoch 5/5
60000/60000 [===========] - 7s - loss: 0.0187 - acc: 0.9943
test loss, test acc = model.evaluate(test images, test labels)
test acc
```

0.99129999

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