# **Distributed Systems**

(3rd Edition)

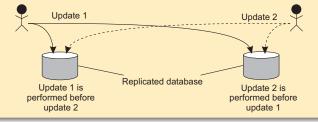
# Chapter 06: Coordination

Version: February 25, 2017

# **Example: Total-ordered multicast**

# Concurrent updates on a replicated database are seen in the same order everywhere

- P<sub>1</sub> adds \$100 to an account (initial value: \$1000)
- P<sub>2</sub> increments account by 1%
- There are two replicas



#### Result

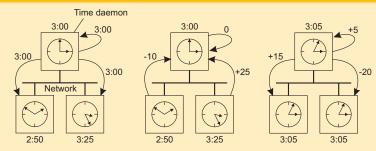
In absence of proper synchronization: replica #1  $\leftarrow$  \$1111, while replica #2  $\leftarrow$  \$1110.

# Keeping time without UTC

#### Principle

Let the time server scan all machines periodically, calculate an average, and inform each machine how it should adjust its time relative to its present time.

#### Using a time server



#### **Fundamental**

You'll have to take into account that setting the time back is never allowed ⇒ smooth adjustments (i.e., run faster or slower).

The Berkeley algorithm 6 / 49

# **Clock synchronization**

#### Precision

The goal is to keep the deviation between two clocks on any two machines within a specified bound, known as the precision  $\pi$ :

$$\forall t, \forall p, q: |C_p(t) - C_q(t)| \leq \pi$$

with  $C_p(t)$  the computed clock time of machine p at UTC time t.

#### Accuracy

In the case of accuracy, we aim to keep the clock bound to a value  $\alpha$ :

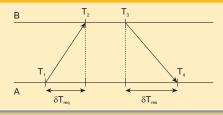
$$\forall t, \forall p : |C_p(t) - t| \leq \alpha$$

#### Synchronization

- Internal synchronization: keep clocks precise
- External synchronization: keep clocks accurate

# Detecting and adjusting incorrect times

#### Getting the current time from a time server



#### Computing the relative offset $\theta$ and delay $\delta$

Assumption:  $\delta T_{reg} = T_2 - T_1 \approx T_4 - T_3 = \delta T_{res}$ 

$$\theta = T_3 + ((T_2 - T_1) + (T_4 - T_3))/2 - T_4 = ((T_2 - T_1) + (T_3 - T_4))/2$$
$$\delta = ((T_4 - T_1) - (T_3 - T_2))/2$$

#### **Network Time Protocol**

Collect eight  $(\theta, \delta)$  pairs and choose  $\theta$  for which associated delay  $\delta$  was minimal.

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# Reference broadcast synchronization

#### Essence

- A node broadcasts a reference message m ⇒ each receiving node p records the time T<sub>p,m</sub> that it received m.
- Note:  $T_{p,m}$  is read from p's local clock.

# Problem: averaging will not capture drift ⇒ use linear regression

NO: Offset[p,q](t) = 
$$\frac{\sum_{k=1}^{M} (T_{p,k} - T_{q,k})}{M}$$
  
YES: Offset[p,q](t) =  $\alpha t + \beta$ 

# Message preparation Time spent in NIC A Delivery time to app. B

Usual critical path

Critical path RBS

RBS minimizes critical path

# The Happened-before relationship

#### Issue

What usually matters is not that all processes agree on exactly what time it is, but that they agree on the order in which events occur. Requires a notion of ordering.

#### The happened-before relation

- If a and b are two events in the same process, and a comes before b, then a → b.
- If a is the sending of a message, and b is the receipt of that message, then a → b
- If  $a \rightarrow b$  and  $b \rightarrow c$ , then  $a \rightarrow c$

#### Note

This introduces a partial ordering of events in a system with concurrently operating processes.

# Logical clocks

#### **Problem**

How do we maintain a global view on the system's behavior that is consistent with the happened-before relation?

#### Attach a timestamp C(e) to each event e, satisfying the following properties:

- P1 If a and b are two events in the same process, and  $a \rightarrow b$ , then we demand that C(a) < C(b).
- P2 If a corresponds to sending a message m, and b to the receipt of that message, then also C(a) < C(b).

#### Problem

How to attach a timestamp to an event when there's no global clock  $\Rightarrow$  maintain a consistent set of logical clocks, one per process.

# Logical clocks: solution

#### Each process $P_i$ maintains a local counter $C_i$ and adjusts this counter

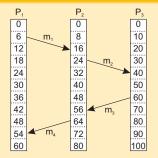
- For each new event that takes place within  $P_i$ ,  $C_i$  is incremented by 1.
- 2 Each time a message m is sent by process  $P_i$ , the message receives a timestamp  $ts(m) = C_i$ .
- 3 Whenever a message m is received by a process  $P_j$ ,  $P_j$  adjusts its local counter  $C_j$  to  $\max\{C_j, ts(m)\}$ ; then executes step 1 before passing m to the application.

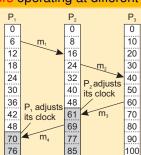
#### **Notes**

- Property P1 is satisfied by (1); Property P2 by (2) and (3).
- It can still occur that two events happen at the same time. Avoid this by breaking ties through process IDs.

# Logical clocks: example

#### Consider three processes with event counters operating at different rates





# Logical clocks: where implemented

# Adjustments implemented in middleware Application layer Application sends message Adjust local clock and timestamp message Middleware layer Middleware sends message Network layer

# **Example: Total-ordered multicast**

#### Solution

- Process  $P_i$  sends timestamped message  $m_i$  to all others. The message itself is put in a local queue  $queue_i$ .
- Any incoming message at P<sub>j</sub> is queued in queue<sub>j</sub>, according to its timestamp, and acknowledged to every other process.

#### $P_i$ passes a message $m_i$ to its application if:

- m<sub>i</sub> is at the head of queue<sub>i</sub>
- (2) for each process  $P_k$ , there is a message  $m_k$  in  $queue_j$  with a larger timestamp.

#### Note

We are assuming that communication is reliable and FIFO ordered.

### Mutual exclusion

#### Problem

A number of processes in a distributed system want exclusive access to some resource.

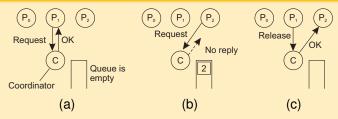
#### **Basic solutions**

Permission-based: A process wanting to enter its critical section, or access a resource, needs permission from other processes.

Token-based: A token is passed between processes. The one who has the token may proceed in its critical section, or pass it on when not interested.

### Permission-based, centralized

#### Simply use a coordinator



- (a) Process  $P_1$  asks the coordinator for permission to access a shared resource. Permission is granted.
- (b) Process  $P_2$  then asks permission to access the same resource. The coordinator does not reply.
- (c) When  $P_1$  releases the resource, it tells the coordinator, which then replies to  $P_2$ .

# Lamport's clocks for mutual exclusion

#### Analogy with total-ordered multicast

- With total-ordered multicast, all processes build identical queues, delivering messages in the same order
- Mutual exclusion is about agreeing in which order processes are allowed to enter a critical section

# Mutual exclusion Ricart & Agrawala

#### The same as Lamport except that acknowledgments are not sent

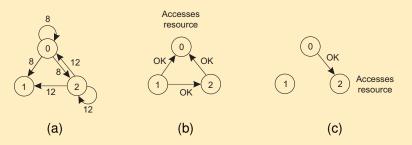
Return a response to a request only when:

- The receiving process has no interest in the shared resource; or
- The receiving process is waiting for the resource, but has lower priority (known through comparison of timestamps).

In all other cases, reply is deferred, implying some more local administration.

# Mutual exclusion Ricart & Agrawala

#### Example with three processes



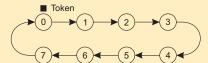
- (a) Two processes want to access a shared resource at the same moment.
- (b)  $P_0$  has the lowest timestamp, so it wins.
- (c) When process  $P_0$  is done, it sends an OK also, so  $P_2$  can now go ahead.

# Mutual exclusion: Token ring algorithm

#### Essence

Organize processes in a logical ring, and let a token be passed between them. The one that holds the token is allowed to enter the critical region (if it wants to).

#### An overlay network constructed as a logical ring with a circulating token



# **Election algorithms**

#### **Principle**

An algorithm requires that some process acts as a coordinator. The question is how to select this special process dynamically.

#### Note

In many systems the coordinator is chosen by hand (e.g. file servers). This leads to centralized solutions  $\Rightarrow$  single point of failure.

#### **Teasers**

- If a coordinator is chosen dynamically, to what extent can we speak about a centralized or distributed solution?
- 2 Is a fully distributed solution, i.e. one without a coordinator, always more robust than any centralized/coordinated solution?

# **Basic assumptions**

- All processes have unique id's
- All processes know id's of all processes in the system (but not if they are up or down)
- Election means identifying the process with the highest id that is up

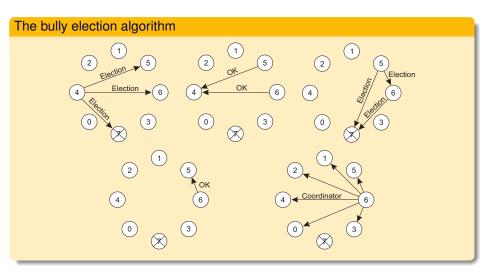
# Election by bullying

#### **Principle**

Consider *N* processes  $\{P_0, \dots, P_{N-1}\}$  and let  $id(P_k) = k$ . When a process  $P_k$  notices that the coordinator is no longer responding to requests, it initiates an election:

- $P_k$  sends an *ELECTION* message to all processes with higher identifiers:  $P_{k+1}, P_{k+2}, \dots, P_{N-1}$ .
- 2 If no one responds,  $P_k$  wins the election and becomes coordinator.
- 3 If one of the higher-ups answers, it takes over and  $P_k$ 's job is done.

# Election by bullying



# Election in a ring

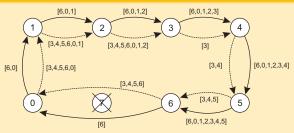
#### **Principle**

Process priority is obtained by organizing processes into a (logical) ring. Process with the highest priority should be elected as coordinator.

- Any process can start an election by sending an election message to its successor. If a successor is down, the message is passed on to the next successor.
- If a message is passed on, the sender adds itself to the list. When it gets back to the initiator, everyone had a chance to make its presence known.
- The initiator sends a coordinator message around the ring containing a list of all living processes. The one with the highest priority is elected as coordinator.

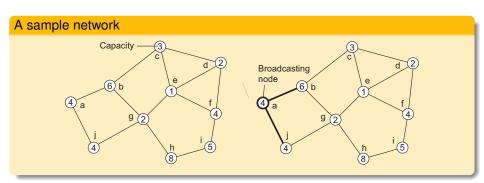
# Election in a ring

#### Election algorithm using a ring



- The solid line shows the election messages initiated by P<sub>6</sub>
- The dashed one the messages by  $P_3$

#### A solution for wireless networks



#### A solution for wireless networks

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#### A solution for wireless networks

# A sample network A sample network The product of the product of