

# VIVASWAT SURESH

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## EDUCATION & COURSEWORK

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### UC San Diego – Computer Science, Mathematics

GPA 3.6

Related Coursework: ML for Physical Applications, Computer Architecture, Advanced Data Structures and Algorithms

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## EXPERIENCE

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### FishSense UCSD, San Diego, CA

Jan. 2021- present

#### Software Engineer

- Developed a Python software pipeline for novel laser-assisted underwater fish measurement.
- Modeled parallax between laser and camera to automatically detect laser in image RAWs.
- Developed a DSP program to synchronize two GoPro videos based on an impulse noise using matrix profiles to create a stereo camera.
- Leveraged the Eigenface algorithm to implement a non-machine learning approach to fish species identification.
- Gathered data and trained a YOLOv4 Object Detection network using Tensorflow2.0 for the sake of autonomous fish tracking.
- Created and developed a depth-based segmentation algorithm to segment fish within a bounding box using data from an Intel RealSense D455 stereo camera.

### Applied Materials, Santa Clara, CA

June 2022 – Dec. 2022

#### Machine Learning Intern

- Leveraged unsupervised learning techniques including time series analysis and matrix profiles, on semiconductor wafer data in order to detect discords and motifs within expansive datasets.
- Implemented a fast similarity search algorithm to quickly comb through decades of data to find similar subsequences to trace anomalies through time.

### Argovis Project, La Jolla, CA

Feb. 2021 – Feb. 2022

#### Software Developer

- Worked on the development of Argovis, [argovis.colorado.edu](http://argovis.colorado.edu), a web app to visualize and download ocean data received from robotic floats located throughout the oceans.
- Created UI changes in Typescript using Angular for oceanographers to better model data on argovis servers.
- Leveraged PyMongo to upgrade outdated algorithm for storing data in MongoDB documents for ease of developer understanding and future development.

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## Projects

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### Semantic Segmentation for Autonomous Vehicles, Python, Tensorflow 2.0, Keras

- Implemented multiple Machine Learning segmentation models using the Cityscapes dataset, namely U-net, U-net++, SegNet, and FCN to compare accuracies of different SOTA segmentation models.

### Autoencoder for Anomaly Detection, Python, Tensorflow 2.0, Keras

- Trained multiple different autoencoders for the purpose of anomaly detection in Antarctic seismic data. Trained a 3d convolutional autoencoder that detected all 143 anomalies present in data.

### Temperature Prediction with Random Forest Regression, Python, Tensorflow 2.0, Keras

- Implemented a machine learning random forest regression model on NOAA data to predict temperature and precipitation at different weather stations across the world and compared these results with a polynomial regression model.

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## Publications

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- P. Tueller *et al.*, "FishSense: Underwater RGBD Imaging for Fish Measurement," *OCEANS 2021: San Diego – Porto, San Diego, CA, USA, 2021*, pp. 1-5, doi: 10.23919/OCEANS44145.2021.9705929.
- MobiCom Conference publication, pending review

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## ADDITIONAL INFORMATION

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- Tools/Languages: Python, Java, C, C++, Typescript, Matlab, Bash, Git, Docker, MongoDB, Angular.
- In my spare time, I enjoy swimming, singing, camping, and climbing. Sometimes all at the same time!