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<b>Experiment</b>	9
<b>Aim</b>	To implement branch and bound algorithm (To implement Travelling salesman problem)
<b>Objective</b>	To solve the Traveling Salesman Problem using the Branch and Bound algorithm and display the optimal path and minimum cost.
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<b>Batch</b>	C

<b>Algorithm and Explanation of the technique used</b>	<pre> func tspBranchAndBound(graph[ ][ ], path[ ], visited[ ], minCost, cost, pos)     if pos == graph.size()         minCost = min(minCost, cost + graph[path[pos - 1]][path[0]])         return      for each vertex i in graph.size()         if not visited[i] and cost + graph[path[pos - 1]][i] &lt; minCost             visited[i] = true             path[pos] = i             tspBranchAndBound(graph, path, visited, minCost, cost + graph[path[pos - 1]][i], pos + 1)             visited[i] = false  func TravelingSalesman(graph[ ][ ], n)     initialize path[ ] with size n     initialize visited[ ] with size n     path[0] = 0     visited[0] = true     minCost = INF     tspBranchAndBound(graph, path, visited, minCost, 0, 1)      if minCost == INF         print "No feasible solution exists."     else         print "Minimum Cost:", minCost </pre>
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1	00	20	30	10	11	10
2	15	00	16	4	2	2
3	3	5	00	2	4	2
4	19	6	18	00	3	3
5	18	4	7	16	00	4

↓ row reduced

00	10	20	0	1		
13	00	14	2	0		
1	5	00	0	2		
16	3	15	00	0		
12	0	3	12	00		
1	0	3	0	0		

At 1 cost = 25

Consider 2 to 2

row 1 = col 2 = 00 < 2 to 1 = 00 → from M1

00	00	00	00	00	0
00	00	11	2	0	0
0	00	00	0	2	0
15	00	12	00	0	0
11	00	0	12	00	0
0	0	0	0	0	0

Rows & columns already reduced

Cost = 0

Total cost = previous reduction + current cost + C(1,2)

= 25 + 0 + 10

1 to 2 = 35

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Consider 1 to 3, Row 1 = col 3 = (2+0) = 00 in M1

00	00	00	00	00	0
12	00	00	2	0	0
00	3	00	0	2	0
15	3	00	00	0	0
11	0	00	12	00	0
11	0	0	0	0	0

Total = 25 + 11 + 19 = 55

1 to 3 = 53

Consider 2 to 4, Row 1 = col 4 = 4 to 1 = 00

00	00	00	00	00	0
12	00	11	00	0	0
0	3	00	00	2	0
00	3	12	00	0	0
11	0	0	0	0	0
0	0	0	0	0	0

Total = 25 + 0 + 0 = 25

1 to 4 = 25

1 to 5

00	00	00	00	00	0
12	00	11	2	00	0
0	3	00	0	00	0
15	3	12	00	00	0
00	0	0	12	00	0
0	0	0	0	0	0

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Total cost = 25 + (2+3)2 + 1 = 31

1 to 5 = 31

1 to 4 is minimum

Consider 1 to 4 col M2

Consider 1 to 4 to 2

4 row = 2 col = 2 to 1 = 00 in M2

00	00	00	00	00	0
00	00	11	00	0	0
0	00	00	00	2	0
00	00	00	00	00	0
11	00	0	00	0	0

Total = previous + current + C(4,2) in M2

= 25 + 0 + 3 = 28

1 to 4 to 2 = 28

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Consider 1 to 4 to 3

4 row = 3 col = 3 to 1 = 00 in M2

00	00	00	00	00	0
12	00	00	00	0	0
00	3	00	00	2	0
00	00	00	00	00	0
11	0	00	00	00	0
11	0	0	0	0	0

Total = 25 + 13 + 12 = 50

1 to 4 to 3 = 50

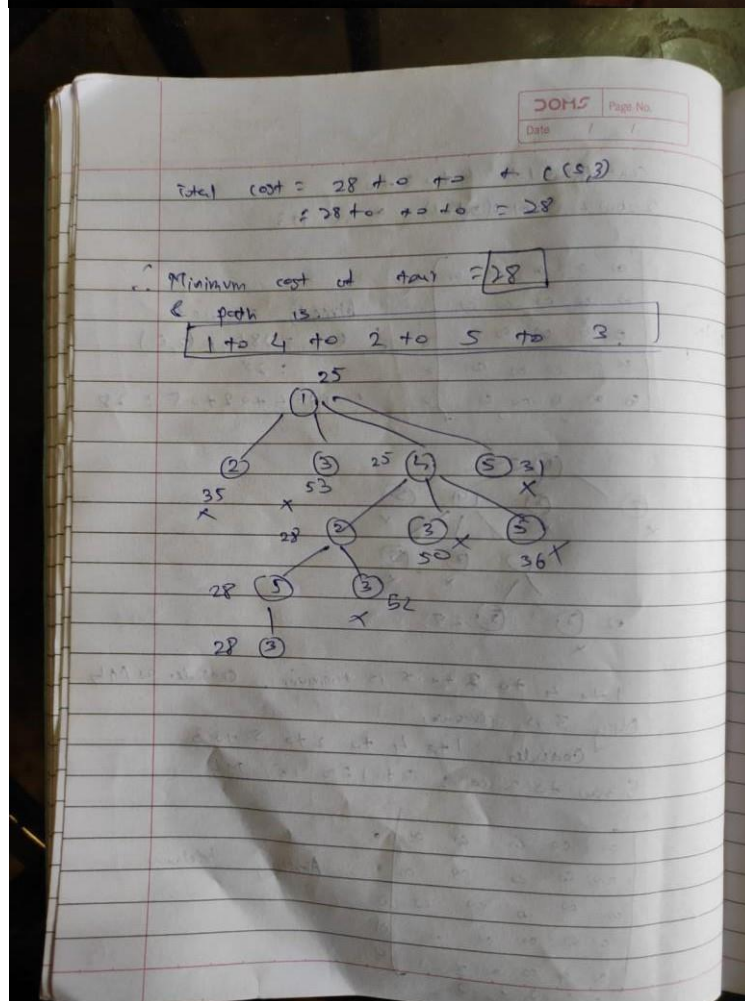
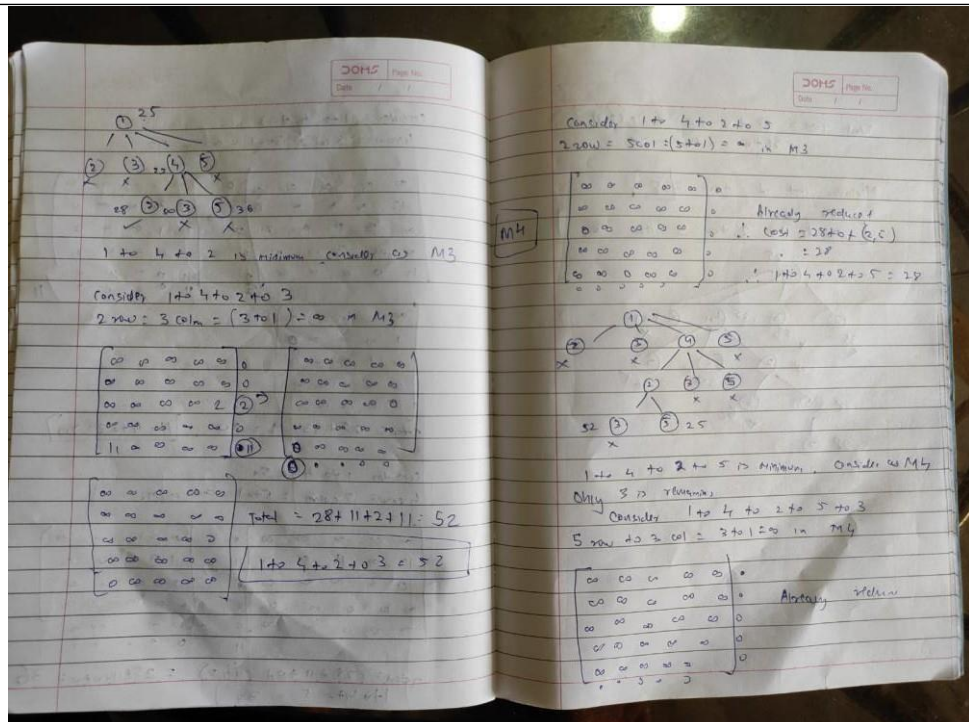
Consider 1 to 4 to 5

4 row = 5 col = 5 to 1 = 00 in M2

00	00	00	00	00	0
12	00	11	00	00	11
0	3	00	00	00	0
00	0	00	00	00	0
00	0	0	00	00	0
00	0	0	0	00	0

Total = 25 + 11 + 0 + C(4,5) = 25 + 11 + 0 = 36

1 to 4 to 5 = 36



Program(Co de)

```
#include <iostream>
#include <vector>
```

```

#include <algorithm>
#include <climits>
using namespace std;

const int INF = INT_MAX;

int calculateCost(const vector<vector<int>>& graph, const
vector<int>& path) {
    int cost = 0;
    for (int i = 0; i < path.size() - 1; ++i) {
        if (graph[path[i]][path[i + 1]] == INF)
            return INF;
        cost += graph[path[i]][path[i + 1]];
    }
    cost += graph[path.back()][path[0]];
    return cost;
}

void tspBranchAndBound(const vector<vector<int>>& graph,
vector<int>& path, vector<bool>& visited, vector<int>&
optimalPath, int& minCost, int cost, int pos) {
    if (pos == graph.size()) {
        int finalCost = cost + graph[path[pos - 1]][path[0]];
        if (finalCost < minCost) {
            minCost = finalCost;
            optimalPath = path;
            return;
        }
    }
    for (int i = 0; i < graph.size(); ++i) {
        if (!visited[i]) {
            visited[i] = true;
            path[pos] = i;
            if (cost + graph[path[pos - 1]][i] < minCost)
                tspBranchAndBound(graph, path, visited,
optimalPath, minCost, cost + graph[path[pos - 1]][i], pos + 1);
            visited[i] = false;
        }
    }
}

int main() {
    int n;
    cout << "Enter the number of cities: ";
    cin >> n;

    vector<vector<int>> graph(n, vector<int>(n));

```

	<pre>         cout &lt;&lt; "Enter the cost matrix (Enter -1 for unreachable cities):\n";         for (int i = 0; i &lt; n; ++i)             for (int j = 0; j &lt; n; ++j)                 cin &gt;&gt; graph[i][j];          vector&lt;int&gt; path(n);         vector&lt;bool&gt; visited(n, false);         path[0] = 0;         visited[0] = true;          vector&lt;int&gt; optimalPath;         int minCost = INF;         tspBranchAndBound(graph, path, visited, optimalPath, minCost, 0, 1);          if (minCost == INF)             cout &lt;&lt; "No feasible solution exists.";         else {             cout &lt;&lt; "Optimal Path: ";             for (int i = 0; i &lt; n; ++i)                 cout &lt;&lt; optimalPath[i]+1 &lt;&lt; " ";             cout &lt;&lt; "\n";             cout &lt;&lt; "Minimum Cost: " &lt;&lt; minCost &lt;&lt; endl;         }          return 0;     } </pre>
<b>Output</b>	<pre> Enter the number of cities: 5 Enter the cost matrix (Enter -1 for unreachable cities): -1 20 30 10 11 15 -1 16 4 2 3 5 -1 2 4 19 6 18 -1 3 16 4 7 16 -1 Optimal Path: 1 4 2 5 3 1 Minimum Cost: 28 </pre>
<b>Justification of the complexity calculated</b>	<p>The time complexity of the Branch and Bound algorithm for the Traveling Salesman Problem is <math>O(n!)</math>, where <math>n</math> is the number of vertices (cities) in the graph. This complexity arises from the algorithm's exploration of all possible permutations of the cities to find the optimal solution. At each level of recursion, the algorithm iterates over all remaining unvisited cities to extend the current partial tour, resulting in <math>n - pos</math> iterations. Although the algorithm prunes branches that cannot lead to an optimal solution through backtracking, in the worst case, it still explores a factorial number of permutations, leading to the <math>O(n!)</math> time complexity.</p>

<b>Conclusion</b>	<p>The Branch and Bound algorithm for the Traveling Salesman Problem offers significant advantages in solving optimization challenges. Its ability to systematically explore the solution space while intelligently pruning branches leads to efficient identification of the optimal solution. This algorithm finds applications across various domains, including logistics, transportation, and manufacturing. In logistics, it aids in route planning, ensuring the most cost-effective and time-efficient delivery schedules. In transportation, it helps in scheduling vehicle routes, minimizing fuel consumption and maximizing service coverage. Moreover, in manufacturing, it assists in optimizing production sequences, reducing operational costs and improving resource utilization. The Branch and Bound algorithm's versatility and effectiveness make it a valuable tool for tackling complex optimization problems, ultimately leading to improved efficiency and resource utilization in real-world scenarios.</p>
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