

Green Vision



Al and Computer Vision for a Greener Tomorrow

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Al GRID Hackathon 2024
Challenge #3: Green Area Recognition







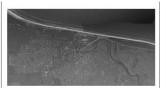


Overview of the Challenge

- Recognising Green Areas in aerial photos.
 - Can the percentage of greening in the urban area be detected?
 - Are there differences in the quality of the greening areas?
 - Can potential for improving the proportion of greening areas be identified?
- Data: Publicly available RGB and CIR images.









Large size of Images and Data!









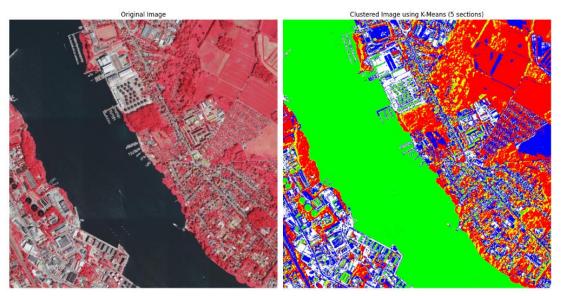
DEMO

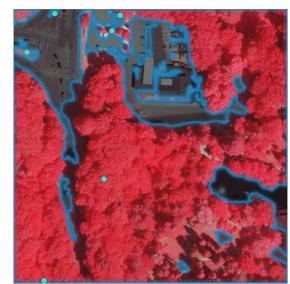




Approaches

- Traditional Computer Vision: Fast and efficient. But lacks generalisability.
- Deep Learning based methods: Can be powerful, but require higher compute and may occassionally fail in a non-human like fashion.





Left: Original Middle: k-means

Right: Segement Anything









Initial Observations

- Challenges: Shadows, water regions, context-dependent applicability.
- Varying qualities of greenery, can be seen, but not visually quantified without any processing.
- SOTA segmentation models do not perform well.
- The data is complicated, but we can use some inductive biases in the data:
 - Lighting conditions are very similar throughout.
 - Residential areas, open-fields etc have a common pattern.
 - CIR images: Plants have low Green pixel intensities.

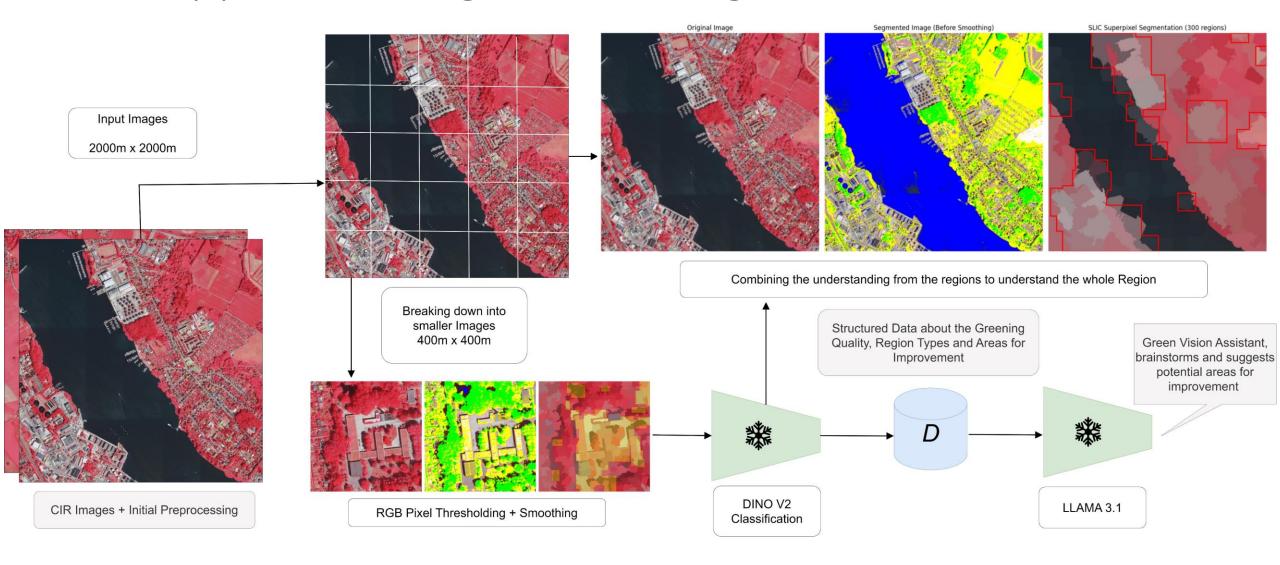








Our Approach: Single Area Image





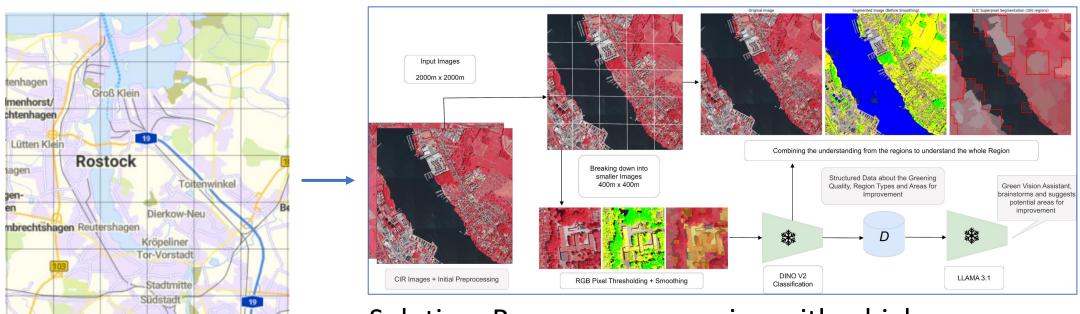






Our Approach: City-Wide Planning

Rostock Metropolian Area: 42 Images (12km x 14km)



Solution: Run a coarser version with a higher compute budget.







Kritzmow

Final Observations

- The approach that worked the optimally for us is a combination of traditional image processing and modern Deep Learning methods.
- Our approach is designed to be modular and deployable under various scenarios.
- Can be completely run (inference) on CPU or up to 4GB of vRAM.
- Areas for improvement/futher work:
 - Improving region classification.
 - The current algorithm is conservative when suggesting areas which could be reviewed better.
 - Outputs of LLMs may not be factually accurate, esp. without RAG/finetuning.









Thank you ©

The implementation is available on our Github Repo:











