



T Vivek Sai Surya Chaitanya

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PROFILE SUMMARY

Graduated with **distinction** and secured **8th rank** in Bachelor of Technology (Computer Science – AI), and currently pursuing a Master's in Computer Science (Autonomous Systems) at the University of Stuttgart. I am seeking a hands-on internship/working student role that bridges AI, robotics, and real-world system interaction.

EDUCATION

Master of Science <i>Computer Science (Major: Autonomous Systems)</i> University of Stuttgart	Oct. 2024 – Present Stuttgart, Germany
Bachelor of Technology <i>Computer Science and Engineering (Artificial Intelligence)</i> Amrita Vishwa Vidyapeetham – GPA: 1.70	Oct. 2020 – Apr 2024 Chennai, India

WORK EXPERIENCE

Student Assistant <i>University of Stuttgart, Germany</i>	Dec 2024 – Sep 2025
<ul style="list-style-type: none">Implemented a vision-guided pick-and-place pipeline for the Franka Research 3 (FR3) collaborative robot using AprilTag-based 6D pose estimation to autonomously assemble wooden hexagon cassettes.Developed and optimized AI-driven perception and control algorithms for automated Lashing Joint assembly, improving precision and cycle time in robotic manufacturing workflows.Integrated camera-based marker detection with ROS2 for real-time feedback control and enhanced robotic positioning accuracy.Contributed to the synchronization of dual robotic systems for coordinated manipulation tasks, including lashing and prestressing of timber elements, leveraging multi-robot communication and control frameworks.	
Research Intern <i>IIITDM, Kancheepuram, India</i>	Jun 2023 – Aug 2023
<ul style="list-style-type: none">Developed an innovative model that combines keras pre-trained models with vision transformers (HybridViT).Implemented quality control measures for research procedures, minimizing errors and ensuring accurate findings, achieving an impressive accuracy rate of 93.71%.Recorded and analyzed data to produce reports of results.	

PROJECTS

Differential Drive FusionBot: From CAD to Autonomous Mapping <i>ROS, Python</i>	June 2024
<ul style="list-style-type: none">Designed a differential drive robot in Fusion 360, converted to URDF, and integrated with ROS for control. Simulated in Gazebo, the robot autonomously maps environments using a laser sensor.	
Hopping Robot Foot Placement Controller <i>MATLAB</i>	Jan 2023
<ul style="list-style-type: none">Implemented Raibert Controller for precise dynamic foot placement, demonstrating control systems expertise.	
Biped Walking Robot Simulation <i>MATLAB</i>	Sep 2022
<ul style="list-style-type: none">Simulated two-legged robot motion in MATLAB, accurately modeling kinematics and dynamics to test control strategies for walking robots.	
A Simulation of Closed-Loop Mechanisms <i>MATLAB</i>	Apr 2022
<ul style="list-style-type: none">Explored closed-loop configurations, analyzing parameter impacts to inform real-world mechanism design and control.	
RoboViz: MATLAB Robotics Visualization Tool <i>MATLAB</i>	Oct 2021
<ul style="list-style-type: none">Created an interactive platform for visualizing and analyzing arm dynamics with user-friendly controls.	

SKILLS

Programming:	Python (NumPy, Open3D, Pandas, SciPy), C++, MATLAB, Java; Linux-based development
Robotics:	ROS1 & ROS2, Manipulation Strategies, Robot Kinematics, Motion Planning, Camera Calibration, Coordinate Transformations
Computer Vision:	Object Detection, OpenCV, AI-based Perception Systems
Machine Learning:	PyTorch, TensorFlow; End-to-End Computer Vision Pipelines, Deep Learning for Perception, Model Training & Evaluation
Tools & Simulation:	Docker, Gazebo; Experience with Depth Cameras (RealSense)
Version Control:	Git, GitHub; Collaborative Software Development and Integration
Research & Evaluation:	Literature Review, Experimental Design, Metric-based Evaluation, Scientific Documentation
Soft Skills:	Analytical Thinking, Independent and Team Collaboration, Problem-Solving, Strategic Approach to Work
Languages:	English (C1), German (A1), Telugu (Native)

CONFERENCE PUBLICATIONS

Aug 2025	• Leveraging CNN Features and Vision Transformers for Enhanced Focal Liver Lesion Classification
Sep 2024	• Enhanced Alzheimer's Disease Classification: A Stacked Model Fusion with Brain MRI Imaging
Apr 2024	• MedDQN: A Deep Reinforcement learning approach for Biomedical Image classification
Jan 2024	• Extractive Document Summarization with Advanced Deep Reinforcement Learning
Nov 2023	• Sarcasm Detection in Telugu and Tamil: An Exploration of Machine Learning and Deep Neural Networks
Oct 2023	• Numerical Solution of First and Second Order Differential Equations with Deep Neural Networks

JOURNAL PROCEEDINGS

Apr 2025	• HybridViT: An Approach for Alzheimer's Disease Classification with ADNI Neuroimaging Data
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