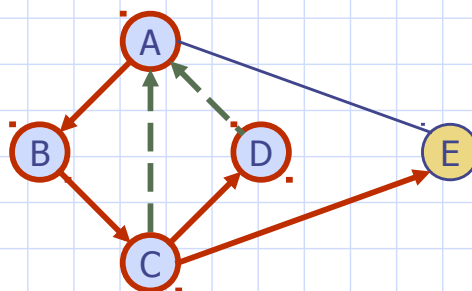
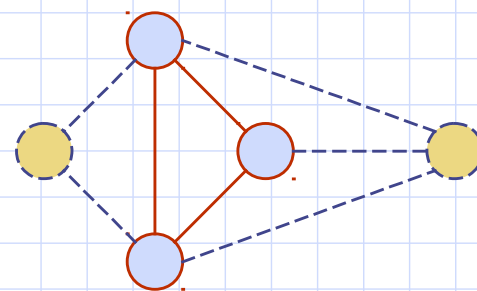


# Depth-First Search

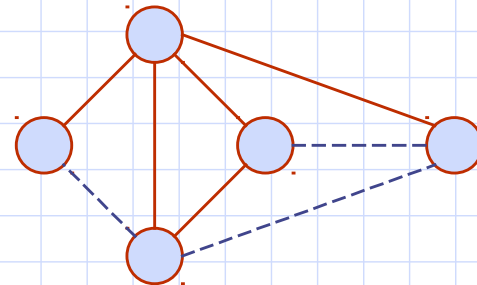


# Subgraphs

- A subgraph  $S$  of a graph  $G$  is a graph such that
  - The vertices of  $S$  are a subset of the vertices of  $G$
  - The edges of  $S$  are a subset of the edges of  $G$
- A spanning subgraph of  $G$  is a subgraph that contains all the vertices of  $G$



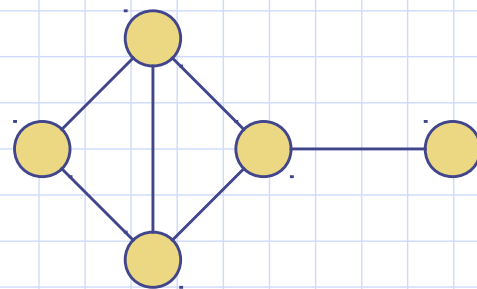
Subgraph



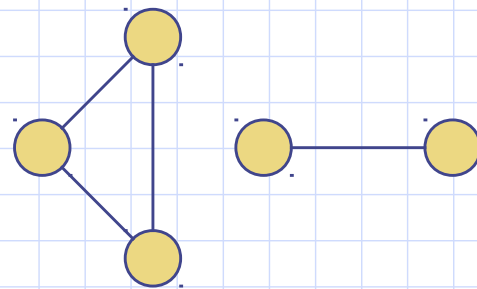
Spanning subgraph

# Connectivity

- A graph is connected if there is a path between every pair of vertices
- A connected component of a graph  $G$  is a maximal connected subgraph of  $G$



Connected graph



Non connected graph with two connected components

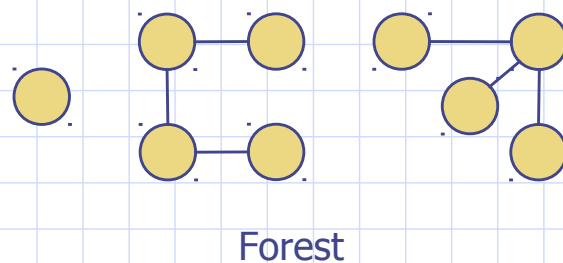
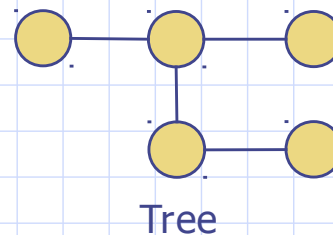
# Trees and Forests

- A (free) tree is an undirected graph  $T$  such that

- $T$  is connected
- $T$  has no cycles

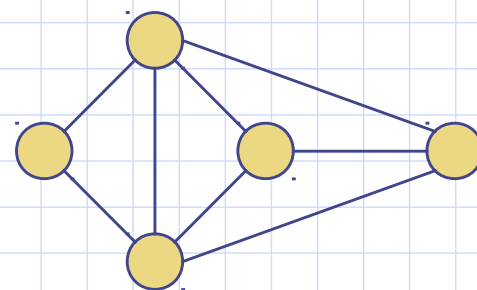
This definition of tree is different from the one of a rooted tree

- A forest is an undirected graph without cycles
- The connected components of a forest are trees

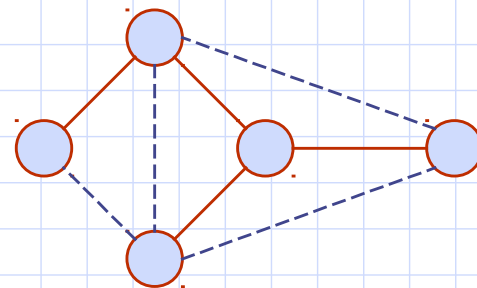


# Spanning Trees and Forests

- A spanning tree of a connected graph is a spanning subgraph that is a tree
- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest



Graph



Spanning tree

# Depth-First Search

- Depth-first search (DFS) is a general technique for traversing a graph
- A DFS traversal of a graph  $G$ 
  - Visits all the vertices and edges of  $G$
  - Determines whether  $G$  is connected
  - Computes the connected components of  $G$
  - Computes a spanning forest of  $G$
- DFS on a graph with  $n$  vertices and  $m$  edges takes  $O(n + m)$  time
- DFS can be further extended to solve other graph problems
  - Find and report a path between two given vertices
  - Find a cycle in the graph
- Depth-first search is to graphs what Euler tour is to binary trees

# DFS Algorithm

- The algorithm uses a mechanism for setting and getting “labels” of vertices and edges

## Algorithm *DFS(G)*

**Input** graph  $G$

**Output** labeling of the edges of  $G$   
as discovery edges and  
back edges

```

for all  $u \in G.vertices()$ 
     $setLabel(u, UNEXPLORED)$ 
for all  $e \in G.edges()$ 
     $setLabel(e, UNEXPLORED)$ 
for all  $v \in G.vertices()$ 
    if  $getLabel(v)$ 
     $= UNEXPLORED$ 
         $DFS(G, v)$ 
  
```

## Algorithm *DFS(G, v)*

**Input** graph  $G$  and a start vertex  $v$  of  $G$

**Output** labeling of the edges of  $G$   
in the connected component of  $v$   
as discovery edges and back edges

```

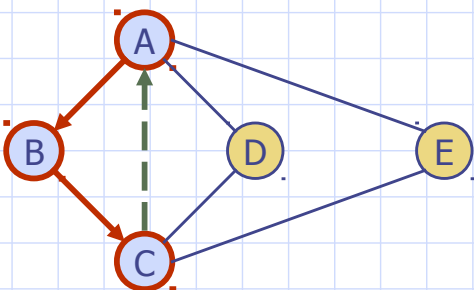
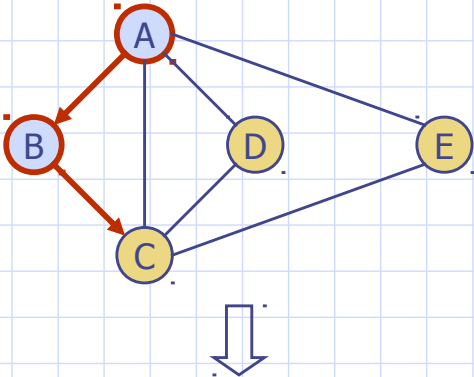
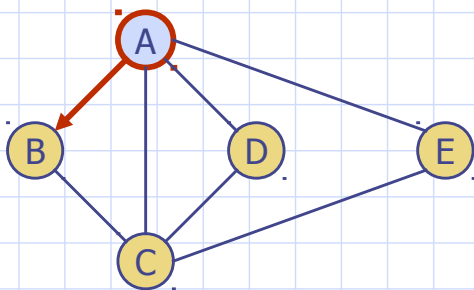
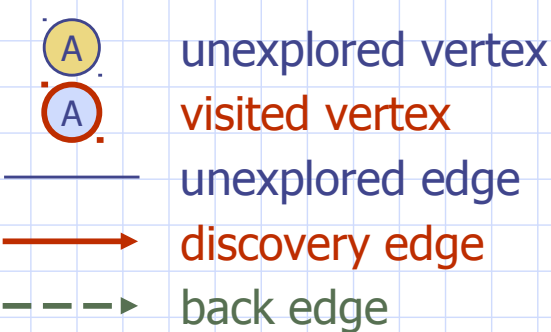
 $setLabel(v, VISITED)$ 
for all  $e \in G.incidentEdges(v)$ 
    if  $getLabel(e) = UNEXPLORED$ 
         $w \leftarrow opposite(v, e)$ 
        if  $getLabel(w)$ 
         $= UNEXPLORED$ 
             $setLabel(e, DISCOVERY)$ 
             $DFS(G, w)$ 
        else
             $setLabel(e, BACK)$ 
  
```

# Python Implementation

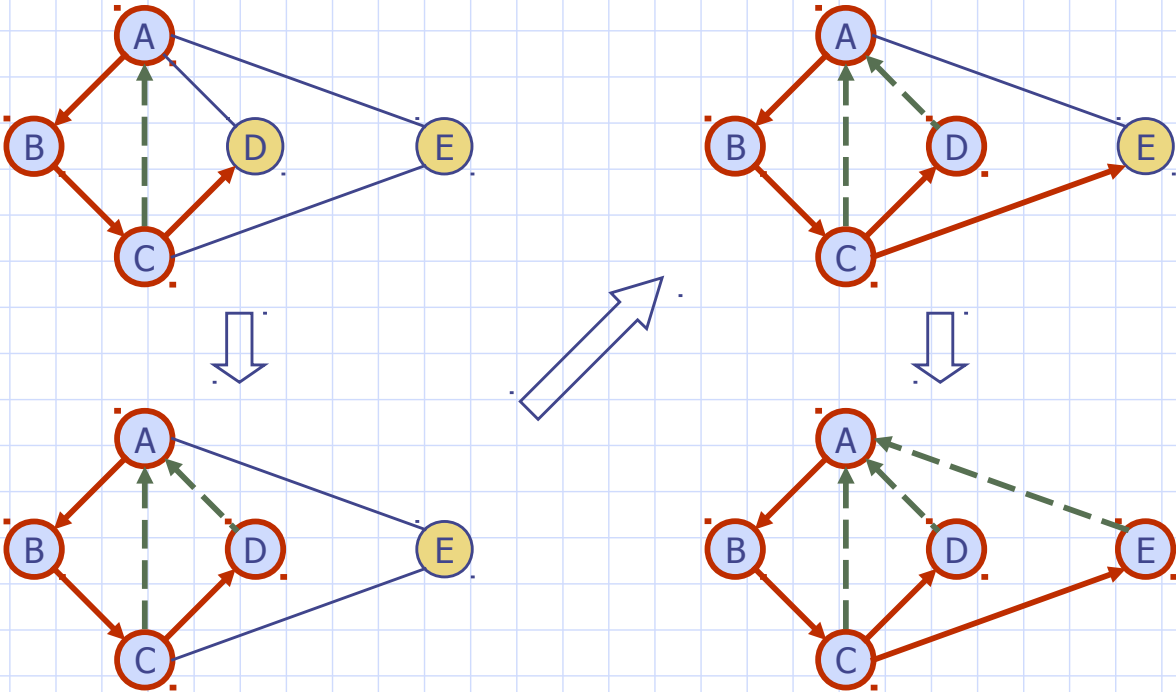
```
1 def DFS(g, u, discovered):
2     """ Perform DFS of the undiscovered portion of Graph g starting at Vertex u.
3
4     discovered is a dictionary mapping each vertex to the edge that was used to
5     discover it during the DFS. (u should be "discovered" prior to the call.)
6     Newly discovered vertices will be added to the dictionary as a result.
7     """
8     for e in g.incident_edges(u):           # for every outgoing edge from u
9         v = e.opposite(u)
10        if v not in discovered:             # v is an unvisited vertex
11            discovered[v] = e               # e is the tree edge that discovered v
12            DFS(g, v, discovered)          # recursively explore from v
```



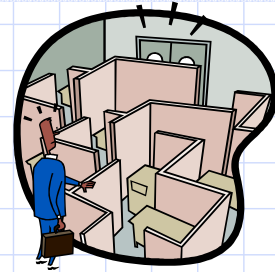
# Example



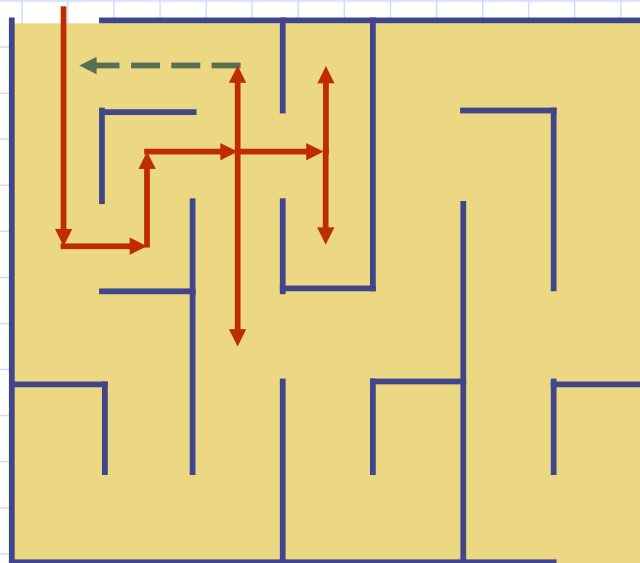
# Example (cont.)



# DFS and Maze Traversal



- The DFS algorithm is similar to a classic strategy for exploring a maze
  - We mark each intersection, corner and dead end (vertex) visited
  - We mark each corridor (edge ) traversed
  - We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)



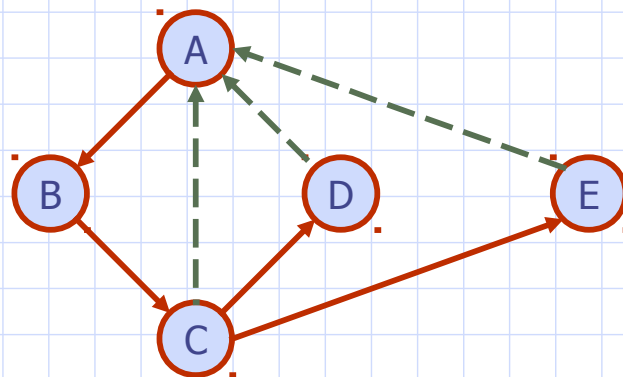
# Properties of DFS

## Property 1

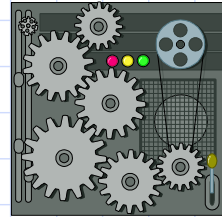
$DFS(G, v)$  visits all the vertices and edges in the connected component of  $v$

## Property 2

The discovery edges labeled by  $DFS(G, v)$  form a spanning tree of the connected component of  $v$



# Analysis of DFS



- ❑ Setting/getting a vertex/edge label takes  $O(1)$  time
- ❑ Each vertex is labeled twice
  - once as UNEXPLORED
  - once as VISITED
- ❑ Each edge is labeled twice
  - once as UNEXPLORED
  - once as DISCOVERY or BACK
- ❑ Method incidentEdges is called once for each vertex
- ❑ DFS runs in  $O(n + m)$  time provided the graph is represented by the adjacency list structure
  - Recall that  $\sum_v \deg(v) = 2m$

# Path Finding



- We can specialize the DFS algorithm to find a path between two given vertices  $u$  and  $z$  using the template method pattern
- We call  $DFS(G, u)$  with  $u$  as the start vertex
- We use a stack  $S$  to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex  $z$  is encountered, we return the path as the contents of the stack

```

Algorithm pathDFS( $G, v, z$ )
  setLabel( $v, VISITED$ )
  S.push( $v$ )
  if  $v = z$ 
    return S.elements()
  for all  $e \in G.incidentEdges(v)$ 
    if getLabel( $e$ ) = UNEXPLORED
       $w \leftarrow opposite(v, e)$ 
      if getLabel( $w$ )
        = UNEXPLORED
        setLabel( $e, DISCOVERY$ )
        S.push( $e$ )
        pathDFS( $G, w, z$ )
        S.pop( $e$ )
      else
        setLabel( $e, BACK$ )
  S.pop( $v$ )
  
```

# Cycle Finding



- We can specialize the DFS algorithm to find a simple cycle using the template method pattern
- We use a stack  $S$  to keep track of the path between the start vertex and the current vertex
- As soon as a back edge  $(v, w)$  is encountered, we return the cycle as the portion of the stack from the top to vertex  $w$

```

Algorithm cycleDFS( $G, v, z$ )
  setLabel( $v, VISITED$ )
  S.push( $v$ )
  for all  $e \in G.incidentEdges(v)$ 
    if getLabel( $e$ ) = UNEXPLORED
       $w \leftarrow opposite(v, e)$ 
      S.push( $e$ )
      if getLabel( $w$ ) = UNEXPLORED
        setLabel( $e, DISCOVERY$ )
        pathDFS( $G, w, z$ )
        S.pop( $e$ )
      else
         $T \leftarrow$  new empty stack
        repeat
           $o \leftarrow S.pop()$ 
          T.push( $o$ )
        until  $o = w$ 
        return T.elements()
  S.pop( $v$ )
  
```