

# Dynamic Programming

# Longest Common Subsequence

- ♦ **Problem:** Given 2 sequences,  $X = \langle x_1, \dots, x_m \rangle$  and  $Y = \langle y_1, \dots, y_n \rangle$ , find a common subsequence whose length is maximum.

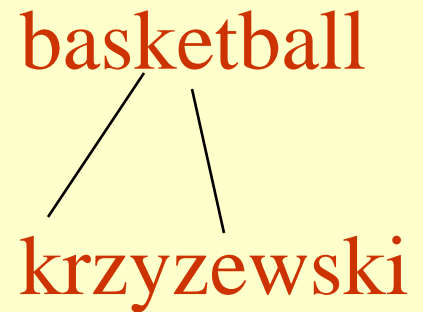
springtime  
printing



ncaa tournament  
north carolina



basketball  
krzyzewski



Subsequence need not be consecutive, but must be in order.

# Other sequence questions

- ♦ **Edit distance:** Given 2 sequences,  $X = \langle x_1, \dots, x_m \rangle$  and  $Y = \langle y_1, \dots, y_n \rangle$ , what is the minimum number of deletions, insertions, and changes that you must do to change one to another?
- ♦ **Protein sequence alignment:** Given a score matrix on amino acid pairs,  $s(a, b)$  for  $a, b \in \{\Lambda\} \cup A$ , and 2 amino acid sequences,  $X = \langle x_1, \dots, x_m \rangle \in A^m$  and  $Y = \langle y_1, \dots, y_n \rangle \in A^n$ , find the alignment with lowest score...

# More problems

**Optimal BST:** Given sequence  $K = k_1 < k_2 < \dots < k_n$  of  $n$  sorted keys, with a search probability  $p_i$  for each key  $k_i$ , build a binary search tree (BST) **with minimum expected search cost**.

**Matrix chain multiplication:** Given a sequence of matrices  $A_1 A_2 \dots A_n$ , with  $A_i$  of dimension  $m_i \times n_i$ , insert parenthesis to minimize the total number of scalar multiplications.

**Minimum convex decomposition of a polygon,**

**Hydrogen placement in protein structures, ...**

# Dynamic Programming

- ◆ Dynamic Programming is an algorithm design technique for **optimization problems**: often minimizing or maximizing.
- ◆ **Like** divide and conquer, DP solves problems by combining solutions to subproblems.
- ◆ **Unlike** divide and conquer, subproblems are not independent.
  - » Subproblems may share subsubproblems,
  - » However, solution to one subproblem may not affect the solutions to other subproblems of the same problem. (More on this later.)
- ◆ DP reduces computation by
  - » Solving subproblems in a bottom-up fashion.
  - » Storing solution to a subproblem the first time it is solved.
  - » Looking up the solution when subproblem is encountered again.
- ◆ Key: determine structure of optimal solutions

# Steps in Dynamic Programming

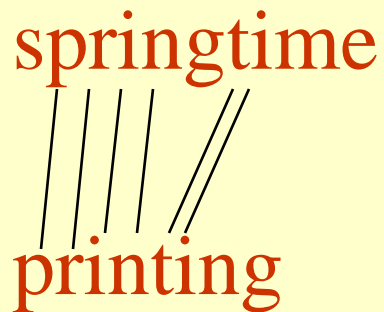
1. Characterize structure of an optimal solution.
2. Define value of optimal solution recursively.
3. Compute optimal solution values either **top-down** with caching or **bottom-up** in a table.
4. Construct an optimal solution from computed values.

We'll study these with the help of examples.

# Longest Common Subsequence

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springtime  
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basketball  
snoeyink



Subsequence need not be consecutive, but must be in order.

# Naïve Algorithm

- ◆ For every subsequence of  $X$ , check whether it's a subsequence of  $Y$ .
- ◆ **Time:**  $\Theta(n2^m)$ .
  - »  $2^m$  subsequences of  $X$  to check.
  - » Each subsequence takes  $\Theta(n)$  time to check: scan  $Y$  for first letter, for second, and so on.



# Optimal Substructure

## **Theorem**

Let  $Z = \langle z_1, \dots, z_k \rangle$  be any LCS of  $X$  and  $Y$ .

1. If  $x_m = y_n$ , then  $z_k = x_m = y_n$  and  $Z_{k-1}$  is an LCS of  $X_{m-1}$  and  $Y_{n-1}$ .
2. If  $x_m \neq y_n$ , then either  $z_k \neq x_m$  and  $Z$  is an LCS of  $X_{m-1}$  and  $Y$ .
3. or  $z_k \neq y_n$  and  $Z$  is an LCS of  $X$  and  $Y_{n-1}$ .

## **Notation:**

prefix  $X_i = \langle x_1, \dots, x_i \rangle$  is the first  $i$  letters of  $X$ .

This says what any longest common subsequence must look like;  
do you believe it?

# Optimal Substructure

## **Theorem**

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**Proof:** (case 1:  $x_m = y_n$ )

Any sequence  $Z'$  that does not end in  $x_m = y_n$  can be made longer by adding  $x_m = y_n$  to the end. Therefore,

- (1) longest common subsequence (LCS)  $Z$  must end in  $x_m = y_n$ .
- (2)  $Z_{k-1}$  is a common subsequence of  $X_{m-1}$  and  $Y_{n-1}$ , and
- (3) there is no longer CS of  $X_{m-1}$  and  $Y_{n-1}$ , or  $Z$  would not be an LCS.

# Optimal Substructure

## **Theorem**

Let  $Z = \langle z_1, \dots, z_k \rangle$  be any LCS of  $X$  and  $Y$ .

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3. or  $z_k \neq y_n$  and  $Z$  is an LCS of  $X$  and  $Y_{n-1}$ .

**Proof:** (case 2:  $x_m \neq y_n$ , and  $z_k \neq x_m$ )

Since  $Z$  does not end in  $x_m$ ,

- (1)  $Z$  is a common subsequence of  $X_{m-1}$  and  $Y$ , and
- (2) there is no longer CS of  $X_{m-1}$  and  $Y$ , or  $Z$  would not be an LCS.

# Recursive Solution

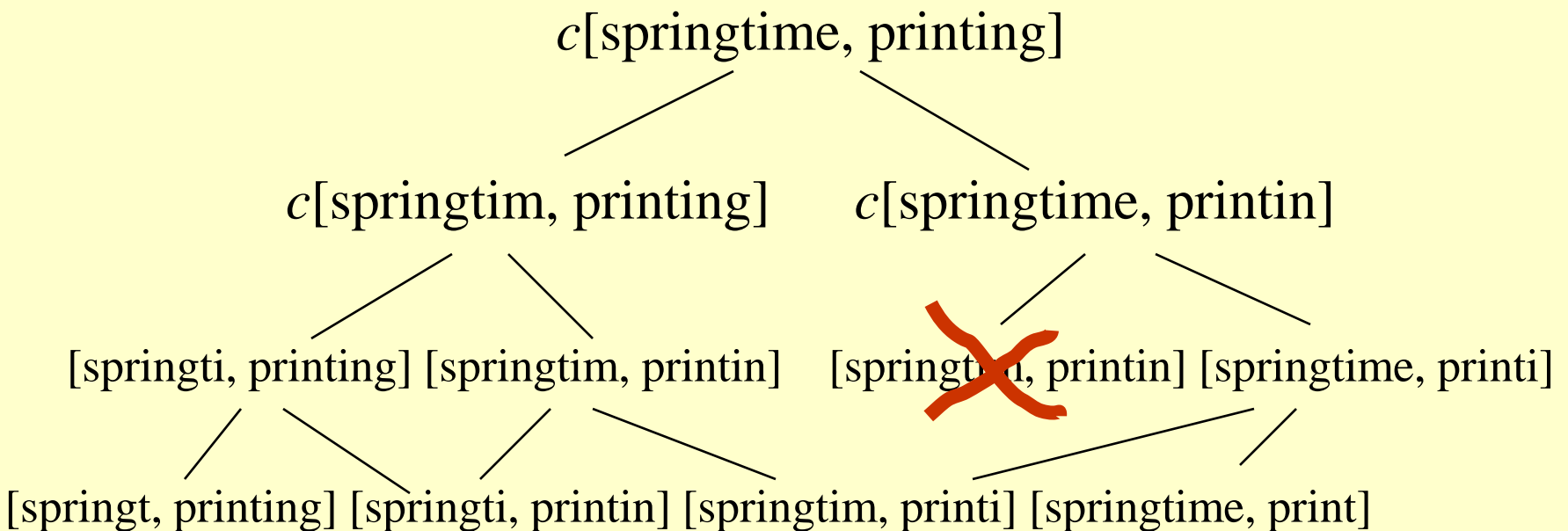
- ◆ Define  $c[i, j] = \text{length of LCS of } X_i \text{ and } Y_j$ .
- ◆ We want  $c[m, n]$ .

$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0, \\ c[i-1, j-1] + 1 & \text{if } i, j > 0 \text{ and } x_i = y_j, \\ \max(c[i-1, j], c[i, j-1]) & \text{if } i, j > 0 \text{ and } x_i \neq y_j. \end{cases}$$

This gives a recursive algorithm and solves the problem.  
But does it solve it well?

# Recursive Solution

$$c[\alpha, \beta] = \begin{cases} 0 & \text{if } \alpha \text{ empty or } \beta \text{ empty,} \\ c[\text{prefix}\alpha, \text{prefix}\beta] + 1 & \text{if } \text{end}(\alpha) = \text{end}(\beta), \\ \max(c[\text{prefix}\alpha, \beta], c[\alpha, \text{prefix}\beta]) & \text{if } \text{end}(\alpha) \neq \text{end}(\beta). \end{cases}$$



# Recursive Solution

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• Keep track of  $c[\alpha, \beta]$  in a table of  $nm$  entries:

- top/down
- bottom/up

		p	r	i	n	t	i	n	g
s									
p									
r									
i									
n									
g									
t									
i									
m									
e									

# Computing the length of an LCS

## LCS-LENGTH ( $X, Y$ )

```
1.  $m \leftarrow \text{length}[X]$ 
2.  $n \leftarrow \text{length}[Y]$ 
3. for  $i \leftarrow 1$  to  $m$ 
4.   do  $c[i, 0] \leftarrow 0$ 
5. for  $j \leftarrow 0$  to  $n$ 
6.   do  $c[0, j] \leftarrow 0$ 
7. for  $i \leftarrow 1$  to  $m$ 
8.   do for  $j \leftarrow 1$  to  $n$ 
9.     do if  $x_i = y_j$ 
10.      then  $c[i, j] \leftarrow c[i-1, j-1] + 1$ 
11.         $b[i, j] \leftarrow \text{"\backslash"}$ 
12.      else if  $c[i-1, j] \geq c[i, j-1]$ 
13.        then  $c[i, j] \leftarrow c[i-1, j]$ 
14.           $b[i, j] \leftarrow \text{"\uparrow"}$ 
15.        else  $c[i, j] \leftarrow c[i, j-1]$ 
16.           $b[i, j] \leftarrow \text{"\leftarrow"}$ 
17. return  $c$  and  $b$ 
```

$b[i, j]$  points to table entry whose subproblem we used in solving LCS of  $X_i$  and  $Y_j$ .

$c[m, n]$  contains the length of an LCS of  $X$  and  $Y$ .

**Time:**  $O(mn)$

# Constructing an LCS

PRINT-LCS ( $b, X, i, j$ )

1. **if**  $i = 0$  or  $j = 0$
2.     **then return**
3. **if**  $b[i, j] = "\diagdown"$
4.     **then** PRINT-LCS( $b, X, i-1, j-1$ )
5.         print  $x_i$
6.     **elseif**  $b[i, j] = "\diagup"$
7.         **then** PRINT-LCS( $b, X, i-1, j$ )
8. **else** PRINT-LCS( $b, X, i, j-1$ )

- Initial call is PRINT-LCS ( $b, X, m, n$ ).
- When  $b[i, j] = \diagdown$ , we have extended LCS by one character. So  
LCS = entries with  $\diagdown$  in them.
- Time:  $O(m+n)$



# Steps in Dynamic Programming

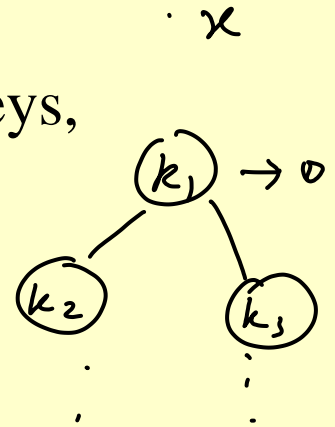
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We'll study these with the help of examples.

# Optimal Binary Search Trees

## ◆ Problem

- » Given sequence  $K = k_1 < k_2 < \dots < k_n$  of  $n$  sorted keys, with a search probability  $p_i$  for each key  $k_i$ .
- » Want to build a binary search tree (BST) **with minimum expected search cost.**
- » Actual cost = # of items examined.
- » For key  $k_i$ , cost =  $\text{depth}_T(k_i) + 1$ , where  $\text{depth}_T(k_i)$  = depth of  $k_i$  in BST  $T$ .



$$E[\text{Cost}(T)] = \sum_{k \in K} \text{pr}(k) \times (d_T(k) + 1) = \sum_{k \in K} \text{pr}(k) d_T(k) + 1$$

# Expected Search Cost

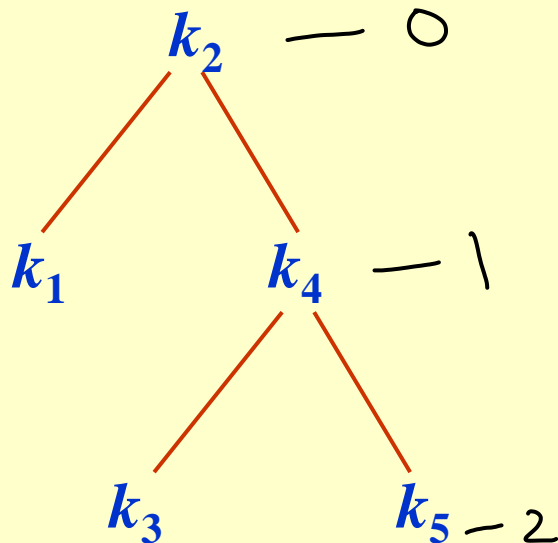
$E[\text{search cost in } T]$

$$\begin{aligned} &= \sum_{i=1}^n (\text{depth}_T(k_i) + 1) \cdot p_i \\ &= \sum_{i=1}^n \text{depth}_T(k_i) \cdot p_i + \sum_{i=1}^n p_i \\ &= 1 + \sum_{i=1}^n \text{depth}_T(k_i) \cdot p_i \quad (15.16) \end{aligned}$$

Sum of probabilities is 1.

# Example

- Consider 5 keys with these search probabilities:  
 $p_1 = 0.25, p_2 = 0.2, p_3 = 0.05, p_4 = 0.2, p_5 = 0.3.$

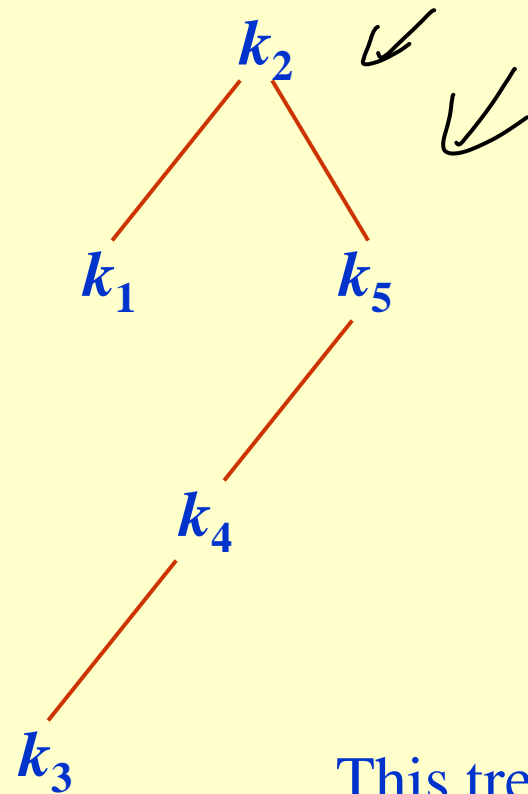


$i$	$\text{depth}_T(k_i)$	$\text{depth}_T(k_i) \cdot p_i$
1	①	0.25
2	①	0
3	2	0.1
4	1	0.2
5	2	0.6
		1.15

Therefore,  $E[\text{search cost}] = 2.15.$

# Example

- ♦  $p_1 = 0.25, p_2 = 0.2, p_3 = 0.05, p_4 = 0.2, p_5 = 0.3$



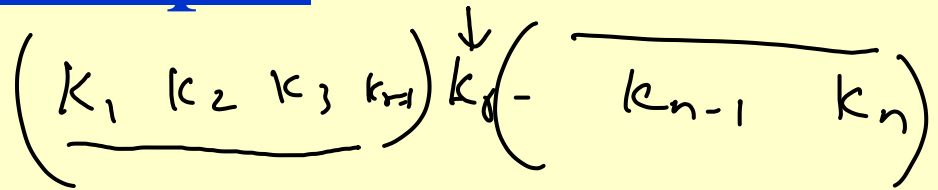
$i$	$\text{depth}_T(k_i)$	$\text{depth}_T(k_i) \cdot p_i$
1	1	0.25
2	0	0
3	3	0.15
4	2	0.4
5	1	0.3
		1.10

Therefore,  $E[\text{search cost}] = 2.10$ .

This tree turns out to be optimal for this set of keys.

# Example

## ♦ Observations:



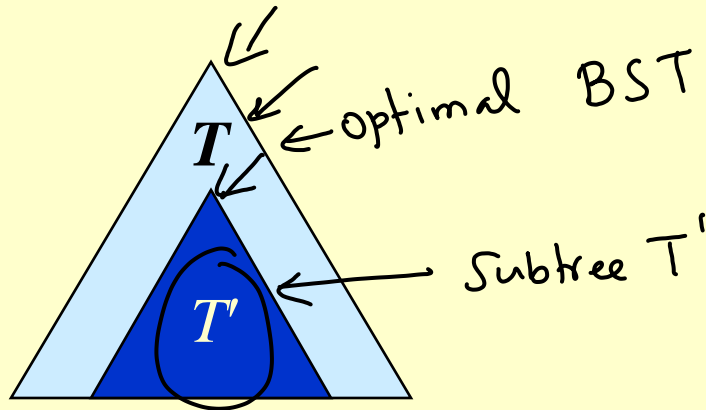
- » Optimal BST **may not** have smallest height.
- » Optimal BST **may not** have highest-probability key at root.

## ♦ Build by exhaustive checking?

- » Construct each  $n$ -node BST.
- » For each,
  - assign keys and compute expected search cost.
- » But there are  $\Omega(4^n/n^{3/2})$  different BSTs with  $n$  nodes.

# Optimal Substructure

- ◆ Any subtree of a BST contains keys in a contiguous range  $k_i, \dots, k_j$  for some  $1 \leq i \leq j \leq n$ .



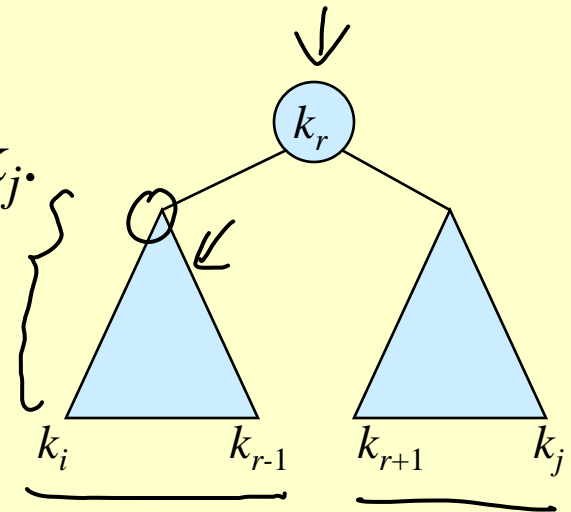
- ◆ If  $T$  is an optimal BST and  $T$  contains subtree  $T'$  with keys  $k_i, \dots, k_j$ , then  $T'$  must be an optimal BST for keys  $k_i, \dots, k_j$ .

For  $T$  to be optimal,  
 $T'$  must also be optimal

- ◆ **Proof:** Cut and paste.

# Optimal Substructure

- ◆ One of the keys in  $k_i, \dots, k_j$ , say  $k_r$ , where  $i \leq r \leq j$ , **must be the root** of an optimal subtree for these keys.
- ◆ Left subtree of  $k_r$  contains  $k_i, \dots, k_{r-1}$ .
- ◆ Right subtree of  $k_r$  contains  $k_{r+1}, \dots, k_j$ .



- ◆ **To find an optimal BST:**

- » Examine all candidate roots  $k_r$ , for  $i \leq r \leq j$
- » Determine all optimal BSTs containing  $k_i, \dots, k_{r-1}$  and containing  $k_{r+1}, \dots, k_j$



# Recursive Solution

- ♦ Find optimal BST for  $k_i, \dots, k_j$ , where  $i \geq 1, j \leq n, j \geq i-1$ .  
When  $j = i-1$ , the tree is empty.  $(i, i-1)$
- ♦ Define  $e[i, j]$  = expected search cost of optimal BST for  $k_i, \dots, k_j$ .
- ♦ If  $j = i-1$ , then  $e[i, j]$  = 0. ↙
- ♦ If  $j \geq i$ ,  
 » Select a root  $k_r$  for some  $i \leq r \leq j$ .  
 » Recursively make an optimal BSTs
  - for  $k_i, \dots, k_{r-1}$  as the left subtree, and
  - for  $k_{r+1}, \dots, k_j$  as the right subtree.

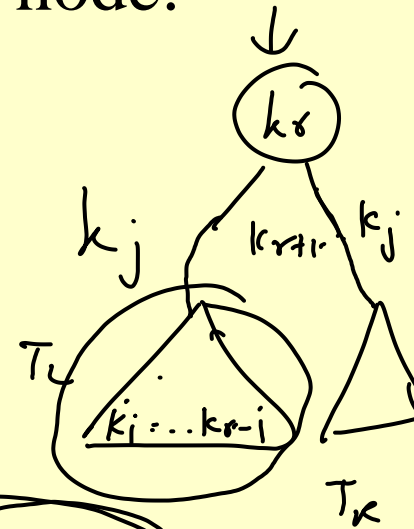
$$j-i+1$$

$$j-r < j-i+1$$

# Recursive Solution

- ◆ When the OPT subtree becomes a subtree of a node:
  - » Depth of every node in OPT subtree goes up by 1.
  - » Expected search cost increases by

$$w(i, j) = \sum_{l=i}^j p_l$$
 ← Cumulative density from (15.16)



- ◆ If  $k_r$  is the root of an optimal BST for  $k_i, \dots, k_j$ :

$$e[i, j] = p_r + (e[i, r-1] + w(i, r-1)) + (e[r+1, j] + w(r+1, j))$$

$$\searrow \searrow = e[i, r-1] + e[r+1, j] + w(i, j). \quad (\text{because } w(i, j) = w(i, r-1) + p_r + w(r+1, j))$$

- ◆ But, we don't know  $k_r$ . Hence,

$$e[i, j] = \begin{cases} 0 & \text{if } j = i - 1 \\ \min_{i \leq r \leq j} \{e[i, r-1] + e[r+1, j] + w(i, j)\} & \text{if } i \leq j \end{cases}$$

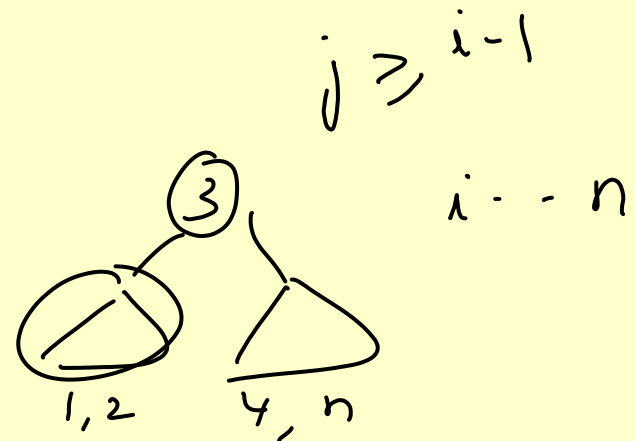
# Computing an Optimal Solution

For each subproblem  $(i, j)$ , store:

- ♦ expected search cost in a table  $e[1..n+1, 0..n]$ 
  - » Will use only entries  $e[i, j]$ , where  $j \geq i-1$ .
- ♦  $\text{root}[i, j]$  = root of subtree with keys  $k_i, \dots, k_j$ , for  $1 \leq i \leq j \leq n$ .
- ♦  $w[1..n+1, 0..n]$  = sum of probabilities
  - »  $w[i, i-1] = 0$  for  $1 \leq i \leq n$ .
  - »  $w[i, j] = w[i, j-1] + p_j$  for  $1 \leq i \leq j \leq n$ .

$$\text{root}(1, n) = 3$$

$$e[1, 2] = 1$$



# Pseudo-code

## OPTIMAL-BST( $p, q, n$ )

```
1.  for  $i \leftarrow 1$  to  $n + 1$ 
2.    do  $e[i, i - 1] \leftarrow 0$ 
3.     $w[i, i - 1] \leftarrow 0$ 
4.  for  $l \leftarrow 1$  to  $n$ 
5.    do for  $i \leftarrow 1$  to  $n - l + 1$ 
6.      do  $j \leftarrow i + l - 1$ 
7.         $e[i, j] \leftarrow \infty$ 
8.         $w[i, j] \leftarrow w[i, j - 1] + p_j$ 
9.        for  $r \leftarrow i$  to  $j$ 
10.         do  $t \leftarrow e[i, r - 1] + e[r + 1, j] + w[i, j]$ 
11.          if  $t < e[i, j]$ 
12.            then  $e[i, j] \leftarrow t$ 
13.               $root[i, j] \leftarrow r$ 
14.  return  $e$  and  $root$ 
```

Consider all trees with  $l$  keys.

Fix the first key.

Fix the last key

Determine the root  
of the optimal  
(sub)tree

Time:  $O(n^3)$

# Elements of Dynamic Programming

- ◆ Optimal substructure
- ◆ Overlapping subproblems

# Optimal Substructure

- ◆ Show that a solution to a problem consists of making a choice, which leaves one or more subproblems to solve.
- ◆ Suppose that you are given this last choice that leads to an optimal solution.
- ◆ Given this choice, determine which subproblems arise and how to characterize the resulting space of subproblems.
- ◆ Show that the solutions to the subproblems used within the optimal solution must themselves be optimal. Usually use cut-and-paste.
- ◆ Need to ensure that a wide enough range of choices and subproblems are considered.

# Optimal Substructure

- ◆ Optimal substructure varies across problem domains:
  - » 1. *How many subproblems* are used in an optimal solution.
  - » 2. *How many choices* in determining which subproblem(s) to use.
- ◆ Informally, running time depends on (# of subproblems overall)  $\times$  (# of choices).
- ◆ How many subproblems and choices do the examples considered contain?
- ◆ Dynamic programming uses optimal substructure **bottom up**.
  - » *First* find optimal solutions to subproblems.
  - » *Then* choose which to use in optimal solution to the problem.

# Optimal Substructure

- ◆ Does optimal substructure apply to all optimization problems? No.
- ◆ Applies to determining the **shortest path** but **NOT** the **longest simple path** of an unweighted directed graph.
- ◆ Why?
  - » **Shortest path has independent subproblems.**
  - » Solution to one subproblem does not affect solution to another subproblem of the same problem.
  - » **Subproblems are not independent in longest simple path.**
    - Solution to one subproblem affects the solutions to other subproblems.
  - » **Example:**



# Overlapping Subproblems

- ◆ The space of subproblems must be “small”.
- ◆ The total number of distinct subproblems is a polynomial in the input size.
  - » A recursive algorithm is exponential because it solves the same problems repeatedly.
  - » If divide-and-conquer is applicable, then each problem solved will be brand new.