

# Exercise 11

Due date:

Name : Vivi  
Student ID : 24S153073  
Grade : \_\_\_\_\_

**Problem 1 Score:** \_\_\_\_\_. **Properties of g-convex sets and functions**

Let  $(\mathcal{M}, \langle \cdot, \cdot \rangle)$  be a Riemannian manifold and consider a geodesically convex subset  $S \subseteq \mathcal{M}$ . Let  $f, f_1, \dots, f_n : S \rightarrow \mathbb{R}$  be g-convex functions.

- (1) Sublevel sets of g-convex functions are g-convex sets.

Let  $s \in \mathbb{R}$ . Show that the sublevel set

$$L_f(s) = \{x \in S : f(x) \leq s\}$$

is g-convex.

- (2) Intersections of sublevel sets are g-convex sets.

Let  $s_1, s_2 \in \mathbb{R}$ . Show that the intersection

$$\bigcap_{j=1}^n L_{f_j}(s_j)$$

is g-convex.

- (3) Sums of nonnegatively scaled g-convex functions are g-convex functions.

Let  $\alpha_1, \dots, \alpha_n \geq 0$ . Show that the function

$$g(x) = \sum_{j=1}^n \alpha_j f_j(x)$$

is g-convex.

- (4) The pointwise maximum of g-convex functions is g-convex.

Show that the function

$$h(x) = \max_{j=1, \dots, n} f_j(x)$$

is g-convex.

**Solution:** (1) Let  $x, y \in L_f(s)$  and  $\gamma : [0, 1] \rightarrow S$  be a geodesic segment with  $\gamma(0) = x$  and  $\gamma(1) = y$ . Since  $S$  is g-convex, we have  $\gamma(t) \in S$  for all  $t \in [0, 1]$ . By the g-convexity of  $f$ , for all  $t \in [0, 1]$ , we have

$$\begin{aligned} f \circ \gamma(t) &\leq (1-t)f(x) + tf(y) \\ &\leq (1-t)s + ts = s, \end{aligned}$$

which implies that  $\gamma(t) \in L_f(s)$  for all  $t \in [0, 1]$ . Therefore,  $L_f(s)$  is g-convex.

- (2) Let  $x, y \in \bigcap_{j=1}^n L_{f_j}(s_j)$  and  $\gamma : [0, 1] \rightarrow S$  be a geodesic segment with  $\gamma(0) = x$  and  $\gamma(1) = y$ . Since  $S$  is g-convex, we have  $\gamma(t) \in S$  for all  $t \in [0, 1]$ . By the g-convexity of  $f_j$ , for all  $t \in [0, 1]$ , we have

$$\begin{aligned} f_j \circ \gamma(t) &\leq (1-t)f_j(x) + tf_j(y) \\ &\leq (1-t)s_j + ts_j = s_j \end{aligned}$$

which implies that  $\gamma(t) \in L_{f_j}(s_j)$  for all  $j = 1, \dots, n$   $\forall t \in [0, 1]$ , then  $\gamma(t) \in \bigcap_{j=1}^n L_{f_j}(s_j)$ . Therefore  $\bigcap_{j=1}^n L_{f_j}(s_j)$  is g-convex.

- (3) Let  $x, y \in S$  and  $\gamma : [0, 1] \rightarrow S$  be a geodesic segment with  $\gamma(0) = x$  and  $\gamma(1) = y$ . Since  $S$  is g-convex, we have  $\gamma(t) \in S$  for all  $t \in [0, 1]$ . By the g-convexity of  $f_j$ , for all  $t \in [0, 1]$ , we have

$$\begin{aligned} g \circ \gamma(t) &= \sum_{j=1}^n \alpha_j f_j \circ \gamma(t) \\ &\leq \sum_{j=1}^n \alpha_j ((1-t)f_j(x) + tf_j(y)) \\ &= (1-t) \sum_{j=1}^n \alpha_j f_j(x) + t \sum_{j=1}^n \alpha_j f_j(y) \\ &= (1-t)g(x) + tg(y) \end{aligned}$$

for all  $t \in [0, 1]$ . Therefore,  $g$  is g-convex.

- (4) Let  $x, y \in S$  and  $\gamma : [0, 1] \rightarrow S$  be a geodesic segment with  $\gamma(0) = x$  and  $\gamma(1) = y$ . Since  $S$  is g-convex, we have  $\gamma(t) \in S$  for all  $t \in [0, 1]$ . By the definition of  $h$ , we have

$$\begin{aligned} h \circ \gamma(t) &= \max_{j=1, \dots, n} f_j \circ \gamma(t) \\ &\leq \max_{j=1, \dots, n} ((1-t)f_j(x) + tf_j(y)) \\ &\leq (1-t) \max_{j=1, \dots, n} f_j(x) + t \max_{j=1, \dots, n} f_j(y) \\ &= (1-t)h(x) + th(y) \end{aligned}$$

for all  $t \in [0, 1]$ . Therefore,  $h$  is g-convex. □

**Problem 2 Score: \_\_\_\_\_ . Intersection of g-convex sets**

The intersection of two convex subsets of a Euclidean space is convex. However, in general, the intersection of two g-convex sets is not g-convex.

- (1) Give an example of a Riemannian manifold  $(\mathcal{M}, \langle \cdot, \cdot \rangle)$  and two g-convex sets  $S_1, S_2 \subseteq \mathcal{M}$  such that  $S_1 \cap S_2$  is not g-convex.

If we make additional assumptions, then the intersection of two g-convex sets is g-convex. A subset  $S \subseteq \mathcal{M}$  is geodesically strongly convex if for any two points  $x, y \in S$ , among all geodesics segments  $\gamma : [0, 1] \rightarrow S$  with  $\gamma(0) = x$  and  $\gamma(1) = y$ , exactly one of them is minimizing and this minimizing geodesic lies entirely in  $S$ .

- (2) Let  $S_1, S_2 \subseteq \mathcal{M}$  be two geodesically strongly convex sets. Show that  $S_1 \cap S_2$  is geodesically strongly convex.

**Solution:** (1) Let  $\mathcal{M} = \mathbb{S}^1$  be the unit circle in  $\mathbb{R}^2$  with the standard metric. Define the following two g-convex sets:

$$\begin{aligned} S_1 &= \mathbb{S}^1 \setminus \{(0, 1)\} \\ S_2 &= \mathbb{S}^1 \setminus \{(0, -1)\}. \end{aligned}$$

Then  $S_1$  and  $S_2$  are g-convex sets. However, the intersection  $S_1 \cap S_2 = \mathbb{S}^1 \setminus \{(0, 1), (0, -1)\}$  is not g-convex because it's not connected.

- (2) Let  $x, y \in S_1 \cap S_2$  and  $\gamma : [0, 1] \rightarrow S_1 \cap S_2$  be the unique geodesic segment with  $\gamma(0) = x$  and  $\gamma(1) = y$ . Since  $S_1, S_2$  are geodesically strongly convex,  $\gamma(t) \in S_1$  and  $\gamma(t) \in S_2$  for all  $t \in [0, 1]$ . Therefore,  $\gamma(t) \in S_1 \cap S_2$  for all  $t \in [0, 1]$ , which implies that  $S_1 \cap S_2$  is geodesically strongly convex. □

**Problem 3 Score: \_\_\_\_\_ . Fréchet mean on hemisphere**

Write some code to generate random points  $x_1, \dots, x_n$  on a hemisphere

$$\mathbb{S}_+^{d-1} := \{x = (x^{(1)}, \dots, x^{(d)}) \in \mathbb{R}^d : x^{(d)} > 0, \|x\| = 1\}$$

near the north pole, and implement the cost function for the intrinsic averaging, that is

$$f : \mathbb{S}_+^{d-1} \rightarrow \mathbb{R}, \quad f(x) = \frac{1}{2n} \sum_{i=1}^n \text{dist}(x, x_i)^2.$$

A global minimizer of  $f$  is called the Fréchet mean of  $x_1, \dots, x_n$ .

Recall that the squared distance between two points  $x, y \in \mathbb{S}_+^{d-1}$  is given by

$$\text{dist}(x, y)^2 = \arccos^2(x^\top y),$$

and the Riemannian gradient of the squared distance is given by

$$\text{grad} \left( x \mapsto \frac{1}{2} \text{dist}(x, y)^2 \right) (x) = \frac{\text{dist}(x, y)}{\sin(\text{dist}(x, y))} (\cos(\text{dist}(x, y))x - y).$$

**Problem 4 Score: \_\_\_\_\_ . Robust covariance estimation**

Consider  $n$  points  $x_1, \dots, x_n \in \mathbb{R}^d$  sampled independently and identically distributed from a distribution  $P$  with zero

mean. We want to estimate the covariance matrix of  $P$ . If  $P$  is a zero-mean normal distribution with covariance  $\Sigma_{true} \in \mathbb{R}^{d \times d}$ , then the maximum likelihood estimation amounts to minimizing the negative log-likelihood

$$\Sigma \mapsto \log(\det \Sigma) + \frac{1}{n} \sum_{j=1}^n x_j^\top \Sigma^{-1} x_j$$

over the  $d \times d$  positive definite matrices

$$\mathcal{P}_d = \{\Sigma \in \mathbb{R}^{d \times d} : \Sigma = \Sigma^\top, \Sigma \succ 0\}.$$

The sample covariance matrix  $\Sigma^* = \frac{1}{n} \sum_{j=1}^n x_j x_j^\top$  is a minimizer of this negative log-likelihood.

The sample covariance is not robust to outliers. So if  $P$  is not normal but some heavy-tailed distribution, then the sample covariance is not suitable. We can obtain a robust estimation of the covariance by minimizing the function

$$f : \mathcal{P}_d \rightarrow \mathbb{R}, \quad f(\Sigma) = \log(\det \Sigma) + \frac{1}{n} \sum_{j=1}^n d \log(x_j^\top \Sigma^{-1} x_j),$$

which places less emphasis on outliers (points far from the mean). A minimizer of this function is called "Tyler's M-estimator of scatter". It does not have a closed form solution, and the cost function  $f$  is non-convex in the Euclidean sense. However, it is g-convex in an appropriate metric, and so a minimizer can be found efficiently (e.g., with RGD).

We consider  $\mathcal{M} = \mathcal{P}_d$  as an open subset of the symmetric  $d \times d$  matrices, and endow it with the Fisher-Rao metric

$$\langle \dot{\Sigma}_1, \dot{\Sigma}_2 \rangle_\Sigma = \text{Tr}(\Sigma^{-1} \dot{\Sigma}_1 \Sigma^{-1} \dot{\Sigma}_2),$$

for  $\Sigma \in \mathcal{P}_d$  and  $\dot{\Sigma}_1, \dot{\Sigma}_2 \in T_\Sigma \mathcal{P}_d = \{\dot{\Sigma} \in \mathbb{R}^{d \times d} : \dot{\Sigma} = \dot{\Sigma}^\top\}$ . In this Riemannian metric,  $\mathcal{P}_d$  is complete and geodesically strongly convex. For every  $\Sigma_0, \Sigma_1 \in \mathcal{P}_d$ , there is a unique geodesic segment between them, given by

$$\gamma(t) = \Sigma_0^{1/2} (\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})^t \Sigma_0^{1/2}, \quad t \in [0, 1].$$

This geodesic segment is minimizing. Alternatively, for every  $\Sigma_0, \Sigma_1 \in \mathcal{P}_d$ , there exists an invertible  $V \in \mathbb{R}^{d \times d}$  and a diagonal  $D \in \mathcal{P}_d$  such that  $\Sigma_0 = VV^\top$ ,  $\Sigma_1 = VDV^\top$ . In this case,

$$\gamma(t) = VD^t V^\top, \quad t \in [0, 1].$$

- (1) Show that the function  $\Sigma \mapsto \log(\det \Sigma)$  is g-convex.
- (2) Show that if  $g : \mathcal{P}_d \rightarrow \mathbb{R}$  is g-convex, then the function  $h(\Sigma) = g(\Sigma^{-1})$  is g-convex.
- (3) Show that if  $x \in \mathbb{R}^d$ , then the function  $\Sigma \mapsto \log(x^\top \Sigma x)$  is g-convex.
- (4) Conclude that the function  $f$  is g-convex.

**Solution:** (1) Let  $\Sigma_0, \Sigma_1 \in \mathcal{P}_d$ , then the unique geodesic segment between  $\Sigma_0$  and  $\Sigma_1$  is given by

$$\gamma(t) = \Sigma_0^{1/2} (\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})^t \Sigma_0^{1/2}, \quad t \in [0, 1].$$

For all  $t \in [0, 1]$ , we have

$$\begin{aligned} \log(\det \gamma(t)) &= \log(\det(\Sigma_0^{1/2} (\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})^t \Sigma_0^{1/2})) \\ &= \log\left(\det(\Sigma_0^{1/2}) \det(\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})^t \det(\Sigma_0^{1/2})\right) \\ &= \log(\det(\Sigma_0)) + t \log(\det(\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})) \\ &= \log(\det(\Sigma_0)) + t \log\left(\det(\Sigma_0^{-1/2}) \det(\Sigma_1) \det(\Sigma_0^{-1/2})\right) \\ &= \log(\det(\Sigma_0)) + t \log(\det(\Sigma_1)) - t \log(\det(\Sigma_0)) \\ &= (1-t) \log(\det(\Sigma_0)) + t \log(\det(\Sigma_1)) \end{aligned}$$

Therefore,  $\log(\det \Sigma)$  is g-convex. Moreover, it's g-affine.

- (2) Let  $\Sigma_0, \Sigma_1 \in \mathcal{P}_d$ , then the unique geodesic segment between  $\Sigma_0$  and  $\Sigma_1$  is given by

$$\gamma(t) = \Sigma_0^{1/2} (\Sigma_0^{-1/2} \Sigma_1 \Sigma_0^{-1/2})^t \Sigma_0^{1/2}, \quad t \in [0, 1].$$

Let  $g : \mathcal{P}_d \rightarrow \mathbb{R}$  be  $g$ -convex, then for all  $t \in [0, 1]$ , we have

$$\begin{aligned} h(\gamma(t)) &= g(\gamma(t)^{-1}) \\ &\leq (1-t)g(\Sigma_0^{-1}) + tg(\Sigma_1^{-1}) \\ &= (1-t)h(\Sigma_0) + th(\Sigma_1). \end{aligned}$$

Therefore,  $h$  is  $g$ -convex.

- (3) Fix  $x \in \mathbb{R}^d \setminus \{0\}$  and  $F : \mathcal{P}_d \rightarrow \mathbb{R}$  given by  $F(\Sigma) = \log(x^\top \Sigma x)$ . Let  $\Sigma \in \mathcal{P}_d$  and  $\dot{\Sigma} \in T_\Sigma \mathcal{P}_d$ , then the differential of  $F$  at  $\Sigma$  in the direction  $\dot{\Sigma}$  is given by

$$\begin{aligned} DF(\Sigma)(\dot{\Sigma}) &= \left. \frac{d}{dt} \log(x^\top (\Sigma + t\dot{\Sigma})x) \right|_{t=0} \\ &= (x^\top \Sigma x)^{-1} x^\top \dot{\Sigma} x \\ &= (x^\top \Sigma x)^{-1} \text{Tr}(\dot{\Sigma} x x^\top). \end{aligned}$$

Then the Euclidean gradient of  $F$  at  $\Sigma$  is given by

$$\text{grad}_\mathcal{E} F(\Sigma) = \frac{x x^\top}{x^\top \Sigma x}.$$

The Euclidean Hessian of  $F$  at  $\Sigma$  is given by

$$\begin{aligned} \text{Hess}_\mathcal{E} F(\Sigma)(\dot{\Sigma}) &= D \text{grad}_\mathcal{E} F(\Sigma)(\dot{\Sigma}) \\ &= D \left( \frac{x x^\top}{x^\top \Sigma x} \right) (\dot{\Sigma}) \\ &= -\frac{x x^\top x^\top \dot{\Sigma} x}{(x^\top \Sigma x)^2}. \end{aligned}$$

Then the Riemannian Hessian of  $F$  at  $\Sigma$  is given by

$$\begin{aligned} \text{Hess}_\mathcal{M} F(\Sigma)(\dot{\Sigma}) &= \Sigma \text{Hess}_\mathcal{E} F(\Sigma)(\dot{\Sigma}) \Sigma + \frac{\dot{\Sigma} \text{grad}_\mathcal{E} F(\Sigma) \Sigma + \Sigma \text{grad}_\mathcal{E} F(\Sigma) \dot{\Sigma}}{2} \\ &= -\frac{\Sigma x x^\top x^\top \dot{\Sigma} x \Sigma}{(x^\top \Sigma x)^2} + \frac{\dot{\Sigma} x x^\top \Sigma + \Sigma x x^\top \dot{\Sigma}}{2 x^\top \Sigma x} \\ &= \frac{1}{2 x^\top \Sigma x} (\dot{\Sigma} x x^\top \Sigma + \Sigma x x^\top \dot{\Sigma} - \frac{2 \Sigma x x^\top x^\top \dot{\Sigma} x \Sigma}{x^\top \Sigma x}). \end{aligned}$$

To show the Riemannian Hessian is positive semidefinite,

$$\begin{aligned} \langle \text{Hess}_\mathcal{M} F(\Sigma)(\dot{\Sigma}), \dot{\Sigma} \rangle_\Sigma &= \text{Tr} \left( \Sigma^{-1} \text{Hess}_\mathcal{M} F(\Sigma)(\dot{\Sigma}) \Sigma^{-1} \dot{\Sigma} \right) \\ &= \frac{1}{2 x^\top \Sigma x} \text{Tr} \left( \Sigma^{-1} (\dot{\Sigma} x x^\top \Sigma + \Sigma x x^\top \dot{\Sigma} - \frac{2 \Sigma x x^\top x^\top \dot{\Sigma} x \Sigma}{x^\top \Sigma x}) \Sigma^{-1} \dot{\Sigma} \right) \\ &= \frac{1}{2 x^\top \Sigma x} \text{Tr} \left( \Sigma^{-1} \dot{\Sigma} x x^\top \dot{\Sigma} + x x^\top \dot{\Sigma} \Sigma^{-1} \dot{\Sigma} - \frac{2 x x^\top x^\top \dot{\Sigma} x \dot{\Sigma}}{x^\top \Sigma x} \right) \\ &= \frac{1}{x^\top \Sigma x} \left( x^\top \dot{\Sigma} \Sigma^{-1} \dot{\Sigma} x - \frac{(x^\top \dot{\Sigma} x)^2}{x^\top \Sigma x} \right) \\ &= \frac{1}{(x^\top \Sigma x)^2} \left[ (x^\top \Sigma x)(x^\top \dot{\Sigma} \Sigma^{-1} \dot{\Sigma} x) - (x^\top \dot{\Sigma} x)^2 \right] \geq 0. \end{aligned}$$

Therefore,  $F(\Sigma) = \log(x^\top \Sigma x)$  is  $g$ -convex.

- (4) As shown in (1), (2), and (3), the functions  $\log(\det \Sigma)$ ,  $\log(\det \Sigma^{-1})$ , and  $\log(x^\top \Sigma x)$  are  $g$ -convex. Therefore, the function  $f$  is  $g$ -convex as a non-negative combination of  $g$ -convex functions.  $\square$