

A decorative graphic on the left side of the slide consisting of two overlapping parallelograms. The front one is blue and the back one is light green. They are positioned diagonally, with the blue one partially covering the green one.

Computer Vision to Support Neuroscience

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Presented for Arbor Biotechnologies on February 15th 2022

Background: Mouse Behavioural Studies





Problem Definition

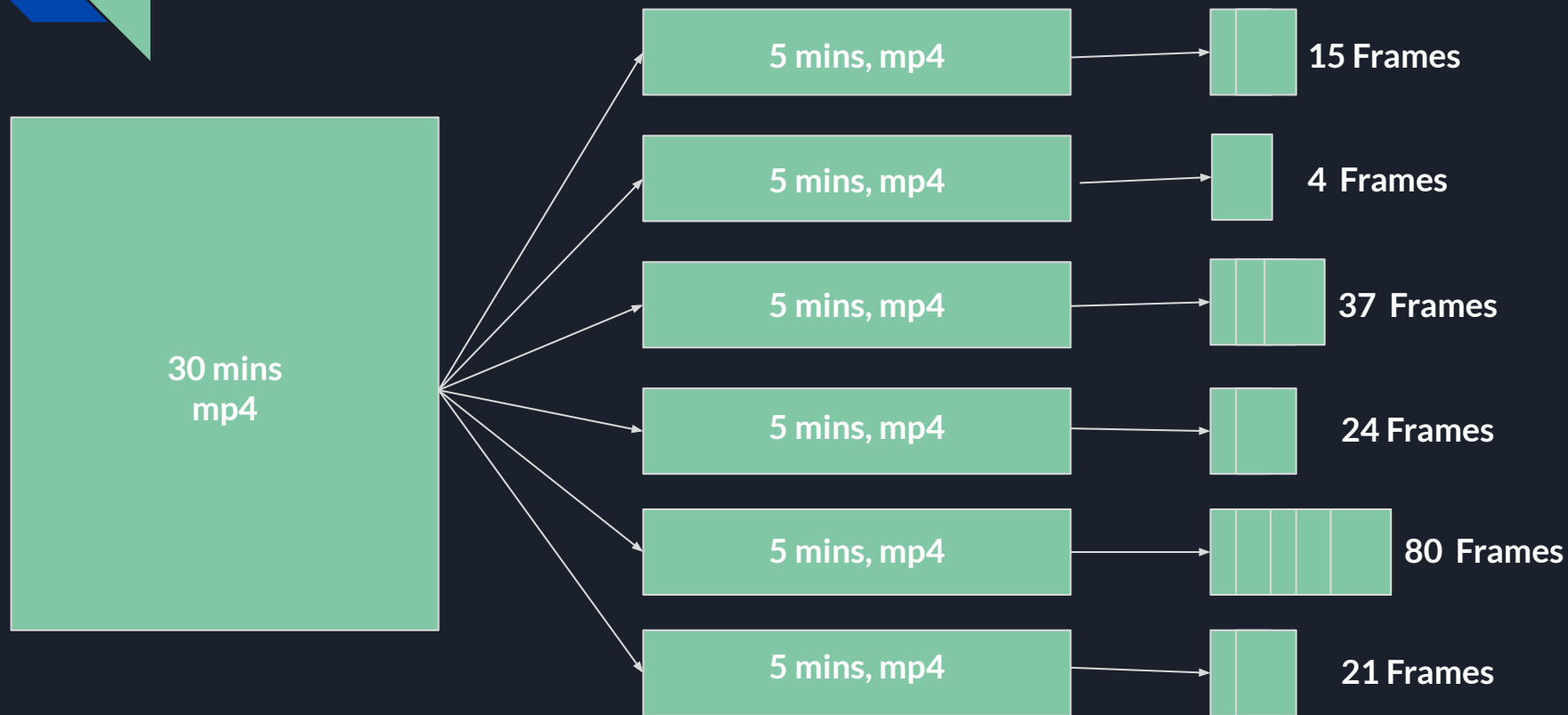
Inefficiency & Accuracy



Solution: An Overview

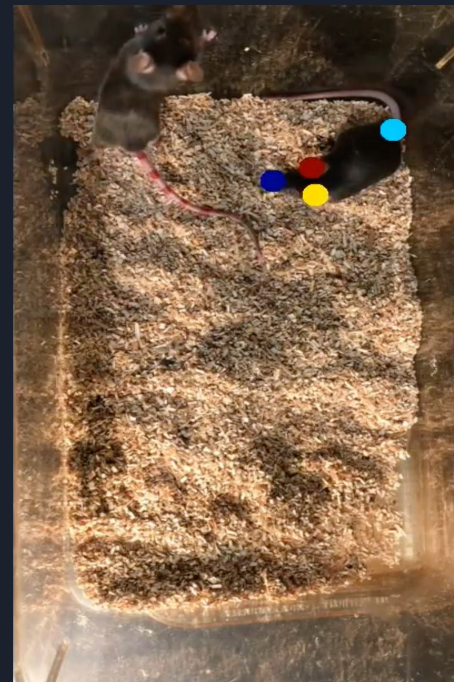
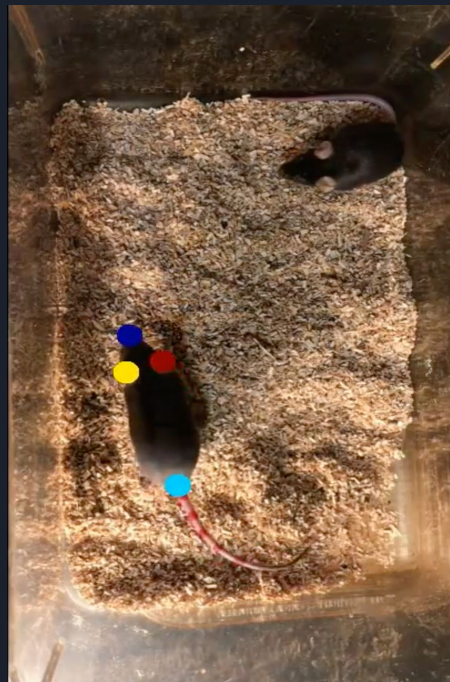
1. Detect mouse in video frame
2. Track mouse throughout video
3. Do this for both mice
4. Analyze Data
5. Derive meaningful interpretation from data

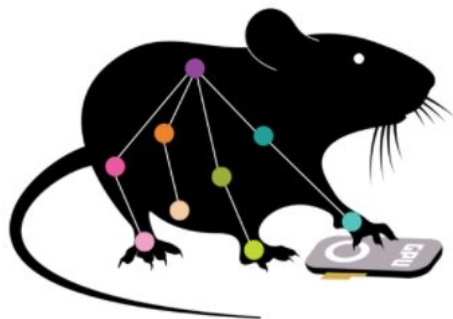
Data Manipulation



Annotation

ResNet-50





DeepLabCut:

a software package for
animal pose estimation



Solution: An Overview

- ~~1. Detect mouse in video frame~~
- ~~2. Track mouse throughout video~~
- ~~3. Do this for both mice~~
4. Analyze Data
5. Derive meaningful interpretation from data



1. Cut video down to manageable chunks
2. Extract frames from video
3. Usage of unsupervised learning to track

Mouse trajectory

Minute 0-5

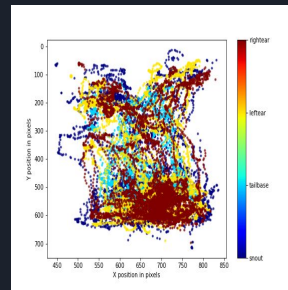
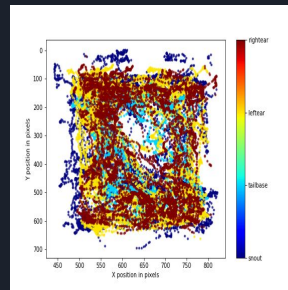
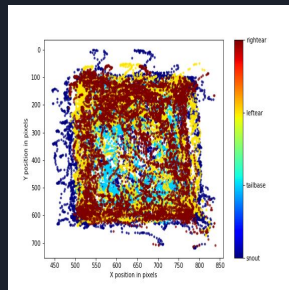
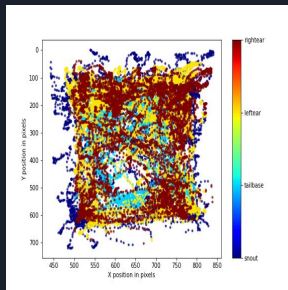
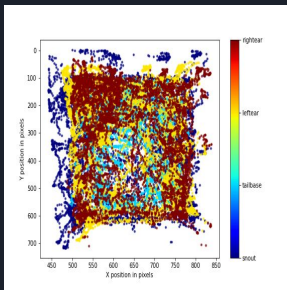
Minute 5-10

Minute 10-15

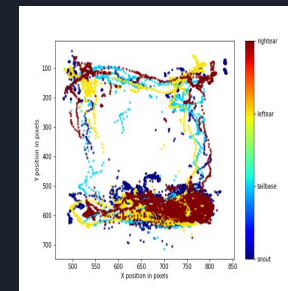
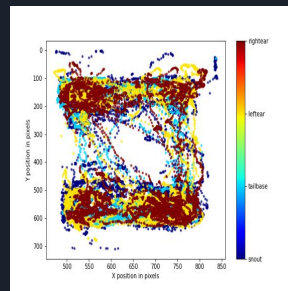
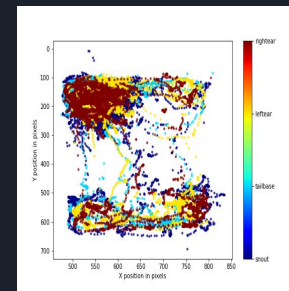
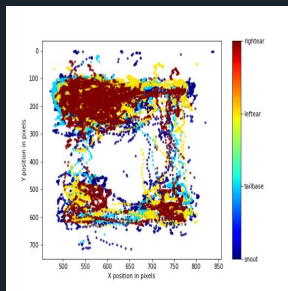
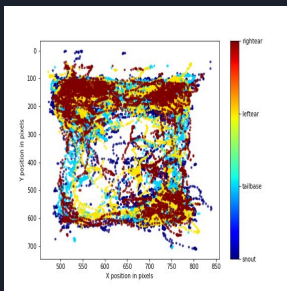
Minute 15-20

Minute 20-25

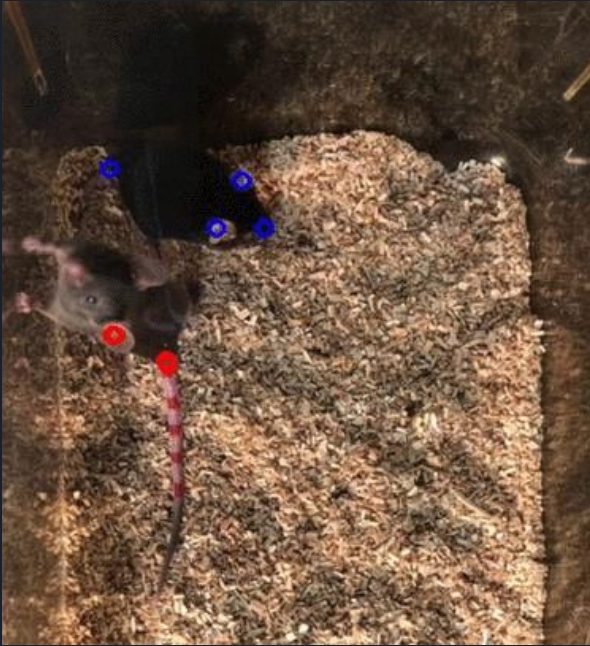
Stripped
Tail
Mouse



Plain Tail
Mouse



Mouse Interaction



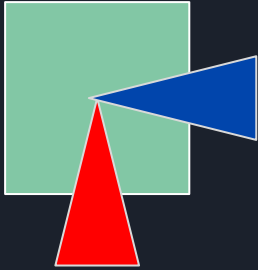
Striped Tail Mouse
initiates approach



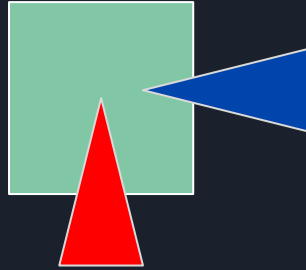
Plain Tail Mouse
initiates approach

Backtracking Algorithm: Blue Initiation

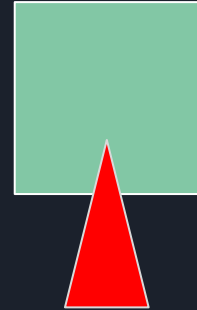
Time of Collision



Blue Enters Collision Region



Red Enters Collision Region





Discussion

- Multi-animal tracking could have been better. There were some cases of quick identity swapping
 - However, after a couple of frames the identities switched back.
 - Models could not account for when animals were overlapped
- Collision region could have been constructed better
- Instead of just using key features we could have created a bounding contour of each mouse for more precise collision detection.