

WildEDS

Wildfire Early Detection System

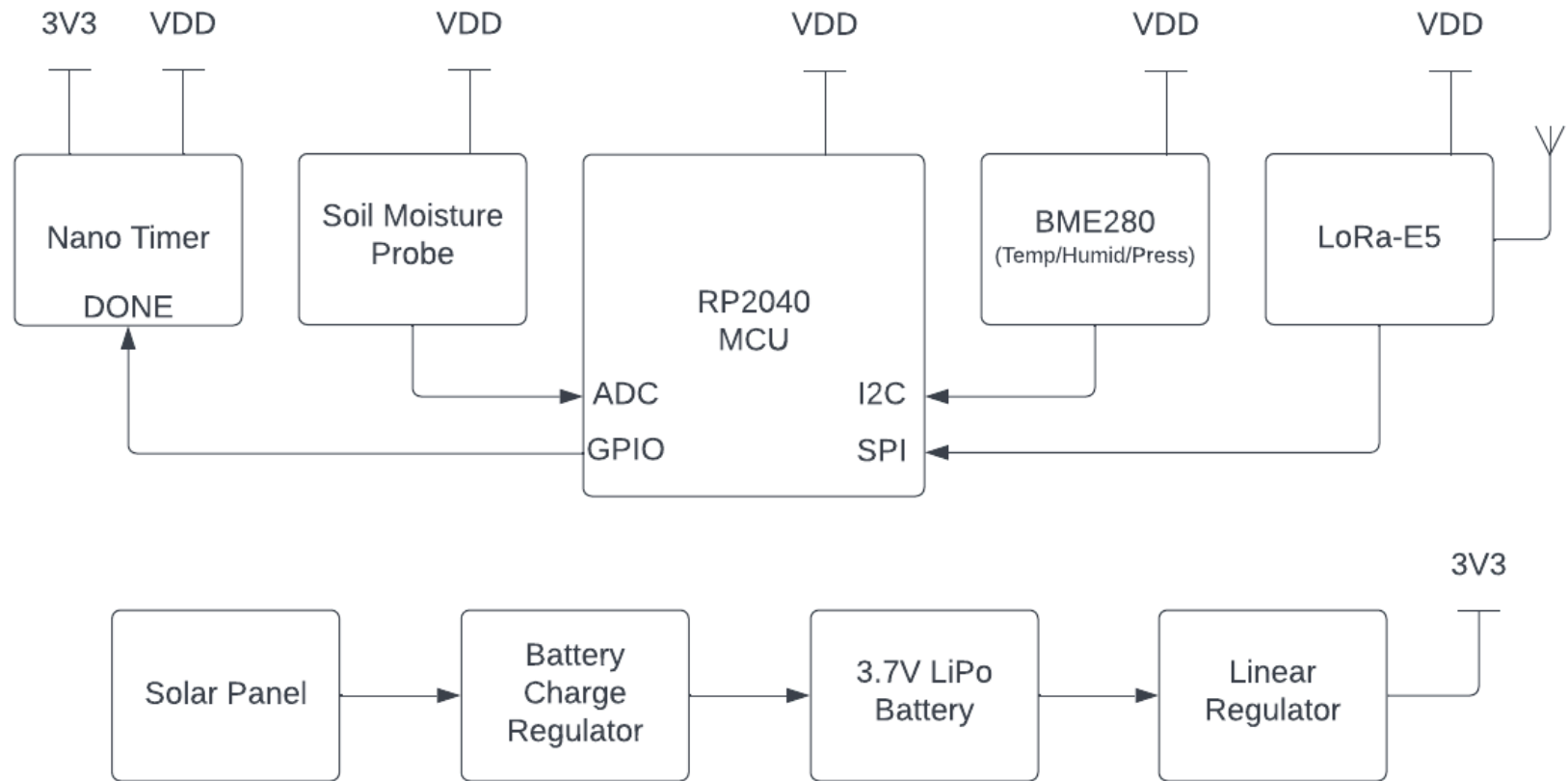
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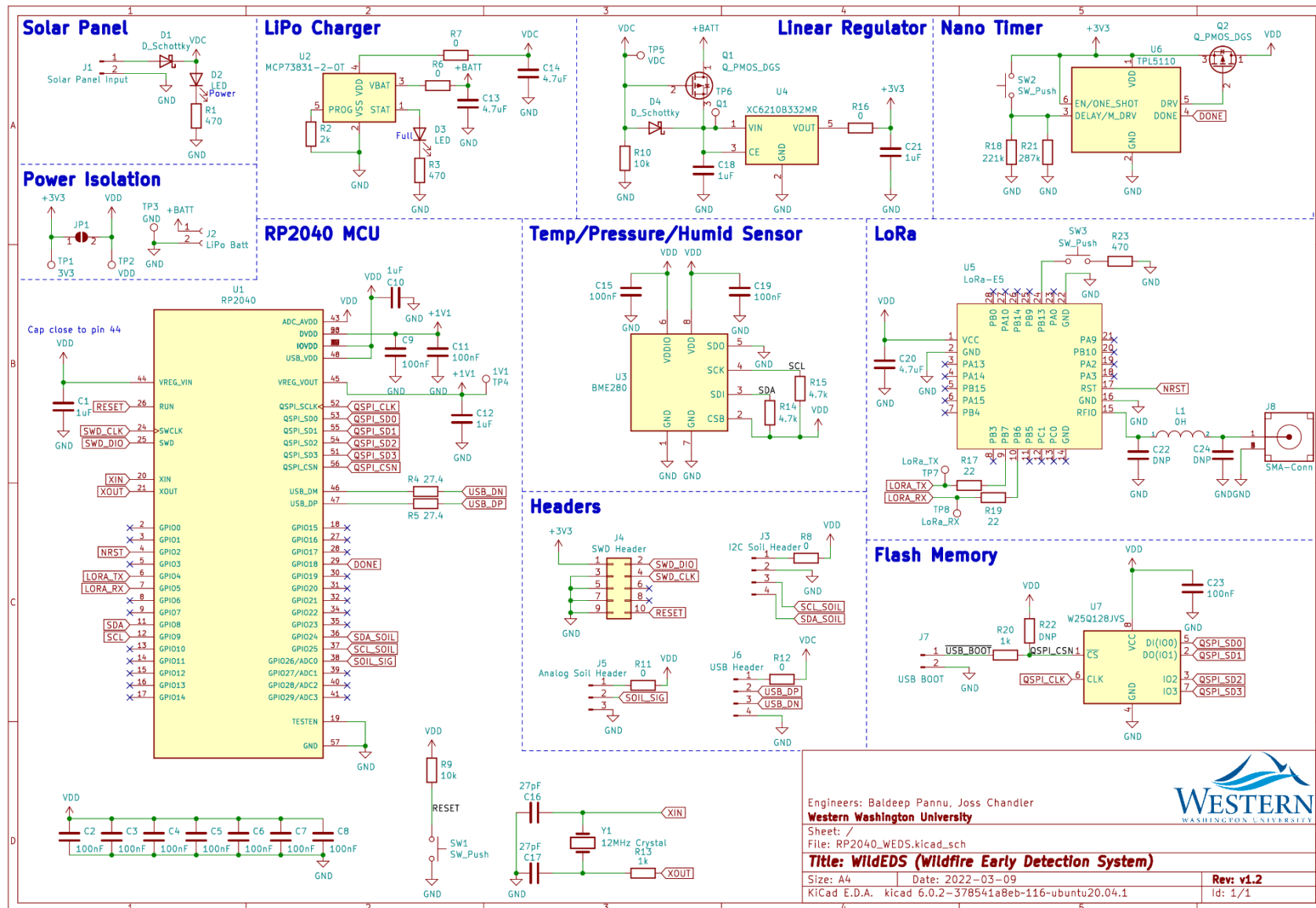
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System Design

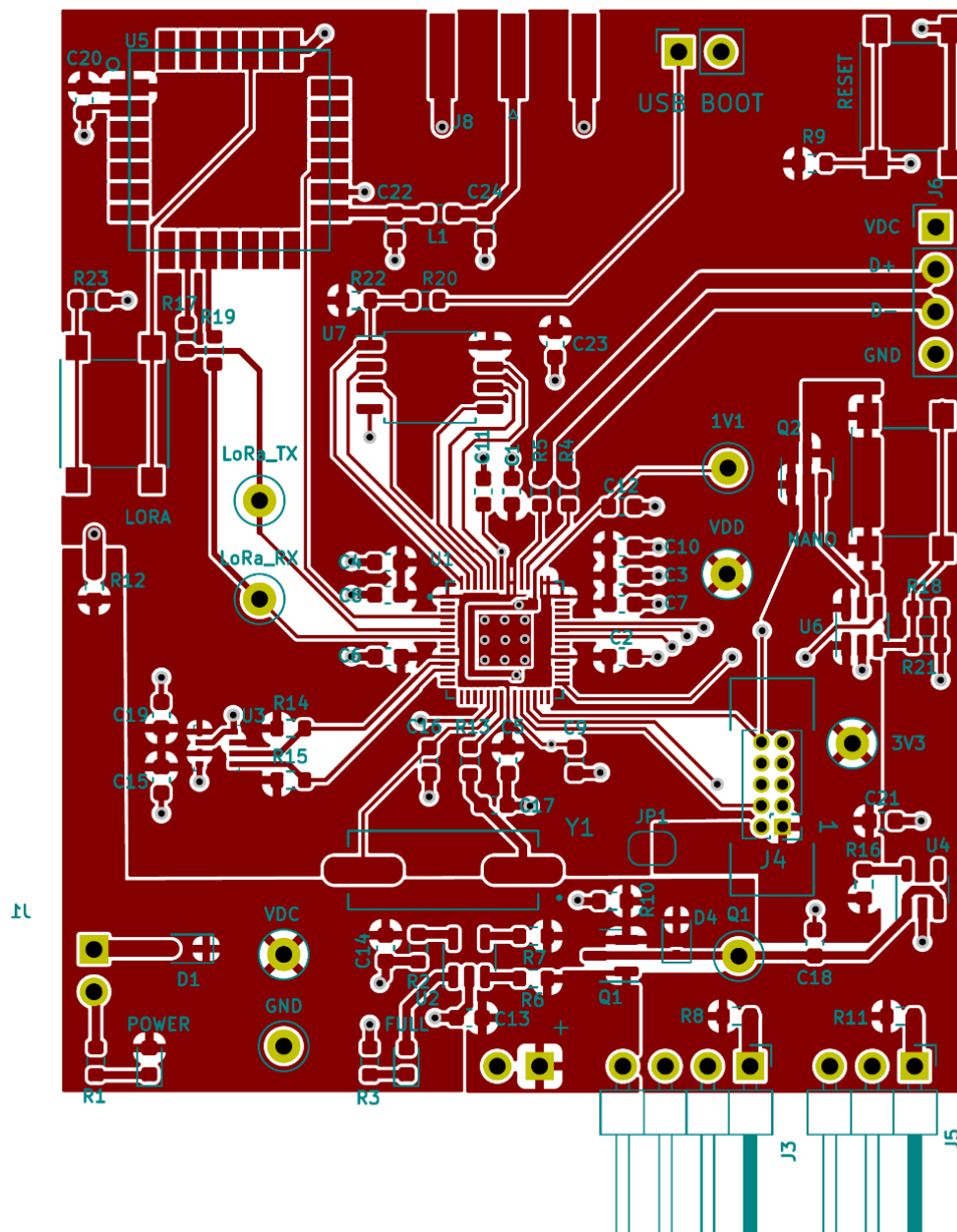


System Schematic

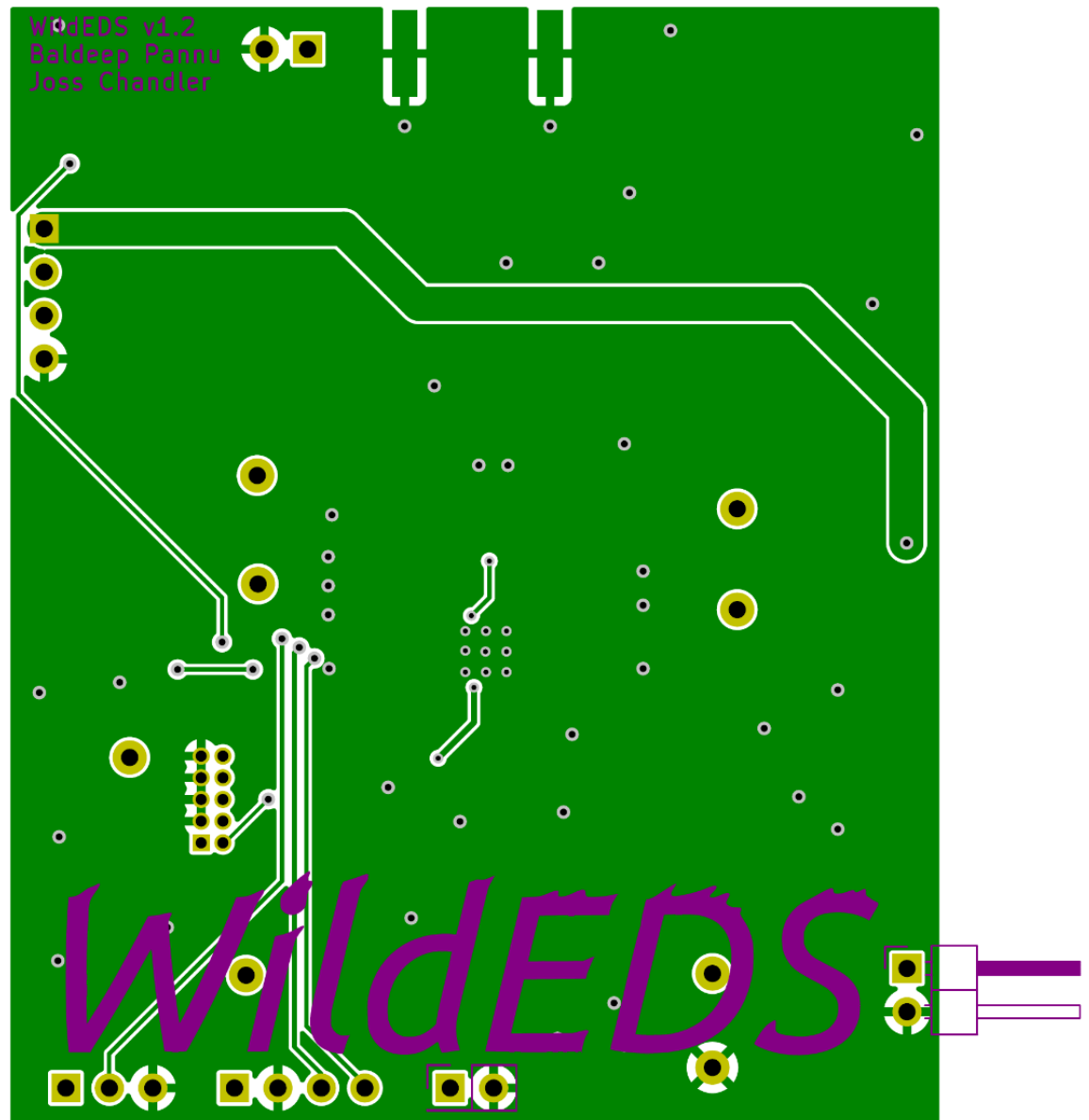


PCB Design

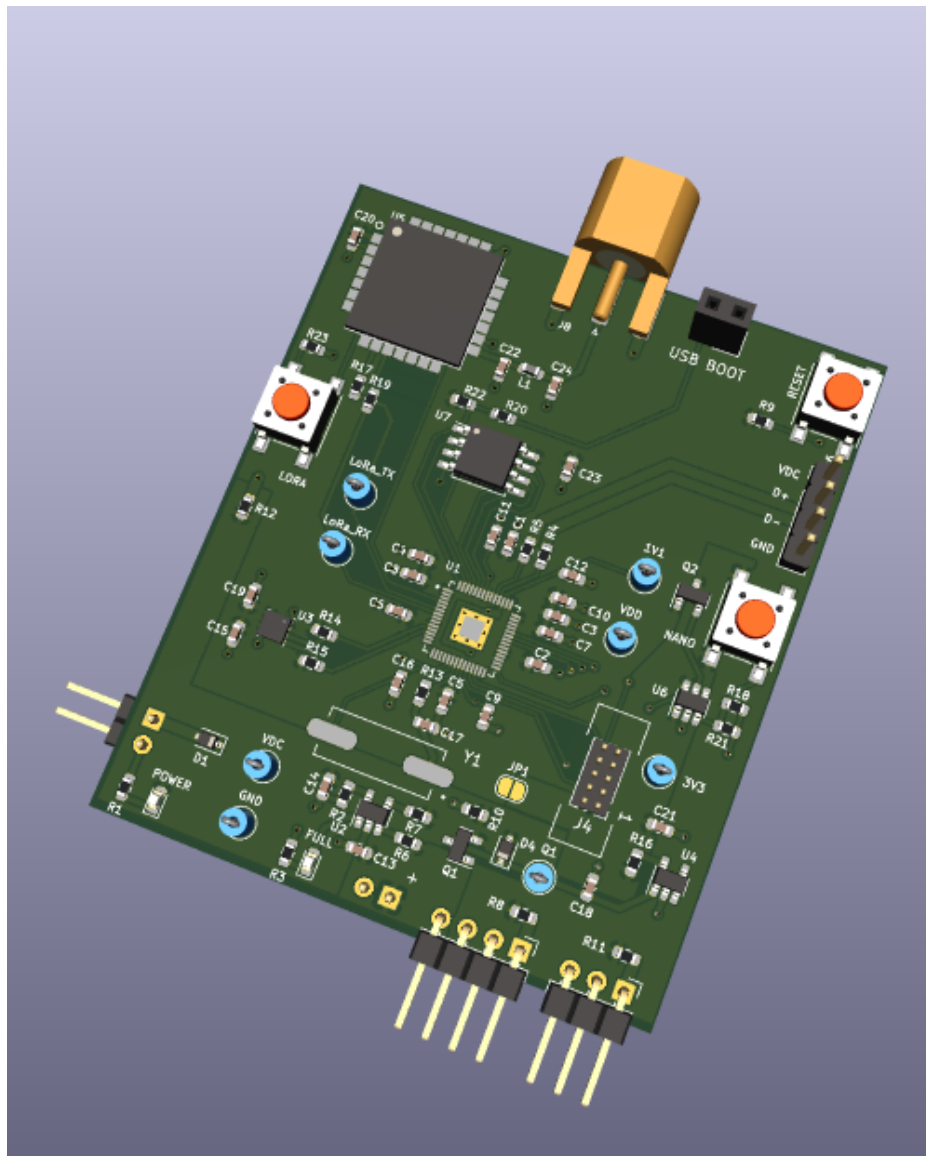
PCB Top



PCB Bottom



PCB 3D Viewer



Bill of Materials

| References | Value | Footprint | MANUFACTURER | Quantity |
|--|--------------------|---|-------------------|----------|
| C2, C3, C4, C5, C6, C7, C8, C9, C11, C15, C19, C23 | 100nF | C_0603_1608Metric | | 12 |
| C1, C10, C12, C18, C21 | 1uF | C_0603_1608Metric | | 5 |
| C13, C14, C20 | 4.7uF | C_0603_1608Metric | | 3 |
| C16, C17 | 27pF | C_0603_1608Metric | | 2 |
| C22, C24 | DNP | C_0603_1608Metric | | 2 |
| R6, R7, R8, R11, R12, R16 | | 0 R_0603_1608Metric | | 6 |
| R1, R3, R23 | | 470 R_0603_1608Metric | | 3 |
| R4, R5 | | 27.4 R_0603_1608Metric | | 2 |
| R9, R10 | 10k | R_0603_1608Metric | | 2 |
| R13, R20 | 1k | R_0603_1608Metric | | 2 |
| R14, R15 | 4.7k | R_0603_1608Metric | | 2 |
| R17, R19 | | 22 R_0603_1608Metric | | 2 |
| R2 | 2k | R_0603_1608Metric | | 1 |
| R18 | 221k | R_0603_1608Metric | | 1 |
| R21 | 287k | R_0603_1608Metric | | 1 |
| R22 | DNP | R_0603_1608Metric | | 1 |
| L1 | 0H | L_0603_1608Metric | | 1 |
| D1, D4 | D_Schottky | D_SOD-323 | | 2 |
| D2, D3 | LED | LED_0603_1608Metric | | 2 |
| U1 | RP2040 | QFN40P700X700X90-57N | Raspberry Pi | 1 |
| U2 | MCP73831-2-OT | SOT-23-5 | Microchip | 1 |
| U3 | BME280 | Bosch_LGA-8_2.5x2.5mm_P0.65mm_ClockwisePinNumbering | Bosch | 1 |
| U4 | XC6210B332MR | SOT-23-5 | Torex | 1 |
| U5 | LoRa-E5 | LoRa-E5 | Seeed | 1 |
| U6 | TPL5110 | SOT-23-6 | Texas Instruments | 1 |
| U7 | W25Q128JVS | SOIC-8_5.23x5.23mm_P1.27mm | Winbond | 1 |
| Y1 | 12MHz Crystal | XTAL1140X470X420N | Abracon | 1 |
| SW1, SW2, SW3 | SW_Push | SW_Push_1P1T_NO_6x6mm_H9.5mm | | 3 |
| Q1, Q2 | Q_PMOS_DGS | SOT-23 | | 2 |
| JP1 | Power Isolation | SolderJumper-2_P1.3mm_Open_RoundedPad1.0x1.5mm | | 1 |
| TP1 | 3V3 | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP2 | VDD | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP3 | GND | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP4 | 1V1 | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP5 | VDC | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP6 | Q1 | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP7 | LoRa_TX | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| TP8 | LoRa_RX | TestPoint_Loop_D1.80mm_Drill1.0mm_Beaded | | 1 |
| J1 | Solar Panel Input | PinHeader_1x02_P2.54mm_Horizontal | | 1 |
| J2 | LiPo Batt | PinHeader_2x01_P2.54mm_Vertical | | 1 |
| J3 | I2C Soil Header | PinHeader_1x04_P2.54mm_Horizontal | | 1 |
| J4 | SWD Header | PinHeader_2x05_P1.27mm_Vertical | | 1 |
| J5 | Analog Soil Header | PinHeader_1x03_P2.54mm_Horizontal | | 1 |
| J6 | USB Header | PinHeader_1x04_P2.54mm_Vertical | | 1 |
| J7 | USB BOOT | PinSocket_1x02_P2.54mm_Vertical | | 1 |
| J8 | SMA-Conn | SMA_Amphenol_132289_EdgeMount_new | Samtec | 1 |

Assembly and Test Procedures

Requirements:

The following are the required materials to assemble WildEDS:

- The design schematic
- Parts outlined on BOM
- Soldering station with:
 - Soldering Iron, Lead-Free Solder, Flux, Hot Air Soldering Station, Lead-Free Solder paste, Soldering oven, and Hot Plate

Procedure:

1. Solar Panel & LiPo Charger:
 - a. Gather components: D1, D2, D3, R1, R2, R3, R6, R7, C13, C14, and U2
 - b. Solder U2 then D1, D2, D3, R1, R2, R3, R6, R7, C13, and C14 using the preferred soldering method.
 - c. Solder the solar panel in the J1 header using a soldering iron.
 - d. Connect the LiPo battery using the J2 header.
2. Linear Regulator:
 - a. Gather components: D4, Q1, R10, R16, C18, C21, and U4
 - b. Solder U4 then D4, Q1, R10, R16, C18, and C21 using the preferred soldering method.
 - c. Solder TP1, TP3, TP5, and TP6 using a soldering iron. Then solder the bridge at JP1.
 - d. Use TP 1 to verify output of 3V3.
 - e. Use TP 3 to verify the functionality of the ground.
 - f. Use TP 5 to verify the functionality of the Solar Panel.
 - g. Use TP 6 to verify the input to the linear regulator is between 3V5 and 4V2.
3. Nano Timer:
 - a. Gather components: Q2, SW2, R18, R21, and U6.
 - b. Solder U6 then Q2, R18, R21, and SW2 using the preferred soldering method.
 - c. Solder TP2 using a soldering iron.
 - d. Use SW2 and TP2 to verify the functionality of the nano timer.
4. RP2040 MCU:
 - a. Gather components: SW1, R4, R5, R9, R13, C1, C2, C3, C4, C5, C6, C7, C8, C9, C10, C11, C12, C16, C17, Crystal oscillator, and U1.
 - b. Solder U1 using the hot plate set to 200 degrees celsius and the hot air station.
 - c. Solder SW1, R4, R5, R9, R13, C1, C2, C3, C4, C5, C6, C7, C8, C9, C10, C11, C12, C16, C17, and the Crystal oscillator using preferred soldering method.
 - d. Solder TP1. will be used later to measure 1V1 from the MCU.
5. Flash Memory
 - a. Gather components: R20, C23, and U7
 - b. Solder U7 then R20 and C23 using the preferred soldering method. Do not populate R22.

- c. Solder J7, the USB connector using a soldering iron.
- 6. Lora Module:
 - a. Gather components: SW3, R17, R19, R23, C20, the Antenna, and U5.
 - b. Solder U5 using the hot plate set to 200 degrees celsius and the hot air station.
 - c. Solder SW3, R17, R19, R23, and C20 using the preferred soldering method. Do not populate L1, C22, and C24.
 - d. Attach the antenna to J8.
 - e. TP7 and TP8 shall be used later to verify the proper functionality of the LoRa Module.
- 7. Temp/Pressure/Humid Sensor:
 - a. Gather components: R14, R15, C15, C19, and U3.
 - b. Solder U3 then solder R14, R15, C15, and C19 using the preferred soldering method.
- 8. Headers:
 - a. Gather components: R8, R11, R12, J3, J4, J5, and J7.
 - b. Solder R8, R11, 12 using the preferred soldering method.
 - c. Solder J3, J4, J5, and J7 using a soldering iron.
 - d. Connect a USB cable into J6 and verify the functionality of the MCU and LoRa module using software and TP1, TP7, and TP8.

Considerations:

Use caution when soldering the MCU and LoRa module as it may overheat.
Avoid using hot air near Headers to avoid melting header.
Practice good solder technique and safety.