Iterative Deepening Depth First Search (DDFS)

0

\* IDDFS is the Search algorithm which performs DFS iteratively.

Here the DFS is run repeatedly with increasing depth limits until the goal is found.

Herative.

Eg:- A

B
C
F
G

1terative. 1

(A) -> level 0

perform DFS

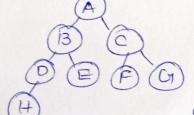
Iterative. 2

A level o B C level o

t perform DFS

A level o

lterative.4



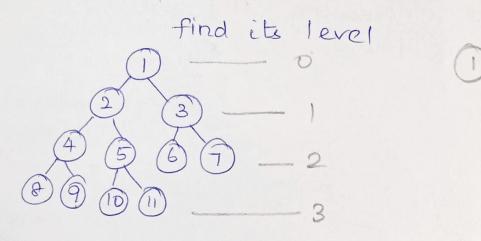
level o

3 om Dfl

2

(F) IDDFS combines DFS's space efficiently and BF's completeness (for finite path) pblms) to get solution path in less memory.

EG:- Groal state: 9.



Sot :-

Stack Status

Perform Dfs. mark 1 as
of 1. No node is visited so pop ct
stack status

POPO [

3

Stack is empty. So terminate. But we didn't breach our goal state. 30 Perform 2nd iteration

iteration 2:- Stack stalus

Olp Seq:-1

1 is visited. adjacent of node 1 is 223. push left child 2 first. Visited 2.

Olp seq:-12 2 1,2

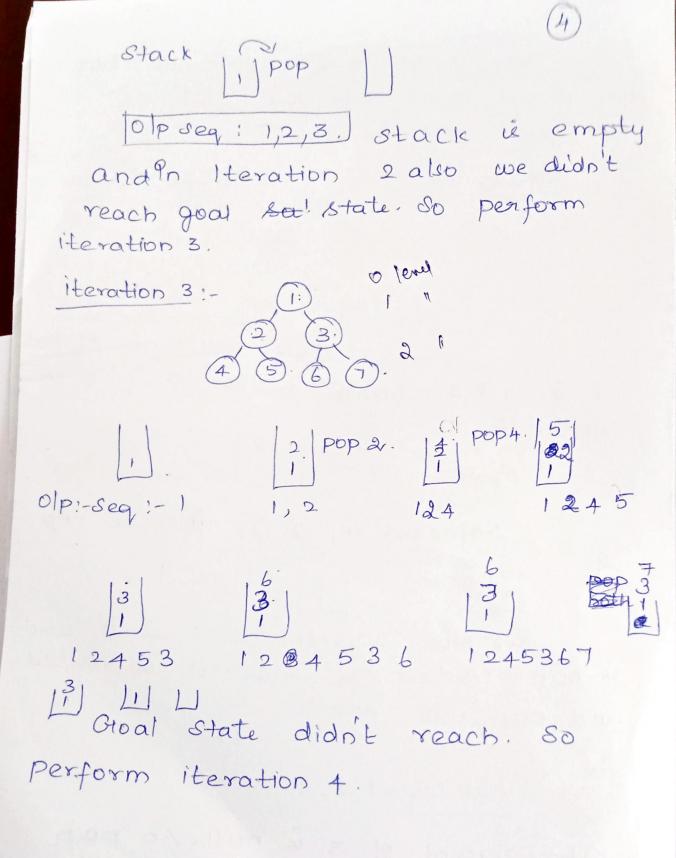
2. Adjacent of 2 is null. so pop.

is not visited. So mark it as visited and push into stack

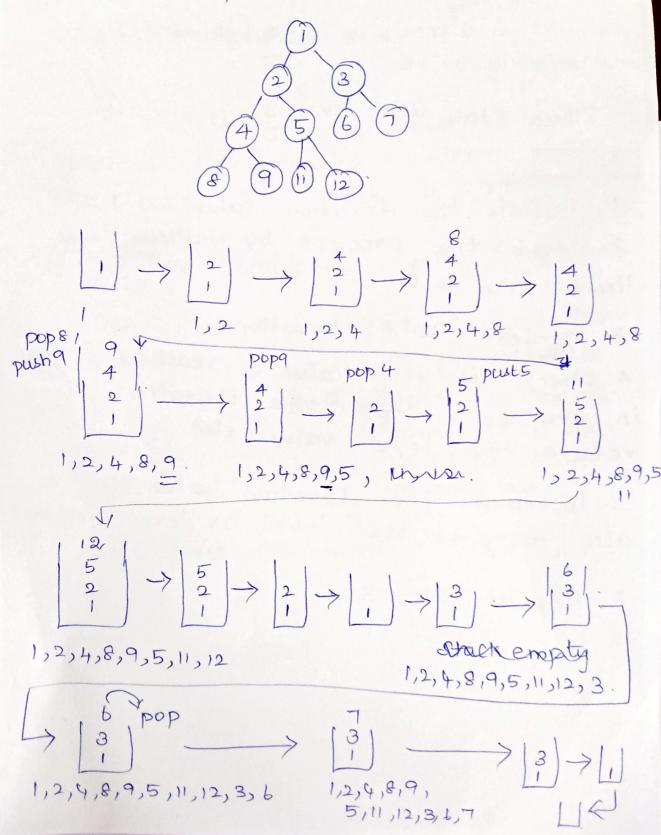
olp seq:-1,2,3

top of stack Adjacent of 3 is null. So pap.

3. [1] Pop [1] > top of Stack is 1, Now
all node of 1 is visited so
pop it.



Iteration 4



Olp seq:
1 2 8 4 9 5 11 12 367

Goal state is in: level. 3.

## AlGI2-

- 1. Initiate the iteration value as 1 2. Start the Process by Setting level limit value to 0.
  - 3. Perform DFS operation
- 4. Check if goal value is reached if goal is reached stop the iteration & return the level value else
- 5. Increase the iteration value by 1 & also increase the level or level limit by 1
- 6. Repeat Step 3



## Performance Evaluation:

- Ocompleteness -> IDDFS is complete as it gives solution
- @ optimalitaty: It does not have optimal sof. because it stops when the first goal node is reached.
  - 3 Time complexity: 0 (bd)

b -> branching factor.

or. no. of nodes

d -> depth of the

Search & ree or.

no. of levels in

Search free

(4) Space complexity: olbd)