

1. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis of \mathbb{V}^3 . Consider the vectors $\mathbf{a} = \mathbf{i} + 2\mathbf{j} - 2\mathbf{k}$ and $\mathbf{b} = 7\mathbf{i} + 4\mathbf{j} + 6\mathbf{k}$. Determine $\mathbf{a} \times \mathbf{b}$ in terms of the given basis vectors.

2. With respect to a right oriented orthonormal basis of \mathbb{V}^3 consider the vectors $\mathbf{a}(3, -1, -2)$ and $\mathbf{b}(1, 2, -1)$. Calculate

$$\mathbf{a} \times \mathbf{b}, \quad (2\mathbf{a} + \mathbf{b}) \times \mathbf{b}, \quad (2\mathbf{a} + \mathbf{b}) \times (2\mathbf{a} - \mathbf{b}).$$

3. Determine the distances between opposite sides of a parallelogram spanned by the vectors $\overrightarrow{AB}(6, 0, 1)$ and $\overrightarrow{AC} = (1.5, 2, 1)$ if the coordinates of the vectors are given with respect to a right oriented orthonormal basis.

4. Consider the vectors $\mathbf{a}(2, 3, -1)$ and $\mathbf{b}(1, -1, 3)$ with respect to an orthonormal basis.

1. Determine the vector subspace $\langle \mathbf{a}, \mathbf{b} \rangle^\perp$.

2. Determine the vector \mathbf{p} which is orthogonal to \mathbf{a} and \mathbf{b} and for which $\mathbf{p} \cdot (2\mathbf{i} - 3\mathbf{j} + 4\mathbf{k}) = 51$.

5. Consider the points $A(1, 2, 0)$, $B(3, 0, -3)$ and $C(5, 2, 6)$ with respect to an orthonormal coordinate system.

1. Determine the area of the triangle ABC .

2. Determine the distance from C to AB .

6. Let ABC be a triangle and let $\mathbf{u} = \overrightarrow{AB}$, $\mathbf{v} = \overrightarrow{BC}$, $\mathbf{w} = \overrightarrow{CA}$. Show that

$$\mathbf{u} \times \mathbf{v} = \mathbf{v} \times \mathbf{w} = \mathbf{w} \times \mathbf{u}.$$

and deduce the law of sines in a triangle.

7. With respect to a right oriented orthonormal coordinate system consider the vectors $\mathbf{a}(2, -3, 1)$, $\mathbf{b}(-3, 1, 2)$ and $\mathbf{c}(1, 2, 3)$. Calculate $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}$ and $\mathbf{a} \times (\mathbf{b} \times \mathbf{c})$.

8. Fix $\mathbf{v} \in \mathbb{V}^3$ and let $\psi : \mathbb{V}^3 \rightarrow \mathbb{V}^3$ be the map $\phi(\mathbf{w}) = \mathbf{v} \times \mathbf{w}$. Is the map linear? Explain why. Give the matrix of ϕ relative to a right oriented orthonormal basis. What changes if we define ϕ by $\phi(\mathbf{w}) = \mathbf{w} \times \mathbf{v}$?

9. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis. Determine the matrices of the linear maps $\phi, \psi : \mathbb{V}^3 \rightarrow \mathbb{V}^3$ defined by $\phi(\mathbf{v}) = \mathbf{w} \times \mathbf{v}$ and $\psi(\mathbf{v}) = \mathbf{v} \times \mathbf{u}$ where

1. $\mathbf{w} = -\mathbf{i} + 3\mathbf{j} + \mathbf{k}$,

2. $\mathbf{w} = \mathbf{i} + \mathbf{k}$,

3. $\mathbf{u} = 2\mathbf{i} - \mathbf{j}$,

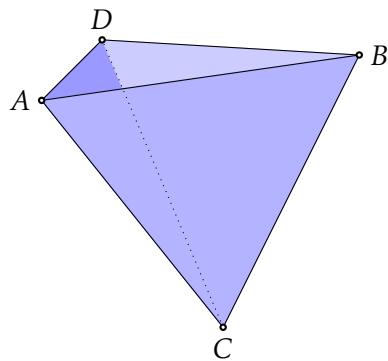
4. $\mathbf{u} = \mathbf{i} + \mathbf{j} + \mathbf{k}$.

10. Prove the following identities:

1. the Jacobi identity,
2. the Lagrange identity,
3. the formula for the cross product of two cross products.

11. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis. Consider the vectors $\mathbf{a} = \mathbf{i} + \mathbf{j}$, $\mathbf{b} = \mathbf{i} - \mathbf{k}$ and $\mathbf{c} = \mathbf{k}$. Determine if

1. $(\mathbf{a}, \mathbf{b}, \mathbf{c})$ is a basis of \mathbb{V}^3 ,
 2. if it is a basis, decide if it is left or right oriented.
- 12.** The points $A(1, 2, -1)$, $B(0, 1, 5)$, $C(-1, 2, 1)$ and $D(2, 1, 3)$ are given with respect to an orthonormal coordinate system. Are the four points coplanar?
- 13.** Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be an orthonormal basis and consider the vectors $\mathbf{u} = -\mathbf{i} + 3\mathbf{j} + \mathbf{k}$ and $\mathbf{w} = \mathbf{k}$. Determine the matrix of the linear map $\phi : \mathbb{V}^3 \rightarrow \mathbb{R}$ defined by $\phi(\mathbf{v}) = [\mathbf{v}, \mathbf{u}, \mathbf{w}]$.
- 14.** Determine the volume of the tetrahedron with vertices $A(2, -1, 1)$, $B(5, 5, 4)$, $C(3, 2, -1)$ and $D(4, 1, 3)$ given with respect to an orthonormal system.



15. The volume of a tetrahedron $ABCD$ is 5. With respect to an orthonormal system $Oxyz$ the vertices are $A(2, 1, -1)$, $B(3, 0, 1)$, $C(2, -1, 3)$ and $D \in Oy$. Determine the coordinates of D .

16. With respect to an orthonormal system consider the vectors $\mathbf{a}(8, 4, 1)$, $\mathbf{b}(2, 2, 1)$ and $\mathbf{c}(1, 1, 1)$. Determine a vector \mathbf{d} satisfying the following properties

1. the angles of \mathbf{d} with \mathbf{a} and with \mathbf{b} are congruent,
2. \mathbf{d} is orthogonal to \mathbf{c} ,
3. $(\mathbf{a}, \mathbf{b}, \mathbf{c})$ and $(\mathbf{a}, \mathbf{b}, \mathbf{d})$ have the same orientation.

1. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis of \mathbb{V}^3 . Consider the vectors $\mathbf{a} = \mathbf{i} + 2\mathbf{j} - 2\mathbf{k}$ and $\mathbf{b} = 7\mathbf{i} + 4\mathbf{j} + 6\mathbf{k}$. Determine $\mathbf{a} \times \mathbf{b}$ in terms of the given basis vectors.

$$\mathbf{a} \times \mathbf{b} = (\mathbf{i} + 2\mathbf{j} - 2\mathbf{k}) \times (7\mathbf{i} + 4\mathbf{j} + 6\mathbf{k})$$

$$= 7\mathbf{i} \times \mathbf{i} + 4\mathbf{i} \times \mathbf{j} + 6\mathbf{i} \times \mathbf{k} +$$

$$+ 14\mathbf{j} \times \mathbf{i} + 8\mathbf{j} \times \mathbf{j} + 12\mathbf{j} \times \mathbf{k} +$$

$$- 14\mathbf{k} \times \mathbf{i} - 8\mathbf{k} \times \mathbf{j} - 12\mathbf{k} \times \mathbf{k}$$

$$= \underbrace{-10\mathbf{i} \times \mathbf{j}}_{= \mathbf{k}} + \underbrace{20\mathbf{i} \times \mathbf{k}}_{= -\mathbf{j}} + \underbrace{20\mathbf{j} \times \mathbf{k}}_{= \mathbf{i}}$$

$$= 20\mathbf{i} - 20\mathbf{j} - 10\mathbf{k}$$



$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 2 & -2 \\ 7 & 4 & 6 \end{vmatrix} = 20\mathbf{i} - 20\mathbf{j} - 10\mathbf{k}$$

2. With respect to a right oriented orthonormal basis of \mathbb{V}^3 consider the vectors $\mathbf{a}(3, -1, -2)$ and $\mathbf{b}(1, 2, -1)$. Calculate

$$\mathbf{a} \times \mathbf{b}, \quad (2\mathbf{a} + \mathbf{b}) \times \mathbf{b}, \quad (2\mathbf{a} + \mathbf{b}) \times (2\mathbf{a} - \mathbf{b}).$$

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & -1 & -2 \\ 1 & 2 & -1 \end{vmatrix} = 5\mathbf{i} + \mathbf{j} + 7\mathbf{k}$$

$(2\mathbf{a} + \mathbf{b}) \times \mathbf{b} =$ you can calculate the components of $2\mathbf{a} + \mathbf{b}$ and a determinant, or

$$= 2\mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{b} = 2\mathbf{a} \times \mathbf{b} = \underbrace{10\mathbf{i} + 2\mathbf{j} + 14\mathbf{k}}_{= 0}$$

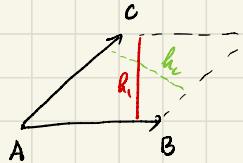
$$(2\mathbf{a} + \mathbf{b}) \times (2\mathbf{a} - \mathbf{b}) = 4 \underbrace{\mathbf{a} \times \mathbf{a}}_{= 0} - 2\mathbf{a} \times \mathbf{b} + 2\mathbf{b} \times \mathbf{a} - \underbrace{\mathbf{b} \times \mathbf{b}}_{= 0} = -4\mathbf{a} \times \mathbf{b} = -20\mathbf{i} - 4\mathbf{j} - 28\mathbf{k}$$

$$-4\mathbf{a} \times \mathbf{b}$$

3. Determine the distances between opposite sides of a parallelogram spanned by the vectors $\vec{AB} = (6, 0, 1)$ and $\vec{AC} = (1.5, 2, 1)$ if the coordinates of the vectors are given with respect to a right oriented orthonormal basis.

Let a be the area of the parallelogram

$$\|\vec{AB} \times \vec{AC}\| = a = h_1, \|\vec{AB}\| = h_2, \|\vec{AC}\|$$



$$\Rightarrow h_1 = \frac{\|\vec{AB} \times \vec{AC}\|}{\|\vec{AB}\|} = \frac{\sqrt{673}}{2\sqrt{37}}$$

$$\|\vec{AB} \times \vec{AC}\| = \left| \begin{array}{ccc} i & j & k \\ 6 & 0 & 1 \\ 1.5 & 2 & 1 \end{array} \right| \| = \left\| -2i - 4.5j + 12k \right\| = \sqrt{4 + \frac{81}{4} + 144} = \frac{\sqrt{673}}{2}$$

$$\|\vec{AB}\| = \sqrt{37}$$

$$\|\vec{AC}\| = \sqrt{\frac{9}{4} + 4 + 1} = \frac{\sqrt{29}}{2}$$

$$\Rightarrow h_2 = \frac{\sqrt{673}}{\sqrt{29}}$$

4. Consider the vectors $\mathbf{a}(2, 3, -1)$ and $\mathbf{b}(1, -1, 3)$ with respect to an orthonormal basis.

1. Determine the vector subspace $\langle \mathbf{a}, \mathbf{b} \rangle^\perp$.
2. Determine the vector \mathbf{p} which is orthogonal to \mathbf{a} and \mathbf{b} and for which $\mathbf{p} \cdot (2i - 3j + 4k) = 51$.

1. Method I take an arbitrary vector $\mathbf{v}(x, y, z)$ and impose the

conditions: $\mathbf{v} \in \langle \mathbf{a}, \mathbf{b} \rangle^\perp \Leftrightarrow \mathbf{v} \perp \mathbf{a}$ and $\mathbf{v} \perp \mathbf{b}$

$\Leftrightarrow \mathbf{v} \cdot \mathbf{a} = 0$ and $\mathbf{v} \cdot \mathbf{b} = 0$

$$\Leftrightarrow \begin{cases} 2x + 3y - z = 0 \\ x - y + 3z = 0 \end{cases}$$

this system allows us to express y and z in terms of x

then $\mathbf{v} \in \langle \mathbf{a}, \mathbf{b} \rangle^\perp \Leftrightarrow \mathbf{v} = \mathbf{v}(x, y(x), z(x))$

Method II $\langle \mathbf{a}, \mathbf{b} \rangle^\perp = \langle \mathbf{a} \times \mathbf{b} \rangle = \left\langle \begin{pmatrix} 8 \\ -7 \\ -5 \end{pmatrix} \right\rangle = \{(8t, -7t, -5t) : t \in \mathbb{R}\}$

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & 3 & -1 \\ 1 & -1 & 3 \end{vmatrix} = 8\mathbf{i} - 7\mathbf{j} - 5\mathbf{k}$$

2. $p \in \langle \mathbf{a}, \mathbf{b} \rangle^\perp \Leftrightarrow p = t \begin{pmatrix} 8 \\ -7 \\ -5 \end{pmatrix}$ for some $t \in \mathbb{R}$

$$p \cdot (2\mathbf{i} - 3\mathbf{j} + 4\mathbf{k}) = 51 \Leftrightarrow (8t\mathbf{i} - 7t\mathbf{j} - 5t\mathbf{k}) \cdot (2\mathbf{i} - 3\mathbf{j} + 4\mathbf{k}) = 51$$

$$\Leftrightarrow 16t + 21t - 20t = 51$$

$$\Leftrightarrow t = \frac{51}{17} = 3$$

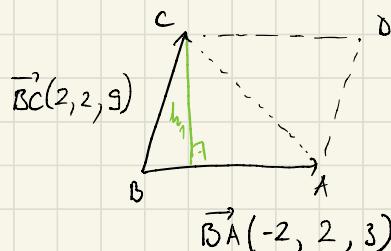
5. Consider the points $A(1, 2, 0)$, $B(3, 0, -3)$ and $C(5, 2, 6)$ with respect to an orthonormal coordinate system.

1. Determine the area of the triangle ABC .

2. Determine the distance from C to AB .

$$\vec{BC} \times \vec{BA} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -2 & 2 & 3 \\ 2 & 2 & 9 \end{vmatrix}$$

$$= 12\mathbf{i} - (-24)\mathbf{j} + (-8)\mathbf{k}$$



$$= 12\mathbf{i} + 24\mathbf{j} - 8\mathbf{k} = 4(3\mathbf{i} + 6\mathbf{j} - 2\mathbf{k})$$

$$\Rightarrow \text{area } \triangle ABC = \frac{\|\vec{BC} \times \vec{BA}\|}{2} = \frac{4 \cdot \sqrt{49}}{2} = 14$$

$$\text{area } \triangle ABC = \frac{h \cdot |\vec{BA}|}{2} = \frac{d(C, \vec{BA}) \cdot \|\vec{BA}\|}{2}$$

$$\Rightarrow d(C, \vec{BA}) = \frac{\|\vec{BC} \times \vec{BA}\|}{\|\vec{BA}\|}$$

$$\|\vec{BA}\| = \sqrt{4+4+9} = \sqrt{17}$$

$$\Rightarrow d(C, \vec{BA}) = \frac{28}{\sqrt{17}}$$

6. Let ABC be a triangle and let $\mathbf{u} = \overrightarrow{AB}$, $\mathbf{v} = \overrightarrow{BC}$, $\mathbf{w} = \overrightarrow{CA}$. Show that

$$\mathbf{u} \times \mathbf{v} = \mathbf{v} \times \mathbf{w} = \mathbf{w} \times \mathbf{u}. \quad (\star)$$

and deduce the law of sines in a triangle.

• we have $\mathbf{u} + \mathbf{v} + \mathbf{w} = \mathbf{0}$

$$\Rightarrow \mathbf{u} = -\mathbf{v} - \mathbf{w}$$

$$\Rightarrow \mathbf{u} \times \mathbf{v} = (-\mathbf{v} - \mathbf{w}) \times \mathbf{v} = \underbrace{-\mathbf{v} \times \mathbf{v}}_{=0} - \mathbf{w} \times \mathbf{v} = -\mathbf{w} \times \mathbf{v} = \mathbf{v} \times \mathbf{w}$$

$$\Rightarrow \mathbf{v} = -\mathbf{u} - \mathbf{w}$$

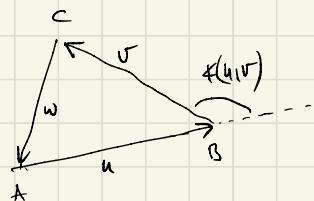
$$\Rightarrow \mathbf{u} \times \mathbf{v} = \mathbf{u} \times (-\mathbf{u} - \mathbf{w}) = -\mathbf{u} \times \mathbf{w} = \mathbf{w} \times \mathbf{u}$$

• from (\star) we have $\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{v} \times \mathbf{w}\| = \|\mathbf{w} \times \mathbf{u}\|$

$$\Leftrightarrow \|\mathbf{u}\| \cdot \|\mathbf{v}\| \cdot \sin \angle(\mathbf{u}, \mathbf{v}) = \|\mathbf{v}\| \cdot \|\mathbf{w}\| \cdot \sin \angle(\mathbf{v}, \mathbf{w}) = \|\mathbf{w}\| \cdot \|\mathbf{u}\| \cdot \sin \angle(\mathbf{w}, \mathbf{u}) \quad | : \|\mathbf{u}\| \cdot \|\mathbf{v}\| \cdot \|\mathbf{w}\|$$

$$\Leftrightarrow \frac{\sin \angle(\mathbf{u}, \mathbf{v})}{\|\mathbf{w}\|} = \frac{\sin \angle(\mathbf{v}, \mathbf{w})}{\|\mathbf{u}\|} = \frac{\sin \angle(\mathbf{w}, \mathbf{u})}{\|\mathbf{v}\|}$$

$$\Leftrightarrow \frac{\sin B}{\|\mathbf{w}\|} = \frac{\sin C}{\|\mathbf{u}\|} = \frac{\sin A}{\|\mathbf{v}\|}$$



7. With respect to a right oriented orthonormal coordinate system consider the vectors $\mathbf{a}(2, -3, 1)$, $\mathbf{b}(-3, 1, 2)$ and $\mathbf{c}(1, 2, 3)$. Calculate $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}$ and $\mathbf{a} \times (\mathbf{b} \times \mathbf{c})$.

$$(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} = (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{b} \cdot \mathbf{c}) \mathbf{a} = (2 \cdot 1 + 3 \cdot 2) \mathbf{b} - (-3 \cdot 1 + 2 \cdot 2) \mathbf{a}$$

$$= - \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix} - 5 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} = \begin{bmatrix} -7 \\ 14 \\ -3 \end{bmatrix}$$

$$\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{c} = - \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix} + 7 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 10 \\ 13 \\ 19 \end{bmatrix}$$

8. Fix $\mathbf{v} \in \mathbb{V}^3$ and let $\psi : \mathbb{V}^3 \rightarrow \mathbb{V}^3$ be the map $\phi(\mathbf{w}) = \mathbf{v} \times \mathbf{w}$. Is the map linear? Explain why. Give the matrix of ϕ relative to a right oriented orthonormal basis. What changes if we define $\phi(\mathbf{w}) = \mathbf{w} \times \mathbf{v}$?

- The map is linear. During the lecture we showed Prop 2.5 from which it follows that

$$\phi(\lambda \mathbf{u} + \beta \mathbf{w}) = \mathbf{v} \times (\lambda \mathbf{u} + \beta \mathbf{w}) = \lambda \mathbf{v} \times \mathbf{u} + \beta \mathbf{v} \times \mathbf{w} = \lambda \phi(\mathbf{u}) + \beta \phi(\mathbf{w}) \quad \begin{array}{l} \# \text{ } \lambda, \beta \in \mathbb{R} \\ \# \text{ } \mathbf{u}, \mathbf{w} \in \mathbb{V}^3 \end{array}$$

- let $\mathbf{v} = v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}$ then $\phi(\mathbf{i}) = (v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}) \times \mathbf{i}$

$\begin{matrix} & k \\ & | \\ i & \end{matrix}$

$$= v_1 \mathbf{i} \times \mathbf{i} + v_2 \mathbf{j} \times \mathbf{i} + v_3 \mathbf{k} \times \mathbf{i}$$

$$= -v_2 \mathbf{k} + v_3 \mathbf{j}$$

similar $\phi(\mathbf{j}) = v_1 \mathbf{k} - v_3 \mathbf{i}$

$$\phi(\mathbf{k}) = -v_1 \mathbf{j} + v_2 \mathbf{i}$$

\Rightarrow the matrix of ϕ with respect to the basis $\mathbf{i}, \mathbf{j}, \mathbf{k}$ is

$$\begin{bmatrix} 0 & -v_3 & v_2 \\ v_3 & 0 & -v_1 \\ -v_2 & v_1 & 0 \end{bmatrix}$$

if we consider $\phi(\mathbf{w}) = \mathbf{w} \times \mathbf{v}$ then, since $\mathbf{w} \times \mathbf{v} = -\mathbf{v} \times \mathbf{w}$,

the matrix of ϕ with respect to the basis $\mathbf{i}, \mathbf{j}, \mathbf{k}$ is

$$\begin{bmatrix} 0 & v_3 & -v_2 \\ -v_3 & 0 & v_1 \\ v_2 & v_1 & 0 \end{bmatrix}$$

9. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis. Determine the matrices of the linear maps $\phi, \psi : \mathbb{V}^3 \rightarrow \mathbb{V}^3$ defined by $\phi(\mathbf{v}) = \mathbf{w} \times \mathbf{v}$ and $\psi(\mathbf{v}) = \mathbf{v} \times \mathbf{u}$ where

1. $\mathbf{w} = -\mathbf{i} + 3\mathbf{j} + \mathbf{k}$,
2. $\mathbf{w} = \mathbf{i} + \mathbf{k}$,
3. $\mathbf{u} = 2\mathbf{i} - \mathbf{j}$,
4. $\mathbf{u} = \mathbf{i} + \mathbf{j} + \mathbf{k}$.

We can do a similar calculation as in the previous exercise

But since we already computed that matrix one could also just

$$\text{use } \begin{bmatrix} 0 & -w_3 & w_2 \\ w_3 & 0 & -w_1 \\ -w_2 & w_1 & 0 \end{bmatrix} \text{ for } \phi$$

so, for 1, the matrix of ϕ is $\begin{bmatrix} 0 & -1 & 3 \\ 1 & 0 & 1 \\ -3 & -1 & 0 \end{bmatrix}$

10. Prove the following identities:

1. the Jacobi identity,
2. the Lagrange identity,
3. the formula for the cross product of two cross products.

1) $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} + (\mathbf{b} \times \mathbf{c}) \times \mathbf{a} + (\mathbf{c} \times \mathbf{a}) \times \mathbf{b} = \mathbf{0}$?

$$(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{b} \cdot \mathbf{c})\mathbf{a}$$

$$(\mathbf{b} \times \mathbf{c}) \times \mathbf{a} = (\mathbf{b} \cdot \mathbf{a})\mathbf{c} - (\mathbf{c} \cdot \mathbf{a})\mathbf{b}$$

$$(\mathbf{c} \times \mathbf{a}) \times \mathbf{b} = (\mathbf{c} \cdot \mathbf{b})\mathbf{a} - (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$$

$$(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} + (\mathbf{b} \times \mathbf{c}) \times \mathbf{a} + (\mathbf{c} \times \mathbf{a}) \times \mathbf{b} = \mathbf{0}$$

$$2) (a \times b) \cdot (c \times d) = (a \cdot c)(b \cdot d) - (b \cdot c)(a \cdot d)$$

$$\text{let } a = (a_1, a_2, a_3) \quad b = (b_1, b_2, b_3) \quad c = (c_1, c_2, c_3) \quad d = (d_1, d_2, d_3)$$

$$\text{then } a \times b = \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = i(a_2 b_3 - b_2 a_3) + j(a_3 b_1 - a_1 b_3) + k(a_1 b_2 - a_2 b_1)$$

$$\text{and } c \times d = i(c_2 d_3 - d_2 c_3) + j(c_3 d_1 - d_3 c_1) + k(c_1 d_2 - d_1 c_2)$$

so

$$(a \times b) \cdot (c \times d) = (a_2 b_3 - b_2 a_3)(c_2 d_3 - d_2 c_3) + (a_3 b_1 - b_3 a_1)(c_3 d_1 - d_3 c_1) + (a_1 b_2 - b_1 a_2)(c_1 d_2 - d_1 c_2)$$

$$\begin{aligned} &= \cancel{a_2 b_3 c_2 d_3} - a_2 \cancel{b_3 d_2 c_3} - b_2 a_3 c_2 d_3 + \cancel{b_2 a_3 d_2 c_3} + \\ &+ \cancel{a_3 b_1 c_3 d_1} - a_3 b_1 d_3 c_1 - b_3 a_1 c_3 d_1 + \cancel{b_3 a_1 d_3 c_1} + \\ &+ \cancel{a_1 b_2 c_1 d_2} - a_1 b_2 d_1 c_2 - b_1 a_2 c_1 d_2 + \cancel{b_1 a_2 d_1 c_2} \end{aligned} \quad \Bigg\}$$

$$(a \cdot c)(b \cdot d) - (b \cdot c)(a \cdot d) = (a_1 c_1 + a_2 c_2 + a_3 c_3)(b_1 d_1 + b_2 d_2 + b_3 d_3) -$$

$$- (b_1 c_1 + b_2 c_2 + b_3 c_3)(a_1 d_1 + a_2 d_2 + a_3 d_3)$$

$$= \cancel{a_1 c_1 b_1 d_1} + \cancel{a_1 c_1 b_2 d_2} + \cancel{a_1 c_1 b_3 d_3} +$$

$$+ \cancel{a_2 c_2 b_1 d_1} + \cancel{a_2 c_2 b_2 d_2} + \cancel{a_2 c_2 b_3 d_3}$$

$$+ \cancel{a_3 c_3 b_1 d_1} + \cancel{a_3 c_3 b_2 d_2} + \cancel{a_3 c_3 b_3 d_3}$$

$$- \cancel{b_1 c_1 a_1 d_1} - \cancel{b_1 c_1 a_2 d_2} - \cancel{b_1 c_1 a_3 d_3}$$

$$- \cancel{b_2 c_2 a_1 d_1} - \cancel{b_2 c_2 a_2 d_2} - \cancel{b_2 c_2 a_3 d_3}$$

$$- \cancel{b_3 c_3 a_1 d_1} - \cancel{b_3 c_3 a_2 d_2} - \cancel{b_3 c_3 a_3 d_3}$$

one checks
that these
are equal

$$3) (\mathbf{a} \times \mathbf{b}) \times (\mathbf{c} \times \mathbf{d}) = \mathbf{b} \cdot [\mathbf{a}, \mathbf{c}, \mathbf{d}] - \mathbf{a} \cdot [\mathbf{b}, \mathbf{c}, \mathbf{d}] = \mathbf{c} \cdot [\mathbf{a}, \mathbf{b}, \mathbf{d}] - \mathbf{d} \cdot [\mathbf{a}, \mathbf{b}, \mathbf{c}]$$

One can do a calculation in coordinates as above

or

$$\begin{aligned} (\mathbf{a} \times \mathbf{b}) \times (\mathbf{c} \times \mathbf{d}) &= (\underbrace{\mathbf{a} \cdot (\mathbf{c} \times \mathbf{d})}_{\substack{(\mathbf{c} \times \mathbf{d}) \cdot \mathbf{a}}} \mathbf{b} - \underbrace{(\mathbf{b} \cdot (\mathbf{c} \times \mathbf{d})) \cdot \mathbf{a}}_{\substack{(\mathbf{c} \times \mathbf{d}) \cdot \mathbf{b}}} \\ &\quad \substack{\text{"} \\ \text{[c, d, a]} \\ \text{"} \\ \text{[c, d, b]} \\ \text{"}} \\ &= [\mathbf{a}, \mathbf{c}, \mathbf{d}] \mathbf{b} - [\mathbf{b}, \mathbf{c}, \mathbf{d}] \mathbf{a} \end{aligned}$$

and

$$\begin{aligned} (\mathbf{a} \times \mathbf{b}) \times (\mathbf{c} \times \mathbf{d}) &= \underbrace{[(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{d}] \cdot \mathbf{c}}_{\substack{\text{"} \\ \text{[a, b, d] c}}} - \underbrace{[(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c}] \cdot \mathbf{d}}_{\substack{\text{"} \\ \text{[a, b, c] d}}} \\ &= [\mathbf{a}, \mathbf{b}, \mathbf{d}] \mathbf{c} - [\mathbf{a}, \mathbf{b}, \mathbf{c}] \mathbf{d} \end{aligned}$$

11. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be a right oriented orthonormal basis. Consider the vectors $\mathbf{a} = \mathbf{i} + \mathbf{j}$, $\mathbf{b} = \mathbf{i} - \mathbf{k}$ and $\mathbf{c} = \mathbf{k}$. Determine if

1. $(\mathbf{a}, \mathbf{b}, \mathbf{c})$ is a basis of \mathbb{V}^3 ,
2. if it is a basis, decide if it is left or right oriented.

$$\mathbf{a} = (1, 1, 0) \quad \mathbf{b} = (1, 0, -1) \quad \mathbf{c} = (0, 0, 1)$$

$$[\mathbf{a}, \mathbf{b}, \mathbf{c}] = \begin{vmatrix} 1 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{vmatrix} = -1 \neq 0 \Rightarrow \mathbf{a}, \mathbf{b}, \mathbf{c} \text{ is a basis}$$

$< 0 \Rightarrow \mathbf{a}, \mathbf{b}, \mathbf{c} \text{ is left oriented}$

12. The points $A(1, 2, -1)$, $B(0, 1, 5)$, $C(-1, 2, 1)$ and $D(2, 1, 3)$ are given with respect to an orthonormal coordinate system. Are the four points coplanar?

A, B, C, D coplanar $\Leftrightarrow \vec{AB}, \vec{AC}, \vec{AD}$ linearly dependent

$$\begin{vmatrix} -1 \\ -1 \\ 6 \end{vmatrix} \quad \begin{vmatrix} -2 \\ 0 \\ 2 \end{vmatrix} \quad \begin{vmatrix} 1 \\ -1 \\ 4 \end{vmatrix}$$

$$\Leftrightarrow \begin{vmatrix} -1 & -1 & 6 \\ -2 & 0 & 2 \\ 1 & -1 & 4 \end{vmatrix} = 0$$

$$12 - 2 - 8 - 2 = 0 \quad \text{true}$$

13. Let $(\mathbf{i}, \mathbf{j}, \mathbf{k})$ be an orthonormal basis and consider the vectors $\mathbf{u} = -\mathbf{i} + 3\mathbf{j} + \mathbf{k}$ and $\mathbf{w} = \mathbf{k}$. Determine the matrix of the linear map $\phi : \mathbb{V}^3 \rightarrow \mathbb{R}$ defined by $\phi(\mathbf{v}) = [\mathbf{v}, \mathbf{u}, \mathbf{w}]$.

Let $\mathbf{v} = (v_1, v_2, v_3)$

$$\phi(\mathbf{v}) = (\mathbf{v} \times \mathbf{u}) \cdot \mathbf{w} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ v_1 & v_2 & v_3 \\ -1 & 3 & 1 \end{vmatrix} \cdot \mathbf{k} = \begin{vmatrix} v_2 & v_3 \\ 3 & 1 \end{vmatrix} \mathbf{i} \cdot \mathbf{k} - \begin{vmatrix} v_1 & v_3 \\ -1 & 1 \end{vmatrix} \mathbf{j} \cdot \mathbf{k} + \begin{vmatrix} v_1 & v_2 \\ -1 & 3 \end{vmatrix} \mathbf{k} \cdot \mathbf{k}$$

$$= 3v_1 + v_2$$

$$\text{so } \phi(1, 0, 0) = 3$$

$$\phi(0, 1, 0) = 1$$

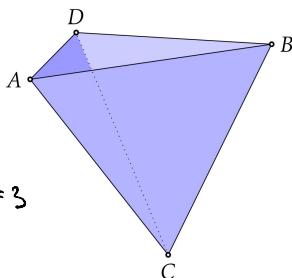
$$\phi(0, 0, 1) = 0$$

so the matrix is $[3 \ 1 \ 0]$

14. Determine the volume of the tetrahedron with vertices $A(2, -1, 1)$, $B(5, 5, 4)$, $C(3, 2, -1)$ and $D(4, 1, 3)$ given with respect to an orthonormal system.

$$\left| \frac{1}{6} \begin{vmatrix} \vec{AB} & \vec{AC} & \vec{AD} \end{vmatrix} \right|$$

$$\left| \frac{1}{6} \begin{vmatrix} 3 & 6 & 3 \\ 1 & 3 & -2 \\ 2 & 2 & 2 \end{vmatrix} \right| = |-8| = 8$$



15. The volume of a tetrahedron $ABCD$ is 5. With respect to an orthonormal system $Oxyz$ the vertices are $A(2, 1, -1)$, $B(3, 0, 1)$, $C(2, -1, 3)$ and $D \in Oy$. Determine the coordinates of D .

$$D \in Oy \Rightarrow D(0, \lambda, 0)$$

the volume of the tetrahedron is $V = \left| \frac{1}{6} \begin{vmatrix} 1 & -1 & 2 \\ 0 & -2 & 4 \\ -2 & 2 & 1 \end{vmatrix} \right| = \frac{1}{6} |-2 + 8 - 8 - 4(-1)| = \frac{1}{6} |2 - 4\lambda|$

$$\text{so } V = \frac{|1 - 2\lambda|}{3} \Leftrightarrow 15 = |1 - 2\lambda| \Leftrightarrow \begin{cases} \lambda = -7 \\ \lambda = 8 \end{cases}$$

16. With respect to an orthonormal system consider the vectors $\mathbf{a}(8, 4, 1)$, $\mathbf{b}(2, 2, 1)$ and $\mathbf{c}(1, 1, 1)$. Determine a vector \mathbf{d} satisfying the following properties

1. the angles of \mathbf{d} with \mathbf{a} and with \mathbf{b} are congruent,
2. \mathbf{d} is orthogonal to \mathbf{c} ,
3. $(\mathbf{a}, \mathbf{b}, \mathbf{c})$ and $(\mathbf{a}, \mathbf{b}, \mathbf{d})$ have the same orientation.

$$\text{let } \mathbf{d} = (d_1, d_2, d_3)$$

$$\angle(\mathbf{d}, \mathbf{a}) = \angle(\mathbf{d}, \mathbf{b}) \Leftrightarrow \cos \angle(d_1, a) = \cos \angle(d_1, b)$$

$$\Leftrightarrow \frac{\mathbf{a} \cdot \mathbf{d}}{\|\mathbf{a}\| \cdot \|\mathbf{d}\|} = \frac{\mathbf{b} \cdot \mathbf{d}}{\|\mathbf{b}\| \cdot \|\mathbf{d}\|}$$

$$\Leftrightarrow \frac{8d_1 + 4d_2 + d_3}{3} = \frac{2d_1 + 2d_2 + d_3}{3}$$

$$\Leftrightarrow 2d_1 - 2d_2 - 2d_3 = 0$$

$$\Leftrightarrow \begin{aligned} d_1 - d_2 - d_3 &= 0 \\ d \cdot c &= 0 \end{aligned} \quad \Rightarrow \quad \begin{aligned} d_1 &= 0 \\ d_2 &= -d_3 \end{aligned} \quad \Rightarrow \quad \mathbf{d} = (0, \lambda, -\lambda)$$

$$\begin{vmatrix} 8 & 4 & 1 \\ 2 & 2 & 1 \\ 1 & 1 & 1 \end{vmatrix} = 16 + 2 + 4 - 2 - 8 - 8 = 4 \Rightarrow \mathbf{a}, \mathbf{b}, \mathbf{c} \text{ is right oriented}$$

$$\begin{vmatrix} 8 & 4 & 1 \\ 2 & 2 & 1 \\ 0 & \lambda & -\lambda \end{vmatrix} = -16\lambda + 2\lambda + 8\lambda - 8\lambda = -14\lambda \text{ should be positive}$$

\Rightarrow all possible vectors are $d(0, \lambda, -\lambda)$ with $\lambda < 0$