

$$\min_{x \in \mathbb{R}^n} \|x\|_1 + \frac{1}{2\alpha} \|x - y\|_2^2$$

where  
 $\alpha > 0$   
 is a given scalar  
 $y$  is a known vector

Task 5  
 HW 4  
 Optimization

Page 1

## 1. Analyze the convexity

1.1. Feasible set is convex:  $x \in \mathbb{R}^n$

1.2.  $\|x\|_1$  - convex

$\|x - y\|_2^2$  - convex

and we know that the sum of convex functions with non-negative coefficients is convex

function  $\left(\|x\|_1 + \frac{1}{2\alpha} \|x - y\|_2^2\right) > 0$  because  $\alpha > 0$  according by condition, therefore objective function is convex

1.3 If feasible set is convex and objective function is convex

$\Rightarrow$  we have convex optimization problem.

## 2. Analyze smoothness

2.1  $\|x\|_1 = \sum_i |x_i|$  - not smooth function, not differentiable

2.2.  $\|x - y\|_2^2$  - smooth function

2.3.  $\left\{ \begin{array}{l} \text{Objective function} \\ \|x\|_1 + \frac{1}{2\alpha} \|x - y\|_2^2 \end{array} \right\} \rightarrow$  not smooth (not differentiable) function

3. Compose equivalent differentiable problem

$$\min_{x \in \mathbb{R}^n} \|x\|_1 + \frac{1}{2\alpha} \|x - y\|_2^2$$

because  $\|x\|_1 = \sum_i |x_i|$

we can introduce an additional variable  $t_i$

$$|x_i| = t_i$$

A)  $\min_x \|x\|_1 + \frac{1}{2\alpha} \|x - y\|_2^2$

$\Downarrow$

$$\min_{(x, t)} \sum_i t_i + \frac{1}{2\alpha} \|x - y\|_2^2$$

s.t.  $|x_i| = t_i$

B) We can ~~is~~ replace equalities on inequalities  
 $|x_i| = t_i$

$$|x_i| \leq t_i$$

and we get an equivalent optimization problem with constraints with inequality.

$$\begin{aligned} \min_{(x, t)} \quad & \sum_i t_i + \frac{1}{2\alpha} \|x - y\|_2^2 \\ \text{s.t.} \quad & |x_i| \leq t_i \end{aligned} \quad \begin{cases} x_i \leq t_i \\ -x_i \leq t_i \end{cases}$$

in a differentiable form.

Task 5

HW4

Optimization

Page 2



4. Write the KKT conditions:

$$\begin{aligned} \min_{(x, t)} \quad & \frac{1}{2\alpha} \|x - y\|_2^2 + \sum_i t_i \\ \text{s.t.} \quad & |x_i| \leq t_i \quad \begin{cases} x_i \leq t_i \\ -x_i \leq t_i \end{cases} \end{aligned}$$

$$x_i - t_i \leq 0$$

$$-x_i - t_i \leq 0$$

$$\mu_i (x_i - t_i) = 0$$

$$v_i (-x_i - t_i) = 0$$

$$\mu_i, v_i \geq 0$$

$$\nabla_{t, x} L_{t, x}(x, t, \mu, v) = 0$$

where

$$L(x, t, \mu, v) = \frac{1}{2\alpha} \|x - y\|_2^2 + \sum_i t_i + \mu_i \sum_i (x_i - t_i) + v_i \sum_i (-x_i - t_i)$$

Task 5

HW4

Optimization

Page 3

5. Solve the KKT system and reconstruct the solution of the original problem.  
Pay special to the dependence of  $x^*$  on  $\alpha$  and  $y$ .

Task 5  
HW 4  
Optimization  
Page 4

$$L = \frac{1}{2\alpha} \|x - y\|_2^2 + \sum_i t_i + \sum_i \mu_i (x_i - t_i) + \sum_i \nu_i (-x_i - t_i)$$

$$= \sum_i (x_i - y_i)^2$$

$$\frac{\partial L}{\partial x_k} = \frac{1}{2\alpha} 2(x_k - y_k) + \mu_k - \nu_k = 0 \quad (x_k - y_k) + \alpha \mu_k - \alpha \nu_k = 0$$

$$\frac{\partial L}{\partial t_k} = 1 - \mu_k - \nu_k = 0 \quad \begin{aligned} \mu_k + \nu_k &= 1 \\ \text{if } \mu_k &= 0 \quad \nu_k = 1 \\ \text{if } \nu_k &= 0 \quad \mu_k = 1 \end{aligned}$$

$\mu_i = 0 \quad \nu_i = \pm$  (I)

$$x_i - y_i - \alpha \nu_i = 0$$

$$x_i - y_i = \alpha \quad x_i = y_i + \alpha$$

$$\nu_i (-x_i - t_i) = 0$$

$$\pm (-x_i - t_i) = 0$$

$$x_i = -t_i$$

$$\mu_i = 0$$

$$\nu_i = \pm$$

$$x_i = -t_i$$

$$x_i = y_i + \alpha$$

$$t_i = -y_i - \alpha$$

$$\mu_i, \nu_i \geq 0 \text{ ok}$$

$$x_i - y_i - \alpha = 0 \text{ ok}$$

$$1 - 0 - \pm = 0 \text{ ok}$$

$\mu_i = \pm \quad \nu_i = 0$  (II)

$$x_i - y_i + \alpha \cdot 1 = 0$$

$$x_i = y_i - \alpha$$

$$\mu_i (x_i - t_i) = 0$$

$$\pm (x_i - t_i) = 0$$

$$x_i = t_i$$

$$\mu_i = \pm$$

$$\nu_i = 0$$

$$x_i = t_i$$

$$x_i = y_i - \alpha$$

$$t_i = y_i - \alpha$$

$$\mu_i, \nu_i \geq 0 \text{ ok}$$

$$x_i - y_i + \alpha = 0 \text{ ok}$$

$$1 - \pm - 0 = 0 \text{ ok}$$



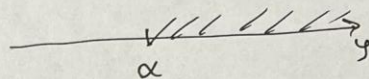
⑤ Part II reconstruct the solution of the original problem

Task 5  
HW4  
Optimization  
Page 5

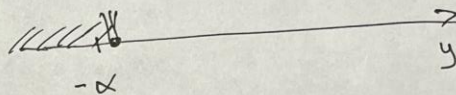
Because in the original problem we have  $\|X\|_1 = \sum_i |x_i|$  and since a module is a "special" function, we need to consider under what conditions  $x=0$ ,  $x>0$  and  $x<0$ .

Now we know, that (I)  $x_i = y_i + \alpha$  ( $\alpha > 0$ )  
(II)  $x_i = y_i - \alpha$

① If  $y_i > \alpha \Rightarrow x_i = y_i - \alpha > 0$



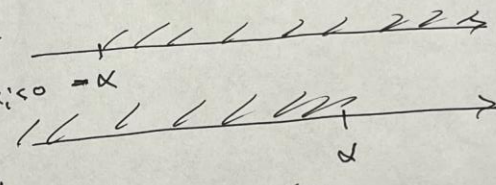
② if  $y_i < -\alpha \Rightarrow x_i = y_i + \alpha < 0$



③ if  $y_i > -\alpha$  and  $y_i \leq \alpha$

$x_i = (y_i + \alpha) > 0$

$y_i \leq \alpha$  ( $y_i - \alpha$ )



then consider the interval

$$-\alpha < y < \alpha$$

in which we have contradiction  $x_i < 0$  and  $x_i > 0$  simultaneously. To eliminate the contradiction, it is necessary to define  $x$  equal to zero for  $-\alpha < y_i < \alpha$ .

$$x_i^* = \begin{cases} y_i - \alpha, & y_i > \alpha \quad (x > 0) \\ 0, & |y_i| \leq \alpha \quad (-\alpha < y < \alpha) \\ y_i + \alpha, & y_i < -\alpha \quad (x < 0) \end{cases}$$



6. Explain why this point is a solution or provide additional analysis

Task 5  
HW4  
Optimization  
Page 6

Consider the behavior of the objective function on a feasible set. Since our function is convex on a feasible set, we need to consider three intervals:

1. At  $x < 0$ , our convex function decreases monotonically (gradient  $< 0$ , Hessian is positive definite everywhere). For a convex function on the interval of monotonous decrease, any critical point is a minimum point. (When the function is limited only to the right). In our case, such a point is  $x = y + \alpha$ .

2. When  $x = 0$ . As we see from point 5 of this solution, for  $x = 0$ ,  $y$  takes values from  $-\alpha$  to  $+\alpha$ , and the value  $f(0) = \frac{y^2}{2\alpha}$ . If we consider the  $y$  as a function of  $\alpha$  (quadratic in  $\alpha$ ), we get that the value of our objective function is proportional to the value of the constant  $\alpha$  - this means that the function itself is constant at this interval, with a predetermined  $\alpha$ , as provided in the condition of the problem. That is, the function is constant (for each  $\alpha$ ) and  $x = 0$  is a solution minimizing our objective function.

3. For  $x > 0$ , our convex function increases monotonically (gradient  $> 0$ , Hessian is positive everywhere). For a convex function on a interval of monotonic increase, any critical point is a minimum point (when the function is limited to the left and not limited to the right). In our case, this is the point  $x = y - \alpha$ .

In addition to what was written in part 5 on page 6, I would like to note that in KKT we have differentiable convex problem with affine constraints.

And this means that we have the necessary and sufficient conditions for the found point  $x^*$  to be the solution of the optimal problem.

Task 5

HW4

Optimization

Page 6.2



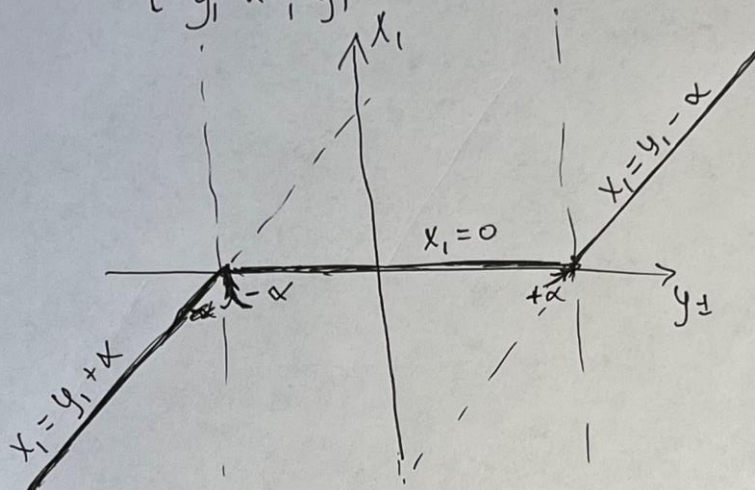
**Bonus** Plot the solution in the case of  $u=1$  and explain why the problem is called "soft thresholding".

Task 5  
HW4  
Optimization

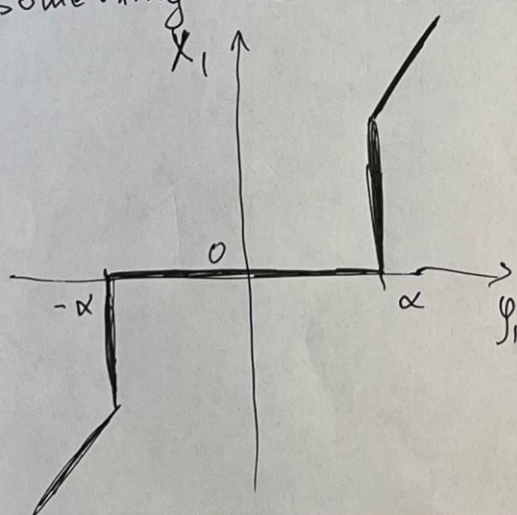
Page 7

$$u=1$$

$$x_i^* = \begin{cases} y_i + \alpha, & y_i < -\alpha \\ 0, & |y_i| \leq \alpha \\ y_i - \alpha, & y_i > \alpha \end{cases}$$



As we can see, the solution has the form of a soft threshold, in contrast to the case of a hard threshold, which looks something like this:



And since the graphical representation of the solution to this problem is in the form of a soft threshold, the problem is called a "soft threshold" problem.