

Identificarea Sistemelor

LABORATOR 1

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PROBLEMA 1

Am inceput laboratorul prin declararea datelor necesare pentru y si u.

```
%DECLARARE DATE
```

```
ny = 2; %numarul de iesiri
nu = 3; %numarul de intrari
nr_esantioane = 200; %numarul de esantioane
index = (1:nr_esantioane)'; %momente de esantionare

date_y = randn(nr_esantioane,ny); %date pe canalele de masura de
iesire
y = [index, date_y]; %datele finale de iesire

date_u = randn(nr_esantioane,nu); %date pe canalele de masura de
intrare
u = [index, date_u]; %datele finale de intrare
```

1.1 Date introduse pentru construirea unui obiect de tip IDDATA folosind functia make_DATA (y).

```
DATA_1 = make_DATA (y); //ny=1;
<MAKE_DATA>:

* Insert the data name block [ENTER means 'DATA']: Data_1
* Insert data notes (ENTER means none): Notes
* Insert the experiment name (ENTER means none): Experiment_1
* Insert the time unit (ENTER means none): s
* Insert the starting date in format <dd-mm-yyy HH:MM:SS> (ENTER means NOW): 01-01-2024
* Insert data name on channel 1 (ENTER means none): Acceleratie
* Insert unit on channel 1 (ENTER means none): m/s^2

<MAKE_DATA>: Data saved in file <Data_1.MAT>.

DATA_1 =

Experiment Experiment_1. Time domain data set with 200 samples.
Sample time: 1 seconds
Name: Data_1

Outputs          Unit (if specified)
  Acceleratie      m/s^2
```

Fig 1.1.

1.2 Date introduse pentru construirea unui obiect de tip IDDATA folosind functia make_DATA_modificat (y,u) cu o intrare si o iesire.

```
DATA_2 = make_DATA_modificat (y, u); //ny=nu=1;
```

```
<MAKE_DATA>:
```

```
* Insert the data name block [ENTER means 'DATA']: Data_2
* Insert data notes (ENTER means none): Notes
* Insert the experiment name (ENTER means none): Experiment_2
* Insert the time unit (ENTER means none): s
* Insert the starting date in format <dd-mmm-yyyy HH:MM:SS> (ENTER means NOW): 01-01-2024
* Insert data name on channel - OUTPUT 1 (ENTER means none): Acceleratie
* Insert unit on channel - OUTPUT 1 (ENTER means none): m/s^2
* Insert data name on channel - INPUT 1 (ENTER means none): Viteza
* Insert unit on channel - INPUT 1 (ENTER means none): m/s
```

```
<MAKE_DATA>: Data saved in file <Data_2.MAT>.
```

```
DATA_2 =
```

```
Experiment Experiment_2. Time domain data set with 200 samples.
```

```
Sample time: 1 seconds
```

```
Name: Data_2
```

Outputs	Unit (if specified)
Acceleratie	m/s^2

Inputs	Unit (if specified)
Viteza	m/s

Fig 1.2.

1.3 Date introduse pentru construirea unui obiect de tip IDDATA folosind functia make_DATA_modificat (y,u), dar cu mai multe intrari si iesiri.

```
DATA_3 = make_DATA_modificat (y, u); //ny=2, nu=3;
```

```
<MAKE_DATA>:
```

```
* Insert the data name block [ENTER means 'DATA']: Data_3
* Insert data notes (ENTER means none): Notes
* Insert the experiment name (ENTER means none): Experiment_3
* Insert the time unit (ENTER means none): s
* Insert the starting date in format <dd-mm-yyyy HH:MM:SS> (ENTER means NOW):
* Insert data name on channel - OUTPUT 1 (ENTER means none): o1
* Insert unit on channel - OUTPUT 1 (ENTER means none): s
* Insert data name on channel - OUTPUT 2 (ENTER means none): o2
* Insert unit on channel - OUTPUT 2 (ENTER means none): m
* Insert data name on channel - INPUT 1 (ENTER means none): i1
* Insert unit on channel - INPUT 1 (ENTER means none): kg
* Insert data name on channel - INPUT 2 (ENTER means none): i2
* Insert unit on channel - INPUT 2 (ENTER means none): c
* Insert data name on channel - INPUT 3 (ENTER means none): i3
* Insert unit on channel - INPUT 3 (ENTER means none): l
```

```
<MAKE_DATA>: Data saved in file <Data_3.MAT>.
```

```
DATA_3 =
```

```
Experiment Experiment_3. Time domain data set with 200 samples.
```

```
Sample time: 1 seconds
```

```
Name: Data_3
```

Outputs	Unit (if specified)
o1	s
o2	m

Inputs	Unit (if specified)
i1	kg
i2	c
i3	l

Fig 1.3.

PROBLEMA 2

Am proiectat rutina **make_IDSS.m**, care contruieste un obiect de tip IDSS.

In urmatoarul exemplu am folosit DATA_2 si am redat **reprezentarea pe stare**.

```
Obiect_IDSS = make_IDSS (DATA_2);
```

Obiect_IDSS =

Discrete-time identified state-space model:

$$x(t+T_s) = A x(t) + B u(t) + K e(t)$$

$$y(t) = C x(t) + D u(t) + e(t)$$

A =

	x1	x2	x3	x4	x5	x6	x7
x1	-0.811	-0.006841	0.2578	0.4961	0.09496	0.04078	-0.01728
x2	-0.1285	0.8016	-0.5324	-0.02365	-0.07716	-0.1251	0.09956
x3	-0.2003	0.3812	0.5085	-0.4528	-0.3763	-0.07108	-0.2172
x4	0.07073	0.2035	0.3373	-0.07501	0.7566	0.6743	-0.1417
x5	-0.06164	-0.152	-0.02912	-0.2317	-0.504	0.5673	0.2904
x6	0.3816	0.1997	0.5062	0.1959	-0.1489	-0.2305	0.1301
x7	-0.08345	0.1518	0.09659	0.1855	-0.1635	0.3808	0.3799

B =

	Viteza
x1	-0.002441
x2	-0.0001791
x3	-0.01238
x4	0.009009
x5	0.002953
x6	0.01823
x7	0.01289

C =

	x1	x2	x3	x4	x5	x6	x7
Acceleratie	1.079	-0.2053	-3.402	5.777	-4.339	3.196	-0.008232

D =

	Viteza
Acceleratie	0

K =

	Acceleratie
x1	0.009717
x2	0.008913
x3	-0.007611
x4	-0.0001478
x5	0.00956
x6	0.004394
x7	-0.008291

Sample time: 1 seconds

Parameterization:

FREE form (all coefficients in A, B, C free).

Feedthrough: none

Disturbance component: estimate

Number of free coefficients: 70

Use "idssdata", "getpvec", "getcov" for parameters and their uncertainties.

Status:

Estimated using N4SID on time domain data "Data_2".

Fit to estimation data: 6.88% (prediction focus)

FPE: 1.355, MSE: 1.022