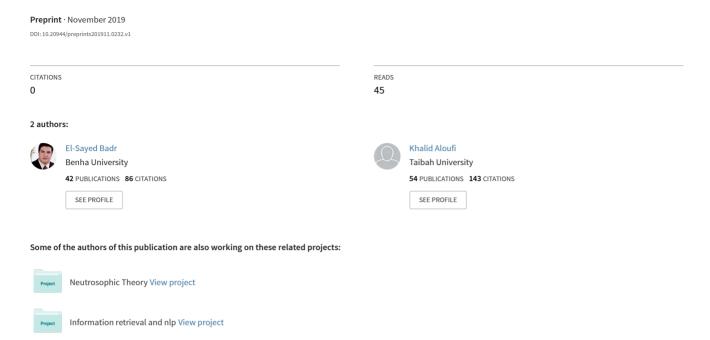
## An Exact Parallel Algorithm for the Radio k-coloring Problem



### An Exact Parallel Algorithm for the Radio k-coloring Problem

E. M. Badr<sup>1</sup> and Khalid Aloufi<sup>2</sup>

<sup>1</sup>Scientific Computing Department, Faculty of Computers & Artificial Intelligence, Benha University, Benha, Egypt. badrgraph@gmail.com

<sup>2</sup>College of Computer Science & Engineering Taibah University Saudi Arabia koufi@taibahu.edu.sa

#### Abstract.

For a positive integer k, a radio k-coloring of a simple connected graph G = (V(G), E(G)) is a mapping  $|f(u)-f(v)| \ge k+1-d(u,v)$  such that  $f:V(G) \to \{0,1,2,...\}$  for each pair of distinct vertices u and v of G, where d(u,v) is the distance between u and v in G. The span of a radio k-coloring f,  $rc_k(f)$ , is the maximum integer it assigns to some vertex of G. The radio k-chromatic number,  $rc_k(G)$  of G is min $\{rc_k(f)\}$ , where the minimum is taken over all radio k-colorings f of G. If k is the diameter of G, then  $rc_k(G)$  is known as the radio number of G. In this work, we propose four algorithms (two serial algorithms and their parallel versions) which related to the radio k-coloring problem. One of them is an approximate algorithm that determines an upper bound of the radio number of a graph G. The approximate algorithm is a polynomial time algorithm while the exact algorithm is an exponential time algorithm. The parallel algorithms are parallelized using the Message Passing Interface (MPI) standard. The experimental results prove the ability of the proposed algorithms to achieve a speedup f for f processors.

**Keywords:** Radio k-coloring; radio number; MPI; parallel algorithm

#### 1. Introduction

Motivated by the channel assignment problem proposed by Hale [1] in wireless networks, radio labeling in graphs has been studied from various perspectives. Let G = (V, E) be a simple, connected and undirected graph. Let diam (G) = d and

 $k \le d$  be a positive integer. We use standard terms or notations as used in common texts such as [2, 3]. For a positive integer k, a radio k-coloring f of a simple connected graph G is an assignment of nonnegative integers to the vertices of G such that for every two distinct vertices u and v of G,  $|f(u)-f(v)| \ge k+1-d(u,v)$  The span of a radio k-coloring f,  $rc_k(f)$ , is the maximum integer assigned to some vertex of G by f. The radio k-chromatic number,  $rc_k(G)$  of G is  $\min\{rc_k(f)\}$ , where the minimum is taken over all radio k-colorings f of G. If k is the diameter of G, then  $rc_k(G)$  is known as the radio number and is denoted by rn(G).

The radio k-coloring problem approaches to the radio coloring problem RCP when k = 2. RCP was first introduced by Griggs and Yeh [4] as the L(2, 1) labelling problem. The RCP in general has been proved to be NP-complete [4], even when restricted to planar graphs, split graphs, or the complements of bipartite graphs [5, 6]. Exact results have been obtained for certain special class of graphs such as paths [7], cycles and trees [4].

Determining the radio number seems a difficult task, even for some basic graphs. For instance, the radio number for paths and cycles has been studied by Chartrand et al. [8, 9], in which, the bounds of the radio numbers for paths and cycles were presented. Later on, the radio numbers for paths and cycles were completely settled in [10].

Badr and Moussa [11] proposed an improved upper bound of the radio k-chromatic number for a given graph against another which is based on work by Saha and Panigrahi [12]. They introduced also a polynomial algorithm which (differs from the first algorithm and derived from Liu and Zhu [10]) which determines the radio number of the path graph  $P_n$ . They [11] also proposed a new integer linear programming model [13-16] for the radio k-coloring problem.

In this work, we propose four algorithms (two serial algorithms and their parallel versions) which related to the radio k-coloring problem. One of them is an approximate algorithm that determines an upper bound of the radio number of a given graph. The other is an exact algorithm which finds the radio number of a graph G. The approximate algorithm is a polynomial time algorithm while the exact algorithm is an exponential time algorithm. The parallel algorithms are parallelized using the Message Passing Interface (MPI) standard. The experimental results, analysis prove the ability of the proposed algorithms to achieve a speedup 7 for 8 processors.

#### 2. Main Contributions

In this section, we propose four algorithms (two serial algorithms and their parallel versions) related to the radio k-coloring problem. One of them is an approximate algorithm that determines an upper bound of the radio number of a given graph. The other is an exact algorithm which finds the radio number of a graph G. The approximate algorithm is a polynomial time algorithm while the exact algorithm is an exponential time algorithm.

### 2.1. An upper bound of the radio number for a given graph G.

Badr and Moussa [11] proposed an upper bound algorithm of the radio number for a given graph as Algorithm 1.

```
Algorithm 1. Finding a radio k-coloring of a graph
        G be an n-vertex simple connected graph and k be a positive integer.
Input:
        the adjacency matrix A[n][n] of G
Output: A radio k-coloring of G.
Begin
       Compute the distance matrix D[n][n] of G using Floyed-Warshall's algorithm and the
       adjacency matrix A[n][n] of G.
       Upper = \infty;
            l = 1 to n
       for
              for i= 1 to n do
                      labeling [i] = 0;
              end
              for i= 1 to n do
                           for j=1 to n do
                                c[i][j]=diam+1-D[i][j];
                           end
                           c[i][i] = \infty;
              end
              for i = 2 to n do
 /*find the minimum value m of the column with position p*/
                         [m, p] = min [c(l, :)];
                         for j = 1 to n
                                     c[p][j] = c[p][j] + m
                                     if c[p][j] < c[l][j]
                                          c[p][j] = c[l][j]
                                     end
                        end
                        labeling [p] = m
              end
                 /* find the max value of the labeling */
                   Max Value = max (labeling))
                   if Upper > Max Value
                          Upper = Max Value
                   end
       end
End
```

#### 2.1.1. Complexity of Algorithm 1:

Here we analyze the complexity of Algorithm 1. Algorithm 1 consists of two steps, the first step is Floyed-Warshall's algorithm and the other is the remiander of Algorithm 1. We know the complexity of Floyed-Warshall's algorithm is  $O(n^3)$  because it has three inner for loops. The remainder of Algorithm 1 has three inner for loop only each of them has length n so the complexity of step 2 is  $O(n^3)$ . Thus the overall complexity for Algorithm 1 is

$$\approx 2O(n^2) + O(n^3) + O(n^3) \approx 2O(n^3) \approx O(n^3)$$
.

# 2.2. An exact sequential algorithm for determining the radio number of a given graph G.

In this section, we propose an exact algorithm (Algorithm 2) which determines the radio number of a given graph with n vertices. Recall the radio k-coloring problem is NP-complete problem so Algorithm 2 is an exponential time algorithm. It based on the brute force technique. Algorithm 2 determines the upper bound k of the radio number of a graph G with order n then it generates all possible labeling sets of the graph G. It is clear that the number of all labeling sets for the graph G is  $k(k-1)(k-2)\cdots(k-n+1)$ . Not of all these labeling sets satisfy the following inequality:  $|f(u)-f(v)| \ge k+1-d(u,v)$  so the following step in Algorithm 2 checks whether or not a certain set whether satisfies the above inequality. Finally, Algorithm 2 determines the radio number of the graph G by taking  $\{\min(\max(L_i)): 1 \le i \le k\}$  where  $L_i$  are the all possible labeling sets for G.

Algorithm 2: A serial algorithm for finding the radio number of a given graph G be an n-vertex simple connected graph and k be a positive integer. the adjacency matrix A[n][n] of G**Output**: A radio *k*-coloring of *G*. Begin Call Algorithm 1 (Finding a radio *k*-coloring of a graph) c = 1;% number of all labeling sets for i = 1: n c = c \* (upper - i+1);end E(1:c, 1: n)=0;i = 1;while i <= c j=0; while j <n j=j+1; num = (rand()\*upper)+1;num=fix(num); Lia = ismember(num,E(i,:));

```
if Lia==1
               j = j-1;
               continue;
          end
          E(i,j) = num;
     end
     Lia=0;
    if
      (i > 1)
         for 1=i:-1:2
             Lia=isequal(E(i,:),E(l-1,:));
             Lia=Lia +0;
         end
      end
      if Lia ==1
          E(i,:)=0;
          continue;
      end
      i = i+1;
  end
 Radio = \infty;
  for i=1:c
     for j=1:n
       for k=j+1:n
               abs (E(i,j)-E(i,k)) >= diam+1-D(j,k)
                     if Radio > max(E(i,:))
                          Radio = max(E(i,:));
                          index = i;
                     end
          end
       end
     end
  end
End /* Begin
```

#### 2.2.1. Complexity of Algorithm 2:

In this section, we analyze the complexity of Algorithm 2. Algorithm 2 consists of more than one procedure: the first procedure is Floyed-Warshall's method. We know the complexity of Floyed-Warshall's algorithm is  $O(n^3)$  because it has only three inner for loops. The second procedure of Algorithm 2 has three inner for loop only each of them has length n so the complexity of the second procedure is  $O(n^3)$ . The remain of Algorithm 1 has the checking subroutine which has complexity  $O(k^n)$  because the first vertex in G takes k possibilities, the second vertex takes (k-1) possibilities, and so on until the last vertex takes (k-n+1) possibilities. Thus the overall complexity for the Algorithm 1 is

$$\approx \mathrm{O}(n^3) + \mathrm{O}(n^3) + \mathrm{O}(k^n) \approx 2 \, \mathrm{O}(n^3) + \mathrm{O}(k^n) \approx \mathrm{O}(k^n) \, .$$

# 2.3. A Parallel Version of Algorithm 1 (for finding the upper bound of the radio number for a given graph *G*

In this section, we propose a parallel version of Algorithm 1, namely PAlgorithm 1, which determines the upper bound of the radio number of a given graph G. In PAlgorithm 1, each processor assigns the label zero to  $\frac{n}{p}$  number of vertices where n and p are the order of G and the number of processors respectively. It is clear that balance loading occurs if mod (n, p) = 0, otherwise unbalance loading occurs.

```
Algorithm 3. Parallel Version of Algorithm 1: Finding an upper bound of the radio k-coloring of a graph G
```

**Input**: Let G be an n-vertex, simple, connected graph, k be a positive integer and A[n][n] be the adjacency matrix of G

**Output**: An upper bound of the radio k-coloring of G Begin

2- Gather the Local\_Upper number from each processors

for  $0 \le i < p$  pardo

Send Local\_ Upper to processor 0

In processor 0

Search rank which corresponding to min(Upper) min\_rank = rankend

3- From processor  $min\_rank$ Print  $Local\_$  Upper % as the upper bound of the radio number of the graph G

#### End

#### 2.4. A Parallel Version of Algorithm 2

In this section, we propose a parallel version of Algorithm 2, namely PAlgorithm 2, which determines the radio number of a given graph G. The main idea of PAlgorithm 2 is that every vertex of the graph G is labeled  $\frac{c}{k}$  times by the integers  $1, 2, 3, \ldots, k$  where c is all possible combinations of n vertices by the upper bound k of the radio number of G which is determines by Procedure 2. The following example explains the above main idea of PAlgorithm 2.

**Example 1:** Consider a graph G with order n = 3 and upper bound k = 4 of the radio number of G. Now, we determine the all possible combinations [ c = k (k-1) (k-2) (k-2)]

3) ... (k-n+1) = 4 \* 3 \* 2 = 24] of n vertices by the upper bound k of the radio number of G as shown:

Table 1: All possible combinations for the graph G with order n and upper bound k = 4

$v_1$	$v_2$	$v_3$									
1		3			3		1			1	
1	2	4	2	1	4	3	1	4	4	1	3
1	3	2	2	3	1	3	2	1	4	2	1
1	3	4	2	3	4	3	2	4	4	2	3
1	4	2	2	4	1	3	4	1	4	3	1
1	4	3	2	4	3	3	4	2	4	3	2
			J								

From above example, it is clear that the first vertex is labeled  $\frac{c}{k} = \frac{24}{4} = 6$  times by

integer 1. Now, we can broadcast the data on all processors according to the label of the first vertex as follows:

```
Algorithm 4. Parallel Version of Algorithm 2 Finding a radio k-coloring of graph G
```

**Input**: Let G be an n-vertex, simple, connected graph, k be a positive integer, and A[n][n] be the adjacency matrix of G

Output: A radio k-coloring of G.

**Begin** 

- 1- Call PAlgorithm 1 % finding an upper bound of the radio number of G by parallel computing
- 2- For all processors

end

end

3- Gather the Local\_Radio number from each processors

for  $0 \le i < p$  pardo

Send Local Radio to processor 0

In processor 0

Search *rank* which corresponding to *min(Radio)* 

min rank = rank

end

4- From processor min rank

Print Local Radio

% as the radio number of the graph G

End

#### 3. Computational Study

The triangular snake graph  $\Delta_k$  is obtained from the path  $P_n$  by replacing each edge of the path by a triangle  $C_3$  [17] where k is the number of blocks. A connected graph in which the k blocks are isomorphic to the cycle  $C_n$  and the block-cutpoint graph is a path denoted by  $kC_n$ -snake [18]. Here we describe the numerical experiments then present computational results, which demonstrate the efficiency of the proposed algorithms on a set of test problems: paths, cycles,  $\Delta_k$  -snakes,  $kC_4$ -snakes and  $kC_6$ -snakes. All test runs were carried out on a computer cluster of the Faculty of Science [19], Cairo University, a homogeneous PC cluster consists of 9 nodes, one master and eight slaves. Each slave node has an Intel(R) core (TM)2 Duo CPU E7400 2.80 GHz and 4 Gb DDR2 RAM and master node has a microprocessor Intel(R) core(TM)2 Quad CPU Q6700 2.66 GHz microprocessor and 4 Gb DDR2 RAM. The processors were interconnected using Fast Ethernet and Scalable Coherent Interface (SCI). By using the message passing interface library MPI and C language, we can write a code for parallel computing simply using the single program multiple data (SPMD) approach.

The abbreviations Ub0, Ub1 and Ub2 are used to denote upper bounds are due to Badr and Moussa [11], Saha and Panigrahi [12] and Badr and Moussa [11] respectively. In [11], we emphasize that Ub0 is based on the integer liner programming model but Ub2 is based on the polynomial time algorithm which its complexity is  $O(n^3)$ . On the other hand, St and Ex are used to denote the exact radio numbers are due to Liu and Zhu [10] and the proposed Algorithm 2 respectively.

Table 2: Comparison among Ub0, Ub1, Ub2, St and Ex for the radio number of path graph

$m(\Gamma_n)$								
N	Ub0	Ub1	Ub2	St	Ex			
1	0	0	0	0	0			
2	1	1	1	1	1			
3	4	3	3	3	3			
4	9	6	5	5	5			
5	16	11	10	10	10			
6	25	15	14	13	13			
7	36	22	20	20	20			
8	49	28	26	25	25			
9	64	37	35	34	34			
10	81	45	42	41	41			
11	100	56	53	52	-			
12	121	66	62	61	-			
13	144	80	75	74	-			
14	169	91	86	85	-			

15	196	107	101	100	-
16	225	120	114	113	-
17	256	138	132	130	-
18	289	153	146	145	-
19	324	173	166	164	-
20	361	190	182	181	-
21	400	213	204	202	-
22	441	231	222	221	-
23	485	256	246	244	-
24	525	276	266	265	_
25	580	303	293	290	-

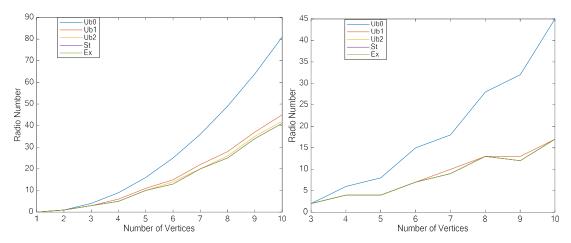


Figure1: Comparison among Ub0, Ub1, Ub2 and St, Ex for a) Path Graph and b) Cycle Graph

Table 2, Table 3 and Figure 1 show Algorithm 1 (Ub2) overcomes both the algorithm which based on integer linear programming [11] Ub0 and the algorithm Ub1 was proposed by Saha and Panigrahi [12]. We also note that Algorithm 2 (Ex) outperforms other algorithms but the proposed Algorithm 2 (Ex) and the algorithm (St) was proposed by Liu and Zhu [10] are equivalent. As well the proposed Algorithm 2 (Ex) is better than the Algorithm (St) because the proposed Algorithm 2 (Ex) determines the exact radio number for a given graph but the Algorithm (St) finds the exact radio numbers for special graphs (path graph and cycle graph) only.

Table 3: Comparison among Ub0, Ub1, Ub2, St and Ex for the radio number of cycle graph

$m(\mathbb{C}_n)$							
N	Ub0	Ub1	Ub2	St	Ex		
1	-	-	-	-	-		
2	-	-	-	-	-		
3	2	2	2	2	2		
4	6	4	4	4	4		
5	8	4	4	4	4		
6	15	7	7	7	7		
7	18	10	9	9	9		
8	28	13	13	13	13		
9	32	13	12	12	12		
10	45	17	17	17	17		

11	50	21	20	20	-
12	66	26	26	26	-
13	72	25	24	24	-
14	91	31	31	31	-
15	98	36	35	35	-
16	120	43	43	36	-
17	128	44	40	32	-
18	153	49	49	41	-
19	162	55	54	36	-
20	190	64	64	46	-
21	200	64	60	40	-
22	231	71	71	51	-
23	253	78	77	44	-
24	276	89	89	56	-
25	300	89	84	48	-

In Table 2 and Table 3, it is clear that the proposed Algorithm 2 (Ex) determine the radio number for paths and cycle with the maximum number of vertices 11 only because of the Algorithm 2 is exponential time algorithm with complexity  $O(k^n)$ . In order to overcome this obstacle, we use more processors for testing graphs which have more than 11 vertices.

Table 4: PAlgorithm 1 ( the upper bound of the radio number) for size 1000 of cycle graph  $C_n$  and path graph  $P_n$ 

Size Proc.	1	2	4	8
$C_{1000}$	146.0418	93.1508	47.1087	28.0769
Speed up	1.00000	1.5678	3.1001	5.2015
P <sub>1000</sub>	113.8448	75.6695	37.1350	22.7231
Speed up	1.0000	1.5045	3.0657	5.0101

From the superiority of Algorithm 1, we have a motivation to introduce the parallel version of algorithm 1, namely PAlgoritm 1.

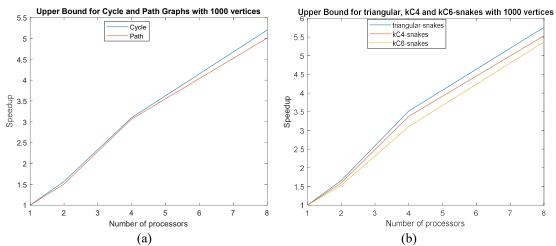


Figure 2: Determining the upper bound of the radio number on (a) Cycle and path graphs with 1000 vertices and (b)  $\Delta_k$  -snakes,  $kC_4$  -snakes and  $kC_6$  -snakes with about 1000 vertices on eight processors

Table 4 and Table 5 have the parallel results for determining the upper bound of the radio number of cycle and path graphs with 1000 vertices and  $\Delta_k$  -snakes,  $kC_4$  -snakes and  $kC_6$ -snakes with about 1000 vertices on eight processors. From these tables, we can observe that speedup of PAlgorithm 1 is about 6. We also note that the maximum number of vertices is 1000 vertices because Algorithm 1 is polynomial time algorithm but Algorithm 2 is exponential time algorithm with complexity  $O(k^n)$  so it run on 11 vertices only.

Table 5: PAlgorithm 1 (the upper bound of the radio number) of  $\Delta_{500}$  -snakes,  $333C_4$  -snakes

and 200C <sub>6</sub> -snakes						
Size Proc.	1	2	4	8		
Δ <sub>500</sub> -snakes	124.2723	74.8313	35.2906	21.5747		
Speed up	1.0000	1.6607	3.5214	5.7601		
333C <sub>4</sub> -snakes	142.2393	88.9886	42.0814	25.6986		
Speed up	1.0000	1.5984	3.3801	5.5349		
200C <sub>6</sub> -snakes	34.2044	22.3252	11.0173	6.3678		
Speed up	1.0000	1.5321	3.1046	5.3715		

From the superiority of Algorithm 2, we have a motivation to introduce the parallel version of Algorithm 2, namely PAlgoritm 2.

Table 6: PAlgorithm 2 (the radio number) for (8 and 10) vertices of cycle graph C<sub>n</sub> and path

graph P <sub>n</sub>						
Size Proc.	1	2	4	8		
$C_8$	447.3240	285.4652	174.3681	65.9682		
Speed up	1.0000	1.5670	2.5654	6.7809		
$C_{10}$	1936.8719	1145.4943	745.3234	304.0185		
Speed up	1.0000	1.6901	2.5987	6.3709		
P <sub>8</sub>	429.7530	293.7679	177.3567	69.1978		
Speed up	1.0000	1.4629	2.4231	6.2105		
P <sub>10</sub>	1936.8719	1232.8911	806.6266	322.2695		
Speed up	1.0000	1.5710	2.4012	6.0101		

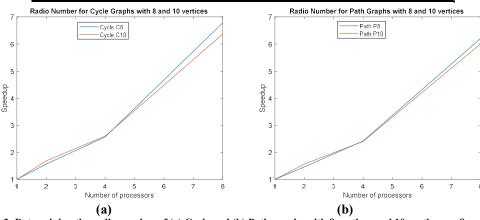


Figure 3: Determining the radio number of (a) Cycle and (b) Path graphs with 8 vertices and 10 vertices on 8 processors

Table 6 and Table 7 have the parallel results for determining the radio number of cycle and path graphs with 8 and 10 vertices and  $\Delta_k$ -snakes,  $kC_4$ -snakes and  $kC_6$ -snakes with about 10 vertices on eight processors. It is clear that the number of vertices is very small because the Algorithm 2 is an exact exponential time algorithm with complexity  $k^n$ . We can use more processors for testing more vertices. From these tables, we can observe that the speedup of PAlgorithm 2 is about 7.

Table 7: PAlgorithm 2 (th	e radio number) of $\Delta_4$	-snakes, $3C_4$ -snakes and	2C <sub>6</sub> -snakes
---------------------------	-------------------------------	-----------------------------	-------------------------

Size Proc.	1	2	4	8
$\Delta_4$ -snakes	1765.8947	1205.0598	479.9801	259.9963
Speed up	1.0000	1.4654	3.6791	6.7920
3C <sub>4</sub> -snakes	1975.9780	1259.6277	559.4502	328.0503
Speed up	1.0000	1.5687	3.5320	6.0234
2C <sub>6</sub> -snakes	2374.3218	1572.7110	597.7949	360.1932
Speed up	1.0000	1.5097	3.9718	6.5918

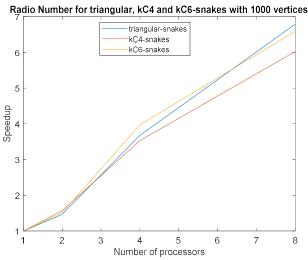


Figure 4: Determining the radio number of  $\Delta_k$  -snakes,  $kC_4$  -snakes and  $kC_6$  -snakes with about 10 vertices on eight processors

#### 4. Conclusion

In this work, we proposed four algorithms (two serial algorithms and their parallel versions) which related to the *radio k-coloring* problem. One of them is an approximate algorithm that determines an upper bound of the radio number for a given graph. The other is an exact algorithm which finds the radio number of a graph *G*. The approximate algorithm is a polynomial time algorithm while the exact algorithm is an exponential time algorithm. The parallel algorithms were parallelized using the Message Passing Interface (MPI) standard. The experimental results,

analysis proved the ability of the proposed algorithms to achieve a speedup 7 for 8 processors.

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