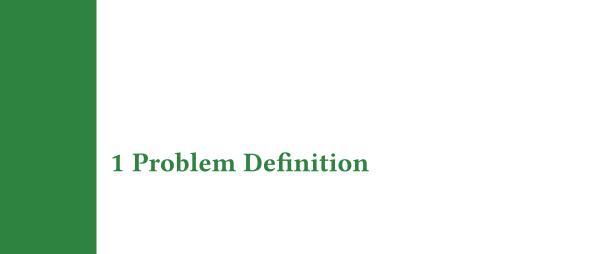
## Scanner

**Selected Fun Problems of the ACM Programming Contest SS25** 04.06.2025

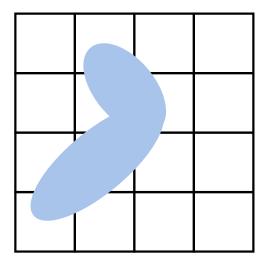
David Knöpp

#### **About questions**

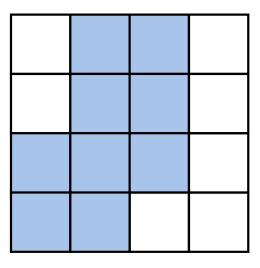
- Please ask questions if you do not understand an important aspect
- Otherwise, please save your questions for the discussion after the presentation



Result Matrix 4/57



Result Matrix 5 / 57

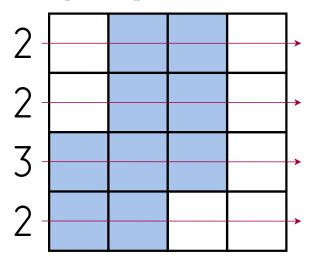


Result Matrix 6 / 57

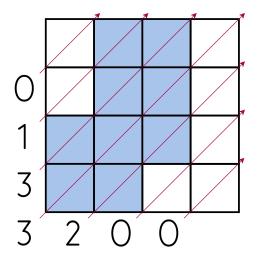
. # # . . # # . # # # .

This is our actual output.

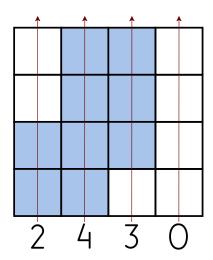
But what is our input?



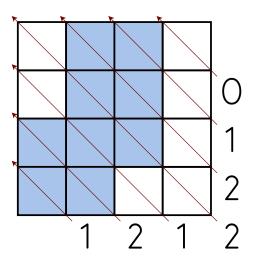
2 2 3 2



2 2 3 2 0 1 3 3 2 0 0



2 2 3 2 0 1 3 3 2 0 0 2 4 3 0



```
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

```
1 2 2 3 2 0 0 1 3 3 2 0 0 2 4 3 0 1 2 1 2 2 1 0
```

Live Demo

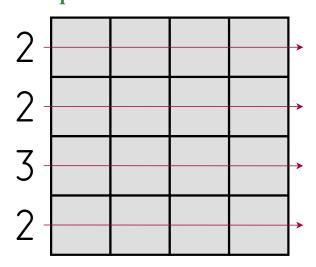


# 2 Solution

Tools 14 / 57

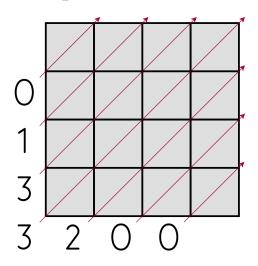
- Python
  - Personal experience
- Numpy
  - Convenient and efficient matrix operations
  - Personal experience

**Example** 15 / 57



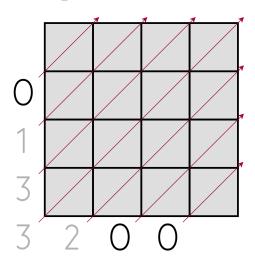
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

Example 16 / 57



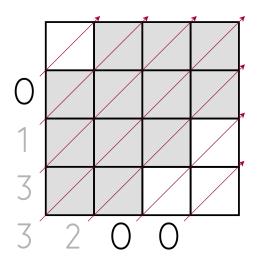
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 17 / 57



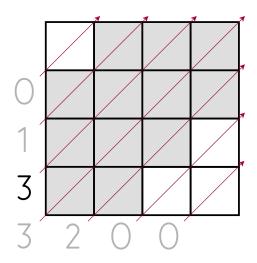
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 18 / 57



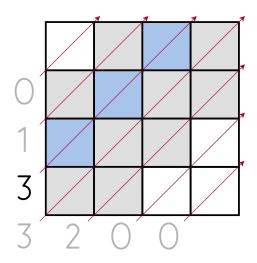
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 19 / 57



```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 20 / 57

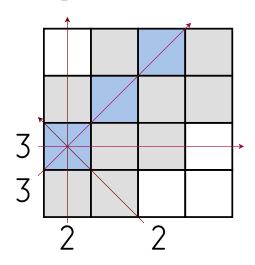


```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 21 / 57

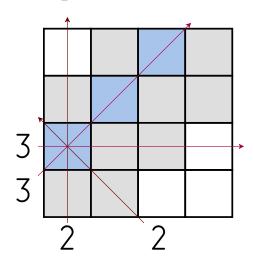
1 2 2 3 2 0 0 0 2 4 3 0 1 2 1 0 0

**Example** 22 / 57



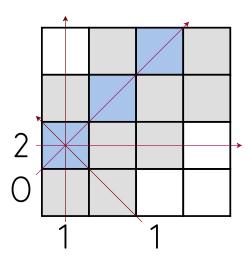
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 23 / 57



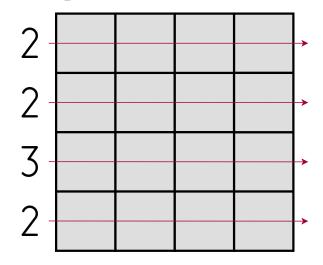
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

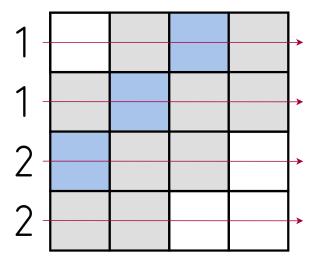
**Example** 24 / 57



```
1
1 1 2 2
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

**Example** 25 / 57





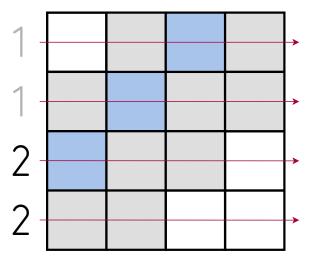
```
1

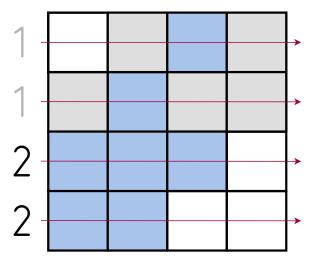
1 1 2 2

0 1 0 3 2 0 0

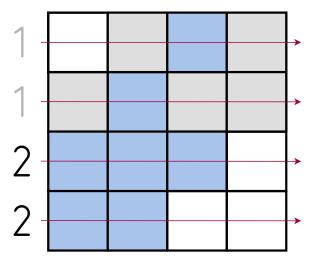
1 3 2 0

1 1 1 1 2 0 0
```



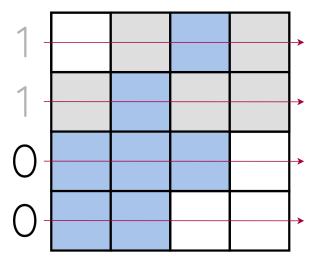


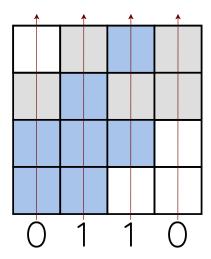
```
1
1 1 <mark>2 2</mark>
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

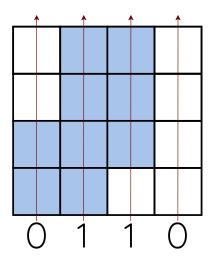


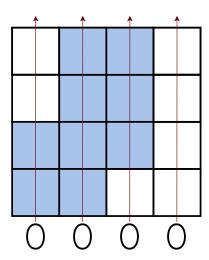
```
1
1 1 2 2
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

30 / 57

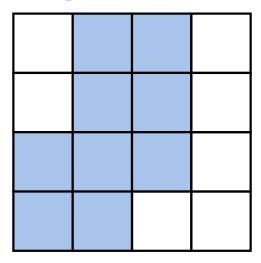








34 / 57



1						
0	0	0	0			
0	0	0	0	0	0	6
0	0	0	0			
0	0	0	0	0	0	0

Fill known cells

```
def compare_and_fill(sensor_data_point, arr):
        # number of unassigned elements
        n of unassigned = n of unassigned(arr)
        # Declare all unassigned as empty
        if sensor_data_point == 0:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = EMPTY
        # Declare all unassigned as full
        elif sensor data point == n of unassigned:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = FULL
                    update sensor data(cell.x, cell.y)
```

Main Loop 36 / 57

```
while(not is done()):
            diag lr = get diagonal lr(matrix)
            diag rl = get diagonal rl(matrix)
            # Horizontals
            for i in range(height):
                compare and fill(sensor data horizontal[i], matrix[i,:])
            # LR-Diags
            for i in range(height + width - 1):
                compare and fill(sensor data diagonal lr[i], diag lr[i])
            # Verticals
            for i in range(width):
                compare and fill(sensor data vertical[i], matrix[:,i])
            # RL-Diags
            for i in range(height + width - 1):
                compare and fill(sensor data diagonal rl[i], diag rl[i])
```

Are we done? 37 / 57

• Does compare\_and\_fill always find a solution?

- What if there is no solution?
- What if there are multiple solutions?

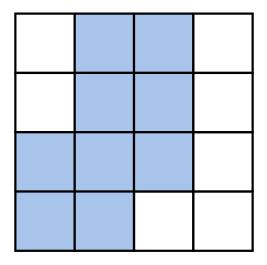
Are we done? 38 / 57

- Does compare\_and\_fill always find a solution?
- What if there is no solution?
- What if there are multiple solutions?

Let's first answer a different question:

• How do we know whether we found a solution?

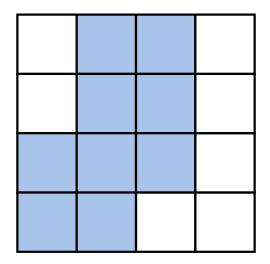
## How do we know whether we found a solution?



All input\_datas-entries are zero

40 / 57

## **Invalid state**



Every cell is assigned, but there is one input\_data-entry left!

 $\Rightarrow$  contradiction

### **Termination Condition**

1. Check whether all input\_data is zero

```
def is_data_used(sensor_data):
    return not np.any(sensor_data != 0)
```

2. Check whether all cells are assigned

```
def is_all_assigned(matrix):
    return not np.any(matrix.cell == UNASSIGNED)
```

3. Check whether we are done

```
def is_done():
    return is_data_used(sensor_data) or is_all_assigned(matrix)
```

**Demo: No Solution** 42 / 57



## **Multiple solutions**

- We assign EMPTY or FULL **only if** we know a state for certain
- $\Rightarrow$  with compare\_and\_fill, we can only detect **single** solutions
- If multiple solutions exist for a given input ⇒ get stuck

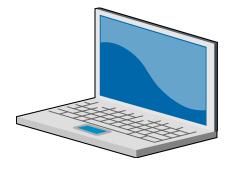
## Multiple Solutions: Local Search

```
# value is either FULL or FMPTY
def search in branch(idx, value, matrix, sensor data):
        # save old data
        old matrix = matrix.copy()
        old sensor data = sensor data.copy()
        # assign variable
        matrix[idx] = value
        if value == FULL:
            update sensor data(idx[1], idx[0])
        fill loop()
        # re-assign old data
        matrix = old matrix
        sensor_data = old_sensor_data
```

## Multiple Solutions: Local Search

```
# ... inside fill loop()
if not has change occured:
            # indices of unassigned fields
            indices of unassigned = np.argwhere(matrix.cell == UNASSIGNED)
            for idx in indices_of_unassigned:
                # recursive calls
                for assignment in [EMPTY, FULL]:
                    search in branch(idx, value, matrix, sensor data)
                    if solutions found > 1:
                        # the solution is ambiguous -> leave loop
                        return
```

Demo: Local Search



Conclusion 47 / 57

### Does the algorithm always find a solution?

Answer: If it exists: Yes! But...

• ... we can get stuck  $\Rightarrow$  perform local search

### What if there is no solution?

Answer: Data will be contradictory

### What if there are multiple solutions?

Answer: We get stuck  $\Rightarrow$  perform local search

3 Discussion

## **Time Complexity**

- Take a matrix of dimension  $(n \times m)$
- Worst case: Local search from the beginning
- Worst case time complexity:  $\mathcal{O}(2^{n \cdot m})$

## Time Complexity: Using matrix property

- Problem Definition: Body Scanner
- ⇒ Matrix property: Most FULL cells are neighbored

## Time Complexity: Using matrix property

- Problem Definition: **Body** Scanner
- ⇒ Matrix property: Most FULL cells are neighbored

```
. . . . . . . . . # # . . . .
. . . . . . . . # # # # # # .
. . . . . . . # # # # # . . .
. . . . . . . # # # # . . # .
. . . . . . # # # # # # # # #
. . . . . # # # # # # # # # #
. . . . . # # # # # # # # # #
. . . . . # . . # # # # # # #
. . . . . . . . . # # # . . .
. . . . . . . . . . # . . . .
```

## Time Complexity: Using matrix property

- Problem Definition: Body Scanner
- ⇒ Matrix property: Most FULL cells are neighbored

```
. . . . . . . . . # # . . . .
. . . . . . . # # # # # # .
. . . . . . . # # # # # . . .
. . . . . . . # # # # . . # .
. . . . . . # # # # # # # # #
. . . . . # # # # # # # # # #
. . . . . # # # # # # # # # #
. . . . . # . . # # # # # # #
. . . . . . . . . # # # . . .
. . . . . . . . . . # . . . .
```

- compare\_and\_fill uses this property.
- Reduces search-space significantly.

# **Demo: Chunk Inputs**



# **Algorithm Justification**

### **Experiment**:

- 1. Generate 10000 inputs of dimension  $(10 \times 15)$
- 2. Run scanner.py: Abort after  $t_{\rm max}=0.01s$
- 3. Measure number of timeouts

## **Algorithm Justification**

### **Experiment**:

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### Results:

matrix type	timeout-rate
random	99.69%
chunk	1.47%

# **Algorithm Justification**

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### Results:

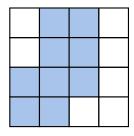
matrix type	timeout-rate
random	99.69%
chunk	1.47%

⇒ Most inputs can be solved in sub-exponential time!

## **Summary**

```
Input:
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

### Output:



```
def compare and fill(sensor data point, arr):
        # number of unassigned elements
        n_of_unassigned = n_of_unassigned(arr)
        # Declare all unassigned as empty
        if sensor data point == 0:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = FMPTY
        # Declare all unassigned as full
        elif sensor data point == n of unassigned:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = FULL
                    update sensor data(cell.x, cell.y)
```