# Scanner

**Selected Fun Problems of the ACM Programming Contest SS25** 04./05.06.2025

David Knöpp

#### **About questions**

- Please ask questions if you don't understand an important aspect
- Otherwise, please save your questions for the discussion after the presentation

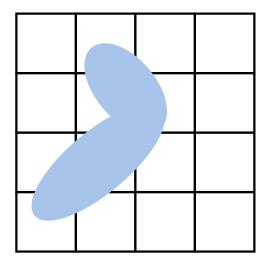
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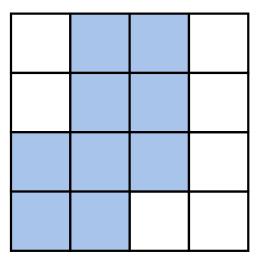
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**1 Problem Definition** 

Result Matrix 5/60



Result Matrix 6/60

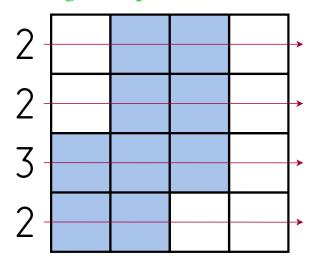


Result Matrix 7/60

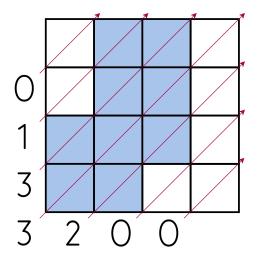
. # # . . # # . # # # .

This is our actual output.

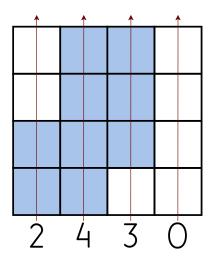
But what is our input?



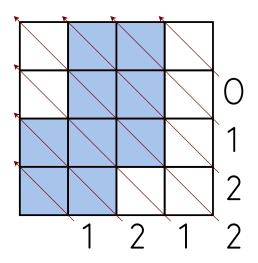
2 2 3 2



2 2 3 2 0 1 3 3 2 0 0



2 2 3 2 0 1 3 3 2 0 0 2 4 3 0



```
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

The number at the top represents the number of matrices that will follow.

In our case, it's just one.

```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

And that's our input!

Live Demo

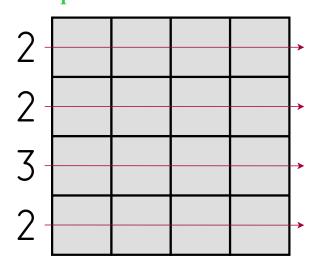


2 Solution

Tools 15 / 60

- Python
  - Personal experience
- Numpy
  - Convenient and efficient matrix operations
  - Personal experience

**Example** 16 / 60



```
1

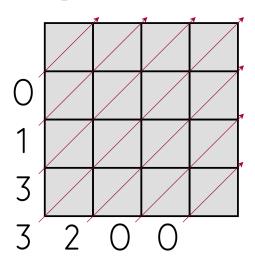
2 2 3 2

0 1 3 3 2 0 0

2 4 3 0

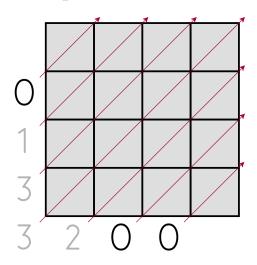
1 2 1 2 2 1 0
```

Example 17 / 60



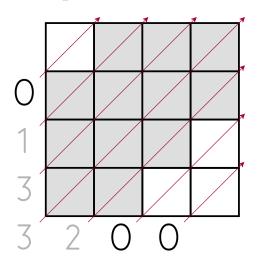
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 18 / 60



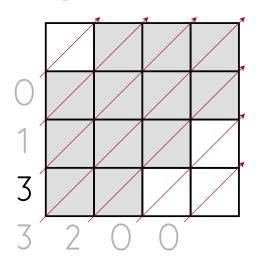
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 19 / 60



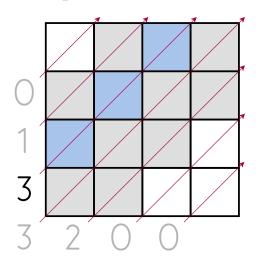
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 20 / 60



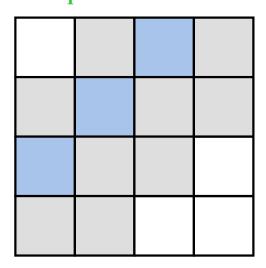
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 21 / 60



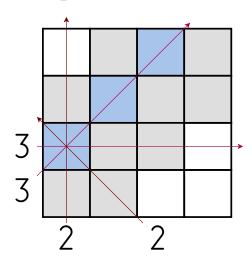
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 22 / 60



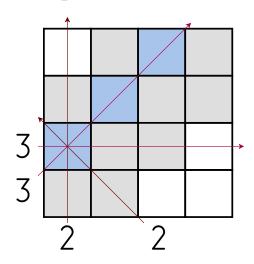
1						
2	2	3	2			
0	1	3	3	2	0	0
2	4	3	0			
1	2	1	2	2	1	0

**Example** 23 / 60



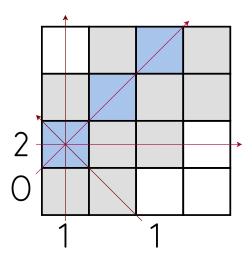
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 24 / 60

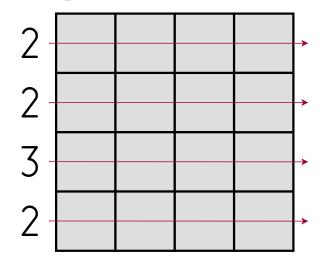


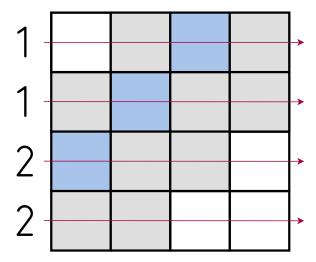
```
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

**Example** 25 / 60



```
1
1 1 2 2
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```





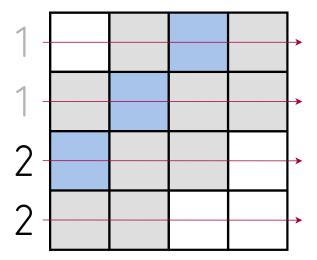
```
1

1 1 2 2

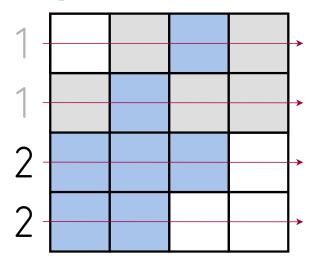
0 1 0 3 2 0 0

1 3 2 0

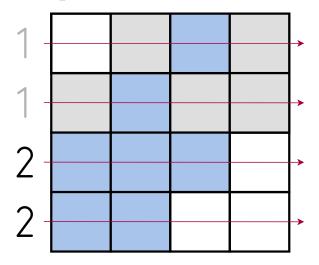
1 1 1 1 2 0 0
```



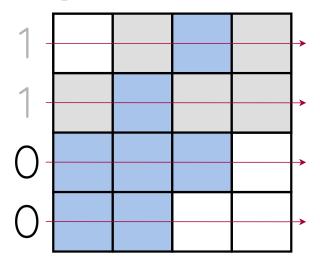
```
1
1 1 2 2
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

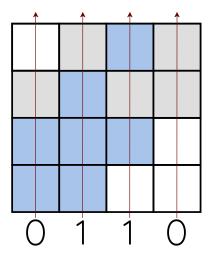


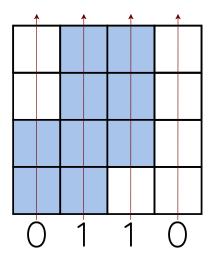
```
1
1 1 <mark>2 2</mark>
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

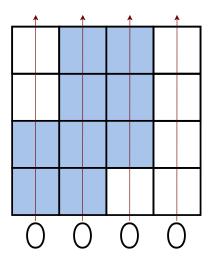


```
1
1 1 2 2
0 1 0 3 2 0 0
1 3 2 0
1 1 1 1 2 0 0
```

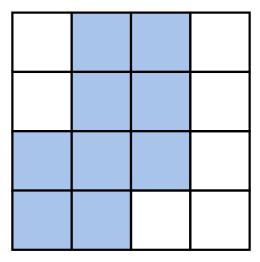








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1						
0	0	0	0			
0	0	0	0	0	0	0
0	0	0	0			
0	0	0	0	0	0	0

- Snippets of the actual Python-program
- Highly simplified treat it like pseudo-code

Fill known cells

```
def compare_and_fill(sensor_data_point, arr):
        # number of unassigned elements
        n of unassigned = n of unassigned(arr)
        # Declare all unassigned as empty
        if sensor_data_point == 0:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = EMPTY
        # Declare all unassigned as full
        elif sensor data point == n of unassigned:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = FULL
                    update sensor data(cell.x, cell.y)
```

Main Loop 38 / 60

```
while(not is done()):
            diag lr = get diagonal lr(matrix)
            diag rl = get diagonal rl(matrix)
            # Horizontals
            for i in range(height):
                compare and fill(sensor data horizontal[i], matrix[i,:])
            # LR-Diags
            for i in range(height + width - 1):
                compare and fill(sensor data diagonal lr[i], diag lr[i])
            # Verticals
            for i in range(width):
                compare and fill(sensor data vertical[i], matrix[:,i])
            # RL-Diags
            for i in range(height + width - 1):
                compare and fill(sensor data diagonal rl[i], diag rl[i])
```

Are we done? 39 / 60

• Does the algorithm always find a solution?

- What if there is no solution?
- What if there are multiple solutions?

Are we done? 40 / 60

- Does the algorithm always find a solution?
- What if there is no solution?
- What if there are multiple solutions?

Let's first answer a different question:

• How do we know whether we found a solution?

#### How do we know whether we found a solution?

1						
0	0	0	0			
0	0	0	0	0	0	0
0	0	0	0			
0	0	0	0	0	0	0

All input\_datas-entries are zero

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#### **Invalid state**

Every cell is assigned, but there is one input\_data-entry left!

 $\Rightarrow$  contradiction

#### **Termination Condition**

1. Check whether all input\_data is zero

```
def is_data_used(sensor_data):
    return not np.any(sensor_data != 0)
```

2. Check whether all cells are assigned

```
def is_all_assigned(matrix):
    return not np.any(matrix.cell == UNASSIGNED)
```

3. Check whether we're done

```
def is_done():
    return is_data_used(sensor_data) or is_all_assigned(matrix)
```

Demo: No Solution 44 / 60



### **Multiple solutions**

- We always only assign EMPTY or FULL to a cell if we know it's state for certain
- Therefore, with our current method, we can only detect certain solutions
- If multiple solutions exist for a given input, we should get stuck

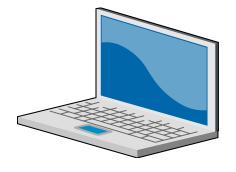
### Multiple Solutions: Local Search

```
# value is either FULL or FMPTY
def search in branch(idx, value, matrix, sensor data):
        # save old data
        old matrix = matrix.copy()
        old sensor data = sensor data.copy()
        # assign variable
        matrix[idx] = value
        if value == FULL:
            update sensor data(idx[1], idx[0])
        fill loop()
        # re-assign old data
        matrix = old matrix
        sensor_data = old_sensor_data
```

## Multiple Solutions: Local Search

```
# ... inside fill loop()
if not has change occured:
            # indices of unassigned fields
            indices of unassigned = np.argwhere(matrix.cell == UNASSIGNED)
            for idx in indices_of_unassigned:
                # recursive calls
                for assignment in [EMPTY, FULL]:
                    search in branch(idx, value, matrix, sensor data)
                    if solutions found > 1:
                        # the solution is ambiguous -> leave loop
                        return
```

Demo: Local Search



Are we done?

#### Does the algorithm always find a solution?

Answer: No!

A full assignment is valid only if all entries of sensor\_data become zero

• We can get stuck  $\Rightarrow$  perform local search

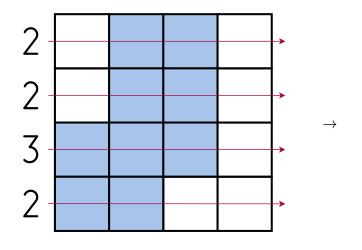
#### What if there is no solution?

Answer: Data will be contradictory

#### What if there are multiple solutions?

Answer: We get stuck  $\Rightarrow$  perform local search

3 Discussion

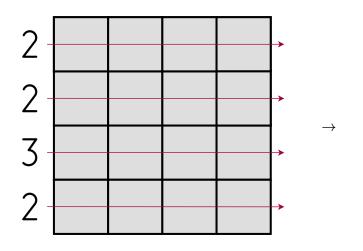


$$2 = 0 + 1 + 1 + 0$$

$$2 = 0 + 1 + 1 + 0$$

$$3 = 1 + 1 + 1 + 0$$

$$2 = 1 + 1 + 0 + 0$$



#### More general:

$$2 = x_0 + x_1 + x_2 + x_3$$

$$2 = x_4 + x_5 + x_6 + x_7$$

$$3 = x_8 + x_9 + x_{10} + x_{11}$$

$$2 = x_{12} + x_{13} + x_{14} + x_{15}$$

For a matrix of dimension  $(n \times n)$ , we get

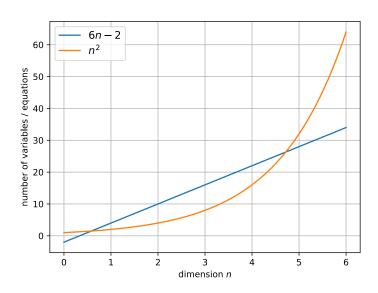
- $2^n$  variables  $x_0, ..., x_{2^n-1} \in \{0, 1\}$
- n + n + (2n 1) + (2n 1) = 6n 2 linearly independent equations

For a matrix of dimension  $(n \times n)$ , we get

- $2^n$  variables  $x_0, ..., x_{2^n-1} \in \{0, 1\}$
- n + n + (2n 1) + (2n 1) = 6n 2 linearly independent equations

Question: For which  $n \in \mathbb{N}$  is the linear system of equations under determined?

$$\Rightarrow$$
 Solve  $2^n > 6n - 2$ 

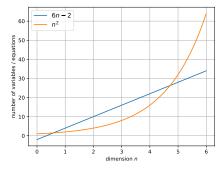


#### Theory indicates:

- For all  $n \geq 5$ , the LSE is underdetermined  $\Rightarrow$  Possibly no solution

#### Experiment confirms this!

- For all valid inputs of n < 5, a solution is found
- For some  $n \ge 5$ , the algorithm gets stuck (we have seen an example)  $\Rightarrow$  perform local search

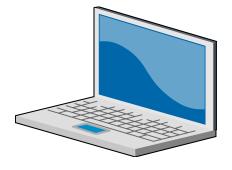


## Why it's a good algorithm for this problem

The problem definition states that we are working with a "body" scanner

- Matrix property: Most FULL cells are located next to each other
- Our algorithm uses this property
- ⇒ Most inputs can be solved in sub-exponential time

# **Demo: Chunk Inputs**

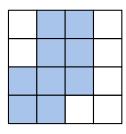


# 4 Summary

#### **Summary**

```
Input:
1
2 2 3 2
0 1 3 3 2 0 0
2 4 3 0
1 2 1 2 2 1 0
```

#### **Output:**



```
def compare and fill(sensor data point, arr):
        # number of unassigned elements
        n of unassigned = n of unassigned(arr)
        # Declare all unassigned as empty
        if sensor data point == 0:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = EMPTY
        # Declare all unassigned as full
        elif sensor_data_point == n_of_unassigned:
            for cell in arr:
                if cell == UNASSIGNED:
                    cell = FULL
                    update sensor data(cell.x, cell.y)
```