

# Pseudo-code for simulating the Snapshot model

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**Reminder:** The method here implemented is the one described in general terms in Carrizo Vergara et al. (2024, Section 6.1). The underlying trajectory model is supposed to depend upon a parameter  $\theta_X$ . The R function present in the repository is a vectorized implementation of this code, which can only be applied for square snapshot regions.

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**Algorithm 1** Algorithm to simulate the Snapshot model

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**Input:**  $N, \theta_X, p$ , the times of snapshot takes  $t_1, \dots, t_n$ , and for every  $k = 1, \dots, n$ , the disjoint regions  $A_{k,1}, \dots, A_{k,m_k}$  over which the snapshots are taken at time  $t_k$ .

- 1: **for**  $j = 1, \dots, N$  **do**
- 2:     Simulate the individual trajectory  $(x_j(t_1), \dots, x_j(t_n)) \sim \mu_{X(t_1), \dots, X(t_n) | \theta_X}$ .
- 3: **end for**
- 4: **Define**  $\vec{Q} = (\vec{Q}_k)_{k \in \{1, \dots, n\}}$  a list of  $n$  null vectors, each vector  $\vec{Q}_k = (Q_{k,1}, \dots, Q_{k,m_k})$  being of dimension  $m_k$  ( $\vec{Q}$  can be a null matrix if  $m_1 = \dots = m_k$ ).
- 5: **for**  $k = 1, \dots, n$  **do**
- 6:     **for**  $l = 1, \dots, m_k$  **do**
- 7:          $Q_{k,l} \leftarrow \sum_{j=1}^N \mathbb{1}_{A_{k,l}}(x_j(t_k))$
- 8:          $Q_{k,l} \leftarrow \text{Binomial}(Q_{k,l}, p)$
- 9:     **end for**
- 10: **end for**
- 11: **return**  $\vec{Q}$

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## References

Carrizo Vergara, R., Kéry, M., & Hefley, T. (2024). Movement-based models for abundance data. *arXiv preprint arXiv:2407.13384*.