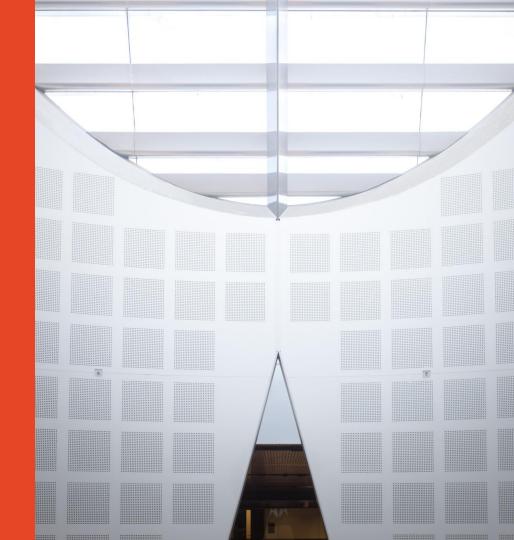
# USE MACHINE LEARNING TO PREDICT BIOMECHANICAL GAIT PARAMETERS DURING GAIT IN PEOPLE WITH KNEE OSTEOARTHRITIS

#### Presented by Group 03 - 1

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#### Information

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  - Motivation of the work, Related work/background study
- Mohan Xi (moxi0368)
  - Outlining of own approach/method/algorithm
- Weijia Chi(wchi0957)
  - Main result of own project
- Feixiang Wang(fwan0760)
  - Discussion/evaluation of our own work
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  - Discussion/evaluation of our own work
- Ruhao Ji (ruji6336)
  - Conclusion and reflection of own work

# Motivation/objective of the work

**Limitations:** traditional laboratory methods for measuring key indices are expensive, limiting their universal application capacity **Goal:** Use deep learning and 3D marker trajectory data to predict HKA, FPA, and **KAM (focus on Peak KAM values)** 

- Hip-Knee-Ankle (HKA) Angle Deviation: Reflects lower limb alignment during walking
- Foot Progression Angle (FPA): Indicates foot rotation relative to the movement direction
- Knee Adduction Moment (KAM): Measures knee joint loading;
   elevated KAM correlates with OA progression

# Related work/background study

#### 1. Methods for Calculating FPA and HKA

#### 2. Advancements in KAM Prediction Using Machine Learning

- Neural Networks (Boswell et al., Rokhmanova et al.),
- RNNs (Wang et al., Palad et al.),
- CNNs (Yan et al., 2022),
- Transformers (Tan et al., 2023),
- Hybrid Models...

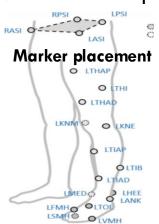
#### 3. Identification of Critical Markers

Statistical, Machine Learning, Neural Networks...

# Outlining of own approach/method/algorithm

#### Data:

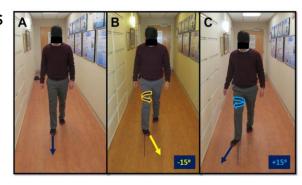
2,920 trajectory files2,920 model output files





The University of Sydney

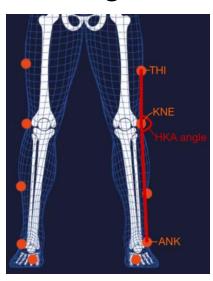
#### For FPA:



$$FPA_{avg} = \frac{1}{n} \sum_{t=t_{15\%}}^{t_{50\%}} FPA(t)$$

where  $t_{15}\%$  and  $t_{50}\%$  denote the time points corresponding to 15% and 50% of the stance phase, respectively, and n is the number of time frames within this interval.

#### For HKA angle deviation:



$$HKA_{dev} = \max_{t} (\theta_{HKA}(t)) - \theta_{HKA}(t_0)$$

where  $HKA_(dev)$  is the change in HKA angle during the stance phase, computed as the difference between the maximum value and the initial value at the first frame  $t_0$ .

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# Outlining of own approach/method/algorithm

For KAM prediction:

csv files

Data preprocessing

9D features

DataLoader + padding

(B, T, N, 9), mask (B, T)

PointNet Frame Encoder

- Determine leg side (L/R)
- Select lower-limb markers
- Construct 9D input features: position (x, y, z) + velocity (x', y', z') + acceleration (x", y", z")
- Training with MSE loss on valid (non-masked) frames.
- Feature selection: Saliency-based analysis using gradients to rank marker importance

MLP Regression Head

(B, T, 256)

Transformer Encoder

(B, T, 256)

(B, T) × mask (B, T) Output: KAM

per frame (B, T)

B: Batch size

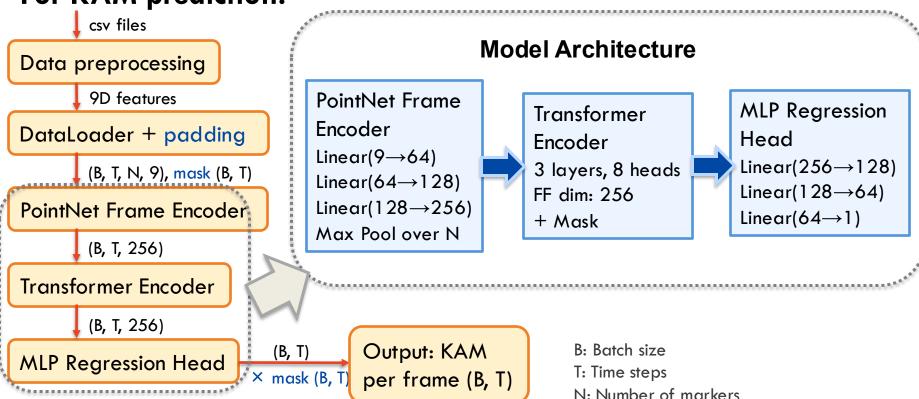
T: Time steps

N: Number of markers

FF dim: Feedforward dimension

# Outlining of own approach/method/algorithm

For KAM prediction:

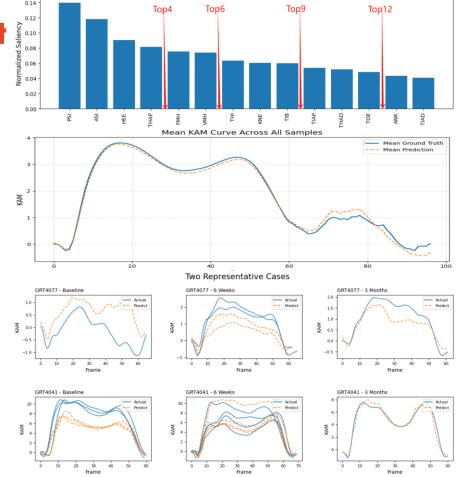


FF dim: Feedforward dimension

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# Main results of own project

- 1. Automated HKA and FPA Calculation Script
- 2. Feature saliency ranking
- 3. Model Accuracy
- Test MSE: 0.40
- Peak 1,2 MSE: 0.55, 0.46
- 4. Model stability check:
- The consistency of prediction error trends across timepoints within individuals
- Peak1,2: 59%, 56%



Symmetric Marker Saliency for KAM Prediction

### Discussion/Evaluation of own work

#### **Extra Information:**

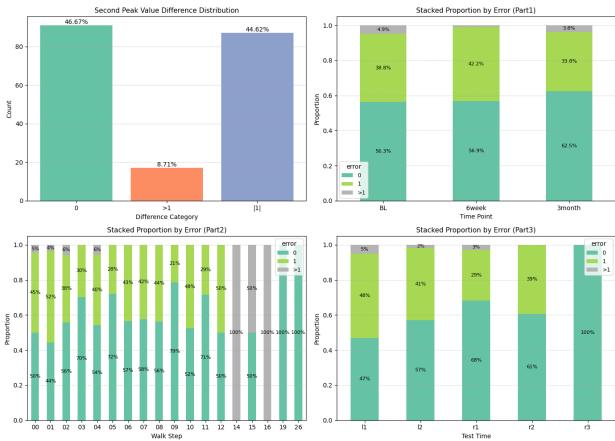
Sample code:

Participant\_ID+Time\_Point +Walk\_Step+Test\_Time( 10006week\_walk01\_I1)

Error Calculation Formula: ABS(Floor(True Peak value)-Floor(Actual Peak Value))

Value\_difference:

Error in 6week — error in Baseline for the same participant\_ID



# Discussion/Evaluation of own work

#### Limitations

 The prediction errors of the same participant at different test time points vary greatly.

 The clinical interpretation and verification of the prediction results are still insufficient.

2D data has the potential as a low-cost alternative.

- The current model mainly focuses on spatio-temporal feature

#### Conclusion and reflection of own work

#### **Key Achievements**

- Accurate Peak KAM Prediction
- Interpretability Enhancement / Cost-Effective Alternative

#### Reflection and Future Directions

- Multimodal Attribution Framework
- Dynamic Adaptation Strategies
- Robustness Enhancement
- Clinical Validation