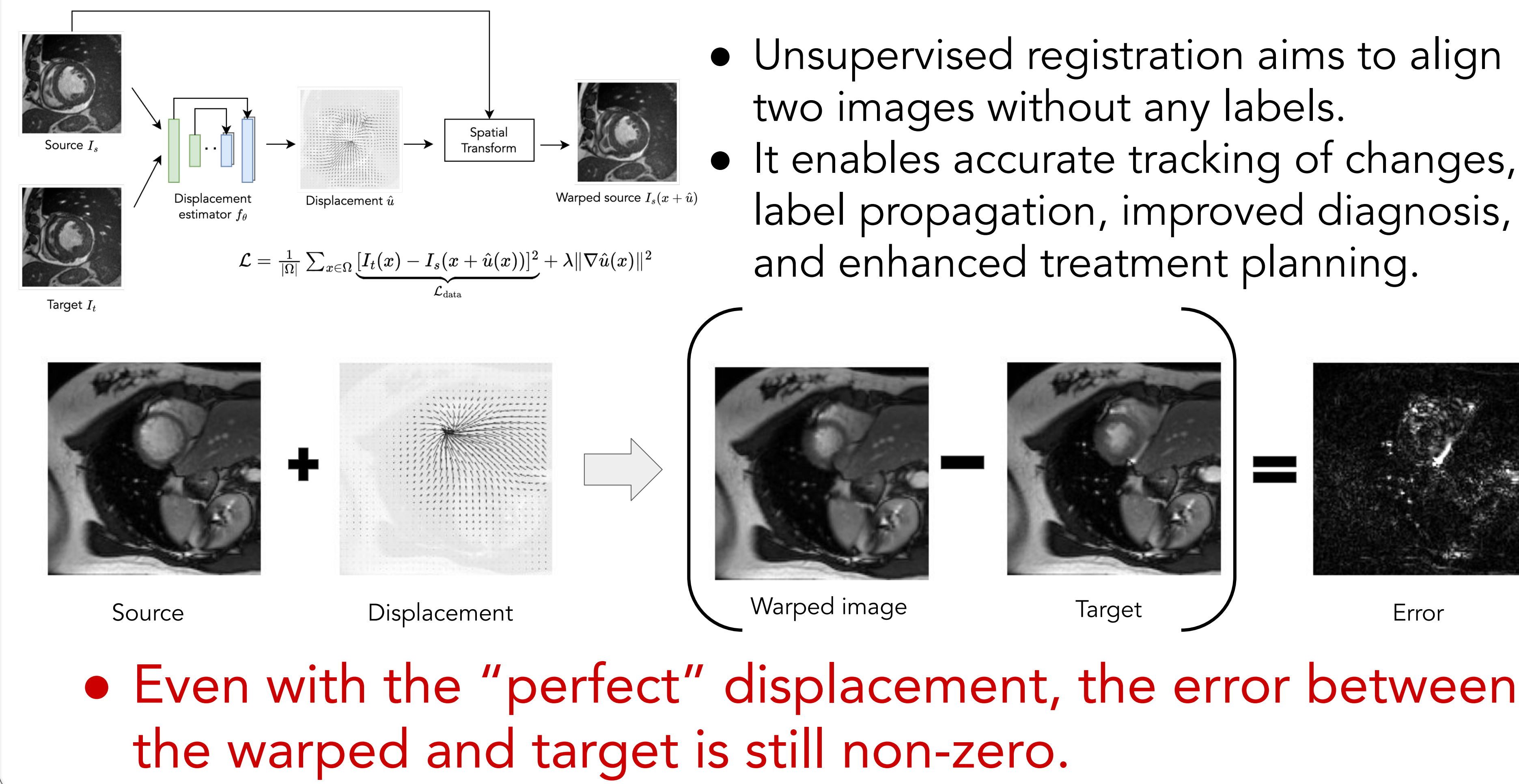
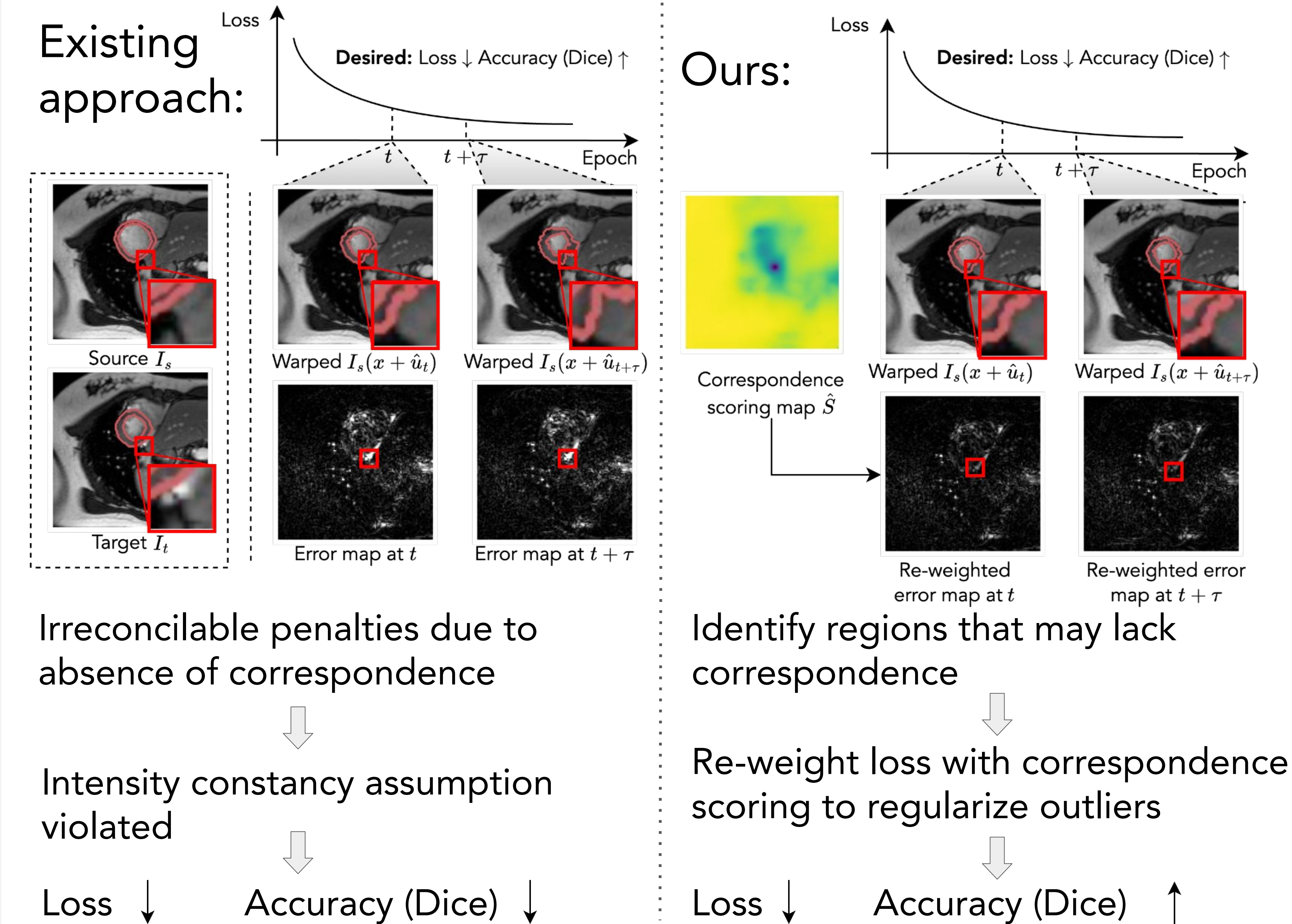


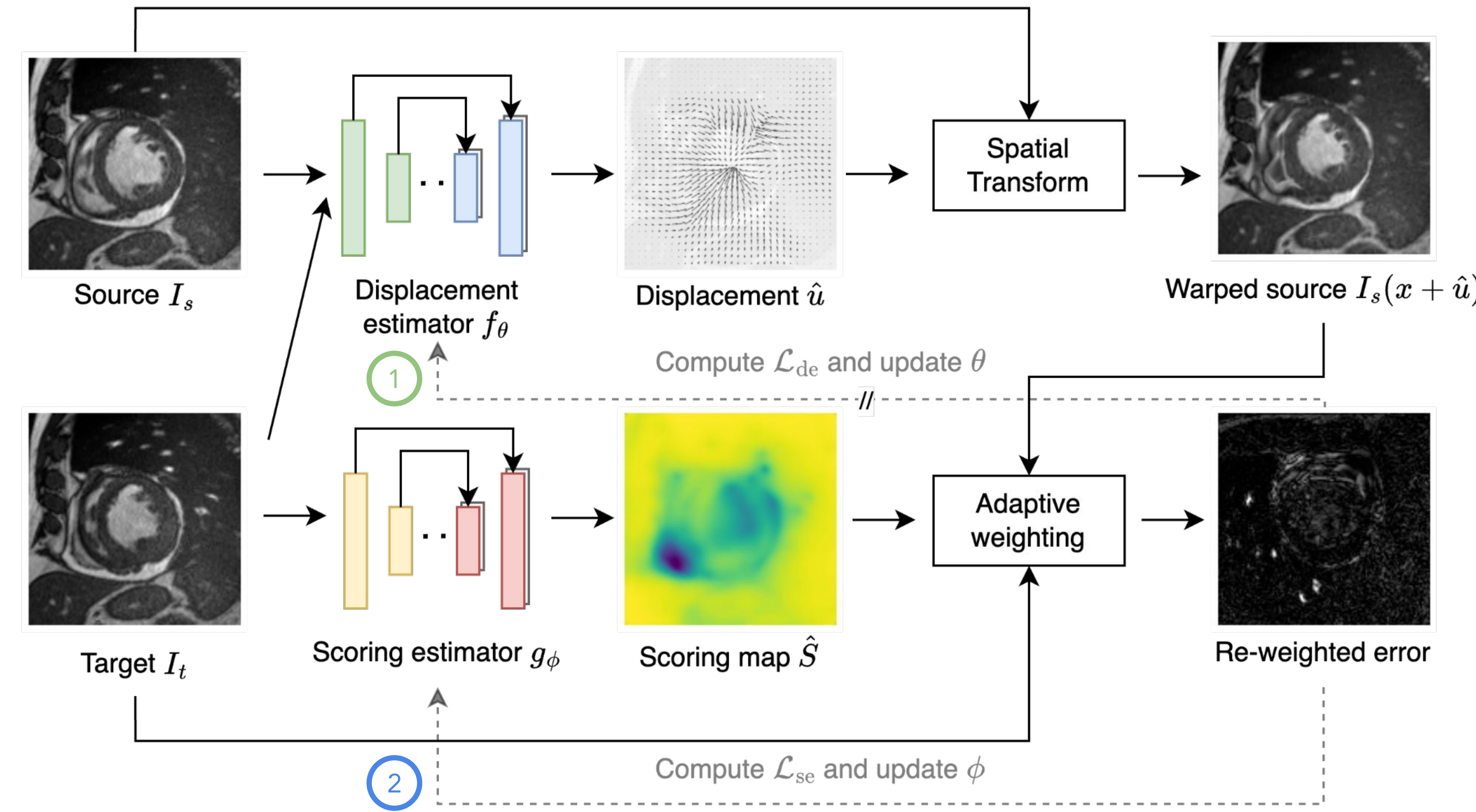
Introduction



Motivation



Methods



Our approach can be plugged-and-played into existing frameworks with no extra cost during inference.
****Note: The displacement and scoring estimators are optimized in separate alternating steps ① and ②**

$$\text{Displacement estimator loss: } \mathcal{L}_{de} = \frac{1}{|\Omega|} \sum_{x \in \Omega} [\hat{S}(x)] [I_t(x) - I_s(x + \hat{u}(x))]^2 + \lambda \|\nabla \hat{u}(x)\|^2$$

$$\text{Scoring estimator loss: } \mathcal{L}_{se} = \mathcal{L}_{ucs} + \alpha \mathcal{L}_{reg} + \beta \mathcal{L}_{smooth}$$

\mathcal{L}_{ucs} : Unsupervised correspondence scoring

\mathcal{L}_{smooth} : Momentum-guided smoothness

$$\mathcal{L}_{ucs} = \frac{1}{|\Omega|} \sum_{x \in \Omega} \hat{S}(x) [I_t(x) - I_s(x + [\hat{u}(x)])]$$

$$\text{Mean residual: } \mu_T = \frac{1}{|\Omega|} \sum_{x \in \Omega} [I_t(x) - I_s(x + [\hat{u}_T(x)])]$$

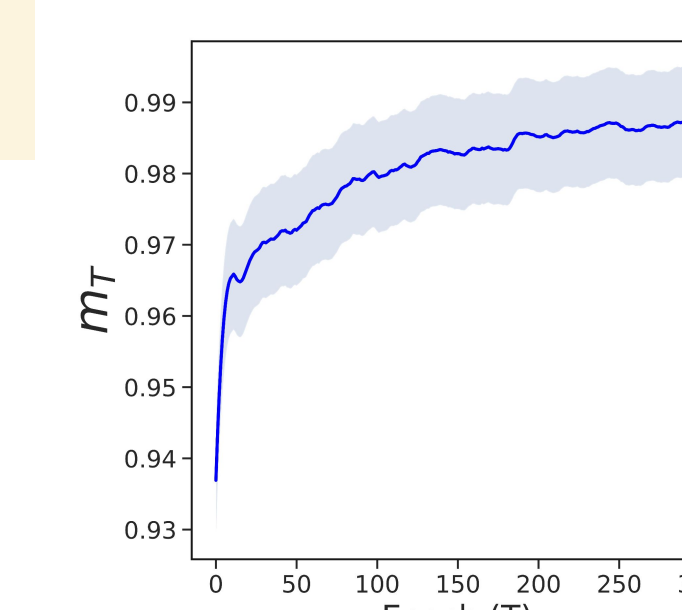
$$\text{Momentum: } b_T = \cos \frac{\pi}{2} \mu_T; m_T = \gamma m_{T-1} + (1 - \gamma) b_T$$

$$\mathcal{L}_{smooth} = m_T \frac{1}{|\Omega|} \sum_{x \in \Omega} \|\nabla \hat{S}(x)\|^2$$

\mathcal{L}_{reg} : Scoring estimator regularization

$$\mathcal{L}_{reg} = \frac{1}{|\Omega|} \sum_{x \in \Omega} [1 - \hat{S}(x)]^2$$

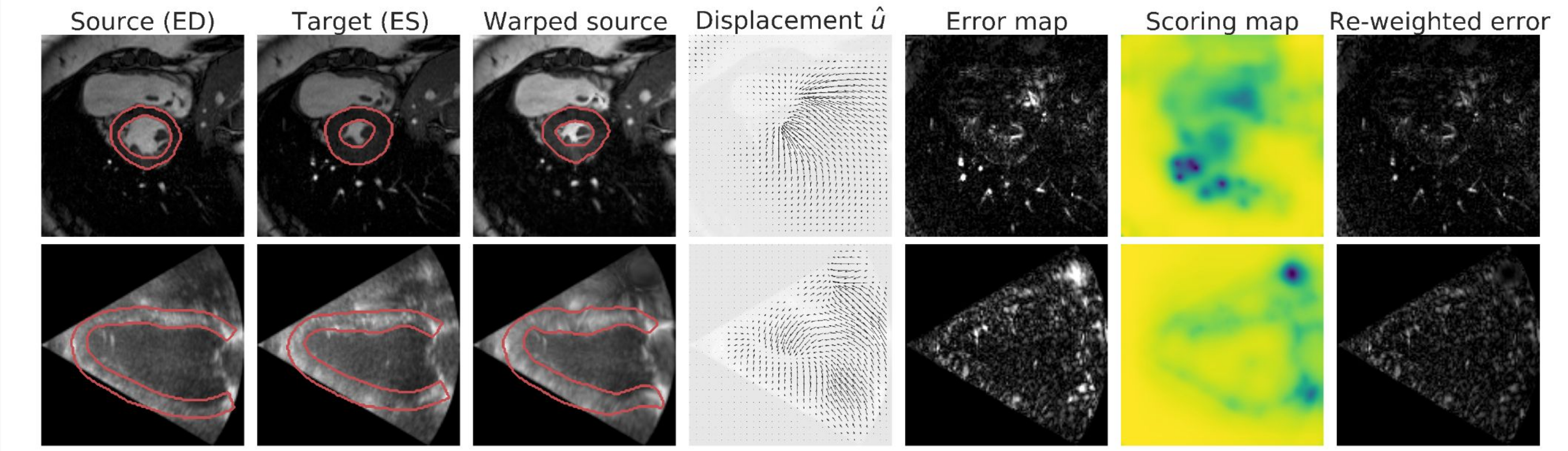
- Regularize the scoring map to avoid the trivial solution of all zeros.



- We treat residuals as a proxy for time
- We use momentum-guided adaptive regularization to encourage exploration during early steps and exploitation during later steps

Results

Scoring map visualization



		ACDC			CAMUS		
		DSC ↑	HD ↓	ASD ↓	DSC ↑	HD ↓	ASD ↓
CNN	Undeformed	47.98	7.91	2.32	66.77	10.87	2.61
	Elastix	77.26	4.95	1.28	80.18	10.02	1.81
	Voxelmorph	79.48	4.79	1.27	81.50	8.72	1.74
	NLL	76.49	5.46	1.45	75.24	11.05	2.20
	β-NLL	78.74	5.07	1.33	79.75	9.39	1.93
	AdaFrame	66.38	5.80	1.67	77.88	10.54	1.93
	AdaReg	78.75	5.13	1.33	79.31	9.78	1.88
	AdaCS (Ours)	80.50	4.69	1.23	81.74	8.55	1.72
	Transmorph	76.94	5.51	1.30	79.24	10.30	1.79
	NLL	73.12	7.22	1.27	75.08	11.60	1.79
Transformer	β-NLL	75.74	6.12	1.29	77.39	10.99	1.86
	AdaFrame	67.95	5.72	1.59	78.06	9.86	1.91
	AdaReg	76.22	5.68	1.29	78.12	10.62	1.84
	AdaCS (Ours)	78.39	5.40	1.32	79.64	9.85	1.79
	Diffusemorph	67.38	5.80	1.67	75.23	9.80	2.07
	NLL	66.24	5.84	1.73	74.78	10.62	2.15
	β-NLL	66.31	5.93	1.74	73.27	9.85	2.25
	AdaFrame	59.78	6.46	1.93	75.04	10.41	2.10
	AdaReg	69.41	6.25	1.78	74.36	10.66	2.21
	AdaCS (Ours)	72.09	5.35	1.53	77.65	9.82	1.99
		ACDC			CAMUS		
		DSC ↑	HD ↓	ASD ↓	DSC ↑	HD ↓	ASD ↓
vsm	NCC	78.55	4.94	1.29	77.01	10.23	1.89
	MI	78.04	5.25	1.35	78.18	9.83	1.99
	TBL	79.31	4.64	1.23	81.18	8.91	1.72
	MAE	78.27	5.36	1.43	78.59	10.23	1.97
	MSE	79.48	4.79	1.27	81.50	8.72	1.74
	AdaCS	80.50	4.69	1.23	81.74	8.55	1.72
tsm	NCC	73.77	6.64	1.12	73.03	11.87	1.70
	MI	73.57	6.57	1.11	74.83	11.94	1.83
	TBL	78.23	5.11	1.27	79.12	9.75	1.84
	MAE	74.30	6.36	1.28	75.96	11.35	1.89
	MSE	76.94	5.51	1.30	79.24	10.30	1.79
	AdaCS	78.39	5.40	1.32	79.64	9.85	1.79
dfm	NCC	70.25	5.29	1.58	75.67	10.75	2.06
	MI	71.16	5.40	1.56	76.19	10.09	2.16
	TBL	69.12	5.73	1.63	76.05	9.54	2.06
	MAE	66.30	5.75	1.71	77.30	10.36	2.09
	MSE	67.38	5.80	1.67	75.23	9.80	2.07
	AdaCS	72.09	5.35	1.53	77.65	9.82	1.99

Our proposed approach consistently outperforms baselines in various architectures and datasets and produces reasonably smooth displacement.

Application - cardiac strain analysis

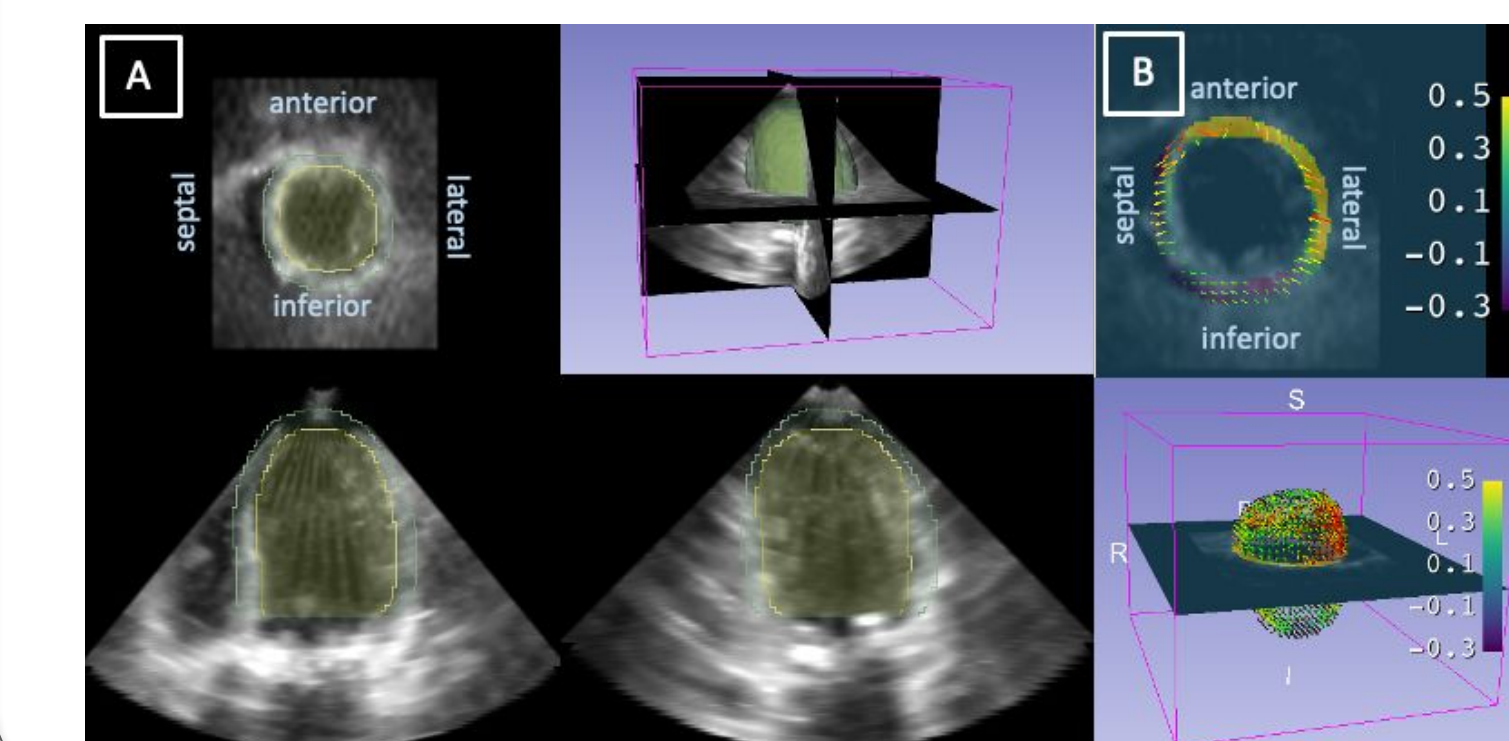


Figure: A) Segmented clinical echo (rest); B) Rest radial strain overlaid with estimated displacement revealing akinetic septal and inferior walls.

We produce regional cardiac strain map that can be used to identify myocardial infarction.