

PROMELA

Formal Methods in SE, 07.03.2020

PROcess MEta LAnguage

- PROMELA is **not** a programming language.
- PROMELA is based on Dijkstra's *guarded command language*.
- PROMELA provides:
 - non-deterministic control structures,
 - primitives for dynamic creation of concurrent processes and
 - primitives for interprocess communication.

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- PROMELA is based on Dijkstra's *guarded command language*.
- PROMELA provides:
 - non-deterministic control structures
 - primitives for dynamic creation of processes and
 - primitives for interprocess communication.

NO:

- functions with return values,
- expressions with side-effects,
- data and function pointers.

Types of Objects

We will work with three basic types of objects:

- processes,
- data objects and
- message channels.

Types of Objects

We will work with three basic types of objects:

- processes,
- data objects and
- message channels.

and also **labels**

Processes

Process Initialization

```
active [2] proctype main() {  
    printf("my pid is: %d\n", _pid)  
}
```

- **active** instantiates 2 processes of the type that follows.
- **proctype** denotes that *main* is a process type.
- *main* is an identifier for the process code block.
- **NB!** ‘;’ is a statement separator, rather than terminator.

Process Initialization

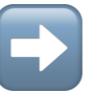
```
active [2] proctype main() {
    printf("my pid is: %d\n", _pid)
}
```

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- **proctype** denotes that *main* is a process type
- *main* is an identifier for the process
- **NB!** ‘;’ is a statement separator, rather than a function separator

```
$ spin test1.pml
                my pid is: 1
                my pid is: 0
2 processes created
```

Process Initialization

```
init {  
    printf("Hello, world!\n")  
}
```

- **init** is a process that is active in the initial system state.
- **init** is commonly used to initialize a system.
- **init + active** processes  instantiated in the declaration order.

Process Initialization

```
init {  
    printf("Hello, world!\n")  
}
```

- **init** is a process that is active in the initial system state.
- **init** is commonly used to initialize a process.
- **init + active processes** ➡ instantiates processes in a specific order.

```
$ spin test1.pml  
Hello, world!  
1 process created
```

Process Initialization

```
proctype you_run(byte x) {
    printf("x = %d, pid = %d\n", x, _pid);
    run you_run(x + 1) // recursive call
}
init {
    run you_run(0)
}
```

- **run** creates the process when the instruction is processed.
- **run** allows for input parameters.

Process Initialization

```
proctype you_run(byte x) {
    printf("x = %d, pid = %d\n", x, _pid);
    run you_run(x + 1) // recursive call
}
init {
    run you_run(0)
}
```

```
$ spin test1.pml
    x = 0, pid = 1
    x = 1, pid = 2
    x = 2, pid = 3
    ...
spin: too many processes (255 max)
      timeout
    ...
255 processes created
```

- **run** creates the process when the processed.
- **run** allows for input parameters.

Process Initialization

```
active proctype you_run(byte x) {  
    printf("x = %d\n", x)  
}
```

- no parameter can be given to **init** or **active** processes.
- if so, parameters of active processes are 0 by default.

Process Initialization

```
active proctype you_run(byte x) {  
    printf("x = %d\n", x)  
}
```

- no parameter can be given to **init** or **active** processes.
- if so, parameters of active process

```
$ spin test1.pml  
      x = 0  
1 process created
```

Data Objects

Basic Types

Type	Range
bit	0, 1
bool	false, true
byte	0..255
chan	1..255
mtype	1..255
pid	0..255
short	-2 ¹⁵ ..2 ¹⁵ -1
int	-2 ³¹ ..2 ³¹ -1
unsigned	0..2 ⁿ -1

- A byte can be printed as a character with the %c.
- There are no floats or strings.

Variable Declarations

bit x,y;	two single bits, initially 0
bool turn = true;	boolean value, initially true
byte a[12];	an array of size 12, all elements are initially 0
byte a[3] = {'h', 'i', '\0'};	byte array emulating a string of 3 symbols
chan m;	uninitialized message channel
mtype n;	uninitialized mtype variable
short b[4] = 89;	an array of size 4, all elements are initially 89
int int = 67;	integer, initially 67
unsigned v : 5;	unsigned stored in 5 bits
unsigned v : 3 = 5;	value range 0..7, initially 5

- All variables are initialized to 0 by default.
- Array indices start at 0.

Expressions

Assignment: `x = 5;`

Operators:

Arithmetic: `+` `-` `*` `/` `%` `++` `--`

Relational: `>` `>=` `<` `<=` `==` `!=`

Logical: `!` `&&` `||`

Bitwise: `&` `|` `^` `>>` `<<`

Variable Scope

Spin (version 6+) has three levels of scope:

- **global**: declaration is outside of all process bodies,
- **local**: declaration within a process body,
- **block**: declaration within a nested block.

Variable Scope

```
init {
    int x;
{
    int y;
    printf("x = %d, y = %d\n", x, y);
    x++; y++
}
printf("x = %d, y = %d\n", x, y)
}
```

Variable Scope

```
init {
    int x; ← local variable of init
    {
        int y;
        printf("x = %d, y = %d\n", x, y);
        x++; y++
    }
    printf("x = %d, y = %d\n", x, y)
}
```

The code illustrates variable scope. The variable `x` is declared at the top level (outside any function) and is highlighted with a yellow box and labeled "local variable of init". Inside the `init` block, there is a local variable `y` which shadows the global `x`. Both `x` and `y` are printed when the inner block exits. In the final `printf` statement, the variable `y` is red, indicating it is no longer in scope and its value is undefined.

Enumerations

```
mtype = {red, green, yellow};  
mtype light = red;
```

- **mtype** defines symbolic values (similar to an enum declaration in C).
- indexed from 0.

Executability & Guarded statements

Process Execution

- Processes execute **concurrently**.
- Processes are scheduled **non-deterministically**.
- Processes are **interleaved**.
- Each process has its own local state: **_pid & variables**.
- Processes can communicate via: **channels or shared variables**.

Statements

- Every basic statement is **atomic**.
- Every statement is either **executable** or **blocked**.
- Basic statements are composed into *compound statements*.

Statements

Always executable:

- print statements **printf();**
- assignments **x = 5;**
- **skip;**
- assertions **assert(x >= 2);**
- **break;**

Statements

Not always executable:

- **run** statement is executable only if there are less than 255 processes alive;
- **timeout** statement is executable only if there is no other executable process expressions.

Statements

- An expression is executable iff it evaluates to true (i.e. non-zero):
 - **(5 < 30)** always executable;
 - **(x < 30)** blocks if x is not less than 30;
 - **(x + 30)** blocks if x is equal to -30.
- Expressions must be side-effect free (**b = c++** is not valid).

Guarded Statements

selection:

```
if
  :: c_0  -> s_0; . . .
  . . .
  :: c_n  -> skip;
  :: else -> s_e; . . .
fi
```

repetition:

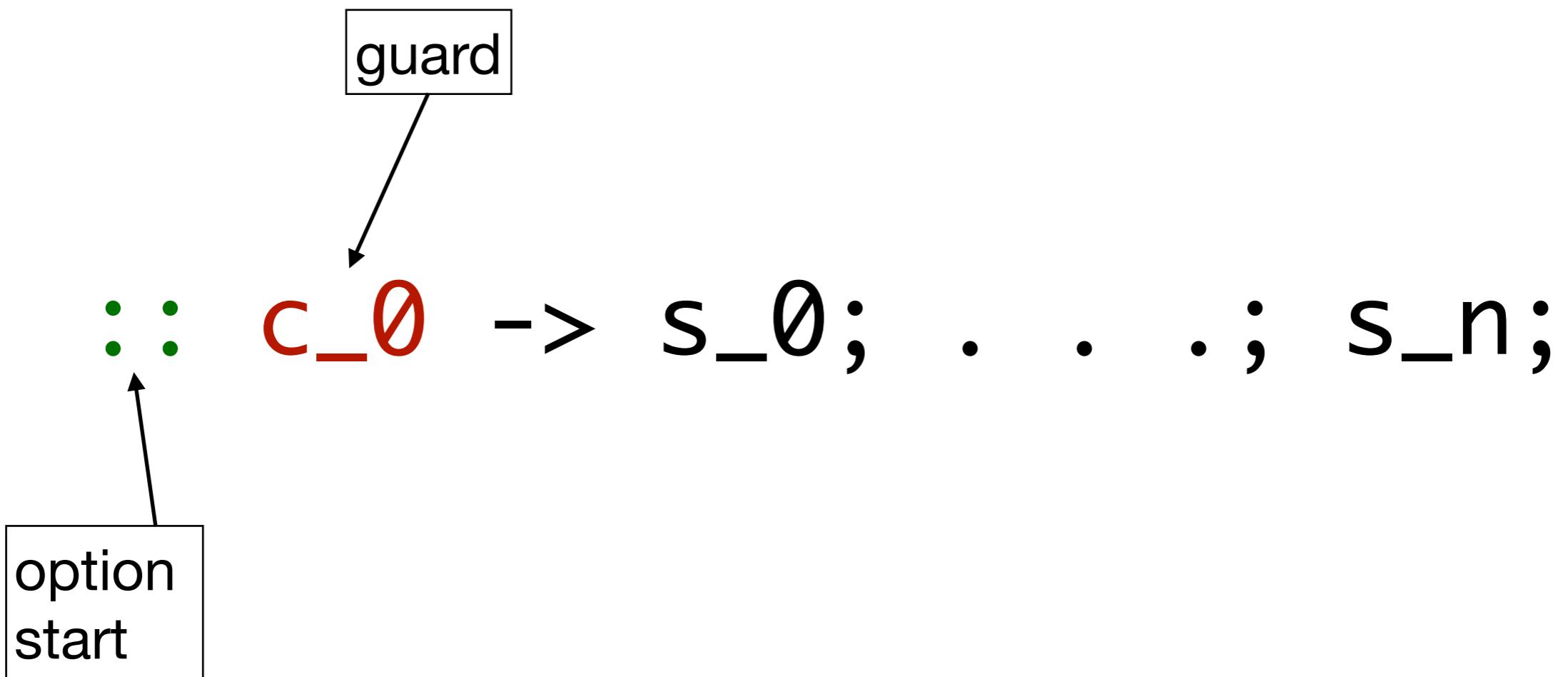
```
do
  :: c_0  -> s_0; . . .
  . . .
  :: c_n  -> s_n; break;
  :: else -> s_e; . . .
od
```

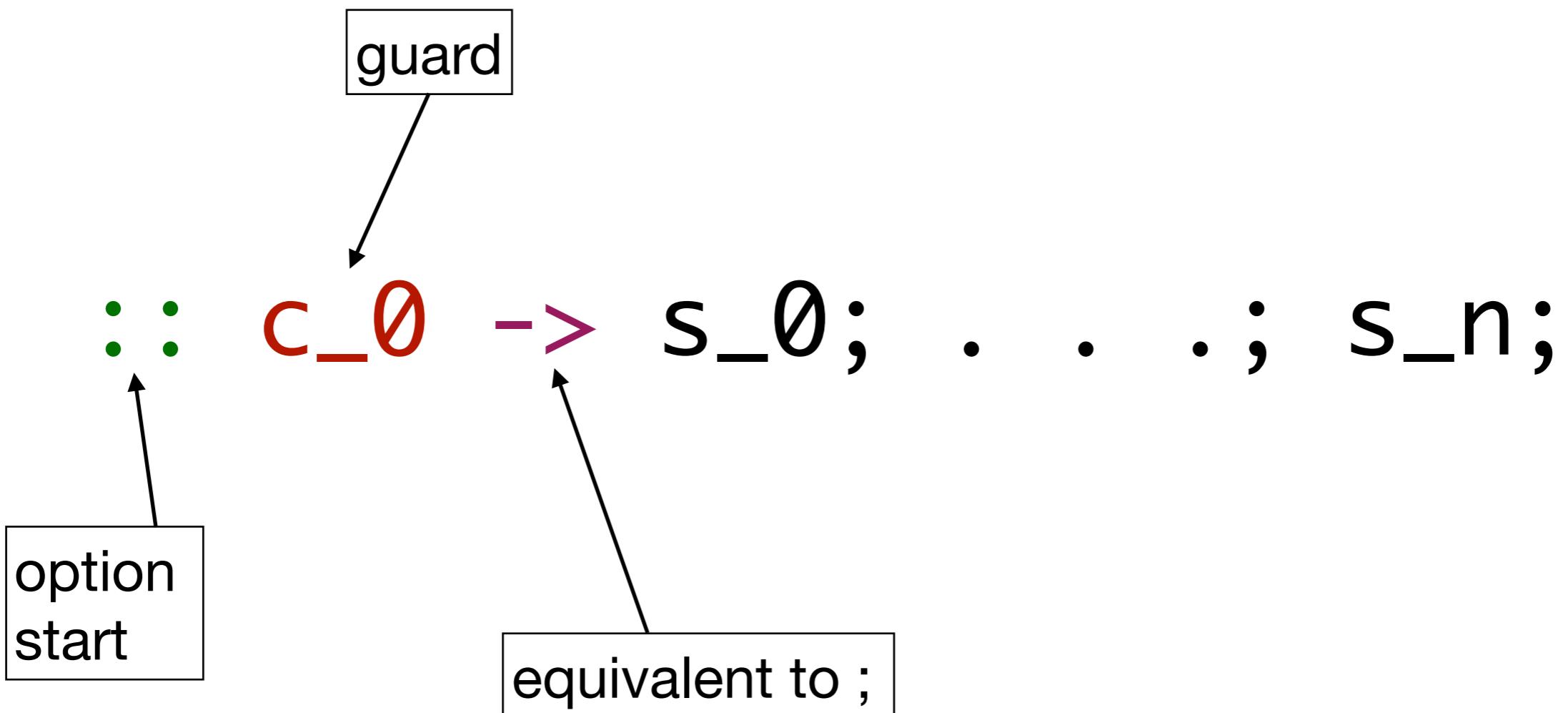
-
- $\{s_i; \dots\}$ executed only if c_i is executable.
 - if more than one c_i is executable, then an executed branch is chosen non-deterministically.
 - if no c_i is executable, the **else** branch is executed (if present).
 - **break** may be used to exit from a loop.
 - **skip** has no effect.

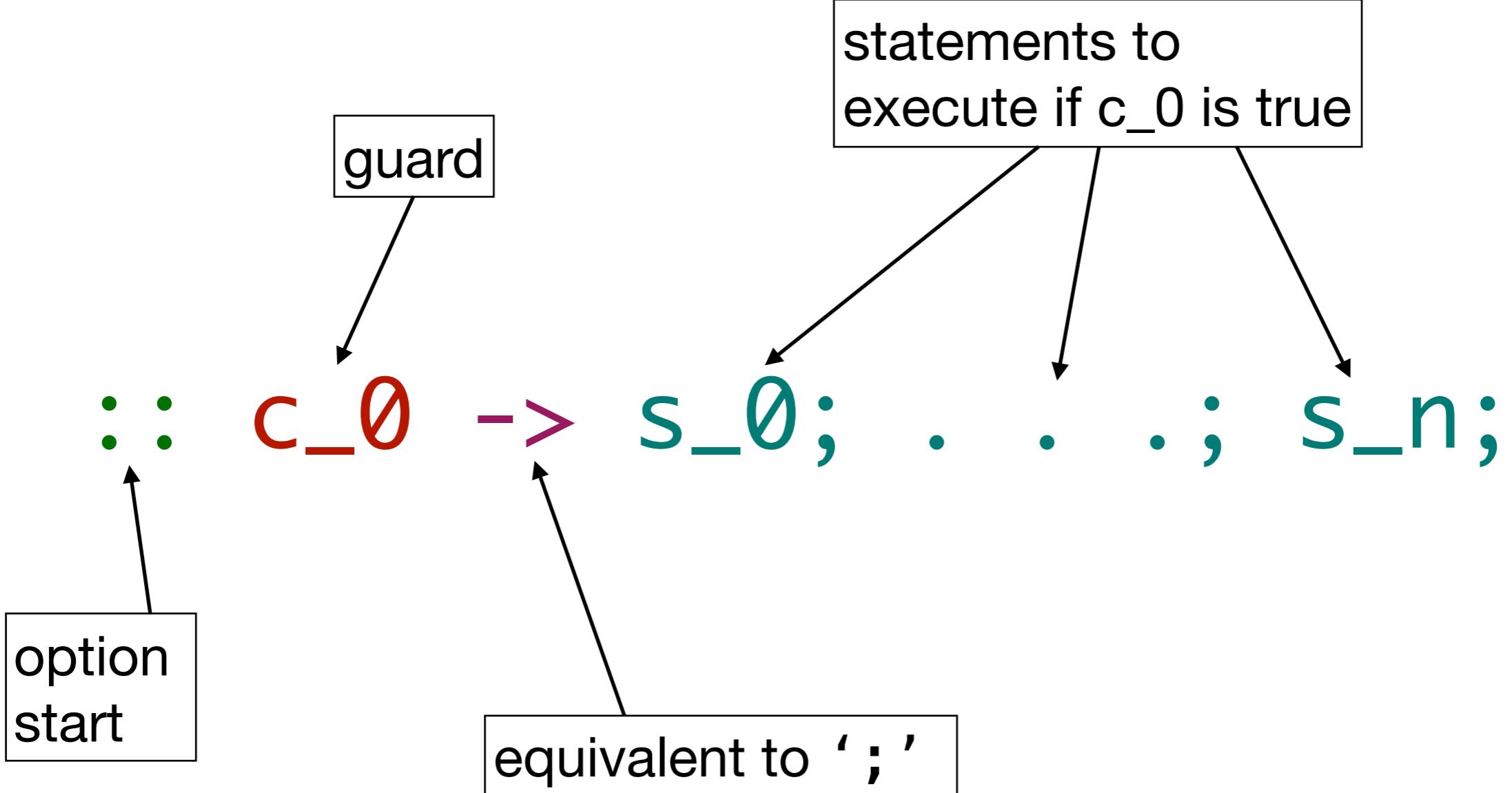
option start

⋮ ⋮ $c_0 \rightarrow s_0; \dots; s_n;$

A diagram illustrating the concept of an option start. A black rectangular box with a thin border contains the text "option start". An arrow originates from the bottom edge of this box and points upwards towards the first element of a sequence. The sequence is represented by three green dots (⋮) followed by a black dot (·), another black dot (·), another black dot (·), and a semicolon. To the right of the semicolon, there is a pair of identifiers: "c_0" and "s_0" separated by a right-pointing arrow (→). This visual cue indicates that the sequence of pairs begins with this specific element.







Guard Examples

Simple selection

if

```
::: (a == b) -> state = state + 1  
::: (a != b) -> state = state - 1
```

fi

Guard Examples

Simple selection with **else**

if

```
:: (a == b) -> state = state + 1  
:: else          -> state = state - 1
```

fi

NB! **else** is executable if no other statement *in the same process* is executable

Guard Examples

Guards may overlap → non-deterministic selection

```
a = 4; b = 4; x = 7;  
if  
    :: (a == b) -> b = 3  
    :: b = 3  
    :: (x >= 5) -> b = 3  
fi
```

NB! Any statement can be guard

Guard Examples

Greatest Common Divisor

```
do
    :: (m > n)      -> m = m - n
    :: (m < n)      -> n = n - m
    :: (m == n)     -> break
od;

printf("GCD = %d\n", m)
```

Guard Examples

skip statement

```
do
    :: !x -> break
    :: else -> skip
od
```

Guard Examples

skip statement as a guard

```
if
  :: (x == 1)    ->  x++
  :: (x == 2)    ->  x--
  :: skip        ->  // ...do smth by default...
fi;
```

Example: Atomicity

```
byte state = 1;

proctype A() {
    state == 1 -> state++
}

proctype B() {
    state == 1 -> state--
}

init{
    run A(); run B();
}
```

Example: Atomicity

```
byte state = 1;

proctype A() {
    state == 1 -> state++
}

proctype B() {
    state == 1 -> state--
}

init{
    run A(); run B();
}
```

Q: What is the final value of **state**?

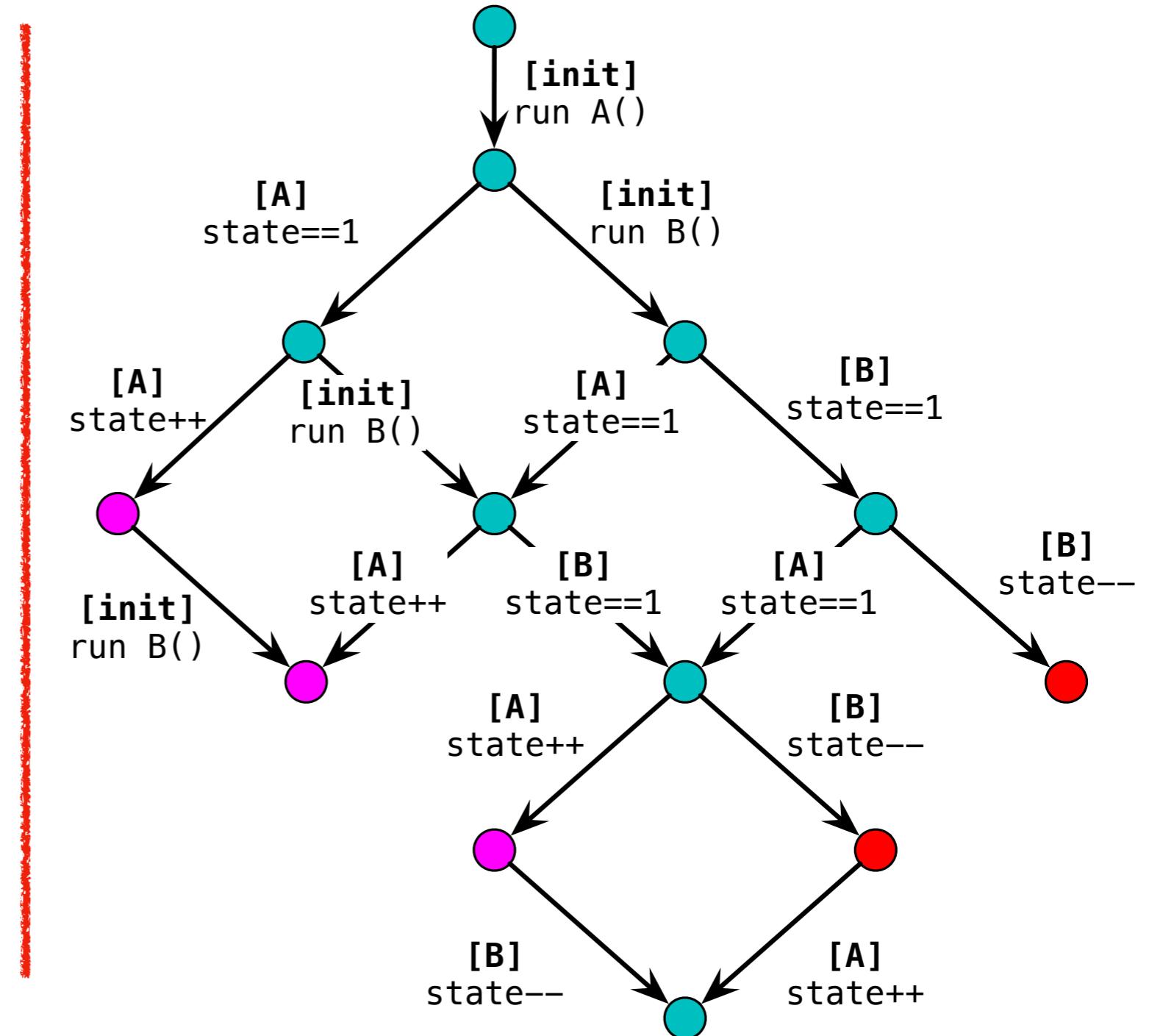
Example: Atomicity

```
byte state = 1;

proctype A() {
    state == 1 -> state++
}

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    state == 1 -> state--
}

init{
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}
```



Q: What is the final value of `state`?

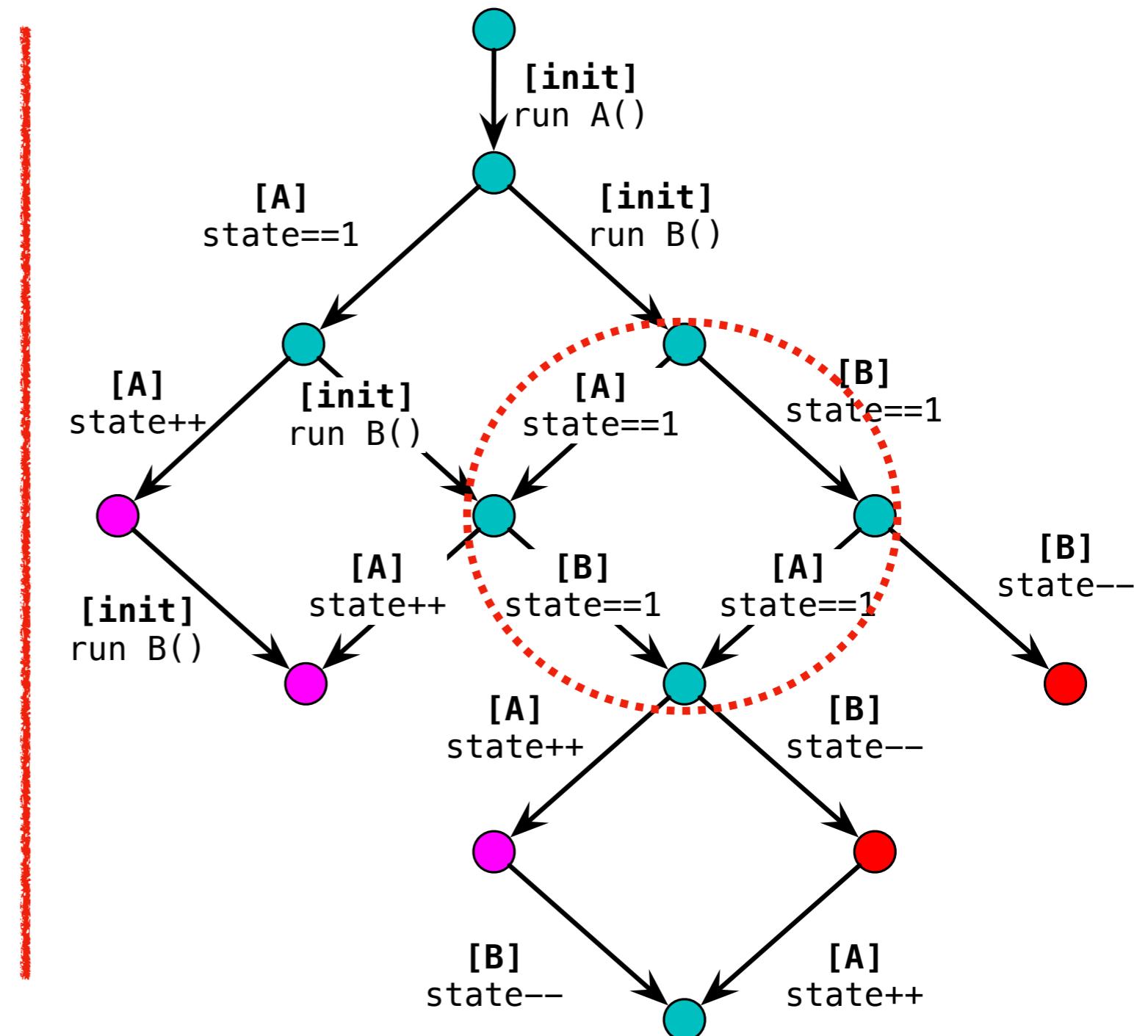
Example: Atomicity

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byte state = 1;

proctype A() {
    state == 1 -> state++
}

proctype B() {
    state == 1 -> state--
}

init{
    run A(); run B();
}
```



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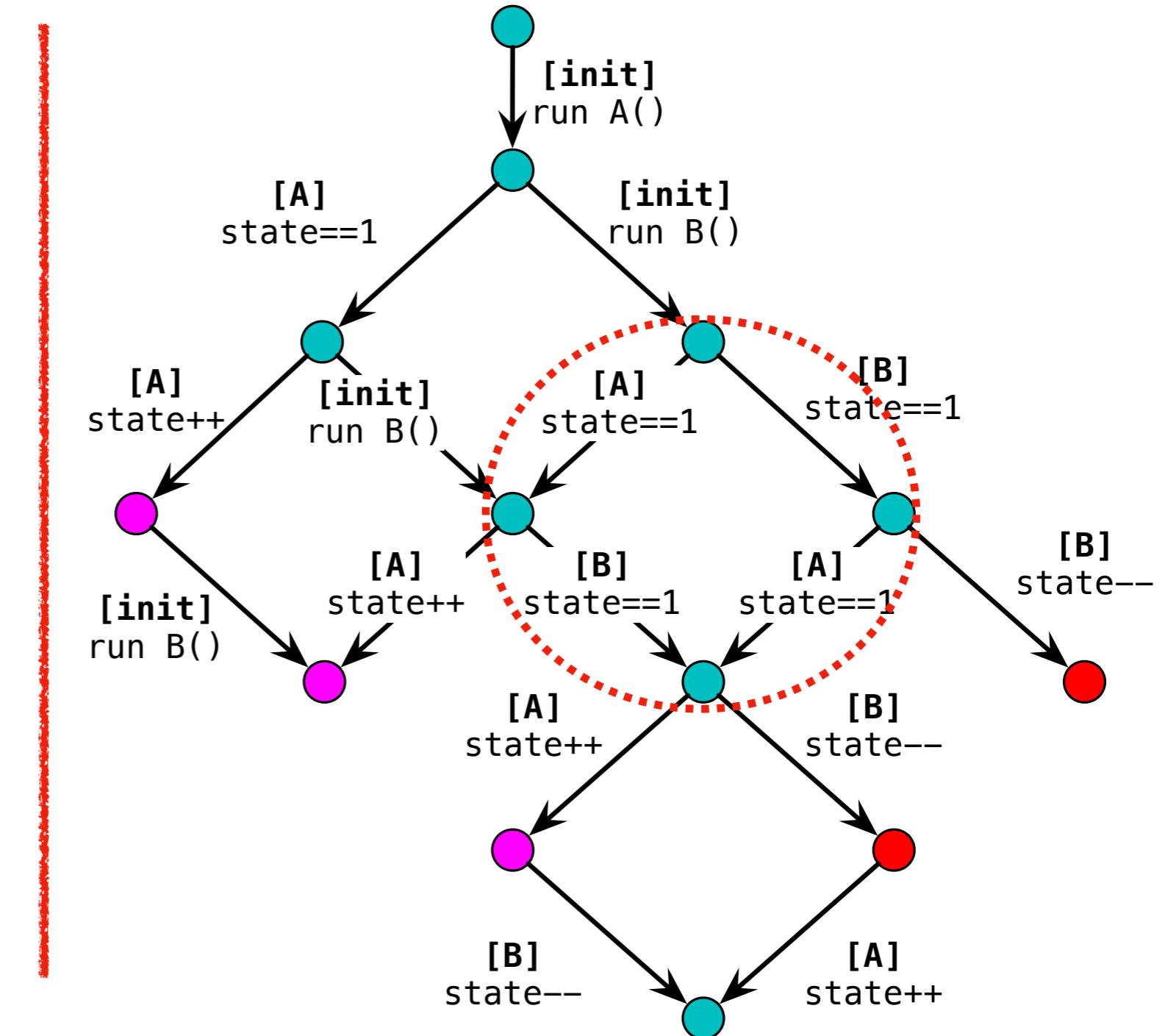
Example: Atomicity

```
byte state = 1;

proctype A() {
    atomic {
        state == 1 -> state++
    }
}

proctype B() {
    atomic {
        state == 1 -> state--
    }
}

init{
    atomic {
        run A(); run B();
    }
}
```



Q: What is the final value of **state**?

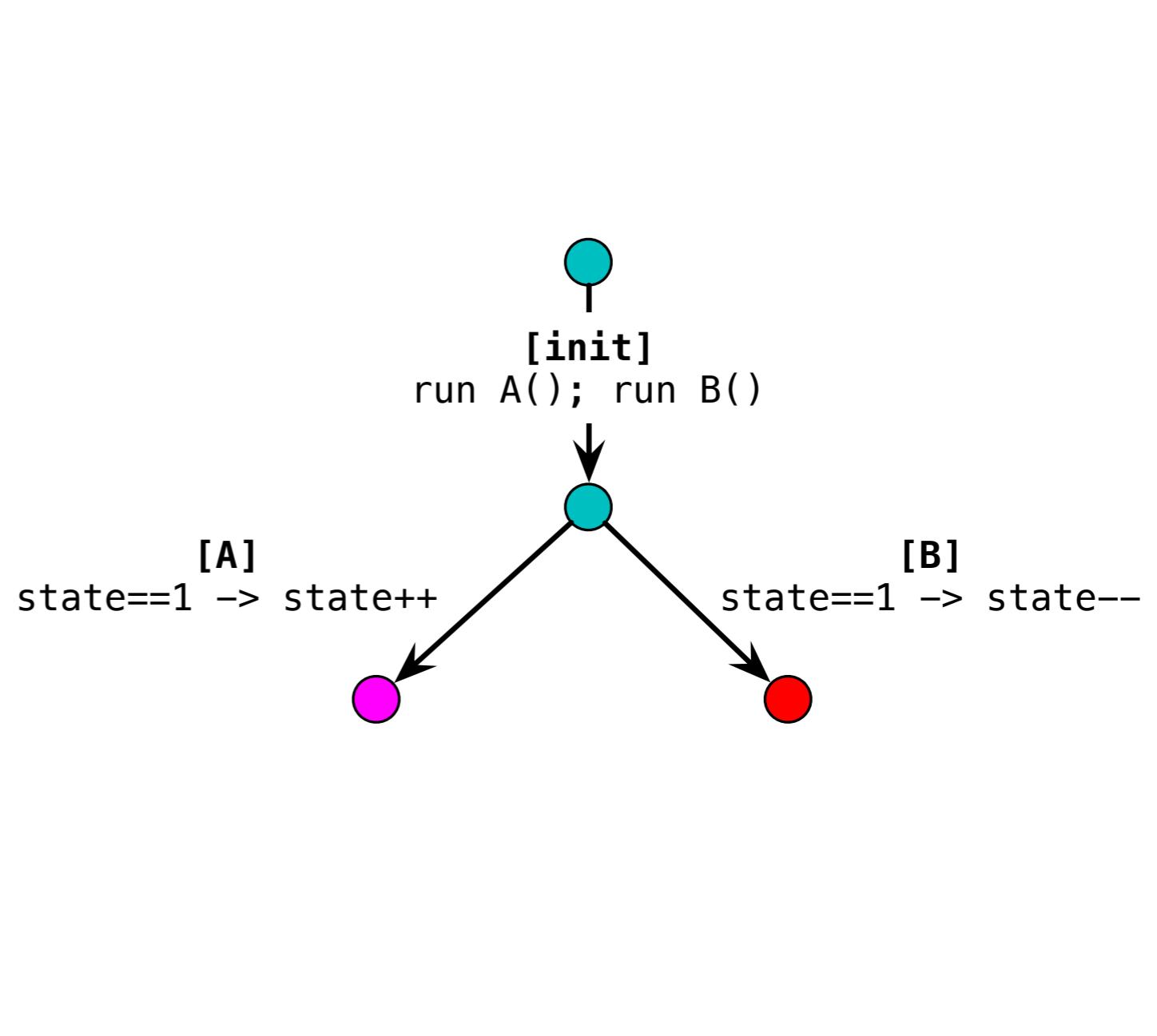
Example: Atomicity

```
byte state = 1;

proctype A() {
    atomic {
        state == 1 -> state++
    }
}

proctype B() {
    atomic {
        state == 1 -> state--
    }
}

init{
    atomic {
        run A(); run B();
    }
}
```



Q: What is the final value of `state`?

atomic

- A process whose control is inside **atomic { }** executes without being interrupted by other processes
- **NB!** Make sure that the sequence cannot be blocked inside. Otherwise, a process will be suspended.

Other use of **atomic**

To group complex manipulations into a single transition:

```
atomic {
    cnt = 0;

    do
        :: (cnt < max) -> z[cnt] = 3; cnt++
        :: (cnt >= max) -> break
    od
}
```

d_step

When the manipulations are deterministic and always executable, d_step is more efficient:

```
d_step {
    cnt = 0;

    do
        :: (cnt < max) -> z[cnt] = 3; cnt++
        :: (cnt >= max) -> break
    od
}
```

NB! If any statement inside d_step is blocked, you will get the run-time error

Guarded statements

timeout statement:

```
timeout -> s_0; . . . ; s_n;
```

- $s_0; . . . ; s_n$; execute only if no other processes are executable.
- it allows to escape deadlocks.

unless statement:

```
{s_0; . . . } unless {c_0 -> s_0'; . . . }
```

- $\{s_0; . . . \}$ execute until c_0 becomes true.
- $\{s_0'; . . . \}$ execute after c_0 becomes true.

Example: Shared Variable

```
mtype = {P, C};  
mtype turn = P;  
  
active proctype producer() {  
    do  
        :: (turn == P) ->  
            printf("Produce\n");  
            turn = C  
    od  
}  
  
active proctype consumer() {  
    do  
        :: (turn == C) ->  
            printf("Produce\n");  
            turn = P  
    od  
}
```

Example: Shared Variable

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mtype = {P, C};  
mtype turn = P;  
  
active proctype producer() {  
    do  
        :: (turn == P) ->  
            printf("Produce\n");  
            turn = C  
    od  
}  
  
active proctype consumer() {  
    do  
        :: (turn == C) ->  
            printf("Consume\n");  
            turn = P  
    od  
}
```

```
$ spin test1.pml  
Produce  
    Consume  
    Produce  
    ...  
1 process created
```

Example: Shared Variable

```
mtype = {P, C};  
mtype turn = P;  
  
active [2] proctype producer() {  
    do  
        :: (turn == P) ->  
            printf("Produce\n");  
            turn = C  
    od  
}  
  
active [2] proctype consumer() {  
    do  
        :: (turn == C) ->  
            printf("Produce\n");  
            turn = P  
    od  
}
```

Example: Shared Variable

```
mtype = {P, C};  
mtype turn = P;  
  
active [2] proctype producer() {  
    do  
        :: (turn == P) ->  
            printf("Produce\n");  
            turn = C  
    od  
}  
  
active [2] proctype consumer() {  
    do  
        :: (turn == C) ->  
            printf("Produce\n");  
            turn = P  
    od  
}
```

Q: Do you see the problem?

```

$ spin -i test1.pml
Select a statement
  choice 3: proc 1 (producer:1) test1.pml:4 (state 4) [((turn==P))]
  choice 4: proc 0 (producer:1) test1.pml:4 (state 4) [((turn==P))]
Select [1-4]: 3
Select a statement
  choice 3: proc 1 (producer:1) test1.pml:6 (state 2) [printf('Produce\\n')]
  choice 4: proc 0 (producer:1) test1.pml:4 (state 4) [((turn==P))]
Select [1-4]: 3
      Produce
Select a statement
  choice 3: proc 1 (producer:1) test1.pml:7 (state 3) [turn = C]
  choice 4: proc 0 (producer:1) test1.pml:4 (state 4) [((turn==P))]
Select [1-4]: 4
Select a statement
  choice 3: proc 1 (producer:1) test1.pml:7 (state 3) [turn = C]
  choice 4: proc 0 (producer:1) test1.pml:6 (state 2) [printf('Produce\\n')]
Select [1-4]: 4
      Produce
Select a statement
  choice 3: proc 1 (producer:1) test1.pml:7 (state 3) [turn = C]
  choice 4: proc 0 (producer:1) test1.pml:7 (state 3) [turn = C]
Select [1-4]:
  . . .

```

Both producers can pass the guard (**turn == P**)

Communication via Channels

Message Channels

- A channel is a **FIFO** message queue.
- A channel can be used to exchange messages among processes.
- Two channel types:
 - buffered channels and
 - synchronous channels (a.k.a. *rendezvous ports*).

Buffered Channels

- A channel storing up to 16 messages, each consisting of 3 fields if the listed types:
chan qname = [16] of {short, byte, bool}

Buffered Channels

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- Useful pre-defined functions:

len, empty, nempty, full, nfull

Buffered Channels

- A channel storing up to 16 messages, each consisting of 3 fields if the listed types:
chan qname = [16] of {short, byte, bool}

- Useful pre-defined functions:
len, empty, nempty, full, nfull

-
- Send a message: **qname!ex1, ex2, ex3.**
Process blocks if **qname** is full.
 - Receive a message: **qname?v1, v2, v3.**
Process blocks if **qname** is empty.

Buffered Channels

- A channel storing up to 16 messages, each consisting of 3 fields if the listed types:
chan qname = [16] of {short, byte, bool}

- Useful pre-defined functions:
len, empty, nempty, full, nfull

-
- Send a message: **qname!ex1, ex2, ex3.**
Process blocks if **qname** is full.
 - **Not-modifying** message receive: **qname?[v1, v2, v3].**
Process blocks if **qname** is empty.

Buffered Channels

- A channel storing up to 16 messages, each consisting of 3 fields if the listed types:

```
chan qname = [16] of {short, byte, bool}
```

- Alternative syntax for message send:

```
qname!ex1(ex2,ex3).
```

- Alternative syntax for message receive:

```
qname?v1(v2,v3).
```

Synchronous Channels

- A synchronous channel has size 0:
chan p = [0] of { byte }
- Messages are exchanged, not stored.
- Synchronous execution: a process executes send at the same time another process receives a message (atomic operation).

Example: Sync Channel

```
mtype = { msgtype };
chan glob = [0] of {mtype, byte};

active proctype A() {
    byte x = 124;
    printf("Send %d\n", x);
    glob!msgtype(x);

    x = 121;
    printf("Send %d\n", x);
    glob!msgtype(x);
}

active proctype B() {
    byte y;
    glob?msgtype(y);
    printf("Received %d\n", y);

    glob?msgtype(y);
    printf("Received %d\n", y);
}
```

Example: Sync Channel

```
mtype = { msgtype };
chan glob = [0] of {mtype, byte};

active proctype A() {
    byte x = 124;
    printf("Send %d\n", x);
    glob!msgtype(x);—  
    x = 121;
    printf("Send %d\n", x);
    glob!msgtype(x);—  
}

active proctype B() {
    byte y;
    glob?msgtype(y);—  
    printf("Received %d\n", y);

    glob?msgtype(y);—  
    printf("Received %d\n", y);
}
```

Example: Sync Channel

```
mtype = { msgtype };  
chan glob = [0] of {mtype, byte};
```

```
active proctype A() {  
    byte x = 124;  
    printf("Send %d\n", x);  
    glob!msgtype(x);—  
  
    x = 121;  
    printf("Send %d\n", x);  
    glob!msgtype(x);—  
}
```

```
active proctype B() {  
    byte y;  
    glob?msgtype(y);—  
    printf("Received %d\n");  
  
    glob?msgtype(y);—  
    printf("Received %d\n");  
}
```

```
$ spin Test1.pml  
Send 124  
Send 121  
Received 124  
Received 121  
2 processes created
```

Sorted Send !!

- A message is inserted into a channel before the first message that follows it in a numerical order.
- Syntax: `chname!!value`.
- e.g.
 - `c!3; c!1;` gives `c([3, 1])`.
 - `c!!3; c!!1;` gives `c([1, 3])`.

Random Receive ??

- Executable if there is at least one message the channel that can be received, **regardless of its position.**
- Syntax: chname??value.
- given c([3, 1])
 - c?1 is blocked since 1 is not accessible but
 - c??1 will work.

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf(<<(%d,%d)\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;   c!!1,1;
    c!!1,3;   c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(%d,%d)\n", v1, 1)
    od
}
```

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf(<<(%d,%d)\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;   c!!1,1;
    c!!1,3;   c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(%d,%d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

Example: Senders and Receivers

```
proctype S1() {  
    c!1,2;    c!1,1;  
    c!1,3;    c!0,1;  
}  
  
proctype R1() {  
    do  
        :: c?v1,v2 ->  
        printf(<<(%d,%d)\n", v1, v2)  
    od  
}  
  
proctype S2() {  
    c!!1,2;   c!!1,1;  
    c!!1,3;   c!!0,1;  
}  
  
proctype R2() {  
    do  
        :: c??v1,1 ->  
        printf("(%d,%d)\n", v1, 1)  
    od  
}
```

Q: What will the receiver print?

(1,2) (1,1) (1,3) (0,1)

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf("%d,%d\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;   c!!1,1;
    c!!1,3;   c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(d,d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf("%d,%d\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;   c!!1,1;
    c!!1,3;   c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(d,d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

(1,1) (0,1)

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf(<<(%d,%d)\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;   c!!1,1;
    c!!1,3;   c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(%d,%d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf(<<(%d,%d)\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;    c!!1,1;
    c!!1,3;    c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf(" (%d,%d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

(0,1) (1,1) (1,2) (1,3)

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf("%d,%d\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;    c!!1,1;
    c!!1,3;    c!!0,1;
}

proctype R2() {
    do
        :: c?v1,1 ->
            printf("(d,d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

Example: Senders and Receivers

```
proctype S1() {
    c!1,2;    c!1,1;
    c!1,3;    c!0,1;
}

proctype R1() {
    do
        :: c?v1,v2 ->
            printf("%d,%d\n", v1, v2)
    od
}

proctype S2() {
    c!!1,2;    c!!1,1;
    c!!1,3;    c!!0,1;
}

proctype R2() {
    do
        :: c??v1,1 ->
            printf("(d,d)\n", v1, 1)
    od
}
```

Q: What will the receiver print?

(0,1) (1,1)

Labels

End-state labels

- are used to mark **valid end-states** and tell them apart from deadlocks,
- includes any label starting with '**end**'.

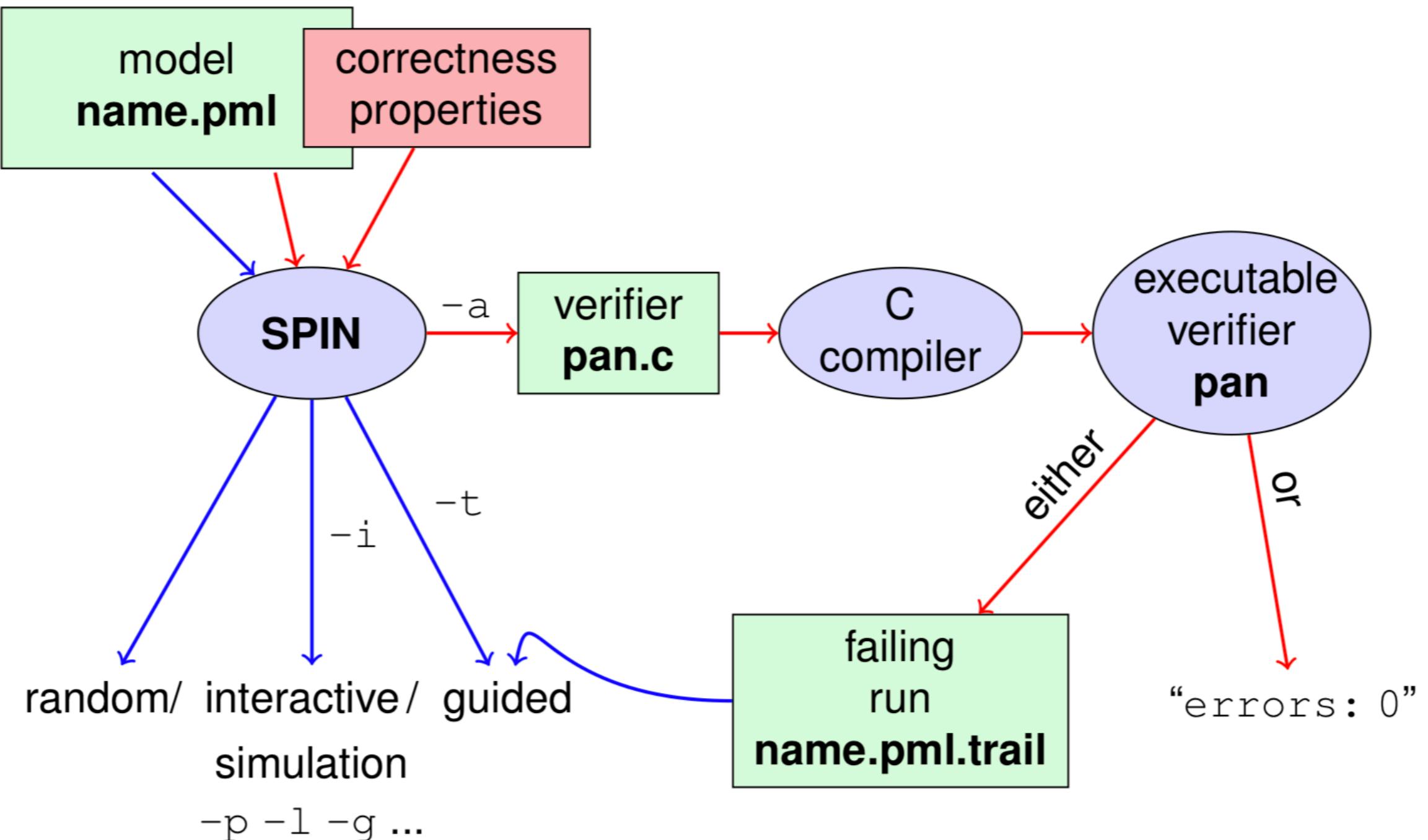
By **default**, the only valid end-state is reached when the process reaches the *syntactic end* of its body.

Progress-state Labels

- are used to mark a state that must be executed for a process to make progress (~liveness),
- includes any label starting with '**progress**'.

Any infinite cycle that does not cross a progress state is a potential starvation loop.

Basic Verification



Assertions

```
chan com = [0] of {byte};
byte var;

proctype p() {
    byte i;
    do
        :: if
            :: i >= 5 -> break;
            :: else -> printf(«Doing something else\n»); i++
        fi
        :: com ? var -> printf(«p received %d\n», var)
    od
}

init {
    run p();
    end: com ! 100;
}
```

Assertions

```
chan com = [0] of {byte};
byte var;

proctype p() {
    byte i;
    do
        :: if
            :: i >= 5 -> break;
            :: else -> printf(«Doing something else\n»); i++
        fi
        :: com ? var -> printf(«p received %d\n», var)
    od
}

init {
    run p();
    end: com ! 100;
}
```

Q: Is it possible that **p** does not read from **com** at all?

Assertions

```
chan com = [0] of {byte};
byte var;

proctype p() {
    byte i;
    do
        :: if
            :: i >= 5 -> break;
            :: else -> printf(«Doing something else\n»); i++
        fi
        :: com ? var -> printf(«p received %d\n», var)
    od
}

init {
    run p();
    end: com ! 100; // end is not a deadlock
}
```

Q: Is it possible that **p** does not read from **com** at all? **YES**

```

$ spin -i Test1.pml
Select a statement
  choice 1: proc 1 (p:1) Test1.pml:5 (state 10) [IF]
  choice 3: proc 0 (:init::1) Test1.pml:16 (state 2) <valid end state> [com!100]
Select [1-3]: 1
Select stmt (proc 1 (p:1) )
  choice 0: other process
Select [0-2]: 2
Select a statement
  choice 1: proc 1 (p:1) Test1.pml:8 (state 4) [printf('Doing something else\n')]
Select [1-2]: 1
  Doing something else
Select a statement
  choice 1: proc 1 (p:1) Test1.pml:8 (state 5) [i = (i+1)]
Select [1-2]: 1
  .
  .
  choice 1: proc 1 (p:1) Test1.pml:8 (state 4) [printf('Doing something else\n')]
Select [1-2]: 1
  Doing something else
  .
  .
  Doing something else
  .
  .
  Doing something else
  .
  .
  Doing something else
Select stmt (proc 1 (p:1) )
  choice 0: other process
  choice 1: ((i>=5))
Select [0-2]: 1
Select a statement
  choice 1: proc 1 (p:1) Test1.pml:5 (state 12) [break]
Select [1-2]: 1
  .
  .
#processes: 1
  var = 0
18: proc 0 (:init::1) Test1.pml:16 (state 2) <valid end state>
2 processes created

```

interactive simulation

Assertions

```
chan com = [0] of {byte};
byte var;

proctype p() {
    byte i;
    do
        :: if
            :: i >= 5 -> break;
            :: else -> printf(<<Doing something else\n>>); i++
        fi
        :: com ? var -> printf(<<p received %d\n>>, var)
    od
    assert(var == 100); // check the value of var
}

init {
    run p();
    end: com ! 100; // end is not a deadlock
}
```

Q: Is it possible that **p** does not read from **com** at all? **YES**

```
$ spin -a Test1.pml && gcc -o pan pan.c && ./pan
pan:1: assertion violated (var==100) (at depth 12)
pan: wrote Test1.pml.trail
```

checks assertions

(Spin Version 6.4.9 -- 17 December 2018)

Warning: Search not completed
+ Partial Order Reduction

indicates sequence of
steps leading to errors

Full statespace search for:

never claim - (none specified)
assertion violations +
acceptance cycles - (not selected)
invalid end states +

State-vector 36 byte, depth reached 12, errors: 1

13 states, stored
0 states, matched
13 transitions (= stored+matched)
0 atomic steps
hash conflicts: 0 (resolved)

Stats on memory usage (in Megabytes):

0.001 equivalent memory usage for states (stored*(State-vector + overhead))
0.291 actual memory usage for states
128.000 memory used for hash table (-w24)
0.534 memory used for DFS stack (-m10000)
128.730 total actual memory usage

pan: elapsed time 0 seconds

```

$ spin -t -p Test1.pml ←
Starting p with pid 1
 1: proc 0 (:init::1) Test1.pml:16 (state 1)[(run p())]
 2: proc 1 (p:1) Test1.pml:8 (state 3)[else]
    Doing something else
 3: proc 1 (p:1) Test1.pml:8 (state 4)[printf('Doing something else\n')]
 3: proc 1 (p:1) Test1.pml:8 (state 5)[i = (i+1)]
 4: proc 1 (p:1) Test1.pml:8 (state 3)[else]
    Doing something else
 5: proc 1 (p:1) Test1.pml:8 (state 4)[printf('Doing something else\n')]
 5: proc 1 (p:1) Test1.pml:8 (state 5)[i = (i+1)]
 6: proc 1 (p:1) Test1.pml:8 (state 3)[else]
    Doing something else
 7: proc 1 (p:1) Test1.pml:8 (state 4)[printf('Doing something else\n')]
 7: proc 1 (p:1) Test1.pml:8 (state 5)[i = (i+1)]
 8: proc 1 (p:1) Test1.pml:8 (state 3)[else]
    Doing something else
 9: proc 1 (p:1) Test1.pml:8 (state 4)[printf('Doing something else\n')]
 9: proc 1 (p:1) Test1.pml:8 (state 5)[i = (i+1)]
10: proc 1 (p:1) Test1.pml:8 (state 3)[else]
    Doing something else
11: proc 1 (p:1) Test1.pml:8 (state 4)[printf('Doing something else\n')]
11: proc 1 (p:1) Test1.pml:8 (state 5)[i = (i+1)]
12: proc 1 (p:1) Test1.pml:7 (state 1)[((i>=5))]
spin: Test1.pml:12, Error: assertion violated
spin: text of failed assertion: assert((var==100))
13: proc 1 (p:1) Test1.pml:12 (state 13)[assert((var==100))]
spin: trail ends after 13 steps
#processes: 2
  var = 0
13: proc 1 (p:1) Test1.pml:13 (state 14) <valid end state>
13: proc 0 (:init::1) Test1.pml:17 (state 2) <valid end state>
2 processes created

```

replays the error-trail

Time for exercises...