

Walchand College of Engineering (Government Aided Autonomous Institute)

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Computer Algorithms

Shortest Path Algorithms

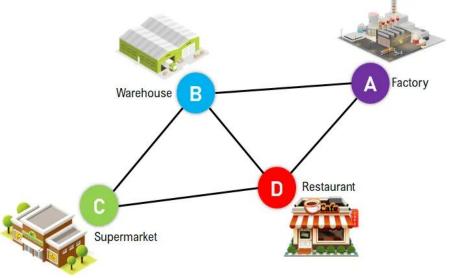
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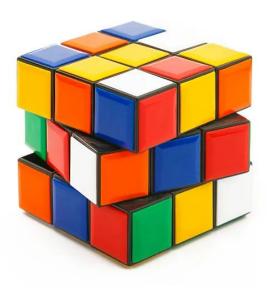
D B Kulkarni

Information Technology Department

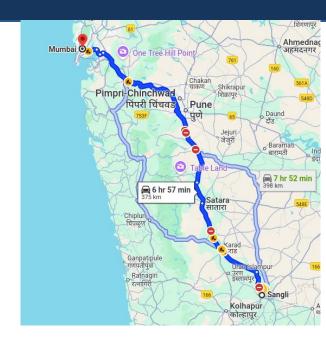


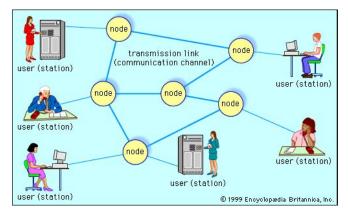
Shortest path: Applications





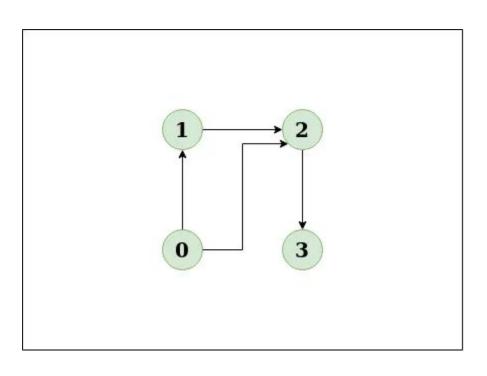
- Automatic direction finding between physical locations, such as driving directions on web mapping websites like Google Maps.
- Solving puzzles, like finding the minimum number of moves to solve a Rubik's Cube.
- Minimizing delay and maximizing bandwidth in telecommunications networks





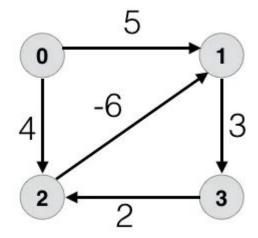


Shortest path: Definitions



Given weighted graph G

- Path: Weighted
 - Shortest path (SP)
- > Cycle (2,1,3,1)
- Negative weight w(2,1)
- Negative weight Cycle



Terminologies/ notations

Weight- w(u,v), Path- $p(u\rightarrow v)$,

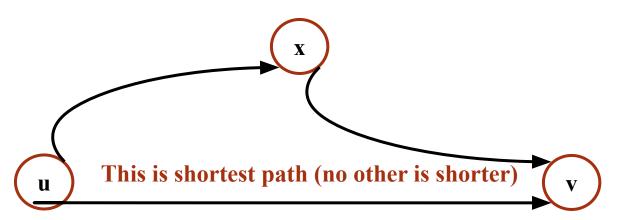
Weight of path- $w(p)=w(p(u\rightarrow v))$

Weight of Shortest path (P)- $\delta(u,v)$ = $min(w(p):u\sim v)$



Properties of SP

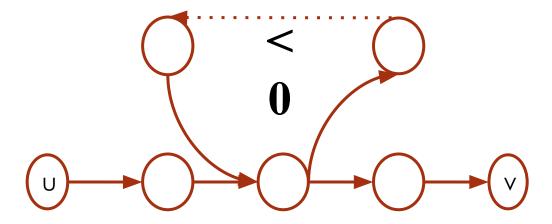
- ightharpoonup Triangle inequality $\delta(u,v) = \delta(u,x) + \delta(x,v)$
- > Upper bound v.d≥δ(s,v)
- No path
- \succ If there is no path from s to v , v.d=δ(s,v)=∞
- Convergence
- > Path relaxation
- Predecessor graph





Complexities

- Edge weights can be negative
- > Negative weight cycle





Shortest path: Variants

- Single Pair Shortest Path (SPSP)
- Single Source Shortest Path (SSSP)
- **S**ingle **D**estinations **S**hortest **P**ath (SDSP)
- All Pair Shortest Path (APSP)

Can we use SPSP to solve other SP variants?



Shortest path

- > Shortest path: Given weighted directed graph, G(V,E) find min weight path from given source vertex u to another vertex v
- The weight w of path p^1 from u to v, $w(p_{u,v}^1)=v_u,v_1,v_2,...,v_k,v_v$ is the sum of weight of constituent edges

$$w(p(v_0->v_k))=\sum_{i=0}^k w(v_{i-1},v_i)$$

> shortest path weight $\delta(u,v)$ to be the shortest path from u to v defined as

$$\delta(\cup,\vee) = \begin{cases} \min\{w(p): u \sim v\} \\ \infty & Otherwise \end{cases}$$



SP: Solution formulation

- For graph G=(V,E), S is the starting vertex, for each vertex νεV we maintain
 - ightharpoonup predecessor vertex v. Π , which can be other vertex or NIL.
 - Shortest path estimate v.d, path length from s to v, is upper bound on weight of shortest path from source S to v, which is ∞ at the beginning.
 - Initialization: For each vertex v εG.V
 - v.d= ∞
 - V.□=NIL
 - S.d=0
- (RELAX) Relaxing the edge (u,v) is testing whether we can improve the shortest path from S to v, found so far by going through u
 - if so updating v.d and V. □

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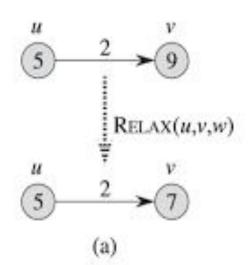


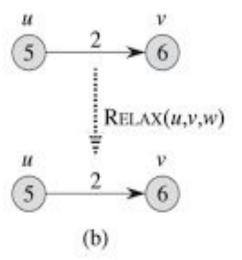
Relaxation

- Relaxing the edge (u,v) is testing whether we can improve the shortest path from S to v, found so far by going through u
 - o if so updating v.d and V. □

V. ∏=∪ }

RELAX (u,v,w) if v.d>u.d+w(u,v) o { v.d=u.d+w(u,v)







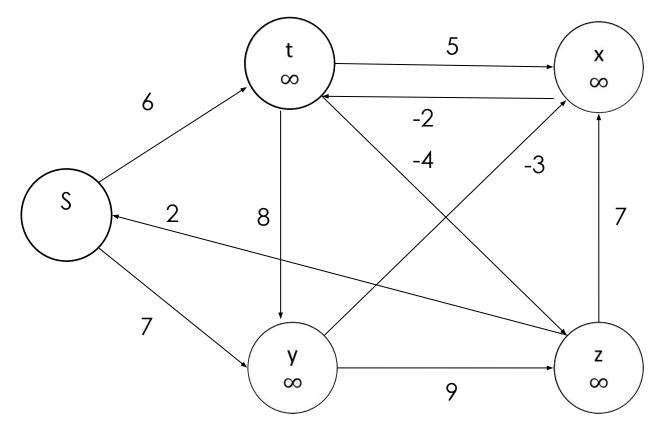
Bellman Ford (BF) Algorithm (SSSP)

- computes <u>shortest paths</u> from a single source <u>vertex</u> to all of the other vertices in a <u>weighted digraph</u>
 - If negative weight cycle is reachable, it exits
- Steps
 - Step 1: initialize
 - ► For all vertices $v. \square = NIL$, $v.d = \infty$, s.d = 0
 - Step 2: relax edges repeatedly
 - For (#vertices-1)
 - For all edges RELAX
 - Step 3: check for negative-weight cycles
 - ► For each edges <u,v>- if u.d+w <v.d then graph contains negative weight cycle

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Edges: (t,x)(t,y)(t,z)(x,t)(y,x)(y,z)(z,x)(z,s)(s,t)(s,y)



Vetrices:5

Steps

Step 1: Initialize graph

S.d=0

For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for

(#vertices -1) times

Check for negative weight cycle Step 3:

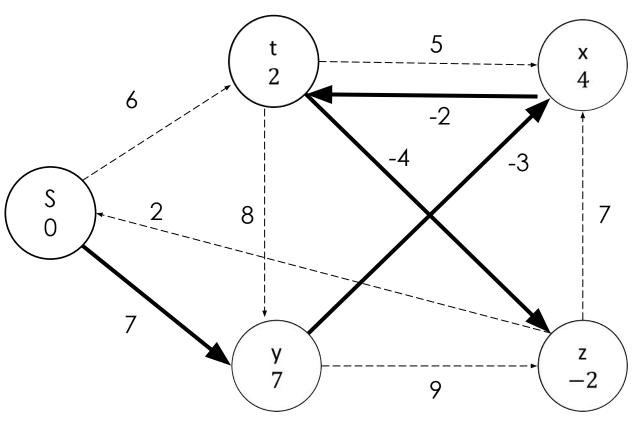
for each edge <u,v>

if u.d+w <v.d

then -ve wt cycle present



Bellman Ford Algorithm: Final status



Steps

Step 1: Initialize graph

S.d=0

For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for

(#vertices -1) times

Step 3: Check for negative weight cycle

for each edge <u,v>

if u.d+w <v.d

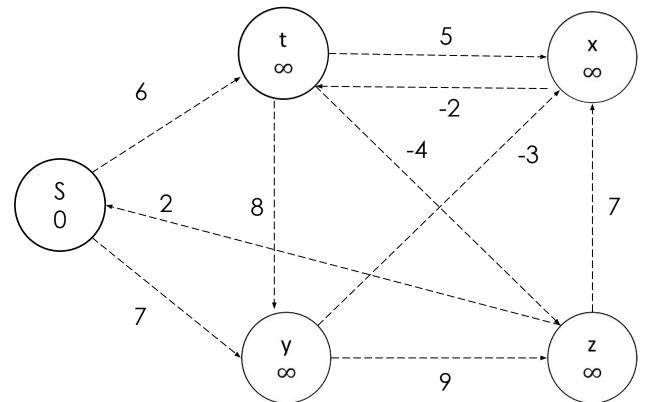
then -ve wt cycle present



Step: 1 Initialization

Edges:

- 1. (†,x)
- 2. (t,y)
- 3. (t,z)
- 4. (x,t)
- 5. (y,x)
- 6. (y,z)
- 7. (z,x)
- 8. (z,s)
- 9. (s,t)
- 10. (s,y)



Vetrices:5

Steps

Step 1: Initialize graph

S.d=0

For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

Step 3: Check for negative weight cycle

for each edge <u,v>

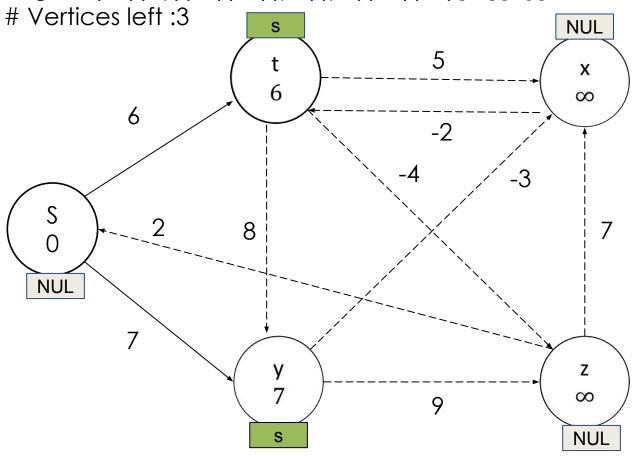
if u.d+w <v.d

then -ve wt cycle present



Step 2: Iteration: 1 (Vertices-4)

Edges: (t,x)(t,y)(t,z)(x,t)(y,x)(y,z)(z,x)(z,s)(s,t)(s,y)



Steps

Step 1: Initialize graph S.d=0For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

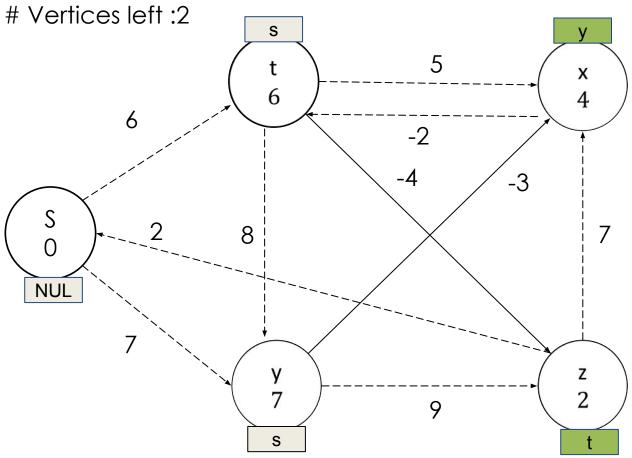
Step 3: Check for negative weight cycle

> for each edge <u,v> if u.d+w <v.d then -ve wt cycle present



Step 2: Iteration: 2 (Vertices-3)

Edges: (t,x)(t,y)(t,z)(x,t)(y,x)(y,z)(z,x)(z,s)(s,t)(s,y)



Steps

Step 1: Initialize graph
S.d=0
For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

Step 3: Check for negative weight cycle

for each edge <u,v>
if u.d+w <v.d
then -ve wt cycle present

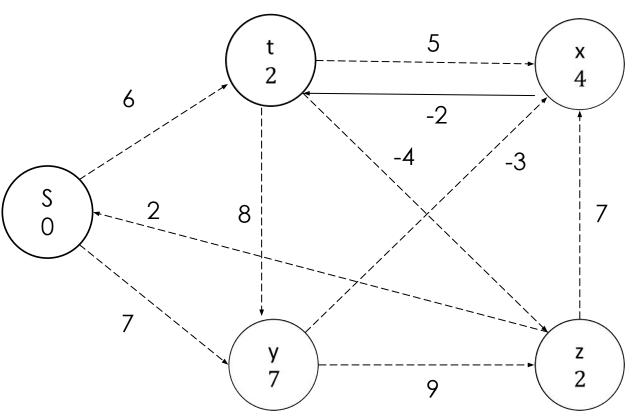
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Step 2: Iteration: 3 (Vertices-2)

Edges: (t,x)(t,y)(t,z)(x,t)(y,x)(y,z)(z,x)(z,s)(s,t)(s,y)

Vertices left:1



Steps

Step 1: Initialize graph
S.d=0
For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

Step 3: Check for negative weight cycle

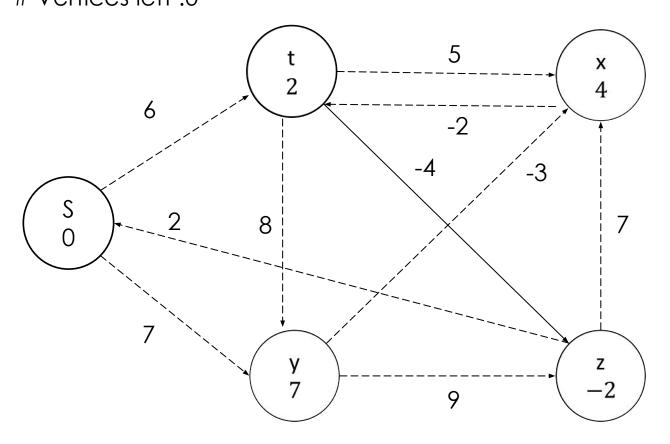
for each edge <u,v>
if u.d+w <v.d
then -ve wt cycle present

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Step 2: Iteration : 4 (Vertices-1)Edges : (†,x)(†,y)(†,z)(x,†)(y,x)(y,z)(z,x)(z,s)(s,†)(s,y)

Vertices left:0



Steps

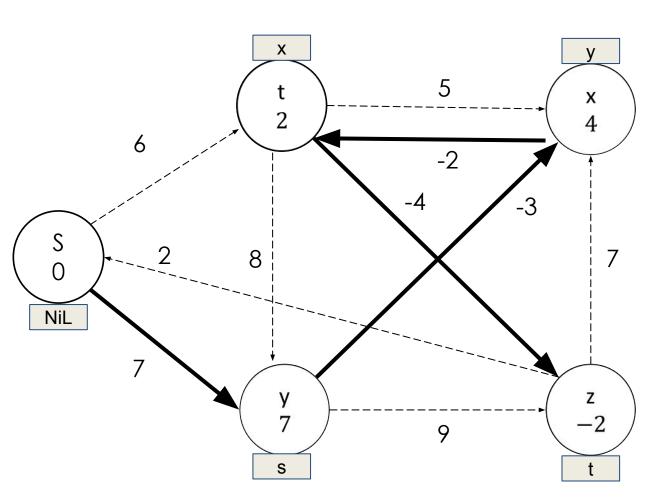
Step 1: Initialize graph S.d=0For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

Step 3: Check for negative weight cycle

> for each edge <u,v> if u.d+w <v.d then -ve wt cycle present





Steps

Step 1: Initialize graph
S.d=0
For all vertices v.d=∞, v.π=NIL

Step 2: Relax all edges repeatedly for (#vertices -1) times

Step 3: Check for negative weight cycle

for each edge <u,v>
if u.d+w <v.d
then -ve wt cycle present

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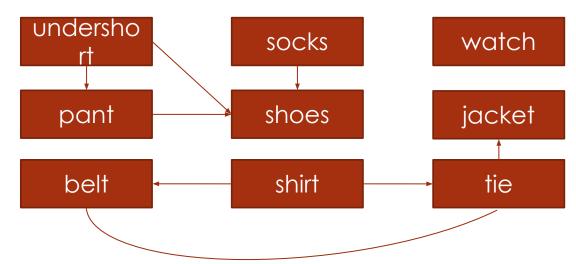
Bellman Ford Algorithm: Analysis

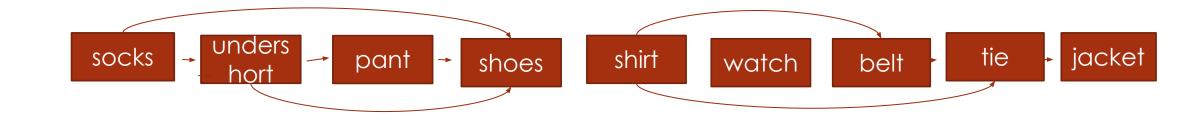
- Complexity V*E
- Order in which the edges are processed affects how quickly the algorithm converges



SSSP in DAG

- If edge relaxation is carried out in some order (as per topological sort order of the vertices), SP can be computed in (V+E) time
- Topological sort: For DAG, its linear ordering of all vertices such that for edge (u,v)u appears before v in ordering.





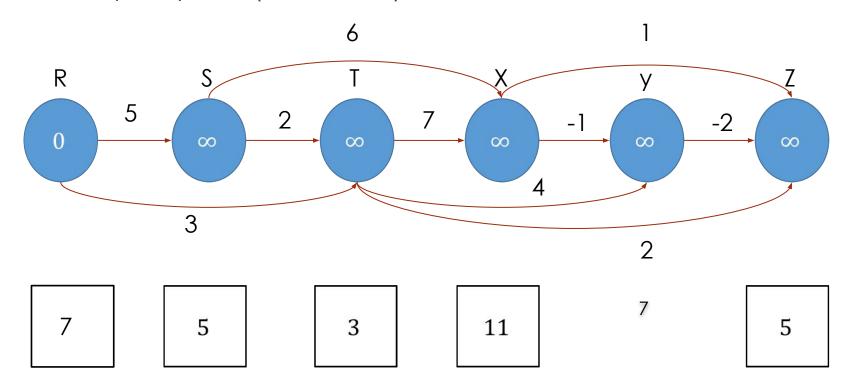


SSSP in DAG: Example

Algorithm

For each vertex u taken in topological order

- For each vertex v&G Adj[u]
- RELAX(u,v,w)
- Complexity- V+E (home work)

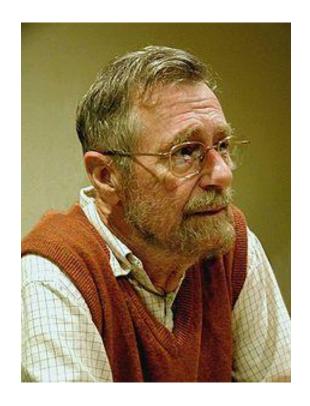




EDSGER WYBE DIJKSTRA

May 11, 1930 – August 6, 2002

"Computer Science is no more about computers than astronomy is about telescopes."





Dijkstra's Algorithm

- > If no negative edge weights, we can beat BF
 - No negative weight cycle?
 - Use a priority queue keyed on d[v]

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SSSP: DIJKSTRA'S ALGORITHM

- Works on both directed and undirected graphs.
- > However, all edges must have nonnegative weights.

Approach: Greedy

- Similar to breadth-first search
 - Grow a tree gradually, advancing from vertices taken from a queue
- Also similar to Prim's algorithm for MST

Input: Weighted graph $G=\{E,V\}$ and source vertex $v \in V$, such that all edge weights are nonnegative

Output: Lengths of shortest paths

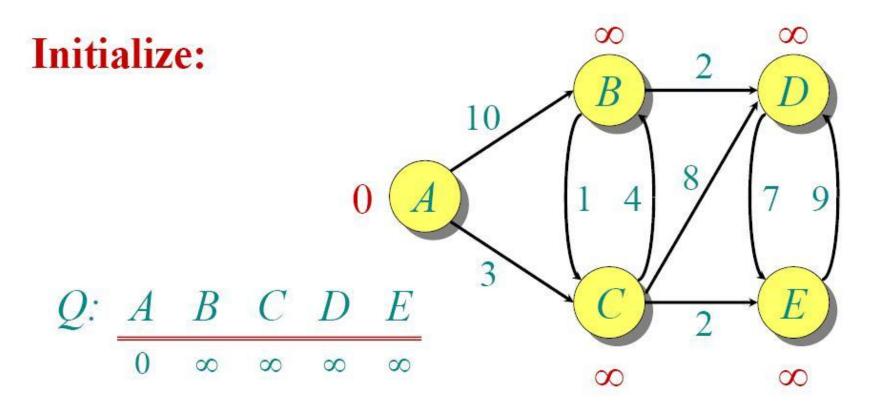


Dijkstra's Algorithm - pseudocode

```
S- Set containing vertices
s- starting vertex (root)
          S←Ø
                                    (S, the set of visited vertices is initially empty)
          Q←V
                                    (Q, the queue initially contains all vertices)
          s.d ←o
                                    (distance to source vertex is zero)
          for all v \in V-\{s\}
          do v.d \leftarrow \infty
                                    (set all other distances to infinity)
        while Q ≠∅
                                             (while the queue is not empty)
        do u \leftarrow mindistance(Q,dist)
                                            (select the element of Q with the min. distance)
        S \leftarrow S \cup \{u\}
                                             (add u to list of visited vertices)
        for all v \in neighbors[u]
             do if v.d > u.d + w(u, v) (if new shortest path found)
                  then v.d \leftarrow u.d + w(u, v) (set new value of shortest path)
        return v.d
```

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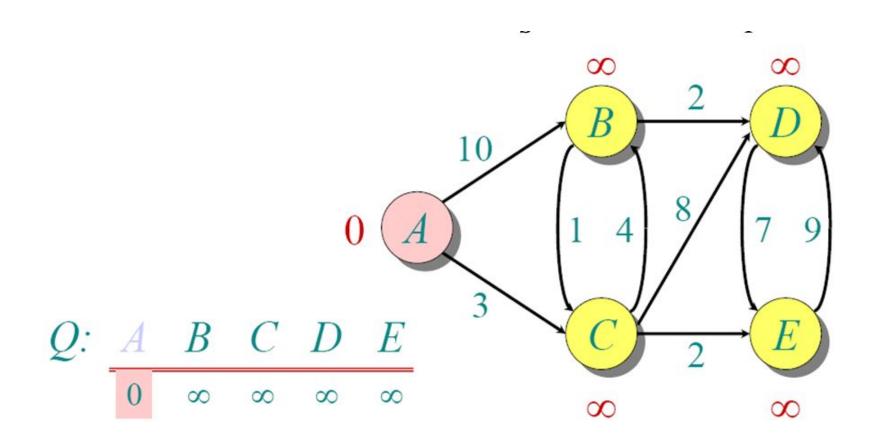




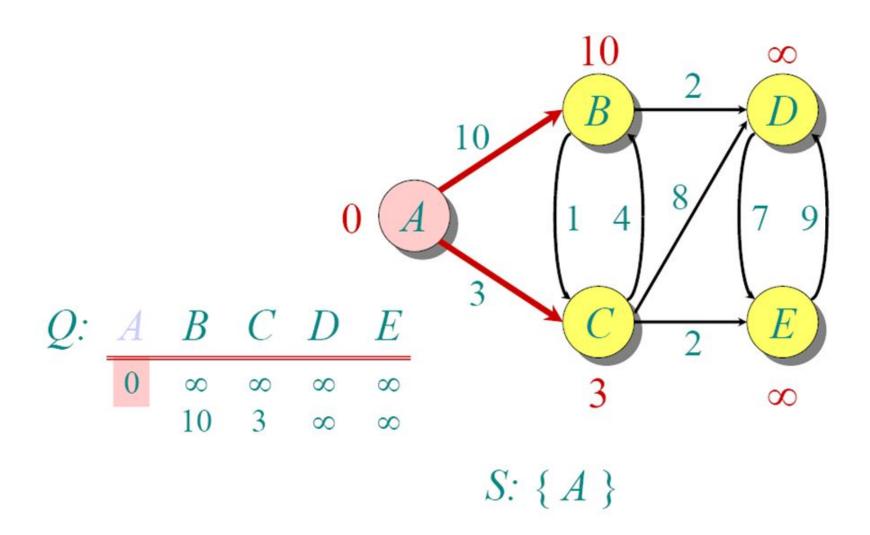
S: {}

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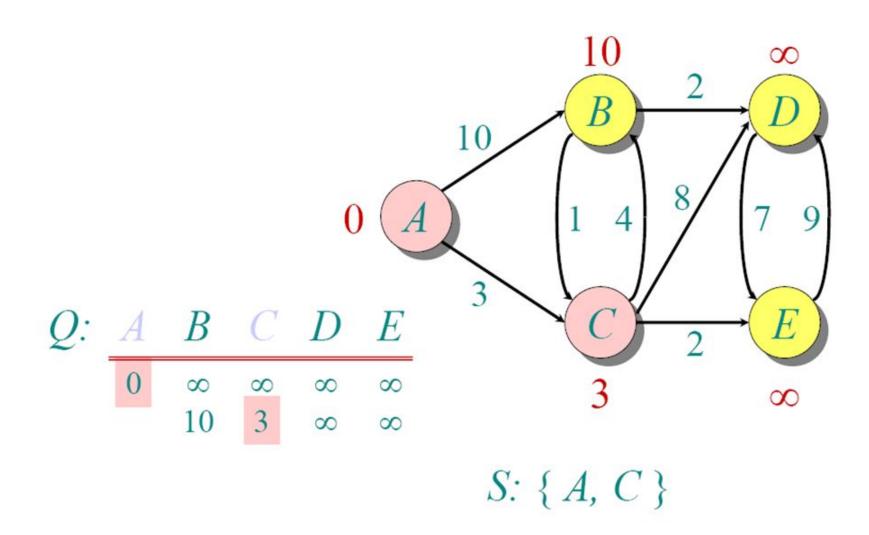




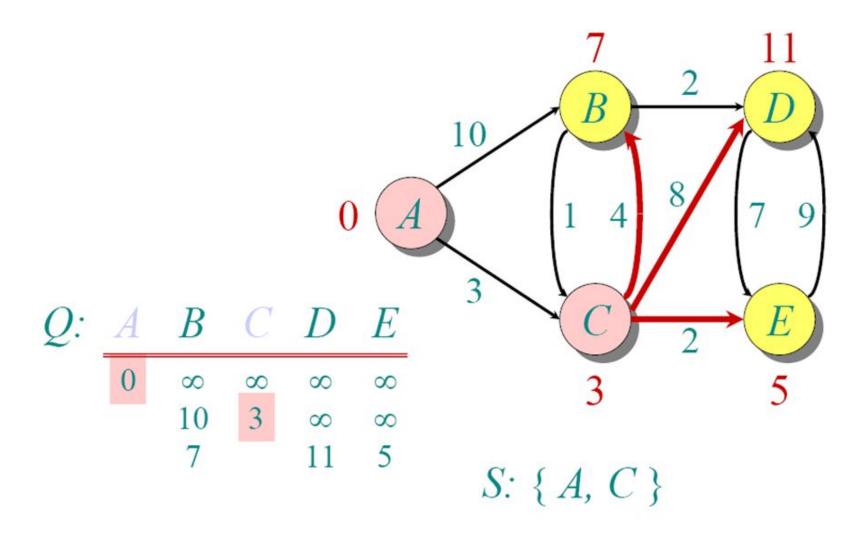






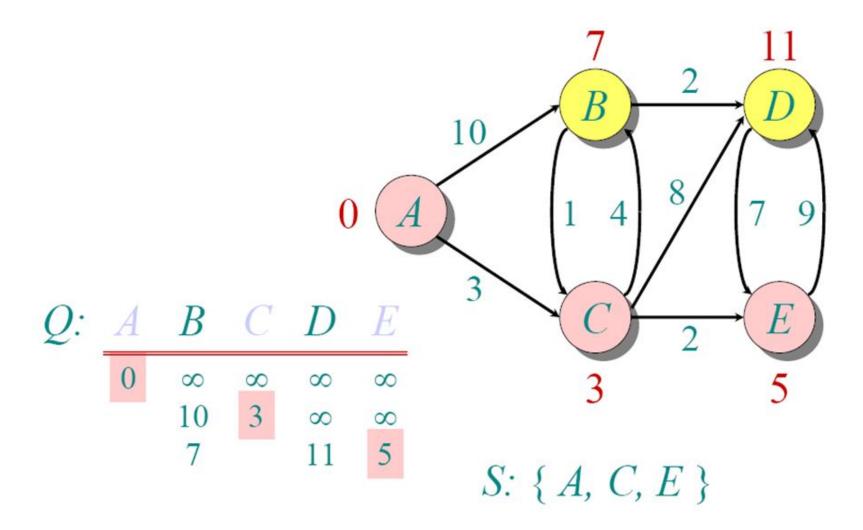






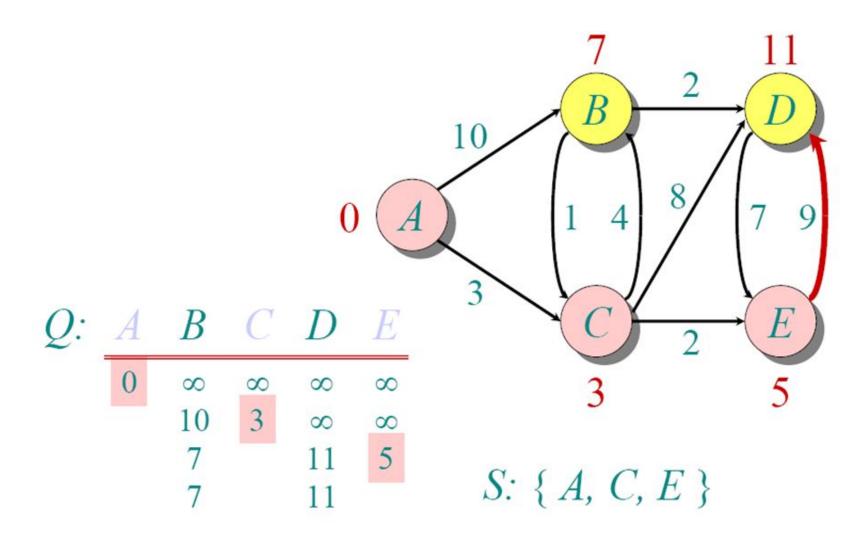
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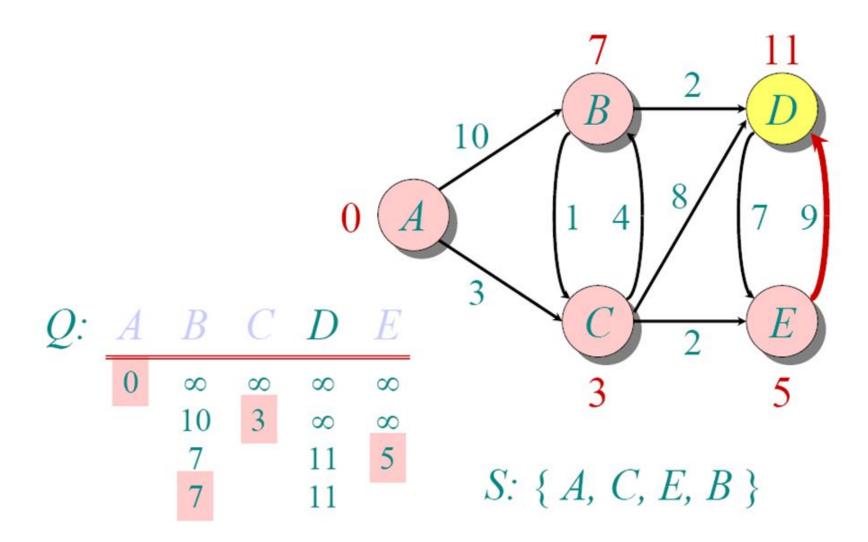
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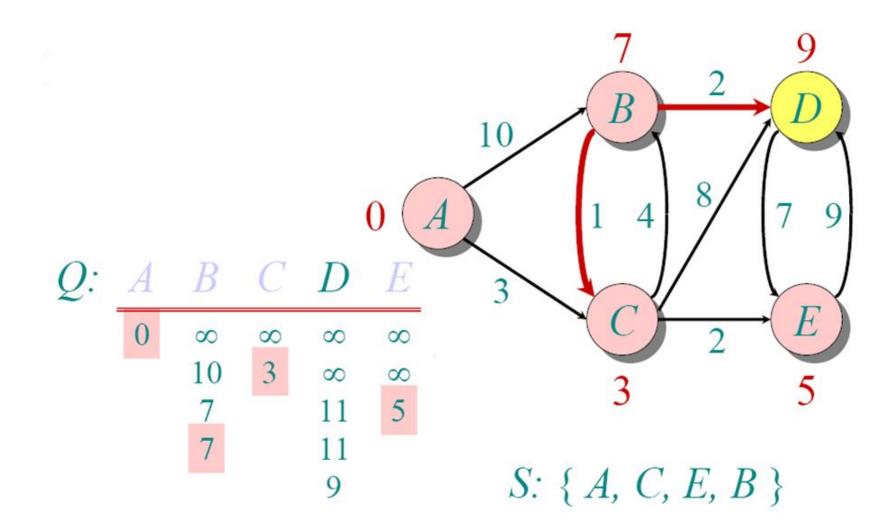


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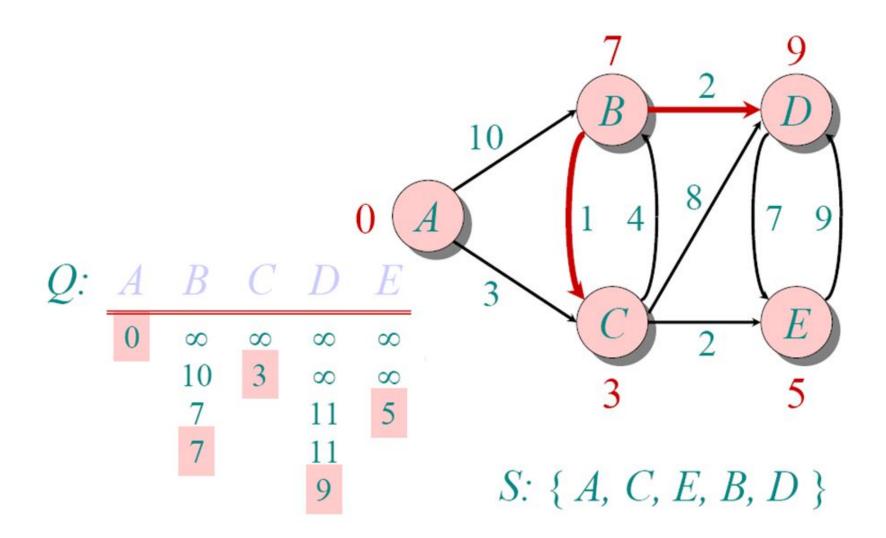






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Difference constraints

Linear Programming

- > Given mxn matrix A, m-vector b and n vector c
- Find vector x of n elements that maximises objective function $\sum_{i=1}^{n} c_i x_i$ subject to m constraints given by $Ax \le b$

System difference constraints

- ➤ Each row of linear programming matrix A contains one 1 and one -1, all other entries of A are 0
- So constraints Ax ≤b are set of m different constraints involving n unknowns of the form x_i-x_i ≤ b_k

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Difference constraints: Example

1	-1	0	0	0				0
1	0	0	0	-1		x ₁		-1
0	1	0	0	-1		x ₂		1
1	0	-1	0	0	Х	x ₃	≤	5
1	0	0	-1	0		X ₄		4
0	0	-1	1	0		X ₅		-1
0	0	-1	0	1				-3
0	0	0	-1	1				-3

$x_1 - x_2 \le 0$
x ₁ -x ₅ ≤-1
x ₂ -x ₅ ≤1
$x_1 - x_3 \le 5$
x ₁ -x ₄ ≤4
x ₄ -x ₃ ≤-1
$x_5 - x_3 \le -3$
x ₅ -x ₄ ≤-3

Application

- > Let event be jobs to be performed during assembly of product
- \triangleright e.g. 5 hrs between x_1 and x_3 i.e. $x_3-x_1 \ge 5$

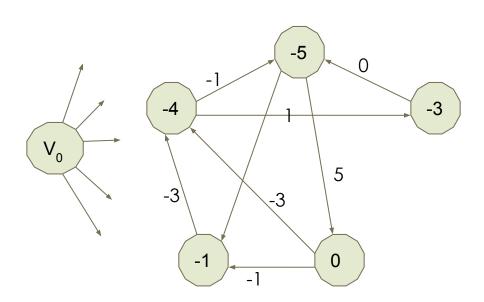
Feasible?? Solution? Yes, (-5,-3,0,-1,-4)



Difference constraints: Graph

Mapping to Graph Algorithm

- > Let n (variables) be no. of vertices and m(constraints, equations) be edges
- Add an edge from x_i to x_i (if x_j should follow x_i)with minimum difference of b_k, with weight b_k from kth constraints
 Add vertex v₀ with edges from v₀ to all other vertices with weight 0



Solving the problem

Bellman-Ford returns

- > False, negative cycle present, no solution exits.
- > True, SSSP from v₀, by Bellman-Ford provides solution



Proofs of shortest path

- Upper bound property
- No path property
- Convergence property
- Path relaxation property
- Predecessor subgraph property

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Examples

- Gift wrapping: Nesting boxes
- Arbitrage: Use of discrepancies in currency exchange rates to transform one unit of currency into more that one unit of same currency.
 - a. e.g. Ind Rs -> US \$ -> Jap yen -> Euro -> Ind Rs

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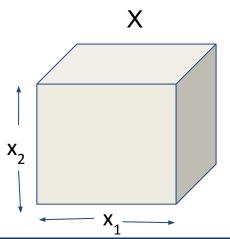


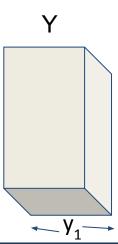
Some problems: Nesting boxes

• Given n boxes, all D dimensional, needs to be nested within one-other (recursively). What is maximum nesting level possible?

Base problem

- Given two boxes X and Y with D dimensions as (x₁,x₂,... x_D) and (y₁, y₂,...y_D) how to decide if X fits into Y?
 - Example $X(x_1, x_2, x_3)$ and $Y(y_1, y_2, y_3)$





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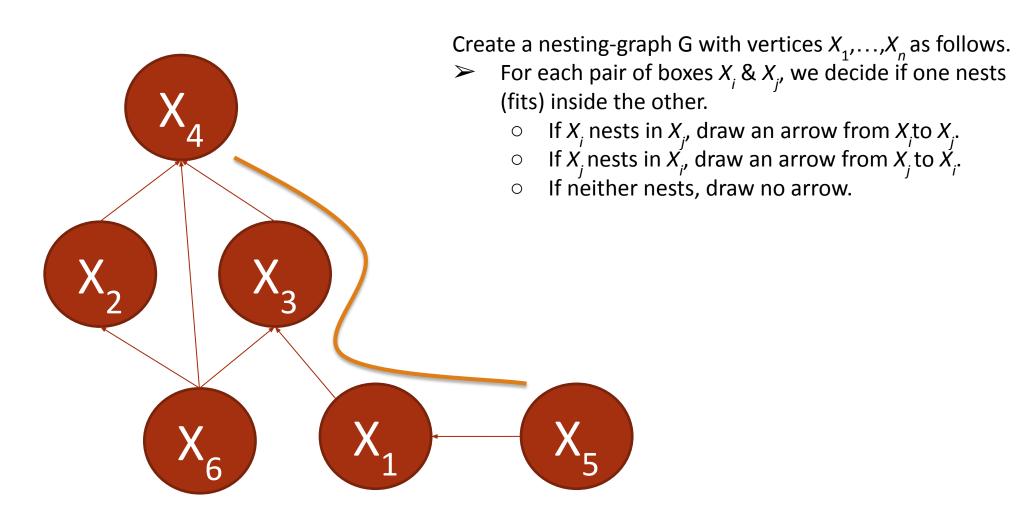
Some problems: Nesting boxes

- Box X nests inside box Y if and only if the increasing sequence of dimensions of X is component-wise strictly less than the increasing sequence of dimensions of Y. Thus, it will suffice to sort both sequences of dimensions and compare them.
- With boxes as vertices, indicate for each pair if one can be contained in other, with a directed edge.

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Nesting boxes: Example



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Nesting boxes: Complexity

- Sorting both length d sequences is done in O(d log d), and comparing their elements is done in O(d), so the total time is O(d lg d).
- To determine the arrows efficiently, after sorting each list of dimensions in O(ndlgd) time, compare all pairs of boxes using the algorithm in $O(n^2*d)$. The resulted graph is acyclic, which allows us to easily find the **longest chain** in it in $O(n^2)$ in a bottom-up manner. Thus, the total time is $O(nd \max(\lg d, n))$.



Some problems: Arbitrage

- Arbitrage is defined as near simultaneous purchase and sale of securities or foreign exchange in different markets in order to profit from price discrepancies. Rs -> US\$ -> EURO -> AUS\$ -> Rs?
- Use of discrepancies in currency exchange rate.
- For the sake of simplicity, let's assume there are no transaction costs and you can trade any currency amount in fractional quantities.
- 1 U.S. dollar bought 0.82 Euro, 1 Euro bought 129.7 Japanese Yen, 1 Japanese Yen bought bought 0.70 Indian Rupee, and 1 Indian Rupee bought 0.0135489 USD U.S. dollars. Then, by converting currencies, a trader can start with 1 U.S. dollar and buy U.S. dollars, thus turning a 0.82*129.7*0.7* 0.0135489 USD =1.042 US dollars, thus making a 4.2% profit.
- Weighted directed graphs can be represented as an adjacency matrix.

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Arbitrage: Analysis

- Arbitrage opportunities arise when a cycle is determined such that the edge weights satisfy the following expression w₁ * w₂ * w₃ * ... * w_n > 1
- The above constraint of finding the cycles is harder in graphs.

Let's take the logarithm on both sides, such that

$$\log(w_1) + \log(w_2) + \log(w_3) + ... + \log(w_n) > 0$$

Taking the negative log, this becomes

$$(-\log(w_1)) + (-\log(w_2)) + (-\log(w_3)) + ... + (-\log(w_n)) < 0$$

Therefore we can conclude that if we can find a cycle of vertices such that the sum of their weights if negative, then we can conclude there exists an opportunity for currency arbitrage. Luckily, Bellman-Ford algorithm is a standard graph algorithm that can be used to easily detect negative weight cycles in O(|V*E|) time.

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Thank You