Things to do after flashing Jetson.

Connect to Jetson using HDMI or Headless.

HDMI

• you can connect to the Jetson using and HDMI cable.

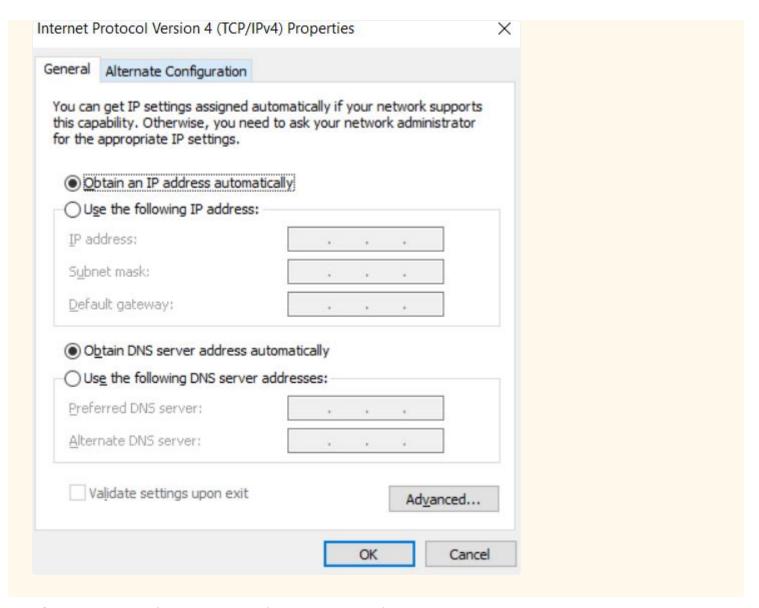
Headless

- you can connect to the Jetson with SSH by establishing a network with a micro/Type C cable (depends on your board production).
- the example below shows a micro cable connection to Jetson NX.



• after connecting the cable we should be able to ping the device using the following IP 192.168.55.1

Warning: if you can't ping the Jetson using 192.168.55.1 you may need to change the IPV4 protocol settings so that it obtains the IP addresses automatically.



if you can ping the Jetson use the SSH protocol to access it

Connect to WIFI from the terminal using nmcli.

What Is nmcli?

NMCLI (NetworkManager Command-line) manages the network manager interface and identifies available internet connections. It can be used to activate, edit, and delete wireless network connections.

Connect to WIFI.

use the following command to connect to your WIFI.

sudo nmcli dev wifi connect <network-ssid> password <network-password>

Disconnect from WIFI.

nmcli con down ssid/uuid

Connect to a saved WIFI.

nmcli con up ssid/uuid

Show all saved connections.

nmcli con show

Install XRDP.

sudo apt-get install xrdp

Warning: you may need to use sudo apt-get update before installing xrdp.

<u>Install Jtop</u>

sudo -H pip3 install -U jetson-stats

Note: we need to reboot the system before using jtop

Install VS-Code.

- go to <u>Download Visual Studio Code Mac, Linux, Windows</u>
- download .deb arm64 version.
- do the following commands.

```
sudo dpkg -i <path_to_downloaded_vs-code_.deb>

sudo apt install apt-transport-https

sudo apt update

sudo apt install
```

• undefinedwe can start vs-code in our current directory using code . undefinedundefined .

Python Libraries Installation

Pip3

sudo apt install python3-pip

PyCUDA

pip3 install PyCUDA

Numpy

pip3 install cython
pip3 install numpy

warning: on the jetson platform you may need to install cython before numpy.

Pillow and Matplotlib

pip3 install --upgrade pip
pip3 install pillow
pip3 install matplotlib

Jetson Stats

Installation

sudo -H pip3 install -U jetson-stats

Note: we need to reboot the system before using jtop

<u>Usage</u>

jtop

Documentation

• click <u>here</u> to go to documentation

VS-Code Installation

- go to Download Visual Studio Code Mac, Linux, Windows
- download .deb arm64 version.
- do the following commands.

```
sudo dpkg -i <path_to_downloaded_vs-code_.deb>

sudo apt install apt-transport-https

sudo apt update

sudo apt install code
```

• undefinedwe can start vs-code in our current directory using code . undefinedundefined .

undefinedundefined

Build QGroundControl on Jetson

QT-5.15.2 Requirements.

Build essentials

sudo apt-get install build-essential perl python3 git

Libxcb

sudo apt-get install '^libxcb.*-dev' libx11-xcb-dev libglu1-mesa-dev libxrender-dev
libxi-dev libxkbcommon-dev libxkbcommon-x11-dev

Accessibility

sudo apt-get install libatspi2.0-dev libdbus-1-dev

Qt WebKit

sudo apt-get install flex bison gperf libicu-dev libxslt-dev ruby

Qt WebEngine

sudo apt-get install libxcursor-dev libxcomposite-dev libxdamage-dev libxrandr-dev libxtst-dev libxss-dev libdbus-1-dev libevent-dev libfontconfig1-dev libcap-dev libpulse-dev libudev-dev libpci-dev libnss3-dev libasound2-dev libegl1-mesa-dev gperf bison nodejs

Qt Multimedia

sudo apt-get install libasound2-dev libgstreamer1.0-dev libgstreamer-plugins-base1.0-dev libgstreamer-plugins-good1.0-dev libgstreamer-plugins-bad1.0-dev

QDoc Documentation Generator Tool

sudo apt install clang libclang-dev

SSL Support

sudo apt install libssl-dev

Warning: SSL Support by default is optional in QT so you may be attempted to skip it; don't because we need it to build QGroundControl

QGroundControl Requirements.

Additional Packages

sudo apt-get install speech-dispatcher libudev-dev libsdl2-dev patchelf build-essential curl

Download and Build QT-5.15.2

Download QT-5.15.2

```
wget http://master.qt.io/archive/qt/5.15/5.15.2/single/qt-everywhere-src-5.15.2.tar.xz
tar -xpf qt-everywhere-src-5.15.2.tar.xz
cd qt-everywhere-src-5.15.2
```

Configure QT-5.15.2

```
sudo ./configure -opensource -confirm-license -dbus-linked -openssl-linked -skip
gtwebengine
```

Note: make sure that you are inside qt-everywhere-src-5.15.2 folder.

you should see the following

```
Note: Also available for Linux: linux-clang linux-icc
Note: When linking against OpenSSL, you can override the default
library names through OPENSSL_LIBS.
For example:
     OPENSSL_LIBS='-L/opt/ssl/lib -lssl -lcrypto' ./configure -openssl-linked
Qt is now configured for building. Just run 'make'.
Once everything is built, you must run 'make install'.
Qt will be installed into '/usr/local/Qt-5.15.2'.
Prior to reconfiguration, make sure you remove any leftovers from
the previous build.
```

Build QT-5.15.2

```
sudo make
sudo make install
Note: sudo make step will take a couple of hours.
```

Copy/Create missing files and folder to /usr/local/Qt-5.15.2

```
sudo cp /usr/lib/aarch64-linux-gnu/libicui18n.so* /usr/local/Qt-5.15.2/lib/
sudo cp /usr/lib/aarch64-linux-gnu/libicudata.so* /usr/local/Qt-5.15.2/lib/
sudo cp /usr/lib/aarch64-linux-gnu/libicuuc.so* /usr/local/Qt-5.15.2/lib/
sudo mkdir /usr/local/Qt-5.15.2/plugins/texttospeech
```

Warning: the missing files/folder shown above are needed to build QGroundControl.

Download and Build QGroundControl.

Clone QGroundControl Repository

```
git clone --recursive -j8 https://github.com/mavlink/qgroundcontrol.git
```

Note: make sure that you aren't inside | qt-everywhere-src-5.15.2 | folder.

Configure QGroundControl

```
cd qgroundcontrol/
mkdir build
cd build
sudo /usr/local/Qt-5.15.2/bin/qmake DEFINES=DISABLE_AIRMAP ../
```

Build QGroundControl

sudo make

Warning: you may want to use 1gb swap memory if you are building QGroundControl on Jetson Nano!.

Access Serial Devices

sudo usermod -a -G dialout \$USER
sudo apt-get remove modemmanager

Launch QGroundControl

./staging/QGroundControl