Partially Optimal Cubic Subspace Clustering

Research Project Machine Learning

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Introduction

2 Partial Optimality for Cubic Clique Partition Problem

3 Cubic Subspace Instance Construction

Experiments and Evaluation

Conclusion

Problem Statement (1)

Finite sample set S, cost function $c: \binom{S}{3} \to \mathbb{R}$. Instance of the **Cubic Clique Partition Problem**:

$$\min_{\mathbf{y}: \; \binom{S}{2} \to \{0,1\}} \sum_{abc \in \binom{S}{3}} c_{abc} \, \mathbf{y}_{ab} \, \mathbf{y}_{bc} \, \mathbf{y}_{ac}$$

subject to $\mathbf{y}_{ab} + \mathbf{y}_{bc} - 1 \leq \mathbf{y}_{ac}$ for all distinct $a,b,c \in \mathcal{S}$.

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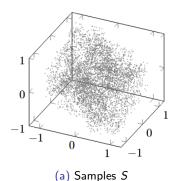
Find a **partially optimal solution**, i.e. fix some labels y_{ab} for distinct $a, b \in S$

$$\begin{cases} \mathbf{y}_{ab} = 1 & \text{join } a, b \\ \mathbf{y}_{ab} = 0 & \text{cut } a, b \\ \mathbf{y}_{ab} = ? & \text{unknown} \end{cases}$$

in such way that there still exists an optimal solution.

Problem Statement (2)

Subspace Instances of the Cubic Clique Partition Problem Samples S: points $S \subset \mathbb{R}^3$



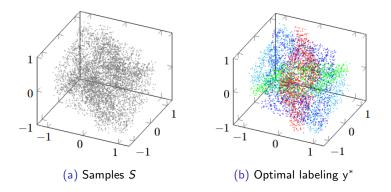
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Optimal labeling y*: original planes



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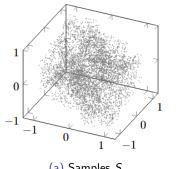
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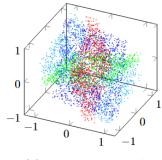
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Optimal labeling y*: original planes

Cost function c? (no concrete plane information given)



(a) Samples S



(b) Optimal labeling y*

Related Work:

- Stein, Di Gregorio, and Andres, "Partial Optimality in Cubic Correlation Clustering"
- Lange, Karrenbauer, and Andres, "Partial Optimality and Fast Lower Bounds for Weighted Correlation Clustering"
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- ② Construct subspace instances of increasing difficulty
 → point generation, appropriate cost function c
- Apply algorithm to the subspace instances, assess partial optimality, accuracy and computation time
 - \rightarrow experiments and evaluation

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Let $Y \neq \emptyset$, $\phi \colon Y \to \mathbb{R}$ and $\sigma \colon Y \to Y$. σ is an **Improving Map** for for the problem $\min_{\mathbf{y} \in Y} \phi$ if for every $\mathbf{y} \in Y$: $\phi(\sigma(\mathbf{y})) \leq \phi(\mathbf{y})$.

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Let $Y\subseteq\{\text{feasible }y\mid y\colon {s\choose 2}\to\{0,1\}\}$, $\phi_{\mathbf{c}}\colon Y\to\mathbb{R}$ and σ an improving map. If for every $y\in Y\colon \sigma(y)_{ab}=\beta$, $ab\in {s\choose 2}$, $\beta\in\{0,1\}$, then there is an optimal solution y^* to $\min_{y\in Y}\phi_{\mathbf{c}}$ such that $y^*_{ab}=\beta$.

Let $ij \in {S \choose 2}$. If there exists $R \subseteq S$ such that $i \in R \land j \notin R$ and

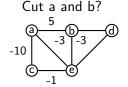
$$c_{ij}^{+} \geq \sum_{p \in R \land q, r \notin R} \sum_{p,q \in R \land r \notin R} c_{pqr}^{-} + \sum_{p \in R \land q \notin R} c_{pq}^{-}$$

then there is an optimal solution y^* to $\min_{\mathbf{y} \in \mathbf{Y}} \phi_{\mathbf{c}}$ such that $\mathbf{y}^*_{ij} = \mathbf{0}$.

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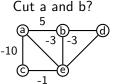
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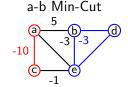


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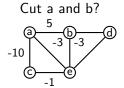




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Improving map $\sigma: Y \to Y$ for $y \in Y$ and $pq \in \binom{S}{2}$:

$$\begin{cases} \sigma(\mathsf{y})_{pq} = 0 & \mathsf{y}_{ij} = 1 \land |\{p,q\} \cap R| = 1 \\ \sigma(\mathsf{y})_{pq} = \mathsf{y}_{pq} & \textit{otherwise} \end{cases}$$

Partial Optimality Conditions

Partial Optimality Conditions:

- Subproblem-CUT-condition (cut subset from its complement)
- Q CUT-conditions (cut pairs and triples)
- JOIN-conditions (join subsets, pairs and triples)

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CUT-conditions can be applied simultaneously.

JOIN-conditions must be applied iteratively!

 $Q_1,Q_2\in Y$: if there exists an optimal $y_1^*\in Q_1$ and there exists an optimal $y_2^*\in Q_2$ \rightarrow there is an optimal $y^*\in Q_1\cap Q_2$:

$$\begin{split} & \min_{\mathbf{y} \in Y} \phi_{\mathbf{c}} = -2 \\ & Q_1 = \{ \mathbf{y} \in Y \mid \mathbf{y}_{ab} = 1 \} \\ & Q_2 = \{ \mathbf{y} \in Y \mid \mathbf{y}_{ac} = 1 \} \\ & \to Q_1 \cap Q_2 = \{ \mathbf{y} \in Y \mid \mathbf{y}_{ab} = 1 \land \mathbf{y}_{ac} = 1 \} \ \ \ \ \end{split}$$



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Apply partial optimality conditions \rightarrow solve subproblems!

Partial Optimality Algorithm

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Partial Optimality Algorithm:
Input: labeling y without fixed labels
while condition applied do
apply subproblem-CUT-condition exhaustively
apply one of JOIN-conditions (in effective order)
end while
apply CUT-conditions exhaustively
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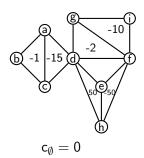
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- Subproblem-CUT-condition: fix 0-labels for element pairs from different sample subsets; solve each subset as an independent problem; accumulate the results in c_∅;
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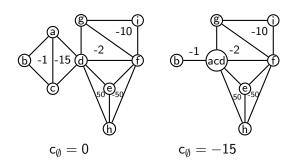
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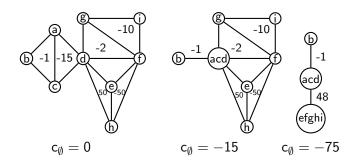
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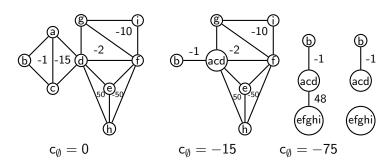
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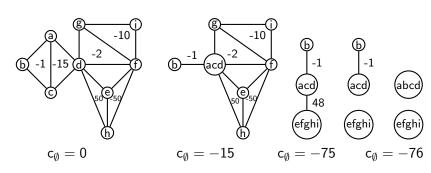
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Other JOIN-conditions

Pair-JOIN-1: join samples $ij \in {S \choose 2}$ if their overall joining reward \geq the sum of rewards and penalties for joining some subset R with $i \in R \land j \notin R$ with \overline{R} (\approx i-j min-cut)

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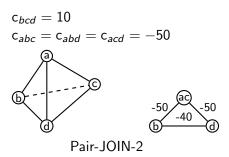
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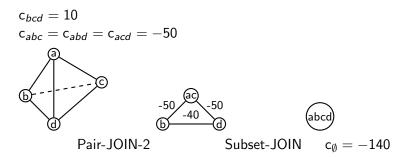
Triple-JOIN: join samples $ijk \in \binom{S}{3}$ if the condition holds (similar to Pair-JOIN-1) (\approx i-jk min-cut)

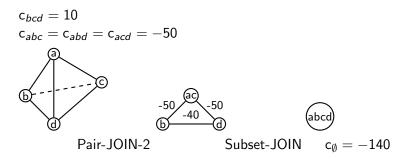
$$c_{bcd} = 10$$

$$c_{abc} = c_{abd} = c_{acd} = -50$$

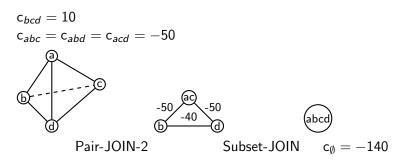








Pair-CUT: cut samples i,j if the direct joing penalty \geq the sum of rewards for joining some subset R with $i \in R \land j \notin R$ with \overline{R} (\approx i-j min-cut)



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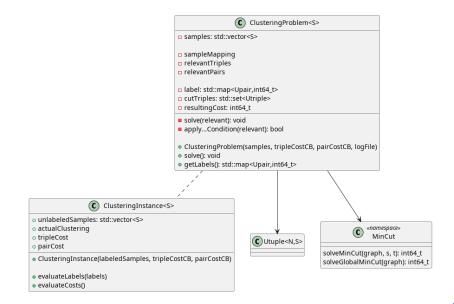
Pair-JOIN-2 Subset-JOIN $c_{\emptyset}=-140$

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Samples in the pyramid with $c_{bcd}=100$ are unjoinable! Triple-CUT is applied to the triple bcd

Program Structure



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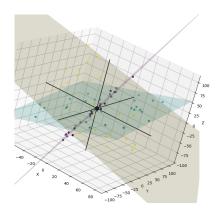
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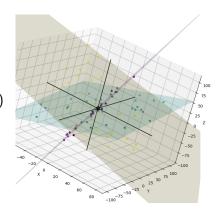
Plane Generation:

• generate 3 planes as distinct normal vectors $\vec{n}_1, \vec{n}_2, \vec{n}_3$ (normalized)



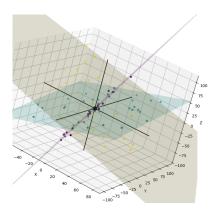
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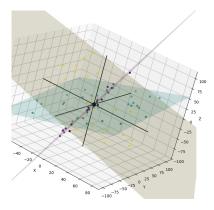
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Point Generation on the plane $(\vec{n}, \vec{r_1}, \vec{r_2})$, parameters (D, σ) :

- random variables $k_1, k_2 \in [-D, D]$ (uniform distribution)
- random variable k_n (normal distribution based on σ)
- generate point $p = k_1 \vec{r_1} + k_2 \vec{r_2} + k_n \vec{n}$

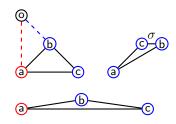
(1) Smallest side
$$s < D/2$$

 $\rightarrow c_{abc} = 0$

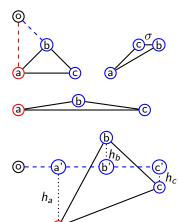




- (1) Smallest side s < D/2 $\rightarrow c_{abc} = 0$
- (2) Largest angle $\alpha > 150^{\circ}$ \rightarrow c_{abc} = 0



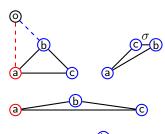
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- (3) h_a, h_b, h_c : distances to the best fitted plane containing the origin; $h_a + h_b + h_c > 3\sigma + 10^{-6}$ $\rightarrow c_{abc} = \frac{(h_a + h_b + h_c) (3\sigma + 10^{-6})}{3D}$

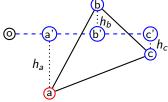


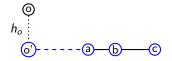
Triangle $abc \in \binom{S}{3}$

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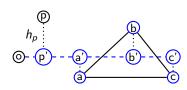
(4) h_o : distance from the origin to the triangle plane; $h_o > \frac{10}{\#points}\sigma + 10^{-6}$ $\rightarrow c_{abc} = 0$





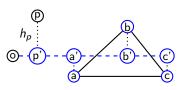


(5) for all points p: h_p : distance to the best fitted plane containing the origin;



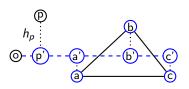
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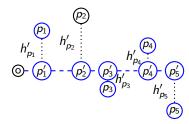
choose
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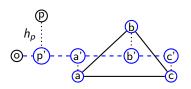


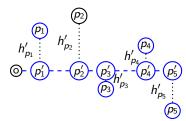


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$$\delta_p := rac{hp' - (\sigma + 10^{-6})}{D}$$
 $M := \{p \mid p ext{ chosen } \wedge \delta_p < 0\}$

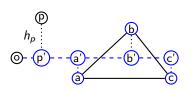


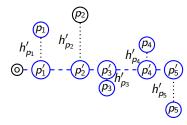


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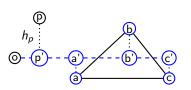


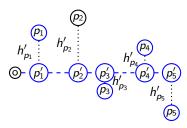


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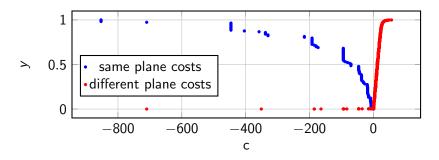
Introduction

2 Partial Optimality for Cubic Clique Partition Problem

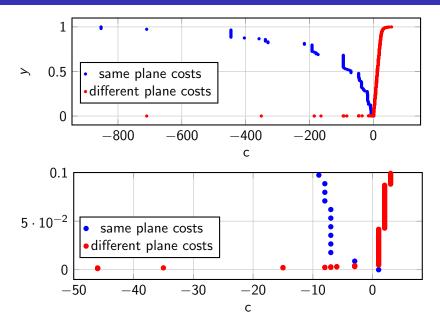
3 Cubic Subspace Instance Construction

4 Experiments and Evaluation

Cost Function Evaluation (3x15 points, $\sigma = 1$)



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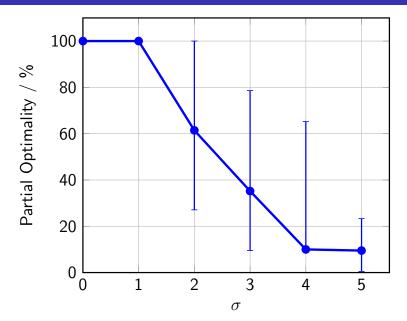
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 - 3x7 points (solve 15 instances)
 - 3x10 points (solve 15 instances)
 - 3x15 points (solve 7 instances)
 - 3x20 points (solve 1 instance)

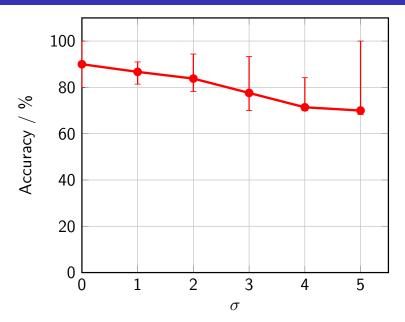
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- Capture
 - 1.quartile (Q1)
 - median (Q2)
 - 3.quartile(Q3)
 - the worst computation time

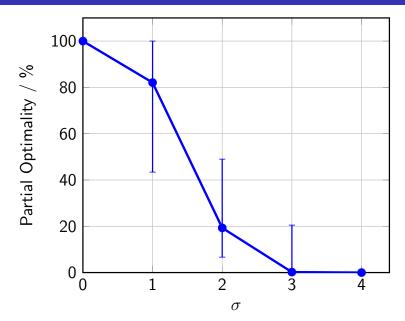
Partial Optimality (3x7 points)



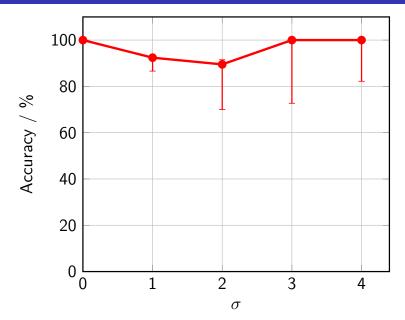
Accuracy (3x7 points)



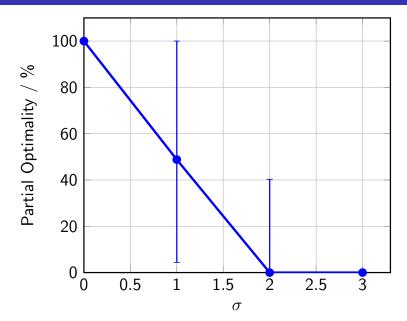
Partial Optimality (3x10 points)



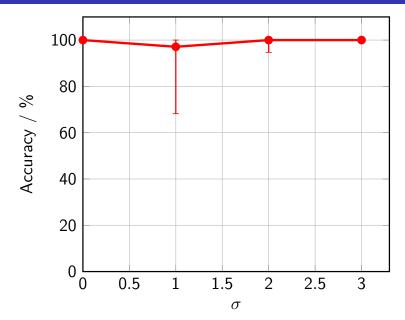
Accuracy (3x10 points)



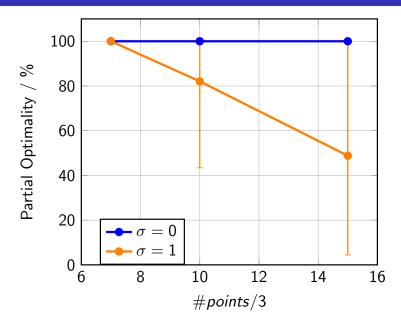
Partial Optimality (3x15 points)



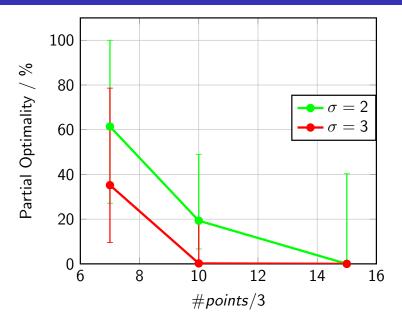
Accuracy (3x15 points)



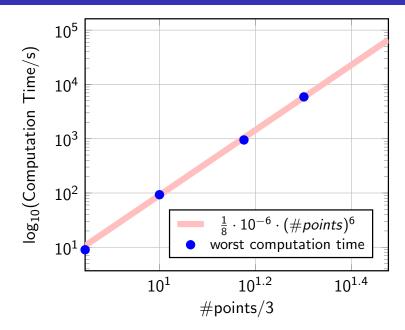
Partial Optimality



Partial Optimality



Computation Time (worst case)



Introduction

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3 Cubic Subspace Instance Construction

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- Implementation of the partial optimality algorithm:
 - arbitrary sample type
 - sparse cost representation
 - pair labeling and triple cuts
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 - high accuracy (over 75%)
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Conclusion

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Future Work:

- optimize and parallelize the algorithm
- overcome the partial optimality loss for c
- determine better parameters for c
- update c with advanced criteria

References

My program, scripts and presentation:

https://github.com/Vovsanka/ResearchProjectML

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