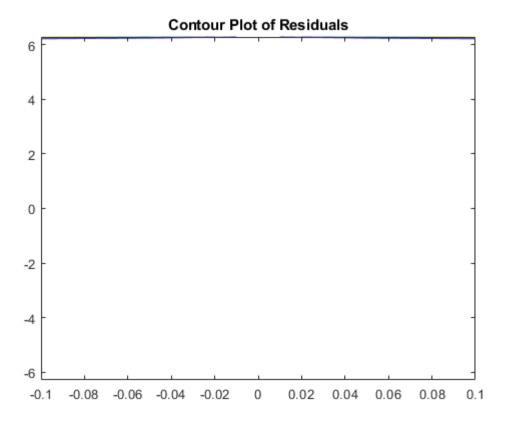
#### **Contents**

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- Echoing outputs for diary

```
clear all
close all
[t, y] = textread('Problem1 TExpo sineData.txt','%f%f','headerlines',1);
xdata = t;
ydata = y;
x1=-0.1:.1:0.1;
x2 = linspace(-2*pi, 2*pi, 315);
[OMEGA, ALPHA] = meshgrid(x1, x2);
%R2 needs to be a matrix
%Make a meshgrid of alpha omega
%calculate R2ALT as a giant matrix
for row = 1:1:length(ALPHA)
   for col = 1:3
       model = t.*(exp( ALPHA(row,col)* t )).*(sin( OMEGA(row,col)*t ));
       RESIDUALS = y - model;
       R2 = norm(RESIDUALS)^2;
       R2altmat(row,col) = R2;
    end
end
figure;
contour (OMEGA, ALPHA, R2altmat)
title('Contour Plot of Residuals');
alpha = -1;
omega = 1;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
```

```
mu start = 0.1;
mu down = 50;
mu_up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
r22 = residual2' * residual2;
r22 < r2
here m = 1
%mu remained the same, we can adjust it downhill
%after this
%now that we checked r22 < r2 1
%change mu by mu_cont
% J1 = t.^3 .* \exp(x0(i,j) .* t) .* \sin(x0(i+1,j+1) .* t);
% J2 = t.^2 .* exp(x0(i,j) .* t) .* cos(x0(i+1 .* t);
% J = [J1 \ J2];
alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];
% mutot = [mu start];
%starting point for next iteration
%this is now iteration 1
mu = 0.1/50;
mtot = [1];
mutot = [mu_start mu];
rtotv = [r2 r22];
%generalize to loop
```

```
ans =
  logical
```



```
r2 it = 100;
r2 baseline = r22;
m = 1;
while r2_it > r2_baseline
    Ja1 = t.^3 .* exp(alphatot(2) .* t) .* sin(omegatot(2) .* t);
   Ja2 = t.^2 .* exp(alphatot(2) .* t) .* cos(omegatot(2) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;
   x1a = x0 - deltaxa;
   model3a = t .* (exp(x1a(1) .* t)) .* (sin(x1a(2)) .* t);
   residual3a = y - model3a;
    r2_it = residual3a' * residual3a;
    if r2_it > r2_baseline
       mu = mu * mu_up;
    m = m+1
end
    alphatota = [alphatot x1a(1)];
    omegatota = [omegatot x1a(2)];
```

```
if r2_it < r2_baseline
    mu = mu/mu_down;
else
    mu = mu;
end

mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r2_it];
disp('Iteration 2')
m
mu
r2_it
disp('Next Iteration')</pre>
```

```
m =
    2
Iteration 2
m =
    2
mu =
    4.0000e-05

r2_it =
    62.2236
Next Iteration
```

```
r3_it = 100;
r2_baseline = r2_it;
m = 1;

while r3_it > r2_baseline || m == 5

Ja1 = t.^3 .* exp(alphatota(3) .* t) .* sin(omegatota(3) .* t);
Ja2 = t.^2 .* exp(alphatota(3) .* t) .* cos(omegatota(3) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;

x2a = x1a - deltaxa;

model4a = t .* (exp(x2a(1) .* t)) .* (sin(x2a(2)) .* t);

residual4a = y - model4a;
```

```
r3_it = residual4a' * residual4a;
    if r3_it > r2_baseline
     mu = mu * mu_up;
    end
    m = m+1
end
   alphatota = [alphatota x2a(1)];
    omegatota = [omegatota x2a(2)];
if r3_it < r2_baseline</pre>
   mu = mu/mu_down;
else
  mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r3_it];
disp('Iteration 3')
mu
r3_it
disp('Next Iteration')
```

```
m =
    2
Iteration 3
m =
    2
mu =
    8.0000e-07
r3_it =
    60.8726
Next Iteration
```

```
r4_it = 100;
r3_baseline = r3_it;
m = 1;
while r4_it > r3_baseline
```

```
Ja1 = t.^3 .* exp(alphatota(4) .* t) .* sin(omegatota(4) .* t);
    Ja2 = t.^2 .* exp(alphatota(4) .* t) .* cos(omegatota(4) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;
    x3a = x2a - deltaxa;
    model5a = t .* (exp(x3a(1) .* t)) .* (sin(x3a(2)) .* t);
    residual5a = y - model5a;
    r4_it = residual5a' * residual5a;
    if r4_it > r3_baseline
      mu = mu * mu up;
    end
    m = m+1
    if m == 5
       break
    end
end
   alphatota = [alphatota x3a(1)];
    omegatota = [omegatota x3a(2)];
if r4 it < r3 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r4_it];
disp('Iteration 4')
m
mu
r4_it
disp('Next Iteration')
```

```
m = 3
m = 4
```

m =

```
5
Iteration 4

m = 5

mu = 5.0000e-04

r4_it = 62.7184

Next Iteration
```

```
r5 it = 100;
r4_baseline = r4_it;
m = 1;
while r5_it > r4_baseline
    Ja1 = t.^3 .* exp(alphatota(5) .* t) .* sin(omegatota(5) .* t);
    Ja2 = t.^2 .* exp(alphatota(5) .* t) .* cos(omegatota(5) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;
    x4a = x3a - deltaxa;
    model6a = t .* (exp(x4a(1) .* t)) .* (sin(x4a(2)) .* t);
    residual6a = y - model6a;
    r5_it = residual6a' * residual6a;
    if r5_it > r4_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x4a(1)];
    omegatota = [omegatota x4a(2)];
if r5 it < r4 baseline</pre>
```

```
mu = mu/mu_down;
else
    mu = mu;
end

mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r5_it];
disp('Iteration 5')
m
mu
r5_it
disp('Next Iteration')
```

```
m =
    2
Iteration 5
m =
    2
mu =
    1.0000e-05
r5_it =
    62.6692
Next Iteration
```

```
r6_it = 100;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline

Ja1 = t.^3 .* exp(alphatota(6) .* t) .* sin(omegatota(6) .* t);
Ja2 = t.^2 .* exp(alphatota(6) .* t) .* cos(omegatota(6) .* t);
Ja = [Ja1 Ja2];
deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
x5a = x4a - deltaxa;
model7a = t .* (exp(x5a(1) .* t)) .* (sin(x5a(2)) .* t);
residual7a = y - model7a;
r6_it = residual7a' * residual7a;
```

```
if r6_it > r5_baseline
    mu = mu * mu_up;
   end
    m = m+1
   if m == 5
     break
   end
end
   alphatota = [alphatota x5a(1)];
   omegatota = [omegatota x5a(2)];
if r6_it < r5_baseline</pre>
 mu = mu/mu_down;
mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r6_it];
disp('Iteration 6')
mu
r6_it
disp('Next Iteration')
```

```
m =
    2
Iteration 6
m =
    2
mu =
    2.0000e-07
r6_it =
    62.1562
Next Iteration
```

```
r7_it = 100;
r6_baseline = r6_it;
m = 1;
```

```
while r7_it > r6_baseline
    Ja1 = t.^3 .* exp(alphatota(7) .* t) .* sin(omegatota(7) .* t);
   Ja2 = t.^2 .* exp(alphatota(7) .* t) .* cos(omegatota(7) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
   x6a = x5a - deltaxa;
   model8a = t .* (exp(x6a(1) .* t)) .* (sin(x6a(2)) .* t);
   residual8a = y - model8a;
   r7_it = residual8a' * residual8a;
   if r7_it > r6_baseline
       mu = mu * mu up;
    end
    m = m+1
   if m == 5
       break
   end
end
   alphatota = [alphatota x6a(1)];
   omegatota = [omegatota x6a(2)];
if r7 it < r6 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r7_it];
disp('Iteration 7')
m
r7 it
disp('Next Iteration')
```

```
2
m =
3
```

m =

```
r8 it = 100;
r7_baseline = r7_it;
m = 1;
while r8_it > r7_baseline
    Ja1 = t.^3 .* exp(alphatota(8) .* t) .* sin(omegatota(8) .* t);
    Ja2 = t.^2 .* exp(alphatota(8) .* t) .* cos(omegatota(8) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;
    x7a = x6a - deltaxa;
    model9a = t .* (exp(x7a(1) .* t)) .* (sin(x7a(2)) .* t);
    residual9a = y - model9a;
    r8_it = residual9a' * residual9a;
    if r8_it > r7_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x7a(1)];
```

```
omegatota = [omegatota x7a(2)];

if r8_it < r7_baseline
    mu = mu/mu_down;
else
    mu = mu;
end

mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r8_it];
disp('Iteration 8')
    m
    mu
r8_it
disp('Next Iteration')</pre>
```

```
m =
   2
m =
   3
m =
   4
m =
   5
Iteration 8
m =
 0.0781
r8_it =
  62.4239
Next Iteration
```

```
r9_it = 100;
r8_baseline = r8_it;
```

```
m = 1;
while r9_it > r8_baseline
    Ja1 = t.^3 .* exp(alphatota(9) .* t) .* sin(omegatota(9) .* t);
    Ja2 = t.^2 .* exp(alphatota(9) .* t) .* cos(omegatota(9) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
end
   alphatota = [alphatota x8a(1)];
   omegatota = [omegatota x8a(2)];
if r9 it < r8 baseline</pre>
   mu = mu/mu_down;
else
  mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r9_it];
disp('Iteration 9')
m
mu
r9 it
disp('Next Iteration')
```

```
2
Iteration 9
m =
```

m =

```
0.0016
r9_it =
62.3401
Next Iteration
```

```
r10 it = 100;
r9_baseline = r9_it;
m = 1;
while r10_it > r9_baseline
    Ja1 = t.^3 .* exp(alphatota(10) .* t) .* sin(omegatota(10) .* t);
    Ja2 = t.^2 .* exp(alphatota(10) .* t) .* cos(omegatota(10) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
    x9a = x8a - deltaxa;
    model11a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual11a = y - model11a;
    r10_it = residual11a' * residual11a;
    if r10 it > r9 baseline
       mu = mu * mu_up;
    end
     m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x9a(1)];
    omegatota = [omegatota x9a(2)];
if r10_it < r9_baseline</pre>
   mu = mu/mu down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r10_it];
disp('Iteration 10')
mu
r10 it
```

```
disp('Next Iteration')

disp('Required 10 iterations to find final values')

%Plot the fit over normal scatter

f2 = figure('Name', 'Part 1 Plot over scatter');

scatter(t,y)
hold on
plot(t, model9a)
title('Raw Data and Fit Part 1')
xlabel('time')
ylabel('displacement')
```

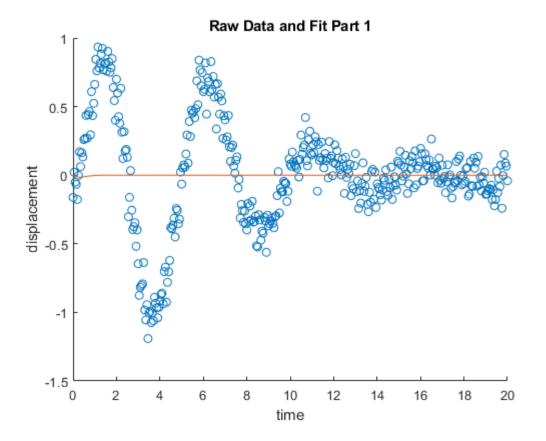
```
m =
    2
Iteration 10

m =
    2

mu =
    0.0016

r10_it =
    62.3401

Next Iteration
Required 10 iterations to find final values
```



# **Echoing outputs for diary**

```
diary vjproblpt1.txt

echo on

mutot

mtot

rtotv

alphatota

omegatota

echo off
```

```
mutot
mutot =
 Columns 1 through 7
   0.1000
           0.0020
                      0.0000
                               0.0000
                                      0.0005
                                                 0.0000 0.0000
 Columns 8 through 11
   0.0001
          0.0781
                     0.0016
                               0.0016
mtot
mtot =
    1
          2
               2
                                                      2
```

```
rtotv
```

```
rtotv =
 Columns 1 through 7
 Columns 8 through 11
alphatota
```

70.7653 70.3216 62.2236 60.8726 62.7184 62.6692 62.1562

62.2922 62.4239 62.3401 62.3401

alphatota =

Columns 1 through 7

-1.0000 -1.5512 -2.2599 -2.8885 -3.5067 -4.1389 -4.7705

Columns 8 through 11

-5.3992 -6.0282 -6.6565 -7.2861

omegatota

omegatota =

Columns 1 through 7

1.0000 -1.4855 -3.1781 -4.9803 -6.7584 -8.5695 -10.3812

Columns 8 through 11

-12.1781 -13.9749 -15.7592 -17.5617

echo off

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## Prob 1 Part 2

```
clear all
close all
[t, y] = textread('Problem1 TExpo sineData.txt','%f%f','headerlines',1);
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu_start = 1;
mu down = 50;
mu_up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
```

```
r22 = residual2' * residual2;
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;
mtot = [1];
mutot = [mu_start mu];
rtotv = [r2 r22];</pre>
```

```
ans =
  logical
```

```
r2 it = 100;
r2_baseline = r22;
m = 1;
while r2_it > r2_baseline
    Ja1 = t.^3 .* exp(alphatot(2) .* t) .* sin(omegatot(2) .* t);
   Ja2 = t.^2 .* exp(alphatot(2) .* t) .* cos(omegatot(2) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;
   x1a = x0 - deltaxa;
   model3a = t .* (exp(x1a(1) .* t)) .* (sin(x1a(2)) .* t);
   residual3a = y - model3a;
    r2_it = residual3a' * residual3a;
   if r2_it > r2_baseline
      mu = mu * mu_up;
    m = m+1
end
   alphatota = [alphatot x1a(1)];
   omegatota = [omegatot x1a(2)];
if r2_it < r2_baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
```

```
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r2_it];
disp('Iteration 2')
m
mu
r2_it
disp('Next Iteration')
```

```
m =
    2
Iteration 2
m =
    2
mu =
    4.0000e-05

r2_it =
    64.2528
Next Iteration
```

```
r3_it = 100;
r2_baseline = r2_it;
m = 1;

while r3_it > r2_baseline || m == 5

Ja1 = t.^3 .* exp(alphatota(3) .* t) .* sin(omegatota(3) .* t);
Ja2 = t.^2 .* exp(alphatota(3) .* t) .* cos(omegatota(3) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;

x2a = x1a - deltaxa;

model4a = t .* (exp(x2a(1) .* t)) .* (sin(x2a(2)) .* t);

residual4a = y - model4a;

r3_it = residual4a' * residual4a;

if r3_it > r2_baseline
    mu = mu * mu_up;
```

```
end
    m = m+1
end
   alphatota = [alphatota x2a(1)];
   omegatota = [omegatota x2a(2)];
if r3_it < r2_baseline</pre>
   mu = mu/mu_down;
else
  mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r3_it];
disp('Iteration 3')
m
mu
r3_it
disp('Next Iteration')
```

```
m =
    2
Iteration 3
m =
    2
mu =
    8.0000e-07
r3_it =
    62.9359
Next Iteration
```

```
r4_it = 100;
r3_baseline = r3_it;
m = 1;

while r4_it > r3_baseline

Ja1 = t.^3 .* exp(alphatota(4) .* t) .* sin(omegatota(4) .* t);
Ja2 = t.^2 .* exp(alphatota(4) .* t) .* cos(omegatota(4) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;

x3a = x2a - deltaxa;
```

```
model5a = t .* (exp(x3a(1) .* t)) .* (sin(x3a(2)) .* t);
    residual5a = y - model5a;
    r4_it = residual5a' * residual5a;
    if r4_it > r3_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
end
   alphatota = [alphatota x3a(1)];
   omegatota = [omegatota x3a(2)];
if r4_it < r3_baseline</pre>
   mu = mu/mu_down;
 mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r4_it];
disp('Iteration 4')
mu
r4 it
disp('Next Iteration')
```

```
m =
    2
Iteration 4
m =
    2
mu =
    1.6000e-08
r4_it =
    62.7490
Next Iteration
```

```
r5 it = 100;
r4 baseline = r4 it;
m = 1;
while r5_it > r4_baseline
   Ja1 = t.^3 .* exp(alphatota(5) .* t) .* sin(omegatota(5) .* t);
   Ja2 = t.^2 .* exp(alphatota(5) .* t) .* cos(omegatota(5) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;
   x4a = x3a - deltaxa;
   model6a = t .* (exp(x4a(1) .* t)) .* (sin(x4a(2)) .* t);
   residual6a = y - model6a;
   r5_it = residual6a' * residual6a;
   if r5 it > r4 baseline
       mu = mu * mu_up;
   end
    m = m+1
   if m == 5
       break
   end
   alphatota = [alphatota x4a(1)];
   omegatota = [omegatota x4a(2)];
if r5_it < r4_baseline</pre>
  mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r5_it];
disp('Iteration 5')
m
mu
r5 it
disp('Next Iteration')
```

```
m = 2
Iteration 5
m = 6
```

```
mu =
    3.2000e-10

r5_it =
    62.7169

Next Iteration
```

```
r6_{it} = 100;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline
    Ja1 = t.^3 .* exp(alphatota(6) .* t) .* sin(omegatota(6) .* t);
    Ja2 = t.^2 .* exp(alphatota(6) .* t) .* cos(omegatota(6) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
    x5a = x4a - deltaxa;
    model7a = t .* (exp(x5a(1) .* t)) .* (sin(x5a(2)) .* t);
    residual7a = y - model7a;
    r6_it = residual7a' * residual7a;
    if r6_it > r5_baseline
       mu = mu * mu up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x5a(1)];
    omegatota = [omegatota x5a(2)];
if r6 it < r5 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r6_it];
disp('Iteration 6')
```

```
m
mu
r6_it
disp('Next Iteration')
```

```
m =
        2
Iteration 6
m =
        2
mu =
      6.4000e-12
r6_it =
      62.7093
Next Iteration
```

```
r7_{it} = 100;
r6_baseline = r6_it;
m = 1;
while r7_it > r6_baseline
   Ja1 = t.^3 .* exp(alphatota(7) .* t) .* sin(omegatota(7) .* t);
   Ja2 = t.^2 .* exp(alphatota(7) .* t) .* cos(omegatota(7) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
   x6a = x5a - deltaxa;
   model8a = t .* (exp(x6a(1) .* t)) .* (sin(x6a(2)) .* t);
    residual8a = y - model8a;
    r7_it = residual8a' * residual8a;
    if r7_it > r6_baseline
       mu = mu * mu_up;
    m = m+1
    if m == 5
```

```
break
    end
end
   alphatota = [alphatota x6a(1)];
   omegatota = [omegatota x6a(2)];
if r7_it < r6_baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r7_it];
disp('Iteration 7')
mu
r7_it
disp('Next Iteration')
```

```
m =
    2
Iteration 7
m =
    2
mu =
    1.2800e-13
r7_it =
    62.7055
Next Iteration
```

```
r8_it = 100;
r7_baseline = r7_it;
m = 1;

while r8_it > r7_baseline

Ja1 = t.^3 .* exp(alphatota(8) .* t) .* sin(omegatota(8) .* t);
Ja2 = t.^2 .* exp(alphatota(8) .* t) .* cos(omegatota(8) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;

x7a = x6a - deltaxa;
```

```
model9a = t .* (exp(x7a(1) .* t)) .* (sin(x7a(2)) .* t);
    residual9a = y - model9a;
    r8_it = residual9a' * residual9a;
    if r8_it > r7_baseline
       mu = mu * mu_up;
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x7a(1)];
    omegatota = [omegatota x7a(2)];
if r8_it < r7_baseline</pre>
   mu = mu/mu_down;
else
 mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r8_it];
disp('Iteration 8')
m
r8_it
disp('Next Iteration')
```

```
m =
    2
Iteration 8
m =
    2
mu =
    2.5600e-15
r8_it =
    62.7023
Next Iteration
```

```
r9 it = 100;
r8 baseline = r8 it;
m = 1;
while r9_it > r8_baseline
    Ja1 = t.^3 .* exp(alphatota(9) .* t) .* sin(omegatota(9) .* t);
    Ja2 = t.^2 .* exp(alphatota(9) .* t) .* cos(omegatota(9) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
   alphatota = [alphatota x8a(1)];
   omegatota = [omegatota x8a(2)];
if r9_it < r8_baseline</pre>
   mu = mu/mu_down;
   mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r9_it];
disp('Iteration 9')
mu
r9 it
disp('Next Iteration')
```

```
m = 2
Iteration 9
m = 6
```

```
mu =
    5.1200e-17

r9_it =
    62.6992

Next Iteration
```

```
r10_{it} = 100;
r9_baseline = r9_it;
m = 1;
while r10_it > r9_baseline
    Ja1 = t.^3 .* exp(alphatota(10) .* t) .* sin(omegatota(10) .* t);
    Ja2 = t.^2 .* exp(alphatota(10) .* t) .* cos(omegatota(10) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
    x9a = x8a - deltaxa;
    model11a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual11a = y - model11a;
    r10_it = residual11a' * residual11a;
    if r10 it > r9 baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x9a(1)];
    omegatota = [omegatota x9a(2)];
if r10_it < r9_baseline</pre>
   mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r10_it];
disp('Iteration 10')
```

```
m
mu
r10_it
disp('Next Iteration')

disp('Required 10 iterations to find final values')

f2 = figure('Name', 'Part 2 Plot over scatter, mu = 1');

scatter(t,y)
hold on
plot(t, model10a)
title('Raw Data and Fit Part 2, \mu = 1')
xlabel('time')
ylabel('displacement')
```

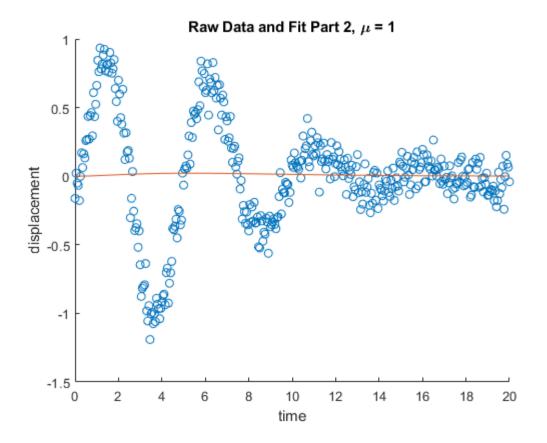
```
m =
    2
Iteration 10

m =
    2

mu =
    5.1200e-17

r10_it =
    62.6992

Next Iteration
Required 10 iterations to find final values
```



# **Echoing outputs for diary**

```
diary vjproblpt2_groupA.txt

echo on

mutot

mtot

rtotv

alphatota

omegatota

echo off
```

```
mutot
mutot =
 Columns 1 through 7
   1.0000
            0.0020
                       0.0000
                                0.0000
                                        0.0000
                                                   0.0000 0.0000
 Columns 8 through 11
   0.0000
            0.0000
                      0.0000
                                0.0000
mtot
mtot =
    1
          2
                                                        2
```

```
rtotv
```

rtotv =

Columns 1 through 7

421.8764 79.5468 64.2528 62.9359 62.7490 62.7169 62.7093

Columns 8 through 11

62.7055 62.7023 62.6992 62.6992

alphatota

alphatota =

Columns 1 through 7

-0.4000 -0.4084 -0.4062 -0.4023 -0.3981 -0.3938 -0.3895

Columns 8 through 11

-0.3853 -0.3810 -0.3768 -0.3725

omegatota

omegatota =

Columns 1 through 7

0.5000 0.0980 0.0240 0.0097 0.0069 0.0064 0.0061

Columns 8 through 11

0.0060 0.0058 0.0057 0.0056

echo off

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#### Contents

- Prob 1 pt2 conservative mu = 100
- mu 1e+05
- Iteration 2
- Iteration 3
- Iteration 4
- Iteration 5
- Iteration 6
- Iteration 7
- Iteration 8
- Iteration 9
- Iteration 10
- Echoing outputs for diary

# Prob 1 pt2 conservative mu = 100

```
clear all
close all
[t, y] = textread('Problem1_TExpo_sineData.txt','%f%f','headerlines',1);
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu start = 100;
mu down = 50;
mu up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
```

```
r22 = residual2' * residual2;
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;

mtot = [1];
mutot = [mu_start mu];
rtotv = [r2 r22];</pre>
```

```
ans =
  logical
```

## mu 1e+05

```
disp('Conservative mu 1e+05')
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu start = 1e+05;
mu_down = 50;
mu_up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
r22 = residual2' * residual2;
```

```
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;
```

```
Conservative mu 1e+05
ans =
  logical
```

```
r2 it = 10000000000000000;
r2_baseline = r22;
m = 1;
while r2_it > r2_baseline
    Ja1 = t.^3 .* exp(alphatot(2) .* t) .* sin(omegatot(2) .* t);
    Ja2 = t.^2 .* exp(alphatot(2) .* t) .* cos(omegatot(2) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;
    x1a = x0 - deltaxa;
    model3a = t .* (exp(x1a(1) .* t)) .* (sin(x1a(2)) .* t);
    residual3a = y - model<math>3a;
    r2_it = residual3a' * residual3a;
    if r2_it > r2_baseline
       mu = mu * mu_up;
    end
    m = m+1
end
    alphatota = [alphatot x1a(1)];
    omegatota = [omegatot x1a(2)];
if r2_it < r2_baseline</pre>
   mu = mu/mu_down;
   mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
```

```
rtotv = [rtotv r2_it];
disp('Iteration 2')
m
mu
r2_it
disp('Next Iteration')
```

```
m =
    2
Iteration 2
m =
    2
mu =
    4.0000e-05

r2_it =
    79.9736
Next Iteration
```

```
r3 it = 10000000000000000;
r2_baseline = r2_it;
m = 1;
while r3_it > r2_baseline || m == 5
    Ja1 = t.^3 .* exp(alphatota(3) .* t) .* sin(omegatota(3) .* t);
    Ja2 = t.^2 .* exp(alphatota(3) .* t) .* cos(omegatota(3) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;
    x2a = x1a - deltaxa;
    model4a = t .* (exp(x2a(1) .* t)) .* (sin(x2a(2)) .* t);
    residual4a = y - model4a;
    r3_it = residual4a' * residual4a;
    if r3_it > r2_baseline
       mu = mu * mu_up;
    end
    m = m+1
```

```
end
    alphatota = [alphatota x2a(1)];
    omegatota = [omegatota x2a(2)];

if r3_it < r2_baseline
    mu = mu/mu_down;

else
    mu = mu;

end

mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r3_it];
disp('Iteration 3')
m
mu
r3_it
disp('Next Iteration')</pre>
```

```
m =
    2
Iteration 3
m =
    2
mu =
    8.0000e-07
r3_it =
    64.3358
Next Iteration
```

```
r4_it = 1000000000000000;
r3_baseline = r3_it;
m = 1;

while r4_it > r3_baseline

Ja1 = t.^3 .* exp(alphatota(4) .* t) .* sin(omegatota(4) .* t);
Ja2 = t.^2 .* exp(alphatota(4) .* t) .* cos(omegatota(4) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;

x3a = x2a - deltaxa;
```

```
model5a = t .* (exp(x3a(1) .* t)) .* (sin(x3a(2)) .* t);
    residual5a = y - model5a;
    r4_it = residual5a' * residual5a;
    if r4 it > r3 baseline
      mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x3a(1)];
   omegatota = [omegatota x3a(2)];
if r4_it < r3_baseline</pre>
   mu = mu/mu_down;
else
 mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r4_it];
disp('Iteration 4')
mu
r4 it
disp('Next Iteration')
```

```
m =
    2
Iteration 4

m =
    2

mu =
    1.6000e-08

r4_it =
    62.9533

Next Iteration
```

```
r5 it = 100000000000000000000;
r4_baseline = r4_it;
m = 1;
while r5_it > r4_baseline
    Ja1 = t.^3 .* exp(alphatota(5) .* t) .* sin(omegatota(5) .* t);
    Ja2 = t.^2 .* exp(alphatota(5) .* t) .* cos(omegatota(5) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;
    x4a = x3a - deltaxa;
    model6a = t .* (exp(x4a(1) .* t)) .* (sin(x4a(2)) .* t);
    residual6a = y - model6a;
    r5_it = residual6a' * residual6a;
    if r5 it > r4 baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
   alphatota = [alphatota x4a(1)];
   omegatota = [omegatota x4a(2)];
if r5_it < r4_baseline</pre>
  mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r5_it];
disp('Iteration 5')
mu
r5 it
disp('Next Iteration')
```

```
m = 2
Iteration 5
m = 6
```

```
mu =
    3.2000e-10

r5_it =
    62.7534

Next Iteration
```

```
r6 it = 100000000000000;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline
    Ja1 = t.^3 .* exp(alphatota(6) .* t) .* sin(omegatota(6) .* t);
    Ja2 = t.^2 .* exp(alphatota(6) .* t) .* cos(omegatota(6) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
    x5a = x4a - deltaxa;
    model7a = t .* (exp(x5a(1) .* t)) .* (sin(x5a(2)) .* t);
    residual7a = y - model7a;
    r6_it = residual7a' * residual7a;
    if r6 it > r5 baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x5a(1)];
    omegatota = [omegatota x5a(2)];
if r6_it < r5_baseline</pre>
    mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
```

```
rtotv = [rtotv r6_it];
disp('Iteration 6')
m
mu
r6_it
disp('Next Iteration')
```

```
m =
    2
Iteration 6
m =
    2
mu =
    6.4000e-12
r6_it =
    62.7184
Next Iteration
```

```
r7_it = 10000000000000000;
r6_baseline = r6_it;
m = 1;
while r7_it > r6_baseline

Jal = t.^3 .* exp(alphatota(7) .* t) .* sin(omegatota(7) .* t);
Ja2 = t.^2 .* exp(alphatota(7) .* t) .* cos(omegatota(7) .* t);
Ja = [Jal Ja2];
deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
x6a = x5a - deltaxa;
model8a = t .* (exp(x6a(1) .* t)) .* (sin(x6a(2)) .* t);
residual8a = y - model8a;
r7_it = residual8a' * residual8a;

if r7_it > r6_baseline
    mu = mu * mu_up;
end
```

```
m = m+1
    if m == 5
      break
   end
   alphatota = [alphatota x6a(1)];
   omegatota = [omegatota x6a(2)];
if r7_it < r6_baseline</pre>
  mu = mu/mu down;
  mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r7_it];
disp('Iteration 7')
mu
r7 it
disp('Next Iteration')
```

```
m =
    2
Iteration 7
m =
    2
mu =
    1.2800e-13
r7_it =
    62.7103
Next Iteration
```

```
r8_it = 1000000000000000;
r7_baseline = r7_it;
m = 1;
while r8_it > r7_baseline

Ja1 = t.^3 .* exp(alphatota(8) .* t) .* sin(omegatota(8) .* t);
Ja2 = t.^2 .* exp(alphatota(8) .* t) .* cos(omegatota(8) .* t);
Ja = [Ja1 Ja2];
```

```
deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;
    x7a = x6a - deltaxa;
    model9a = t .* (exp(x7a(1) .* t)) .* (sin(x7a(2)) .* t);
    residual9a = y - model9a;
    r8 it = residual9a' * residual9a;
    if r8_it > r7_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
   alphatota = [alphatota x7a(1)];
   omegatota = [omegatota x7a(2)];
if r8_it < r7_baseline</pre>
   mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r8_it];
disp('Iteration 8')
m
mu
r8 it
disp('Next Iteration')
```

```
m =
    2
Iteration 8
m =
    2
mu =
    2.5600e-15
r8_it =
    62.7063
```

```
r9 it = 1000000000000000;
r8_baseline = r8_it;
m = 1;
while r9_it > r8_baseline
    Ja1 = t.^3 .* exp(alphatota(9) .* t) .* sin(omegatota(9) .* t);
    Ja2 = t.^2 .* exp(alphatota(9) .* t) .* cos(omegatota(9) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
       mu = mu * mu up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x8a(1)];
    omegatota = [omegatota x8a(2)];
if r9 it < r8 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r9_it];
disp('Iteration 9')
m
r9 it
disp('Next Iteration')
```

```
m =
```

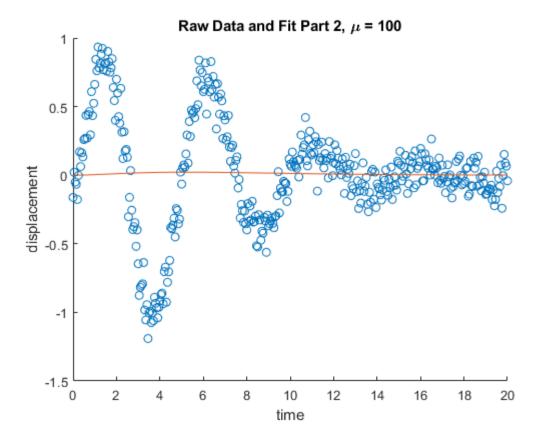
```
Iteration 9
m =
    2
mu =
    5.1200e-17
r9_it =
    62.7030
Next Iteration
```

```
r10 it = 1000000000000000000;
r9_baseline = r9_it;
m = 1;
while r10_it > r9_baseline
    Ja1 = t.^3 .* exp(alphatota(10) .* t) .* sin(omegatota(10) .* t);
    Ja2 = t.^2 .* exp(alphatota(10) .* t) .* cos(omegatota(10) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
   x9a = x8a - deltaxa;
    model11a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual11a = y - model11a;
    r10_it = residual11a' * residual11a;
    if r10_it > r9_baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x9a(1)];
    omegatota = [omegatota x9a(2)];
if r10_it < r9_baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
```

```
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r10_it];
disp('Iteration 10')
m
mu
r10_it
disp('Next Iteration')
% disp('Required 10 iterations to find final values')
f2 = figure('Name', 'Part 2 Plot over scatter, mu = 100');
scatter(t,y)
hold on
plot(t, model10a)
title('Raw Data and Fit Part 2, \mu = 100')
xlabel('time')
ylabel('displacement')
```

```
m =
    2
Iteration 10
m =
    2
mu =
    5.1200e-17
r10_it =
    62.7030
```

Next Iteration



#### **Echoing outputs for diary**

```
diary vjprob1pt2_groupB.txt

echo on

mutot

mtot

rtotv

alphatota

omegatota

echo off
```

```
mutot
mutot =
 Columns 1 through 7
 100.0000
            0.0020
                       0.0000
                                0.0000
                                        0.0000
                                                    0.0000 0.0000
 Columns 8 through 11
   0.0000
            0.0000
                      0.0000
                                0.0000
mtot
mtot =
    1
          2
                                                        2
```

```
rtotv
```

rtotv =

Columns 1 through 7

421.8764 97.5580 79.9736 64.3358 62.9533 62.7534 62.7184

Columns 8 through 11

62.7103 62.7063 62.7030 62.7030

alphatota

alphatota =

Columns 1 through 7

-0.4000 -0.4014 -0.4095 -0.4073 -0.4034 -0.3992 -0.3949

Columns 8 through 11

-0.3906 -0.3863 -0.3821 -0.3778

omegatota

omegatota =

Columns 1 through 7

0.5000 0.4972 0.1000 0.0249 0.0099 0.0070 0.0064

Columns 8 through 11

0.0062 0.0060 0.0059 0.0057

echo off

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#### Contents

- Problem 1 part 2 mu 1e+05
- mu 1e+05
- Iteration 2
- Iteration 3
- Iteration 4
- Iteration 5
- Iteration 6
- Iteration 7
- Iteration 8
- Iteration 9
- Iteration 10
- Echoing outputs for diary

#### Problem 1 part 2 mu 1e+05

```
clear all
close all
[t, y] = textread('Problem1_TExpo_sineData.txt','%f%f','headerlines',1);
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu start = 1e+05;
mu down = 50;
mu up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
```

```
r22 = residual2' * residual2;
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

%Iteration 0 values

mu = 0.1/50;
mtot = [1];
mutot = [mu_start mu];
rtotv = [r2 r22];</pre>
```

```
ans =
  logical
```

#### mu 1e+05

```
disp('Conservative mu 1e+05')
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu start = 1e+05;
mu_down = 50;
mu_up = 5;
% mu_rscout = mu_old * mu_up;
% mu cont = mu old/mu down;
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;
r22 = residual2' * residual2;
```

```
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;
```

```
Conservative mu 1e+05
ans =
  logical
```

```
r2 it = 10000000000000000;
r2_baseline = r22;
m = 1;
while r2_it > r2_baseline
    Ja1 = t.^3 .* exp(alphatot(2) .* t) .* sin(omegatot(2) .* t);
    Ja2 = t.^2 .* exp(alphatot(2) .* t) .* cos(omegatot(2) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;
    x1a = x0 - deltaxa;
    model3a = t .* (exp(x1a(1) .* t)) .* (sin(x1a(2)) .* t);
    residual3a = y - model<math>3a;
    r2_it = residual3a' * residual3a;
    if r2_it > r2_baseline
       mu = mu * mu_up;
    end
    m = m+1
end
    alphatota = [alphatot x1a(1)];
    omegatota = [omegatot x1a(2)];
if r2_it < r2_baseline</pre>
   mu = mu/mu_down;
   mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
```

```
rtotv = [rtotv r2_it];
disp('Iteration 2')
m
mu
r2_it
disp('Next Iteration')
```

```
m =
    2
Iteration 2
m =
    2
mu =
    4.0000e-05

r2_it =
    79.9736
Next Iteration
```

```
r3 it = 10000000000000000;
r2_baseline = r2_it;
m = 1;
while r3_it > r2_baseline || m == 5
    Ja1 = t.^3 .* exp(alphatota(3) .* t) .* sin(omegatota(3) .* t);
    Ja2 = t.^2 .* exp(alphatota(3) .* t) .* cos(omegatota(3) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;
    x2a = x1a - deltaxa;
    model4a = t .* (exp(x2a(1) .* t)) .* (sin(x2a(2)) .* t);
    residual4a = y - model4a;
    r3_it = residual4a' * residual4a;
    if r3_it > r2_baseline
       mu = mu * mu_up;
    end
    m = m+1
```

```
end
    alphatota = [alphatota x2a(1)];
    omegatota = [omegatota x2a(2)];

if r3_it < r2_baseline
    mu = mu/mu_down;

else
    mu = mu;

end

mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r3_it];
disp('Iteration 3')
m
mu
r3_it
disp('Next Iteration')</pre>
```

```
m =
    2
Iteration 3
m =
    2
mu =
    8.0000e-07
r3_it =
    64.3358
Next Iteration
```

```
r4_it = 1000000000000000;
r3_baseline = r3_it;
m = 1;

while r4_it > r3_baseline

Ja1 = t.^3 .* exp(alphatota(4) .* t) .* sin(omegatota(4) .* t);
Ja2 = t.^2 .* exp(alphatota(4) .* t) .* cos(omegatota(4) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;

x3a = x2a - deltaxa;
```

```
model5a = t .* (exp(x3a(1) .* t)) .* (sin(x3a(2)) .* t);
    residual5a = y - model5a;
    r4_it = residual5a' * residual5a;
    if r4 it > r3 baseline
      mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x3a(1)];
   omegatota = [omegatota x3a(2)];
if r4_it < r3_baseline</pre>
   mu = mu/mu_down;
else
 mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r4_it];
disp('Iteration 4')
mu
r4 it
disp('Next Iteration')
```

```
m =
    2
Iteration 4
m =
    2
mu =
    1.6000e-08
r4_it =
    62.9533
Next Iteration
```

```
r5 it = 10000000000000000;
r4_baseline = r4_it;
m = 1;
while r5_it > r4_baseline
   Ja1 = t.^3 .* exp(alphatota(5) .* t) .* sin(omegatota(5) .* t);
   Ja2 = t.^2 .* exp(alphatota(5) .* t) .* cos(omegatota(5) .* t);
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;
   x4a = x3a - deltaxa;
   model6a = t .* (exp(x4a(1) .* t)) .* (sin(x4a(2)) .* t);
   residual6a = y - model6a;
   r5_it = residual6a' * residual6a;
   if r5 it > r4 baseline
       mu = mu * mu_up;
   end
    m = m+1
   if m == 5
      break
   end
   alphatota = [alphatota x4a(1)];
   omegatota = [omegatota x4a(2)];
if r5_it < r4_baseline</pre>
  mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r5_it];
disp('Iteration 5')
mu
r5 it
disp('Next Iteration')
```

```
m = 2
Iteration 5
m = 6
```

```
mu =
    3.2000e-10

r5_it =
    62.7534

Next Iteration
```

```
r6 it = 100000000000000;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline
    Ja1 = t.^3 .* exp(alphatota(6) .* t) .* sin(omegatota(6) .* t);
    Ja2 = t.^2 .* exp(alphatota(6) .* t) .* cos(omegatota(6) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
    x5a = x4a - deltaxa;
    model7a = t .* (exp(x5a(1) .* t)) .* (sin(x5a(2)) .* t);
    residual7a = y - model7a;
    r6_it = residual7a' * residual7a;
    if r6 it > r5 baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x5a(1)];
    omegatota = [omegatota x5a(2)];
if r6_it < r5_baseline</pre>
    mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
```

```
rtotv = [rtotv r6_it];
disp('Iteration 6')
m
mu
r6_it
disp('Next Iteration')
```

```
m =
    2
Iteration 6
m =
    2
mu =
    6.4000e-12
r6_it =
    62.7184
Next Iteration
```

```
r7_it = 10000000000000000;
r6_baseline = r6_it;
m = 1;
while r7_it > r6_baseline

Jal = t.^3 .* exp(alphatota(7) .* t) .* sin(omegatota(7) .* t);
Ja2 = t.^2 .* exp(alphatota(7) .* t) .* cos(omegatota(7) .* t);
Ja = [Jal Ja2];
deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
x6a = x5a - deltaxa;
model8a = t .* (exp(x6a(1) .* t)) .* (sin(x6a(2)) .* t);
residual8a = y - model8a;
r7_it = residual8a' * residual8a;

if r7_it > r6_baseline
    mu = mu * mu_up;
end
```

```
m = m+1
    if m == 5
      break
   end
   alphatota = [alphatota x6a(1)];
   omegatota = [omegatota x6a(2)];
if r7_it < r6_baseline</pre>
  mu = mu/mu down;
  mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r7_it];
disp('Iteration 7')
mu
r7 it
disp('Next Iteration')
```

```
m =
    2
Iteration 7
m =
    2
mu =
    1.2800e-13
r7_it =
    62.7103
Next Iteration
```

```
r8_it = 1000000000000000;
r7_baseline = r7_it;
m = 1;
while r8_it > r7_baseline

Ja1 = t.^3 .* exp(alphatota(8) .* t) .* sin(omegatota(8) .* t);
Ja2 = t.^2 .* exp(alphatota(8) .* t) .* cos(omegatota(8) .* t);
Ja = [Ja1 Ja2];
```

```
deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;
    x7a = x6a - deltaxa;
    model9a = t .* (exp(x7a(1) .* t)) .* (sin(x7a(2)) .* t);
    residual9a = y - model9a;
    r8 it = residual9a' * residual9a;
    if r8_it > r7_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
   alphatota = [alphatota x7a(1)];
   omegatota = [omegatota x7a(2)];
if r8_it < r7_baseline</pre>
   mu = mu/mu down;
else
   mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r8_it];
disp('Iteration 8')
m
mu
r8 it
disp('Next Iteration')
```

```
m =
    2
Iteration 8
m =
    2
mu =
    2.5600e-15
r8_it =
    62.7063
```

```
r9 it = 1000000000000000;
r8_baseline = r8_it;
m = 1;
while r9_it > r8_baseline
    Ja1 = t.^3 .* exp(alphatota(9) .* t) .* sin(omegatota(9) .* t);
    Ja2 = t.^2 .* exp(alphatota(9) .* t) .* cos(omegatota(9) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
       mu = mu * mu up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x8a(1)];
    omegatota = [omegatota x8a(2)];
if r9 it < r8 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r9_it];
disp('Iteration 9')
m
r9 it
disp('Next Iteration')
```

```
m =
```

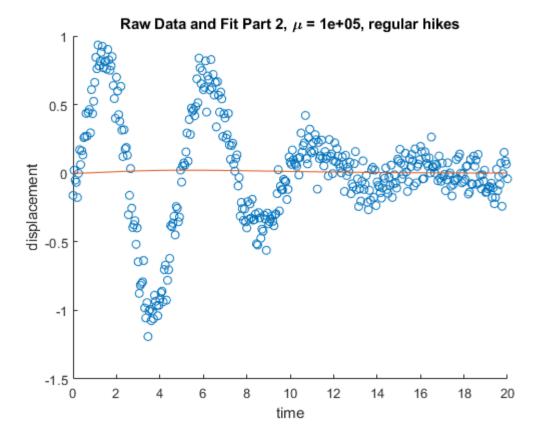
```
Iteration 9
m =
    2
mu =
    5.1200e-17
r9_it =
    62.7030
Next Iteration
```

```
r10 it = 1000000000000000000;
r9_baseline = r9_it;
m = 1;
while r10_it > r9_baseline
    Ja1 = t.^3 .* exp(alphatota(10) .* t) .* sin(omegatota(10) .* t);
    Ja2 = t.^2 .* exp(alphatota(10) .* t) .* cos(omegatota(10) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
   x9a = x8a - deltaxa;
    model11a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual11a = y - model11a;
    r10_it = residual11a' * residual11a;
    if r10_it > r9_baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x9a(1)];
    omegatota = [omegatota x9a(2)];
if r10_it < r9_baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
```

```
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r10_it];
disp('Iteration 10')
mu
r10_it
disp('Next Iteration')
% disp('Required 10 iterations to find final values')
f2 = figure('Name', 'Part 2 Plot over scatter, mu = 1e+05, regular hikes');
scatter(t,y)
hold on
plot(t, model10a)
title('Raw Data and Fit Part 2, \mu = 1e+05, regular hikes')
xlabel('time')
ylabel('displacement')
```

```
m =
    2
Iteration 10
m =
    2
mu =
    5.1200e-17
r10_it =
    62.7030
```

Next Iteration



### **Echoing outputs for diary**

```
diary vjprob1pt2_groupC.txt

echo on

mutot

mtot

rtotv

alphatota

omegatota

echo off
```

```
mutot
mutot =
  1.0e+05 *
 Columns 1 through 7
   1.0000
             0.0000
                      0.0000
                               0.0000
                                       0.0000
                                                  0.0000 0.0000
 Columns 8 through 11
   0.0000
          0.0000
                      0.0000
                               0.0000
mtot
mtot =
```

```
1 2 2 2 2 2 2 2 2 2
rtotv
rtotv =
 Columns 1 through 7
 421.8764 412.2513 79.9736 64.3358 62.9533 62.7534 62.7184
 Columns 8 through 11
  62.7103 62.7063 62.7030 62.7030
alphatota
alphatota =
 Columns 1 through 7
 -0.4000 -0.4014 -0.4095 -0.4073 -0.4034 -0.3992 -0.3949
 Columns 8 through 11
  -0.3906 -0.3863 -0.3821 -0.3778
omegatota
omegatota =
 Columns 1 through 7
  0.5000 0.4972 0.1000 0.0249 0.0099 0.0070 0.0064
 Columns 8 through 11
  0.0062 0.0060 0.0059 0.0057
```

echo off

.....

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### **Table of Contents**

# Problem 1 part 2 mu 1e+05 change hike

```
clear all
close all
[t, y] = textread('Problem1 TExpo sineData.txt','%f
%f','headerlines',1);
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';
J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);
J = [J1 \ J2];
model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);
residual = y - model;
r2 = residual' * residual;
mu_start = 1e+05;
mu_down = 5;
mu up = 5;
% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax ;
```

```
model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;

r22 = residual2' * residual2;
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;

mtot = [1];
mutot = [mu_start mu];
rtotv = [r2 r22];

ans =
  logical
  1</pre>
```

## mu 1e+05

```
disp('Conservative mu 1e+05')
alpha = -0.4;
omega = 0.5;
xk = [alpha omega]';

J1 = t.^3 .* exp(alpha .* t) .* sin(omega .* t);
J2 = t.^2 .* exp(alpha .* t) .* cos(omega .* t);

J = [J1 J2];

model = t .* (exp(alpha .* t)) .* (sin(omega) .* t);

residual = y - model;

r2 = residual' * residual;

mu_start = 1e+05;
mu_down = 5;
mu_up = 5;

% mu_rscout = mu_old * mu_up;
% mu_cont = mu_old/mu_down;
```

```
mmax = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;

model2 = t .* (exp(x0(1) .* t)) .* (sin(x0(2)) .* t);
residual2 = y - model2;

r22 = residual2' * residual2;
r22 < r2

alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];

mu = 0.1/50;

Conservative mu 1e+05

ans =
  logical
  1</pre>
```

```
r2_it = 10000000000000000;
r2_baseline = r22;
m = 1;
while r2_it > r2_baseline

Ja1 = t.^3 .* exp(alphatot(2) .* t) .* sin(omegatot(2) .* t);
Ja2 = t.^2 .* exp(alphatot(2) .* t) .* cos(omegatot(2) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;

x1a = x0 - deltaxa;

model3a = t .* (exp(xla(1) .* t)) .* (sin(xla(2)) .* t);

residual3a = y - model3a;

r2_it = residual3a' * residual3a;

if r2_it > r2_baseline
```

```
mu = mu * mu_up;
    end
     m = m+1
end
    alphatota = [alphatot x1a(1)];
    omegatota = [omegatot x1a(2)];
if r2_it < r2_baseline</pre>
    mu = mu/mu_down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r2_it];
disp('Iteration 2')
mu
r2 it
disp('Next Iteration')
m =
     2
Iteration 2
m =
     2
mu =
   4.0000e-04
r2_it =
   79.9736
Next Iteration
```

```
r3_it = 10000000000000;
r2_baseline = r2_it;
m = 1;
while r3_it > r2_baseline || m == 5
```

```
Ja1 = t.^3 .* exp(alphatota(3) .* t) .* sin(omegatota(3) .* t);
    Ja2 = t.^2 .* exp(alphatota(3) .* t) .* cos(omegatota(3) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;
    x2a = x1a - deltaxa;
    model4a = t .* (exp(x2a(1) .* t)) .* (sin(x2a(2)) .* t);
    residual4a = y - model4a;
    r3_it = residual4a' * residual4a;
    if r3_it > r2_baseline
        mu = mu * mu_up;
     m = m+1
end
    alphatota = [alphatota x2a(1)];
    omegatota = [omegatota x2a(2)];
if r3_it < r2_baseline</pre>
    mu = mu/mu_down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r3_it];
disp('Iteration 3')
mu
r3 it
disp('Next Iteration')
m =
     2
Iteration 3
m =
     2
mu =
   8.0000e-05
```

```
r3_it =

64.3359

Next Iteration
```

```
r4_it = 100000000000000;
r3_baseline = r3_it;
m = 1;
while r4_it > r3_baseline
    Ja1 = t.^3 .* exp(alphatota(4) .* t) .* sin(omegatota(4) .* t);
    Ja2 = t.^2 .* exp(alphatota(4) .* t) .* cos(omegatota(4) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;
    x3a = x2a - deltaxa;
    model5a = t .* (exp(x3a(1) .* t)) .* (sin(x3a(2)) .* t);
    residual5a = y - model5a;
    r4_it = residual5a' * residual5a;
    if r4 it > r3 baseline
        mu = mu * mu_up;
    end
     m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x3a(1)];
    omegatota = [omegatota x3a(2)];
if r4_it < r3_baseline</pre>
    mu = mu/mu down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
```

```
rtotv = [rtotv r4_it];
disp('Iteration 4')
m
mu
r4_it
disp('Next Iteration')
m =
     2
Iteration 4
m =
     2
mu =
   1.6000e-05
r4_it =
   62.9533
Next Iteration
```

```
r5_it = 10000000000000000;
r4_baseline = r4_it;
m = 1;
while r5_it > r4_baseline

Ja1 = t.^3 .* exp(alphatota(5) .* t) .* sin(omegatota(5) .* t);
Ja2 = t.^2 .* exp(alphatota(5) .* t) .* cos(omegatota(5) .* t);
Ja = [Ja1 Ja2];

deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;

x4a = x3a - deltaxa;

model6a = t .* (exp(x4a(1) .* t)) .* (sin(x4a(2)) .* t);

residual6a = y - model6a;

r5_it = residual6a' * residual6a;
```

```
if r5_it > r4_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x4a(1)];
    omegatota = [omegatota x4a(2)];
if r5_it < r4_baseline</pre>
    mu = mu/mu_down;
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r5_it];
disp('Iteration 5')
m
mu
r5_it
disp('Next Iteration')
m =
     2
Iteration 5
m =
     2
mu =
   3.2000e-06
r5_it =
   62.7534
Next Iteration
```

```
r6 it = 100000000000000;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline
    Ja1 = t.^3 .* exp(alphatota(6) .* t) .* sin(omegatota(6) .* t);
    Ja2 = t.^2 .* exp(alphatota(6) .* t) .* cos(omegatota(6) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
    x5a = x4a - deltaxa;
    model7a = t .* (exp(x5a(1) .* t)) .* (sin(x5a(2)) .* t);
    residual7a = y - model7a;
    r6_it = residual7a' * residual7a;
    if r6_it > r5_baseline
        mu = mu * mu_up;
    end
     m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x5a(1)];
    omegatota = [omegatota x5a(2)];
if r6_it < r5_baseline</pre>
    mu = mu/mu_down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r6_it];
disp('Iteration 6')
m
mu
r6_it
disp('Next Iteration')
```

```
m =
    2
Iteration 6
m =
    2

mu =
    6.4000e-07

r6_it =
    62.7184

Next Iteration
```

```
r7 \text{ it} = 10000000000000000;
r6_baseline = r6_it;
m = 1;
while r7_it > r6_baseline
    Ja1 = t.^3 .* exp(alphatota(7) .* t) .* sin(omegatota(7) .* t);
    Ja2 = t.^2 .* exp(alphatota(7) .* t) .* cos(omegatota(7) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
    x6a = x5a - deltaxa;
    model8a = t .* (exp(x6a(1) .* t)) .* (sin(x6a(2)) .* t);
    residual8a = y - model8a;
    r7_it = residual8a' * residual8a;
    if r7_it > r6_baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
```

```
break
    end
end
    alphatota = [alphatota x6a(1)];
    omegatota = [omegatota x6a(2)];
if r7_it < r6_baseline</pre>
    mu = mu/mu_down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r7_it];
disp('Iteration 7')
mu
r7 it
disp('Next Iteration')
m =
     2
Iteration 7
m =
     2
mu =
   1.2800e-07
r7_it =
   62.7103
Next Iteration
```

```
r8_it = 1000000000000000;
r7_baseline = r7_it;
m = 1;
while r8_it > r7_baseline
```

```
Ja1 = t.^3 .* exp(alphatota(8) .* t) .* sin(omegatota(8) .* t);
    Ja2 = t.^2 .* exp(alphatota(8) .* t) .* cos(omegatota(8) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;
    x7a = x6a - deltaxa;
    model9a = t .* (exp(x7a(1) .* t)) .* (sin(x7a(2)) .* t);
    residual9a = y - model9a;
    r8_it = residual9a' * residual9a;
    if r8_it > r7_baseline
        mu = mu * mu_up;
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x7a(1)];
    omegatota = [omegatota x7a(2)];
if r8_it < r7_baseline</pre>
    mu = mu/mu down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r8 it];
disp('Iteration 8')
m
mu
r8 it
disp('Next Iteration')
m =
     2
Iteration 8
m =
     2
```

```
mu =
    2.5600e-08

r8_it =
    62.7063

Next Iteration
```

mu = mu;

```
r9_it = 100000000000000;
r8_baseline = r8_it;
m = 1;
while r9_it > r8_baseline
    Ja1 = t.^3 .* exp(alphatota(9) .* t) .* sin(omegatota(9) .* t);
    Ja2 = t.^2 .* exp(alphatota(9) .* t) .* cos(omegatota(9) .* t);
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
        mu = mu * mu_up;
    end
     m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x8a(1)];
    omegatota = [omegatota x8a(2)];
if r9_it < r8_baseline</pre>
    mu = mu/mu down;
else
```

```
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r9_it];
disp('Iteration 9')
mu
r9_it
disp('Next Iteration')
m =
     2
Iteration 9
m =
     2
mu =
   5.1200e-09
r9_it =
   62.7030
Next Iteration
```

```
r10_it = 1000000000000000000;
r9_baseline = r9_it;
m = 1;
while r10_it > r9_baseline

    Ja1 = t.^3 .* exp(alphatota(10) .* t) .* sin(omegatota(10) .* t);
    Ja2 = t.^2 .* exp(alphatota(10) .* t) .* cos(omegatota(10) .* t);
    Ja = [Ja1 Ja2];

    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
    x9a = x8a - deltaxa;

    model11a = t .* (exp(x8a(1) .* t)) .* (sin(x8a(2)) .* t);
```

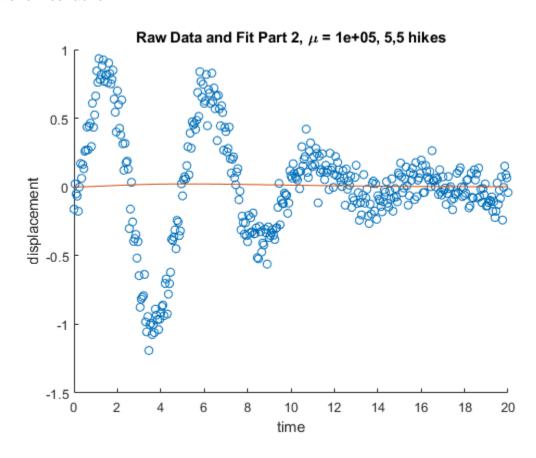
```
residual11a = y - model11a;
    r10_it = residual11a' * residual11a;
    if r10_it > r9_baseline
        mu = mu * mu up;
    end
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x9a(1)];
    omegatota = [omegatota x9a(2)];
if r10_it < r9_baseline</pre>
    mu = mu/mu_down;
else
    mu = mu;
end
mutot = [mutot mu];
mtot = [mtot m];
rtotv = [rtotv r10_it];
disp('Iteration 10')
mu
r10_it
disp('Next Iteration')
% disp('Required 10 iterations to find final values')
f2 = figure('Name', 'Part 2 Plot over scatter, mu = 1e+05, 5,5
hikes');
scatter(t,y)
hold on
plot(t, model10a)
title('Raw Data and Fit Part 2, \mu = 1e+05, 5,5 hikes')
xlabel('time')
ylabel('displacement')
m =
     2
Iteration 10
m =
```

2

mu =
 5.1200e-09

r10\_it =
 62.7030

Next Iteration



# **Echoing outputs for diary**

diary vjprob1pt2\_groupD.txt

echo on

mutot
mtot
rtotv
alphatota
omegatota

```
echo off
mutot
mutot =
 1.0e+05 *
 Columns 1 through 7
  1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
 Columns 8 through 11
  0.0000 0.0000 0.0000 0.0000
mtot
mtot =
   1 2 2 2 2 2 2 2 2 2
rtotv
rtotv =
 Columns 1 through 7
 421.8764 412.2513 79.9736 64.3359 62.9533 62.7534 62.7184
 Columns 8 through 11
 62.7103 62.7063 62.7030 62.7030
alphatota
alphatota =
 Columns 1 through 7
 -0.4000 -0.4014 -0.4095 -0.4073 -0.4034 -0.3992 -0.3949
 Columns 8 through 11
 -0.3906 -0.3863 -0.3821 -0.3778
omegatota
omegatota =
 Columns 1 through 7
   0.5000 0.4972 0.1000 0.0249 0.0099 0.0070 0.0064
```

Columns 8 through 11

0.0062 0.0060 0.0059 0.0057

echo off

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#### **Contents**

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- Plotting
- Sensitivity and specificity
- ROC
- Echoing Results to Diary

#### **Problem 2**

```
close all
clear all
[x,y] = textread('Problem2 LogisticData.txt','%f%f','headerlines',1);
%beta 0 is alpha
%beta 1 is omega
alpha = 4;
omega = -4;
xk = [alpha omega]';
J1 = \exp(-(alpha + omega .* x)) ./ (1 + \exp(-(alpha + omega .* x))).^2;
J2 = (x .* exp(-(alpha + omega .* x))) ./ (1 + exp(-(alpha + omega .* x))).^2;
J = [J1 \ J2];
model = 1 ./ (1 + exp(-(alpha + omega.*x)));
residual = y - model;
r2 = residual' * residual;
mu start = 500;
mu down = 50;
mu_up = 5;
deltax = inv(J'*J + mu_start.*[1 0; 0 1]) *J' * residual;
x0 = xk - deltax;
model2 = 1 ./ (1 + exp(-(x0(1) + x0(2).*x)));
residual2 = y - model2;
r22 = residual2' * residual2;
r22 < r2
```

```
alphatot = [xk(1) x0(1)];
omegatot = [xk(2) x0(2)];
mu = 0.1/50;
mutot = [mu start mu];
rtotv = [r2 r22];
r2 it = 10000000000000000;
r2 baseline = r22;
m = 1;
while r2_it > r2_baseline
    Jal = exp(-(alphatot(2) + omegatot(2) .* x)) ./ (1 + exp(-(alphatot(2) + omegatot(2) .* x))
x))).^2;
   Ja2 = (x \cdot *exp(-(alphatot(2) + omegatot(2) \cdot *x))) \cdot /(1 + exp(-(alphatot(2) + omegatot(2) \cdot *x)))
x))).^2;
   Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual2;
    x1a = x0 - deltaxa;
    model3a = 1 ./ (1 + exp(-(x1a(1) + x1a(2) .* x)));
    residual3a = y - model3a;
    r2_it = residual3a' * residual3a;
    if r2 it > r2 baseline
       mu = mu * mu_up;
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatot x1a(1)];
    omegatota = [omegatot x1a(2)];
if r2 it < r2 baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r2_it];
disp('Iteration 2')
mu
r2 it
disp('Next Iteration')
```

```
ans =
 logical
 0
m =
    2
m =
m =
    4
m =
    5
Iteration 2
    5
mu =
  1.2500
r2_it =
   60.8568
Next Iteration
```

```
Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual3a;
    x2a = x1a - deltaxa;
    model4a = 1 ./ (1 + exp(-(x2a(1) + x2a(2) .* x)));
    residual4a = y - model4a;
    r3_it = residual4a' * residual4a;
    if r3_it > r2_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
   alphatota = [alphatota x2a(1)];
   omegatota = [omegatota x2a(2)];
if r3_it < r2_baseline</pre>
   mu = mu/mu down;
else
  mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r3_it];
disp('Iteration 3')
m
mu
r3 it
disp('Next Iteration')
```

```
2
m = 3
m = 4
m = 5
Iteration 3
```

m =

```
m =
    5

mu =
    781.2500

r3_it =
    60.9611

Next Iteration
```

```
r4 it = 10000000000000000;
r3_baseline = r3_it;
m = 1;
while r4_it > r3_baseline
    Ja1 = exp(-(alphatota(4) + omegatota(4) .* x)) ./ (1 + exp(-(alphatota(4) + omegatota(4) .* x)))
x))).^2;
    Ja2 = (x \cdot *exp(-(alphatota(4) + omegatota(4) \cdot *x))) \cdot /(1 + exp(-(alphatota(4) + omegatota(4))))
.* x))).^2;
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual4a;
    x3a = x2a - deltaxa;
    model5a = 1 ./ (1 + exp(-(x3a(1) + x3a(2) .* x)));
    residual5a = y - model5a;
    r4 it = residual5a' * residual5a;
    if r4 it > r3 baseline
        mu = mu * mu_up;
    end
    m = m+1
    if m == 5
        break
    end
end
    alphatota = [alphatota x3a(1)];
    omegatota = [omegatota x3a(2)];
if r4_it < r3_baseline</pre>
   mu = mu/mu down;
else
   mu = mu;
```

```
end
mutot = [mutot mu];
rtotv = [rtotv r4_it];
disp('Iteration 4')
m
mu
r4_it
disp('Next Iteration')
```

```
m =
    2
m =
   3
m =
m =
   5
Iteration 4
m =
   5
mu =
 4.8828e+05
r4_it =
  60.9612
Next Iteration
```

```
r5_it = 100000000000000;
r4_baseline = r4_it;
m = 1;
while r5_it > r4_baseline

Ja1 = exp(-(alphatota(5) + omegatota(5) .* x) ) ./ (1 + exp(-(alphatota(5) + omegatota(5) .* x))).^2;
Ja2 = (x .* exp(-(alphatota(5) + omegatota(5) .* x))) ./ (1 + exp(-(alphatota(5) + omegatota(5) .* x)))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x)))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x)))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x)))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x))./ (1 + exp(-(alphatota(5) + omegatota(5) .* x))
```

```
.* x))).^2;
   Ja = [Ja1 Ja2];
   deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual5a;
   x4a = x3a - deltaxa;
   model6a = 1 ./ (1 + exp(-(x4a(1) + x4a(2) .* x)));
   residual6a = y - model6a;
   r5_it = residual6a' * residual6a;
   if r5_it > r4_baseline
      mu = mu * mu_up;
   end
    m = m+1
   if m == 5
      break
    end
end
   alphatota = [alphatota x4a(1)];
   omegatota = [omegatota x4a(2)];
if r5_it < r4_baseline</pre>
  mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r5_it];
disp('Iteration 5')
r5 it
disp('Next Iteration')
```

m =

```
r6 it = 10000000000000000;
r5_baseline = r5_it;
m = 1;
while r6_it > r5_baseline
    Jal = exp(-(alphatota(6) + omegatota(6) .* x)) ./ (1 + exp(-(alphatota(6) + omegatota(6) .* x)))
x))).^2;
    Ja2 = (x \cdot * exp(-(alphatota(6) + omegatota(6) \cdot * x))) \cdot / (1 + exp(-(alphatota(6) + omegatota(6))))
.* x))).^2;
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual6a;
    x5a = x4a - deltaxa;
    model7a = 1 ./ (1 + exp(-(x5a(1) + x5a(2) .* x)));
    residual7a = y - model7a;
    r6_it = residual7a' * residual7a;
    if r6 it > r5 baseline
        mu = mu * mu_up;
    end
     m = m+1
    if m == 5
       break
    end
    alphatota = [alphatota x5a(1)];
    omegatota = [omegatota x5a(2)];
if r6_it < r5_baseline</pre>
mu = mu/mu down;
```

```
else
    mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r6_it];
disp('Iteration 6')
m
mu
r6_it
disp('Next Iteration')
```

```
m =
 2
m =
3
m =
   4
m =
  5
Iteration 6
m =
 5
mu =
1.9073e+11
r6_it =
 60.9612
Next Iteration
```

```
r7_it = 10000000000000;
r6_baseline = r6_it;
m = 1;
while r7_it > r6_baseline
```

```
Ja1 = \exp(-(alphatota(7) + omegatota(7) .* x)) ./ (1 + exp(-(alphatota(7) + omegatota(7) .*
               Ja2 = (x \cdot * exp(-(alphatota(7) + omegatota(7) \cdot * x))) \cdot / (1 + exp(-(alphatota(7) + omegatota(7) + omegatota(7) + exp(-(alphatota(7) + omegatota(7) + exp(-(alphatota(7) + omegatota(7) + omegatota(7) + exp(-(alphatota(7) + omegatota(7) + omega
 .* x))).^2;
                Ja = [Ja1 Ja2];
                deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual7a;
                x6a = x5a - deltaxa;
                model8a = 1 ./ (1 + exp(-(x6a(1) + x6a(2) .* x)));
                residual8a = y - model8a;
                r7_it = residual8a' * residual8a;
                if r7_it > r6_baseline
                               mu = mu * mu_up;
                end
                  m = m+1
                if m == 5
                              break
                end
 end
                alphatota = [alphatota x6a(1)];
                omegatota = [omegatota x6a(2)];
 if r7_it < r6_baseline</pre>
               mu = mu/mu down;
              mu = mu;
 mutot = [mutot mu];
 rtotv = [rtotv r7 it];
 disp('Iteration 7')
 mu
 r7 it
 disp('Next Iteration')
```

```
2
m = 3
m = 4
```

m =

```
r8 it = 10000000000000000;
r7_baseline = r7_it;
m = 1;
while r8 it > r7 baseline
    Ja1 = exp(-(alphatota(8) + omegatota(8) .* x)) ./ (1 + exp(-(alphatota(8) + omegatota(8) .* x)))
x))).^2;
   Ja2 = (x \cdot * exp(-(alphatota(8) + omegatota(8) \cdot * x))) \cdot / (1 + exp(-(alphatota(8) + omegatota(8)
.* x))).^2;
   Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual8a;
    x7a = x6a - deltaxa;
    model9a = 1 ./ (1 + exp(-(x7a(1) + x7a(2) .* x)));
    residual9a = y - model9a;
    r8_it = residual9a' * residual9a;
    if r8_it > r7_baseline
       mu = mu * mu up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x7a(1)];
```

```
omegatota = [omegatota x7a(2)];

if r8_it < r7_baseline
    mu = mu/mu_down;
else
    mu = mu;
end

mutot = [mutot mu];
rtotv = [rtotv r8_it];
disp('Iteration 8')
m
mu
r8_it
disp('Next Iteration')</pre>
```

```
m =
    2

m =
    3

m =
    4

Iteration 8

m =
    4

mu =
    2.9802e+15

r8_it =
    60.9612

Next Iteration
```

```
r9_it = 100000000000000;
r8_baseline = r8_it;
m = 1;
while r9_it > r8_baseline

Ja1 = exp(-(alphatota(9) + omegatota(9) .* x) ) ./ (1 + exp(-(alphatota(9) + omegatota(9) .*
```

```
x))).^2;
    Ja2 = (x .* exp(-(alphatota(9) + omegatota(9) .* x))) ./ (1 + exp(-(alphatota(9) + omegatota(9) .* x)))
    Ja = [Ja1 Ja2];
    deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual9a;
    x8a = x7a - deltaxa;
    model10a = 1 ./ (1 + exp(-(x8a(1) + x8a(2) .* x)));
    residual10a = y - model10a;
    r9_it = residual10a' * residual10a;
    if r9_it > r8_baseline
       mu = mu * mu_up;
    end
    m = m+1
    if m == 5
       break
    end
end
    alphatota = [alphatota x8a(1)];
    omegatota = [omegatota x8a(2)];
if r9_it < r8_baseline</pre>
   mu = mu/mu_down;
else
   mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r9_it];
disp('Iteration 9')
m
mu
r9_it
disp('Next Iteration')
```

```
2
m = 3
Iteration 9
m =
```

3

m =

```
mu =
    1.4901e+16

r9_it =
    60.9612

Next Iteration
```

```
r10 it = 1000000000000000000;
r9_baseline = r9_it;
m = 1;
while r10 it > r9 baseline
              Jal = exp(-(alphatota(10) + omegatota(10) .* x)) ./ (1 + exp(-(alphatota(10) + omegatota(10) .* x)))
x))).^2;
             Ja2 = (x .* exp(-(alphatota(10) + omegatota(10) .* x))) ./ (1 + exp(-(alphatota(10) .* x
omegatota(10) .* x))).^2;
             Ja = [Ja1 Ja2];
              deltaxa = inv(J'*J + mu.*[1 0; 0 1]) *J' * residual10a;
              x9a = x8a - deltaxa;
              model11a = 1 ./ (1 + exp(-(x9a(1) + x9a(2) .* x)));
              residual11a = y - model11a;
              r10_it = residual11a' * residual11a;
              if r10_it > r9_baseline
                          mu = mu * mu up;
              end
                m = m+1
              if m == 5
                          break
               end
end
              alphatota = [alphatota x9a(1)];
              omegatota = [omegatota x9a(2)];
if r10 it < r9 baseline</pre>
             mu = mu/mu_down;
else
             mu = mu;
end
mutot = [mutot mu];
rtotv = [rtotv r10_it];
disp('Iteration 10')
```

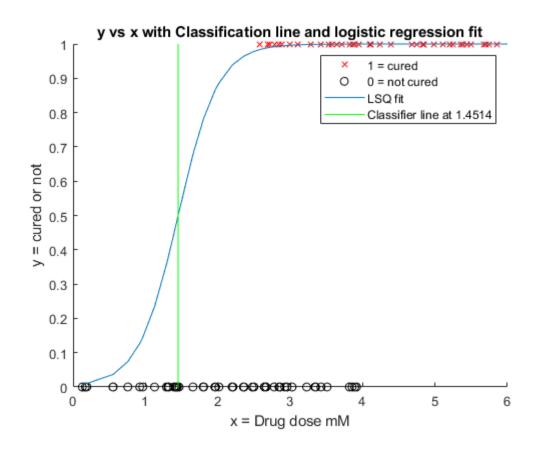
```
m
mu
r10_it
disp('Next Iteration')
% disp('Required 10 iterations to find final values')
```

```
m =
    2
Iteration 10
m =
    2
mu =
    1.4901e+16
r10_it =
    60.9612
Next Iteration
```

#### **Plotting**

```
vertx = -alphatota(9)/omegatota(9)
yind = find(y>0,100);
yind2 = find(y<1, 100);
scatter(x(yind), y(yind),'r', 'x'); %all ones
hold on
scatter(x(yind2),y(yind2),'k', 'o');
hold on
fp = flip(model9a);
plot(x, -model9a+1)
hold on
line([vertx vertx], [0 1], 'Color', 'g')
title('y vs x with Classification line and logistic regression fit');
xlabel('x = Drug dose mM');
ylabel('y = cured or not');
legend('1 = cured', '0 = not cured', 'LSQ fit', 'Classifier line at 1.4514')
xlim([0 6])
```

```
vertx = 1.4514
```



#### Sensitivity and specificity

```
%we know that there are 50 positives, 50 neg

xind1 = find(x(yind) > vertx, 50);
tp = length(xind1);
xind4 = find(x(yind) < vertx, 50);
fn = length(xind4);
xind2 = find(x(yind2) < vertx, 50);
tf = length(xind2);
xind3 = find(x(yind2) > vertx, 50);
fp = length(xind3);

sensitivity = tp/(tp + fn);
specificity = tf/(tf + fp);
```

#### **ROC**

```
%do the above for the model with x* from 0 to 6 (0 1 2 3 4 5 6)

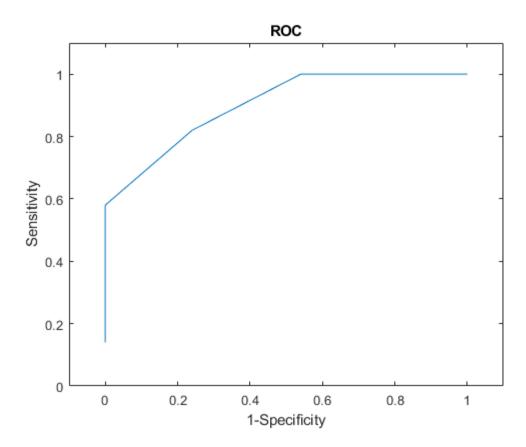
yinda = find(y>0,100);

yind2a = find(y<1, 100);

sense = [];

spec = [];
```

```
for i = 0:6
    xindla = find(x(yinda) > i, 50);
    tpa = length(xindla);
    xind2a = find(x(yind2a) < i, 50);
    tfa = length(xind2a);
    xind3a = find(x(yind2a) > i, 50);
    fpa = length(xind3a);
    xind4a = find(x(yinda) < i, 50);
    fna = length(xind4a);
    ss = tpa/(tpa + fna);
    sp = 1 - (tfa/(tfa + fpa));
    sense = [sense ss];
    spec = [spec sp];
end
figure;
plot(spec, sense)
title('ROC')
xlabel('1-Specificity');
ylabel('Sensitivity');
ylim([0 1.1]);
xlim([-0.1 1.1]);
```



#### **Echoing Results to Diary**

```
diary vjprob2.txt

echo on

mutot
rtotv
```

```
beta_one = omegatota
sensitivity
specificity
echo off
mutot
mutot =
 1.0e+16 *
 Columns 1 through 7
  0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
 Columns 8 through 11
  0.0119 0.2980 1.4901 1.4901
rtotv
rtotv =
 Columns 1 through 7
 55.9632 55.9721 60.8568 60.9611 60.9612 60.9612 60.9612
 Columns 8 through 11
 60.9612 60.9612 60.9612 60.9612
beta_o = alphatota
beta_o =
 Columns 1 through 7
  4.0000 4.0022 5.2663 5.2790 5.2790 5.2790 5.2790
 Columns 8 through 11
  5.2790 5.2790 5.2790 5.2790
beta_one = omegatota
beta_one =
 Columns 1 through 7
 -4.0000 -3.9980 -3.6501 -3.6371 -3.6371 -3.6371 -3.6371
 Columns 8 through 11
  -3.6371 -3.6371 -3.6371 -3.6371
sensitivity
```

beta o = alphatota

sensitivity =

specificity
specificity =
 0.3400

echo off

1

.....

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### **Problem 3**

```
clear all
close all
day1 = [1.7 1.72 1.73 2.30 2.40 2.50 2.55 2.6];
day15 = [3.8 \ 3.95 \ 4.00 \ 4.3 \ 4.4 \ 4.5 \ 4.7 \ 4.9 \ 5 \ 5.10]';
day29 = [4.2 \ 4.3 \ 4.4 \ 4.45 \ 4.50 \ 4.51 \ 4.70 \ 4.75 \ 4.80 \ 4.85]';
day36 = [4.9 5.1 5.73 5.75 5.77 5.78 5.82 5.85]';
convplctrl = [2.5 4.2 4.25 4.4 4.6 4.8 5 5.2 5.6 5.8 5.9 6 6.2 6.3 6.4
  6.5]';
totvec = [day1' day15' day29' day36' convplctrl'];
totvecl = {'d1', 'd1', 'd1', 'd1', 'd1', 'd1', 'd1', 'd1', ...
     'd15', 'd
     'd29', ...
          'd36', 'd36', 'd36', 'd36', 'd36', 'd36', 'd36', 'd36', ...
     'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', ...
     'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl', 'cptrl'};
d1m = mean(day1);
d15m = mean(day15);
d29m = mean(day29);
d36m = mean(day36);
convplm = mean(convplctrl);
totvecm = mean(totvec);
figure;
daylones = ones(length(dayl),1);
h = scatter(daylones,dayl,'r');
hold on
day15ones = 15*ones(length(day15),1);
h1 = scatter(day15ones,day15, 'g');
hold on
day29ones = 29*ones(length(day29),1);
h2 = scatter(day29ones,day29, 'b');
hold on
day36ones = 36*ones(length(day36),1);
h3 = scatter(day36ones,day36,'y');
hold on
convones = 60*ones(length(convplctrl),1);
h4 = scatter(convones, convplctrl, 'm');
```

```
ylim([0 7])
xlim([0 62])
hl0 = line([0:3], [dlm dlm dlm dlm], 'Color', 'r');
hl1 = line([12:18], [d15m d15m d15m d15m d15m])
 d15m], 'Color', 'g');
hl2 = line([26:32], [d29m d29m d29m d29m d29m d29m])
 d29m], 'Color', 'b', 'LineWidth', 3);
hl3 = line([33:39], [d36m d36m d36m d36m d36m d36m])
 d36m], 'Color', 'y');
h14 = line([57:63], [convplm convplm convplm convplm convplm
 convplm], 'Color', 'm');
11 = [1:60];
hl5 = line(ll,
 totvecm*ones(length(11),1)', 'Color', 'k', 'LineStyle', '--');
title('S-2P')
ylabel('Reciprocal Enpdpoint Titer (log-scale)')
xlabel('Study Day')
set(gca,'XTickLabel',{'0','10','20','30','40','50','Convalescent'});
hold off
dtot = totvec' - totvecm*ones(length(totvec),1);
SStot = dtot'*dtot;
doftot = length(totvec)-1;
%do it for each each group
%take variable
SSerror = sscalc(day1) + sscalc(day15) + sscalc(day29) + sscalc(day36)
 + sscalc(convplctrl);
groupdof = doftot - 4;
SSgroup = length(day1)*(d1m - totvecm) + length(day15)*(d15m -
 totvecm) + length(day29)*(d29m - totvecm) + length(day36)*(d36m -
 totvecm) + ...
    length(convplctrl)*(convplm - totvecm); %odd not sure why this
 didn't work
SSgroup_real = SStot-SSerror;
groupodof = 4;
groupvar = SSgroup_real/groupodof;
errorvar = SSerror/groupdof;
F = groupvar/errorvar;
DOF = [groupodof groupdof doftot]';
% xx = ['Days (Categorical)';'Error';'Total'];
SS = [SSgroup_real, SSerror, SStot]';
```

```
MS = [groupvar, errorvar, NaN]';
FF = [F, NaN, NaN]';
pp = [1, NaN, NaN]';
Fcrit = [2.5695, NaN, NaN]';
tfields = { 'DOF'
            'MS'
            1 F 1
            'Fcrit'
            'isp' };
fulltable = table(DOF, SS, MS, FF, Fcrit, pp, 'VariableNames',
 tfields);
%tukey test
DGM = zeros(5,5);
DGM(2,1) = d1m - d15m;
DGM(3,1) = d1m - d29m;
DGM(4,1) = d1m - d36m;
DGM(5,1) = dlm - convplm;
DGM(3,2) = d15m - d29m;
DGM(4,2) = d15m - d36m;
DGM(5,2) = d15m - convplm;
DGM(4,3) = d29m - d36m;
DGM(5,3) = d29m - convplm;
DGM(5,4) = d36m - convplm;
% DGM
% abs(DGM)
% HSD
q = 4.011;
mse = errorvar;
HSD = zeros(5,5);
HSD(2,1) = 4.011 * ((mse/2)*(1/8 + 1/10))^0.5;
HSD(3,1) = 4.011 * ((mse/2)*(1/8 + 1/10))^0.5;
HSD(4,1) = 4.011 * ((mse/2)*(1/8 + 1/8))^0.5;
HSD(5,1) = 4.011 * ((mse/2)*(1/8 + 1/16))^0.5;
HSD(3,2) = 4.011 * ((mse/2)*(1/10 + 1/10))^0.5;
HSD(4,2) = 4.011 * ((mse/2)*(1/10 + 1/8))^0.5;
HSD(5,2) = 4.011 * ((mse/2)*(1/16 + 1/10))^0.5;
HSD(4,3) = 4.011 * ((mse/2)*(1/8 + 1/10))^0.5;
HSD(5,3) = 4.011 * ((mse/2)*(1/16 + 1/10))^0.5;
HSD(5,4) = 4.011 * ((mse/2)*(1/16 + 1/8))^0.5;
% HSD
% DGM - HSD
diary VJprob3.txt
echo on
fulltable
disp('Since F is greater than critical value, p is less than alpha and
thus we can reject the null hypothesis.')
disp('Group 1 is statistically dissimilar to all the rest. Group 4 and
 5 are statistically the same, thus are the higher titer.')
```

```
disp('According to abs(DGM) - HSD, group 2 and 3 are statistically
 similar.')
disp('Day 15 and 36 are statistically dissimilar.')
disp('Group 2 and 5 are statistically similar.')
disp('Group 3 and 4 are statistically dissimilar.')
echo off
fulltable
fulltable =
  3×6 table
    DOF
             SS
                       MS
                                   F
                                           Fcrit
                                                      isp
           60.685
                                           2.5695
     4
                      15.171
                                 32.754
           21.769
    47
                     0.46318
                                    NaN
                                              NaN
                                                      NaN
    51
           82.454
                         NaN
                                    NaN
                                              NaN
                                                      NaN
 thus we can reject the null hypothesis.')
```

disp('Since F is greater than critical value, p is less than alpha and

Since F is greater than critical value, p is less than alpha and thus we can reject the null hypothesis.

disp('Group 1 is statistically dissimilar to all the rest. Group 4 and 5 are statistically the same, thus are the higher titer.')

Group 1 is statistically dissimilar to all the rest. Group 4 and 5 are statistically the same, thus are the higher titer.

disp('According to abs(DGM) - HSD, group 2 and 3 are statistically similar.')

According to abs(DGM) - HSD, group 2 and 3 are statistically similar.

disp('Day 15 and 36 are statistically dissimilar.')

Day 15 and 36 are statistically dissimilar.

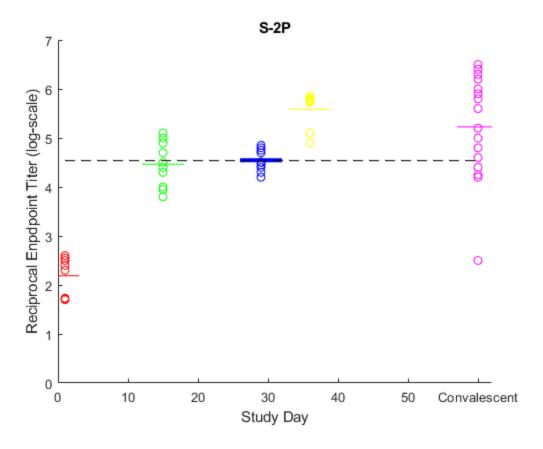
disp('Group 2 and 5 are statistically similar.')

Group 2 and 5 are statistically similar.

disp('Group 3 and 4 are statistically dissimilar.')

Group 3 and 4 are statistically dissimilar.

echo off



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