
Table of Contents

BE606 HW3 Problem 1	1
Part 1	1
knnsearch	3
Webmap	8

BE606 HW3 Problem 1

```
close all
clear all
```

Part 1

```
A = readtable('housing.csv');

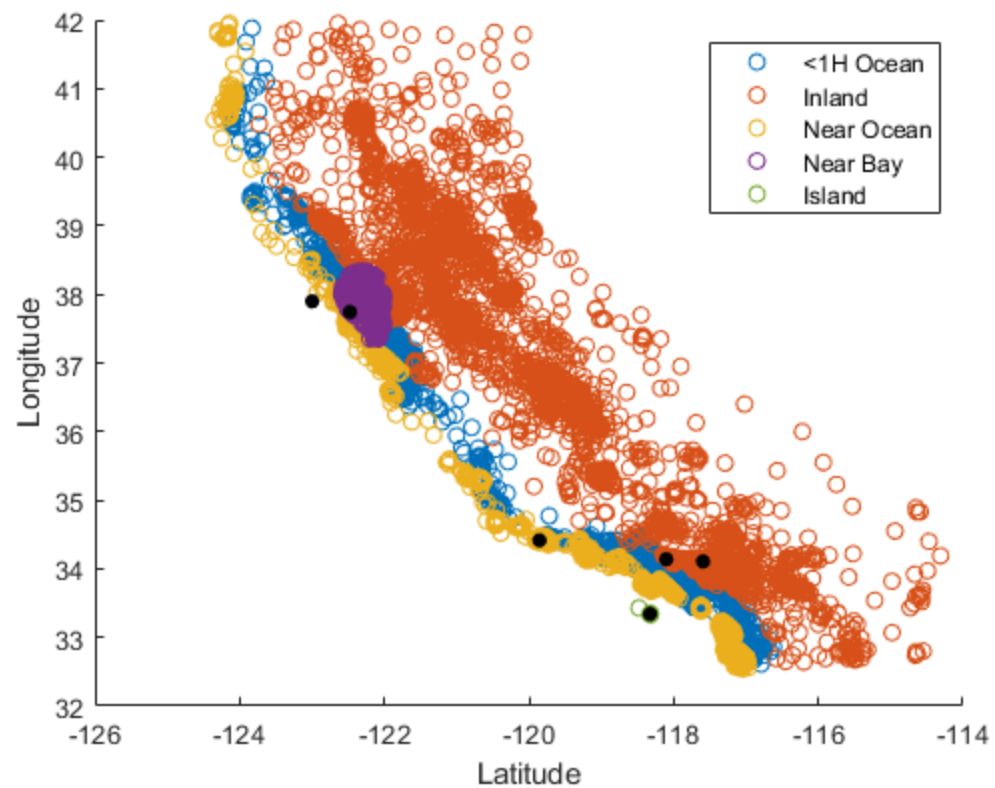
for i = 1:1:20640
    if strcmp(A.ocean_proximity(i), 'NEAR BAY')
        A.ocean_proximity(i) = strrep(A.ocean_proximity(i), 'NEAR
BAY', '4');
    elseif strcmp(A.ocean_proximity(i), '<1H OCEAN')
        A.ocean_proximity(i) = strrep(A.ocean_proximity(i), '<1H
OCEAN', '1');
    elseif strcmp(A.ocean_proximity(i), 'INLAND')
        A.ocean_proximity(i) =
strrep(A.ocean_proximity(i), 'INLAND', '2');
    elseif strcmp(A.ocean_proximity(i), 'NEAR OCEAN')
        A.ocean_proximity(i) = strrep(A.ocean_proximity(i), 'NEAR
OCEAN', '3');
    else
        A.ocean_proximity(i) =
strrep(A.ocean_proximity(i), 'ISLAND', '5');
    end
    % str2double(A.ocean_proximity(i));
end

OPClass = A.ocean_proximity;
abc = cellfun(@str2num, OPClass);
B = table2array(A(:,1:9));

B = [B abc];

figure;
plotmatrix(B)

x1 = B(:,1);
```

knnsearch

```
X = [x1 x2];  
Ynew = [x1new' x2new'];  
  
[idx, eD] = knnsearch(X,Ynew,'K', 20);  
  
house1idx = idx(1,:)';  
house1x1 = x1(house1idx);  
house1x2 = x2(house1idx);  
house1y = y(house1idx);  
  
house2idx = idx(2,:)';  
house2x1 = x1(house2idx);  
house2x2 = x2(house2idx);  
house2y = y(house2idx);  
  
house3idx = idx(3,:)';  
house3x1 = x1(house3idx);  
house3x2 = x2(house3idx);  
house3y = y(house3idx);  
  
house4idx = idx(4,:)';  
house4x1 = x1(house4idx);  
house4x2 = x2(house4idx);
```

```

house4y = y(house4idx);

house5idx = idx(5,:);
house5x1 = x1(house5idx);
house5x2 = x2(house5idx);
house5y = y(house5idx);

house6idx = idx(6,:);
house6x1 = x1(house6idx);
house6x2 = x2(house6idx);
house6y = y(house6idx);

houseclasstot = [mode(house1y) mode(house2y) mode(house3y)
mode(house4y) mode(house5y) mode(house6y)];
%make into table for output
for jj = 1:6
    fprintf('New House #%d ',jj)
    fprintf('Classified as %d\n', houseclasstot(jj))
    disp('')
end

House1table=table(house1x1, house1x2, house1y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})
House2table=table(house2x1, house2x2, house2y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})
House3table=table(house3x1, house3x2, house3y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})
House4table=table(house4x1, house4x2, house4y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})
House5table=table(house5x1, house5x2, house5y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})
House6table=table(house6x1, house6x2, house6y, 'VariableNames',
{'Longitude','Latitude', 'HousingClass'})

New House #1 Classified as 2
New House #2 Classified as 3
New House #3 Classified as 4
New House #4 Classified as 1
New House #5 Classified as 3
New House #6 Classified as 3

House1table =

20x3 table

    Longitude    Latitude    HousingClass
    _____    _____    _____
    -117.59         34.1         2
    -117.6          34.11        2
    -117.58         34.11        2
    -117.58         34.1         2
    -117.59         34.09        2

```

-117.61	34.1	2
-117.58	34.09	2
-117.61	34.12	2
-117.61	34.09	2
-117.61	34.09	2
-117.59	34.13	2
-117.6	34.08	2
-117.62	34.11	2
-117.62	34.11	2
-117.61	34.13	2
-117.61	34.08	2
-117.61	34.08	2
-117.62	34.09	2
-117.57	34.13	2
-117.56	34.12	2

House2table =

20×3 table

<i>Longitude</i>	<i>Latitude</i>	<i>HousingClass</i>
_____	_____	_____
-122.93	38.02	3
-122.84	38.07	3
-122.86	38.1	3
-122.81	38.08	3
-122.71	37.9	3
-122.71	37.88	3
-122.69	37.91	3
-122.7	38.03	3
-122.68	38.01	3
-122.66	37.93	3
-122.8	38.18	3
-122.68	38.07	3
-122.64	37.96	3
-122.96	38.26	3
-122.65	38.01	3
-122.64	38.01	3
-122.64	38.01	3
-122.62	37.85	3
-122.62	37.97	3
-122.9	38.28	3

House3table =

20×3 table

<i>Longitude</i>	<i>Latitude</i>	<i>HousingClass</i>
_____	_____	_____
-122.47	37.74	4

-122.47	37.74	4
-122.47	37.74	4
-122.47	37.74	4
-122.48	37.74	3
-122.48	37.74	3
-122.48	37.74	3
-122.48	37.74	3
-122.47	37.75	4
-122.47	37.75	4
-122.47	37.75	4
-122.47	37.75	4
-122.47	37.75	4
-122.47	37.75	4
-122.48	37.75	4
-122.48	37.75	4
-122.48	37.75	4
-122.48	37.75	4
-122.48	37.75	4
-122.47	37.73	3

House4table =

20×3 table

<i>Longitude</i>	<i>Latitude</i>	<i>HousingClass</i>
<hr/>	<hr/>	<hr/>
-118.1	34.14	1
-118.1	34.14	1
-118.11	34.14	1
-118.11	34.14	1
-118.1	34.13	1
-118.1	34.13	1
-118.1	34.13	1
-118.1	34.15	2
-118.1	34.15	2
-118.09	34.14	2
-118.11	34.15	1
-118.11	34.15	1
-118.09	34.15	2
-118.09	34.15	2
-118.09	34.15	2
-118.09	34.15	2
-118.09	34.15	2
-118.12	34.14	1
-118.12	34.14	1
-118.1	34.12	1
-118.1	34.12	1

House5table =

20×3 table

<i>Longitude</i>	<i>Latitude</i>	<i>HousingClass</i>
<hr/>	<hr/>	<hr/>
-119.86	34.42	3
-119.86	34.41	3
-119.85	34.4	3
-119.85	34.44	3
-119.88	34.42	3
-119.83	34.43	3
-119.84	34.44	3
-119.88	34.43	3
-119.88	34.43	3
-119.88	34.43	3
-119.88	34.4	3
-119.83	34.44	3
-119.83	34.44	3
-119.88	34.44	3
-119.86	34.38	3
-119.86	34.38	3
-119.82	34.43	3
-119.84	34.45	3
-119.82	34.44	3
-119.82	34.44	3

House6table =

20×3 table

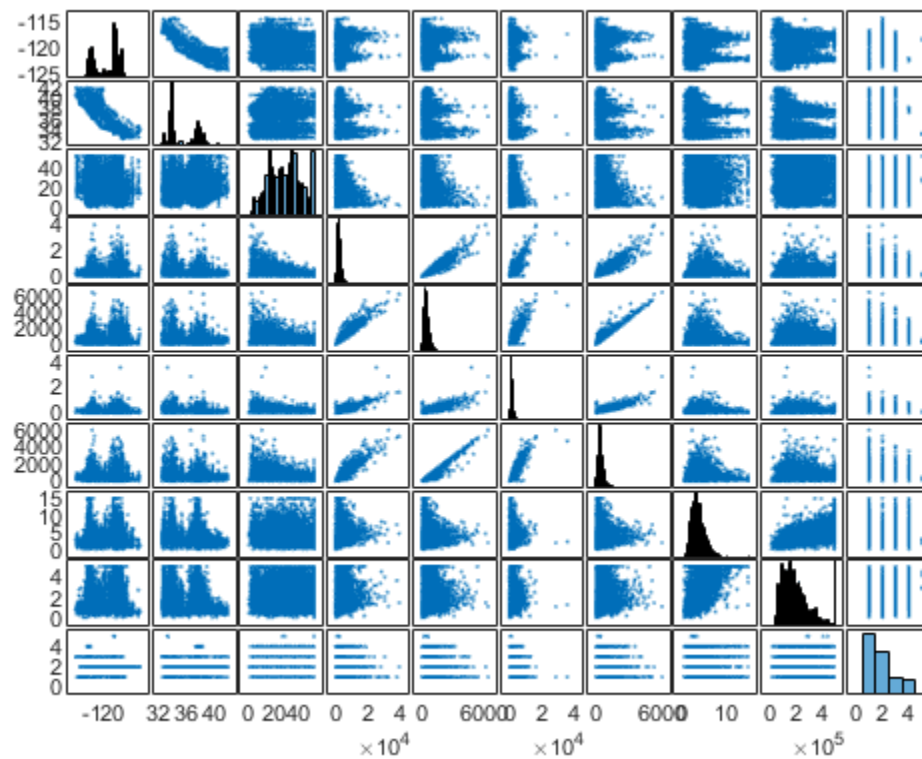
<i>Longitude</i>	<i>Latitude</i>	<i>HousingClass</i>
<hr/>	<hr/>	<hr/>
-118.33	33.34	5
-118.32	33.34	5
-118.32	33.35	5
-118.32	33.33	5
-118.48	33.43	5
-118.31	33.67	3
-118.28	33.68	3
-118.33	33.69	3
-118.29	33.71	3
-118.29	33.71	3
-118.29	33.71	3
-118.29	33.71	3
-118.39	33.71	3
-118.33	33.72	3
-118.31	33.72	3
-118.3	33.72	3
-118.3	33.72	3
-118.3	33.72	3
-118.29	33.72	3
-118.29	33.72	3

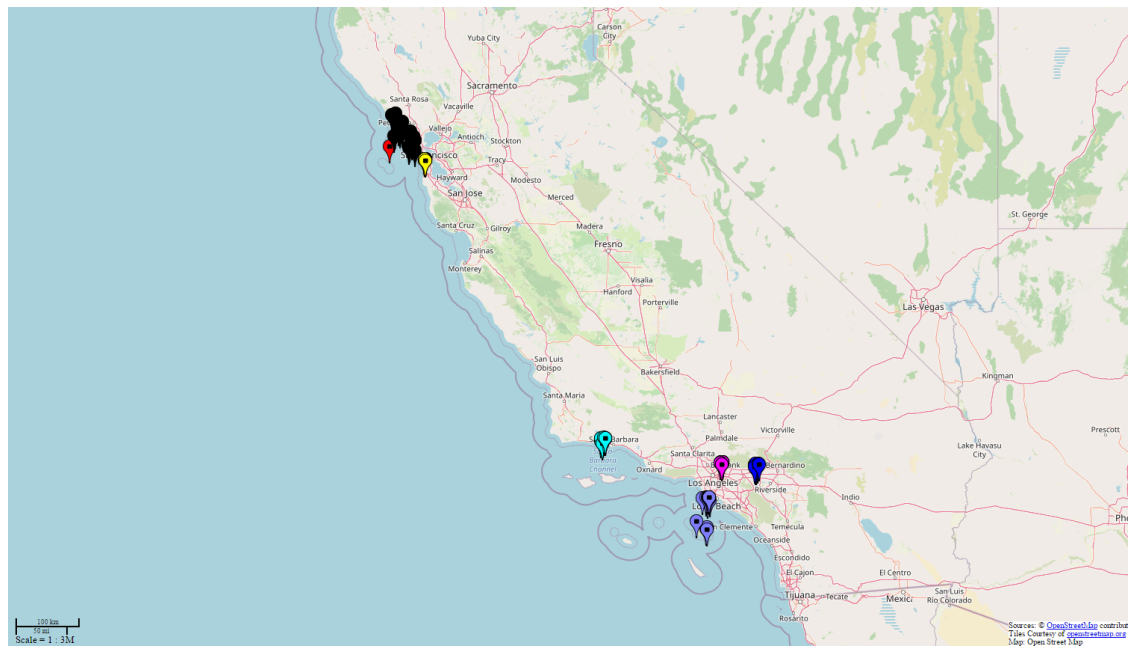
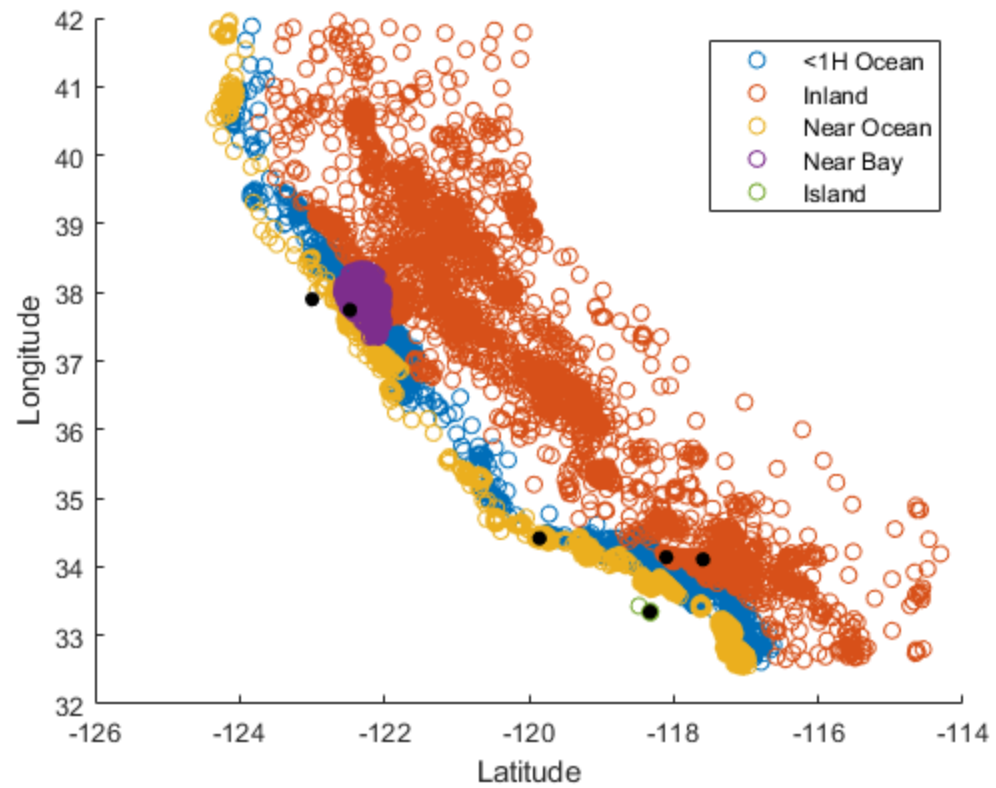
Webmap

```
wm = webmap('Open Street Map');
newhouses = geoint(x2new, x1new);
webmarker_nh = wmmarker(newhouses, 'Color', 'red');

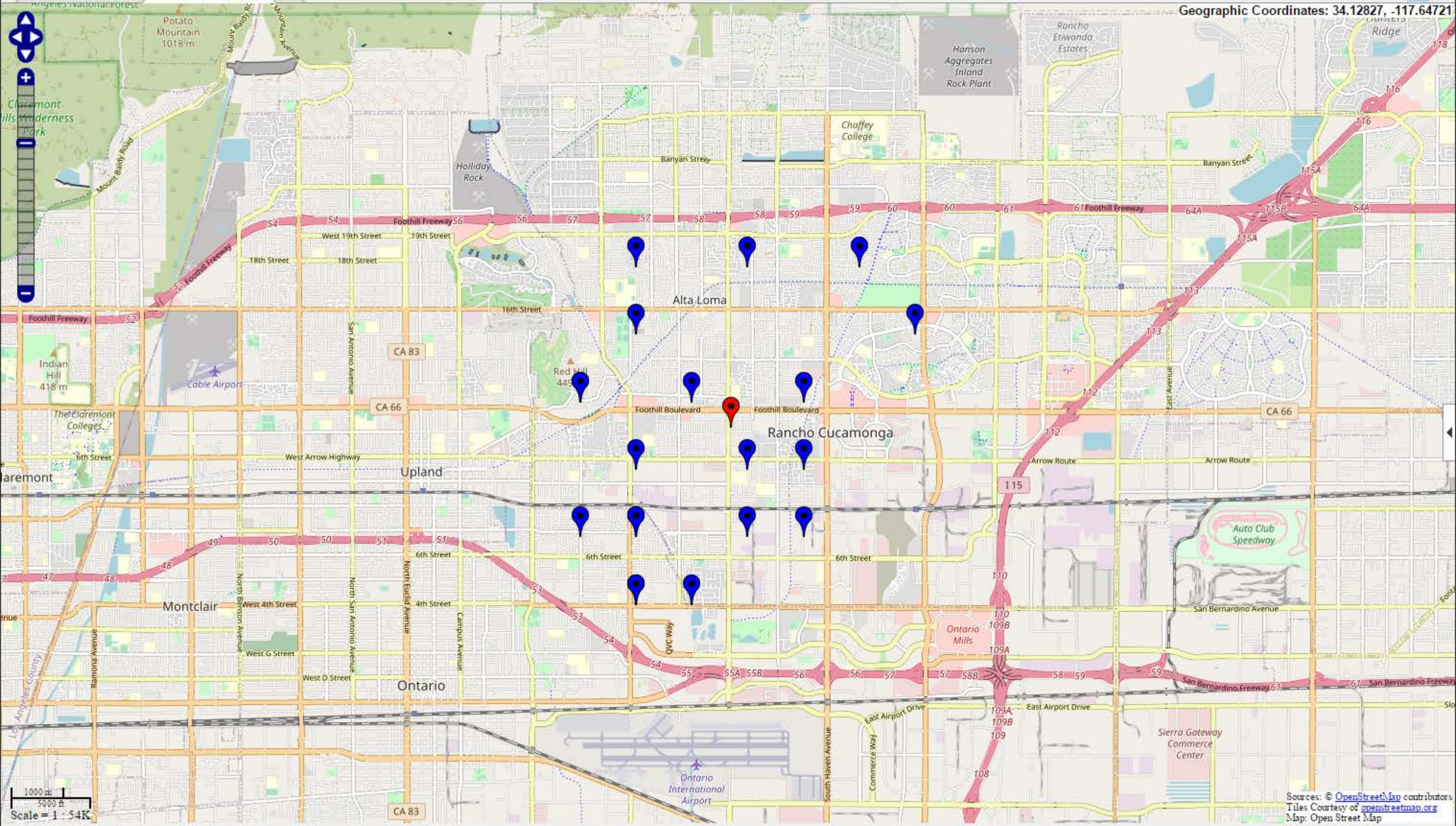
h1 = geoint(house1x2, house1x1);
h2 = geoint(house2x2, house2x1);
h3 = geoint(house3x2, house3x1);
h4 = geoint(house4x2, house4x1);
h5 = geoint(house5x2, house5x1);
h6 = geoint(house6x2, house6x1);

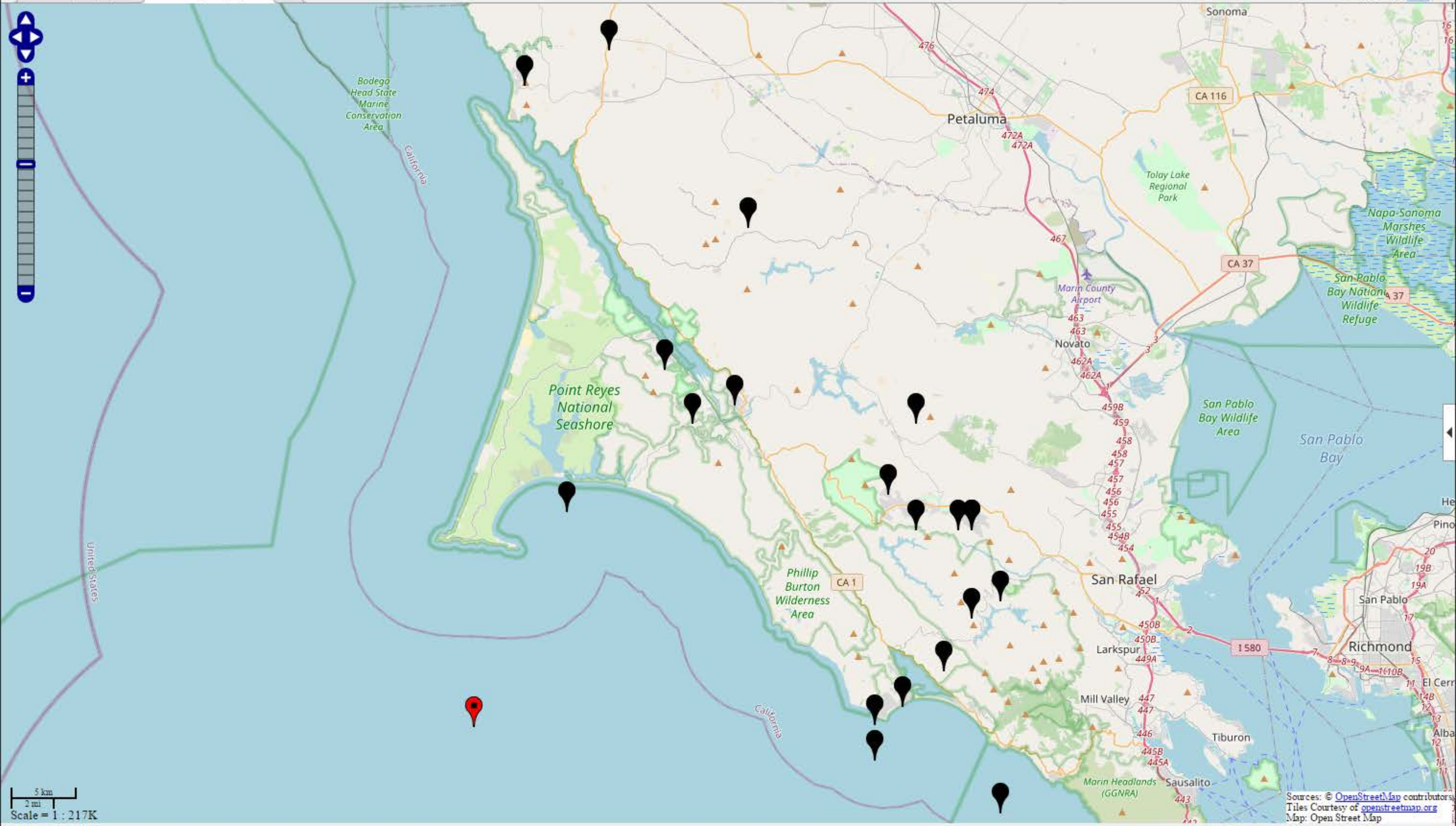
wmmarker(h1, 'Color', 'b');
wmmarker(h2, 'Color', 'k');
wmmarker(h3, 'Color', 'y');
wmmarker(h4, 'Color', 'm');
wmmarker(h5, 'Color', 'c');
wmmarker(h6, 'Color', [0.5 0.5 1]);
```

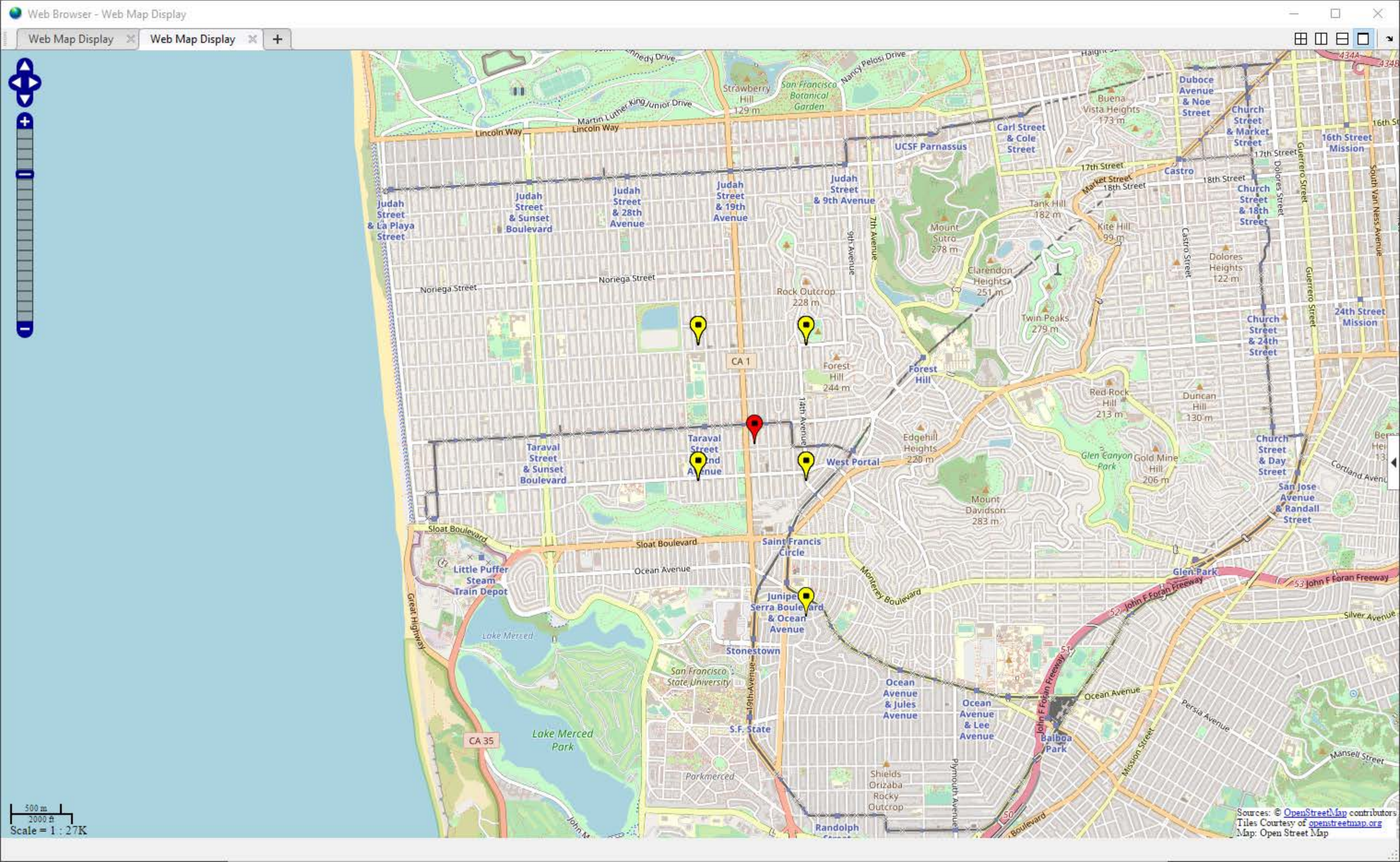


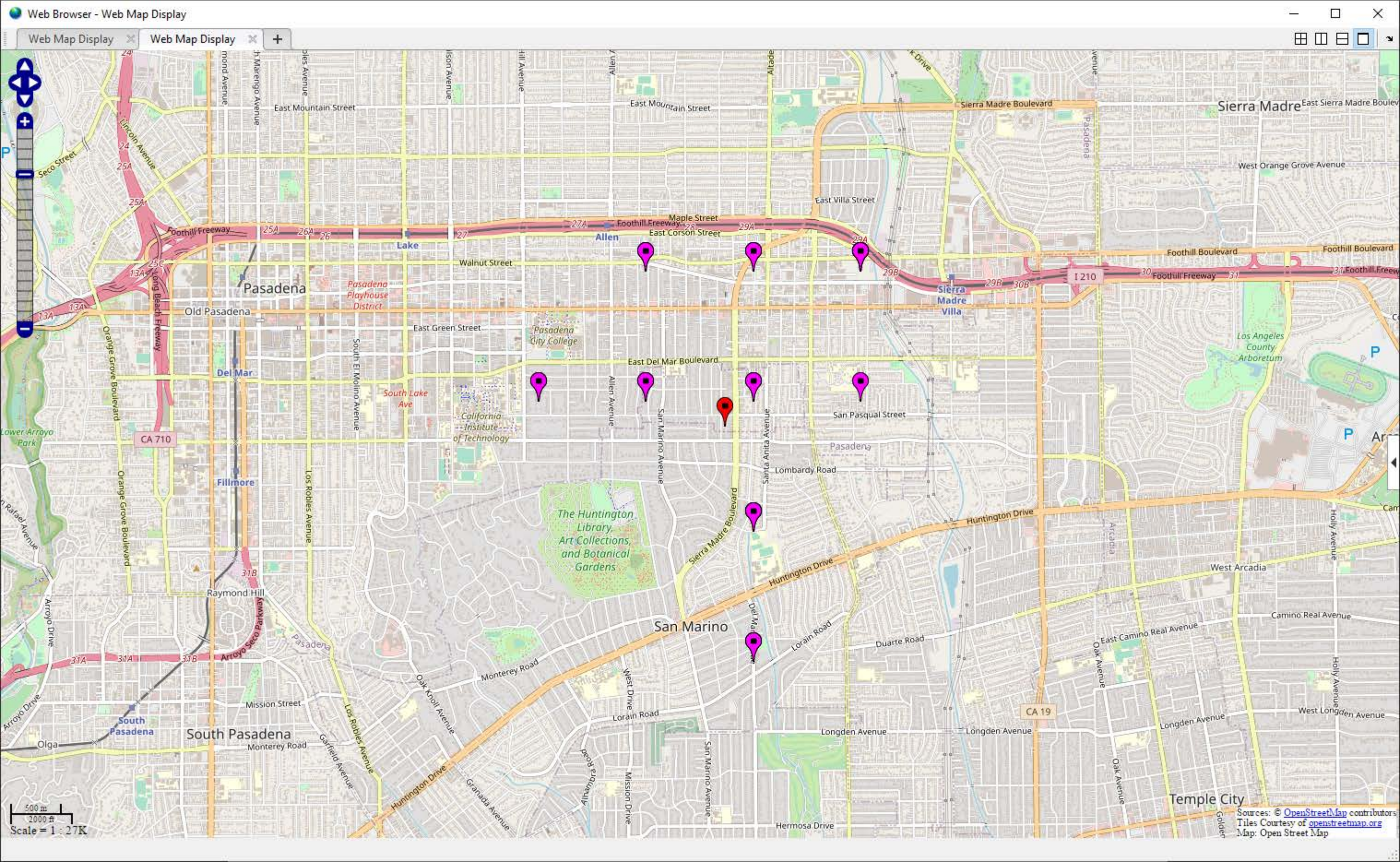


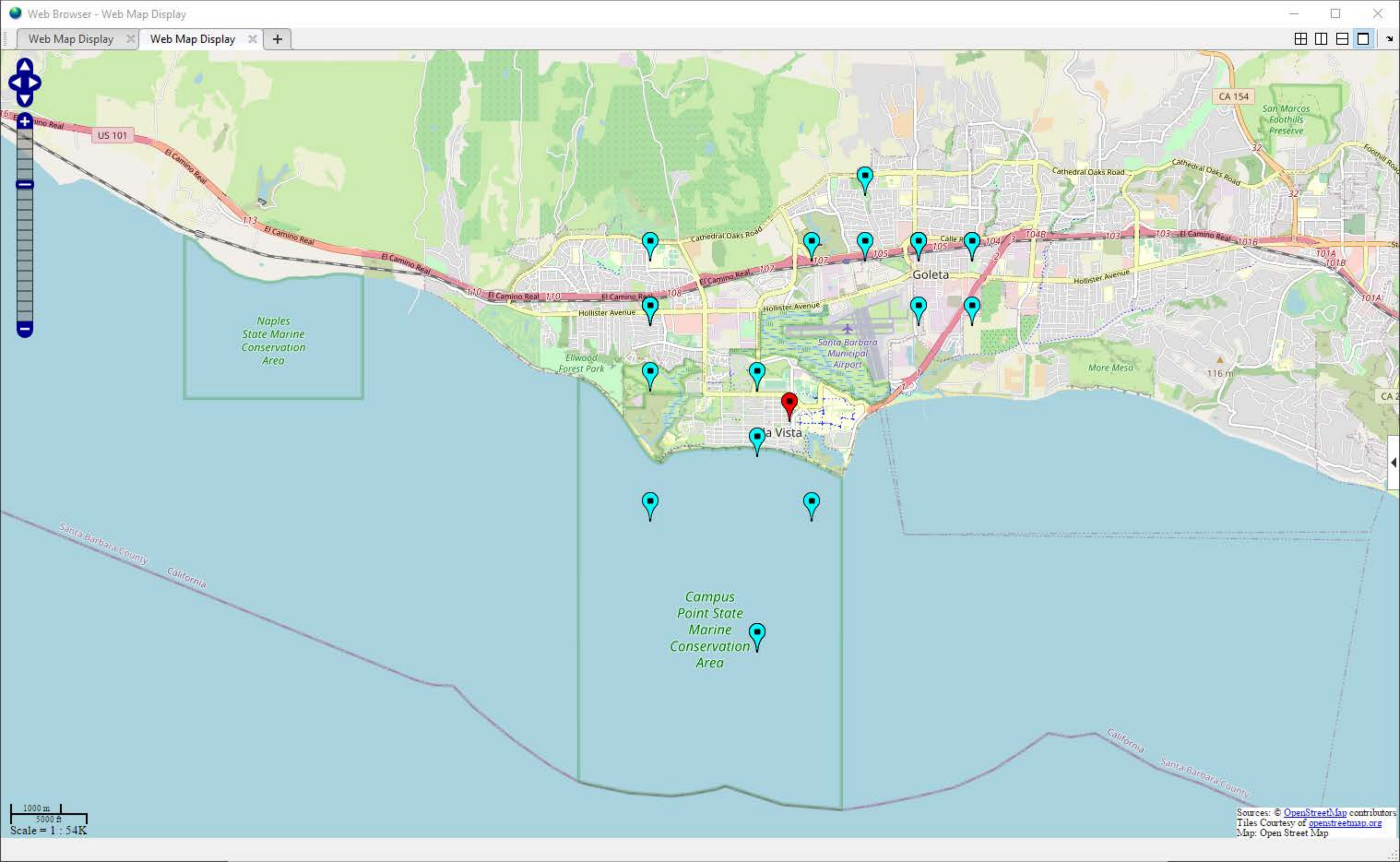
Published with MATLAB® R2018b











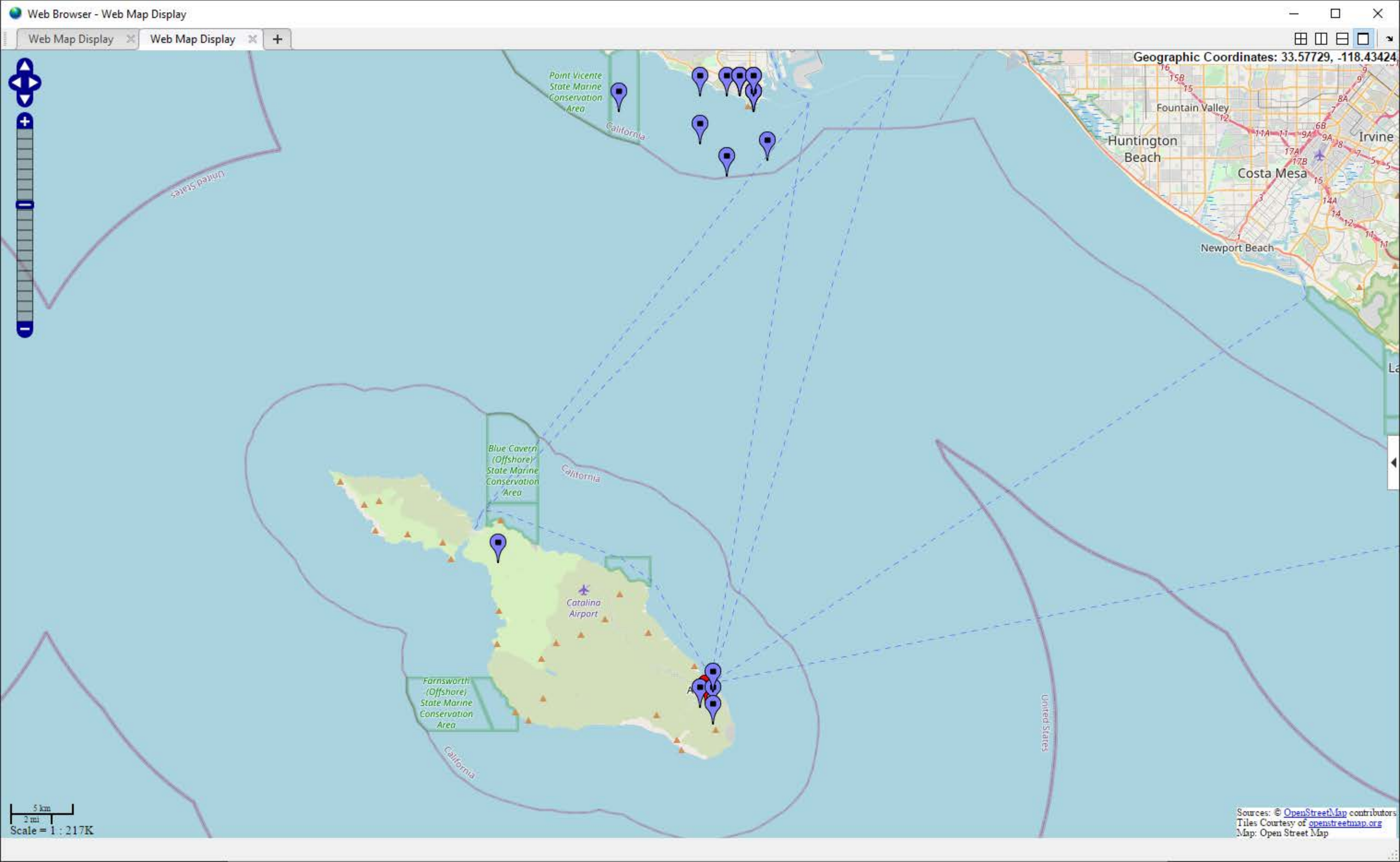


Table of Contents

BE606 HW3 Problem 2a	1
Part 2	1
Part 3 Questions	3

BE606 HW3 Problem 2a

```
clear all
close all
```

Part 2

```
A = readtable('housing.csv');
B = table2array(A(:,1:9));
x1 = B(:,1);
x2 = B(:,2);
X = [x1,x2];

figure;
hist3(X, 'CDataMode', 'auto', 'FaceColor', 'interp', 'Nbins', [100 100])
title('Housing Data')
xlabel('Longitude')
ylabel('Latitude')
% tic
% kmeans
f = figure;

for rr = 1:5
    [class,cent] = kmeans(X,7);
    subplot(2,5,rr)
    %     tic
    for kk = 1:7
        hold on
        plot(x1(class==kk),x2(class==kk),'.','DisplayName',...
            ['C',num2str(kk),' = 
',num2str(cent(kk,1))',' ',num2str(cent(kk,2))])
        legend('Location', 'northoutside')

    plot(cent(kk,1),cent(kk,2),'.','MarkerSize',15,'color','k', 'HandleVisibility','off')
    end
    %     toc

    hold off
    title(['(k = 7), Replicate #', num2str(rr)])
    xlabel('Longitude')
```

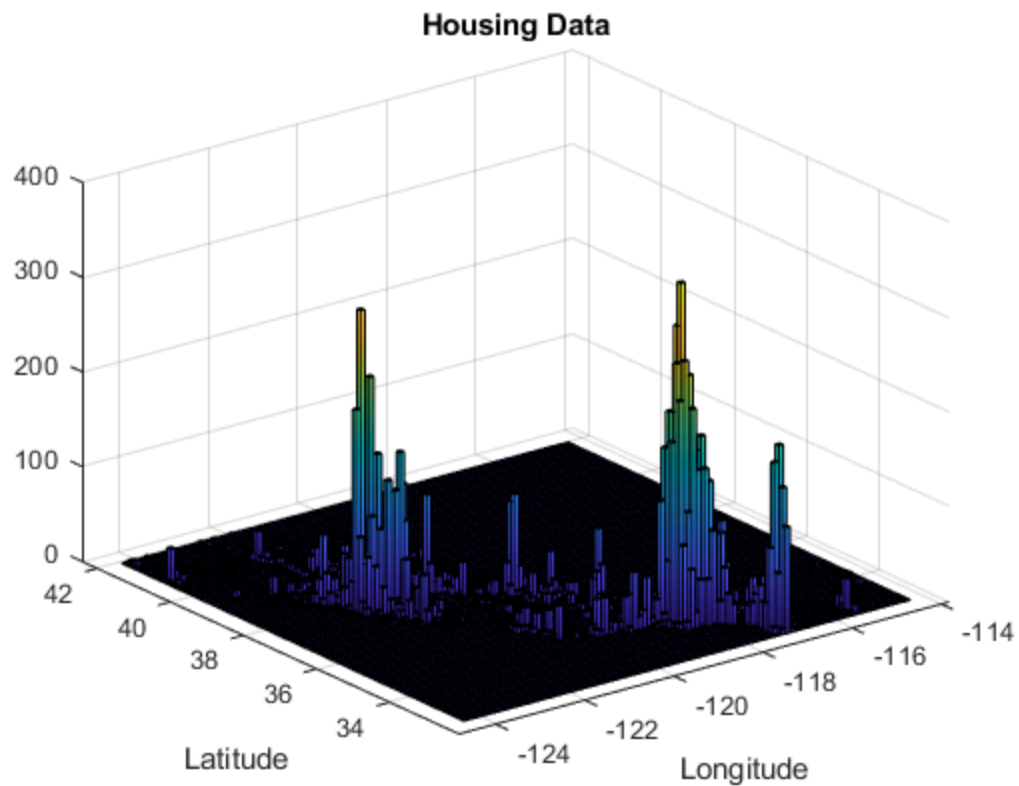
```

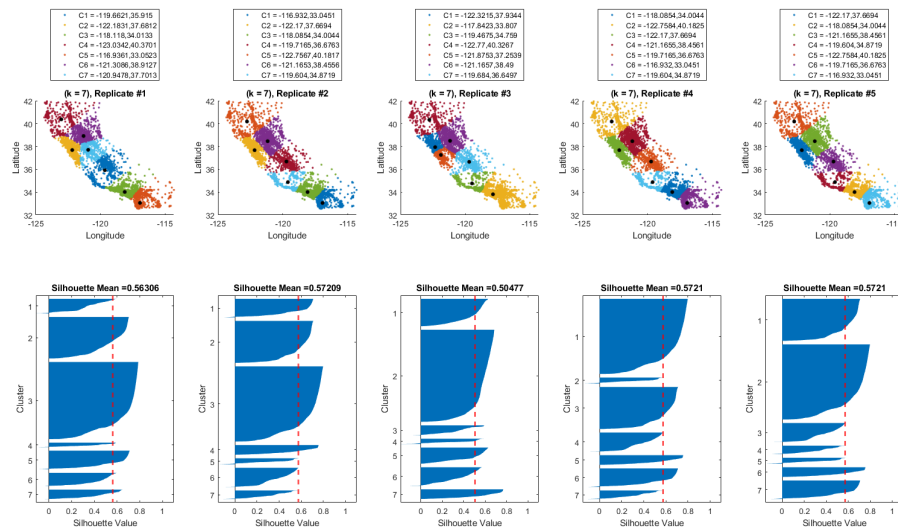
ylabel('Latitude')

subplot(2,5,rr+5)
sil = silhouette(X,class, 'Euclidean'); %save value for mean
%   toc
silhouette(X,class, 'Euclidean') %repeat to easily plot
%   toc
hold on
xline(mean(sil), 'r--', 'LineWidth', 2);
hold off

title(['Silhouette Mean =', num2str(mean(sil))])
end
% toc
f.WindowState = 'maximized'; %use this to maximize plot on screen
%though it does not work so well in the printout

```





Part 3 Questions

```

disp('Q1')
disp('Clusters 2 and 3 of replicate 2 contain the largest population
centers in California. Cluster 2 contains LA County, the largest
county in the US')
disp('and cluster 3 contains the bay area.')
disp('Q2')
disp('Yes the 7 clusters make sense, each cluter either contains
population centers, or the distance is minimized. Centroid 6 is
Northern California, where there are mainly national forests and some
smaller cities/towns')
disp('Centroid 2 contains LA County, largest population center in the
state')
disp('Centroid 3 contains the Bay area and its most likely commuting
areas')
disp('Centroid 4 is essentially San Diego and its commuting regions,
as well as reservations.')
disp('Centroid 5 is mostly Yosemite and other forests in the
interior')
disp('Centroid 1 is similar to centroid 5, with the inclusion of
Sacramento')
disp('Q3')
disp('Between 2 and 3, there is a decrease in distance and essentially
a split of LA County, and an increase in the lower middle centroid.')
disp('Q4')
disp('The equation for silhouette coeff, uses max distances in its
denominator, and since the middle centroid increased in size, and
pushed two centroids close together, we see a reduction in overall
silhouette score.')
disp('Q5')
disp('I prefer replicate 2, as it still has a high silhouette score,
and pretty accurately depicts the Bay Area, LA County, San Diego

```

as well as the national forests/parks. There should be a few large clusters, since there are higher population densities in certain regions.')

Q1

Clusters 2 and 3 of replicate 2 contain the largest population centers in California. Cluster 2 contains LA County, the largest county in the US and cluster 3 contains the bay area.

Q2

Yes the 7 clusters make sense, each cluster either contains population centers, or the distance is minimized. Centroid 6 is Northern California, where there are mainly national forests and some smaller cities/towns

Centroid 2 contains LA County, largest population center in the state

Centroid 3 contains the Bay area and its most likely commuting areas

Centroid 4 is essentially San Diego and its commuting regions, as well as reservations.

Centroid 5 is mostly Yosemite and other forests in the interior

Centroid 1 is similar to centroid 5, with the inclusion of Sacramento

Q3

Between 2 and 3, there is a decrease in distance and essentially a split of LA County, and an increase in the lower middle centroid.

Q4

The equation for silhouette coeff, uses max distances in its denominator, and since the middle centroid increased in size, and pushed two centroids close together, we see a reduction in overall silhouette score.

Q5

I prefer replicate 2, as it still has a high silhouette score, and pretty accurately depicts the Bay Area, LA County, San Diego as well as the national forests/parks. There should be a few large clusters, since there are higher population densities in certain regions.

Published with MATLAB® R2018b

Table of Contents

BE606 HW3 Problem 2b	1
Part 2	1
Part 3 Questions	2

BE606 HW3 Problem 2b

```
clear all
close all
```

Part 2

```
A = readtable('housing.csv');
B = table2array(A(:,1:9));
x1 = B(:,1);
x2 = B(:,2);
X = [x1,x2];

f = figure;
for kk = 4:1:9
    [class,cent] = kmeans(X,kk,'Replicates',100);
    subplot(2,6,kk-3)

    for jj = 1:kk
        hold on

        plot(x1(class==jj),x2(class==jj),'.','DisplayName',...
            ['C',num2str(jj),' = ',num2str(cent(jj,1))',' ',num2str(cent(jj,2))])
        legend('Location','northoutside')

    plot(cent(jj,1),cent(jj,2),'.','MarkerSize',15,'color','k','HandleVisibility','off')

    end
    hold off

    title(['k =', num2str(kk)])
    xlabel('Longitude')
    ylabel('Latitude')

    subplot(2,6,kk+3)
    sil = silhouette(X,class,'Euclidean'); %save value for mean

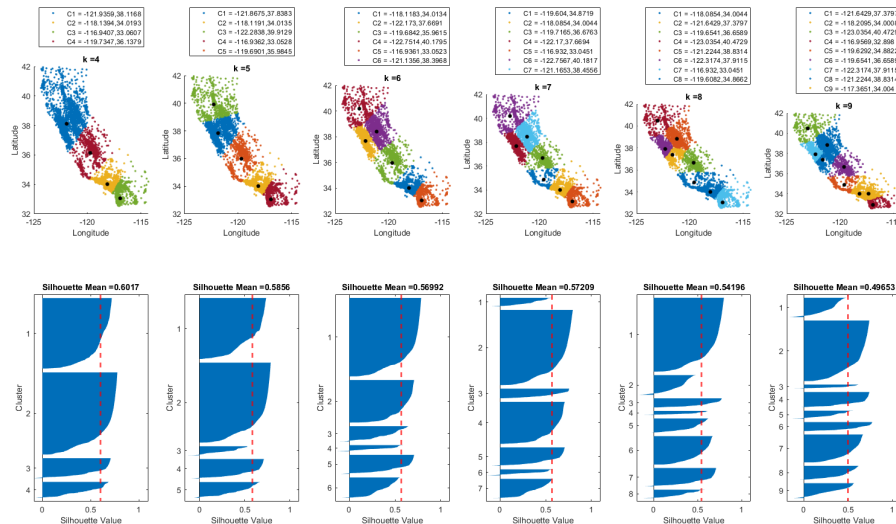
    silhouette(X,class,'Euclidean') %repeat to easily plot

    hold on
```

```

xline(mean(sil), 'r--', 'LineWidth', 2);
hold off
title(['Silhouette Mean =', num2str(mean(sil))])
end
f.WindowState = 'maximized';

```



Part 3 Questions

```

disp('Q1')
disp('The two large clusters contain where the majority of the
population lives. One contains LA County and its surroundings, and
the other contains nearly a quarter of California.')
disp('Q2')
disp('In k=5, there is a marked improvement as the large northern
California cluster can be split in two, allowing for more appropriate
geographical classification. San Francisco is now in its own
cluster.')
disp('Q3')
disp('Yes, the silhouette score did not decrease much, and now each
population center in CA is more accurately described. Cluster size is
also not as drastically large.')
disp('Q4')
disp('After k=7 the silhouette score begins to decrease. Though there
are more clusters, sectioning off cities and communities possibly
more effectively, we are beginning to generate too many clusters.
Realistically the two best were k=6/7 considering the silhouette
mean is relatively close, and the map intuitively maps the major
population centers.')

```

Q1

The two large clusters contain where the majority of the population lives. One contains LA County and its surroundings, and the other contains nearly a quarter of California.

Q2

In $k=5$, there is a marked improvement as the large northern California cluster can be split in two, allowing for more appropriate geographical classification. San Francisco is now in its own cluster.

Q3

Yes, the silhouette score did not decrease much, and now each population center in CA is more accurately described. Cluster size is also not as drastically large.

Q4

After $k=7$ the silhouette score begins to decrease. Though there are more clusters, sectioning off cities and communities possibly more effectively, we are beginning to generate too many clusters. Realistically the two best were $k=6/7$ considering the silhouette mean is relatively close, and the map intuitively maps the major population centers.

Published with MATLAB® R2018b

Table of Contents

BE606 HW3 Problem 2c	1
Part 1	1
Part 2	5
Part 3	9

BE606 HW3 Problem 2c

```
clear all
close all
```

Part 1

```
A = double(imread('default_rgb_reference.tif'));

red = A(:,:,1);
green = A(:,:,2);
blue = A(:,:,3);

figure;
plot3(red,green,blue, 'k.')
grid on
title('Raw Scatter Plot of Intensities')

xlabel('red intensities')
ylabel('green intensities')
zlabel('blue intensities')

X = [red(:), green(:), blue(:)];

[class,cent] = kmeans(X,3,'Replicates',10);

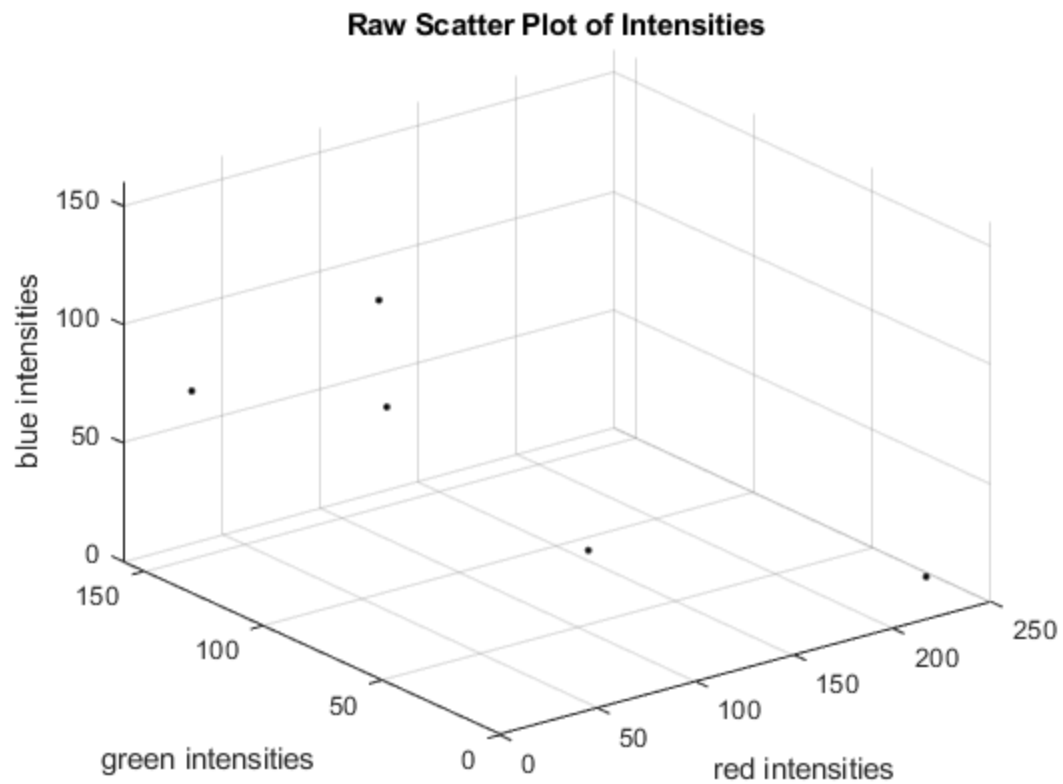
figure;

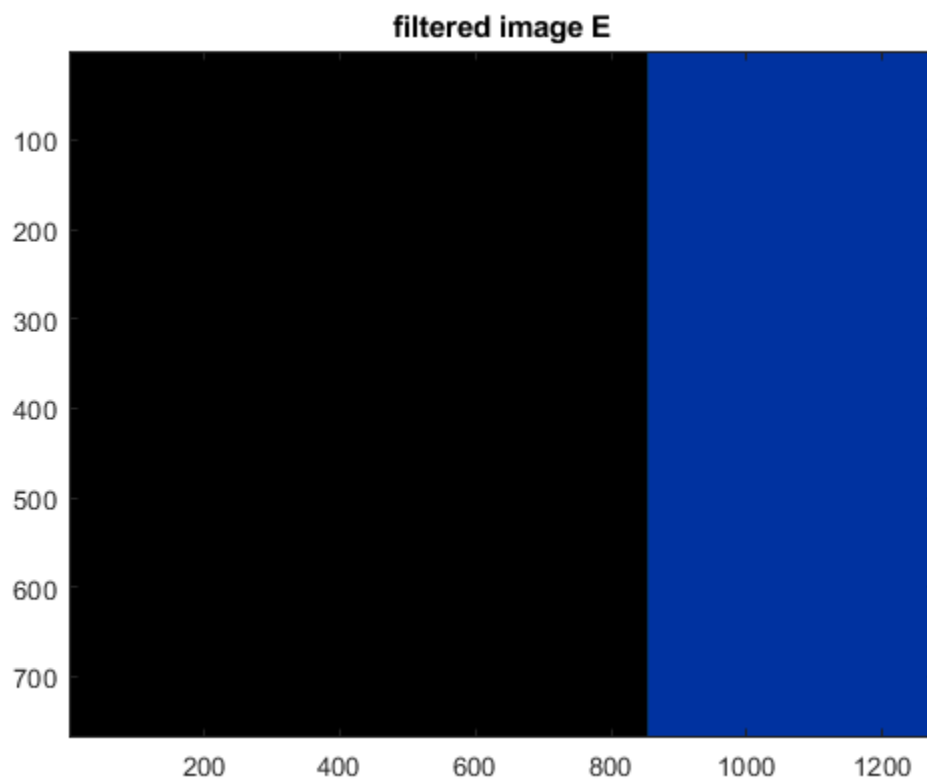
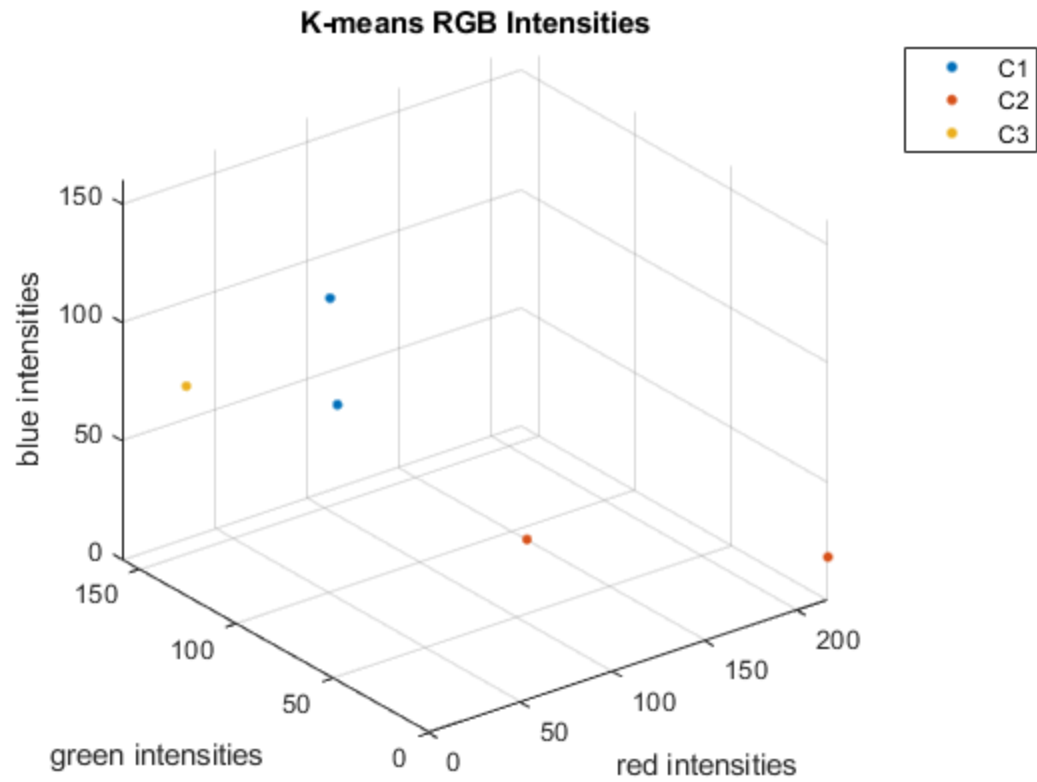
for i = 1:3
    cl = i == class;
    plot3(red(cl),green(cl),blue(cl),'.','MarkerSize',12)
    hold on
end
grid on
legend('C1','C2','C3')
title('K-means RGB Intensities')
xlabel('red intensities')
ylabel('green intensities')
zlabel('blue intensities')
```

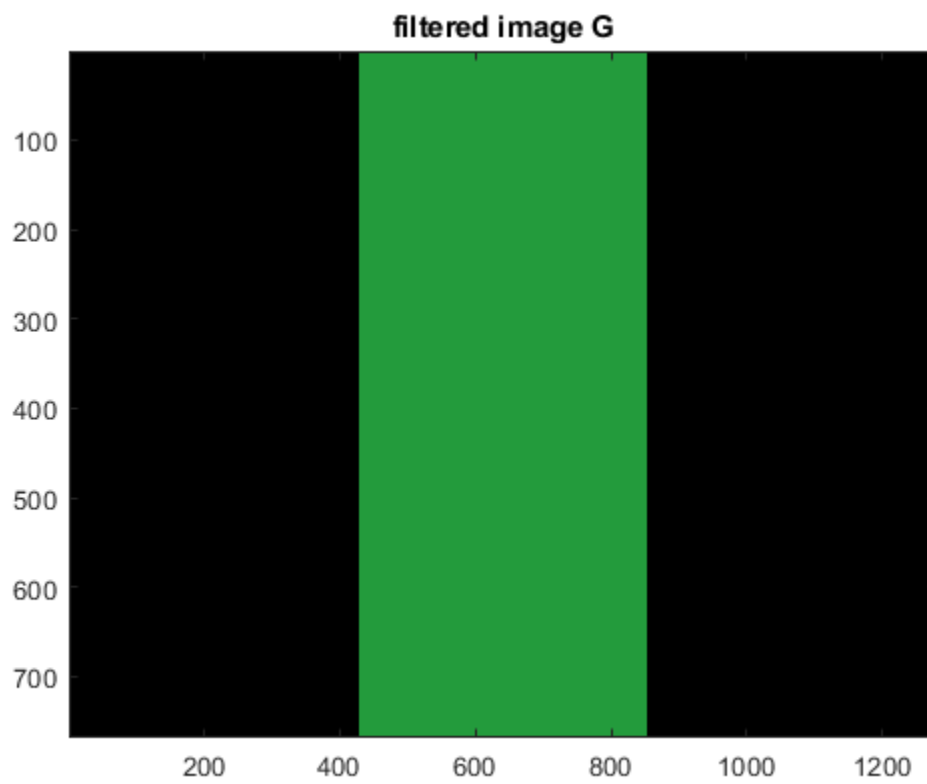
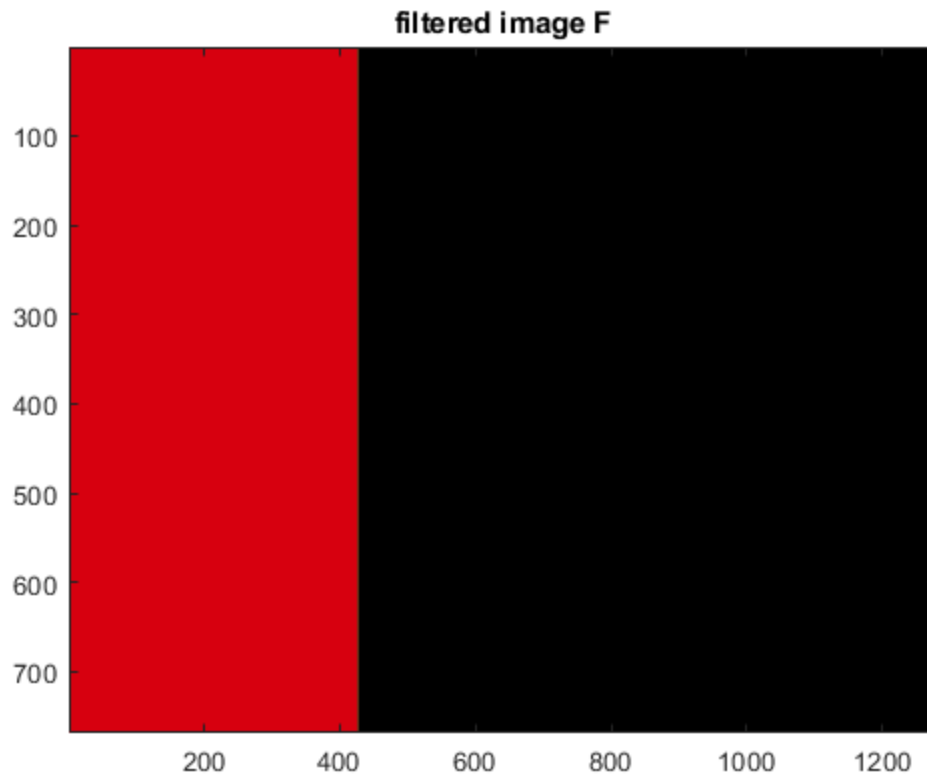
```
E = NaN*ones(size(X));  
E(1==class,:) = X(1==class,:);  
E = uint8(reshape(E,size(A)));  
figure;  
image(E)  
title('filtered image E')
```

```
F = NaN*ones(size(X));  
F(2==class,:) = X(2==class,:);  
F = uint8(reshape(F,size(A)));  
figure;  
image(F)  
title('filtered image F')
```

```
G = NaN*ones(size(X));  
G(3==class,:) = X(3==class,:);  
G = uint8(reshape(G,size(A)));  
figure;  
image(G)  
title('filtered image G')
```







Part 2

```
A = double(imread('confocal_image01.tif'));

red = A(:,:,1);
green = A(:,:,2);
blue = A(:,:,3);

X = [red(:), green(:), blue(:)];
%Using 4 centroids intuitively makes sense here--we have R,G,B and
  Black
%colors in the image
[class,cent] = kmeans(X,4,'Replicates',50);

figure;

for i = 1:4
    cl = i == class;
    plot3(red(cl),green(cl),blue(cl),'.','MarkerSize',12)
    hold on
end
legend('C1','C2','C3','C4')
title('K-means RGB Intensities of confocal w/4 Clusters')
xlabel('red intensities')
ylabel('green intensities')
zlabel('blue intensities')

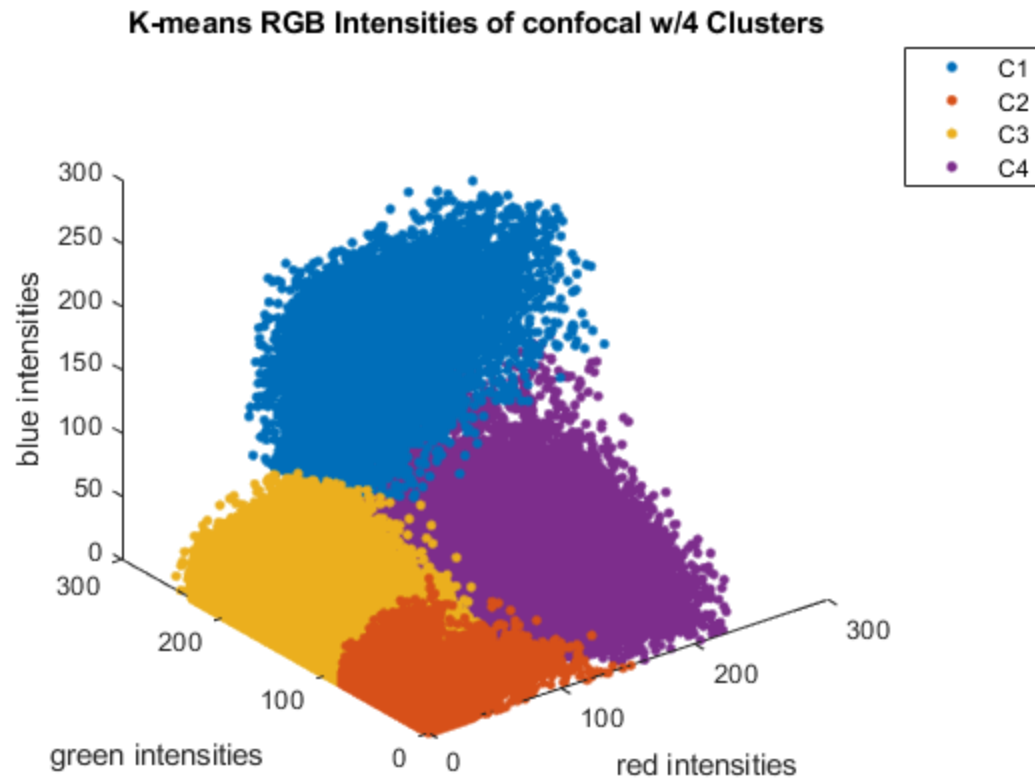
E = NaN*ones(size(X));
E(1==class,:) = X(1==class,:);
E = uint8(reshape(E,size(A)));
figure;
image(E)
title('Cluster 1')

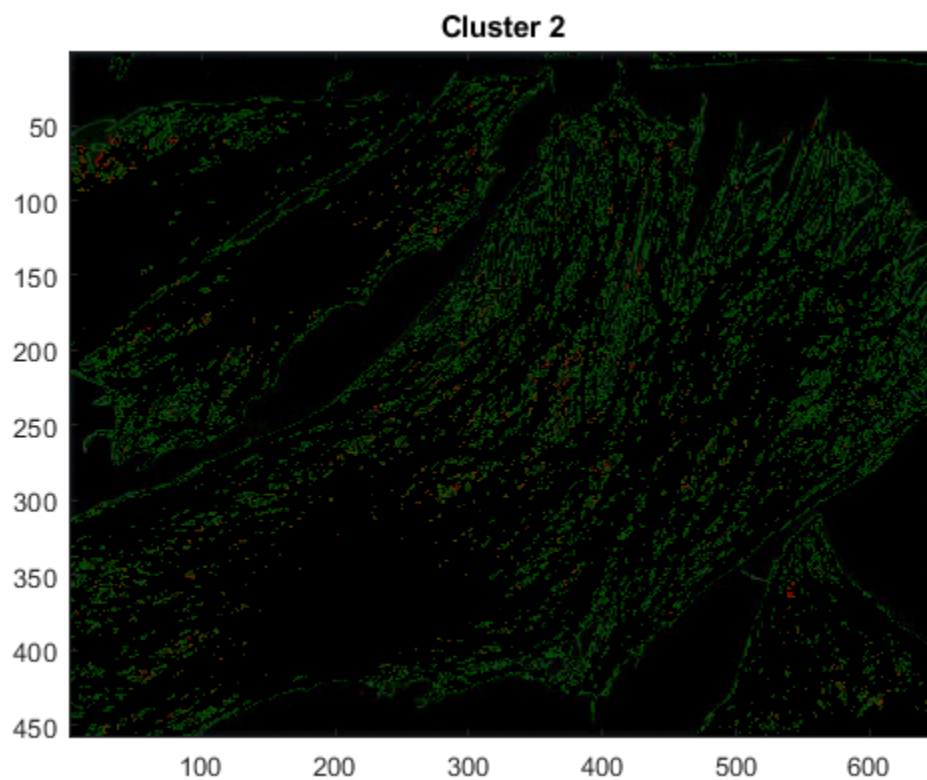
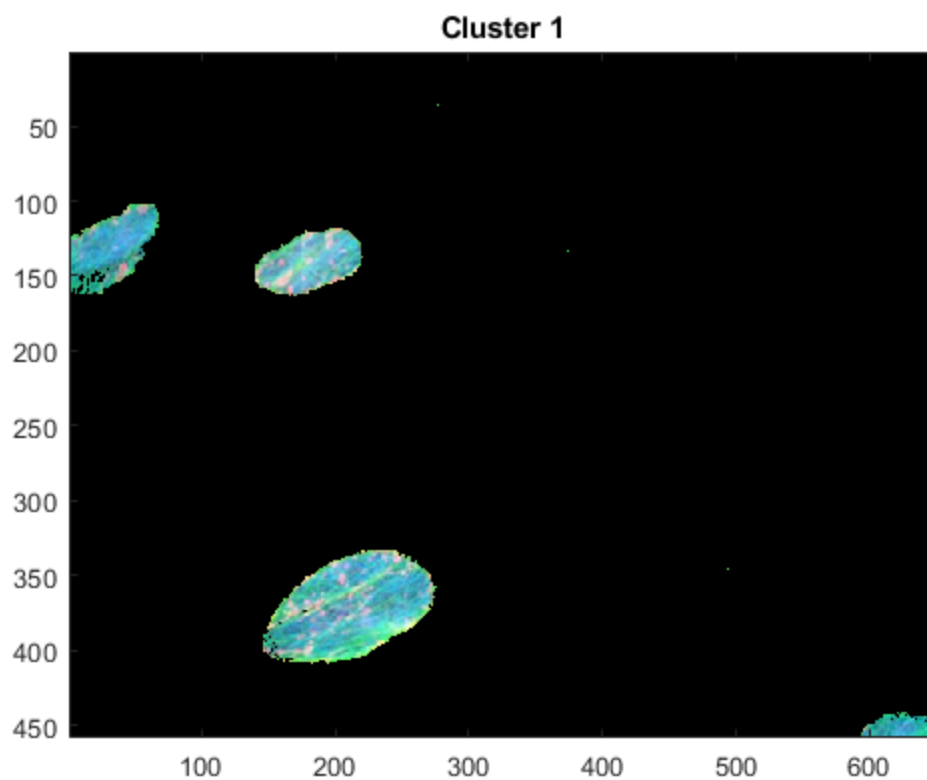
F = NaN*ones(size(X));
F(2==class,:) = X(2==class,:);
F = uint8(reshape(F,size(A)));
figure;
image(F)
title('Cluster 2')

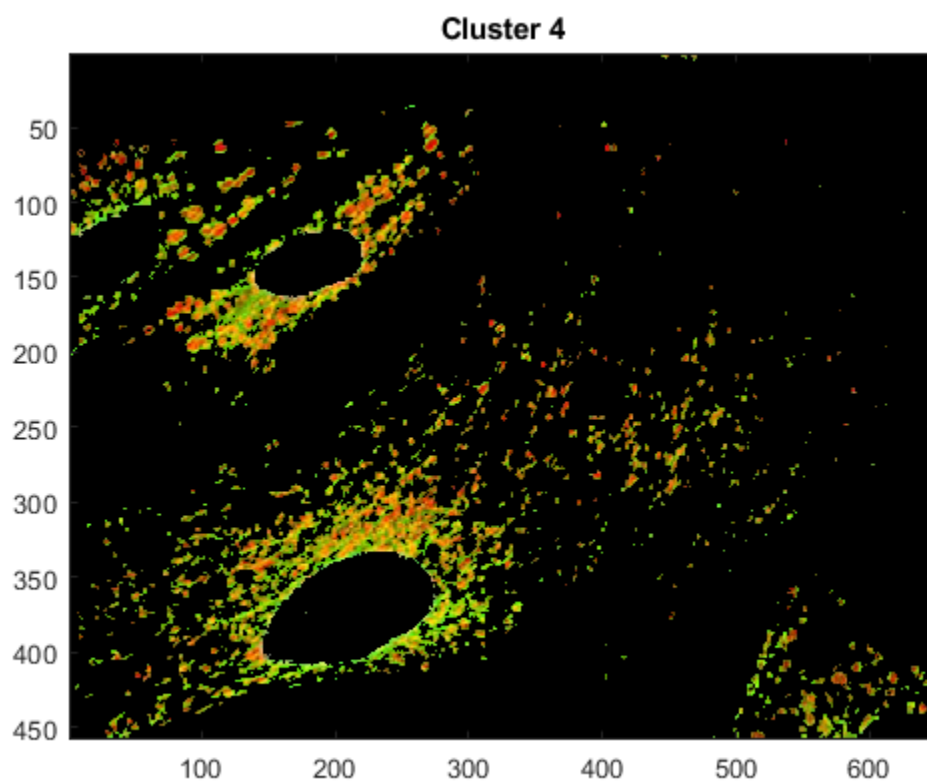
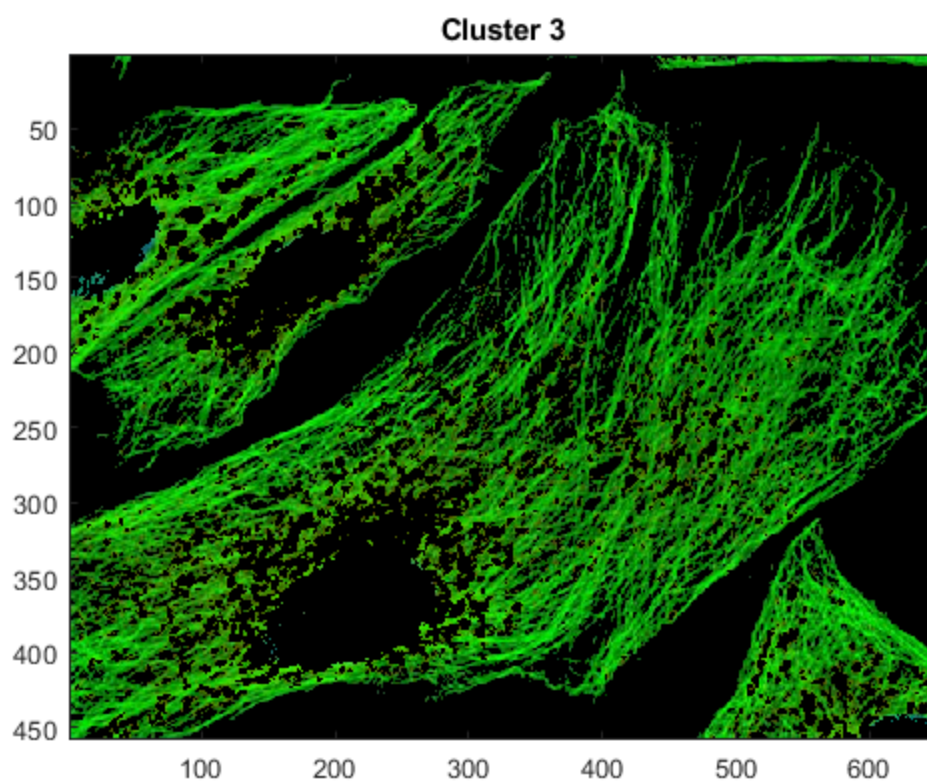
G = NaN*ones(size(X));
G(3==class,:) = X(3==class,:);
G = uint8(reshape(G,size(A)));
figure;
image(G)
title('Cluster 3')

H = NaN*ones(size(X));
H(4==class,:) = X(4==class,:);
```

```
H = uint8(reshape(H,size(A)));  
figure;  
image(H)  
title('Cluster 4')
```







Part 3

```
A = double(imread('Bacteria_image01.tif'));

red = A(:,:,1);
green = A(:,:,2);
blue = A(:,:,3);

%because we're essentially looking for 3 classes (red, y/g and
    background)
%k = 3

X = [red(:), green(:), blue(:)];

[class,cent] = kmeans(X,3,'Replicates',50);

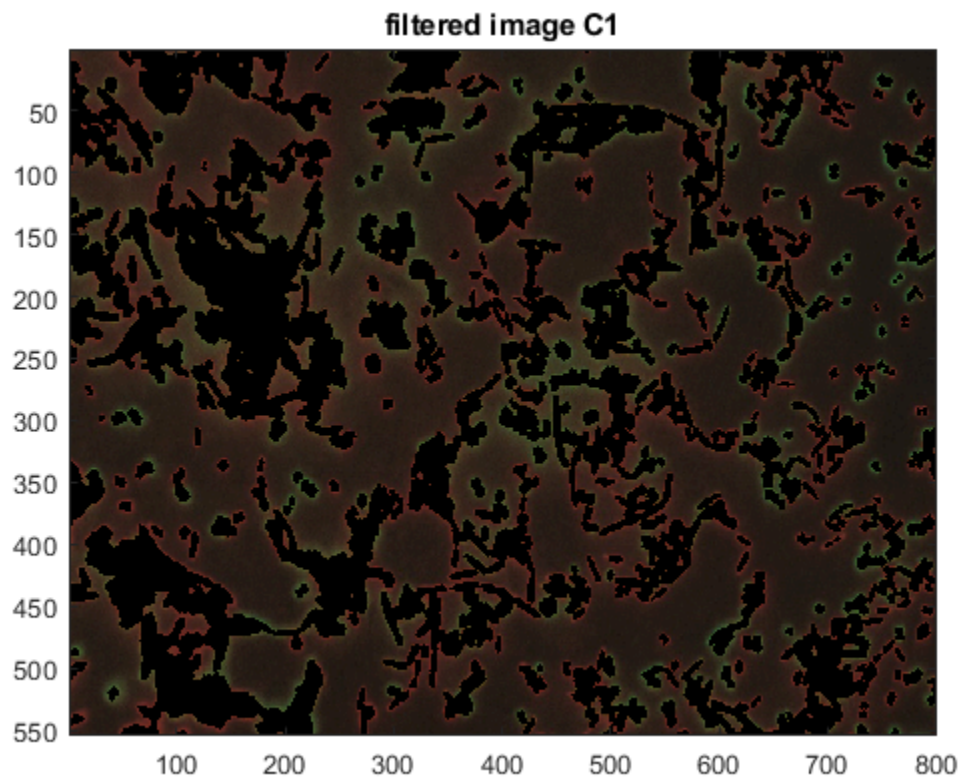
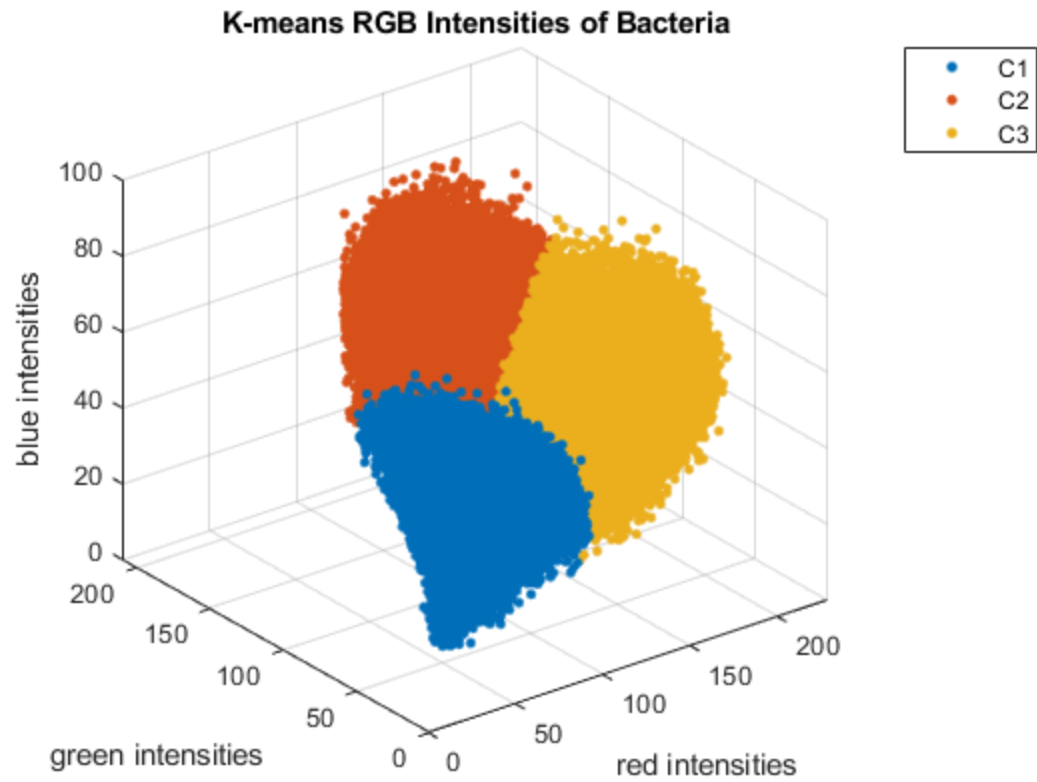
figure;

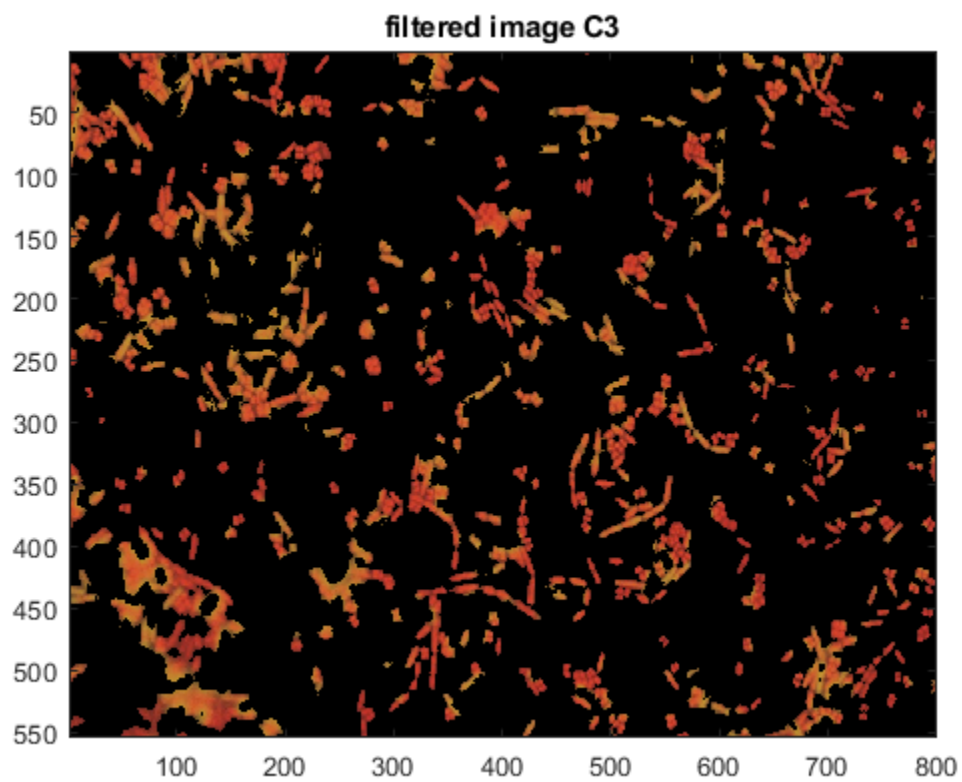
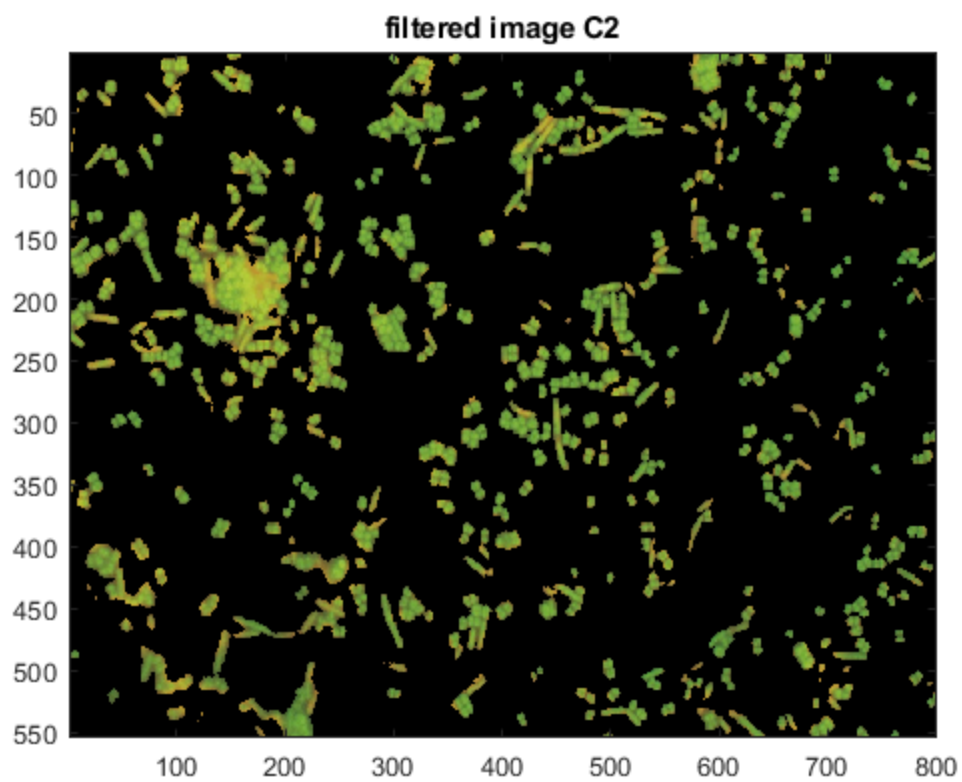
for i = 1:3
    cl = i == class;
    plot3(red(cl),green(cl),blue(cl),'.','MarkerSize',12)
    hold on
end
grid on
legend('C1','C2','C3')
title('K-means RGB Intensities of Bacteria')
xlabel('red intensities')
ylabel('green intensities')
zlabel('blue intensities')

E = NaN*ones(size(X));
E(1==class,:) = X(1==class,:);
E = uint8(reshape(E,size(A)));
figure;
image(E)
title('filtered image C1')

F = NaN*ones(size(X));
F(2==class,:) = X(2==class,:);
F = uint8(reshape(F,size(A)));
figure;
image(F)
title('filtered image C2')

G = NaN*ones(size(X));
G(3==class,:) = X(3==class,:);
G = uint8(reshape(G,size(A)));
figure;
image(G)
title('filtered image C3')
```





Published with MATLAB® R2018b

HW3_P3_Jha_Vibhav

April 27, 2021

0.1 HW3 Problem 3

0.2 Name: Vibhav Jha

0.2.1 Imports

```
[149]: import struct
import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
import sklearn
from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay
import random
```

0.2.2 1. Loading the data

```
[3]: # training images
with open('train-images-idx3-ubyte', 'rb') as f:
    magic, size = struct.unpack(">II", f.read(8))
    nrows, ncols = struct.unpack(">II", f.read(8))
    train_data = np.fromfile(f, dtype=np.dtype(np.uint8).newbyteorder('>'))
    train_data = train_data.reshape((size, nrows, ncols))

# training labels
with open('train-labels-idx1-ubyte', 'rb') as f:
    magic, size = struct.unpack(">II", f.read(8))
    train_labels = np.fromfile(f, dtype=np.dtype(np.uint8).newbyteorder('>'))

# test images
with open('t10k-images-idx3-ubyte', 'rb') as f:
    magic, size = struct.unpack(">II", f.read(8))
    nrows, ncols = struct.unpack(">II", f.read(8))
    test_data = np.fromfile(f, dtype=np.dtype(np.uint8).newbyteorder('>'))
    test_data = test_data.reshape((size, nrows, ncols))

# test labels
with open('t10k-labels-idx1-ubyte', 'rb') as f:
    magic, size = struct.unpack(">II", f.read(8))
    test_labels = np.fromfile(f, dtype=np.dtype(np.uint8).newbyteorder('>'))
```

```
[5]: print('Train Data Shape', np.shape(train_data))

      print('Train Label Shape', np.shape(train_labels))

      print('Test Data Shape', np.shape(test_data))

      print('Test Label Shape', np.shape(test_labels))
```

Train Data Shape (60000, 28, 28)
 Train Label Shape (60000,)
 Test Data Shape (10000, 28, 28)
 Test Label Shape (10000,)

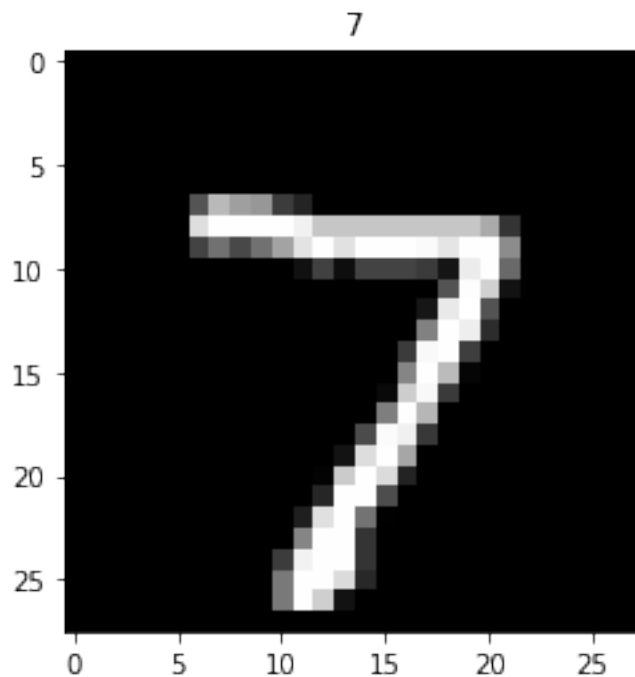
c. Image plots

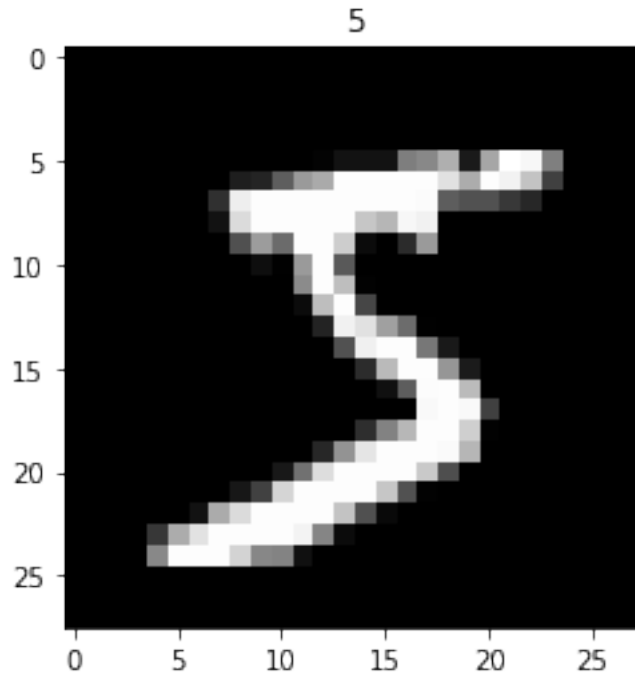
```
[10]: plt.figure(1)
      plt.imshow(test_data[0], cmap='gray')
      plt.title(test_labels[0])

      plt.figure(2)
      plt.imshow(train_data[0], cmap='gray')
      plt.title(train_labels[0])

      print('The labels and images match.')
```

The labels and images match.





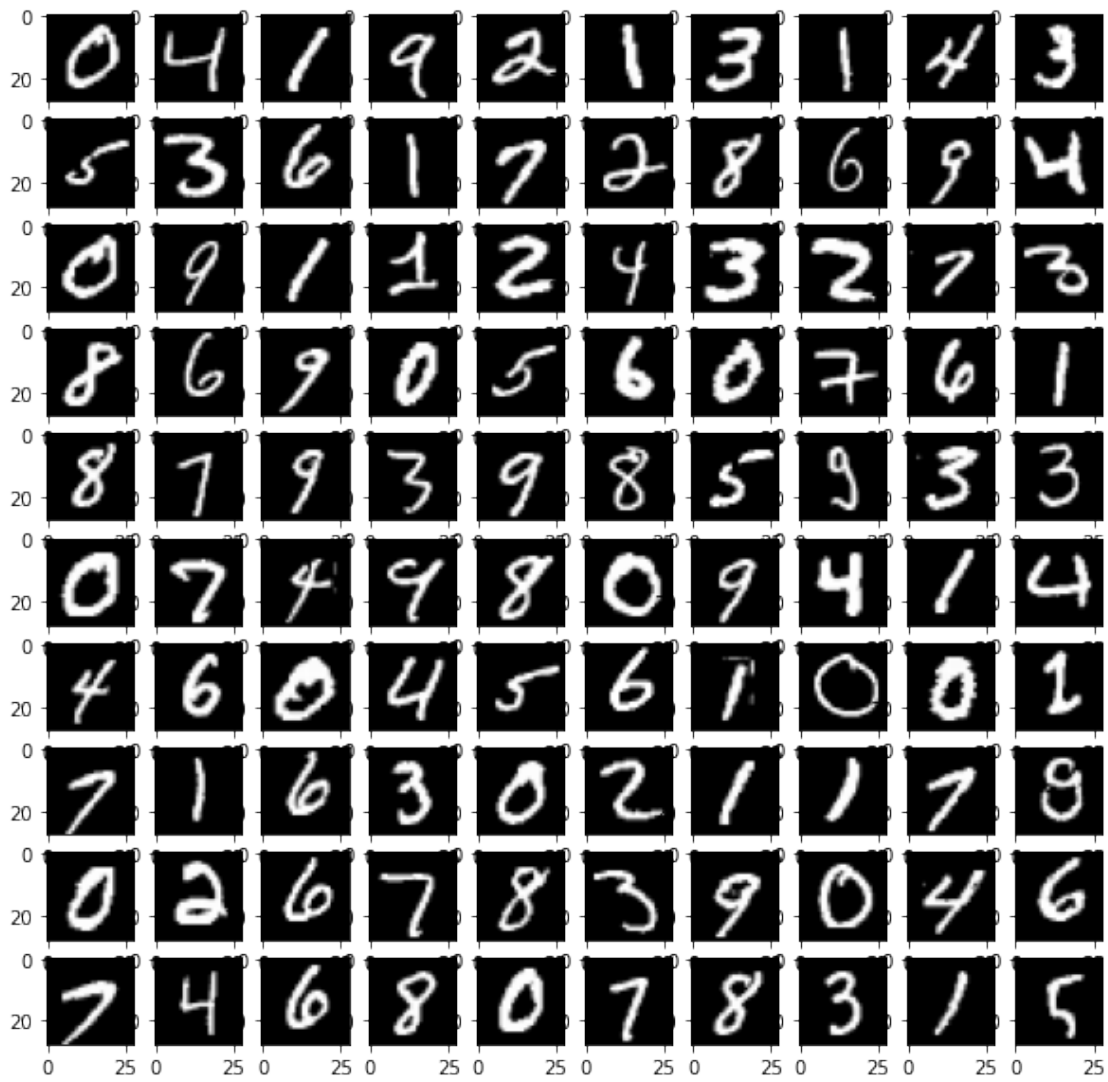
d. Image plot (10x10 grid)

```
[15]: plt.subplots(figsize=(10,10))
      for c in range(10):
          for r in range(10):
              a = r*10 + c + 1
              plt.subplot(10,10,a)
              plt.imshow(train_data[a], cmap = 'gray')
      plt.suptitle('Training Data')

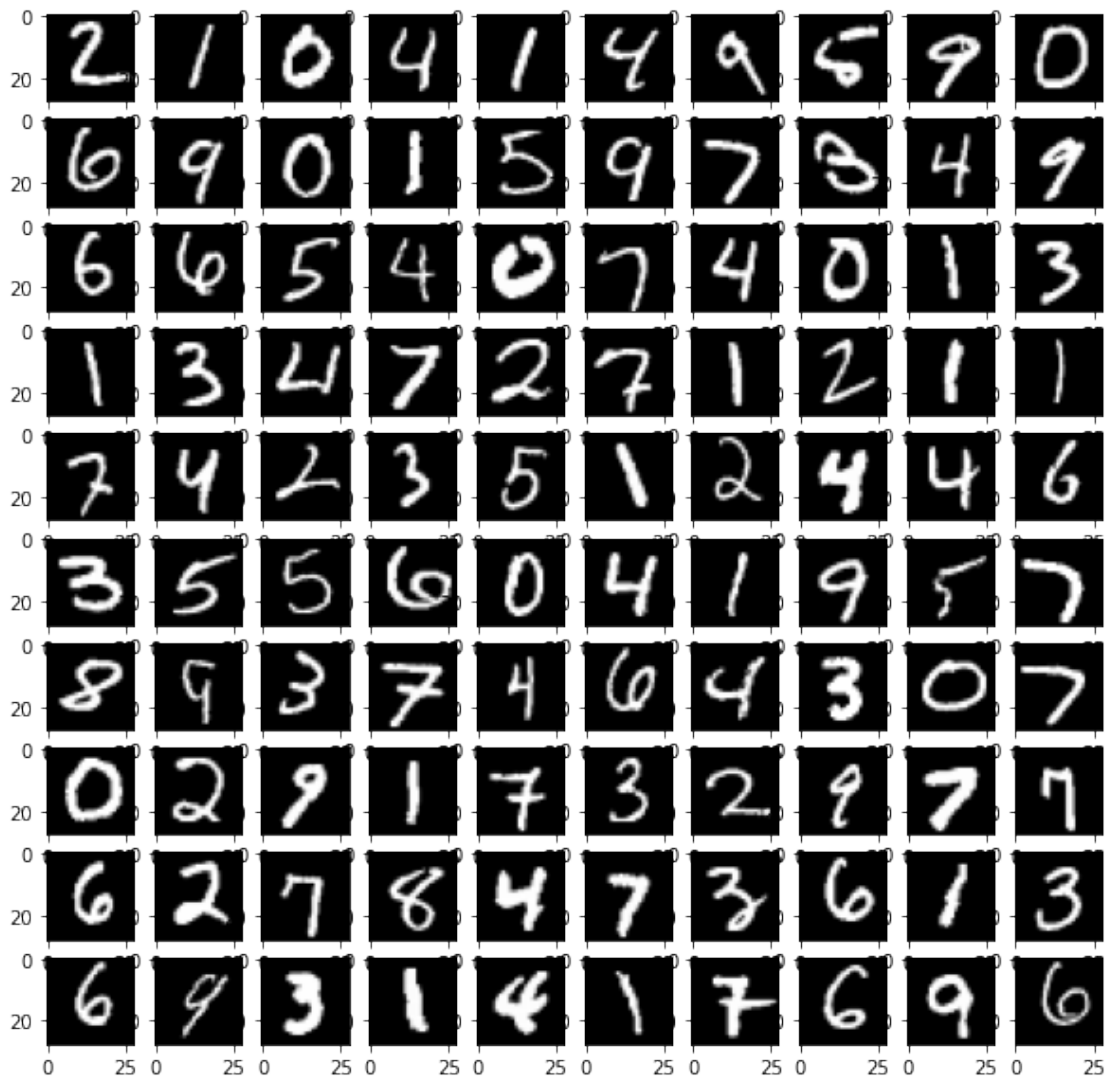
      plt.subplots(figsize=(10,10))
      for c in range(10):
          for r in range(10):
              a = r*10 + c + 1
              plt.subplot(10,10,a)
              plt.imshow(test_data[a], cmap = 'gray')
      plt.suptitle('Testing Data')
```

```
[15]: Text(0.5, 0.98, 'Testing Data')
```

Training Data



Testing Data



e. Digit frequency

```
[29]: trainlab100 = train_labels[:100]
testlab100 = test_labels[:100]
#a = np.where(trainlab100==0)
#print(a)
#np.size(a)

print('Occurences of 0 in the first 100 train labels: ', np.size(np.
→where(trainlab100==0)))
```

```

print('Occurences of 1 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==1)))
print('Occurences of 2 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==2)))
print('Occurences of 3 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==3)))
print('Occurences of 4 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==4)))
print('Occurences of 5 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==5)))
print('Occurences of 6 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==6)))
print('Occurences of 7 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==7)))
print('Occurences of 8 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==8)))
print('Occurences of 9 in the first 100 train labels: ', np.size(np.
    ↳where(trainlab100==9)))
print('')
print('Occurences of 0 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==0)))
print('Occurences of 1 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==1)))
print('Occurences of 2 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==2)))
print('Occurences of 3 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==3)))
print('Occurences of 4 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==4)))
print('Occurences of 5 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==5)))
print('Occurences of 6 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==6)))
print('Occurences of 7 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==7)))
print('Occurences of 8 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==8)))
print('Occurences of 9 in the first 100 test labels: ', np.size(np.
    ↳where(testlab100==9)))

```

```

Occurences of 0 in the first 100 train labels: 13
Occurences of 1 in the first 100 train labels: 14
Occurences of 2 in the first 100 train labels: 6
Occurences of 3 in the first 100 train labels: 11
Occurences of 4 in the first 100 train labels: 11
Occurences of 5 in the first 100 train labels: 5

```



```
Occurrences of 6 in the first 100 train labels: 11
Occurrences of 7 in the first 100 train labels: 10
Occurrences of 8 in the first 100 train labels: 8
Occurrences of 9 in the first 100 train labels: 11
```

```
Occurrences of 0 in the first 100 test labels: 8
Occurrences of 1 in the first 100 test labels: 14
Occurrences of 2 in the first 100 test labels: 8
Occurrences of 3 in the first 100 test labels: 11
Occurrences of 4 in the first 100 test labels: 14
Occurrences of 5 in the first 100 test labels: 7
Occurrences of 6 in the first 100 test labels: 10
Occurrences of 7 in the first 100 test labels: 15
Occurrences of 8 in the first 100 test labels: 2
Occurrences of 9 in the first 100 test labels: 11
```

0.2.3 2. Data prepartion

Normalization and reshaping

```
[296]: train_labels6 = train_labels[:6000]
train_data6 = train_data[:6000]
print('Occurrences of 0 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==0)))
print('Occurrences of 1 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==1)))
print('Occurrences of 2 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==2)))
print('Occurrences of 3 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==3)))
print('Occurrences of 4 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==4)))
print('Occurrences of 5 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==5)))
print('Occurrences of 6 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==6)))
print('Occurrences of 7 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==7)))
print('Occurrences of 8 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==8)))
print('Occurrences of 9 in the first 6000 train labels: ', np.size(np.
    ↳where(train_labels6==9)))

#scaler = sklearn.preprocessing.MinMaxScaler()
#train_norm = sklearn.preprocessing.MinMaxScaler(train_data6)
#train_norm = scaler.train_data6_
#np.shape(train_norm) this didn't work for some reason, so doing it manually_
    ↳using a for loop
```

```

#same story for preprocessing.normalize()

train_data_norm = np.zeros([0,784])
for i in train_data6: #general normalization formula
    train_data_norm = np.vstack((train_data_norm,((i - np.min(i)) / (np.max(i) -
    np.min((i))))).flatten()))

train_data_norm = train_data_norm.T #transpose to get ndims x nsamples
print('New Train Data Shape: ',np.shape(train_data_norm))

test_data_norm = np.zeros([0,784])
for ii in test_data:
    test_data_norm = np.vstack((test_data_norm,((ii - np.min(ii)) / (np.max(ii) -
    np.min((ii))))).flatten()))

test_data_norm = test_data_norm.T
print('New Test Data Shape: ',np.shape(test_data_norm))

```

```

Occurences of 0 in the first 6000 train labels: 592
Occurences of 1 in the first 6000 train labels: 671
Occurences of 2 in the first 6000 train labels: 581
Occurences of 3 in the first 6000 train labels: 608
Occurences of 4 in the first 6000 train labels: 623
Occurences of 5 in the first 6000 train labels: 514
Occurences of 6 in the first 6000 train labels: 608
Occurences of 7 in the first 6000 train labels: 651
Occurences of 8 in the first 6000 train labels: 551
Occurences of 9 in the first 6000 train labels: 601
New Train Data Shape: (784, 6000)
New Test Data Shape: (784, 10000)

```

One-hot encoding of labels

```

[297]: train_int = np.zeros([0,10])

for jj in range(6000):
    train_int = np.vstack((train_int, (np.arange(10) == train_labels[jj].
    astype(int))))
train_int = train_int.T

print('1-hot encoded Train Labels: ',np.shape(train_int))
print('Train', train_labels[0], ' ', train_int[:,0])

test_int = np.zeros([0,10])
for jj in range(10000):
    test_int = np.vstack((test_int, (np.arange(10) == test_labels[jj].
    astype(int))))
test_int = test_int.T

```

```
print('1-hot encoded Test Labels: ', np.shape(test_int))
print('Test ', test_labels[0], ' ', test_int[:,0])
```

```
1-hot encoded Train Labels: (10, 6000)
Train 5 [0. 0. 0. 0. 0. 1. 0. 0. 0. 0.]
1-hot encoded Test Labels: (10, 10000)
Test 7 [0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]
```

0.2.4 3. Neural Network

Computational graph

```
[62]: tf.reset_default_graph() #heavily adapted from Michelucci p.110-111 and recitatio
#784 as it is 28*28
learning_rate = tf.placeholder(tf.float64, shape=())
X = tf.placeholder(tf.float64, [784, None])
Y = tf.placeholder(tf.float64, [10, None])

#want 10 neurons, so 10 weights
weights = tf.Variable(tf.random_normal(shape = [10, 784], dtype=tf.float64,
→seed=12345))

bias = tf.Variable(tf.zeros([10,1], tf.float64))

out = tf.sigmoid(tf.matmul(weights, X) + bias)

#from Michelucci p108 with the inclusion of the no nan from p77
cost = - tf.reduce_mean(tf.math.multiply_no_nan(Y,tf.log(out)) + tf.math.
→multiply_no_nan((1-Y),tf.log(1-out)), axis=1 )

optimizer = tf.train.GradientDescentOptimizer(learning_rate).minimize(cost)

init = tf.global_variables_initializer()

saver = tf.train.Saver()
```

Training function

```
[114]: def mnist_trainer(epochs, trainx, trainlabels, lrate, costf, optimizerf):
    sess = tf.Session()
    sess.run(init)

    cost_history = np.empty(shape=[10], dtype = float)
    for ee in range(epochs):
        [_, cost_] = sess.run([optimizer, cost], feed_dict = {X: trainx, Y:
→trainlabels, learning_rate:lrate})

        cost_history = np.append(cost_history, np.mean(cost_))
```

```

        if (ee%500 == 0):
            print('Cost = ', np.mean(cost_), 'at epoch ', ee)
            save_mod = saver.save(sess, 'trained_model_' + str(lrate) + '_' +
→str(epochs) + '.ckpt')
            return sess, cost_history, save_mod

s1, chist1, saved1 = mnist_trainer(epochs = 10001,
                                   trainx = train_data_norm,
                                   trainlabels = train_int,
                                   lrate = 0.05,
                                   costf = cost,
                                   optimizerf = optimizer)
s1.close()

s2, chist2, saved2 = mnist_trainer(epochs = 50001,
                                   trainx = train_data_norm,
                                   trainlabels = train_int,
                                   lrate = 0.05,
                                   costf = cost,
                                   optimizerf = optimizer)
s2.close()

s3, chist3, saved3 = mnist_trainer(epochs = 50001,
                                   trainx = train_data_norm,
                                   trainlabels = train_int,
                                   lrate = 0.01,
                                   costf = cost,
                                   optimizerf = optimizer)
s3.close()

```

```

Cost = 2.1182936721476553 at epoch 0
Cost = 0.27998292388249524 at epoch 500
Cost = 0.20307103433352286 at epoch 1000
Cost = 0.17104236086479957 at epoch 1500
Cost = 0.1523633175459273 at epoch 2000
Cost = 0.1397022359518514 at epoch 2500
Cost = 0.13033701063250494 at epoch 3000
Cost = 0.1230082450100857 at epoch 3500
Cost = 0.11704592620593783 at epoch 4000
Cost = 0.11205470319914505 at epoch 4500
Cost = 0.10778404062490321 at epoch 5000
Cost = 0.10406686941551509 at epoch 5500
Cost = 0.10078706993627766 at epoch 6000
Cost = 0.09786095486433724 at epoch 6500
Cost = 0.09522634659131059 at epoch 7000
Cost = 0.09283589400966233 at epoch 7500
Cost = 0.09065277318198824 at epoch 8000

```

Cost = 0.08864780065633096 at epoch 8500
Cost = 0.08679744633296001 at epoch 9000
Cost = 0.08508244598020351 at epoch 9500
Cost = 0.08348681929148014 at epoch 10000
Cost = 2.1182936721476553 at epoch 0
Cost = 0.27998292388249524 at epoch 500
Cost = 0.20307103433352286 at epoch 1000
Cost = 0.17104236086479957 at epoch 1500
Cost = 0.1523633175459273 at epoch 2000
Cost = 0.1397022359518514 at epoch 2500
Cost = 0.13033701063250494 at epoch 3000
Cost = 0.1230082450100857 at epoch 3500
Cost = 0.11704592620593783 at epoch 4000
Cost = 0.11205470319914505 at epoch 4500
Cost = 0.10778404062490321 at epoch 5000
Cost = 0.10406686941551509 at epoch 5500
Cost = 0.10078706993627766 at epoch 6000
Cost = 0.09786095486433724 at epoch 6500
Cost = 0.09522634659131059 at epoch 7000
Cost = 0.09283589400966233 at epoch 7500
Cost = 0.09065277318198824 at epoch 8000
Cost = 0.08864780065633096 at epoch 8500
Cost = 0.08679744633296001 at epoch 9000
Cost = 0.08508244598020351 at epoch 9500
Cost = 0.08348681929148014 at epoch 10000
Cost = 0.08199716189054078 at epoch 10500
Cost = 0.08060212276116276 at epoch 11000
Cost = 0.07929200940329773 at epoch 11500
Cost = 0.07805848371783727 at epoch 12000
Cost = 0.07689432438626831 at epoch 12500
Cost = 0.07579323908763191 at epoch 13000
Cost = 0.07474971456184852 at epoch 13500
Cost = 0.07375889565799124 at epoch 14000
Cost = 0.07281648676737945 at epoch 14500
Cost = 0.07191867072993789 at epoch 15000
Cost = 0.0710620415604673 at epoch 15500
Cost = 0.07024354826138748 at epoch 16000
Cost = 0.06946044764749522 at epoch 16500
Cost = 0.06871026457507187 at epoch 17000
Cost = 0.06799075830004488 at epoch 17500
Cost = 0.06729989393229985 at epoch 18000
Cost = 0.06663581813682132 at epoch 18500
Cost = 0.06599683837725842 at epoch 19000
Cost = 0.06538140511582786 at epoch 19500
Cost = 0.06478809648212798 at epoch 20000
Cost = 0.06421560500643417 at epoch 20500
Cost = 0.0636627260828897 at epoch 21000
Cost = 0.06312834788654638 at epoch 21500

Cost = 0.06261144251696187 at epoch 22000
Cost = 0.06211105818142225 at epoch 22500
Cost = 0.06162631226407052 at epoch 23000
Cost = 0.061156385154413365 at epoch 23500
Cost = 0.060700514730863554 at epoch 24000
Cost = 0.06025799141300995 at epoch 24500
Cost = 0.059828153710953694 at epoch 25000
Cost = 0.05941038421192426 at epoch 25500
Cost = 0.0590041059540067 at epoch 26000
Cost = 0.05860877914459871 at epoch 26500
Cost = 0.05822389818747583 at epoch 27000
Cost = 0.0578489889873679 at epoch 27500
Cost = 0.05748360650492249 at epoch 28000
Cost = 0.05712733253805903 at epoch 28500
Cost = 0.05677977370816147 at epoch 29000
Cost = 0.05644055963147156 at epoch 29500
Cost = 0.05610934125760294 at epoch 30000
Cost = 0.05578578935841618 at epoch 30500
Cost = 0.05546959315170966 at epoch 31000
Cost = 0.0551604590453675 at epoch 31500
Cost = 0.054858109488814685 at epoch 32000
Cost = 0.05456228191987569 at epoch 32500
Cost = 0.054272727796402555 at epoch 33000
Cost = 0.05398921170329844 at epoch 33500
Cost = 0.053711510526779846 at epoch 34000
Cost = 0.05343941268884652 at epoch 34500
Cost = 0.053172717435953 at epoch 35000
Cost = 0.05291123417676127 at epoch 35500
Cost = 0.052654781864613545 at epoch 36000
Cost = 0.05240318842099132 at epoch 36500
Cost = 0.05215629019674043 at epoch 37000
Cost = 0.05191393146824835 at epoch 37500
Cost = 0.0516759639660939 at epoch 38000
Cost = 0.05144224643394315 at epoch 38500
Cost = 0.05121264421568078 at epoch 39000
Cost = 0.05098702886893545 at epoch 39500
Cost = 0.050765277803300216 at epoch 40000
Cost = 0.050547273941673486 at epoch 40500
Cost = 0.050332905403250736 at epoch 41000
Cost = 0.050122065206799 at epoch 41500
Cost = 0.04991465099292798 at epoch 42000
Cost = 0.04971056476415907 at epoch 42500
Cost = 0.04950971264166353 at epoch 43000
Cost = 0.049312004637616216 at epoch 43500
Cost = 0.049117354442171454 at epoch 44000
Cost = 0.04892567922413048 at epoch 44500
Cost = 0.04873689944442455 at epoch 45000
Cost = 0.04855093868158693 at epoch 45500

Cost = 0.04836772346843875 at epoch 46000
Cost = 0.04818718313925023 at epoch 46500
Cost = 0.04800924968668656 at epoch 47000
Cost = 0.04783385762788032 at epoch 47500
Cost = 0.04766094387901065 at epoch 48000
Cost = 0.047490447637803294 at epoch 48500
Cost = 0.047322310273397776 at epoch 49000
Cost = 0.04715647522306051 at epoch 49500
Cost = 0.046992887895254555 at epoch 50000
Cost = 2.1182936721476553 at epoch 0
Cost = 0.6425182246590546 at epoch 500
Cost = 0.45780883553476787 at epoch 1000
Cost = 0.36604690533082984 at epoch 1500
Cost = 0.31374149726180545 at epoch 2000
Cost = 0.2800565789265448 at epoch 2500
Cost = 0.25629042694719756 at epoch 3000
Cost = 0.23838421930333062 at epoch 3500
Cost = 0.22425527033156967 at epoch 4000
Cost = 0.21272793082639768 at epoch 4500
Cost = 0.20308520646571906 at epoch 5000
Cost = 0.19486334613296252 at epoch 5500
Cost = 0.18774634309607824 at epoch 6000
Cost = 0.18150864343165932 at epoch 6500
Cost = 0.17598343456684834 at epoch 7000
Cost = 0.17104432195090086 at epoch 7500
Cost = 0.16659378014092457 at epoch 8000
Cost = 0.16255537259172503 at epoch 8500
Cost = 0.15886831611193955 at epoch 9000
Cost = 0.1554835999313468 at epoch 9500
Cost = 0.15236120382329682 at epoch 10000
Cost = 0.14946809207953493 at epoch 10500
Cost = 0.14677672892021656 at epoch 11000
Cost = 0.14426395517835408 at epoch 11500
Cost = 0.14191013689488133 at epoch 12000
Cost = 0.13969851811094794 at epoch 12500
Cost = 0.13761471801394515 at epoch 13000
Cost = 0.13564632861065215 at epoch 13500
Cost = 0.13378258677373023 at epoch 14000
Cost = 0.1320141056052944 at epoch 14500
Cost = 0.13033265475533948 at epoch 15000
Cost = 0.12873098104956815 at epoch 15500
Cost = 0.12720266183475287 at epoch 16000
Cost = 0.12574198457621596 at epoch 16500
Cost = 0.12434384743102653 at epoch 17000
Cost = 0.1230036766165854 at epoch 17500
Cost = 0.12171735730585889 at epoch 18000
Cost = 0.12048117549374653 at epoch 18500
Cost = 0.11929176882201169 at epoch 19000

Cost = 0.11814608476220453 at epoch 19500
Cost = 0.1170413448721461 at epoch 20000
Cost = 0.11597501408813278 at epoch 20500
Cost = 0.11494477421016265 at epoch 21000
Cost = 0.11394850089358974 at epoch 21500
Cost = 0.11298424358629469 at epoch 22000
Cost = 0.11205020795215673 at epoch 22500
Cost = 0.11114474040421111 at epoch 23000
Cost = 0.11026631443818313 at epoch 23500
Cost = 0.10941351851199269 at epoch 24000
Cost = 0.10858504526156557 at epoch 24500
Cost = 0.10777968187959339 at epoch 25000
Cost = 0.1069963015131153 at epoch 25500
Cost = 0.1062338555591285 at epoch 26000
Cost = 0.10549136675591038 at epoch 26500
Cost = 0.10476792298223123 at epoch 27000
Cost = 0.1040626716880412 at epoch 27500
Cost = 0.10337481488923414 at epoch 28000
Cost = 0.10270360466636763 at epoch 28500
Cost = 0.10204833911327867 at epoch 29000
Cost = 0.10140835868677107 at epoch 29500
Cost = 0.10078304291325184 at epoch 30000
Cost = 0.10017180741252871 at epoch 30500
Cost = 0.09957410120307203 at epoch 31000
Cost = 0.09898940425689177 at epoch 31500
Cost = 0.09841722527581259 at epoch 32000
Cost = 0.09785709966429947 at epoch 32500
Cost = 0.09730858767708281 at epoch 33000
Cost = 0.0967712727226265 at epoch 33500
Cost = 0.09624475980595963 at epoch 34000
Cost = 0.09572867409657199 at epoch 34500
Cost = 0.09522265960895707 at epoch 35000
Cost = 0.09472637798499325 at epoch 35500
Cost = 0.0942395073687324 at epoch 36000
Cost = 0.09376174136531926 at epoch 36500
Cost = 0.09329278807674635 at epoch 37000
Cost = 0.09283236920797565 at epoch 37500
Cost = 0.09238021923765997 at epoch 38000
Cost = 0.09193608464828511 at epoch 38500
Cost = 0.09149972321106839 at epoch 39000
Cost = 0.09107090332138318 at epoch 39500
Cost = 0.09064940338085321 at epoch 40000
Cost = 0.09023501122259872 at epoch 40500
Cost = 0.08982752357639552 at epoch 41000
Cost = 0.08942674557077243 at epoch 41500
Cost = 0.0890324902692976 at epoch 42000
Cost = 0.08864457823850709 at epoch 42500
Cost = 0.08826283714511937 at epoch 43000


```
Cost = 0.08788710138034621 at epoch 43500
Cost = 0.08751721170926555 at epoch 44000
Cost = 0.08715301494336802 at epoch 44500
Cost = 0.08679436363452313 at epoch 45000
Cost = 0.08644111578873956 at epoch 45500
Cost = 0.08609313459820822 at epoch 46000
Cost = 0.0857502881902357 at epoch 46500
Cost = 0.08541244939177844 at epoch 47000
Cost = 0.08507949550838974 at epoch 47500
Cost = 0.08475130811648801 at epoch 48000
Cost = 0.0844277728679423 at epoch 48500
Cost = 0.08410877930605673 at epoch 49000
Cost = 0.0837942206921122 at epoch 49500
Cost = 0.08348399384169977 at epoch 50000
```

0.2.5 4. Training and testing

a. Cost history

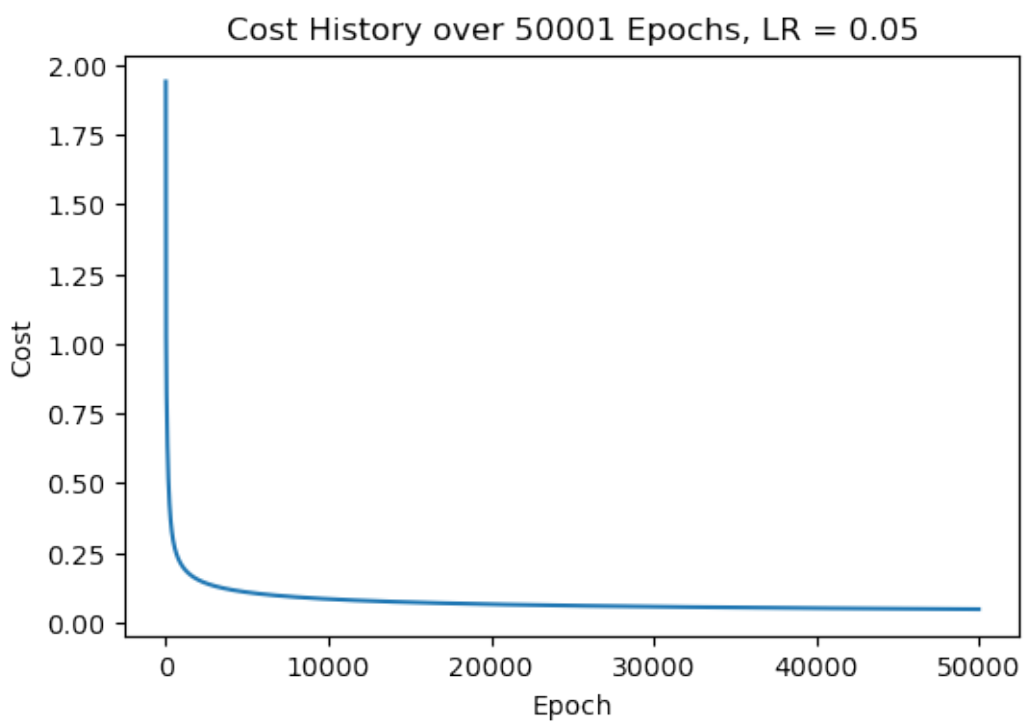
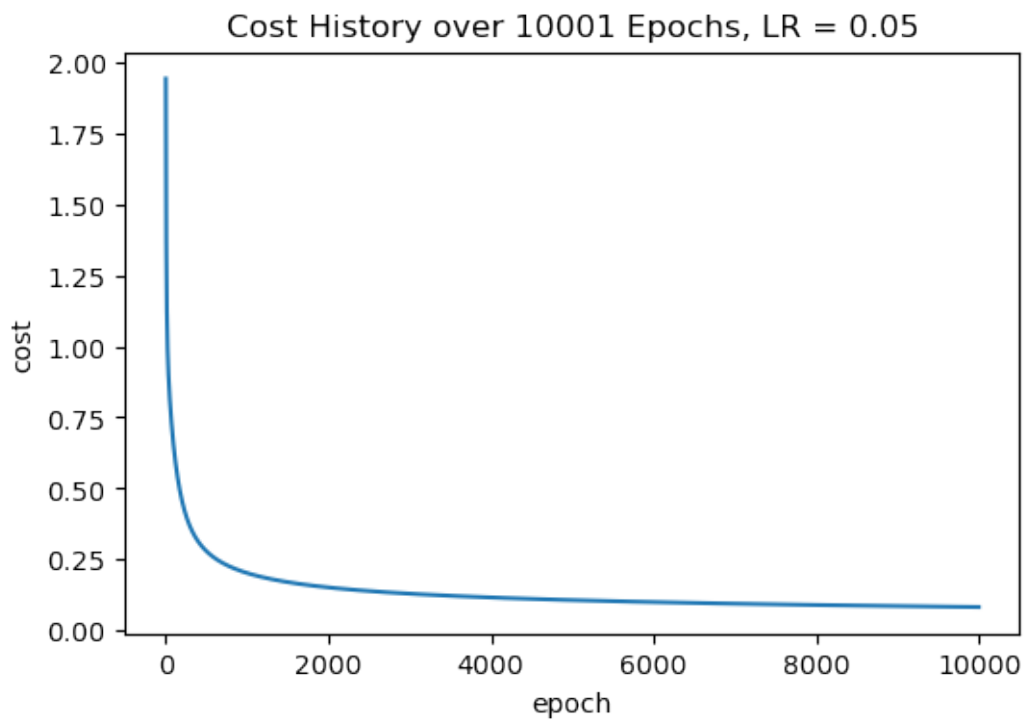
```
[295]: plt.figure()

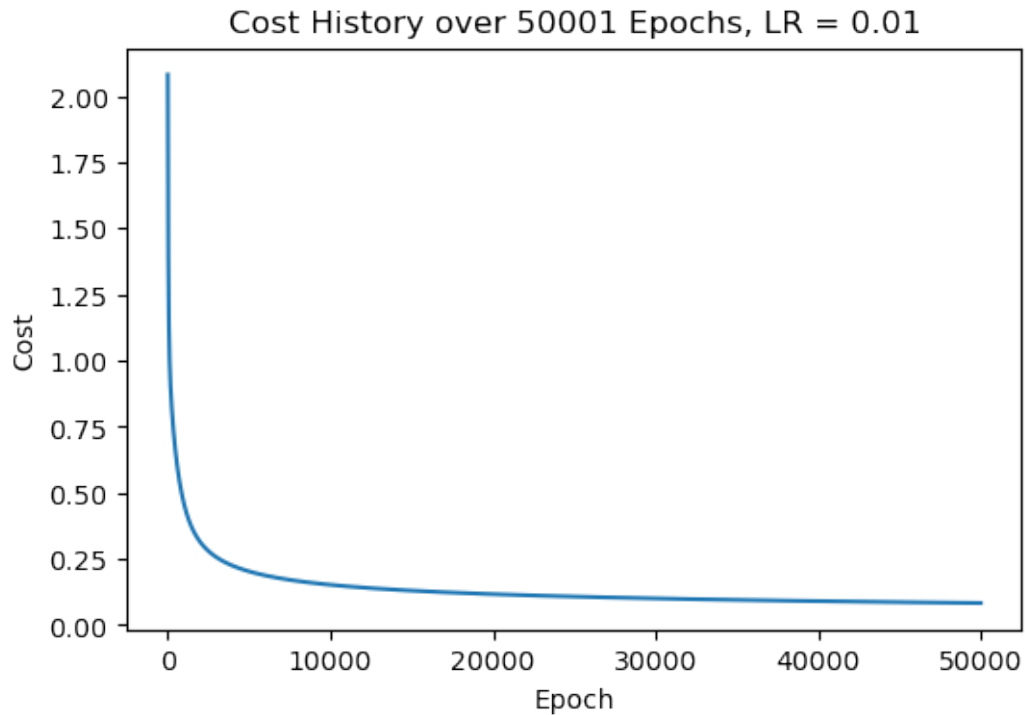
# print(np.shape(chist1))
plt.plot(chist1[11:])
plt.title('Cost History over 10001 Epochs, LR = 0.05')
plt.xlabel('epoch')
plt.ylabel('cost')

plt.figure()
plt.plot(chist2[11:])
plt.title('Cost History over 50001 Epochs, LR = 0.05')
plt.xlabel('Epoch')
plt.ylabel('Cost')

plt.figure()
plt.plot(chist3[11:])
plt.title('Cost History over 50001 Epochs, LR = 0.01')
plt.xlabel('Epoch')
plt.ylabel('Cost')
```

```
[295]: Text(0, 0.5, 'Cost')
```





b. Confusion matrix

```
[142]: plt.rcParams['figure.dpi'] = 100
sess = tf.Session()
saver.restore(sess, saved1)
ytestout = sess.run(out, {X:test_data_norm})
ytestout = np.argmax(ytestout, axis =0)
cm1 = confusion_matrix(np.argmax(test_int, axis=0), ytestout)
plt.figure()

ConfusionMatrixDisplay(confusion_matrix = cm1).plot()
plt.title('LR0.05,E10001')

sess.close()

sess = tf.Session()
saver.restore(sess, saved2)
ytestout = sess.run(out, {X:test_data_norm})
ytestout = np.argmax(ytestout, axis =0)
cm2 = confusion_matrix(np.argmax(test_int, axis=0), ytestout)
plt.figure()
```

```

ConfusionMatrixDisplay(confusion_matrix = cm2).plot()
plt.title('LR0.05,E50001')
sess.close()

sess = tf.Session()
saver.restore(sess, saved3)
ytestout = sess.run(out, {X:test_data_norm})
ytestout = np.argmax(ytestout, axis=0)
cm3 = confusion_matrix(np.argmax(test_int, axis=0), ytestout)
plt.figure()

ConfusionMatrixDisplay(confusion_matrix = cm3).plot()
plt.title('LR0.01')
sess.close()

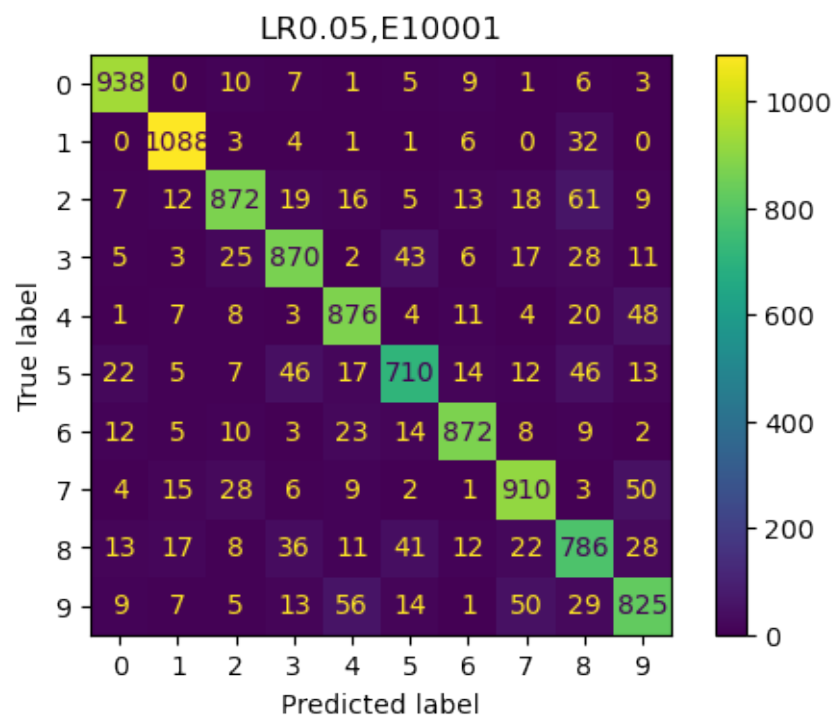
```

INFO:tensorflow:Restoring parameters from trained_model_0.05_10001.ckpt

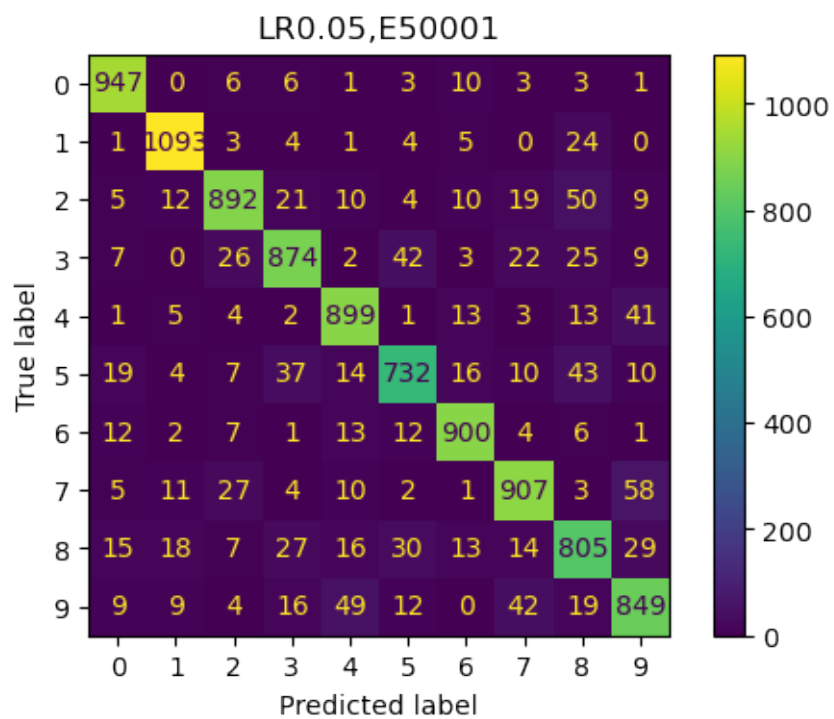
INFO:tensorflow:Restoring parameters from trained_model_0.05_50001.ckpt

INFO:tensorflow:Restoring parameters from trained_model_0.01_50001.ckpt

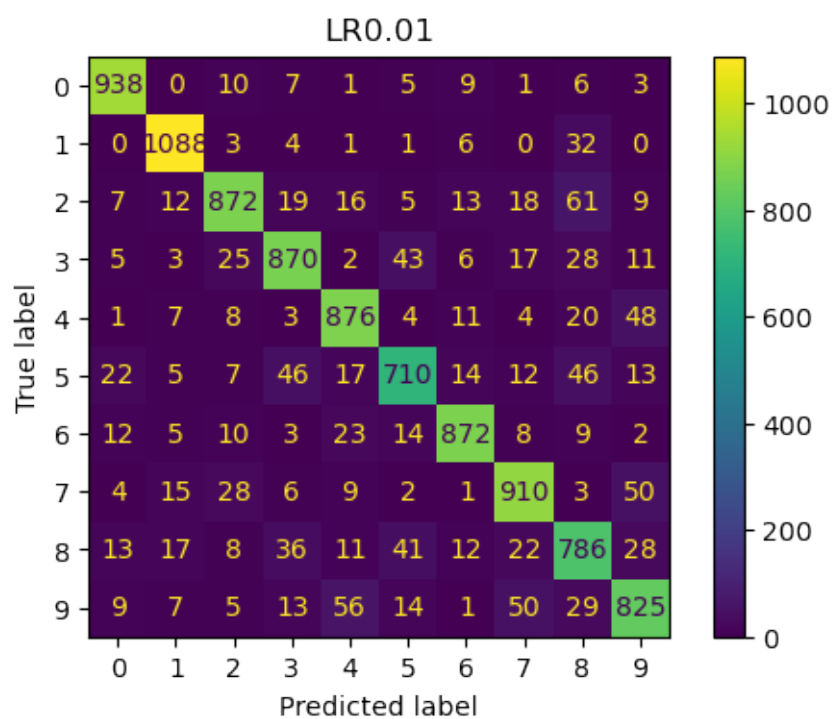
<Figure size 600x400 with 0 Axes>



<Figure size 600x400 with 0 Axes>

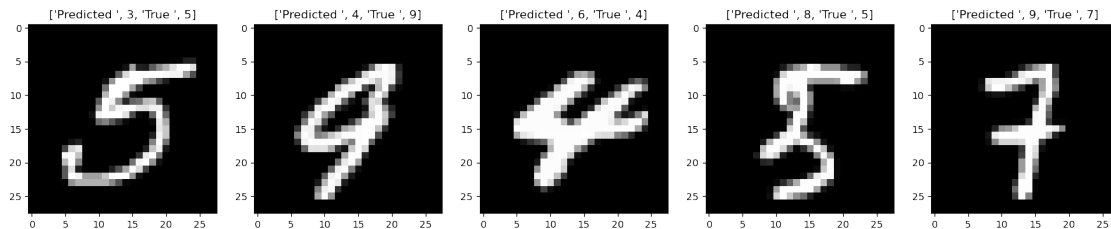


<Figure size 600x400 with 0 Axes>



c. Common misclassifications

```
[293]: cases = [219, 7580, 6759, 3776, 307]
plt.figure(figsize = (20,20))
for i in range(5):
    plt.subplot(1,5,i+1)
    plt.imshow(test_data[cases[i]], cmap = 'gray')
    plt.title(['Predicted ', ytestout[cases[i]], 'True ', test_labels[cases[i]]])
```



```
[294]: print('9 and 4 can be easily misclassified as the 9 is not always connected at_
    ↳the top, thus looking like a 4.')
print('5 and 3 are written similarly, however if the upper stem on the five is_
    ↳close to the rest of the number, it can begin to look a little like a_
    ↳compacted 3.')
print('6 and 4 are most likely for a similar reason as to nine, however if we_
    ↳trace a 6 the bottom part, if done crudely, can look like the line going_
    ↳through a 4.')
print('8 and 5: a very compacted 5 nearly can resemble two circles on top of_
    ↳each other, thus becoming an 8.')
print('9 and 7, if 7 is written with a horizontal line through it and possible_
    ↳and extra vertical line from the top, it resembles a 9.')
print('Ultimately, handwriting styles are unique to a person, and depending on_
    ↳how one chooses to write many numbers can have very similar features to_
    ↳others, in this case we see')
print('5 and 3, 9 and 4, 8 and 5, 9 and 7')
```

9 and 4 can be easily misclassified as the 9 is not always connected at the top, thus looking like a 4.

5 and 3 are written similarly, however if the upper stem on the five is close to the rest of the number, it can begin to look a little like a compacted 3.

6 and 4 are most likely for a similar reason as to nine, however if we trace a 6 the bottom part, if done crudely, can look like the line going through a 4.

8 and 5: a very compacted 5 nearly can resemble two circles on top of each other, thus becoming an 8.

9 and 7, if 7 is written with a horizontal line through it and possible and

extra vertical line from the top, it resembles a 9.

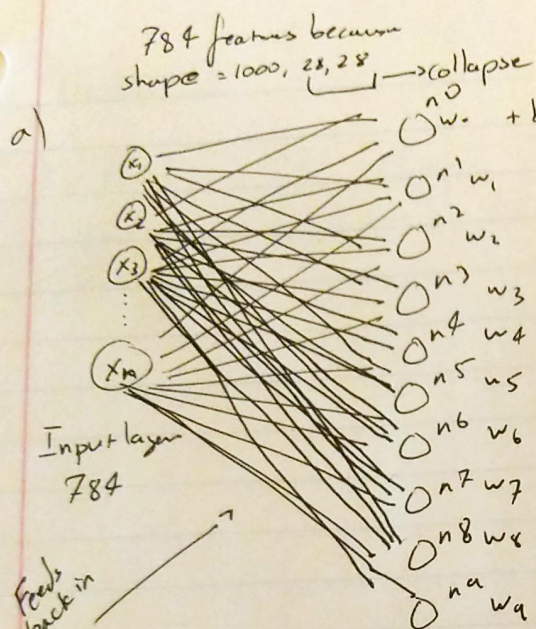
Ultimately, handwriting styles are unique to a person, and depending on how one chooses to write many numbers can have very similar features to others, in this case we see

5 and 3, 9 and 4, 8 and 5, 9 and 7

[]:

[]:

Problem 3



Only 1 layer of neurons, since 10 rest
→ so its actually the output layer
using sigmoid neurons
activation f(x) → $f(z) = \frac{1}{1 + e^{-z}}$

$$\text{cost} \rightarrow L(y^{(i)}, \hat{y}^{(i)}) = - (y^{(i)} \log \hat{y}^{(i)} + (1 - y^{(i)}) \log (1 - \hat{y}^{(i)}))$$

each neuron is connected to all inputs

take neuron 0 for example

$$x_1 w_0 + x_2 w_0 + \dots + x_{784} w_0$$

where the w_0 corresponds to n_0 , we also add the bias term

after ~~the first~~ each pass we go back and use gradient descent to optimize

b) Unless the cost was minimized, would make it as NaN and attempt to reclassify by ~~adjusting~~ the adjusted parameters.