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## **Fire detection extracted from webcam**

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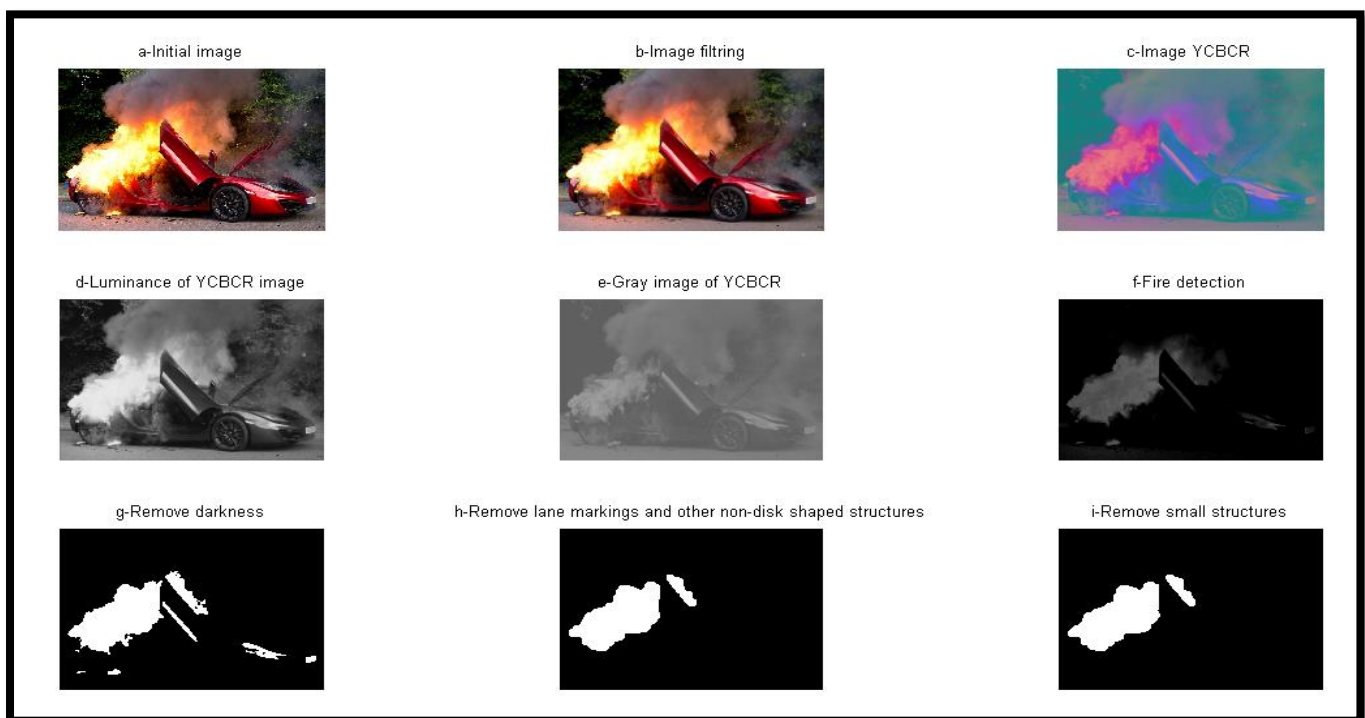
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## PART I: Capture fire from image

How can we distinct the fire color from images and capturing it :

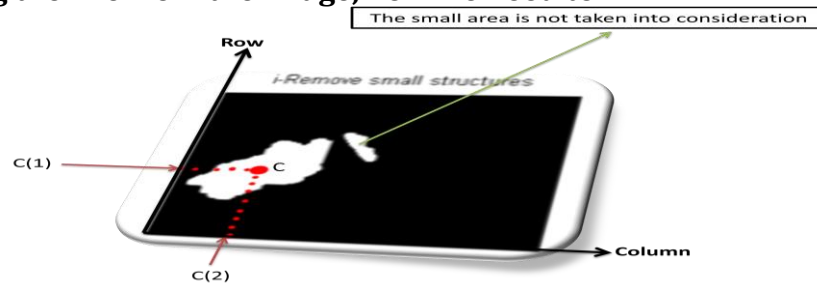
1. Step (a-b-c): distinct the fire color in image by converting the rgb image to YCBCR type
2. Step(d-e-f): subtract the fire color in image from the intersection between the gray image (converted from the YCBCR) and the red (converted from the YCBCR)
3. Step(g-h-i): remove all the darkness and all small structures and lane marking and other non-disk shaped structures

<b>a-</b> RGB = imread('fire2.png');	<b>b-</b> RGB=imresize(RGB, [360 360]); RGB=imfilter(RGB,H);	<b>c-</b> YCBCR = rgb2ycbcr(RGB);
<b>d-</b> im_red=YCBCR(:, :,1);	<b>e-</b> im_gray=rgb2gray(YCBCR);	<b>f-</b> im_diff=imsubtract(im_red,im_gray);
<b>g-</b> noDarkCars = imextendedmax(im_diff, darkCarValue);	<b>h-</b> noSmallStructures = imopen(noDarkCars, sedisk);	<b>i-</b> noSmallStructures = bwareaopen(noSmallStructures, 500);



## PART I: Centroid the fire area

After subtracting the fire from the image, now we need to:



1. Get the area and centroid of each remaining object in the image.
2. The object with the largest area is the light-colored fire.
3. Create a copy of the original image and tag the fire by changing the centroid pixel value to red.

```
taggedFire(:,:,k) = singleFrame; // K represented one specific frame in video
```

```
stats = regionprops(noSmallStructures, {'Centroid','Area'}) // measures a set of properties for each  
connected component(object) in image. Properties can be a comma-separated list of strings in this  
case regionprops computes the 'Area', 'Centroid', measurements
```

```
if ~isempty([stats.Area])
```

```
areaArray = [stats.Area];
```

```
[junk,idx] = max(areaArray);
```

```
c = stats(idx).Centroid;
```

```
c = floor(fliplr(c));
```

```
floor() //rounds the elements of A to the nearest integers less than or equal to A.
```

```
B = fliplr(A) //returns A with columns flipped in the left-right direction, that is, about a vertical axis.
```

```
c = 320.5000 240.5000
```

```
fliplr(c)
```

```
c = 240.5000 320.5000
```

```
floor(c)
```

```
c = 240 320
```

```
width = 2; //for determine the centroid pixel with a high dimension
```

```
row = c(1)-width:c(1)+width //row = 236 237 238 239 240 241 242 243 244
```

```
col = c(2)-width:c(2)+width; //col = 316 317 318 319 320 321 322 323 324
```

```
taggedFire (row,col,1,k) = 255; //the red color get the high value
```

```
taggedFire (row,col,2,k) = 0; //the green color get the low value
```

```
taggedFire (row,col,3,k) = 0; //the blue color get the low value
```

```
end
```



## **PART I: Final code**

```
Obj = VideoReader('fire2.avi');
get(Obj);
J= read(Obj, inf);
nframes = get(Obj, 'NumberOfFrames')
taggedFire = zeros([size(J,1) size(J,2) 3 nframes], class(J));
for k = 1:nframes
    darkValue = 50;
    singleFrame = read(Obj, k);
    t=[9 9];
    H = fspecial('Gaussian', t,1);
    ImageG=imfilter(singleFrame,H);
    YCBCR = rgb2ycbcr(ImageG);
    im_red=YCBCR(:,:,1);
    im_gray = rgb2gray(YCBCR);
    I=imsubtract(im_red,im_gray);
    noDark = imextendedmax(I, darkValue);
    sedisk = strel('disk',2);
    noSmallStructures = imopen(noDark, sedisk);
    noSmallStructures = bwareaopen(noSmallStructures, 150);
    taggedFire(:,:,k) = singleFrame;
    stats = regionprops(noSmallStructures, {'Centroid','Area'});
    if ~isempty([stats.Area])
        areaArray = [stats.Area];
        [junk,idx] = max(areaArray);
        c = stats(idx).Centroid;
        c = floor(fliplr(c));
        width = 2;
        row = c(1)-width:c(1)+width;
        col = c(2)-width:c(2)+width;
        taggedFire (row,col,1,k) = 255;
        taggedFire (row,col,2,k) = 0;
        taggedFire (row,col,3,k) = 0;
    end
end
    frameRate = get(Obj,'FrameRate');
    implay(taggedFire,frameRate);
```

## **PART II: Creat video input from webcam**

```
vid = videoinput('winvideo', 1, 'MJPG_640x480');  
  
//Construct a video input object  
src = getselectedsource(vid);  
  
//View the properties for the selected video source object.  
vid.FramesPerTrigger = 1;  
set(vid,'TriggerRepeat', Inf);  
  
// Configure the number of frames to log upon triggering.  
vid.ReturnedColorspace = 'rgb';  
hVideoOut = vision.VideoPlayer;  
hVideoOut.Name = 'Fire detected';  
start(vid);
```

### **Description**

#### **obj = videoinput(adaptorname)**

Constructs the video input object obj. A video input object represents the connection between MATLAB and a particular image acquisition device.

Adaptorname is a text string that specifies the name of the adaptor used to communicate with the device.

Use the '**IMAQHWINFO**' function to determine the adaptors available on your system.

#### **obj = videoinput(adaptorname,deviceId,format,P1,V1,...)**

creates a video input object obj with the specified property values. If an invalid property name or property value is specified, the object is not created.gf

```
>>imaqhwinfo(winvideo)  
ans =  
InstalledAdaptors: {'matrox' 'winvideo'}  
MATLABVersion: '7.12 (R2011a)'  
ToolboxName: 'Image Acquisition Toolbox'  
ToolboxVersion: '4.1 (R2011a)'
```

## **PART II: Creat timer**

```
c=clock;  
display(['year month day hour minute seconds'])
```

### **Description**

c = clock returns a six-element date vector containing the current date and time in decimal form:[year month day hour minute seconds]

## **PART II: Creat sound effect when the fire detect**

```
y=fix(c)  
  
cf = 2000;           // carrier frequency (Hz)  
sf = 22050;         // sample frequency (Hz)  
d = 5.0;            // duration (s)  
n = sf * d;         // number of samples  
s = (1:n) / sf;     // sound data preparation  
s = sin(2 * pi * cf * s); // sinusoidal modulation  
sound(s, sf);       //sound presentation  
pause(d + 0.5);     // waiting for sound end
```

## **PART II: Final code**

```
vid = videoinput('winvideo', 1, 'MJPG_640x480');
src = getselectedsource(vid);
vid.FramesPerTrigger = 1;
vid.ReturnedColorspace = 'rgb';
set(vid,'TriggerRepeat', Inf);
hVideoOut = vision.VideoPlayer;
hVideoOut.Name = 'Fire detected';
start(vid);
nframes= 300;
for k = 1:nframes
    black=0;
    white=0;
    RGB=getsnapshot(vid); //Acquire and display a single image frame.
    t=[9 9];
    H = fspecial('Gaussian', t,1);
    RGBF=imfilter(RGB,H);
    YCBCR = rgb2ycbcr(RGBF);
    im_red=YCBCR(:, :,1);
    im_gray=rgb2gray(YCBCR);
    im_diff=imsubtract(im_red,im_gray);
    darkCarValue = 50;
    noDarkCars = imextendedmax(im_diff, darkCarValue);
    sedisk = strel('disk',10);
    noSmallStructures = imopen(noDarkCars, sedisk);
    noSmallStructures = bwareaopen(noSmallStructures, 500);
    taggedFire= zeros(size(RGB,1),size(RGB,2),3,nframes);
    taggedFire(:, :,k) = RGB;
    stats = regionprops(noSmallStructures, {'Centroid','Area'});
    if ~isempty([stats.Area])
        areaArray = [stats.Area] ;
        if(areaArray~=307200)
            c=clock;
            display('year month day hour minute seconds')
```



```

y=fix(c)
cf = 2000;           // carrier frequency (Hz)
sf = 22050;         // sample frequency (Hz)
d = 5.0;            //duration (s)
n = sf * d;         // number of samples
s = (1:n) / sf;     // sound data preparation
s = sin(2 * pi * cf * s); // sinusoidal modulation
sound(s, sf);       // sound presentation
pause(d + 0.5);     // waiting for sound end
end

[junk,idx] = max(areaArray);
x = stats(idx).Centroid
x = floor(fliplr(x))
width = 4;
row = x(1)-width:x(1)+width;
col = x(2)-width:x(2)+width ;
taggedFire (row,col,1,k) = 255;
taggedFire (row,col,2,k) = 0;
taggedFire (row,col,3,k) = 0;
end
frameRate = get(vid);
step(hVideoOut,[taggedFire(:, :, k) RGB]);
end
delete(vid); //Remove video input object from memory.

```