

#### Lecture Pattern Analysis

# Part 08: Mean Shift

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#### Introduction

- Mean Shift is another widely known algorithm for clustering<sup>1</sup>
- It iteratively performs gradient ascent on the derivative of a kernel
- This iteration converges to a mode (local maximum) of the density without estimating the full density



#### **Kernel Notation and Constraints**

- The kernel has to be radially symmetric, i.e.,
   the kernel function may only depend on the Euclidean distance to a sample
- $\bullet$  The kernel functions must accept squared differences  $\|\boldsymbol{x}_0-\boldsymbol{x}\|_2^2$  as input,

$$K(\mathbf{x}_0, \mathbf{x}) = c \cdot k(\|\mathbf{x}_0 - \mathbf{x}\|_2^2) \tag{1}$$

where c is an arbitrary constant and k(x) is the so-called kernel profile

- This definition admits in particular the
  - · Gaussian kernel with

$$k_{\text{Gauss}}(x) = \exp(-\frac{1}{2}x) \tag{2}$$

Epanechnikov kernel<sup>2</sup> with

$$k_{\mathsf{Ep}}(x) = \begin{cases} 1 - x & \mathsf{for}|x| \le 1\\ 0 & \mathsf{otherwise} \end{cases} \tag{3}$$

• Kernel sizes: Assume that distances  $\|\mathbf{x}_0 - \mathbf{x}\|_2^2$  are already size-normalized<sup>3</sup>

<sup>3</sup>See paper by Comaniciu/Meer Eqn. (1) and Eqn. (2)

<sup>&</sup>lt;sup>2</sup>The typical way to write the Epanechnikov kernel is shown in Hastie/Tibshirani/Friedman Eqn. (6.3) and Eqn. (6.4) for the 1-D case. Our notation differs because our input is already squared and pre-factors factors are absorbed in c in Eqn. 1

#### **Gradient Computation**

· To find the maximum, calculate the gradient of a kernel density estimate

$$\nabla \rho(\mathbf{x}) = \nabla \frac{1}{N} \sum_{i=1}^{N} K_{\lambda}(\mathbf{x}_{i}, \mathbf{x}) = \frac{1}{N} \sum_{i=1}^{N} \nabla K_{\lambda}(\mathbf{x}_{i}, \mathbf{x})$$
(4)

- Insert  $K_{\lambda}(\mathbf{x}_0,\mathbf{x}) = ck(\|\mathbf{x}_0 \mathbf{x}\|_2^2)$ , and substitute  $s = \|\mathbf{x}_0 \mathbf{x}\|_2^2$
- Then, the first derivative of k(s) w.r.t.  $\mathbf{x}$  consists of

$$\frac{\partial k(s)}{\partial s} = k'(s) \qquad \frac{\partial s}{\partial \mathbf{x}} = \frac{\partial (\mathbf{x}_i - \mathbf{x})^T (\mathbf{x}_i - \mathbf{x})}{\partial \mathbf{x}} = -2(\mathbf{x}_i - \mathbf{x}) \quad (5)$$

which is used to find an extremum (maximum!) where the gradient is 0

$$\nabla \rho(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^{N} c \cdot k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2) (-2(\mathbf{x}_i - \mathbf{x})) \stackrel{!}{=} 0$$
 (6)



#### From the Gradient to the Mean Shift Vector

The gradient equation directly provides one gradient ascend step:

$$\nabla p(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^{N} c \cdot k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2)(-2(\mathbf{x}_i - \mathbf{x})) = 0$$
 (7)

$$\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2)(-2(\mathbf{x}_i - \mathbf{x})) = 0$$
 (8)

$$\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2) \cdot \mathbf{x}_i - \sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2) \cdot \mathbf{x} = 0$$
 (9)

$$\frac{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2) \cdot \mathbf{x}_i}{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}\|_2^2)} - \mathbf{x} = 0$$
(10)

The last row is the normalized gradient, also called the mean shift vector

#### Mean Shift Algorithm

1. Calculate the mean shift vector  $m^{(t)}(\mathbf{x})$  for iteration t:

$$m^{(t)}(\mathbf{x}) = \frac{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}^{(t)}\|_2^2) \cdot \mathbf{x}_i}{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}^{(t)}\|_2^2)} - \mathbf{x}^{(t)}$$
(11)

2. Update position  $\mathbf{x}^{(t)}$ :

$$\mathbf{x}^{(t+1)} = \mathbf{x}^{(t)} + m^{(t)}(\mathbf{x}) = \frac{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}^{(t)}\|_2^2) \cdot \mathbf{x}_i}{\sum_{i=1}^{N} k'(\|\mathbf{x}_i - \mathbf{x}^{(t)}\|_2^2)}$$
(12)

(note that  $\mathbf{x}^{(t)}$  cancels, since it also occurs in  $m^{(t)}(\mathbf{x})$ )

3. Goto 1) until convergence (i.e., at a mode where gradient is 0)



#### Mean Shift for Clustering

- Approach for using mean shift for clustering:
  - Run mean shift for each sample
  - Group samples that converge to nearby locations into the same cluster
- Required parameters for mean shift clustering:
  - The kernel parameters (only window size for Epanechnikov and Gauss)
  - Cluster linking parameters for postprocessing (e.g., a distance threshold)
- Larger kernels lead to less clusters (less local maxima)
- Smaller kernels lead to more clusters (more local maxima)
- The shape of mean shift clusters is potentially less regular than the shape of GMM or k-means clusters



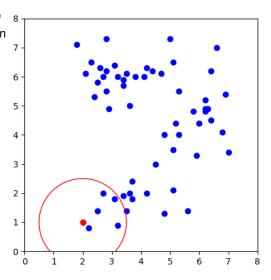
#### Remarks

- With the Epanechnikov kernel, the update is just the mean of the samples within a *D*-dimensional sphere, hence the name "mean shift"
- General caveat: the Euclidean distance is sensitive to scaling differences  $\rightarrow$  normalize the dimensions of the samples (this also applies to k-means)

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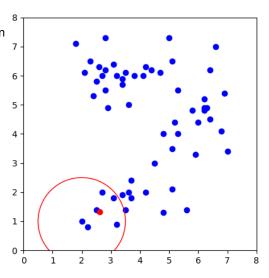


- Two steps per iteration are shown: calculation of mean shift vector and update of the sample position
- Red dot: current location on the sample path
- Red circle: kernel support
- Gray: path of a sample
- Red cross: Mode at the end of a path of a sample





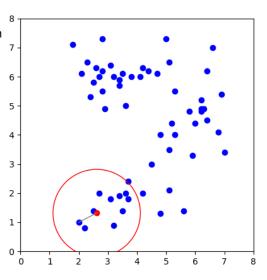
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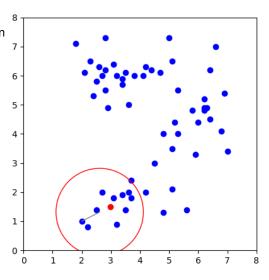
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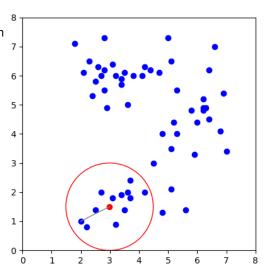
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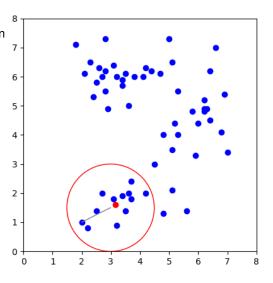


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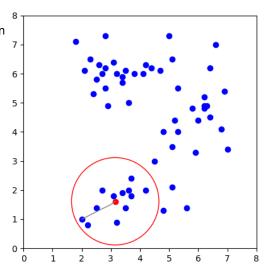


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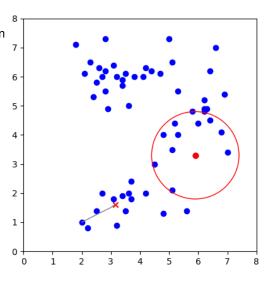
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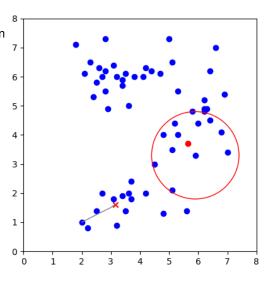


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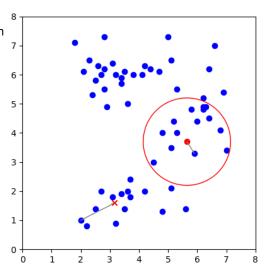
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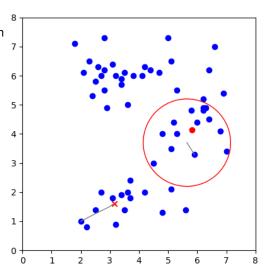
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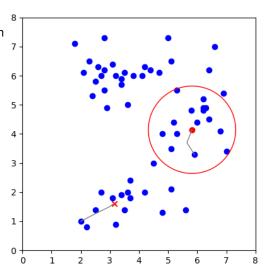


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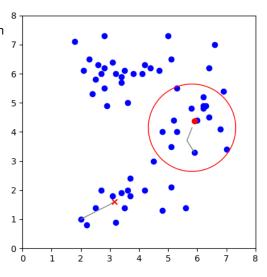


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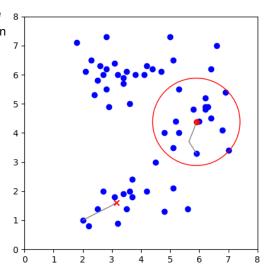
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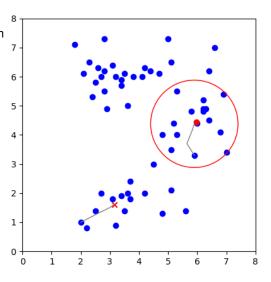
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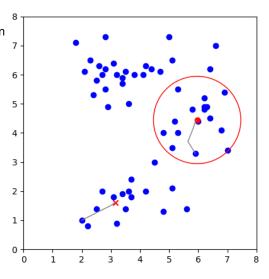


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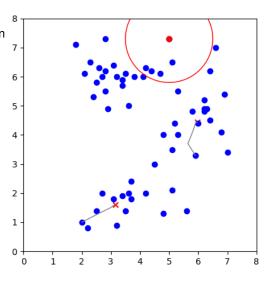
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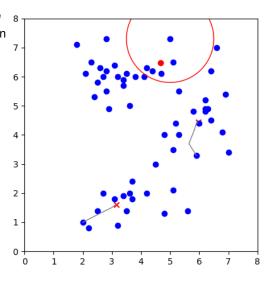


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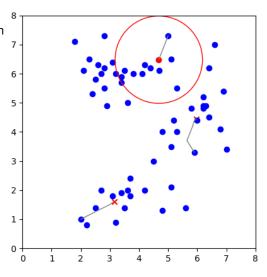
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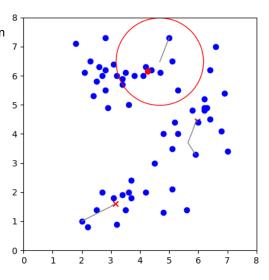
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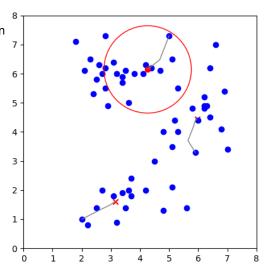
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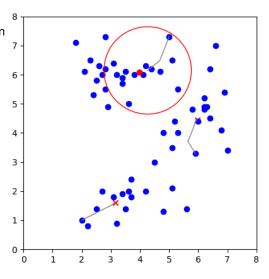
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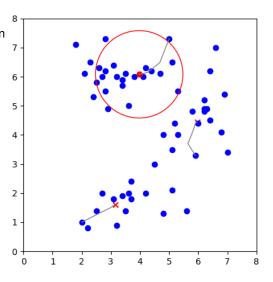
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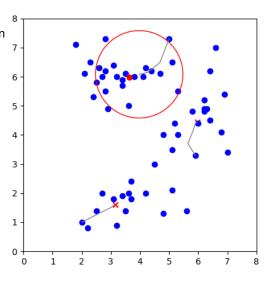


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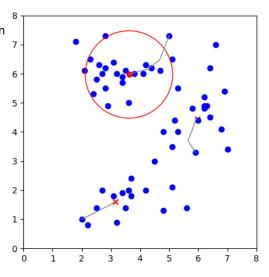
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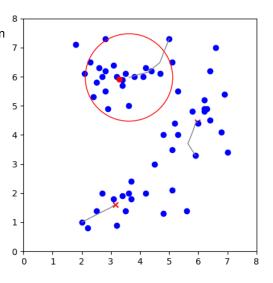
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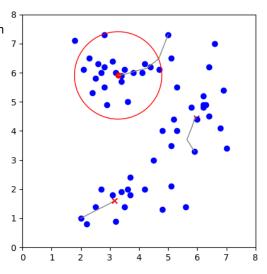


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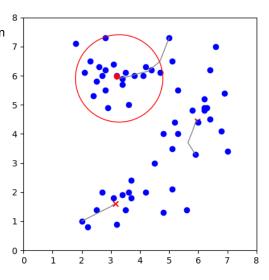
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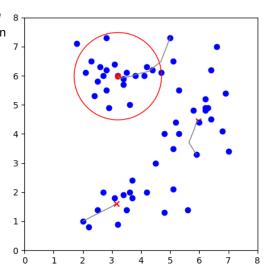
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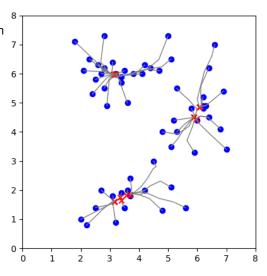


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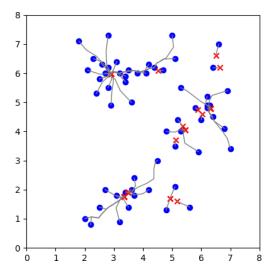


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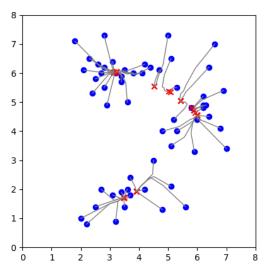


- Smaller kernel (1.5 ightarrow 1): more clusters
- Gray: path of a sample
- Red cross: Mode at the end of a path of a sample



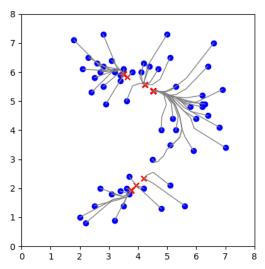


- Larger kernel (1.5 ightarrow 2): clusters start to merge
- Note the characteristic mode ridge in the upper part
- Gray: path of a sample
- Red cross: Mode at the end of a path of a sample



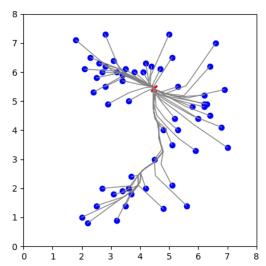


- Larger kernel (1.5 ightarrow 2.5): upper 2 clusters almost merged
- Gray: path of a sample
- Red cross: Mode at the end of a path of a sample





- Larger kernel (1.5 → 3): only a single cluster
- Gray: path of a sample
- Red cross: Mode at the end of a path of a sample





#### Lecture Pattern Analysis

# Part 09: Model Selection for K-Means

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#### Introduction

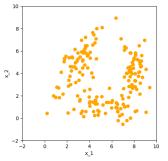
- Clustering is unsupervised, and does not provide an objective function for model selection
- So, specifically for k-means: what k shall we choose?
- Even if the application demands, e.g., the "3 most important clusters", k=3 could be a poor choice if the intrinsic number of clusters is larger
- In this lecture, we investigate the Gap-Statistics as a statistical way to determine k<sup>1</sup>
- The idea is to
  - examine the k-means optimization criterion, the Within-Cluster Distance W(C), for different k,
  - and to select the smallest k for which W(C) is substantially better than the W(C) of k+1 clusters

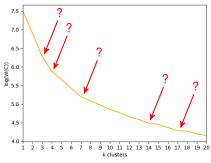
<sup>&</sup>lt;sup>1</sup>The gap statistics is covered in the book by Hastie/Tibshirani/Friedman Sec. 14.3.11



# Examining the Within-Cluster-Distance W(C)

- Investigate the progression of W(C) for different k
- For increasing k, W(C) has to decrease (exceptions are bad local minima):





- Hence, the optimum k can not be found by searching for the minimal W(C)
- An alternative is the "elbow method", to search for a elbow on the curve
- However, which elbow is significant? At  $k = \{3, 4, 7, 14, 17\}$ ?



#### **Gap Statistics**

- Tibshirani *et al.* propose to relate W(C) of our samples to the W(C) of an artificially created reference
- This reference are clusterings of uniform sample distributions
- More specifically:
  - 1. Draw B sets of uniformly distributed samples (Tibshirani uses B=20)
  - 2. On those distributions, calculate for different k the mean of the log of W(C), denote the result  $\log(W_{\text{unif}}(C))$
  - 3. For k clusters, calculate the gap G(k) as the difference between the reference  $\log(W_{\text{unif}}(C))$  and our log-within cluster distances  $\log(W(C))$
  - 4. Select the optimum k as

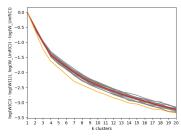
$$k^* = \underset{k}{\operatorname{argmin}} \{ k | G(k) \ge G(k+1) - s'_{k+1} \}$$
 (1)

where  $s'_{k+1} = s_k \cdot \sqrt{1 + 1/B}$  is an unbiased estimate of the standard deviation  $s_k$  of  $\log(W_{\text{unif}}(C))$ 



# **Example: Within-Cluster Distances on the Uniform Distribution**

• Offset-corrected  $\log(W(C))$  (orange) and  $\log(W_{\text{unif}}(C))$  (red), and the B=20 individual reference curves (gray):



 Gaps and standard deviations for curve differences. k\* = 3 is selected:

