

Computer Vision

(Summer Semester 2020)

Lecture 5, Part 4

Cameras and Optics (Pinhole Cameras)

Cameras and Optics

- Pinhole Camera Model
 - Perspective Projection
 - Intrinsic and Extrinsic Camera Parameters
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- Note: The core of these slides stems from the class CSCI 1430: “Introduction to Computer Vision” by James Tompkin, Fall 2017, Brown University.

What is a camera?

The screenshot shows the Google Translate web interface. At the top, the Google logo is on the left, and navigation icons (apps, notifications, profile) are on the right. Below the logo is the 'Translate' heading and a 'Turn off instant translation' link with a star icon. The main input area has a language selector with 'French', 'English', 'Italian', and 'Detect language' options. The source text 'camera' is entered in the input box, and the target text 'room' is displayed in the output box. Below the input box are icons for voice input and a character count '6/5000'. Below the output box are icons for saving, copying, voice output, and sharing. At the bottom, there are sections for 'Synonyms of camera' (listing 'vano, camera da letto' and '4 more synonyms') and 'Translations of camera' (listing 'room', 'chamber', 'house', 'apartment', and 'lodging' with their respective Italian translations). At the very bottom, there are links for 'Google Translate for Business: Translator Toolkit', 'Website Translator', and 'Global Market Finder'.

Camera obscura: dark room

- Known during classical period in China and Greece (e.g., Mo-Ti, China, 470BC to 390BC)

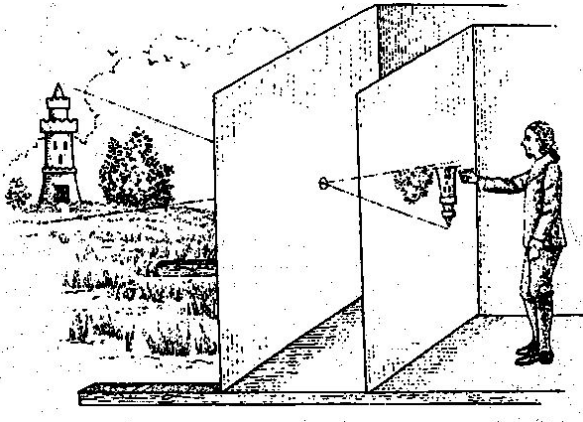


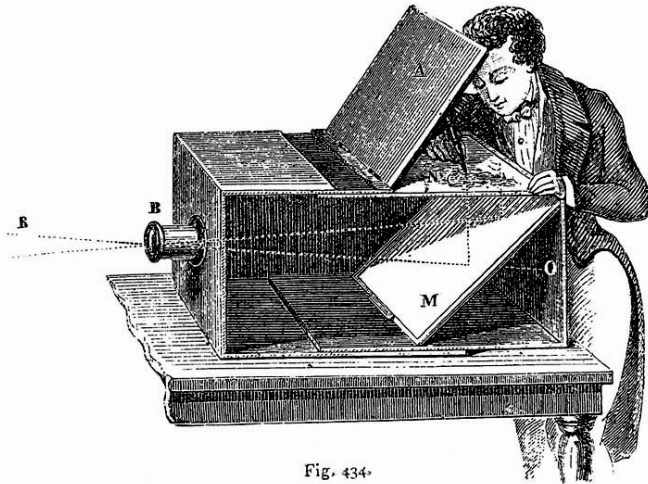
Illustration of Camera Obscura



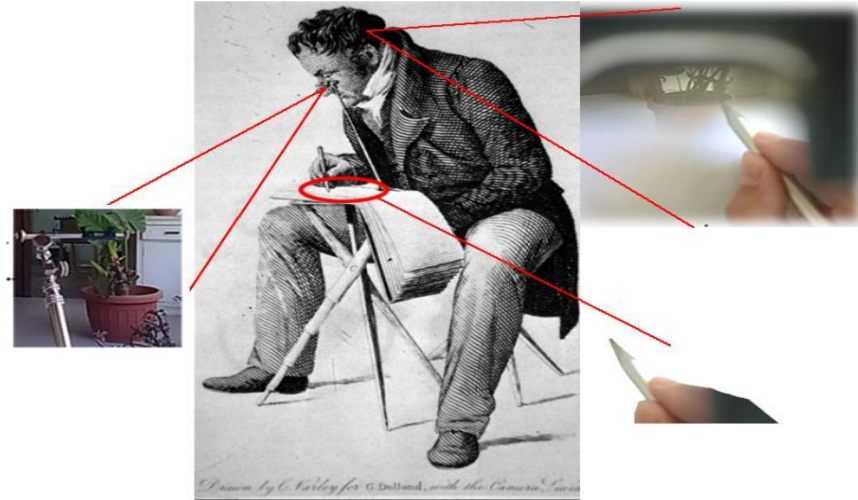
Freestanding camera obscura at UNC Chapel Hill

Photo by Seth Ilys

Camera obscura / lucida used for tracing



Lens Based Camera Obscura, 1568



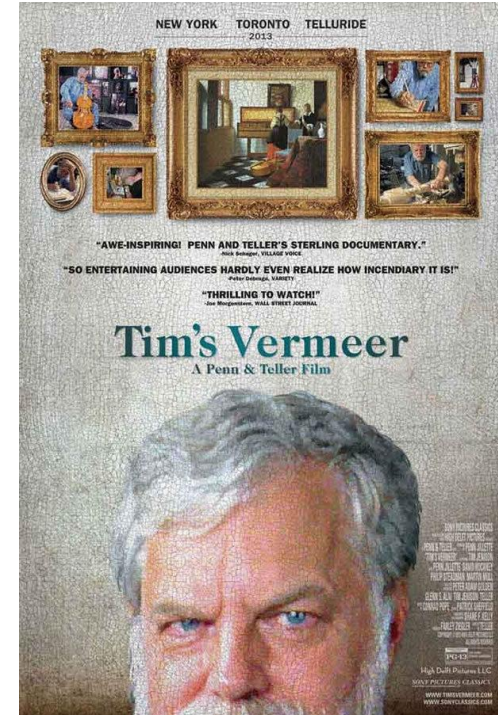
Camera lucida

drawingchamber.wordpress.com

Tim's Vermeer



Johannes Vermeer, The Music Lesson, 1665



Tim Jenison (Lightwave 3D, Video Toaster)

Tim's Vermeer -- Video Still



First Photograph

Oldest surviving photograph
Took 8 hours on pewter plate



Joseph Niepce, 1826

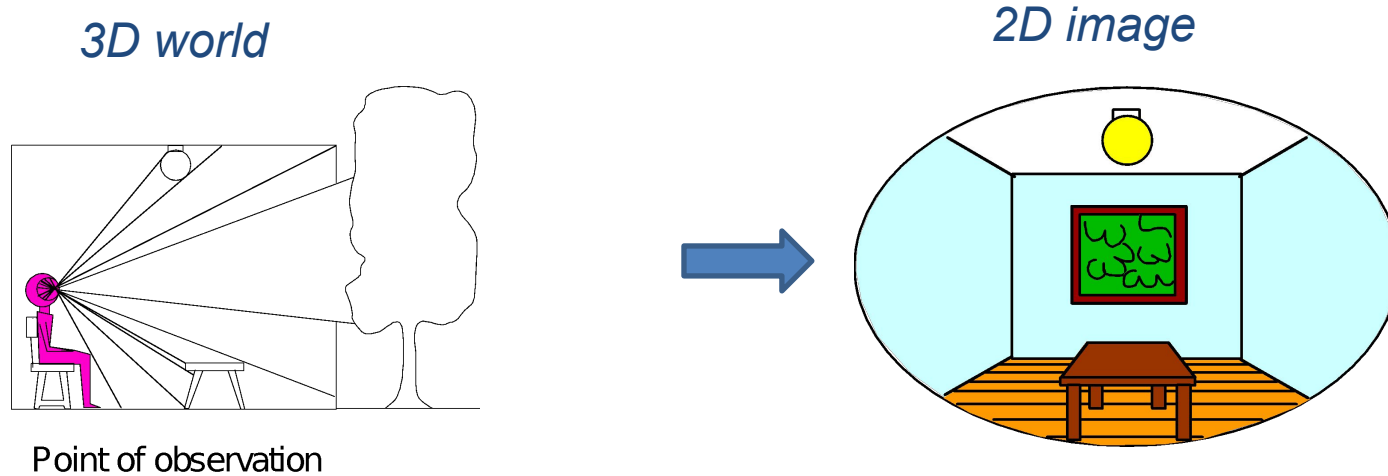
Photograph of the first photograph



Stored at UT Austin

Niepce later teamed up with Daguerre, who eventually created Daguerrotypes

Dimensionality Reduction Machine (3D to 2D)



Figures © Stephen E. Palmer, 2002



Lake Sørvágsvatn in Faroe Islands



*optical tricks/illusions
via 3D → 2D*

100 meters above sea level



Lake Sørvágsvatn in Faroe Islands



~~400~~ 30 meters above sea level

*optical tricks/illusions
via 3D → 2D*

*amusingplanet.com, thanks to Aaron
Gokaslan*



*optical tricks/illusions
via 3D \rightarrow 2D*



*optical tricks/illusions
via 3D \rightarrow 2D*

Holbein's The Ambassadors - 1533



*optical tricks/illusions
via 3D → 2D*

Holbein's The Ambassadors – Memento Mori



*optical tricks/illusions
via 3D → 2D*

Cameras and World Geometry

How tall is this woman?

How high is the camera?

What is the camera rotation wrt. world?



Which ball is closer?

Photo Tourism

Exploring photo collections in 3D

Noah Snavely Steven M. Seitz Richard Szeliski
University of Washington *Microsoft Research*

SIGGRAPH 2006

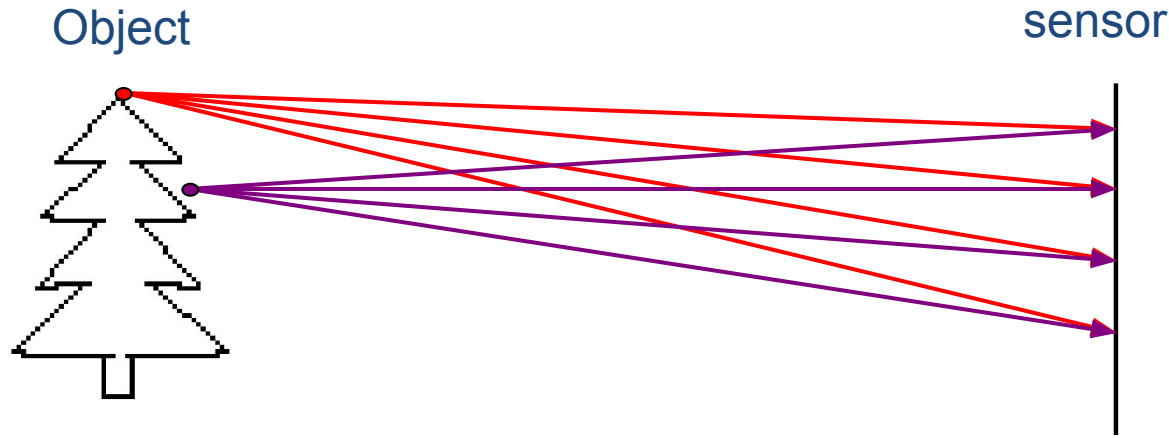
<https://www.youtube.com/watch?v=lgBQCoEfiMs>

1. Feature Matching
2. Registration
3. Camera Calibration

Let's design a camera

Idea 1: Put a sensor in front of an object

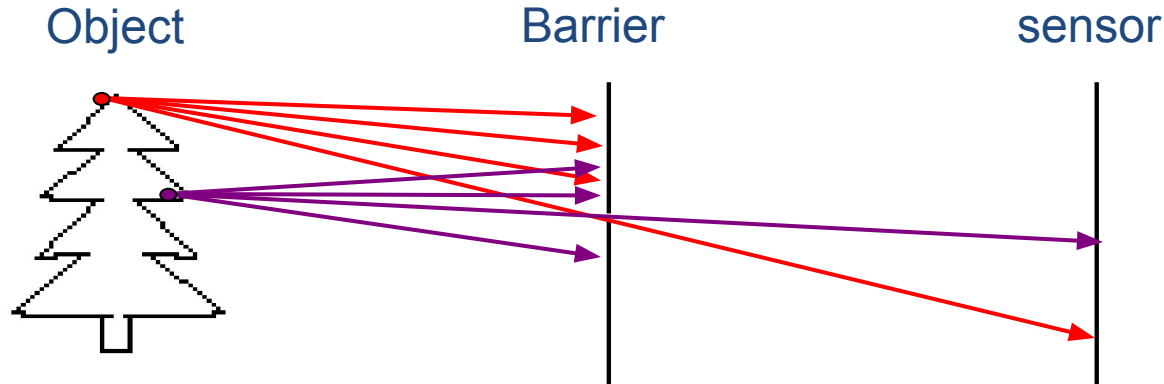
Do we get a reasonable image? → multiple features get mapped to same points on the sensor



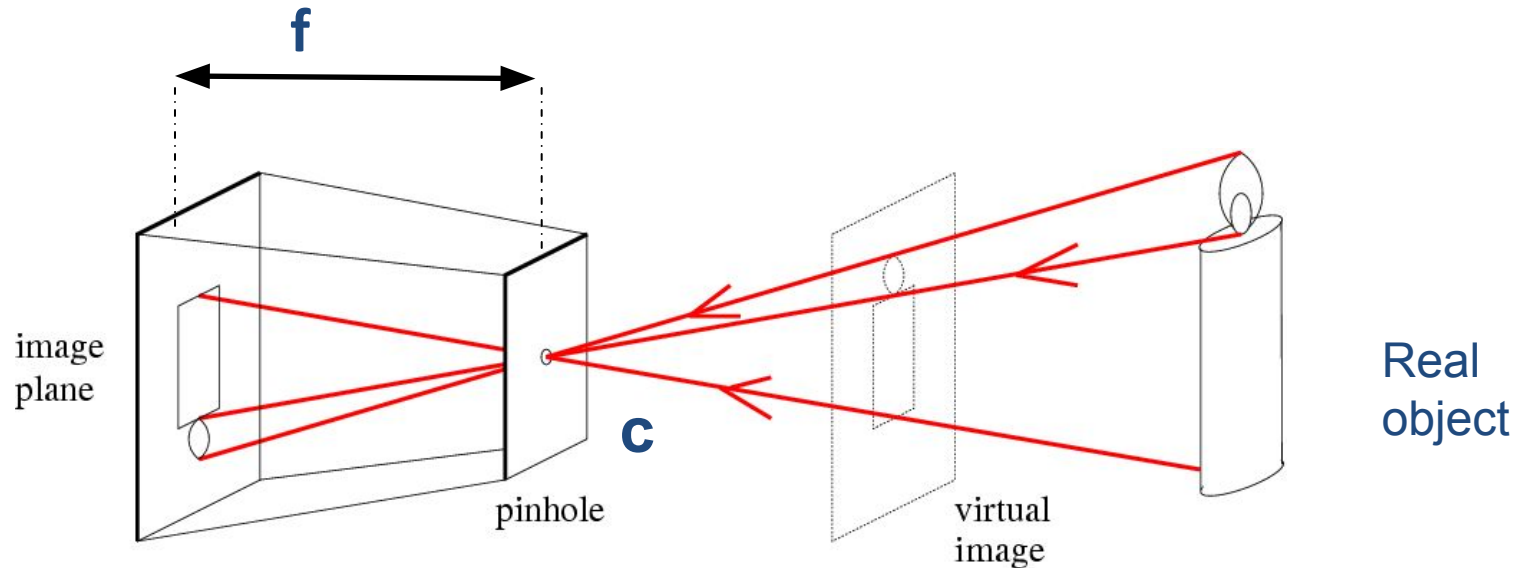
Let's design a camera

Idea 2: Add a barrier to block most rays

- Pinhole in barrier
- Only sense light from one direction.
 - Reduces blurring.
- In most cameras, this **aperture** can vary in size.



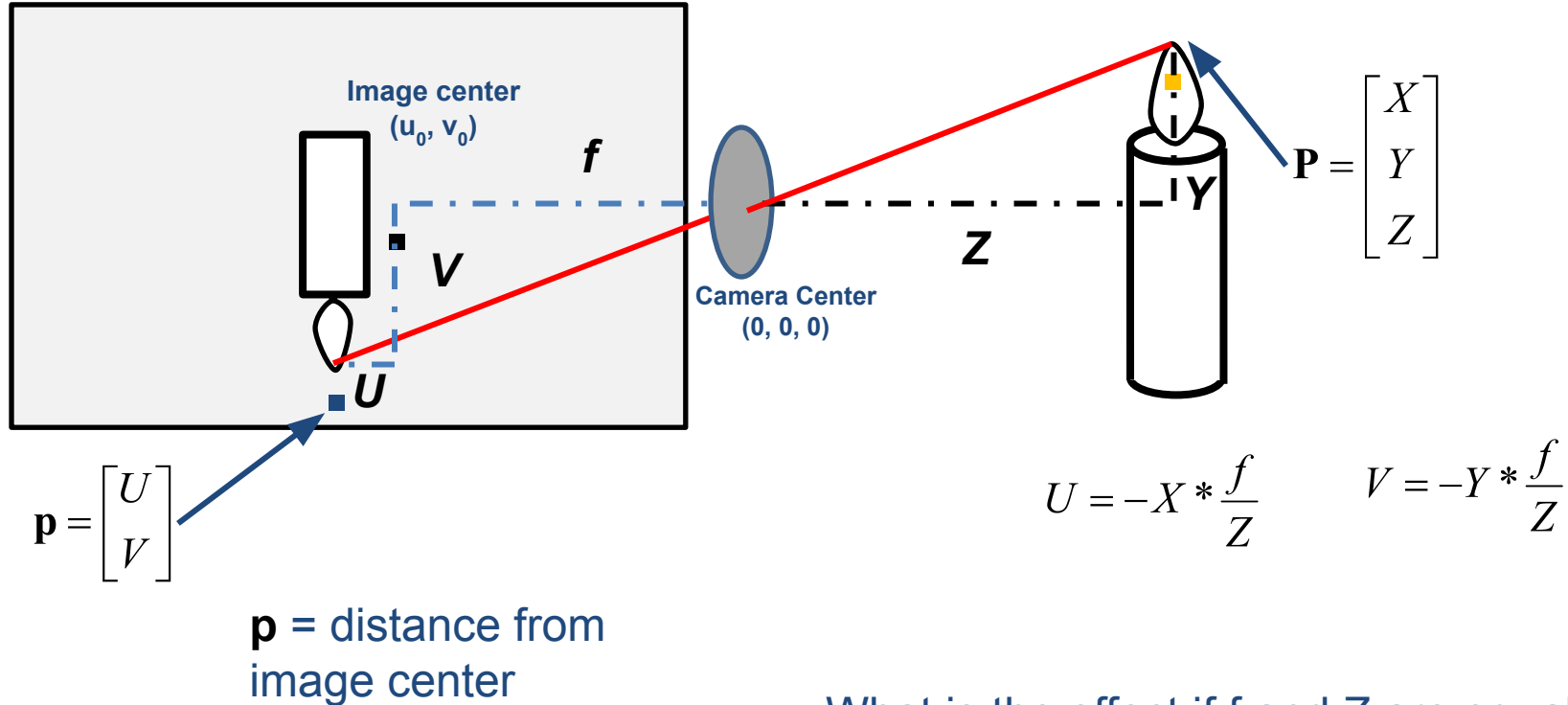
Pinhole camera model



f = Focal length

C = Optical center of the camera

Projection: world coordinates \rightarrow image coordinates



What is the effect if f and Z are equal?