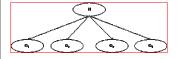


10-701/15-781, Spring 2008

Naïve Bayes Classifier

Eric Xing
Lecture 3, January 23, 2008

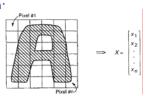




Reading: Chap. 4 CB and handouts

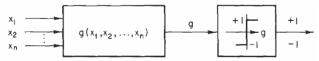
Classification

Representing data



P(Y) 1°(X1Y)

• Choosing hypothesis class



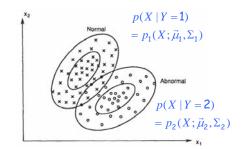
- Learning: h:X → Y
 - X features
 - Y target classes

Suppose you know the following



. . .

Classification-specific Dist.: P(X|Y)



Bayes classifier:

 $T(P,k) \gtrsim T(P,k)$ $h_g(x) = \ln \frac{P}{P_n} \gtrsim \frac{\pi}{R_n}$

• Class prior (i.e., "weight"): P(Y)

• This is a generative model of the data!

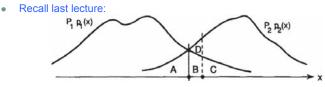
Optimal classification



• Theorem: Bayes classifier is optimal!

• That is $error_{true}(h_{Bayes})) \leq error_{true}(h), \ \forall h(\mathbf{x})$

• Proof:



• How to learn a Bayes classifier?

Recall Bayes Rule



$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$$

Which is shorthand for:

$$(\forall i, j) P(Y = y_i | X = x_j) = \frac{P(X = x_j | Y = y_i) P(Y = y_i)}{P(X = x_j)}$$

Equivalently: (2)

$$(\forall i, j) P(Y = y_i | X = x_j) = \frac{P(X = x_j | Y = y_i) P(Y = y_i)}{\sum_k P(X = x_j | Y = y_k) P(Y = y_k)}$$

Recall Bayes Rule



$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$$

Which is shorthand for:

$$(\forall i, j) P(Y = y_i | X = x_j) = \frac{P(X = x_j | Y = y_i) P(Y = y_i)}{P(X = x_j)}$$

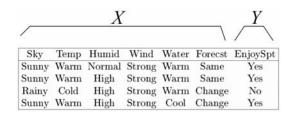
Common abbreviation:

$$(\forall i, j) P(y_i | x_j) = \frac{P(x_j | y_i) P(y_i)}{\sum_k P(x_j | y_k) P(y_k)}$$

Learning Bayes Classifier



• Training data:

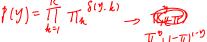


- Learning = estimating P(X|Y), and P(Y)
- Classification = using Bayes rule to calculate P(Y | X_{new})

How hard is it to learn the optimal classifier?

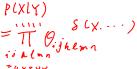


- How do we represent these? How many parameters?
 - Prior, P(Y):
 - Suppose Y is composed of k classes





- Likelihood, P(X|Y):
 - Suppose **X** is composed of *n* binary features





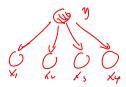
• Complex model! High variance with limited data!!!

Naïve Bayes:



$$P(X_1...X_n|Y) = \prod_{i=1}^{n} P(X_i|Y)$$

assuming that X_i and X_j are conditionally independent given Y, for all $i \neq j$





Conditional Independence



 X is conditionally independent of Y given Z, if the probability distribution governing X is independent of the value of Y, given the value of Z

$$(\forall i, j, k) P(X = i | Y = j, Z = k) = P(X = i | Z = k)$$

Which we often write

$$P(X \mid Y, Z) = P(X \mid Z)$$

e.g.,

P(Thunder|Rain, Lightning) = P(Thunder|Lightning)

• Equivalent to:

$$P(X, Y \mid Z) = P(X \mid Z)P(Y \mid Z)$$

The Naïve Bayes assumption



- Naïve Bayes assumption:
 - Features are independent given class:

$$P(X_1, X_2|Y) = P(X_1|X_2, Y)P(X_2|Y)$$

= $P(X_1|Y)P(X_2|Y)$

• More generally:

$$P(X_1...X_n|Y) = \prod_{i} P(X_i|Y_i)$$

- How many parameters now?
- # para = Kn
- Suppose **X** is composed of *n* binary features

The Naïve Bayes Classifier



- Given:
 - Prior P(Y)
 - n conditionally independent features X given the class Y
 - For each X_i, we have likelihood P(X_i|Y)
- Decision rule:

$$y^* = h_{NB}(\mathbf{x}) = \arg \max_{y} P(y)P(x_1, \dots, x_n \mid y)$$
$$= \arg \max_{y} P(y) \prod_{i} P(x_i \mid y)$$

• If assumption holds, NB is optimal classifier!

Naïve Bayes Algorithm



- Train Naïve Bayes (examples)
 - for each* value y_ν
 - estimate $\pi_k \equiv P(Y = y_k)$
 - for each* value x_{ij} of each attribute $X_i \in [0, \dots, M]$.
 - estimate $\theta_{ijk} \equiv P(X_i = x_{ij}|Y = y_k)$
- Classify (X_{new})

$$Y^{new} \leftarrow \arg\max_{y_k} P(Y = y_k) \prod_i P(X_i = x_{ij} | Y = y_k)$$
$$Y^{new} \leftarrow \arg\max_{y_k} \pi_k \prod_i \theta_{ijk}$$

* probabilities must sum to 1, so need estimate only n-1 parameters...

Learning NB: parameter estimation



Maximum Likelihood Estimate (MLE):
 choose θ that maximizes probability of observed data D

$$\hat{\theta} = \arg\max_{\theta} P(\mathcal{D}|\theta)$$

Maximum a Posteriori (MAP) estimate:
 choose θ that is most probable given prior probability and the data

$$\hat{\theta} = \arg \max_{\theta} P(\theta|\mathcal{D})$$

$$= \arg \max_{\theta} \frac{P(\mathcal{D}|\theta)\mathcal{P}(\theta)}{P(\mathcal{D})}$$

$$\hat{\mathcal{D}}_{xyx} = \int \mathcal{P}(\theta|\mathcal{D}) d\theta$$

MLE for the parameters of NB



Discrete features:

- Maximum likelihood estimates (MLE's): $\hat{\theta} = \arg\max_{\alpha} P(\mathcal{D}|\theta)$
- Given dataset
 - (Count(A=a,B=b) € number of examples where A=a and B=b

$$\begin{array}{lll} \left(\overline{\Pi} \right) = p\left(\underline{Y} \right) = \overline{\prod} \prod_{i=1}^{N} \overline{\Pi}_{k} & \text{obj.} & \text{obj.} & \text{obj.} \\ \left(\overline{\Pi} \right) = \ln p|\underline{Y} \right) & = \sum_{i:k} \delta\left(\underline{y}_{i} \cdot \underline{k} \right) \log \overline{\Pi}_{k}. & \overline{\Pi}_{k} = \frac{Count}{N} \left(\underline{Y} = \underline{k} \right) \\ & = \sum_{i:k} \delta\left(\underline{y}_{i} \cdot \underline{k} \right) \log \overline{\Pi}_{k}. & \overline{\Pi}_{k} = \frac{Count}{N} \left(\underline{X}_{i} = \underline{j}, \underline{y} = \underline{k} \right) \\ & = \sum_{i:k} \delta\left(\underline{y}_{i} \cdot \underline{k} \right) \log \overline{\Pi}_{k}. & \overline{\Pi}_{k} = \frac{Count}{N} \left(\underline{X}_{i} = \underline{j}, \underline{y} = \underline{k} \right) \\ & = \sum_{i:k} \delta\left(\underline{y}_{i} \cdot \underline{k} \right) \log \overline{\Pi}_{k}. & \overline{\Pi}_{k} = \frac{Count}{N} \left(\underline{X}_{i} = \underline{j}, \underline{y} = \underline{k} \right) \end{array}$$

Subtleties of NB classifier 1 – Violating the NB assumption



- Often the X_i are not really conditionally independent
- We use Naïve Bayes in many cases anyway, and it often works pretty well
 - often the right classification, even when not the right probability (see [Domingos&Pazzani, 1996])
 - But the resulting probabilities $P(Y|X_{new})$ are biased toward 1 or 0 (why?)

Subtleties of NB classifier 2 – Insufficient training data



- What if you never see a training instance where X₁₀₀₀=a when Y=b?
 - e.g., Y={SpamEmail or not}, X₁₀₀₀={'Rolex'}
 - $P(X_{1000}=T \mid Y=T)=0$
- Thus, no matter what the values X₂,...,X_n take:
 - $P(Y=T \mid X_1, X_2, ..., X_{1000} = T, ..., X_n) = 0$

• What now???

$$\theta_{vk} = \frac{c(y)^{2v} + \frac{1}{4}}{c(y)}$$

MAP for the parameters of NB



Discrete features:

• Maximum a Posteriori (MAP) estimate: (MAP's):

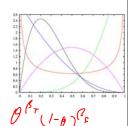
$$\hat{\theta} = \arg \max_{\theta} \frac{P(\mathcal{D}|\theta)P(\theta)}{P(\mathcal{D})}$$

- Given prior:
 - Consider binary feature
 - θ is a Bernoulli rate

$$\underline{P(\theta; \alpha_T, \alpha_F)} = \frac{\Gamma(\alpha_T + \alpha_F)}{\Gamma(\alpha_T)\Gamma(\alpha_F)} \theta^{\alpha_T - 1} (1 - \theta)^{\alpha_F - 1} = \frac{\theta^{\alpha_T - 1} (1 - \theta)^{\alpha_F - 1}}{B(\alpha_T, \alpha_F)}$$

• Let β_a =Count(X=a) = number of examples where X=a

$$P(\theta \mid \mathcal{D}) = \frac{\theta^{\beta_T + \alpha_T - 1} (1 - \theta)^{\beta_F + \alpha_F - 1}}{B(\beta_T + \alpha_T, \beta_F + \alpha_F)} \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$



Bayesian learning for NB parameters - a.k.a. smoothing



Posterior distribution of θ

$$P(D(0) = 10^{47} (1-10)^{47}$$
 $0^{4} = \frac{47}{100}$

- $P(\theta \mid \mathcal{D}) = \frac{\theta^{\beta_T + \alpha_T 1} (1 \theta)^{\beta_F + \alpha_F 1}}{B(\beta_T + \alpha_T, \beta_F + \alpha_F)} \sim Beta(\beta_T + \alpha_T, \beta_T + \alpha_F)$
- $P(\theta \mid \mathcal{D}) = \frac{\prod_{j=1}^{K} \theta_{j}^{\beta_{j} + \alpha_{j} 1}}{B(\beta_{1} + \alpha_{1}, \dots, \beta_{K} + \alpha_{K})} \sim Dirichlet(\beta_{1} + \alpha_{1}, \dots, \beta_{K} + \alpha_{K})$ $\widehat{\theta}_{Ryp} = \underbrace{\widehat{\theta}_{7} + \widehat{\theta}_{7}}_{P + \theta_{7}} + \underbrace{\widehat{\theta}_{7} + \widehat{\theta}_{7}}_{P + \theta_{7}} + \underbrace{\widehat{\theta}_{7} + \widehat{\theta}_{7}}_{P + \theta_{7}}$
- MAP estimate:

$$\hat{\theta} = \arg \max_{\theta} P(\theta|\mathcal{D}) = \frac{\beta_{\tau} + \delta_{\tau} - 1}{(\beta_{\tau} + \delta_{\tau} - 1) + (\beta_{F} + \delta_{F} - 1)} \Rightarrow \frac{\beta_{\tau}}{\beta_{\tau} + \delta_{\tau}}$$

Beta prior equivalent to extra thumbtack flips

$$N = \beta_7 + \beta_F$$

- As $N \rightarrow \infty$ prior is "forgotten"
- But, for small sample size, prior is important!

MAP for the parameters of NB



- Dataset of N examples
 - Let β_{iab} =Count(X_i=a,Y=b) = number of examples where X_i=a and Y=b
 - Let γ_b=Count(Y=b)
- Prior

 $Q(X_i|Y) \propto Multinomial(\alpha_{i1}, ..., \alpha_{iK})$ or $Multinomial(\alpha/K)$ $Q(Y) \propto Multinomial(\tau_{iI}, ..., \tau_{iM})$ or $Multinomial(\tau/M)$

m "virtual" examples

MAP estimate

$$\hat{\pi}_k = \arg \max_{\pi_k} \prod_k P(Y = y_k; \pi_k) P(\pi_k | \vec{\tau}) = ?$$

$$\hat{\theta}_{ijk} = \arg \max_{\theta_{ijk}} \prod_j P(X_i = x_{ij} | Y = y_k; \theta_{ijk}) P(\theta_{ijk} | \vec{\alpha}_{ik}) = ?$$

Now, even if you never observe a feature/class, posterior probability never zero

Text classification



- · Classify e-mails
 - Y = {Spam,NotSpam}
- · Classify news articles
 - Y = {what is the topic of the article?}
- Classify webpages
 - Y = {Student, professor, project, ...}
- What about the features X?
 - The text!

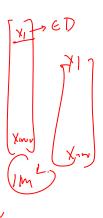
Features X are entire document – X_i for ith word in article



Article from rec.sport.hockey

Path: cantaloupe.srv.cs.cmu.edu!das-news.harvard.eFrom: xxx@yyy.zzz.edu (John Doe)
Subject: Re: This year's biggest and worst (opinic Pate: 5 Apr 93 09:53:39 GMT

I can only comment on the Kings, but the most obvious candidate for pleasant surprise is Alex Zhitnik. He came highly touted as a defensive defenseman, but he's clearly much more than that. Great skater and hard shot (though wish he were more accurate). In fact, he pretty much allowed the Kings to trade away that huge defensive liability Paul Coffey. Kelly Hrudey is only the biggest disappointment if you thought he was any good to begin with. But, at best, he's only a mediocre goaltender. A better choice would be Tomas Sandstrom, though not through any fault of his own, but because some thugs in Toronto decided



NB for Text classification



- P(X|Y) is huge!!!
 - Article at least 1000 words, **X**={X₁,...,X₁₀₀₀}
 - X_i represents ith word in document, i.e., the domain of X_i is entire vocabulary, e.g., Webster Dictionary (or more), 10,000 words, etc.
- NB assumption helps a lot!!!
 - $P(X_i=x_i|Y=y)$ is just the probability of observing word x_i in a document on topic y

$$h_{NB}(\mathbf{x}) = \arg \max_{y} P(y) \prod_{i=1}^{LengthDoc} P(x_i|y)$$

Bag of words model



- Typical additional assumption Position in document doesn't matter: P(X_i=x_i|Y=y) = P(X_k=x_i|Y=y)
 - "Bag of words" model order of words on the page ignored
 - Sounds really silly, but often works very well!

$$P(y) \prod_{i=1}^{LengthDoc} P(x_i|y)$$

When the lecture is over, remember to wake up the person sitting next to you in the lecture room.

Bag of words model

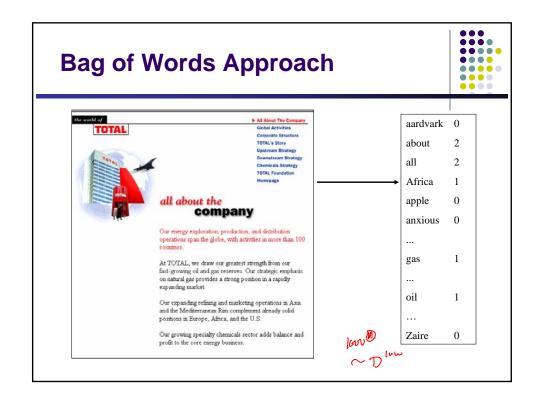


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$$P(y) \prod_{i=1}^{LengthDoc} P(x_i|y)$$

= \(\text{\text{X}}_{\text{\text{y}}} \)

in is lecture lecture next over person remember room sitting the the to to up wake when you



NB with Bag of Words for text classification



- Learning phase:
 - Prior P(Y)
 - Count how many documents you have from each topic (+ prior)
 - P(X_i|Y)
 - For each topic, count how many times you saw word in documents of this topic (+ prior)
- Test phase:
 - For each document
 - Use naïve Bayes decision rule

$$h_{NB}(\mathbf{x}) = \arg \max_{y} P(y) \prod_{i=1}^{LengthDoc} P(x_i|y)$$

Twenty News Groups results



Given 1000 training documents from each group Learn to classify new documents according to which newsgroup it came from

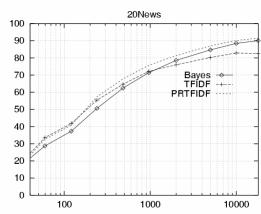
comp.graphics misc.forsale
comp.os.ms-windows.misc
comp.sys.ibm.pc.hardware
comp.sys.mac.hardware
comp.windows.x misc.forsale
rec.autos
rec.motorcycles
rec.sport.baseball
rec.sport.hockey

alt.atheism sci.space
soc.religion.christian sci.crypt
talk.religion.misc sci.electronics
talk.politics.mideast
talk.politics.misc
talk.politics.guns

Naive Bayes: 89% classification accuracy

Learning curve for Twenty News Groups





Accuracy vs. Training set size (1/3 withheld for test)

What if we have continuous X_i ?



• Eg., character recognition: X_i is ith pixel





• Gaussian Naïve Bayes (GNB):

ssian Naïve Bayes (GNB):
$$P(X_i = x \mid Y = y_k) = \frac{1}{\sigma_{ik}\sqrt{2\pi}} e^{\frac{-(x-\mu_{ik})^2}{2\sigma_{ik}^2}}$$
The mest assume variance rependent of Y (i.e., σ_i), and the state of Y (i.e., σ_i), and the state of Y (i.e., σ_i),

Sometimes assume variance

- is independent of Y (i.e., σ_i),
- or independent of X_i (i.e., σ_k)
- or both (i.e., σ)

Estimating Parameters: Y discrete, Xi continuous



Maximum likelihood estimates:

$$\hat{\mu}_{ik} = \frac{1}{\sum_{j} \delta(Y^j = y_k)} \sum_{j} X_i^j \delta(Y^j = y_k)$$

$$\hat{\sigma}_{ik}^2 = \frac{1}{\sum_j \delta(Y^j = y_k) - 1} \sum_j (X_i^j - \hat{\mu}_{ik})^2 \delta(Y^j = y_k)$$

Gaussian Naïve Bayes



$$P(y|y) = \frac{P(x|y)P(y)}{P(x)} = \frac{\pi_{k} \pi_{k} \pi_{k} \pi_{k} \pi_{k} \pi_{k}}{\sum_{i \neq j} N(x_{i} \mid M_{i}, \sigma_{i}^{2})}$$

$$= \frac{\pi_{i} \pi_{k} \pi_{k} \pi_{k} \pi_{k} \pi_{k}}{\prod_{i \neq j} \sum_{j \neq j} \sum_{i \neq j} \sum_{j \neq j} \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}}$$

$$= \frac{1}{1 + \frac{\pi_{i}}{\pi_{k}} p_{i} \left(\frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}} + \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}\right)}$$

$$= \frac{1}{1 + \frac{\pi_{i}}{\pi_{k}} p_{j} \left(\frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}} + \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}\right)}$$

$$= \frac{1}{1 + \frac{\pi_{i}}{\pi_{k}} p_{j} \left(\frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}} + \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}\right)}$$

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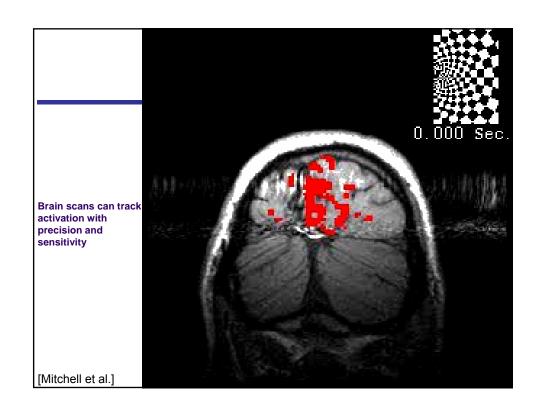
$$= \frac{1}{1 + \frac{\pi_{i}}{\pi_{k}} p_{j} \left(\frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}} + \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}\right)}$$

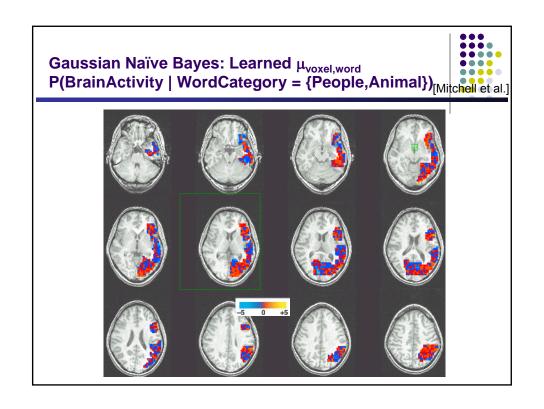
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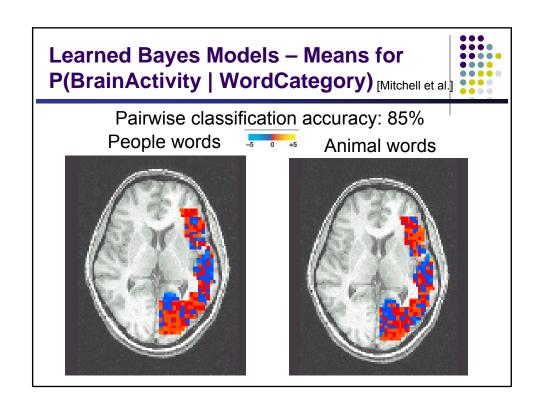
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$$= \frac{1}{1 + \frac{\pi_{i}}{\pi_{k}} p_{j} \left(\frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}} + \frac{(x_{i} \cdot M_{i})^{2}}{2\sigma_{i}^{2}}\right)}$$

Example: GNB for classifying mental states [Mitchell et al.] -1 mm resolution -2 images per sec. 15,000 voxels/image non-invasive, safe measures Blood Oxygen Level Dependent (BOLD) response Typical impulse response







What you need to know about Naïve Bayes



- Optimal decision using Bayes Classifier
- Naïve Bayes classifier
 - What's the assumption
 - Why we use it
 - How do we learn it
 - Why is Bayesian estimation important
- Text classification
 - Bag of words model
- Gaussian NB
 - Features are still conditionally independent
 - Each feature has a Gaussian distribution given class