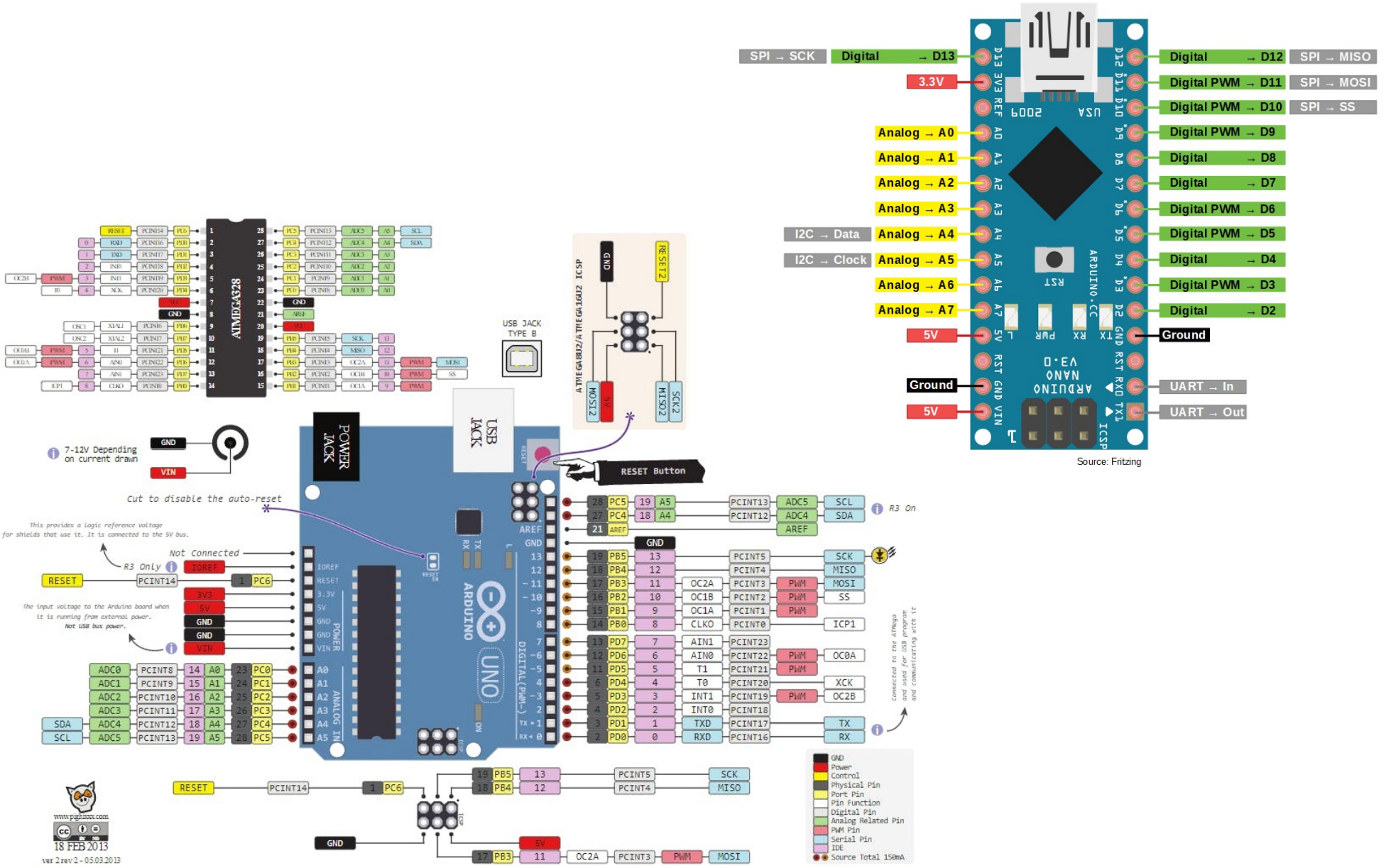
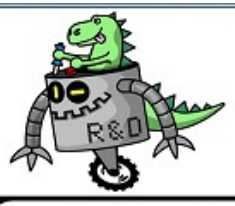


Source: Fritzing

Arduino Cheat Sheet V.02b

Mostly taken from the extended reference:
http://arduino.cc/en/Reference/Extended
Gavin Smith – Robots and Dinosaurs, The Sydney Hackspace



Structure

```
void setup()   void loop()
```

Control Structures

```
if (x<5){  } else {  }
switch (myvar) {
   case 1:
     break;
   case 2:
     break;
   default:
}
for (int i=0; i <= 255; i++){   }
while (x<5){  }
do {  } while (x<5);
continue; //Go to next in do/for/while loop
return x; // Or 'return;' for voids.
goto          // considered harmful :-)
```

Further Syntax

```
// (single line comment)
/*  (multi-line comment) */
#define DOZEN 12 //Not baker's!
#include <avr/pgmspace.h>
```

General Operators

```
= (assignment operator)
+  (addition)          - (subtraction)
* (multiplication)  / (division)
% (modulo)
== (equal to)        != (not equal to)
< (less than)        > (greater than)
<= (less than or equal to)
>= (greater than or equal to)
&& (and)     || (or)      ! (not)
```

Pointer Access

```
& reference operator
* dereference operator
```

Bitwise Operators

```
& (bitwise and)  | (bitwise or)
^ (bitwise xor) ~ (bitwise not)
<< (bitshift left)   >> (bitshift right)
```

Compound Operators

```
++ (increment)     -- (decrement)
+= (compound addition)
-= (compound subtraction)
*= (compound multiplication)
/= (compound division)
&= (compound bitwise and)
|= (compound bitwise or)
```

Constants

```
HIGH | LOW
INPUT | OUTPUT
true | false
143 // Decimal number
0173 // Octal number
B11011111 //Binary (8-bits only)
0x7B // Hex number
7U // Force unsigned
10L // Force long
15UL // Force long unsigned
10.0 // Forces floating point
2.4e5 // 245,000
```

Data Types

```
void
boolean          (0, 1, false, true)
char   (e.g. 'a' -128 to 127)
unsigned char (0 to 255)
byte   (0 to 255)
int      (-32,768 to 32,767)
unsigned int (0 to 65535)
word   (0 to 65535)
long          (-2,147,483,648 to
               2,147,483,647)
unsigned long (0 to 4,294,967,295)
float          (-3.4028235E+38 to
               3.4028235E+38)
double (currently same as float)
sizeof(myint) // returns 2 bytes
```

Strings

```
char S1[15];
char S2[8]={'a','r','d','u','i','n','o'};
char S3[8]={'a','r','d','u','i','n','o','\0'};
   //Included \0 null termination
char S4[ ] = "arduino";
char S5[8] = "arduino";
char S6[15] = "arduino";
```

Arrays

```
int myInts[6];
int myPins[] = {2, 4, 8, 3, 6};
int mySensVals[6] = {2, 4, -8, 3, 2};
```

Conversion

```
char()          byte()
int()           word()
long()          float()
```

Qualifiers

```
static  // persists between calls
volatile     // use  RAM (nice for ISR)
const  // make read-only
PROGMEM // use flash
```

Digital I/O

```
pinMode(pin, [INPUT,OUTPUT])
digitalWrite(pin, value)
int digitalRead(pin)
//Write High to inputs to use pull-up res
```

Analog I/O

```
analogReference([DEFAULT,INTERNAL,EXTERNAL])
int analogRead(pin) //Call twice if
switching pins from high Z source.
analogWrite(pin, value) // PWM
```

Advanced I/O

```
tone(pin, freqhz)
tone(pin, freqhz ,duration_ms)
noTone(pin)
shiftOut(dataPin, clockPin,
[MSBFIRST,LSBFIRST], value)
unsigned long pulseIn(pin, [HIGH,LOW])
```

Time

```
unsigned long millis() // 50 days overflow.
unsigned long micros() // 70 min overflow
delay(ms)
delayMicroseconds(us)
```

Math

```
min(x, y)     max(x, y)      abs(x)
constrain(x, minval, maxval )
map(val, fromL, fromH, toL, toH)
pow(base, exponent)  sqrt(x)
sin(rad)      cos(rad)       tan(rad)
```

Random Numbers

```
randomSeed(seed) // Long or int
long random(max)
long random(min, max)
```

Bits and Bytes

```
lowByte()          highByte()
bitRead(x,bitn)    bitWrite(x,bitn,bit)
bitSet(x,bitn)     bitClear(x,bitn)
bit(bitn) //bitn:  0-LSB 7-MSB
```

External Interrupts

```
attachInterrupt(interrupt, function,
[LOW,CHANGE,RISING,FALLING])
detachInterrupt(interrupt)
interrupts()
noInterrupts()
```

Libraries:

Serial.

```
begin([300, 1200, 2400, 4800, 9600,
14400, 19200, 28800, 38400, 57600,
115200])
end()
int available()
int read()
flush()
print()
println()
write()
```

EEPROM (#include <EEPROM.h>)

```
byte read(intAddr)
     write(intAddr,myByte)
```

Servo (#include <Servo.h>)

```
attach(pin , [min_uS, max_uS])
write(angle) // 0-180
writeMicroseconds(uS) //1000-2000,
 1500 is midpoint
read() // 0-180
attached() //Returns boolcan
detach()
```

SoftwareSerial(RxPin,TxPin)

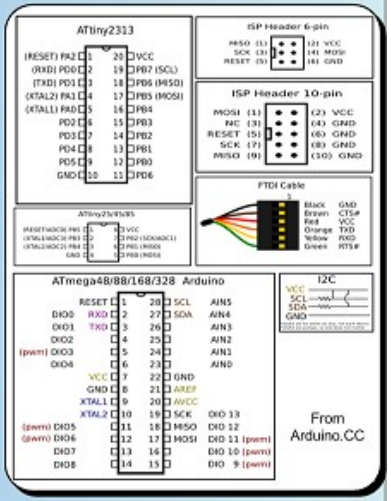
```
// #include<SoftwareSerial.h>
begin(longSpeed) // up to 9600
char read() // blocks till data
print(myData) or println(myData)
```

Wire (#include <Wire.h>) // For **I2C**

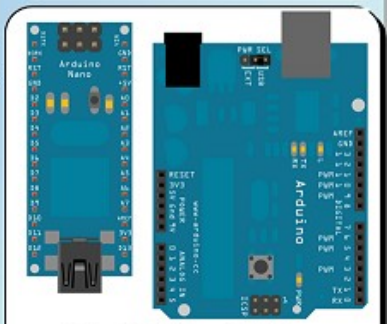
```
begin()          // Join as master
begin(addr) // Join as slave @ addr
requestFrom(address, count)
beginTransmission(addr) // Step 1
send(mybyte)          // Step 2
send(char * mystring)
send(byte * data, size)
endTransmission()     // Step 3
byte available() // Num of bytes
byte receive() //Return next byte
onReceive(handler)
onRequest(handler)
```

	ATMega168	ATMega328	ATmega1280
Flash [2k for bootloader)	16kB	32kB	128kB
SRAM	1kB	2kB	8kB
EEPROM	512B	1kB	4kB

	Duemilanove/ Nano/ Pro/ ProMini	Mega
# of IO	14 + 6 analog (Nano has 14+8)	54 + 16 analog
Serial Pins	0 - RX 1 - TX	0 - RX1 1 - TX1 19 - RX2 18 - TX2 17 - RX3 16 - TX3 15 - RX4 14 - TX4
Ext Interrupts	2 - (Int 0) 3 - (Int 1)	2,3,21,20,19,18 (IRQ0- IRQ5)
PWM pins	5,6 - Timer 0 9,10 - Timer 1 3,11 - Timer 2	0-13
SPI	10 - SS 11 - MOSI 12 - MISO 13 - SCK	53 - SS 51 - MOSI 50 - MISO 52 - SCK
I2C	Analog4 - SDA Analog5 - SCK	20 - SDA 21 - SCL



From Arduino.CC



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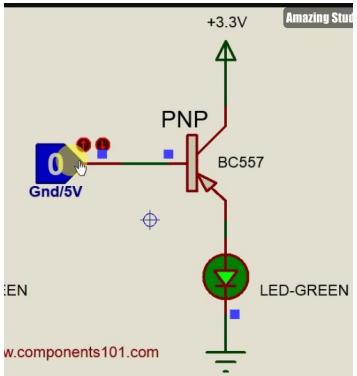
+3.3V
PNP
BC557
Gnd/5V
LED-GREEN
w.components101.com