https://www.reddit.com/r/ControlTheory/comments/15zsyz6/lecture_series_related_to_probabilistic_robotics/?rdt=46242

SLAM course - https://www.youtube.com/playlist?list=PLgnQpQtFTOGQrZ4O5QzbIHgl3b1JHimN_

Factor Graphs intro - https://gtsam.org/2020/06/01/factor-graphs.html

Control Theory mini lectures - https://youtube.com/playlist?list=PLMrJAkhIeNNR20Mz-VpzgfQs5zrYi085m&si=GucQGg7sCX2Z5tVM

Kalman Filter big - https://www.kalmanfilter.net/

SLAM with programming - https://youtube.com/playlist?list=PLpUPoM7Rgzi_7YWn14Va2FODh7LzADBSm&si=RSUCbvAzyusSnQHV

Intuitive Introductory Texts for Baysian and Kalman Filters with Notebook - https://github.com/rlabbe/Kalman-and-Bayesian-Filters-in-Python