

Workshop on

Domain-Specific Languages for Performance-Portable Weather and Climate Models





Content:

Basic Concepts II

(horizontal dependencies, temporaries, backends & performance)

Presenter:

Tobias Wicky

Learning goals for this session

- Understand the GT4Py execution model
- Understand how horizontal loop bounds work
- Hands-on with different backends and performance

Execution Model (aka "Parallel Model")

The **execution model** specifies the behavior of elements of a programming language.

By applying the execution model, one can derive the behavior of a program that was written in that programming language.

When "reading code", we essentially apply the execution model to the code.

See https://github.com/GridTools/concepts/wiki/GTScript-Parallel-model

Execution Model: Vertical

GT4Py

Python pseudocode

```
for k_ in random.sample(range(k, K)):
  b[i:I, j:J, k_] = a[i:I, j:J, k_]
```

- PARALLEL computation has no specified order in k
- Other vertical loop orders exist (see later!)
- Data races can occur

Execution Model: Vertical

GT4Py

```
@stencil(backend=backend)
def vertical_sum( a: Field[float]):
    with computation(PARALLEL), interval(...):
        a = a[0, 0, -1]
```

Python pseudocode

- PARALLEL computation has no specified order in k
- Other vertical loop orders exist (see later!)
- Data races can occur

Race condition! (GT4Py will issue an error)

Execution Model: Horizontal

GT4Py

Python pseudocode

```
for k_ in range(k, K):
  b[i:I, j:J, k_] = 0.5 * (
    a[i+1:I+1, j:J, k_] +
    a[i-1:I-1, j:J, k_]
)
```

- Horizontal (ij-direction) execution policy for a single statement is always parallel
- Data-races can occur with horizontal dependencies

Execution Model: Horizontal

GT4Py

Python pseudocode

- Horizontal (ij-direction) execution policy for a single statement is always parallel
- Data-races can occur with horizontal dependencies

Execution Model: Summary

- computations are executed sequentially in the order they appear in the code
- vertical intervals are executed sequentially in the order defined by the iteration policy of the computation
- every vertical interval is executed as a sequential for-loop over the K-range following the order defined by the iteration policy

Note: The DSL compiler often catches unsafe / illegal code, but checks are not complete.

Horizontal Compute Domains

GT4Py

Python pseudocode

```
for k_ in range(k, K):
    a[i-1:I+1, j:J, k_] = 1.
    b[i:I, j:J, k_] = 0.5 * (
        a[i+1:I+1, j:J, k_] +
        a[i-1:I-1, j:J, k_]
)
```

- Horizontal (ij-direction) execution policy for a single statement is always parallel
- Horizontal loop bounds are deduced automatically

Horizontal loops are deduced automatically by dependency and offset analysis.

Horizontal Compute Domains

GT4Py

Python pseudocode

```
for k_ in range(k, K):
  b[i:I, j:J, k_] = 0.5 * (
    a[i+1:I+1, j:J, k_] +
    a[i-1:I-1, j:J, k_]
)
  a[i:I, j:J, k_] = 1.
```

- Horizontal (ij-direction) execution policy for a single statement is always parallel
- Horizontal loop bounds are deduced automatically

Horizontal loops are deduced automatically by dependency and offset analysis.

Horizontal Compute Domains: Example

```
def c sw(...):
 with computation(PARALLEL), interval(...):
   ut = dt2 * ut * dy * sin sq3[-1, 0, 0]
   vt = dt2 * vt * dx * sin sq4[0, -1, 0]
   delpc = upwind step(delp, ut, vt, rarea, 1., 1.)
   ptc = upwind step(pt, ut, vt, rarea, delp, delpc)
   wc = upwind step(w, ut, vt, rarea, delp, delpc)
   # compute kinetic energy (ke)
   ucc = uc[1, 0, 0]
   vcc = vc[0, 1, 0]
   ke = 0.5 * dt2 * (ua * ucc + va * vcc)
                                                          [(-1, 0), (-1, 0)]
   # compute absolute vorticity (vort)
   fx = uc * dxc
   fy = vc * dyc
   vort = fx[0, -1, 0] - fx - fy[-1, 0, 0] + fy
   vort = fc + rarea c * vort
   # transport absolute vorticity
   fy1 = dt2 * (v - uc * cosa u) / sina u
                                                           [(0, 0), (-1, 0)]
   fy = fy1[0, -1, 0]
                                                           [(0, 0), (0, 0)]
   fx1 = dt2 * (u - vc * cosa v) / sina v
                                                           [(-1, 0), (0, 0)]
   fx = fx1[-1, 0, 0]
                                                           [(0, 0), (0, 0)]
   # update time-centered winds on the C-grid
   uc = uc + fy1 * fy + rdxc * (ke[-1, 0, 0] - ke)
                                                           [(0, 0), (0, 0)]
   vc = vc - fx1 * fx + rdyc * (ke[0, -1, 0] - ke)
                                                           [(0, 0), (0, 0)]
```

Temporary Variables (aka "Temporaries")

```
def average_stencil( a: Field[float]):
    with computation(PARALLEL):
    with interval(...):
        tmp = 0.5 * (a[1, 0, 0] + a[-1, 0, 0])
        a = tmp
```

Python pseudocode

```
for k_ in range(k, K):
  tmp[i:I, j:J, k_] = 0.5 * (
    a[i+1:I+1, j:J, k_] +
    a[i-1:I-1, j:J, k_]
)
  a[i:I, j:J, k_] = tmp[i:I, j:J, k_]
```

tmp is a field!

- Use temporaries to store intermediate results and avoid race-conditions
- Temporary variables are automatically typed, dimensioned, and allocated

Temporary variables hold intermediate results in a computation.

Temporary Variables (aka "Temporaries")

```
GT4Py
```

```
def average_stencil( a: Field[float]):
    with computation(PARALLEL):
    with interval(...):
        tmp = 1.
        a = 0.5*(tmp[1, 0, 0] + tmp[-1, 0, 0])
```

Python pseudocode

```
for k__in_range(k, K):
    tmp[i-1:I+1, j:J, k_] = 1.
    a[i:I, j:J, k_] = 0.5 * (
        tmp[i+1:I+1, j:J, k_] +
        tmp[i-1:I-1, j:J, k_]
)
```

tmp is extended in i-direction!

- Use temporaries to store intermediate results and avoid race-conditions
- Temporary variables are automatically typed, dimensioned, and allocated

Horizontal loops are deduced automatically by dependency and offset analysis.

Temporary Variables (aka "Temporaries")

tmp can be a scalar! (if statements are fused)

```
Loop based Python
```

```
for k_ in range(k, K):
    for i_ in range(i, I):
        for j_ in range(j, J):
        tmp = 0.5 * (
            a[i_+1, j_, k_] +
            a[I_-1, j_, k_]
        )
        b[i_, j_, k_] = tmp
```

 Optimizers will fuse loops and choose the most efficient dimensionality and memory location for temporaries

> User should think of temporaries as fields, but their shape may be different in generated code

Temporary Variables: Example

```
def c sw(...):
 with computation(PARALLEL), interval(...):
   ut = dt2 * ut * dy * sin sq3[-1, 0, 0]
   vt = dt2 * vt * dx * sin sq4[0, -1, 0]
   delpc = upwind step(delp, ut, vt, rarea, 1., 1.)
   ptc = upwind step(pt, ut, vt, rarea, delp, delpc)
   wc = upwind step(w, ut, vt, rarea, delp, delpc)
   # compute kinetic energy (ke)
   ucc = uc[1, 0, 0]
   vcc = vc[0, 1, 0]
   ke = 0.5 * dt2 * (ua * ucc + va * vcc)
   # compute absolute vorticity (vort)
   fx = uc * dxc
   fy = vc * dyc
   vort = fx[0, -1, 0] - fx - fy[-1, 0, 0] + fy
   vort = fc + rarea c * vort
   # transport absolute vorticity
   fy1 = dt2 * (v - uc * cosa u) / sina u
   fy = fy1[0, -1, 0]
   fx1 = dt2 * (u - vc * cosa v) / sina v
   fx = fx1[-1, 0, 0]
   # update time-centered winds on the C-grid
   uc = uc + fy1 * fy + rdxc * (ke[-1, 0, 0] - ke)
   vc = vc - fx1 * fx + rdyc * (ke[0, -1, 0] - ke)
```

Backends

















explicit ijk-loops

numpy

gtx86

gtmc
OpenMP for

CUDA blocks and threading in ij-direction

gtcuda

Prototypes

CUDA Kokkos AMD

• • • •

vectorized syntax

ij-blocking

KIJ

OpenMP for

IJK

ij-blocking and

i-vectorization

IJK

storage order

parallelism

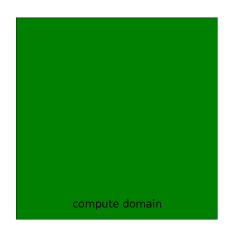
IJK

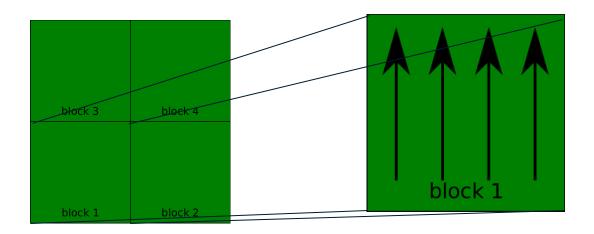
IJK

Backends: Differences

From the execution model:

Horizontal (ij-direction) execution policy for a single statement is always parallel





coarse-grain parallelism

fine-grain parallelism

Backends: Loop-Order

From the execution model: computations are executed sequentially in the order they appear in the code

Backends: Loop-Order

From the execution model: computations are executed sequentially in the order they appear in the code

```
for k_ in range(k, K):
    for i_ in range(i, I):
        for j_ in range(j, J):
        b = 0.5 * (
            a[i_+1, j_, k_] +
            a[I_-1, j_, k_]
        )
```

```
for i_ in range(i, I):
    for j_ in range(j, J):
        for k_ in range(k, K):
        b = 0.5 * (
            a[i_+1, j_, k_] +
            a[I_-1, j_, k_]
        )
```

Hands-on Session

Session-1A.2.ipynb for the following hands-on session

- Apply temporaries
- Investigate runtime and performance
- Understand execution model and storage layouts

See you on Slack! **Next huddle at 11:30 am EST.**