```
#include defiting.bb
#include Keltypa.hb
#incl
```

Threads

Pthread library

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Thread libraries

- It provides the programmer the interface to use the threads
- The management can be done
 - ➤ A user level (by functions)
 - ➤ A kernel level (via system calls)
- The most used thread libraries are
 - POSIX threads
 - ➤ Windows 32/64
 - > Java

Implemented at user and kernel level

Implemented by means of a thread library of the system hosting Java (Pthread POSIX or Windows 32/64)

Implemented at kernel level

Pthreads

- POSIX threads or Pthreads
 - ➤ Is the standard UNIX library for treads
 - IEEE POSIX 1003.1 2004 Edition
 - ➤ Defined for C language, but available in other languages (e.g., FORTRAN)
- Using Pthreads
 - ➤ A thread is a function that is executed in concurrency with the main thread

A process with multiple threads = a set of independently executing functions that share the process resources

Pthreads

- The Pthreads library allows
 - Creating and manipulating threads
 - > Destroying thread
 - Synchronizing threads
 - Protection of resources shared by threads
 - > Thread scheduling
- It defines more than 60 functions
 - > All functions have a pthread_ prefix
 - pthread_equal, pthread_self, pthread_create, pthread_exit, pthread_join, pthread_cancel, pthread_detach

Library linkage

- The Pthread system calls are defined in
 - > pthreads.h
 - > Thus you have to insert in the .c files
 - #include <pthread.h>
 - > Compile your program linking the pthread library
 - gcc -Wall -g -o <exeName> <file.c> -lpthread

Thread Identifier

- A thread is uniquely identified
 - > By a type identifier pthread_t
 - Similar to the PID of a process (pid_t)
 - > The type **pthread_t** is opaque
 - Its definition is implementation dependent
 - Can be used only by functions specifically defined in Pthreads
 - It is not possible compare directly two identifiers or print their values
 - ➤ It has meaning only within the process where the thread is executed
 - Remember that the PID is global within the system

Operating Systems

pthread_equal system call

```
int pthread_equal (
  pthread_t tid1,
  pthread_t tid2,
);
```

- Compares two thread identifiers
- Arguments
 - > Two thread identifiers
- Return value
 - Nonzero if the two threads are equal
 - > Zero otherwise

Operating Systems (Soon I normal del Molan):

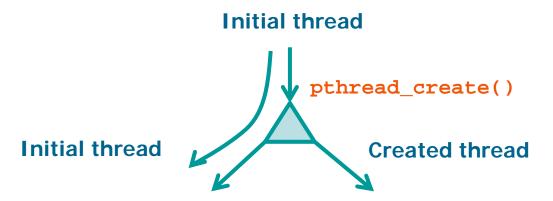
pthread_self system call

```
pthread_t pthread_self ( void );
```

- Returns the thread identifier of the calling thread
 - ▶ It can be used by a thread (with pthread_equal) to self-identify

pthread_create system call

- At run-time a program consists of one process and one thread
- pthread_create allows creating a new thread
 - The maximum number of thread that can be created is undefined and implementation dependent



pthread_create system call

```
int pthread_create (
  pthread_t *tid,
  const pthread_attr_t *attr,
  void *(*startRoutine)(void *),
  void *arg );
```

Arguments

- ➤ Identifier of the generated thread (tid)
- > Thread attributes (attr)
- > NULL is the default attribute
- C function executed by the thread
 (startRoutine)

A **single** argument

- Argument passed to the start routine (arg)
- > **NULL** if no argument

pthread_create system call

```
int pthread_create (
  pthread_t *tid,
  const pthread_attr_t *attr,
  void *(*startRoutine)(void *),
  void *arg
  );
```

- Return value
 - > 0 on success
 - > Error code on failure

pthread_exit system call

- * A process (with all its threads) terminates if
 - Its thread calls exit (or _exit or _Exit)
 - > The main thread execute return
 - ➤ The main thread receives a signal whose action is to terminate
- A single thread can terminate (without affecting the other process threads)
 - > Executing return
 - Executing pthread_exit
 - Receiving a cancellation request performed by another thread using pthread_cancel

Operating Systems

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System call pthread_exit

```
void pthread_exit (
  void *valuePtr
);
```

- It allows a thread to terminate returning a termination status
- Arguments
 - The **ValuePtr** value is kept by the kernel until a thread calls **pthread_join**
 - This value is available to the thread that calls pthread_join

Thread creation

```
void *tF () {
    ...
  pthread_exit (NULL);
}
```

Attributes

Arguments

```
pthread_t tid;
int rc;
rc = pthread_create (&tid, NULL, tF, NULL);
if (rc) {
    // Error ...
    exit (-1);
}

pthread_exit (NULL);
// exit (0);
// return (0); (in main)
Terminates only
the main thread

Terminates the
process
(all its threads)
```

Creation of N threads with 1 argument

```
void *tF (void *par) {
  int *tidP, tid;
  ...
  tidP = (int *) par;
  tid = *tidP;
  ...
  pthread_exit (NULL);
}
```

Collects the tids

```
pthread_t th[NUM_THREADS];
int rc, t;

for (t=0; t<NUM_THREADS; t++) {
   rc = pthread_create (&th[t], NULL, tF,
        (void *) &t);
   if (rc) {...}
}
   Address of t
pthread_exit(NULL);</pre>
```

Creation of N threads with 1 argument

A thread can be executed when t is changed

Creation of N threads with 1 argument

Cast of a value void * ↔ long int

```
void *tF (void *par) {
  long int tid;
  ...
  tid = (long int) par;
  ...
  pthread_exit(NULL);
}
```

Creation of N threads with 1 argument

Cast of vector void * ↔ long int

```
void *tF (void *par) {
  long int tid;
  ...
  tid = (long int) par;
  ...
  pthread_exit(NULL);
}
```

Creation of N threads with 1 argument

Cast of a vector of pointers
void * ↔ int

```
void *tF (void *par) {
  int *tid, taskid;
  ...
  tid = (int *) par;
  taskid = *tid;
  ...
  pthread_exit(NULL);
}
```

```
int tA[NUM_THREADS];
for (t=0; t<NUM_THREADS; t++) {
   tA[t] = t;
   rc = pthread_create (&th[t], NULL, tF,
        (void *) &tA[t]);
   if (rc) { ... }
   The pointer to a
        vector element</pre>
```

Cast to a vector

Creation of N threads with 1 struct

```
struct tS {
  int tid;
  char str[N];
};
```

```
void *tF (void *par) {
  struct tS *tD;
  int tid; char str[L];

tD = (struct tS *) par;
  tid = tD->tid; strcpy (str, tD->str);
...
```

```
pthread_t t[NUM_THREADS];
struct ts v[NUM_THREADS];
...
for (t=0; t<NUM_THREADS; t++) {
  v[t].tid = t;
  strcpy (v[t].str, str);
  rc = pthread_create (&t[t], NULL, tF, (void *) &v[t]);
  ...
}
Address of a struct</pre>
```

Operating Systems

pthread_join system call

- At its creation a thread can be declared
 - > Joinable
 - Another thread may "wait" (pthread_join) for its termination, and collect its exit status
 - Detached
 - No thread can explicitly wait for its termination (not joinable)

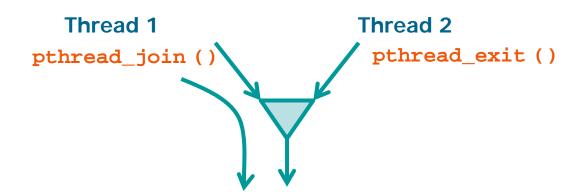
pthread_join system call

- If a thread
 - is joinable, its termination status is retained until another thread performs a pthread_join for that thread
 - is detached its termination status is immediately released
- A thread calling pthread_join waits until the required thread calls phread_exit

pthread_join () system call

```
int pthread_join (
  pthread_t tid,
  void **valuePtr
);
```

Used by a thread to wait the termination of another thread



pthread_join system call

```
int pthread_join (
  pthread_t tid,
  void **valuePtr
);
```

valuePtr can be set to **NULL** if you are not interested in the return value

Arguments

- ➤ Identifier (tid) of the waited-for thread
- The void pointer **ValuePtr** will obtain the value returned by thread **tid**
 - Returned by pthread_exit
 - Returned by return
 - PTHREAD_CANCELED if the thread was deleted

pthread_join () system call

```
int pthread_join (
  pthread_t tid,
  void **valuePtr
);
```

Return value

- > 0 on success
- > Error code on failure
 - If the thread was detached pthread_join should fail
 - If it fails, it returns the constant **EINVAL** or **ESRCH**

Returns the exit status (tid in this example)
Tricky: tid is an int

```
void *tF (void *par) {
  long int tid;
  ...
  tid = (long int) par;
  ...
  pthread_exit ((void *) tid);
}
```

```
void *status;
long int s;
...
/* Wait for threads */
for (t=0; t<NUM_THREADS; t++) {
   rc = pthread_join (th[t], &status);
   s = (long int ) status;
   if (rc) { ... }
}
...</pre>
Waits each thread,
and collects its exit
status
```

```
Use of a
                                            shared global
int myglobal;
                                              variable
void *threadF (void *arg) {
                                     The global variable is
  int *argc = (int *) arg;
                                       incremented by
  int i, j;
  for (i=0; i<20; i++) {
                                     means of a copy on
    j = myglobal;
    j = j + 1;
    printf ("t");
                                        The thread can sleep
    if (*argc > 1) sleep (1);
    myglobal = j;
                                              or not
  printf ("(T:myglobal=%d)", myglobal);
  return NULL;
```

```
int main (int argc, char *argv[]) {
  pthread_t mythread;
  int i;
  pthread_create (&mythread, NULL, threadF, &argc);
  for (i=0; i<20; i++) {
    myglobal = myglobal + 1;
    printf ("m");
    sleep (1);
  }
  pthread_join (mythread, NULL);
  printf ("(M:myglobal=%d)", myglobal);
  exit (0);
}</pre>
```

The thread executes immediately No loss of increments

Example

Thread and main thread alternates their execution every second. The increments of the thread are lost

> ./pgrm 1
mtmtmtmtmtmtmtmtmtmtmtmtmtmtmtmtmt(T:myglobal=21)
M:myglobal=21)

2sec waiting for the main thread Only some increments are lost

> ./pgrm 1
mttmttmttmttmttmttmttmttm(T:myglobal=21)mmmmmmm
m(M:myglobal=30)

pthread_cancel system call

```
int pthread_cancel (
  pthread_t tid
);
```

- Terminates the target thread
 - The effect is similar to a call to pthread_exit(PTHREAD_CANCELED) performed by the target thread
- The thread calling pthread_cancel does not wait for termination of the target thread (it continues)

pthread_cancel() system call

```
int pthread_cancel (
  pthread_t tid
);
```

- Arguments
 - > Target thread (tid) identifier
- Return value
 - > 0 on success
 - > Error code on failure

pthread_detach system call

```
int pthread_detach (
  pthread_t tid
);
```

The attribute of the pthread_create allows creating a detached thread

- Declares thread tid as detached
 - ➤ The status information will not be kept by the kernel at the termination of the thread
 - No thread can join with that thread
 - Calls to pthread_join should fail with error code EINVAL or ESRCH

pthread_detach system call

```
int pthread_detach (
  pthread_t tid
);
```

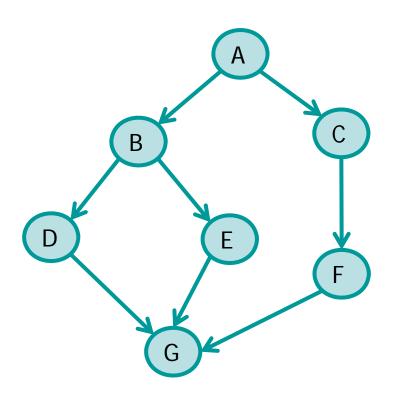
- Arguments
 - > Thread (tid) identifier
- Return value
 - > 0 on success
 - > Error code on failure

```
pthread_t tid;
int rc;
void *status;
rc = pthread_create (&tid, NULL, PrintHello, NULL);
if (rc) { ... }
pthread_detach (tid);
                                          Detach a thread
rc = pthread_join (tid, &status);
if (rc) {
  // Error
  exit (-1);
                               Error if try to join
pthread_exit (NULL);
```

```
Creates a detached
pthread_attr_t attr;
                                           thread using the
void *status;
                                            attribute of
                                          pthread_create
pthread_attr_init (&attr);
pthread_attr_setdetachstate (&attr,
  PTHREAD CREATE DETACHED);
                                          Creates a detached
  //PTHREAD CREATE JOINABLE);
                                               thread
rc = pthread_create (&t[t], &attr, tF, NULL);
if (rc) {...}
                                         Destroys the attribute
                                               object
pthread attr destroy (&attr);
rc = pthread_join (thread[t], &status);
if (rc) {
  // Error
  exit (-1);
                                    Error if try to join
```

Exercise

Implement, using threads, this precedence graph



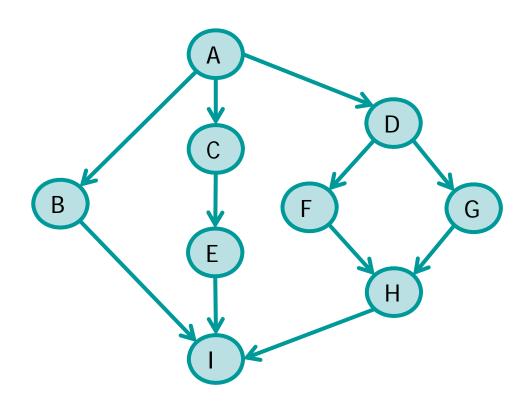
```
void waitRandomTime (int max){
  sleep ((int)(rand() % max) + 1);
int main (void) {
  pthread_t th_cf, th_e;
 void *retval;
  srand (getpid());
 waitRandomTime (10);
 printf ("A\n");
```

```
waitRandomTime (10);
pthread_create (&th_cf,NULL,CF,NULL);
waitRandomTime (10);
printf ("B\n");
waitRandomTime (10);
pthread_create (&th_e,NULL,E,NULL);
waitRandomTime (10);
printf ("D\n");
pthread_join (th_e, &retval);
pthread_join (th_cf, &retval);
waitRandomTime (10);
printf ("G\n");
return 0;
```

```
static void *CF () {
 waitRandomTime (10);
 printf ("C\n");
 waitRandomTime (10);
 printf ("F\n");
 return ((void *) 1); // Return code
static void *E () {
 waitRandomTime (10);
 printf ("E\n");
 return ((void *) 2); // Return code
```

Exercise

Implement, using threads, this precedence graph



Exercise

- Given a text file, passed as an argument of the command line
- ❖ Implement a concurrent program using three threads (T₁, T₂, T₃) that process the file content in pipeline
 - > T₁: Read from file the next character
 - ▶ T₂: Transforms the character read by T₁ in uppercase
 - > T₃: Displays the character produced by T₂

```
static void *GET (void *arg) {
  char *c = (char *) arg;
  *c = fgetc (fg);
  return NULL;
}
static void *UPD (void *arg) {
  char *c = (char *) arg;
  *c = toupper (*c);
  return NULL;
}
static void *PRINT (void *arg) {
  char *c = (char *) arg;
  putchar (*c);
  return NULL;
}
```

```
FILE *fg;
char next, this, last;

int main (int argc, char ** argv) {
   int retC;
   pthread_t tGet, tUpd, tPrint;
   void *retV;

if ((fg = fopen(argv[1], "r")) == NULL){
     perror ("Errore fopen\n");
     exit (0);
   }
   this = ' ';
   last = ' ';
   next = ' ';
```

```
while (next != EOF) {
  pthread_create (&tGet,NULL,GET,&next);
  pthread_create (&tUpd,NULL,UPD,&this);
  pthread_create (&tPrint,NULL,PRINT,&last);
  pthread_join (tGet, &retV);
  pthread_join (tUpd, &retV);
  pthread_join (tPrint, &retV);
  last = this;
  this = next;
}
```

```
// Last two chars processing

pthread_create(&tUpd,NULL,UPD,&this);
pthread_create(&tPrint,NULL,PRINT,&last);
pthread_join (tUpd, &retV);
pthread_join (tPrint, &retV);
pthread_create(&tPrint,NULL,PRINT,&this);

return 0;
}
```