

ECE521 Lecture7

Logistic Regression



UNIVERSITY OF
TORONTO

Outline

- **Logistic regression (Continue)**
- A single neuron
- Learning neural networks
- Multi-class classification

Logistic regression

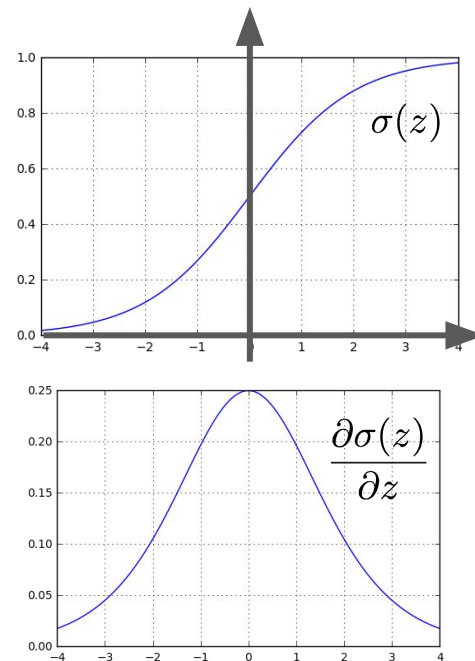
- The output of a logistic regression model is a sigmoid function of a weighted sum of its inputs:

$$\hat{y}^{(m)} = \sigma(z^{(m)}) = \sigma(W^T \mathbf{x}^{(m)} + b)$$

- Recall the sigmoid function and its nice derivatives:
 - The sigmoid output is bounded between 0 and 1

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$\frac{\partial \sigma(z)}{\partial z} = \sigma(z)(1 - \sigma(z))$$



Logistic regression

- We may choose to train logistic regression model using a squared L2 loss function:

$$\mathcal{L} = \frac{1}{2} \sum_m \|\hat{y}^{(m)} - t^{(m)}\|_2^2 \qquad \hat{y}^{(m)} = \sigma(z^{(m)}) = \sigma(W^T \mathbf{x}^{(m)} + b)$$

- The gradient of the loss function w.r.t. W and b can be obtained easily using chain-rule of calculus:

Gradient
of the
weight
vector

$$\frac{\partial \mathcal{L}}{\partial W} = \sum_m \frac{\partial \mathcal{L}}{\partial \hat{y}^{(m)}} \frac{\partial \hat{y}^{(m)}}{\partial z^{(m)}} \frac{\partial z^{(m)}}{\partial W}$$
$$\frac{\partial \mathcal{L}}{\partial W} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \hat{y}^{(m)} (1 - \hat{y}^{(m)}) \mathbf{x}^{(m)}$$

Gradient of
the bias??
(your own
exercise)

Logistic regression

- Using squared L2 loss function to train logistic regression models has a major flaw:
 - If the model parameters are ill initialized and the model is making opposite predictions at the first iteration of a gradient descent algorithm. Learning will happen really slowly using squared L2 loss because the vanishing gradient from the sigmoid function.
 - One way to see this is to have a model

$$\mathcal{L} = \frac{1}{2} \sum_m \|\hat{y}^{(m)} - t^{(m)}\|_2^2$$

$$\frac{\partial \mathcal{L}}{\partial W} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \hat{y}^{(m)} (1 - \hat{y}^{(m)}) \mathbf{x}^{(m)}$$

Cross-entropy loss function

- Cross-entropy is a better loss function.


$$\mathcal{L} = \sum_m -t^{(m)} \log \sigma(z^{(m)}) - (1 - t^{(m)}) \log(1 - \sigma(z^{(m)}))$$

- Take the gradient w.r.t. W . The gradient under the cross-entropy loss is the same as the gradient for the linear regression model!

$$\frac{\partial \mathcal{L}}{\partial W} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \mathbf{x}^{(m)} \quad \text{where, } \hat{y}^{(m)} = \sigma(z^{(m)}) \\ = \sigma(W^T \mathbf{x}^{(m)} + b)$$

Learning logistic regression

- What is happening during learning?

$$\frac{\partial \mathcal{L}}{\partial W} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \mathbf{x}^{(m)}$$


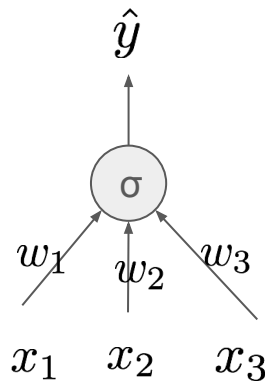
The gradient is the correlation between **the error** and **the inputs**

- In what circumstances is the gradient zero? i.e. the model stops learning any new information.
 - Either all the individual gradients are zero. (perfectly separable case)
 - The gradients from different training examples cancel out. (most likely scenario)

Learning logistic regression

- The gradient is the correlation between the mistakes and the input features.
 - After learning, the values of the individual weights indicate the importance of its input to the final prediction
 - If an input feature x_n is positively correlated with the target label, its weight will be a large positive value

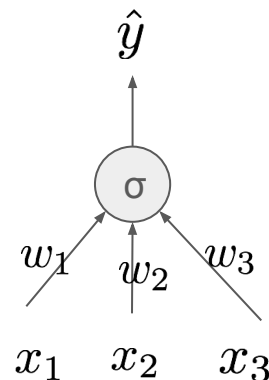
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Learning logistic regression

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Learning logistic regression for movie review

- Convert text string into a reasonable input feature vectors:
 - The bag-of-words representation:
 - Count the frequency of a word appears from a preset vocabulary

[good, fantastic, ..., terrible, disappointed, awesome,...]

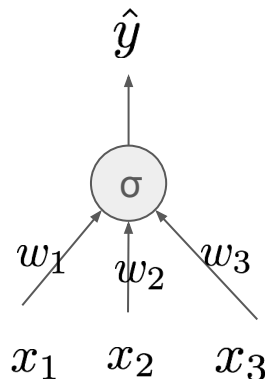
[2, 0, ..., 0, 1, 5, ...]

Learning logistic regression for movie review

- Consider a positive word that correlates to the positive review of a movie:
 - Assume the prediction starts at random 50% random guessing.
 - The weight of the positive word should increase during learning
- [good, fantastic, ..., terrible, disappointed, awesome,...]

[2, 0, ..., 0, 1, 5, ...]

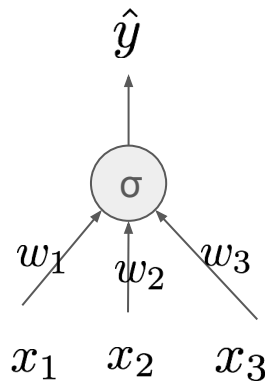
$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \mathbf{x}^{(m)}$$



Learning logistic regression for movie review

- Consider a random word that appears frequently and appears in both positive and negative review:
 - Its weight will likely to be around zero.
 - The gradient is not very informative and the error will cancel out between the positive class and negative class.

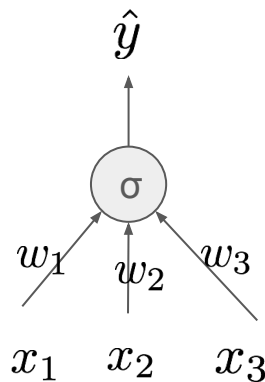
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Learning logistic regression for movie review

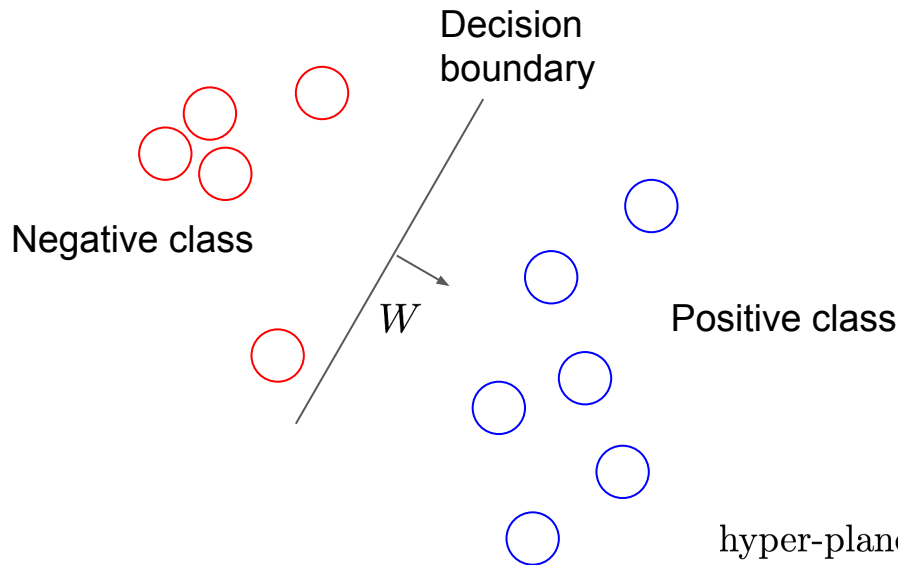
- Consider a random word that appears rarely and only appears in the positive review:
 - The model will likely not perform well because it is overly confident about a rare instance.
 - MAP should fix this problem

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}} = \sum_m (\hat{y}^{(m)} - t^{(m)}) \mathbf{x}^{(m)}$$



Intuitive geometry of logistic regression

- Decision boundary of logistic regression
 - The weight vector is perpendicular to the decision boundary



$$P(t = 1|\mathbf{x}, W) = P(t = 0|\mathbf{x}, W)$$

$$\sigma(W^T \mathbf{x} + b) = 1 - \sigma(W^T \mathbf{x} + b)$$

hyper-plane of a decision boundary: $W^T \mathbf{x} = 0$

Concept in the course so far

- **Problem formulations:**

- i.i.d., different distance functions, squared L2 loss, cross-entropy loss, MLE, MAP, weight-decay regularizer

- **Learning algorithms:**

- gradient descent, stochastic gradient descent, momentum,

- **Models:**

- linear regression, logistic regression, k-NN (no learning required)

- **Some theoretical results**

- Provide some additional intuitions: how to pick the optimal regressor, optimal decision rules (how to set the threshold/decision boundary), expected loss

Outline

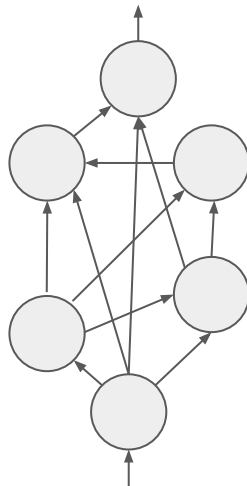
- **Logistic regression**
- Learning objectives:
 - Logistic/sigmoid function and its derivatives
 - Cross-entropy loss function and its derivatives
 - Probabilistic interpretation (assignment 2)

Outline

- Logistic regression (Continue)
- **A single neuron**
- Learning neural networks
- Multi-class classification

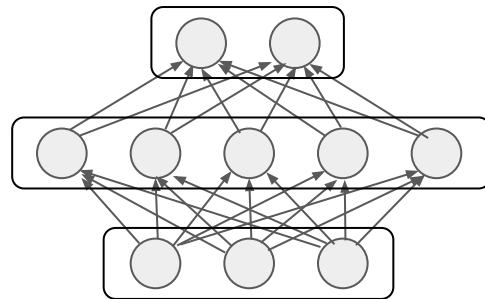
Neural networks

- Neural networks are flexible computation models that consist of many smaller computational modules called neurons or hidden units:
 - Neural networks are like a continuous real valued electrical circuits.
 - It is very modular and some special modules are designed for reusability and abstraction.
 - All continuous functions are neural networks.
 - All the learnt knowledges of a neural network are stored in its weight connections, it is also called “connectionism” (a pre AI winter name)



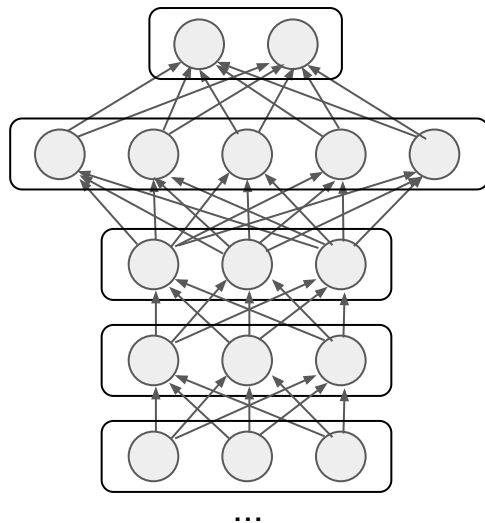
Neural networks

- One very useful abstraction is the concept of a “layer”:
 - A hidden layer is a group of hidden units that have connections only to all the hidden units one layer above and one layer below.
 - There is no inter-layer connection between the hidden units within a layer.
 - This abstraction is computationally efficient because all the hidden units within a layer can be computed in parallel.



Neural networks

- Deep learning typical refers to a neural network with more than three hidden layers.
 - Deep neural networks can mathematically represent any continuous function given enough layers, but they also require additional tricks to learn useful representations for any tasks.
 - They work really well in supervised learning given enough data.
 - Deep neural network is like the complex system in biology, we understand a lot about what the simple module does but it quickly becomes really hard to understand what the system does, i.e. a “black box”.



An artificial neuron

- An artificial neuron is a simple computation unit that receive inputs from other simple computation units:
 - The effect of each input on the final output of the neuron is controlled by a weight
 - The weights can be positive or negative values for encoding +ve or -ve contribution from the inputs

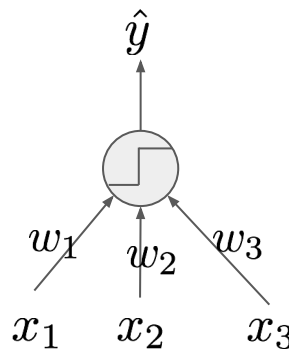
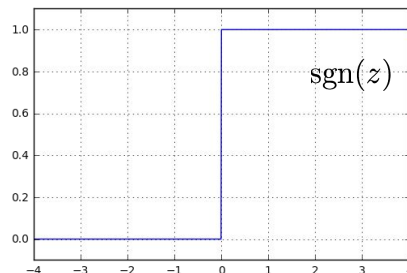
An artificial neuron

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 - The effect of each input on the final output of the neuron is controlled by a weight
 - The weights can be positive or negative values for encoding +ve or -ve contribution from the inputs
 - A weighted sum of the inputs was first proposed by McCulloch-Pitts (1943)

$$\text{sgn}(z) = \begin{cases} 1 & z \geq 0 \\ 0 & z < 0 \end{cases}$$

$$\hat{y} = \text{sgn}\left(\sum_n w_n x_n + b\right)$$

$$\frac{\partial \text{sgn}}{\partial z} = 0, \forall z \neq 0$$



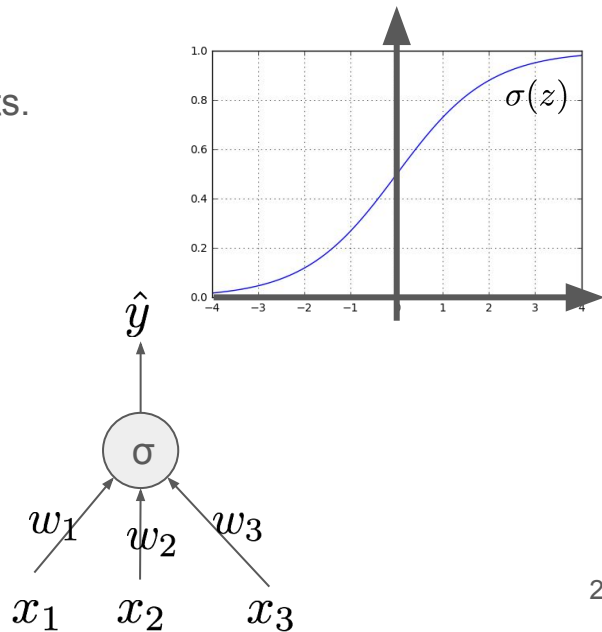
Some simple neurons: sigmoid neurons

- Instead of using a hard step function, a soft, smooth and differentiable step function is desirable if we are going to use the gradient descent algorithm to learn our model:
 - Sigmoid neurons can be thought of as soft thresholding units.
 - Logistic regression models are simply neural networks with a single logistic neuron.

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

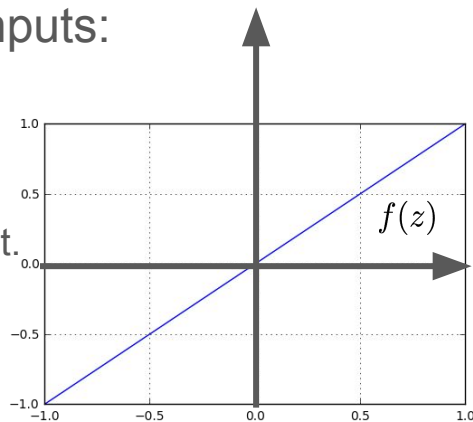
$$\frac{\partial \sigma}{\partial z} = \sigma(z)(1 - \sigma(z))$$

$$\hat{y} = \sigma\left(\sum_n w_n x_n + b\right)$$



Some simple neurons: linear neurons

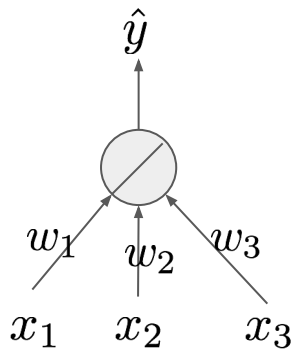
- A Linear neuron directly output the weighted sum of the inputs:
 - Linear regression is the simplest neural network with a single linear neuron.
 - It has a constant partial derivative which is great for gradient descent.
 - However, stacking layers of linear neurons does not increase the representation power of a model. Non-linearity is important for building richer and more flexible models.



$$f(z) = z$$

$$\frac{\partial f}{\partial z} = 1$$

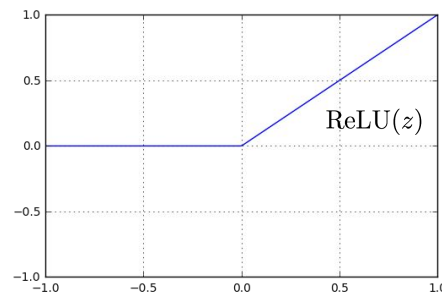
$$\hat{y} = \sum_n w_n x_n + b$$



Some simple neurons: rectified linear units (ReLU)

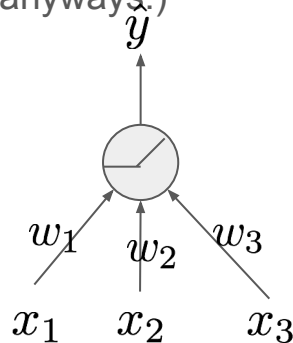
- Linear neurons can easily be modified to exhibit non-linear behaviors:

- The non-positive values are forced to be zero.
- The ReLU neurons still have very nice constant gradient if the weighted sum of the inputs is positive.
- It is mathematically non-differentiable at zero, but we ignore that and use gradient descent anyways. It will work brilliantly well.
(numerically, we will never get exactly zero summed inputs anyways.)



$$\text{ReLU}(z) = \max(0, z) \quad \hat{y} = \text{ReLU}\left(\sum_n w_n x_n + b\right)$$

$$\frac{\partial \text{ReLU}}{\partial z} = \begin{cases} 1 & z > 0 \\ 0 & z < 0 \end{cases}$$

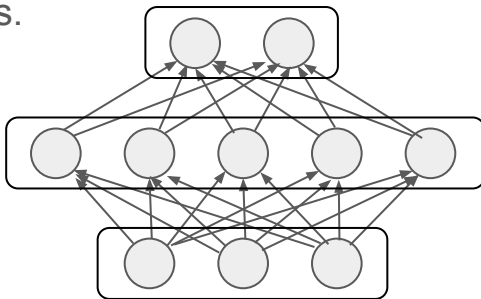


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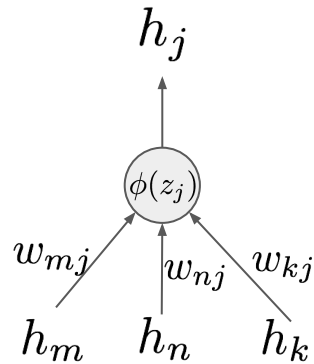
Neural networks

- There are two ways to solve a problem: 1. hire the most ingenious software engineers to hard code a program. 2. gather a huge dataset and learn the program from the data.
 - Deep neural networks avoid time-consuming feature engineering by hand and as the datasets grow larger, they can discover better features with no human intervention.
 - Neural networks can also be understood as a form of adaptive basis function model where the model learns layers of basis functions. The activation function used for a neuron is similar to the non-linear basis functions.



Notations for neural networks

- The model now consist of many artificial neurons wired together into a large network, for clarity, we will use the following notation for our algorithms:
 - The output a neuron or the hidden activation is denoted as h
 - Scalar weight connections are indexed by the two neuron it connects with
 - The input to the network is denoted x
 - The output of the network is denoted as \hat{y}
 - The element-wise hidden activation function or the activation function or non-linearity, denoted as $\phi(\cdot)$, is the non-linear transformation for the weighted sum of the inputs of a neuron, e.g. sigmoid, ReLU...
 - The weighted sum of a neuron's inputs is denoted as z



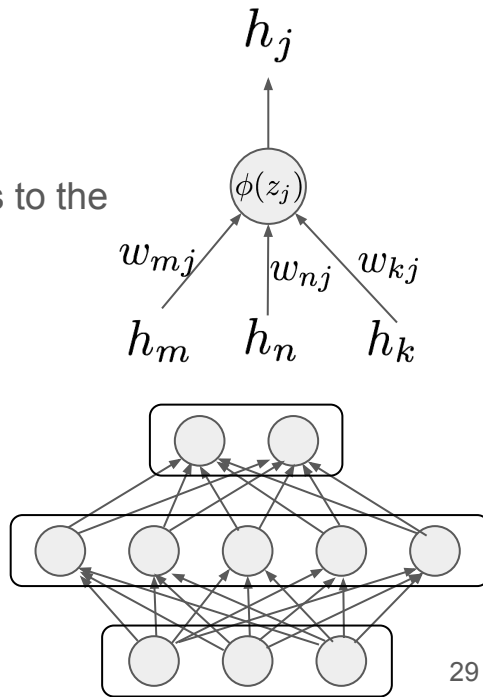
Forward propagation

- The forward propagation computes all the hidden activations h and the output of the neural network

- $h_j = \phi(z_j) = \phi(\sum_n w_{nj}h_n + b_j)$
- This requires computing all the hidden activations that are the inputs to the current hidden units.
- The forward propagation can be written as a recursive algorithm:

```
def forwardprop(output_node):  
    weighted_sum = 0.  
    for input_node in output_node.inputs:  
        activation = forwardprop(input_node)  
        weighted_sum += activation * weights[input_node, output_node]  
    return activationFunc(weighted_sum)
```

- The naive recursive algorithm is bad because there are a lot of redundant computations. We would like to cache the appropriate intermediate values and reuse them.



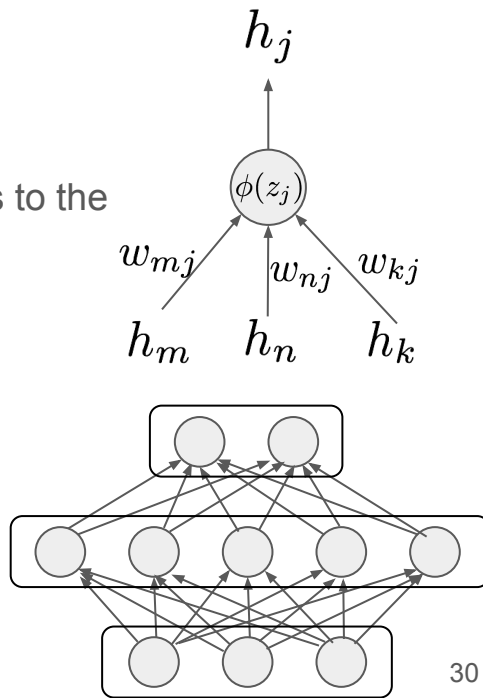
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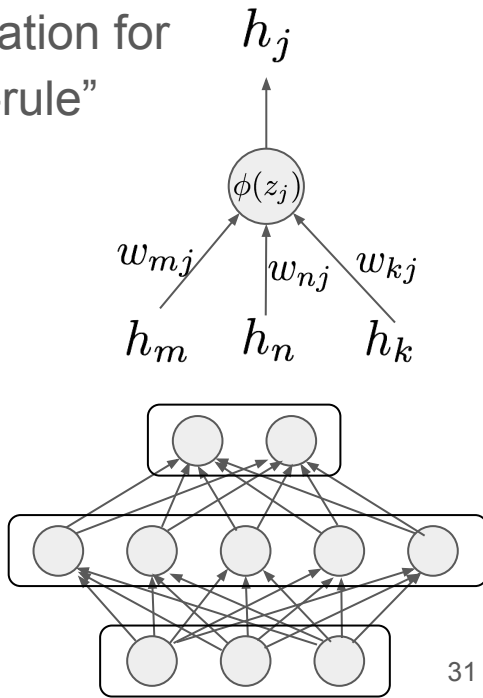


Back-propagation

- Back-propagation (Rumelhart, Hinton and Williams, 1986) is a form of dynamic programming method to re-use previous computation for computing the gradient of some variable using the “chain-rule” from calculus.

- $h_j = \phi(z_j) = \phi(\sum_n w_{nj} h_n + b_j)$
- In its simplest form: $\frac{\partial \mathcal{L}}{\partial w_{nj}} = \frac{\partial \mathcal{L}}{\partial h_j} \frac{\partial h_j}{\partial z_j} \frac{\partial z_j}{\partial w_{nj}}$
- $\frac{\partial \mathcal{L}}{\partial h_j}$ can be further expanded until the output of the neural network.
- The key observation here is that the gradient of a connection is a product between the input and the partial derivative of the weighted sum of that neuron.

$$\frac{\partial \mathcal{L}}{\partial w_{nj}} = \frac{\partial \mathcal{L}}{\partial z_j} h_n$$



Back-propagation

- What do we need to compute the gradients of the weights?

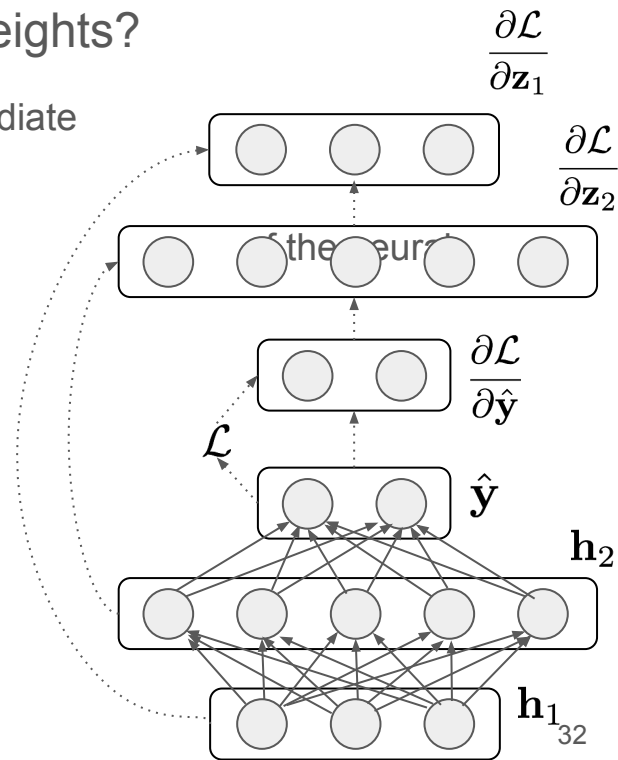
- First, we need to do a forward pass and cache all the intermediate hidden activations.
- Differentiate the loss function w.r.t. the output network as the initial step for back-propagation
- The intermediate hidden activations are needed for the partial derivative of the weighted sums

$$\frac{\partial \mathcal{L}}{\partial \mathbf{z}_1} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{z}_2} \frac{\partial \mathbf{z}_2}{\partial \mathbf{z}_1}$$

Back-propagation (left to right)

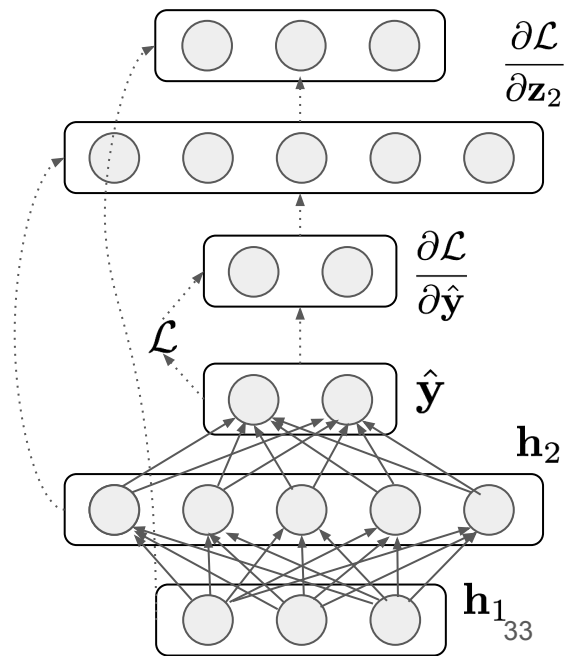
$$\frac{\partial \mathcal{L}}{\partial W_1} = \frac{\partial \mathcal{L}}{\partial \mathbf{z}_1} \mathbf{h}_1^T$$

Weight matrix gradient is an outer product



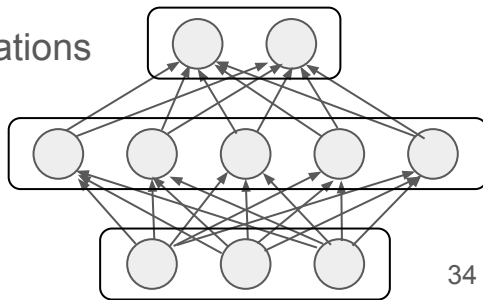
TensorFlow, back-propagation and auto-diff

- TensorFlow at its core is a forward/back-propagation execution engine: $\frac{\partial \mathcal{L}}{\partial \mathbf{z}_1}$
 - The computation graphs are neural networks
 - The automatic differentiation execute back-propagation for the variables (weights) in the computation graph. It can be automated if the partial derivatives of each math operator are pre-defined.
 - `session.run()` or `eval()` runs forward/back-propagation algorithm and cache the needed intermediate computation results for later.
 - The TensorFlow framework also computes the independent computations in parallel asynchronously.



TensorFlow and back-propagation

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