

Metric Spaces

Vu Tuong Vi Nguyen

University of North Florida

yuuri.yu.196@gmail.com

December 12, 2024

Overview

1 Why is Metric Space important?

2 What is a Metric Space?

3 Topological Properties

- Openness and Closeness
- Compactness
- Connectedness

4 Topological Spaces

Why is Metric Space Important?

- Introduced in 1906 by Maurice Frechet, and further developed by Felix Hausdorff.
- Generalize the notion of distance.
- Their properties are widely used such as in geometry or limit problems.

Definition of a Metric Space

Definition

A metric space is a set X together with a function $\rho : X \times X \longrightarrow \mathbb{R}$ (called the metric of X) which satisfies the following properties for all $x, y, z \in X$:

POSITIVE DEFINITE: $\rho(x, y) \geq 0$ with $\rho(x, y) = 0$ if and only if $x = y$,

SYMMETRIC: $\rho(x, y) = \rho(y, x)$,

TRIANGLE INEQUALITY: $\rho(x, y) \leq \rho(x, z) + \rho(z, y)$.

[Notice that by definition, $\rho(x, y)$ is finite valued for all $x, y \in X$.]

Example 1 - Discrete

Example

The set S is a metric space that is defined by $\rho : X \times X \longrightarrow \mathbb{R}$ such that

$$\rho(x, y) = \begin{cases} 0 & \text{if } x = y, \\ 1 & \text{if } x \neq y. \end{cases} \quad (1)$$

Example 1 (cont.)

Proof.

Positive definite: For $x, y \in S$, it is always true that $\rho(x, y) \geq 0$ where $\rho(x, y) = 0 \iff x = y$.

Symmetric: We observe that 0 and 1 are the only solutions of $\rho(x, y)$ such that the position of x and y are not important. Therefore, $\rho(x, y) = \rho(y, x)$.

Triangle inequality: Let $z \in S$. Since $\max\{\rho(x, y)\}_{x, y \in S} = 1$. We have the following cases:

Case $x = y = z$: Then $\rho(x, z) + \rho(z, y) = 0$. And having $\rho(x, y) = 0$.

So $\rho(x, z) + \rho(z, y) = \rho(x, y)$.

Case $x \neq y \neq z$: Then $\rho(x, y) = 1 < \rho(x, z) + \rho(z, y) = 1 + 1 = 2$

Case one is difference: Assume $x = y$ and $x \neq z$.

Then, $\rho(x, y) = 0 < \rho(x, z) + \rho(z, y) = 2$

Assume $x \neq y$ and, WLOG $x = z$.

Then, $\rho(x, y) = \rho(x, z) + \rho(z, y) = 1$

Therefore, $\rho(x, y) \leq \rho(x, z) + \rho(z, y)$. □

Example 2 - Continuous

Example

\mathbb{R}^2 is a metric space with the function $\rho(x, y) = |x - y|$ for $x, y \in \mathbb{R}$

Example 2 (cont.)

Proof.

Positive definite: For $x, y \in \mathbb{R}$, it is always true that $\rho(x, y) = |x - y| \geq 0$ where $\rho(x, y) = 0 \iff x = y$.

Symmetric: By definition of absolute value, we have:

$$\begin{aligned}\rho(x, y) &= |x - y| \\ &= |-(y - x)| \\ &= |y - x| \\ &= \rho(y, x)\end{aligned}$$

Triangle inequality: Let $z \in \mathbb{R}$. We have:

$$\begin{aligned}\rho(x, z) + \rho(z, y) &= |x - z| + |z - y| \\ &\geq |x - z + z - y| = |x - y| = \rho(x, y)\end{aligned}$$

Therefore, $\rho(x, y) \leq \rho(x, z) + \rho(z, y)$. □

Openness and Closeness

Definition

Let $a \in X$ and $r > 0$. The *open ball* (in X) with *center* a and *radius* r is the set

$$B_r(a) := \{x \in X : \rho(x, a) < r\},$$

and the *closed ball* (in X) with *center* a and *radius* r is the set

$$\{x \in X : \rho(x, a) \leq r\}.$$

Definition

- i) A set $V \subseteq X$ is said to be *open* if and only if for every $x \in V$ there is an $\epsilon > 0$ such that the open ball $B_\epsilon(x)$ is contained in V .
- ii) A set $E \subseteq X$ is said to be *closed* if and only if $E^c := X \setminus E$ is open.

Proposition

Every open ball is open, and every closed ball is closed.

Proof.

Let $B_r(a)$ be an open ball, $x \in B_r(a)$, and $\epsilon = r - \rho(x, a)$.

For $y \in B_\epsilon(x)$, by the Triangle Inequality and chosen ϵ , we have:

$$\begin{aligned}\rho(y, a) &\leq \rho(y, x) + \rho(x, a) \\ &< \epsilon + \rho(x, a) \\ &= r\end{aligned}$$

Thus, $y \in B_r(a)$. In other words, $B_\epsilon(x) \subseteq B_r(a)$.

By the definition of openness and closeness, $B_r(a)$ is open. Hence, every open ball is open.

Similarly, the set $\{x \in X : \rho(x, a) > r\}$ is open, so its complement $\{x \in X : \rho(x, a) \leq r\}$ is closed. Hence, every closed ball is closed. □

Theorem

Let X be a metric space.

i) If $\{V_\alpha\}_{\alpha \in A}$ is any collection of open sets in X , then

$$\bigcup_{\alpha \in A} V_\alpha$$

is open.

ii) If $\{V_k := 1, 2, \dots, n\}$ is a finite collection of open sets in X , then

$$\bigcap_{k=1}^n V_k := \bigcap_{k \in \{1, 2, \dots, n\}} V_k$$

is open.

Proof.

i) Let $x \in \bigcup_{\alpha \in A} V_\alpha$. Then, $x \in V_\alpha$ which is open for some $\alpha \in A$. Thus, there is an $r > 0$ such that $B_r(x) \subseteq V_\alpha$.

By the definition of openness and closeness, $\bigcup_{\alpha \in A} V_\alpha$ is open.

ii) Let $x \in \bigcap_{k=1}^n V_k$. Then $x \in V_k$ which is open for some $k = 1, 2, \dots, n$. Thus, there are some numbers $r_k > 0$ such that $B_{r_k}(x) \subseteq V_k$. For any $r \in r_k$, $r > 0$ and $B_r(x) \subseteq V_k$.

By the definition of openness and closeness, $\bigcap_{k=1}^n V_k$ is open. □

Compactness

Definition

Let $\nu = \{V_\alpha\}_{\alpha \in A}$ be a collection of subsets of a metric space X and suppose that E is a subset of X .

i) ν is said to *cover* E (or be a *covering* of E) if and only if

$$E \subseteq \bigcup_{\alpha \in A} V_\alpha$$

ii) ν is said to be an *open covering* of E if and only if ν covers E and each V_α is open.

iii) Let ν be a covering of E . ν is said to have a *finite* (respectively, *countable*) *subcovering* if and only if there is a finite (respectively, countable) subset A_0 of A such that $\{V_\alpha\}_{\alpha \in A_0}$ covers E .

Example

$\nu = \{(\frac{1}{k+1}, \frac{k}{k+1})\}_{k \in \mathbb{N}}$ is an open covering of $(0,1)$.

ν is a covering of $(0,1)$ since $(0,1) \subseteq \bigcup_{k \in \mathbb{N}} (\frac{1}{k+1}, \frac{k}{k+1})$

And since $(\frac{1}{k+1}, \frac{k}{k+1})$ is open for every $k \in \mathbb{N}$, ν is an open covering.

Compact Sets

Definition

A subset H of a metric space X is said to be *compact* if and only if every open subcovering of H has a finite subcover.

Proposition

A compact set is always closed.

Theorem

Let H be a subset of a metric space X . If H is compact, then H is closed and bounded.

Proof.

Let H be a compact subset of a metric space X . By Proposition above, we know that a compact set is always closed, so H is closed.

Take $b \in X$ and note $\{B_n(b) : n \in \mathbb{N}\}$ covers X .

As given that H is compact, we have:

$$H \subset \bigcup_{n=1}^N B_n(b) \text{ for some } N \in \mathbb{N}.$$

Hence, $H \subset B_N(b)$ or H is bounded.

Therefore, H is closed and bounded. □

Connectedness

Definition

Let X be a metric space.

- i) A pair of nonempty open sets U, V in X is said to *separate* X if and only if $X = U \cup V$ and $U \cap V = \emptyset$.
- ii) X is said to be *connected* if and only if X cannot be separated by any pair of open sets U, V .

Example

\mathbb{R} under discrete metric is separate because $(-\infty, 0]$ and $(0, \infty)$ are both open subsets of \mathbb{R} such that $\mathbb{R} = (-\infty, 0] \cup (0, \infty)$ and $(-\infty, 0] \cap (0, \infty) = \emptyset$.

\mathbb{R} under a continuous metric such as $|x - y|$ is connected because the metric itself is continuous. So, S is not separated by any pairs of open sets U, V .

Definition of a Topological Space

Definition

Let X be a set. A *topology* on X is a collection τ of subsets of X satisfying the following conditions

(T1) the total set, X , and the empty set, \emptyset , are elements of τ ;

(T2) if $\{U_\gamma\}_{\gamma \in \Gamma}$ is a (possibly infinite) family of elements of τ , then

$$\bigcup_{\gamma \in \Gamma} U_\gamma \in \tau;$$

(T3) if $\{U_1, \dots, U_n\} \subseteq \tau$ is a finite family of elements of τ , then

$$\bigcap_{i=1}^n U_i \in \tau.$$

A *topological space* is a pair (X, τ) where τ is a topology on X .

Example 1

Example

(X, τ) is a topological space where $X = \{1, 2, 3\}$ and $\tau = \{\emptyset, X, \{2\}, \{1, 2\}, \{2, 3\}\}$

Proof.

(T1): As we observe, $X, \emptyset \in \tau$.

(T2): From the given τ , we have: $\bigcup_{\gamma=1}^5 U_{\gamma} \in \tau$. That is the union of families of elements of τ is also in τ .

(T3): Since any intersection of families of elements in τ is in τ , we conclude that $\bigcap_{i=1}^5 U_i \in \tau$.

Thus, τ is a topology. Hence, (X, τ) is a topological space. □

Example 2

Example

Let's consider the same set X with a different τ , say τ_0 .

We have $X = \{1, 2, 3\}$ and $\tau_0 = \{\emptyset, X, \{2\}, \{3\}\}$

(T1): We can see that $\emptyset, X \in \tau_0$.

(T2): $\{2\} \cup \{3\} = \{2, 3\} \notin \tau_0$.

Thus, τ_0 is not a topology.

Hence, the pair (X, τ_0) is not a topological space.

Every Metric Space is a Topological Space

Proof.

Recall that the collection of all open sets of a metric space is closed under union and intersection.

For a metric space (X, ρ) , let τ be the collection of all open subsets of X which respect to metric ρ . Thus, τ is a topology on X .

Hence, the pair (X, τ) is a topological space. □

References



William R. Wade (2010)

Pearson Prentice Hall

An Introduction to Analysis 10, 342 – 382.



Alex Gonzalez

Metric and Topological Spaces.



Stephan C. Carlson (2017)

Britannica.com.

Metric Space.



Stephan C. Carlson (2016)

Britannica.com.

Hausdorff Space.