```
format long e
% 6.4
A = [1,0;0,1;1,0];
ans_6a_1 = A*(A'*A)^(-1)*A';
x = [1,2,3]';
ans_6a_2 = ans_6a_1*x;
B = [1,2;0,1;1,0];
ans_6b_1 = B*(B'*B)^(-1)*B';
ans_6b_2 = ans_6b_1*x;
%%%%% 11.3
t = linspace(0,1,50);
Atil = fliplr(vander(t));
A = Atil(:,1:12);
b = cos(4*t');
% Part a - least square via normal eq
R = chol(A'*A); % cholesky factorization
w_a = R' \setminus (A'*b); % solve lower triangular sys R*w = A*b
x_a = R \setminus w_a; % solve upper triangular sys Rx = w
% part d - least square via qr
[q,r] = qr(A, econ');
x d = r \setminus (q'*b);
% part e - least square via \
x_e = A b;
% part f - least squart via svd
[u,sig,v] = qr(A, econ');
w_f = sig(u'*b); % solve diagonal system sw= u*b
x_f = v*w_f;
%%%% Ranking question
A rank 6 = [1,-1,0,0;-1,0,1,0;1,0,0,-1;0,0,1,-1;0,1,0,-1;1,1,1,1];
b_{rank_6} = [4,9,6,3,7,20]';
x_{ank_6} = A_{ank_6}b_{ank_6}
A_{rank_5} = [1,-1,0,0;-1,0,1,0;1,0,0,-1;0,0,1,-1;0,1,0,-1];
b_{rank_5} = [4,9,6,3,7]';
x_{rank_5} = A_{rank_5}b_{rank_5};
A_{rank_{-}61} = [1,-1,0,0;-1,0,1,0;1,0,0,-1;0,0,1,-1;0,1,0,-1;1,1,1,1];
b_{rank_61} = [4,9,6,3,7,30]';
x_rank_61 = A_rank_61\b_rank_61;
Warning: Rank deficient, rank = 3, tol = 1.922963e-15.
```

Published with MATLAB® R2022b