

Machine Learning with Kernel Methods

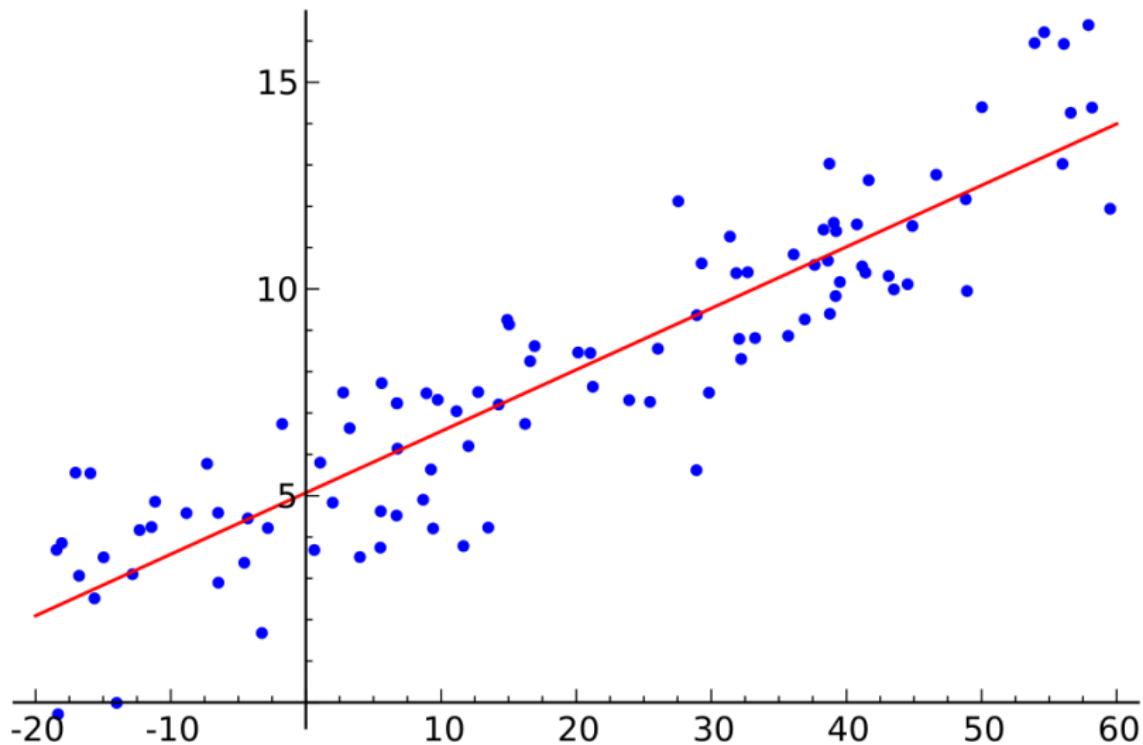


Julien Mairal & Jean-Philippe Vert

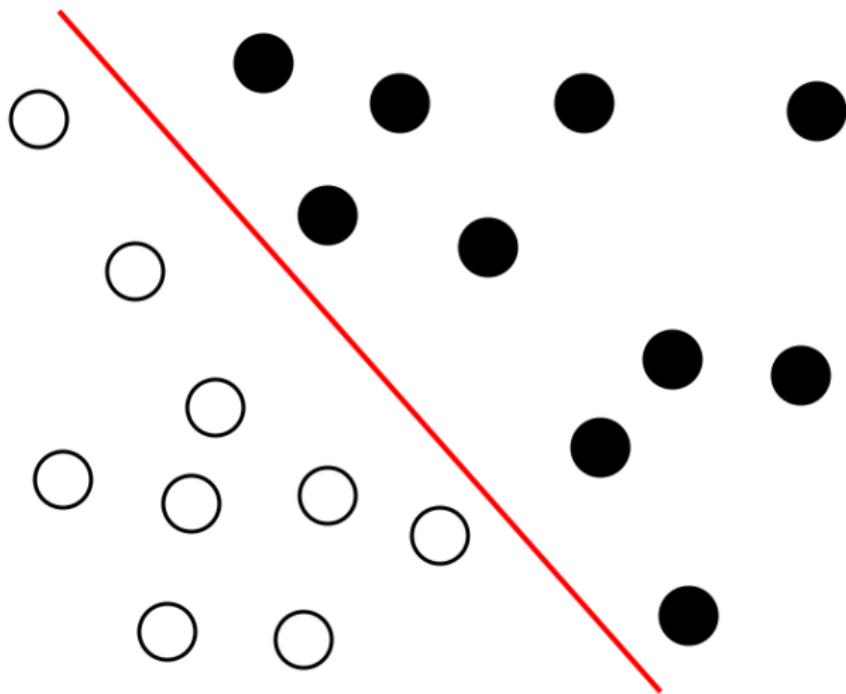
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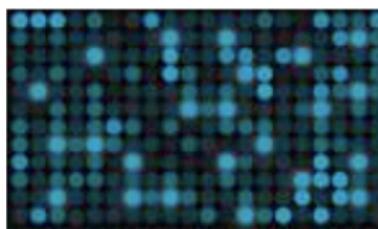
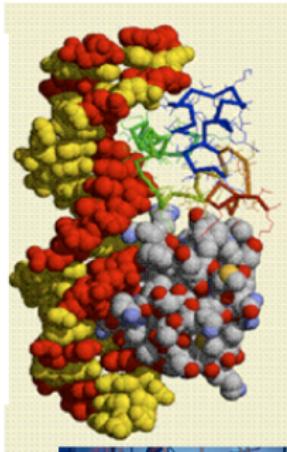
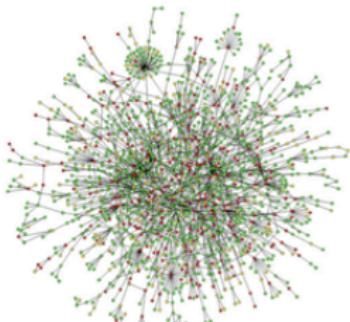
Starting point: what we know is how to solve



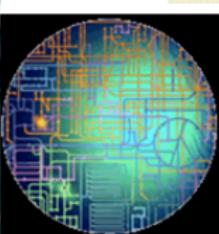
Or



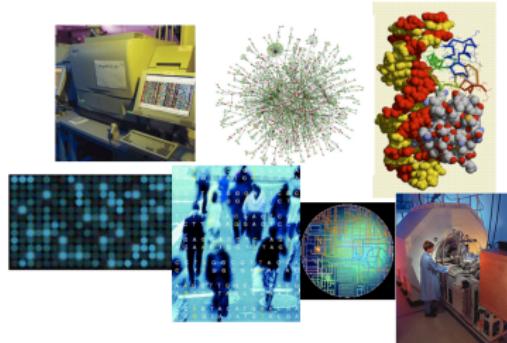
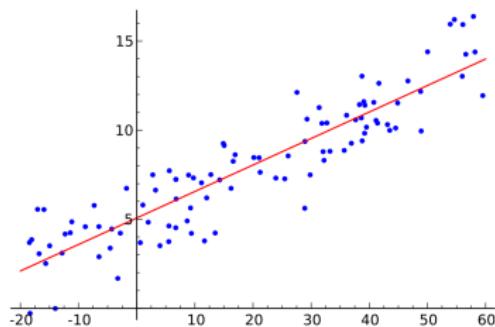
But real data are often more complicated...



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Main goal of this course



Extend
well-understood, linear statistical learning techniques
to
real-world, complicated, structured, high-dimensional data
based on
a rigorous mathematical framework
leading to
practical modelling tools and algorithms

Organization of the course

Contents

- ① Present the **basic mathematical theory** of kernel methods.
- ② Introduce algorithms for **supervised** and **unsupervised** machine learning with kernels.
- ③ Develop a working knowledge of **kernel engineering** for specific data and applications (graphs, biological sequences, images).
- ④ Discuss **open research topics** related to kernels such as large-scale learning with kernels and “deep kernel learning” .

Practical

- Course homepage with slides, schedules, homework etc...:
<http://cbio.mines-paristech.fr/~jvert/svn/kernelcourse/course/2020mva>
- Evaluation: 40% homework + 60% final exam.

Outline

1 Kernels and RKHS

- Positive Definite Kernels
- Reproducing Kernel Hilbert Spaces (RKHS)
- Examples
- Smoothness functional

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2 Kernel tricks

- The kernel trick
- The representer theorem

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- The representer theorem

3 Kernel Methods: Supervised Learning

- Kernel ridge regression
- Kernel logistic regression
- Large-margin classifiers
- Interlude: convex optimization and duality
- Support vector machines

Outline

4 Kernel Methods: Unsupervised Learning

- Kernel PCA
- Kernel K-means and spectral clustering
- A quick note on kernel CCA

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5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- Kernels for biological sequences
- Kernels for graphs
- Kernels on graphs

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6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
- Foundations of deep learning from a kernel point of view

Kernels and RKHS

Overview

Motivations

- Develop **versatile** algorithms to process and analyze data...
- ...without making any assumptions regarding the **type of data** (vectors, strings, graphs, images, ...)

The approach

- Develop methods based on **pairwise comparisons**.
- By imposing constraints on the pairwise comparison function (positive definite kernels), we obtain a **general framework for learning from data** (optimization in RKHS).

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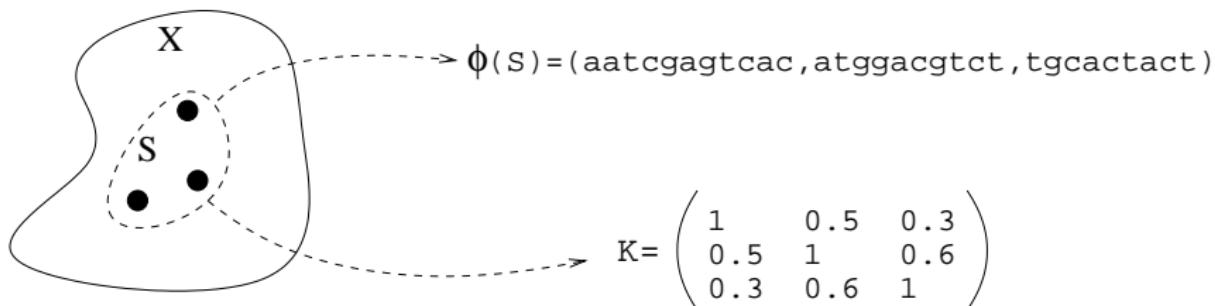
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Representation by pairwise comparisons



Idea

- Define a “comparison function”: $K : \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$.
- Represent a set of n data points $\mathcal{S} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ by the $n \times n$ matrix:

$$[K]_{ij} := K(\mathbf{x}_i, \mathbf{x}_j).$$

Representation by pairwise comparisons

Remarks

- \mathbf{K} is always an $n \times n$ matrix, whatever the nature of data: **the same algorithm will work for any type of data** (vectors, strings, ...).
- Total modularity between the **choice of function K** and the **choice of the algorithm**.
- Poor scalability with respect to the dataset size (n^2 to compute and store \mathbf{K})... but wait until the end of the course to see how to deal with large-scale problems
- We will restrict ourselves to a **particular class** of pairwise comparison functions.

Positive Definite (p.d.) Kernels

Definition

A **positive definite (p.d.) kernel** on a set \mathcal{X} is a function $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ that is **symmetric**:

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K(\mathbf{x}, \mathbf{x}') = K(\mathbf{x}', \mathbf{x}),$$

and which satisfies, for all $N \in \mathbb{N}$, $(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N) \in \mathcal{X}^N$ and $(a_1, a_2, \dots, a_N) \in \mathbb{R}^N$:

$$\sum_{i=1}^N \sum_{j=1}^N a_i a_j K(\mathbf{x}_i, \mathbf{x}_j) \geq 0.$$

Similarity matrices of p.d. kernels

Remarks

- Equivalently, a kernel K is p.d. if and only if, for any $N \in \mathbb{N}$ and any set of points $(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N) \in \mathcal{X}^N$, the **similarity matrix** $[\mathbf{K}]_{ij} := K(\mathbf{x}_i, \mathbf{x}_j)$ is positive semidefinite.
- **Kernel methods** are algorithms that take such matrices as input.

The simplest p.d. kernel, for real numbers

Lemma

Let $\mathcal{X} = \mathbb{R}$. The function $K : \mathbb{R}^2 \mapsto \mathbb{R}$ defined by:

$$\forall (x, x') \in \mathbb{R}^2, \quad K(x, x') = xx'$$

is p.d.

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is p.d.

Proof:

- $xx' = x'x$
- $\sum_{i=1}^N \sum_{j=1}^N a_i a_j x_i x_j = \left(\sum_{i=1}^N a_i x_i \right)^2 \geq 0$

□

The simplest p.d. kernel, for vectors

Lemma

Let $\mathcal{X} = \mathbb{R}^d$. The function $K : \mathcal{X}^2 \mapsto \mathbb{R}$ defined by:

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K(\mathbf{x}, \mathbf{x}') = \langle \mathbf{x}, \mathbf{x}' \rangle_{\mathbb{R}^d}$$

is p.d. (it is often called the linear kernel).

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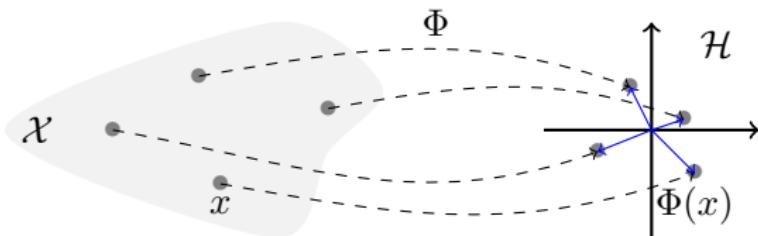
is p.d. (it is often called the **linear kernel**).

Proof:

- $\langle \mathbf{x}, \mathbf{x}' \rangle_{\mathbb{R}^d} = \langle \mathbf{x}', \mathbf{x} \rangle_{\mathbb{R}^d}$
- $\sum_{i=1}^N \sum_{j=1}^N a_i a_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle_{\mathbb{R}^d} = \| \sum_{i=1}^N a_i \mathbf{x}_i \|_{\mathbb{R}^d}^2 \geq 0$

□

A more ambitious p.d. kernel

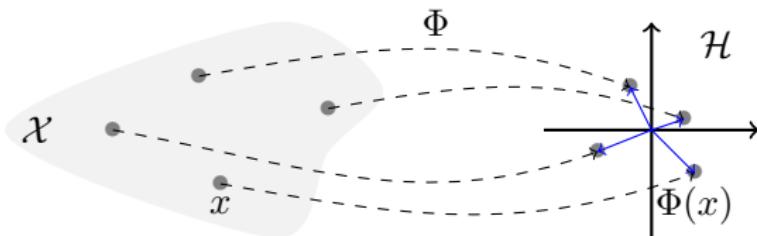


Lemma

Let \mathcal{X} be any set, and $\Phi : \mathcal{X} \mapsto \mathbb{R}^d$. Then, the function $K : \mathcal{X}^2 \mapsto \mathbb{R}$ defined as follows is p.d.:

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K(\mathbf{x}, \mathbf{x}') = \langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle_{\mathbb{R}^d}.$$

A more ambitious p.d. kernel



Lemma

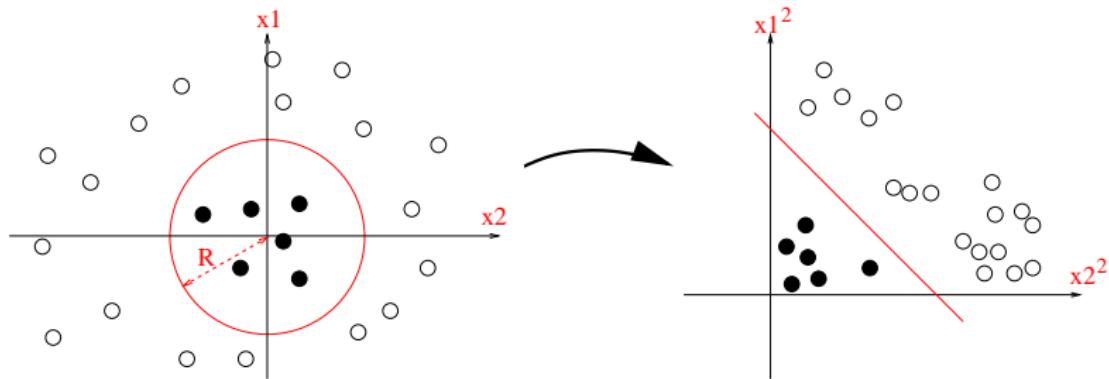
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Proof:

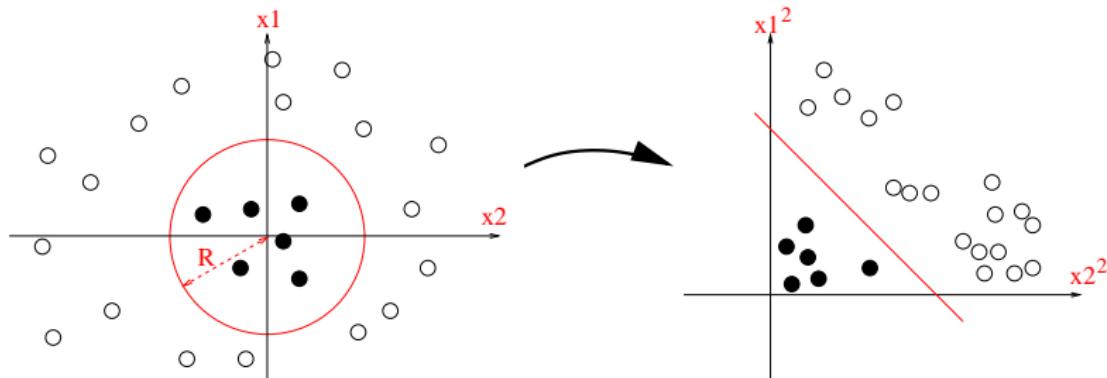
- $\langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle_{\mathbb{R}^d} = \langle \Phi(\mathbf{x}'), \Phi(\mathbf{x}) \rangle_{\mathbb{R}^d}$
- $\sum_{i=1}^N \sum_{j=1}^N a_i a_j \langle \Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j) \rangle_{\mathbb{R}^d} = \| \sum_{i=1}^N a_i \Phi(\mathbf{x}_i) \|_{\mathbb{R}^d}^2 \geq 0$ □

Example: polynomial kernel



For $\mathbf{x} = (x_1, x_2)^\top \in \mathbb{R}^2$, let $\Phi(\mathbf{x}) = (x_1^2, \sqrt{2}x_1x_2, x_2^2) \in \mathbb{R}^3$:

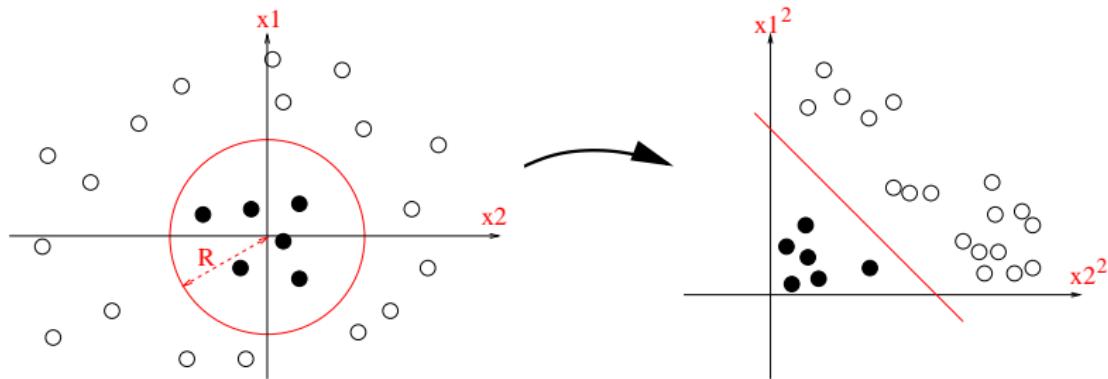
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$$\begin{aligned} K(\mathbf{x}, \mathbf{x}') &= x_1^2 x_1'^2 + 2x_1 x_2 x_1' x_2' + x_2^2 x_2'^2 \\ &= (x_1 x_1' + x_2 x_2')^2 \\ &= \langle \mathbf{x}, \mathbf{x}' \rangle_{\mathbb{R}^2}^2 . \end{aligned}$$

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Exercise: show that $\langle \mathbf{x}, \mathbf{x}' \rangle_{\mathbb{R}^p}^d$ is p.d. on $\mathcal{X} = \mathbb{R}^p$ for any $d \in \mathbb{N}$.

Conversely: Kernels as inner products

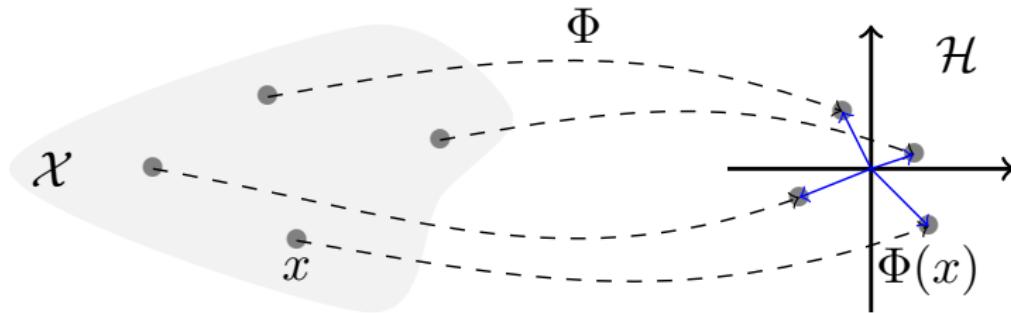
Theorem (Aronszajn, 1950)

K is a p.d. kernel on the set \mathcal{X} if and only if there exists a Hilbert space \mathcal{H} and a mapping

$$\Phi : \mathcal{X} \mapsto \mathcal{H}$$

such that, for any x, x' in \mathcal{X} :

$$K(x, x') = \langle \Phi(x), \Phi(x') \rangle_{\mathcal{H}} .$$



In case of ...

Definitions

- An **inner product** on an \mathbb{R} -vector space \mathcal{H} is a mapping $(f, g) \mapsto \langle f, g \rangle_{\mathcal{H}}$ from \mathcal{H}^2 to \mathbb{R} that is **bilinear, symmetric** and such that $\langle f, f \rangle_{\mathcal{H}} > 0$ for all $f \in \mathcal{H} \setminus \{0\}$.
- A vector space endowed with an inner product is called **pre-Hilbert**. It is endowed with a **norm** defined as $\|f\|_{\mathcal{H}} = \langle f, f \rangle_{\mathcal{H}}^{\frac{1}{2}}$.
- A **Cauchy sequence** $(f_n)_{n \geq 0}$ is a sequence whose elements become progressively arbitrarily close to each other:

$$\lim_{N \rightarrow +\infty} \sup_{n, m \geq N} \|f_n - f_m\|_{\mathcal{H}} = 0.$$

- A **Hilbert space** is a pre-Hilbert space **complete** for the norm $\|\cdot\|_{\mathcal{H}}$. That is, any Cauchy sequence in \mathcal{H} converges in \mathcal{H} .

Completeness is necessary to keep “good” convergence properties of Euclidean spaces in an infinite-dimensional context.

Proof: finite case

- Assume $\mathcal{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$ is finite of size N .
- Any p.d. kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is entirely defined by the $N \times N$ symmetric positive semidefinite matrix $[\mathbf{K}]_{ij} := K(\mathbf{x}_i, \mathbf{x}_j)$.
- It can therefore be diagonalized on an orthonormal basis of eigenvectors $(\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_N)$, with non-negative eigenvalues $0 \leq \lambda_1 \leq \dots \leq \lambda_N$, i.e.,

$$K(\mathbf{x}_i, \mathbf{x}_j) = \left[\sum_{l=1}^N \lambda_l \mathbf{u}_l \mathbf{u}_l^\top \right]_{ij} = \sum_{l=1}^N \lambda_l [\mathbf{u}_l]_i [\mathbf{u}_l]_j = \langle \Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j) \rangle_{\mathbb{R}^N},$$

with

$$\Phi(\mathbf{x}_i) = \begin{pmatrix} \sqrt{\lambda_1} [\mathbf{u}_1]_i \\ \vdots \\ \sqrt{\lambda_N} [\mathbf{u}_N]_i \end{pmatrix}. \quad \square$$

Proof: general case

- Mercer (1909) for $\mathcal{X} = [a, b] \subset \mathbb{R}$ (more generally \mathcal{X} compact) and K continuous.
- Kolmogorov (1941) for \mathcal{X} countable.
- Aronszajn (1944, 1950) for the general case.

We will go through the proof of the general case by introducing the concept of Reproducing Kernel Hilbert Spaces (RKHS).

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Functional spaces for machine learning

Before we go into formal details

- Among the Hilbert spaces \mathcal{H} mentioned in Aronszjan's theorem, we will see that one of them, **called RKHS**, is of interest to us.
- This is a **space of functions** from \mathcal{X} to \mathbb{R} .
- In other words, each data point \mathbf{x} in \mathcal{X} will be represented by a **function** $\Phi(\mathbf{x}) = K_{\mathbf{x}}$ in \mathcal{H} .

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- In other words, each data point x in \mathcal{X} will be represented by a **function** $\Phi(x) = K_x$ in \mathcal{H} .

Example of functional mapping

- Consider $\mathcal{X} = \mathbb{R}$. We could decide to represent each scalar x in \mathbb{R} as a Gaussian function centered at x :

$$K_x : y \mapsto e^{-\frac{1}{2\alpha}(x-y)^2}.$$

- What would be the corresponding \mathcal{H} (if it exists)? What would be the inner-product?

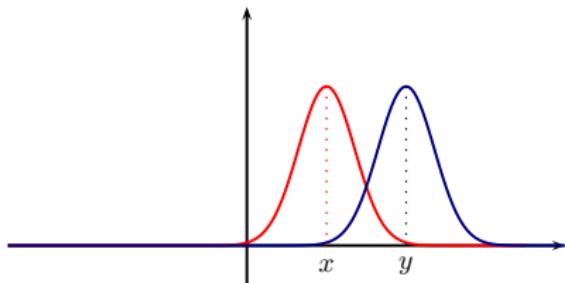
Functional spaces for machine learning

What does it mean to map a data point to a function?

Ex: if x, y in \mathbb{R} and $K(x, y) = e^{-\frac{1}{\sigma^2}(x-y)^2}$ is the Gaussian kernel,

$$\Phi(x) : t \mapsto e^{-\frac{1}{2\alpha^2}(x-t)^2}$$

$$\Phi(y) : t \mapsto e^{-\frac{1}{2\alpha^2}(y-t)^2}$$



- Data points are mapped to Gaussian functions living in a Hilbert space \mathcal{H} .
- But \mathcal{H} is much richer and contains much more than Gaussian functions!
- Prediction functions f live in \mathcal{H} : $f(x) = \langle f, \Phi(x) \rangle$.

RKHS Definition

Definition

Let \mathcal{X} be a set and $\mathcal{H} \subset \mathbb{R}^{\mathcal{X}}$ be a class of functions forming a (real) Hilbert space with inner product $\langle \cdot, \cdot \rangle_{\mathcal{H}}$. The function $K : \mathcal{X}^2 \mapsto \mathbb{R}$ is called a reproducing kernel (r.k.) of \mathcal{H} if

- ① \mathcal{H} contains all functions of the form

$$\forall \mathbf{x} \in \mathcal{X}, \quad K_{\mathbf{x}} : \mathbf{t} \mapsto K(\mathbf{x}, \mathbf{t}) .$$

- ② For every $\mathbf{x} \in \mathcal{X}$ and $f \in \mathcal{H}$ the reproducing property holds:

$$f(\mathbf{x}) = \langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}} .$$

If a r.k. exists, then \mathcal{H} is called a reproducing kernel Hilbert space (RKHS).

RKHS: why do we care?

The principle of RKHS gives us a simple recipe to do machine learning:

- Map data \mathbf{x} in \mathcal{X} to a **high-dimensional Hilbert space** \mathcal{H} (the RKHS) through a kernel mapping $\Phi : \mathcal{X} \rightarrow \mathcal{H}$, with $\Phi(\mathbf{x}) = K_{\mathbf{x}}$.
- In \mathcal{H} , consider **simple linear models** $f(\mathbf{x}) = \langle f, \Phi(\mathbf{x}) \rangle_{\mathcal{H}}$.
- If $\mathcal{X} = \mathbb{R}^p$, a linear function in $\Phi(\mathbf{x})$ may be nonlinear in \mathbf{x} .
- For instance, for supervised learning, given training data $(y_i, \mathbf{x}_i)_{i=1,\dots,n}$, we may want to minimize the **empirical risk**.

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2.$$

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More formal details to come...

An equivalent definition of RKHS

Theorem

The Hilbert space $\mathcal{H} \subset \mathbb{R}^{\mathcal{X}}$ is a RKHS if and only if for any $\mathbf{x} \in \mathcal{X}$, the (linear) mapping:

$$\begin{aligned} F : \quad & \mathcal{H} \rightarrow \mathbb{R} \\ f & \mapsto f(\mathbf{x}) \end{aligned}$$

is **continuous**.

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is continuous.

Corollary

Convergence in a RKHS implies pointwise convergence, i.e., if $(f_n)_{n \in \mathbb{N}}$ converges to f in \mathcal{H} , then $(f_n(\mathbf{x}))_{n \in \mathbb{N}}$ converges to $f(\mathbf{x})$ for any $\mathbf{x} \in \mathcal{X}$.

Proof

If \mathcal{H} is a RKHS then $f \mapsto f(\mathbf{x})$ is continuous

If a r.k. K exists, then for any $(\mathbf{x}, f) \in \mathcal{X} \times \mathcal{H}$:

$$\begin{aligned}|f(\mathbf{x})| &= |\langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}}| \\&\leq \|f\|_{\mathcal{H}} \cdot \|K_{\mathbf{x}}\|_{\mathcal{H}} \quad (\text{Cauchy-Schwarz}) \\&\leq \|f\|_{\mathcal{H}} \cdot K(\mathbf{x}, \mathbf{x})^{\frac{1}{2}},\end{aligned}$$

because $\|K_{\mathbf{x}}\|_{\mathcal{H}}^2 = \langle K_{\mathbf{x}}, K_{\mathbf{x}} \rangle_{\mathcal{H}} = K(\mathbf{x}, \mathbf{x})$. Therefore $f \in \mathcal{H} \mapsto f(\mathbf{x}) \in \mathbb{R}$ is a continuous linear mapping. \square

Since F is linear, it is indeed sufficient to show that $f \rightarrow 0 \Rightarrow f(x) \rightarrow 0$.

Proof (Converse)

If $f \mapsto f(\mathbf{x})$ is continuous then \mathcal{H} is a RKHS

Conversely, let us assume that for any $\mathbf{x} \in \mathcal{X}$ the linear form $f \in \mathcal{H} \mapsto f(\mathbf{x})$ is continuous.

Then by Riesz representation theorem (general property of Hilbert spaces) there exists a unique $g_{\mathbf{x}} \in \mathcal{H}$ such that:

$$f(\mathbf{x}) = \langle f, g_{\mathbf{x}} \rangle_{\mathcal{H}} .$$

The function $K(\mathbf{x}, \mathbf{y}) = g_{\mathbf{x}}(\mathbf{y})$ is then a r.k. for \mathcal{H} . □

Uniqueness of r.k. and RKHS

Theorem

- If \mathcal{H} is a RKHS, then it has a unique r.k.
- Conversely, a function K can be the r.k. of at most one RKHS.

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Consequence

This shows that we can talk of "the" kernel of a RKHS, or "the" RKHS of a kernel.

Proof

If a r.k. exists then it is unique

Let K and K' be two r.k. of a RKHS \mathcal{H} . Then for any $\mathbf{x} \in \mathcal{X}$:

$$\begin{aligned}\|K_{\mathbf{x}} - K'_{\mathbf{x}}\|_{\mathcal{H}}^2 &= \langle K_{\mathbf{x}} - K'_{\mathbf{x}}, K_{\mathbf{x}} - K'_{\mathbf{x}} \rangle_{\mathcal{H}} \\&= \langle K_{\mathbf{x}} - K'_{\mathbf{x}}, K_{\mathbf{x}} \rangle_{\mathcal{H}} - \langle K_{\mathbf{x}} - K'_{\mathbf{x}}, K'_{\mathbf{x}} \rangle_{\mathcal{H}} \\&= K_{\mathbf{x}}(\mathbf{x}) - K'_{\mathbf{x}}(\mathbf{x}) - K_{\mathbf{x}}(\mathbf{x}) + K'_{\mathbf{x}}(\mathbf{x}) \\&= 0.\end{aligned}$$

This shows that $K_{\mathbf{x}} = K'_{\mathbf{x}}$ as functions, i.e., $K_{\mathbf{x}}(\mathbf{y}) = K'_{\mathbf{x}}(\mathbf{y})$ for any $\mathbf{y} \in \mathcal{X}$. In other words, $\mathbf{K} = \mathbf{K}'$. □



Proof

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The RKHS of a r.k. K is unique

Left as exercise.

An important result

Theorem

A function $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is **p.d.** if and only if it is a **r.k.**

Proof

A r.k. is p.d.

- ① A r.k. is **symmetric** because, for any $(\mathbf{x}, \mathbf{y}) \in \mathcal{X}^2$:

$$K(\mathbf{x}, \mathbf{y}) = \langle K_{\mathbf{x}}, K_{\mathbf{y}} \rangle_{\mathcal{H}} = \langle K_{\mathbf{y}}, K_{\mathbf{x}} \rangle_{\mathcal{H}} = K(\mathbf{y}, \mathbf{x}).$$

- ② It is **p.d.** because for any $N \in \mathbb{N}, (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N) \in \mathcal{X}^N$, and $(a_1, a_2, \dots, a_N) \in \mathbb{R}^N$:

$$\begin{aligned} \sum_{i,j=1}^N a_i a_j K(\mathbf{x}_i, \mathbf{x}_j) &= \sum_{i,j=1}^N a_i a_j \langle K_{\mathbf{x}_i}, K_{\mathbf{x}_j} \rangle_{\mathcal{H}} \\ &= \| \sum_{i=1}^N a_i K_{\mathbf{x}_i} \|_{\mathcal{H}}^2 \\ &\geq 0. \quad \square \end{aligned}$$

Proof

A p.d. kernel is a r.k. (1/4)

- Let \mathcal{H}_0 be the vector subspace of $\mathbb{R}^{\mathcal{X}}$ spanned by the functions $\{K_{\mathbf{x}}\}_{\mathbf{x} \in \mathcal{X}}$.
- For any $f, g \in \mathcal{H}_0$, given by:

$$f = \sum_{i=1}^m a_i K_{\mathbf{x}_i}, \quad g = \sum_{j=1}^n b_j K_{\mathbf{y}_j},$$

let:

$$\langle f, g \rangle_{\mathcal{H}_0} := \sum_{i,j} a_i b_j K(\mathbf{x}_i, \mathbf{y}_j).$$

Proof

A p.d. kernel is a r.k. (2/4)

- $\langle f, g \rangle_{\mathcal{H}_0}$ does not depend on the expansion of f and g because:

$$\langle f, g \rangle_{\mathcal{H}_0} = \sum_{i=1}^m a_i g(\mathbf{x}_i) = \sum_{j=1}^n b_j f(\mathbf{y}_j).$$

- This also shows that $\langle \cdot, \cdot \rangle_{\mathcal{H}_0}$ is a **symmetric bilinear form**.
- This also shows that for any $\mathbf{x} \in \mathcal{X}$ and $f \in \mathcal{H}_0$:

$$\langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}_0} = f(\mathbf{x}).$$

Proof

A p.d. kernel is a r.k. (3/4)

- K is assumed to be p.d., therefore:

$$\|f\|_{\mathcal{H}_0}^2 = \sum_{i,j=1}^m a_i a_j K(\mathbf{x}_i, \mathbf{x}_j) \geq 0.$$

In particular Cauchy-Schwarz is valid with $\langle \cdot, \cdot \rangle_{\mathcal{H}_0}$.

- By Cauchy-Schwarz, we deduce that $\forall \mathbf{x} \in \mathcal{X}$:

$$|f(\mathbf{x})| = |\langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}_0}| \leq \|f\|_{\mathcal{H}_0} K(\mathbf{x}, \mathbf{x})^{\frac{1}{2}},$$

therefore $\|f\|_{\mathcal{H}_0} = 0 \implies f = 0$.

- \mathcal{H}_0 is therefore a **pre-Hilbert space** endowed with the inner product $\langle \cdot, \cdot \rangle_{\mathcal{H}_0}$.

Proof

A p.d. kernel is a r.k. (4/4)

- For any Cauchy sequence $(f_n)_{n \geq 0}$ in $(\mathcal{H}_0, \langle \cdot, \cdot \rangle_{\mathcal{H}_0})$, we note that:

$$\forall (\mathbf{x}, m, n) \in \mathcal{X} \times \mathbb{N}^2, \quad |f_m(\mathbf{x}) - f_n(\mathbf{x})| \leq \|f_m - f_n\|_{\mathcal{H}_0} K(\mathbf{x}, \mathbf{x})^{\frac{1}{2}}.$$

Therefore for any \mathbf{x} the sequence $(f_n(\mathbf{x}))_{n \geq 0}$ is Cauchy in \mathbb{R} and has therefore a limit.

- If we add to \mathcal{H}_0 the functions defined as the pointwise limits of Cauchy sequences, then the space becomes complete and is therefore a **Hilbert space**, with K as r.k. (up to a few technicalities, left as exercise). \square

Application: back to Aronszajn's theorem

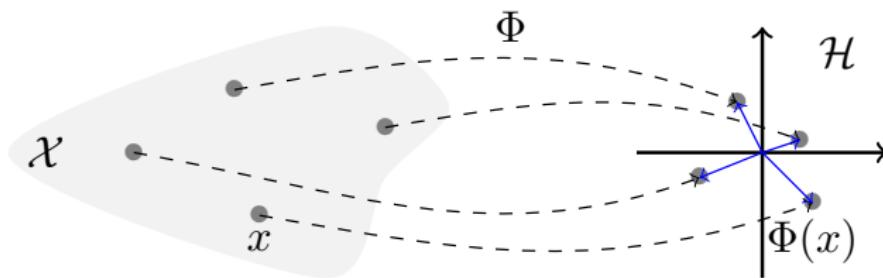
Theorem (Aronszajn, 1950)

K is a p.d. kernel on the set \mathcal{X} if and only if there exists a Hilbert space \mathcal{H} and a mapping

$$\Phi : \mathcal{X} \mapsto \mathcal{H},$$

such that, for any \mathbf{x}, \mathbf{x}' in \mathcal{X} :

$$K(\mathbf{x}, \mathbf{x}') = \langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle_{\mathcal{H}}.$$



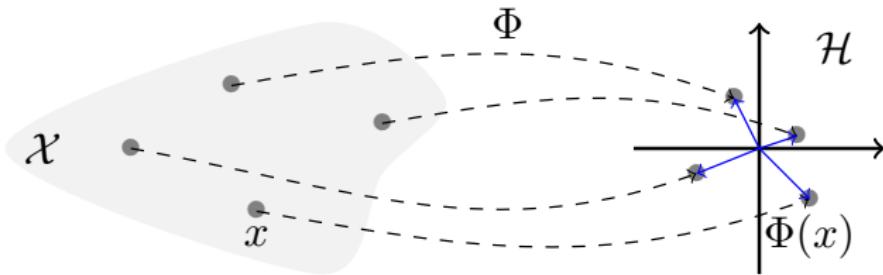
Proof of Aronzsajn's theorem

- If K is p.d. over a set \mathcal{X} then it is the r.k. of a Hilbert space $\mathcal{H} \subset \mathbb{R}^{\mathcal{X}}$.
- Let the mapping $\Phi : \mathcal{X} \rightarrow \mathcal{H}$ defined by:

$$\forall \mathbf{x} \in \mathcal{X}, \quad \Phi(\mathbf{x}) = K_{\mathbf{x}}.$$

- By the reproducing property we have:

$$\forall (\mathbf{x}, \mathbf{y}) \in \mathcal{X}^2, \quad \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{\mathcal{H}} = \langle K_{\mathbf{x}}, K_{\mathbf{y}} \rangle_{\mathcal{H}} = K(\mathbf{x}, \mathbf{y}). \quad \square$$



Outline

1 Kernels and RKHS

- Positive Definite Kernels
- Reproducing Kernel Hilbert Spaces (RKHS)
- Examples
- Smoothness functional

2 Kernel tricks

3 Kernel Methods: Supervised Learning

4 Kernel Methods: Unsupervised Learning

5 The Kernel Jungle

6 Open Problems and Research Topics

The linear kernel

Take $\mathcal{X} = \mathbb{R}^d$ and the **linear kernel**:

$$K(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle_{\mathbb{R}^d}.$$

Theorem

The RKHS of the linear kernel is the set of linear functions of the form

$$f_{\mathbf{w}}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle_{\mathbb{R}^d} \quad \text{for } \mathbf{w} \in \mathbb{R}^d,$$

endowed with the inner product

$$\forall \mathbf{w}, \mathbf{v} \in \mathbb{R}^d, \quad \langle f_{\mathbf{w}}, f_{\mathbf{v}} \rangle_{\mathcal{H}} = \langle \mathbf{w}, \mathbf{v} \rangle_{\mathbb{R}^d}$$

and corresponding norm

$$\forall \mathbf{w} \in \mathbb{R}^d, \quad \| f_{\mathbf{w}} \|_{\mathcal{H}} = \| \mathbf{w} \|_2.$$

Proof

The set \mathcal{H} of functions described in the theorem is the dual of \mathbb{R}^d , hence it is a Hilbert space:

$$\mathcal{H} = \left\{ f_{\mathbf{w}}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle_{\mathbb{R}^d} : \mathbf{w} \in \mathbb{R}^d \right\}.$$

- \mathcal{H} contains all functions of the form $K_{\mathbf{w}} : \mathbf{x} \mapsto \langle \mathbf{w}, \mathbf{x} \rangle_{\mathbb{R}^d}$.
- For every \mathbf{x} in \mathbb{R}^d , and $f_{\mathbf{w}}$ in \mathcal{H} ,

$$f_{\mathbf{w}}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle_{\mathbb{R}^d} = \langle f_{\mathbf{w}}, K_{\mathbf{x}} \rangle_{\mathcal{H}}.$$

\mathcal{H} is thus **the** RKHS of the linear kernel.

The polynomial kernel

Let us find the RKHS of the **polynomial kernel** of degree 2:

$$\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d, \quad K(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle_{\mathbb{R}^d}^2 = (\mathbf{x}^\top \mathbf{y})^2$$

The polynomial kernel

Let us find the RKHS of the **polynomial kernel** of degree 2:

$$\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d, \quad K(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle_{\mathbb{R}^d}^2 = (\mathbf{x}^\top \mathbf{y})^2$$

First step: Look for an inner-product.

$$\begin{aligned} K(\mathbf{x}, \mathbf{y}) &= \text{trace} \left(\mathbf{x}^\top \mathbf{y} \mathbf{x}^\top \mathbf{y} \right) \\ &= \text{trace} \left(\mathbf{y}^\top \mathbf{x} \mathbf{x}^\top \mathbf{y} \right) \\ &= \text{trace} \left(\mathbf{x} \mathbf{x}^\top \mathbf{y} \mathbf{y}^\top \right) \\ &= \left\langle \mathbf{x} \mathbf{x}^\top, \mathbf{y} \mathbf{y}^\top \right\rangle_F, \end{aligned}$$

where F is the Frobenius norm for matrices in $\mathbb{R}^{d \times d}$. Note that we have proven here that K is p.d.

The polynomial kernel

Second step: propose a candidate RKHS.

We know that \mathcal{H} contains all the functions

$$f(\mathbf{x}) = \sum_i a_i K(\mathbf{x}_i, \mathbf{x}) = \sum_i a_i \left\langle \mathbf{x}_i \mathbf{x}_i^\top, \mathbf{x} \mathbf{x}^\top \right\rangle_F = \left\langle \sum_i a_i \mathbf{x}_i \mathbf{x}_i^\top, \mathbf{x} \mathbf{x}^\top \right\rangle_F.$$

Any symmetric matrix in $\mathbb{R}^{d \times d}$ may be decomposed as $\sum_i a_i \mathbf{x}_i \mathbf{x}_i^\top$. Our candidate RKHS \mathcal{H} will be the set of quadratic functions

$$f_{\mathbf{S}}(\mathbf{x}) = \left\langle \mathbf{S}, \mathbf{x} \mathbf{x}^\top \right\rangle_F = \mathbf{x}^\top \mathbf{S} \mathbf{x} \quad \text{for } \mathbf{S} \in \mathcal{S}^{d \times d},$$

where $\mathcal{S}^{d \times d}$ is the set of **symmetric**¹ matrices in $\mathbb{R}^{d \times d}$, endowed with the inner-product $\langle f_{\mathbf{S}_1}, f_{\mathbf{S}_2} \rangle_{\mathcal{H}} = \langle \mathbf{S}_1, \mathbf{S}_2 \rangle_F$.

¹Why is it important?

The polynomial kernel

Third step: check that the candidate is a Hilbert space.

This step is trivial in the present case since it is easy to see that \mathcal{H} a Euclidean space, isomorphic to $\mathcal{S}^{d \times d}$ by $\Phi : \mathbf{S} \mapsto f_{\mathbf{S}}$. Sometimes, things are not so simple and we need to prove the completeness explicitly.

Fourth step: check that \mathcal{H} is the RKHS.

- ① \mathcal{H} contains all the functions $K_{\mathbf{x}} : \mathbf{t} \mapsto K(\mathbf{x}, \mathbf{t}) = \langle \mathbf{x}\mathbf{x}^T, \mathbf{t}\mathbf{t}^T \rangle_F$.
- ② For all $f_{\mathbf{S}}$ in \mathcal{H} and \mathbf{x} in \mathcal{X} ,

$$f_{\mathbf{S}}(\mathbf{x}) = \left\langle \mathbf{S}, \mathbf{x}\mathbf{x}^T \right\rangle_F = \langle f_{\mathbf{S}}, f_{\mathbf{x}\mathbf{x}^T} \rangle_{\mathcal{H}} = \langle f_{\mathbf{S}}, K_{\mathbf{x}} \rangle_{\mathcal{H}} .$$

□

Remark

All points \mathbf{x} in \mathcal{X} are mapped to a rank-one matrix $\mathbf{x}\mathbf{x}^T$, hence to a function $K_{\mathbf{x}} = f_{\mathbf{x}\mathbf{x}^T}$ in \mathcal{H} . However, most of points in \mathcal{H} do not admit a pre-image (why?).

Exercise: what is the RKHS of the general polynomial kernel?

Combining kernels

Theorem

- If K_1 and K_2 are p.d. kernels, then:

$$K_1 + K_2,$$

$$K_1 K_2, \text{ and}$$

$$cK_1, \text{ for } c \geq 0,$$

are also p.d. kernels

- If $(K_i)_{i \geq 1}$ is a sequence of p.d. kernels that converges pointwisely to a function K :

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K(\mathbf{x}, \mathbf{x}') = \lim_{n \rightarrow \infty} K_i(\mathbf{x}, \mathbf{x}'),$$

then K is also a p.d. kernel.

Proof: for $K_1 K_2$, see next slide; otherwise, left as exercise

Proof for $K_1 K_2$ is p.d.

Proof.

Consider n points in \mathcal{X} and the corresponding $n \times n$ p.s.d. kernel matrices \mathbf{K}_1 and \mathbf{K}_2 . As p.s.d. matrices, they admit factorizations $\mathbf{K}_1 = \mathbf{X}^\top \mathbf{X}$ and $\mathbf{K}_2 = \mathbf{Y}^\top \mathbf{Y}$. Then,

$$\begin{aligned} [\mathbf{K}]_{ij} &= [\mathbf{K}_1]_{ij} [\mathbf{K}_2]_{ij} \\ &= \text{trace} \left((\mathbf{x}_i^\top \mathbf{x}_j)(\mathbf{y}_j^\top \mathbf{y}_i) \right) \\ &= \text{trace} \left((\mathbf{y}_i \mathbf{x}_i^\top)(\mathbf{x}_j \mathbf{y}_j^\top) \right) \\ &= \left\langle \mathbf{x}_i \mathbf{y}_i^\top, \mathbf{x}_j \mathbf{y}_j^\top \right\rangle_F \\ &= \langle \mathbf{z}_i, \mathbf{z}_j \rangle_{\mathbb{R}^{n^2}}, \end{aligned}$$

where the \mathbf{x}_i 's and the \mathbf{y}_i 's are the columns of \mathbf{X} and \mathbf{Y} , respectively and $\mathbf{z}_i = \text{vec}(\mathbf{x}_i \mathbf{y}_i^\top)$. Thus, \mathbf{K} is p.s.d. and $K = K_1 K_2$ is a p.d. kernel. □

Examples

Theorem

If K is a kernel, then e^K is a kernel too.

Examples

Theorem

If K is a kernel, then e^K is a kernel too.

Proof:

$$e^{K(\mathbf{x}, \mathbf{x}')} = \lim_{n \rightarrow +\infty} \sum_{i=0}^n \frac{K(\mathbf{x}, \mathbf{x}')^i}{i!}$$

Quizz : which of the following are p.d. kernels?

- $\mathcal{X} = (-1, 1), \quad K(x, x') = \frac{1}{1-xx'}$

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- $\mathcal{X} = \mathbb{N}, \quad K(x, x') = LCM(x, x')$

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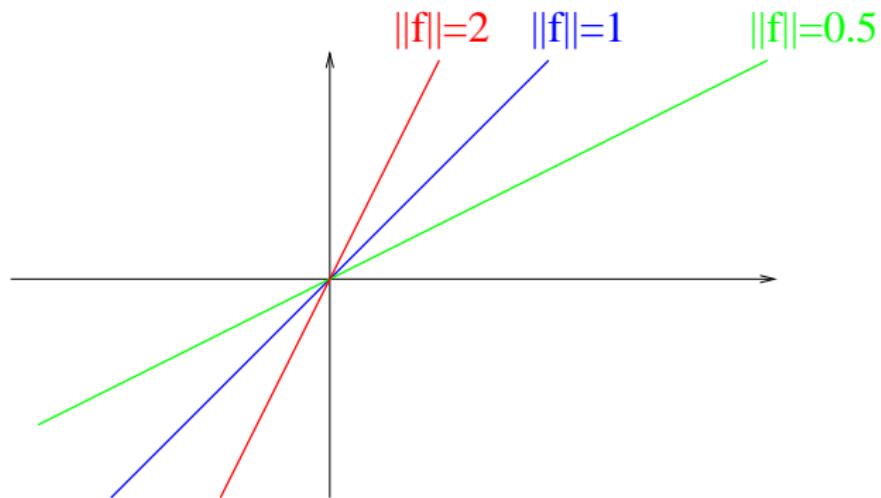
4 Kernel Methods: Unsupervised Learning

5 The Kernel Jungle

6 Open Problems and Research Topics

Remember the RKHS of the linear kernel

$$\begin{cases} K_{lin}(\mathbf{x}, \mathbf{x}') &= \mathbf{x}^\top \mathbf{x}' . \\ f(\mathbf{x}) &= \mathbf{w}^\top \mathbf{x} , \\ \|f\|_{\mathcal{H}} &= \|\mathbf{w}\|_2 . \end{cases}$$



Smoothness functional

A simple inequality

- By Cauchy-Schwarz we have, for any function $f \in \mathcal{H}$ and any two points $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$:

$$\begin{aligned} |f(\mathbf{x}) - f(\mathbf{x}')| &= |\langle f, K_{\mathbf{x}} - K_{\mathbf{x}'} \rangle_{\mathcal{H}}| \\ &\leq \|f\|_{\mathcal{H}} \times \|K_{\mathbf{x}} - K_{\mathbf{x}'}\|_{\mathcal{H}} \\ &= \|f\|_{\mathcal{H}} \times d_K(\mathbf{x}, \mathbf{x}'). \end{aligned}$$

- The norm of a function in the RKHS controls **how fast** the function varies over \mathcal{X} with respect to the **geometry defined by the kernel** (Lipschitz with constant $\|f\|_{\mathcal{H}}$).

Important message

Small norm \implies slow variations.

Kernels and RKHS : Summary

- P.d. kernels can be thought of as **inner product** after embedding the data space \mathcal{X} in some Hilbert space. As such a p.d. kernel defines a **metric** on \mathcal{X} .
- A realization of this embedding is the **RKHS**, valid without restriction on the space \mathcal{X} nor on the kernel.
- The RKHS is a space of functions over \mathcal{X} . The **norm** of a function in the RKHS is related to its degree of **smoothness** w.r.t. the metric defined by the kernel on \mathcal{X} .
- We will now see some applications of kernels and RKHS in statistics, before coming back to the problem of **choosing (and eventually designing) the kernel**.

Kernel tricks

Motivations

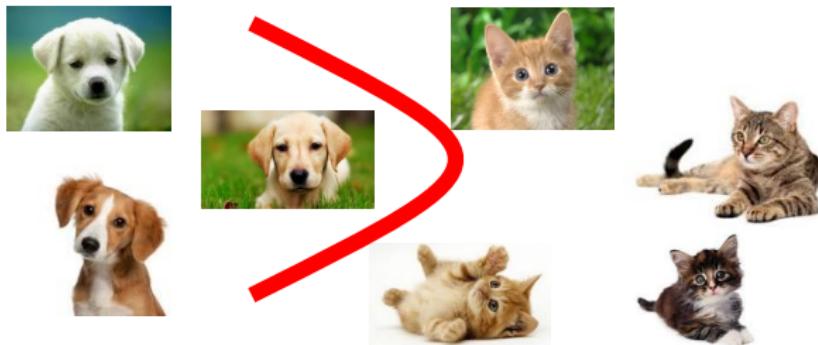
Two theoretical results underpin a family of powerful algorithms for data analysis using p.d. kernels, collectively known as **kernel methods**:

- The **kernel trick**, based on the representation of p.d. kernels as inner products;
- The **representer theorem**, based on some properties of the regularization functional defined by the RKHS norm.

Motivation from supervised learning

For instance, in supervised learning, the goal is to learn a **prediction function** $f : \mathcal{X} \rightarrow \mathcal{Y}$ given labeled training data $(\mathbf{x}_i, y_i)_{i=1,\dots,n}$ with \mathbf{x}_i in \mathcal{X} , and y_i in \mathcal{Y} :

$$\min_{f \in \mathcal{F}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\lambda \Omega(f)}_{\text{regularization}}.$$



(Vapnik, 1995)...

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The labels y_i are, for instance, in

- $\{-1, +1\}$ for **binary** classification problems.
- $\{1, \dots, K\}$ for **multi-class** classification problems.
- \mathbb{R} for **regression** problems.
- \mathbb{R}^k for **multivariate regression** problems.

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Example with linear models: logistic regression, etc.

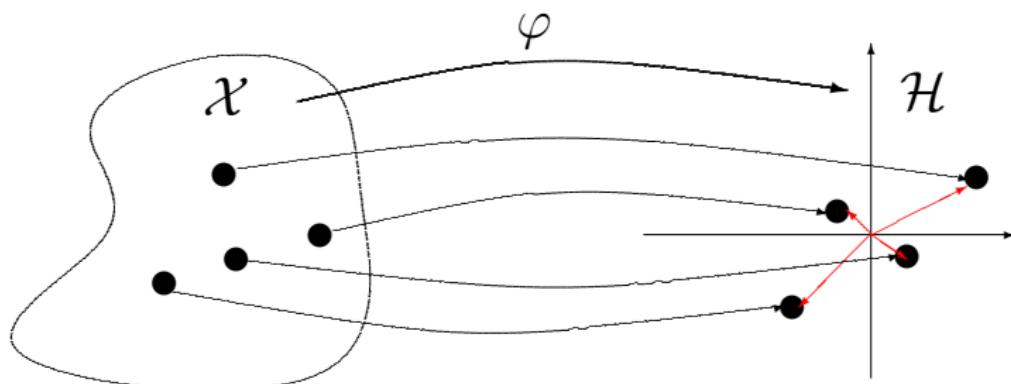
- assume there exists a linear relation between y and features \mathbf{x} in \mathbb{R}^p .
- $f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b$ is parametrized by \mathbf{w}, b in \mathbb{R}^{p+1} ;
- L is often a **convex** loss function;
- $\Omega(f)$ is often the squared ℓ_2 -norm $\|\mathbf{w}\|^2$.

Motivation from supervised learning

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2.$$

- Kernel methods allow you to **map** data x in \mathcal{X} to a Hilbert space and work with **linear forms**:

$$\Phi : \mathcal{X} \rightarrow \mathcal{H} \quad \text{and} \quad f(\mathbf{x}) = \langle \Phi(\mathbf{x}), f \rangle_{\mathcal{H}}.$$



Motivation from supervised learning

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2.$$

First purpose: embed data in a vectorial space where

- many **geometrical operations** exist (angle computation, projection on linear subspaces, definition of barycenters....).
- one may learn potentially **rich infinite-dimensional models**.
- **regularization** is natural and theoretically grounded.

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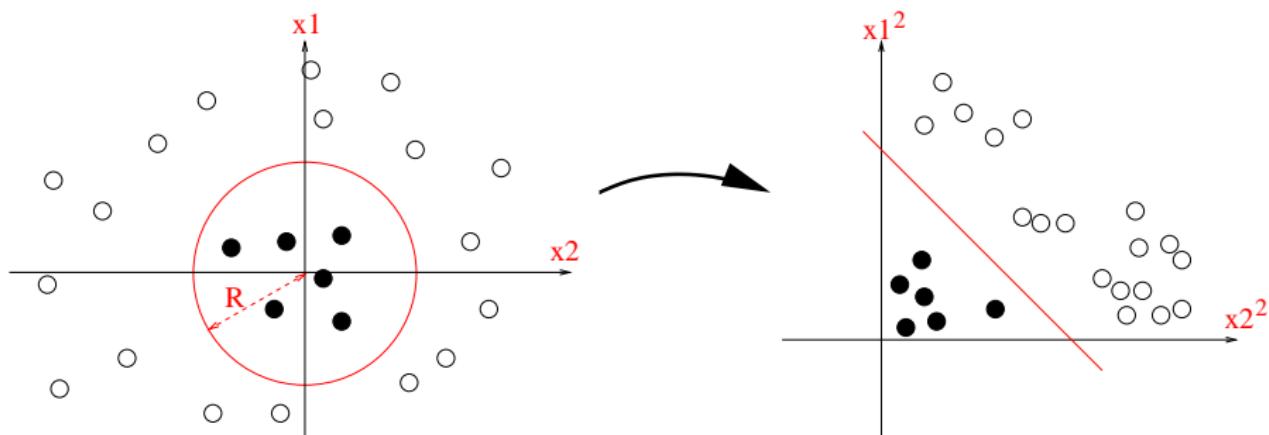
- many **geometrical operations** exist (angle computation, projection on linear subspaces, definition of barycenters....).
- one may learn potentially **rich infinite-dimensional models**.
- **regularization** is natural and theoretically grounded.

The principle is **generic** and does not assume anything about the nature of the set \mathcal{X} (vectors, sets, graphs, sequences).

Motivation from supervised learning

Second purpose: unhappy with the current Euclidean structure?

- lift data to a higher-dimensional space with **nicer properties** (e.g., linear separability, clustering structure).
- then, the **linear** form $f(\mathbf{x}) = \langle \Phi(\mathbf{x}), f \rangle_{\mathcal{H}}$ in \mathcal{H} may correspond to a **non-linear** model in \mathcal{X} .



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The kernel trick

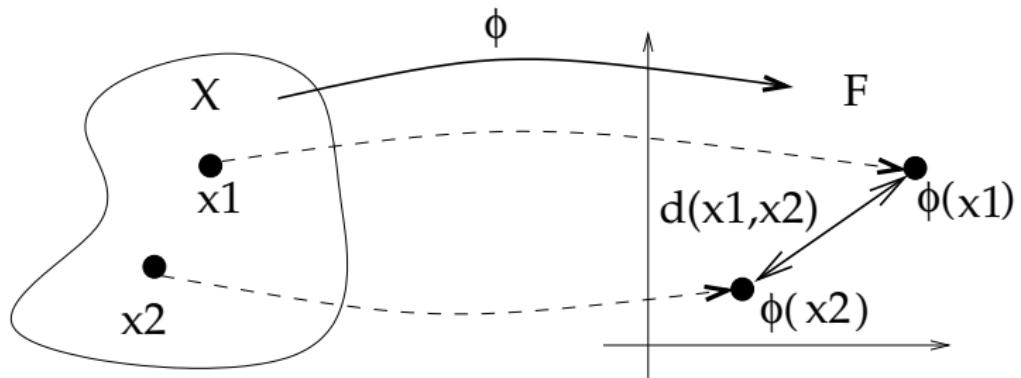
Proposition

Any algorithm to process finite-dimensional vectors that can be expressed only in terms of pairwise inner products can be applied to potentially infinite-dimensional vectors in the feature space of a p.d. kernel by replacing each inner product evaluation by a kernel evaluation.

Remarks:

- The proof of this proposition is trivial, because the kernel is exactly the inner product in the feature space.
- This trick has huge practical applications.
- Vectors in the feature space are only manipulated implicitly, through pairwise inner products.

Example 1: computing distances in the feature space



$$\begin{aligned} d_K(x_1, x_2)^2 &= \| \Phi(x_1) - \Phi(x_2) \|_{\mathcal{H}}^2 \\ &= \langle \Phi(x_1) - \Phi(x_2), \Phi(x_1) - \Phi(x_2) \rangle_{\mathcal{H}} \\ &= \langle \Phi(x_1), \Phi(x_1) \rangle_{\mathcal{H}} + \langle \Phi(x_2), \Phi(x_2) \rangle_{\mathcal{H}} - 2 \langle \Phi(x_1), \Phi(x_2) \rangle_{\mathcal{H}} \end{aligned}$$

$$d_K(x_1, x_2)^2 = K(x_1, x_1) + K(x_2, x_2) - 2K(x_1, x_2)$$

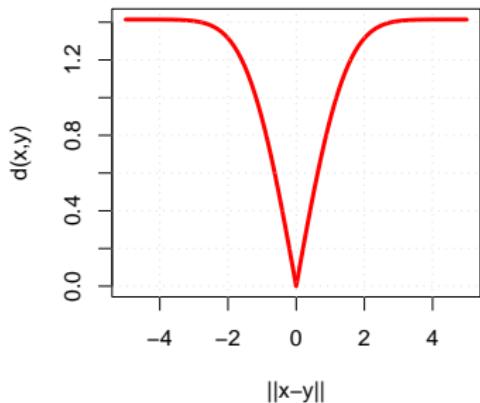
Distance for the Gaussian kernel

- The Gaussian kernel with bandwidth σ on \mathbb{R}^d is:

$$K(\mathbf{x}, \mathbf{y}) = e^{-\frac{\|\mathbf{x}-\mathbf{y}\|^2}{2\sigma^2}},$$

- $K(\mathbf{x}, \mathbf{x}) = 1 = \|\Phi(\mathbf{x})\|_{\mathcal{H}}^2$, so all points are on the unit sphere in the feature space.
- The distance between the images of two points \mathbf{x} and \mathbf{y} in the feature space is given by:

$$d_K(\mathbf{x}, \mathbf{y}) = \sqrt{2 \left[1 - e^{-\frac{\|\mathbf{x}-\mathbf{y}\|^2}{2\sigma^2}} \right]}$$



Example 2: distance between a point and a set

Problem

- Let $\mathcal{S} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$ be a finite set of points in \mathcal{X} .
- How to define and compute the **similarity** between any point \mathbf{x} in \mathcal{X} and the set \mathcal{S} ?

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A solution:

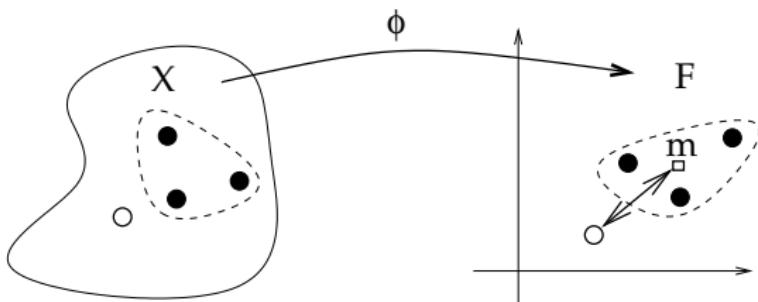
- Map all points to the feature space.
- Summarize \mathcal{S} by the **barycenter** of the points:

$$\boldsymbol{\mu} := \frac{1}{n} \sum_{i=1}^n \Phi(\mathbf{x}_i) .$$

- Define the distance between \mathbf{x} and \mathcal{S} by:

$$d_K(\mathbf{x}, \mathcal{S}) := \| \Phi(\mathbf{x}) - \boldsymbol{\mu} \|_{\mathcal{H}} .$$

Computation



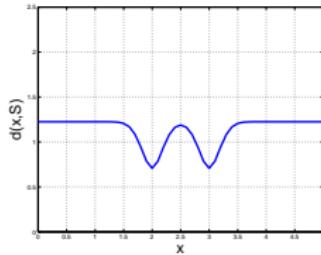
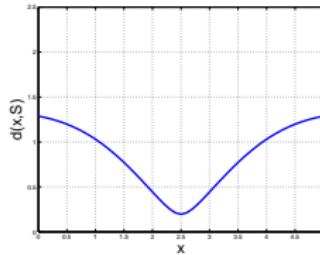
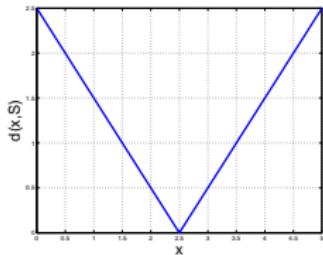
$$\begin{aligned} d_K(\mathbf{x}, \mathcal{S}) &= \left\| \Phi(\mathbf{x}) - \frac{1}{n} \sum_{i=1}^n \Phi(\mathbf{x}_i) \right\|_{\mathcal{H}} \\ &= \sqrt{K(\mathbf{x}, \mathbf{x}) - \frac{2}{n} \sum_{i=1}^n K(\mathbf{x}, \mathbf{x}_i) + \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n K(\mathbf{x}_i, \mathbf{x}_j)}. \end{aligned}$$

Remark

The barycentre μ only exists in the feature space in general: it does not necessarily have a pre-image \mathbf{x}_μ such that $\Phi(\mathbf{x}_\mu) = \mu$.

1D illustration

- $\mathcal{S} = \{2, 3\}$
- Plot $f(x) = d(x, \mathcal{S})$



$$K(x, y) = xy.$$

(linear)

$$K(x, y) = e^{-\frac{(x-y)^2}{2\sigma^2}}.$$

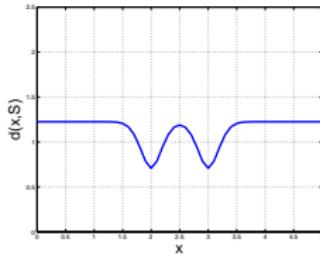
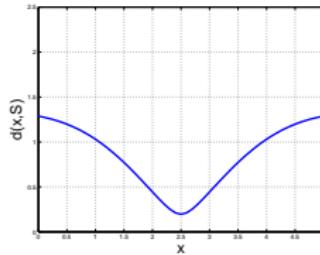
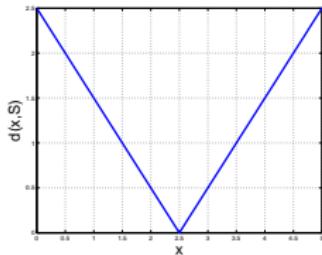
with $\sigma = 1$.

$$K(x, y) = e^{-\frac{(x-y)^2}{2\sigma^2}}.$$

with $\sigma = 0.2$.

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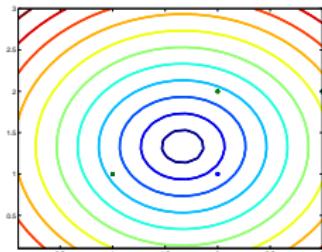
with $\sigma = 0.2$.

Remarks

- for the linear kernel, $\mathcal{H} = \mathbb{R}$, $\mu = 2.5$ and $d(x, \mathcal{S}) = |x - \mu|$.
- for the Gaussian kernel $d(x, \mathcal{S}) = \sqrt{C - \frac{2}{n} \sum_{i=1}^n K(x_i, x)}$.

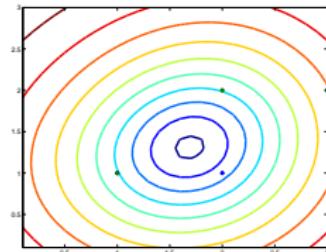
2D illustration

- $\mathcal{S} = \{(1, 1)', (1, 2)', (2, 2)'\}$
- Plot $f(\mathbf{x}) = d(\mathbf{x}, \mathcal{S})$



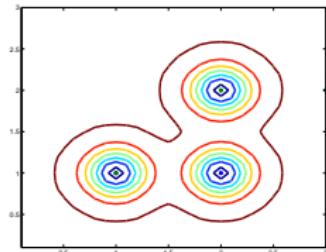
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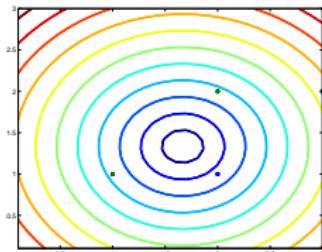


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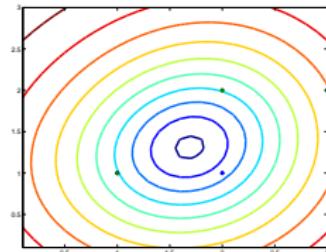
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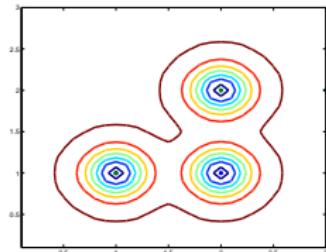
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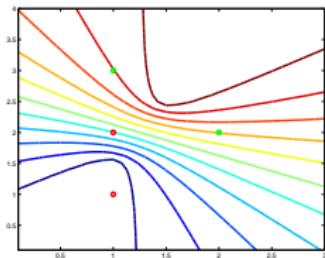
with $\sigma = 0.2$.

Remark

- as before, the barycenter μ in \mathcal{H} (which is a single point in \mathcal{H}) may carry a lot of information about the training data.

Basic application in discrimination

- $\mathcal{S}_1 = \{(1, 1)', (1, 2)'\}$ and $\mathcal{S}_2 = \{(1, 3)', (2, 2)'\}$
- Plot $f(\mathbf{x}) = d(\mathbf{x}, \mathcal{S}_1)^2 - d(\mathbf{x}, \mathcal{S}_2)^2$

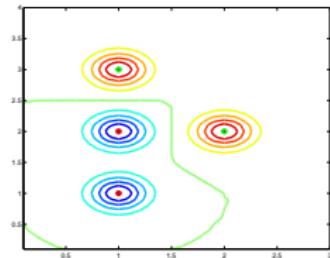


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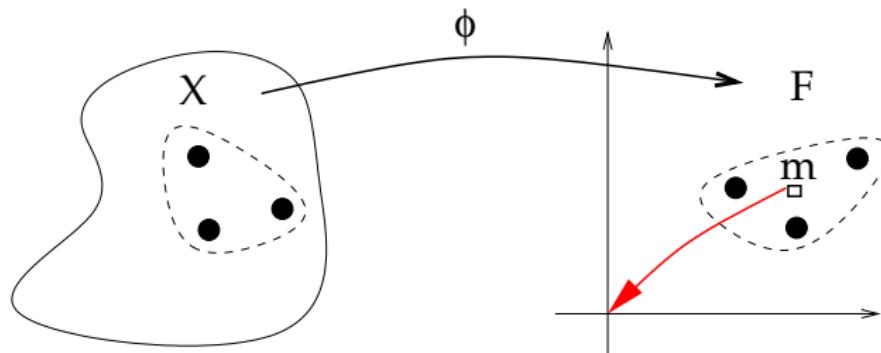
$$K(\mathbf{x}, \mathbf{y}) = e^{-\frac{(\mathbf{x}-\mathbf{y})^2}{2\sigma^2}}.$$

with $\sigma = 0.2$.

Example 3: Centering data in the feature space

Problem

- Let $\mathcal{S} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$ be a finite set of points in \mathcal{X} endowed with a p.d. kernel K . Let \mathbf{K} be their $n \times n$ Gram matrix: $[\mathbf{K}]_{ij} = K(\mathbf{x}_i, \mathbf{x}_j)$.
- Let $\boldsymbol{\mu} = 1/n \sum_{i=1}^n \Phi(\mathbf{x}_i)$ their barycenter, and $\mathbf{u}_i = \Phi(\mathbf{x}_i) - \boldsymbol{\mu}$ for $i = 1, \dots, n$ be centered data in \mathcal{H} .
- How to compute the centered Gram matrix $[\mathbf{K}^c]_{i,j} = \langle \mathbf{u}_i, \mathbf{u}_j \rangle_{\mathcal{H}}$?



Computation

- A direct computation gives, for $0 \leq i, j \leq n$:

$$\begin{aligned}\mathbf{K}_{i,j}^c &= \langle \Phi(\mathbf{x}_i) - \boldsymbol{\mu}, \Phi(\mathbf{x}_j) - \boldsymbol{\mu} \rangle_{\mathcal{H}} \\ &= \langle \Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j) \rangle_{\mathcal{H}} - \langle \boldsymbol{\mu}, \Phi(\mathbf{x}_i) + \Phi(\mathbf{x}_j) \rangle_{\mathcal{H}} + \langle \boldsymbol{\mu}, \boldsymbol{\mu} \rangle_{\mathcal{H}} \\ &= \mathbf{K}_{i,j} - \frac{1}{n} \sum_{k=1}^n (\mathbf{K}_{i,k} + \mathbf{K}_{j,k}) + \frac{1}{n^2} \sum_{k,l=1}^n \mathbf{K}_{k,l}.\end{aligned}$$

- This can be rewritten in matricial form:

$$\mathbf{K}^c = \mathbf{K} - \mathbf{U}\mathbf{K} - \mathbf{K}\mathbf{U} + \mathbf{U}\mathbf{K}\mathbf{U} = (\mathbf{I} - \mathbf{U})\mathbf{K}(\mathbf{I} - \mathbf{U}),$$

where $\mathbf{U}_{i,j} = 1/n$ for $1 \leq i, j \leq n$.

Kernel trick Summary

- The kernel trick is a trivial statement with **important applications**.
- It can be used to obtain **nonlinear** versions of well-known linear algorithms, e.g., by replacing the classical inner product by a Gaussian kernel.
- It can be used to apply classical algorithms to **non vectorial** data (e.g., strings, graphs) by again replacing the classical inner product by a valid kernel for the data.
- It allows in some cases to embed the initial space to a **larger feature space** and involve points in the feature space with no pre-image (e.g., barycenter).

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Motivation

- An RKHS is a space of (potentially nonlinear) functions, and $\|f\|_{\mathcal{H}}$ measures the smoothness of f .
- Given a set of data $(\mathbf{x}_i \in \mathcal{X}, y_i \in \mathbb{R})_{i=1,\dots,n}$, a natural way to estimate a regression function $f : \mathcal{X} \rightarrow \mathbb{R}$ is to solve something like:

$$\min_{f \in \mathcal{H}} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell(y_i, f(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\lambda \|f\|_{\mathcal{H}}^2}_{\text{regularization}}. \quad (1)$$

for a loss function ℓ such as $\ell(y, t) = (y - t)^2$.

- How to solve in practice this problem, potentially in infinite dimension?

The Theorem

Representer Theorem

- Let \mathcal{X} be a set endowed with a p.d. kernel K , \mathcal{H} the corresponding RKHS, and $\mathcal{S} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subseteq \mathcal{X}$ a finite set of points in \mathcal{X} .
- Let $\Psi : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ be a function of $n + 1$ variables, strictly increasing with respect to the last variable.
- Then, any solution to the optimization problem:

$$\min_{f \in \mathcal{H}} \Psi(f(\mathbf{x}_1), \dots, f(\mathbf{x}_n), \|f\|_{\mathcal{H}}),$$

admits a representation of the form:

$$\forall \mathbf{x} \in \mathcal{X}, \quad f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}) = \sum_{i=1}^n \alpha_i K_{\mathbf{x}_i}(\mathbf{x}).$$

In other words, the solution lives in a finite-dimensional subspace:

$$f \in \text{Span}(K_{\mathbf{x}_1}, \dots, K_{\mathbf{x}_n}).$$

Proof (1/2)

- Let $\xi(f)$ be the functional that is minimized in the statement of the representer theorem, and \mathcal{H}_S the linear span in \mathcal{H} of the vectors $K_{\mathbf{x}_i}$:

$$\mathcal{H}_S = \left\{ f \in \mathcal{H} : f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}), (\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n \right\}.$$

- \mathcal{H}_S is a finite-dimensional subspace, therefore any function $f \in \mathcal{H}$ can be uniquely decomposed as:

$$f = f_S + f_{\perp},$$

with $f_S \in \mathcal{H}_S$ and $f_{\perp} \perp \mathcal{H}_S$ (by orthogonal projection).

Proof (2/2)

- \mathcal{H} being a RKHS it holds that:

$$\forall i = 1, \dots, n, \quad f_{\perp}(\mathbf{x}_i) = \langle f_{\perp}, K_{\mathbf{x}_i} \rangle_{\mathcal{H}} = 0,$$

because $K_{\mathbf{x}_i} = (\mathbf{x}_i, \cdot) \in \mathcal{H}$, therefore:

$$\forall i = 1, \dots, n, \quad f(\mathbf{x}_i) = f_S(\mathbf{x}_i).$$

- Pythagoras' theorem in \mathcal{H} then shows that:

$$\|f\|_{\mathcal{H}}^2 = \|f_S\|_{\mathcal{H}}^2 + \|f_{\perp}\|_{\mathcal{H}}^2.$$

- As a consequence, $\xi(f) \geq \xi(f_S)$, with equality if and only if $\|f_{\perp}\|_{\mathcal{H}} = 0$. **The minimum of Ψ is therefore necessarily in \mathcal{H}_S .**



Remarks

Often the function Ψ has the form:

$$\Psi(f(\mathbf{x}_1), \dots, f(\mathbf{x}_n), \|f\|_{\mathcal{H}}) = c(f(\mathbf{x}_1), \dots, f(\mathbf{x}_n)) + \lambda \Omega(\|f\|_{\mathcal{H}})$$

where $c(\cdot)$ measures the “fit” of f to a given problem (regression, classification, dimension reduction, ...) and Ω is strictly increasing. This formulation has two important consequences:

- **Theoretically**, the minimization will enforce the norm $\|f\|_{\mathcal{H}}$ to be “small”, which can be beneficial by ensuring a sufficient level of smoothness for the solution (regularization effect).
- **Practically**, we know by the representer theorem that the solution lives in a **subspace of dimension n** , which can lead to efficient algorithms although the RKHS itself can be of infinite dimension.

Practical use of the representer theorem (1/2)

- When the representer theorem holds, we know that we can look for a solution of the form

$$f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}), \quad \text{for some } \boldsymbol{\alpha} \in \mathbb{R}^n.$$

- For any $j = 1, \dots, n$, we have

$$f(\mathbf{x}_j) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}_j) = [\mathbf{K}\boldsymbol{\alpha}]_j.$$

- Furthermore,

$$\|f\|_{\mathcal{H}}^2 = \left\| \sum_{i=1}^n \alpha_i K_{\mathbf{x}_i} \right\|_{\mathcal{H}}^2 = \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j) = \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}.$$

Practical use of the representer theorem (2/2)

- Therefore, a problem of the form

$$\min_{f \in \mathcal{H}} \Psi(f(\mathbf{x}_1), \dots, f(\mathbf{x}_n), \|f\|_{\mathcal{H}}^2)$$

is equivalent to the following n -dimensional optimization problem:

$$\min_{\alpha \in \mathbb{R}^n} \Psi([\mathbf{K}\alpha]_1, \dots, [\mathbf{K}\alpha]_n, \alpha^\top \mathbf{K}\alpha).$$

- This problem can usually be solved analytically or by numerical methods; we will see many examples in the next sections.

Remarks

Dual interpretations of kernel methods

Most kernel methods have two complementary interpretations:

- A **geometric interpretation** in the feature space, thanks to the kernel trick. Even when the feature space is “large”, most kernel methods work in the linear span of the embeddings of the points available.
- A **functional interpretation**, often as an optimization problem over (subsets of) the RKHS associated to the kernel.

The representer theorem has important consequences, but it is in fact rather trivial. We are looking for a function f in \mathcal{H} such that for all \mathbf{x} in \mathcal{X} , $f(\mathbf{x}) = \langle K_{\mathbf{x}}, f \rangle_{\mathcal{H}}$. The part f^\perp that is orthogonal to the $K_{\mathbf{x}_i}$'s is thus “useless” to explain the training data.

Kernel Methods

Supervised Learning

Supervised learning

Definition

Given:

- \mathcal{X} , a space of **inputs**,
- \mathcal{Y} , a space of **outputs**,
- $\mathcal{S}_n = (\mathbf{x}_i, y_i)_{i=1, \dots, n}$, a **training set** of (input,output) pairs,

the **supervised learning problem** is to estimate a function $h : \mathcal{X} \rightarrow \mathcal{Y}$ to **predict** the output for any future input.

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Depending on the nature of the output, this covers:

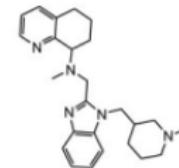
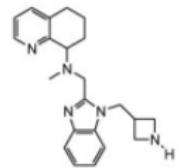
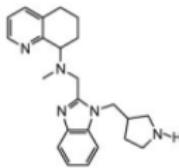
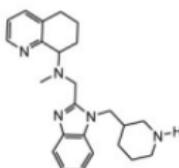
- **Regression** when $\mathcal{Y} = \mathbb{R}$;
- **Classification** when $\mathcal{Y} = \{-1, 1\}$ or any set of two labels;
- **Structured output** regression or classification when \mathcal{Y} is more general.

Example: regression

Task: predict the capacity of a small molecule to inhibit a drug target

\mathcal{X} = set of molecular structures (graphs?)

$\mathcal{Y} = \mathbb{R}$

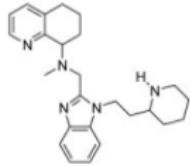
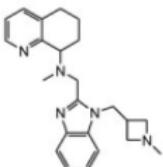
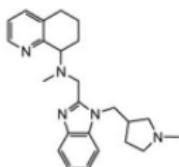


$IC_{50} = 51 \pm 2 \text{nM}$

$IC_{50} = 24 \pm 1 \text{nM}$

$IC_{50} = 84 \pm 7 \text{nM}$

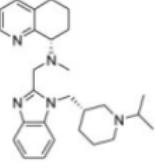
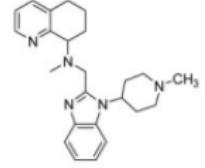
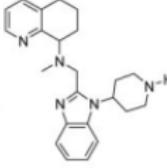
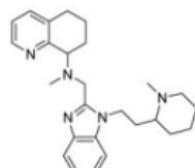
$IC_{50} = 19 \pm 2 \text{nM}$



$IC_{50} = 57 \pm 2 \text{nM}$

$IC_{50} = 66 \pm 5 \text{nM}$

$IC_{50} = 64 \pm 4 \text{nM}$



$IC_{50} = 33 \pm 1 \text{nM}$

$IC_{50} = 99 \pm 6 \text{nM}$

$IC_{50} = 95 \pm 8 \text{nM}$

$IC_{50} = 2.0 \pm 1 \text{nM}$

Example: classification

Task: recognize if an image is a dog or a cat

\mathcal{X} = set of images (\mathbb{R}^d)

$\mathcal{Y} = \{\text{cat}, \text{dog}\}$



Example: classification

Task: recognize if an image is a dog or a cat

\mathcal{X} = set of images (\mathbb{R}^d)

$\mathcal{Y} = \{\text{cat}, \text{dog}\}$



Example: structured output

Task: translate from Japanese to French

\mathcal{X} = finite-length strings of japanese characters

\mathcal{Y} = finite-length strings of french characters

The screenshot shows the Google Translate interface on a web browser. The URL in the address bar is `translate.google.fr`. The main content area has "Traduction" at the top left and "Désactiver la traduction instantanée" at the top right. Below this, there are two input fields: one for Japanese ("Japonais - détecté") containing the text "猿も木から落ちる" and another for French ("Français") containing the translation "Même les singes tombent des arbres". The "Traduire" button is located between the two input fields. At the bottom of the page, there are links for "À propos de Google Traduction", "Communauté", "Mobile", "G+", and "Envoyer des commentaires".

Supervised learning with kernels: general principles

- ① Express $h : \mathcal{X} \rightarrow \mathcal{Y}$ using a real-valued function $f : \mathcal{Z} \rightarrow \mathbb{R}$:

- regression $\mathcal{Y} = \mathbb{R}$:

$$h(\mathbf{x}) = f(\mathbf{x}) \quad \text{with} \quad f : \mathcal{X} \rightarrow \mathbb{R} \quad (\mathcal{Z} = \mathcal{X})$$

- classification $\mathcal{Y} = \{-1, 1\}$:

$$h(\mathbf{x}) = \text{sign}(f(\mathbf{x})) \quad \text{with} \quad f : \mathcal{X} \rightarrow \mathbb{R} \quad (\mathcal{Z} = \mathcal{X})$$

- structured output:

$$h(\mathbf{x}) = \arg \max_{\mathbf{y} \in \mathcal{Y}} f(\mathbf{x}, \mathbf{y}) \quad \text{with} \quad f : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R} \quad (\mathcal{Z} = \mathcal{X} \times \mathcal{Y})$$

- ② Define an empirical risk function $R_n(f)$ to assess how "good" a candidate function f is on the training set \mathcal{S}_n , typically the average of a loss:

$$R_n(f) := \frac{1}{n} \sum_{i=1}^n \ell(f(\mathbf{x}_i), \mathbf{y}_i)$$

- ③ Define a p.d. kernel on \mathcal{Z} and solve

$$\min_{f \in \mathcal{H}, \|f\|_{\mathcal{H}} \leq B} R_n(f) \quad \text{or} \quad \min_{f \in \mathcal{H}} R_n(f) + \lambda \|f\|_{\mathcal{H}}^2$$

Remarks

$$\min_{f \in \mathcal{H}} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell(f(\mathbf{x}_i), y_i)}_{\text{empirical risk, data fit}} + \underbrace{\lambda \|f\|_{\mathcal{H}}^2}_{\text{regularization}}.$$

- Regularization is important, particularly in high dimension, to prevent **overfitting**
- When $\mathcal{Z} = \mathbb{R}^d$ and K is the linear kernel, $f = f_w$ is a linear model and the regularization is $\|w\|^2$
- Using more general spaces \mathcal{Z} and kernels K allows to
 - learn **non-linear functions** over a functional space endowed with a natural regularization (remember, small norm in RKHS = "smooth")
 - learn functions over **non-vectorial data**, such as strings and graphs

We will now see a few methods in more details

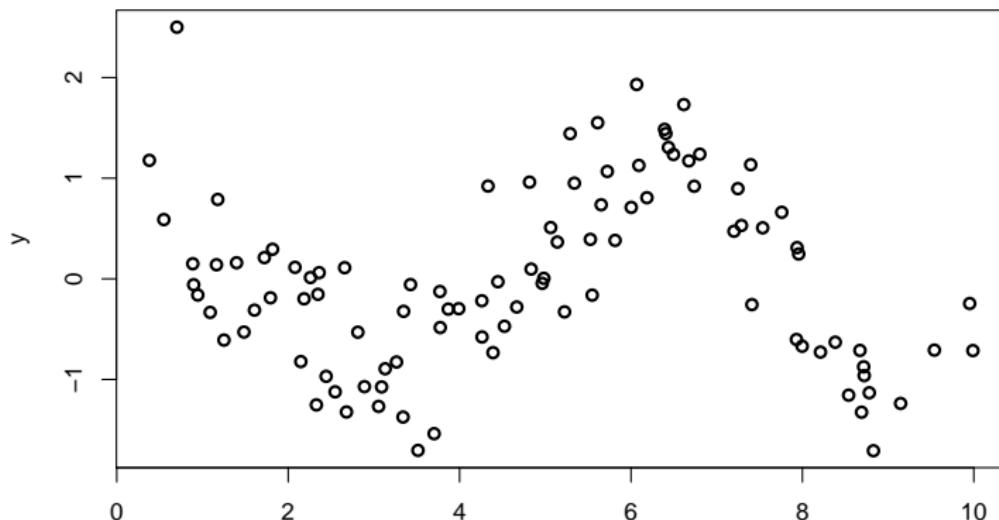
Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
 - Kernel ridge regression
 - Kernel logistic regression
 - Large-margin classifiers
 - Interlude: convex optimization and duality
 - Support vector machines
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
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Regression

Setup

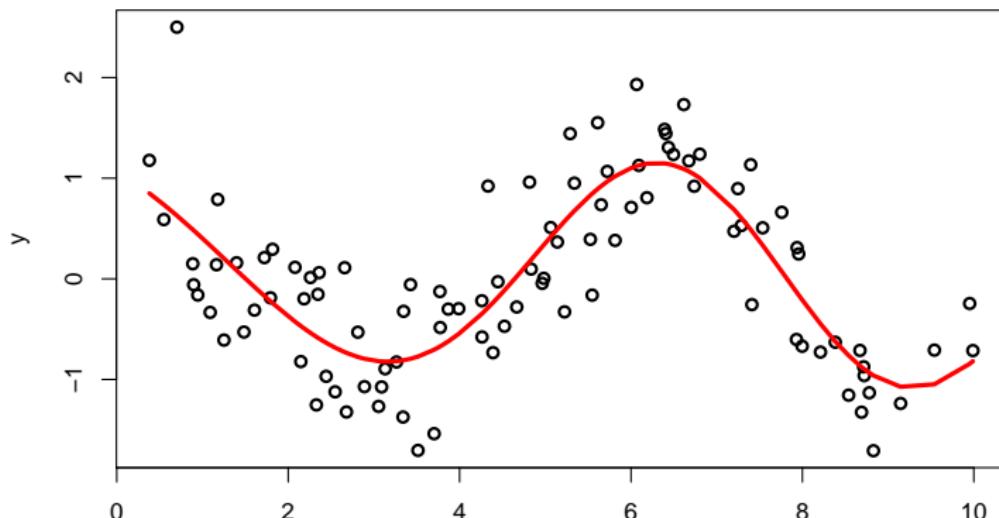
- \mathcal{X} set of inputs
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- $\mathcal{S}_n = (\mathbf{x}_i, y_i)_{i=1, \dots, n} \in (\mathcal{X} \times \mathbb{R})^n$ a training set of n pairs
- Goal = find a function $f : \mathcal{X} \rightarrow \mathbb{R}$ to predict y by $f(\mathbf{x})$



Regression

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Least-square regression over a general functional space

- Let us quantify the error if f predicts $f(\mathbf{x})$ instead of y by the squared error:

$$\ell(f(\mathbf{x}), y) = (y - f(\mathbf{x}))^2$$

- Fix a set of functions \mathcal{H} .
- Least-square regression** amounts to finding the function in \mathcal{H} with the smallest empirical risk, called in this case the mean squared error (MSE):

$$\hat{f} \in \arg \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2$$

- Issues: unstable (especially in large dimensions), overfitting if \mathcal{H} is too “large”.

Kernel ridge regression (KRR)

- Let us now consider a RKHS \mathcal{H} , associated to a p.d. kernel K on \mathcal{X} .
- KRR is obtained by **regularizing** the MSE criterion by the RKHS norm:

$$\hat{f} = \arg \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}}^2 \quad (2)$$

- 1st effect = prevent overfitting by penalizing non-smooth functions.*

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- 1st effect = prevent overfitting by penalizing non-smooth functions.*
- By the representer theorem, any solution of (2) can be expanded as

$$\hat{f}(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}).$$

- 2nd effect = simplifying the solution.*

Solving KRR

- Let $\mathbf{y} = (y_1, \dots, y_n)^\top \in \mathbb{R}^n$
- Let $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_n)^\top \in \mathbb{R}^n$
- Let \mathbf{K} be the $n \times n$ Gram matrix: $\mathbf{K}_{ij} = K(\mathbf{x}_i, \mathbf{x}_j)$
- We can then write:

$$(\hat{f}(\mathbf{x}_1), \dots, \hat{f}(\mathbf{x}_n))^\top = \mathbf{K}\boldsymbol{\alpha}$$

- The following holds as usual:

$$\|\hat{f}\|_{\mathcal{H}}^2 = \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}$$

- The KRR problem (2) is therefore equivalent to:

$$\arg \min_{\boldsymbol{\alpha} \in \mathbb{R}^n} \frac{1}{n} (\mathbf{K}\boldsymbol{\alpha} - \mathbf{y})^\top (\mathbf{K}\boldsymbol{\alpha} - \mathbf{y}) + \lambda \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}$$

Solving KRR

$$\arg \min_{\alpha \in \mathbb{R}^n} \frac{1}{n} (\mathbf{K}\alpha - \mathbf{y})^\top (\mathbf{K}\alpha - \mathbf{y}) + \lambda \alpha^\top \mathbf{K}\alpha$$

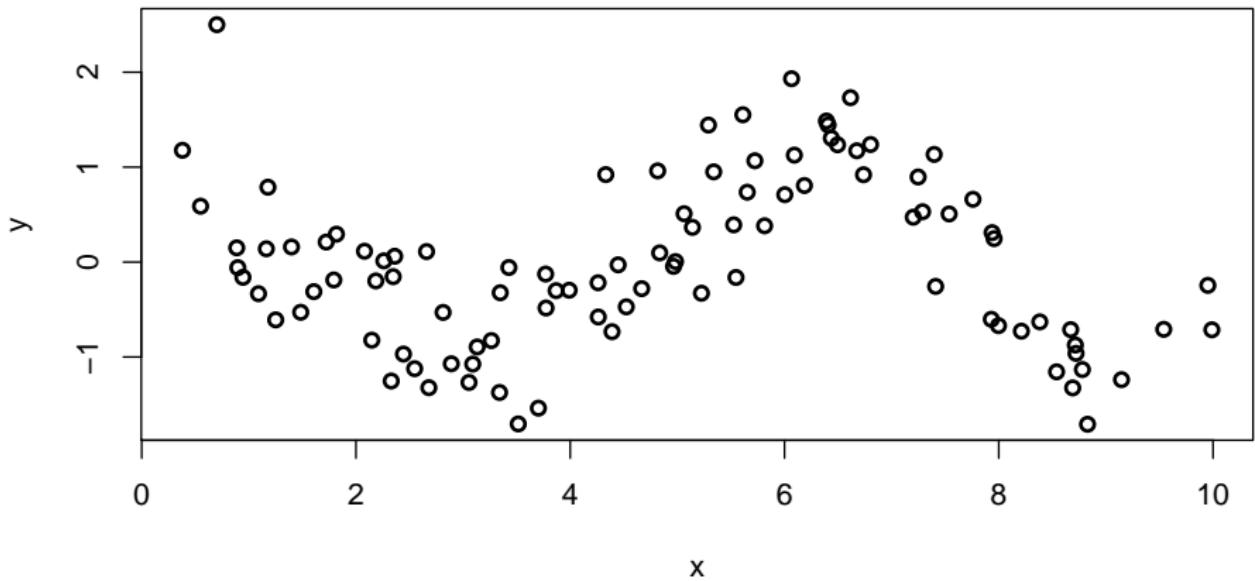
- This is a convex and differentiable function of α . Its minimum can therefore be found by setting the gradient in α to zero:

$$\begin{aligned} 0 &= \frac{2}{n} \mathbf{K} (\mathbf{K}\alpha - \mathbf{y}) + 2\lambda \mathbf{K}\alpha \\ &= \mathbf{K} [(\mathbf{K} + \lambda n \mathbf{I}) \alpha - \mathbf{y}] \end{aligned}$$

- For $\lambda > 0$, $\mathbf{K} + \lambda n \mathbf{I}$ is invertible (because \mathbf{K} is positive semidefinite) so one solution is to take:

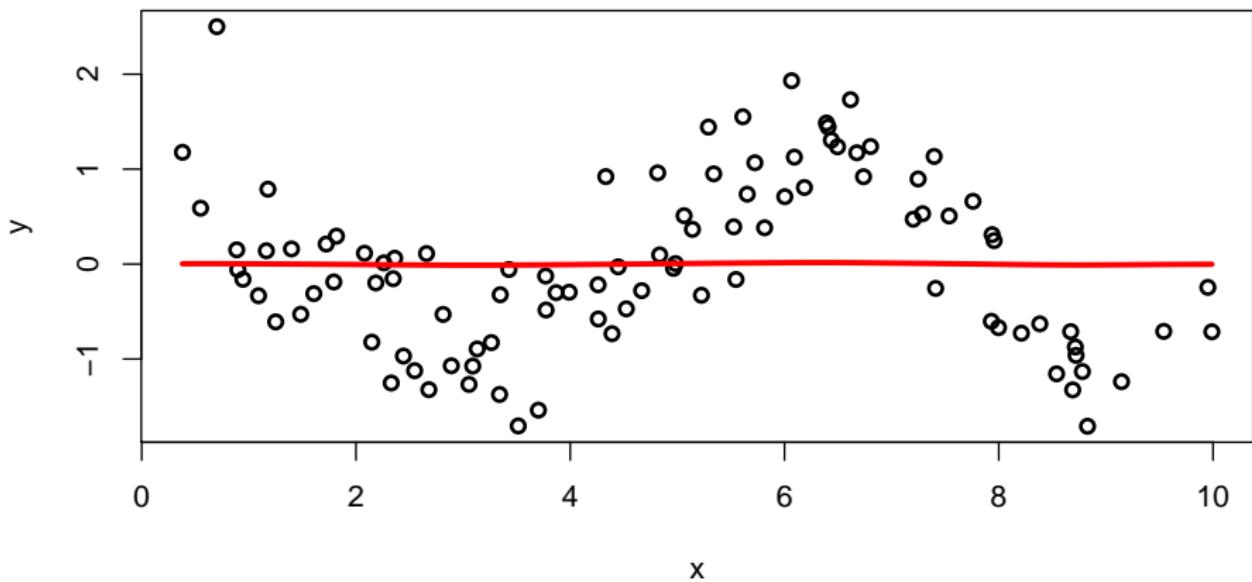
$$\alpha = (\mathbf{K} + \lambda n \mathbf{I})^{-1} \mathbf{y}.$$

Example (KRR with Gaussian RBF kernel)



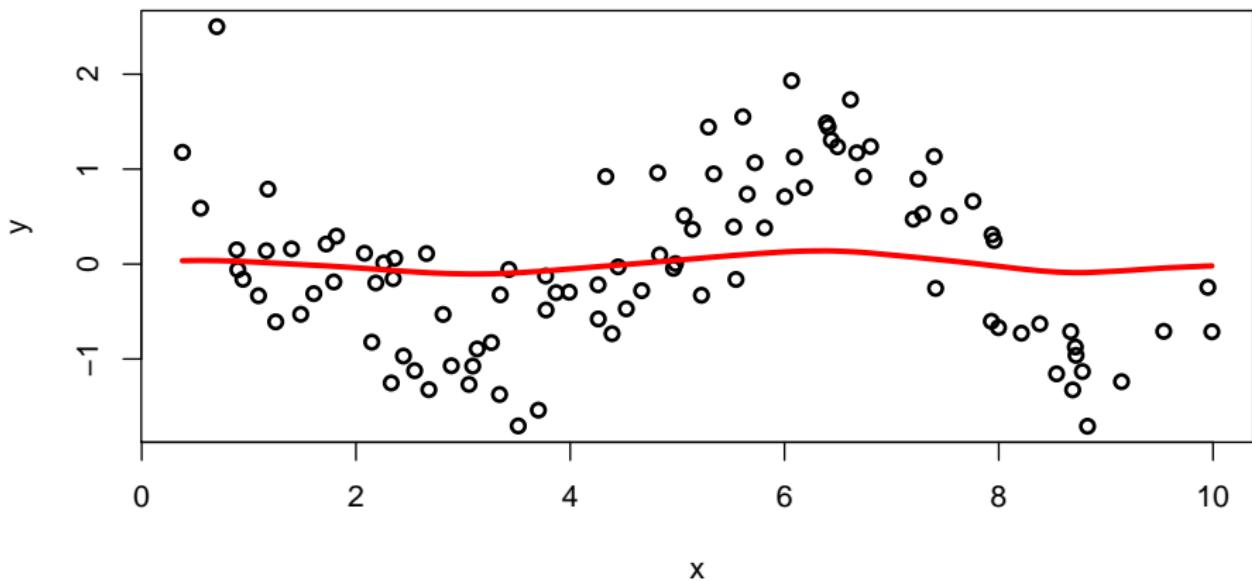
Example (KRR with Gaussian RBF kernel)

lambda = 1000



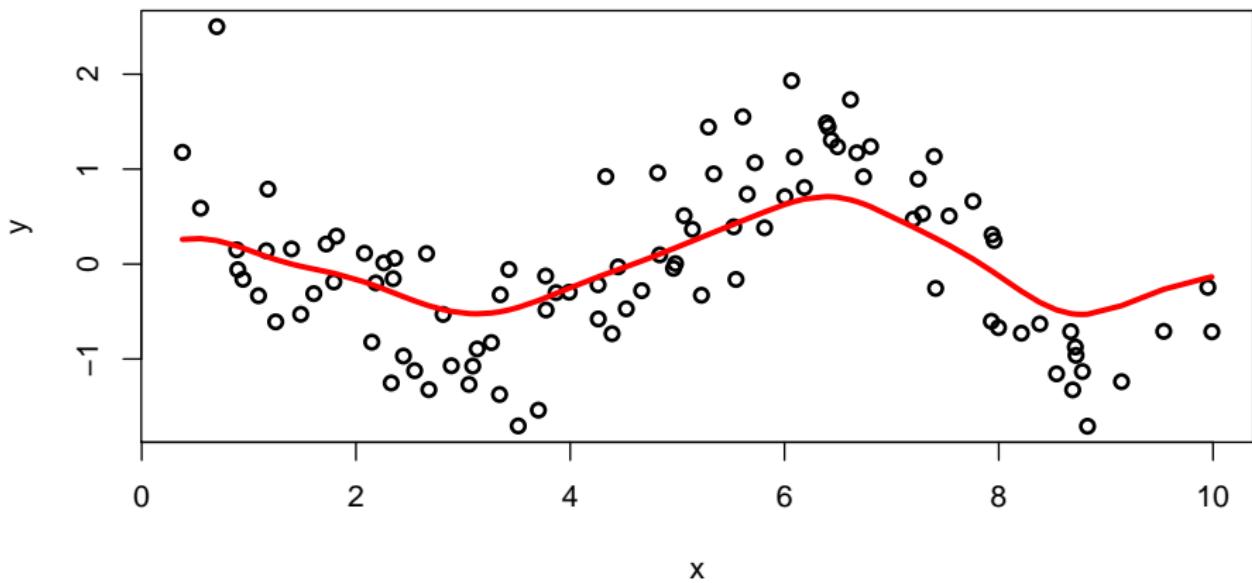
Example (KRR with Gaussian RBF kernel)

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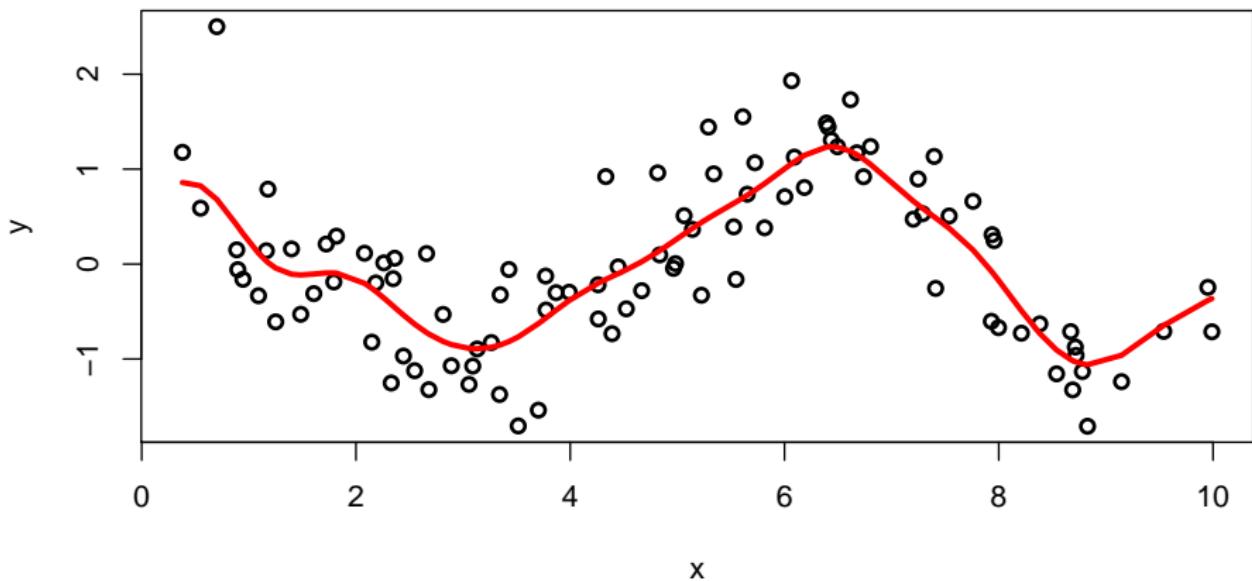
Example (KRR with Gaussian RBF kernel)

lambda = 10



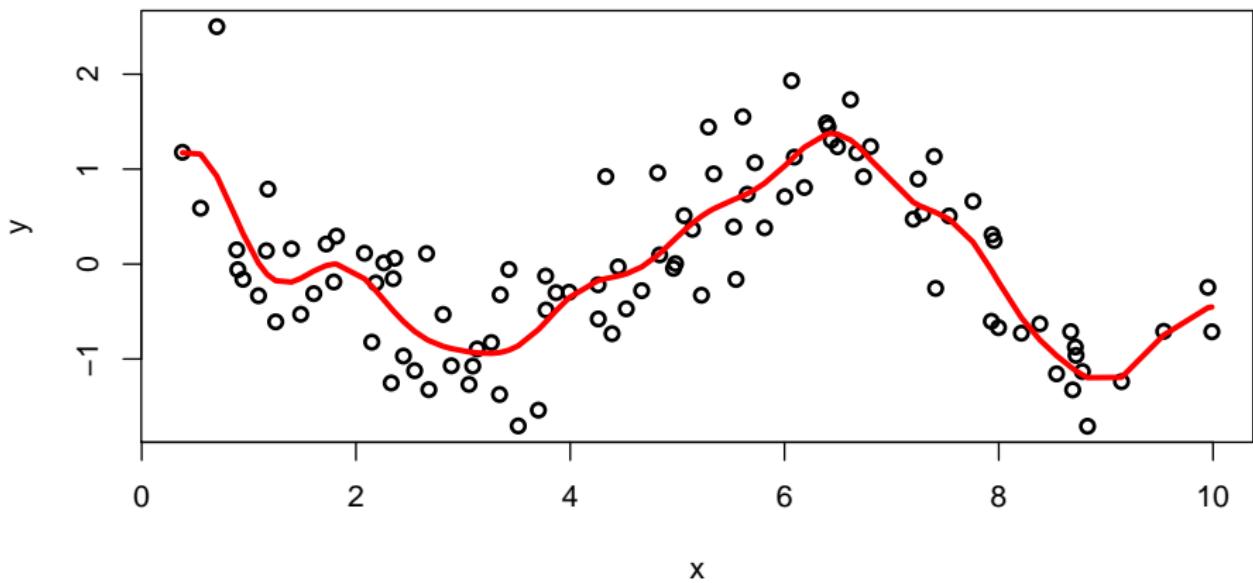
Example (KRR with Gaussian RBF kernel)

lambda = 1



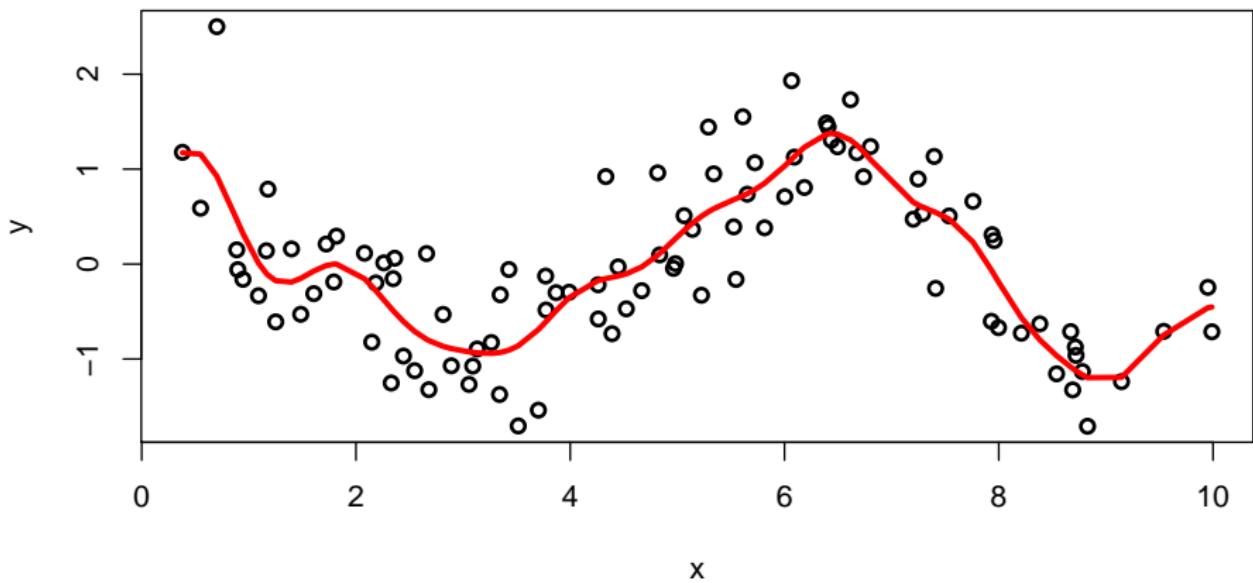
Example (KRR with Gaussian RBF kernel)

lambda = 0.1



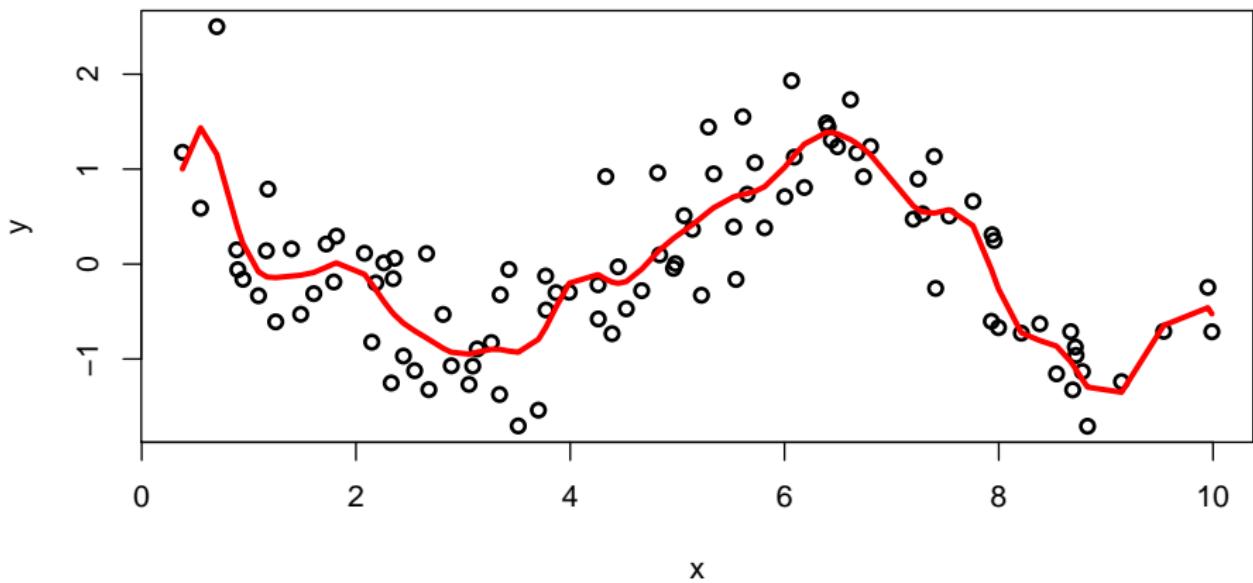
Example (KRR with Gaussian RBF kernel)

lambda = 0.01



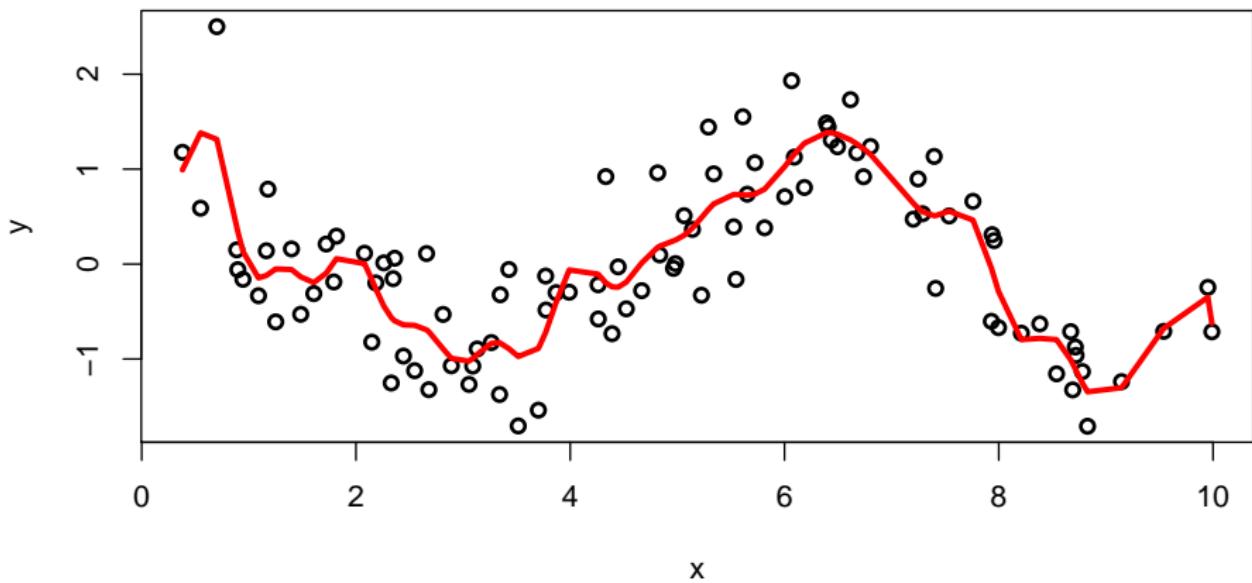
Example (KRR with Gaussian RBF kernel)

lambda = 0.001



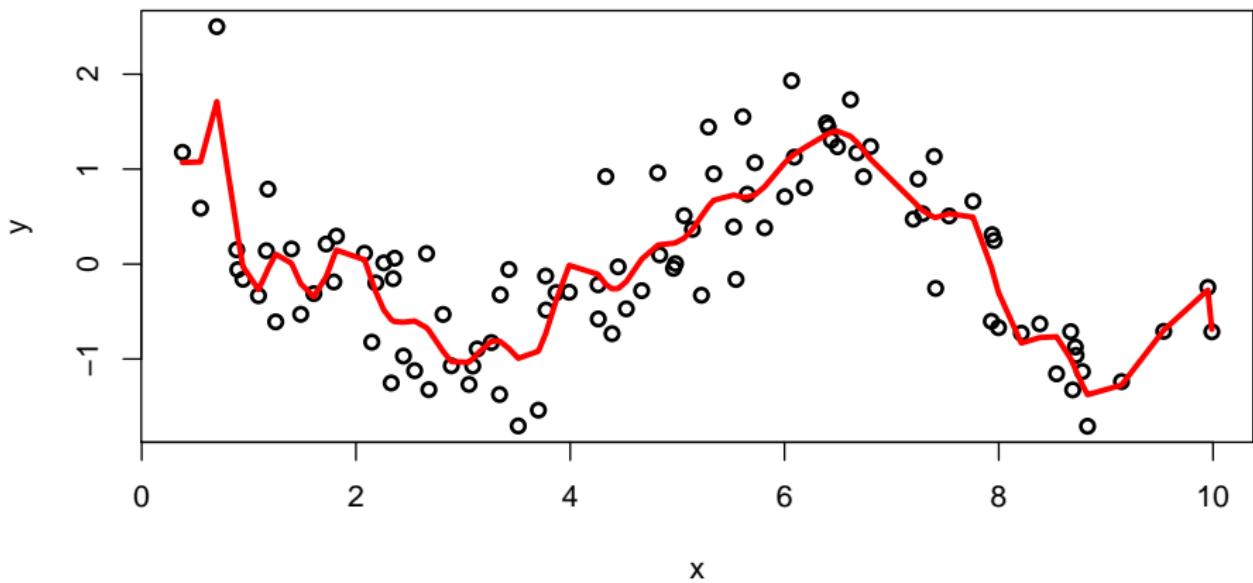
Example (KRR with Gaussian RBF kernel)

lambda = 0.0001



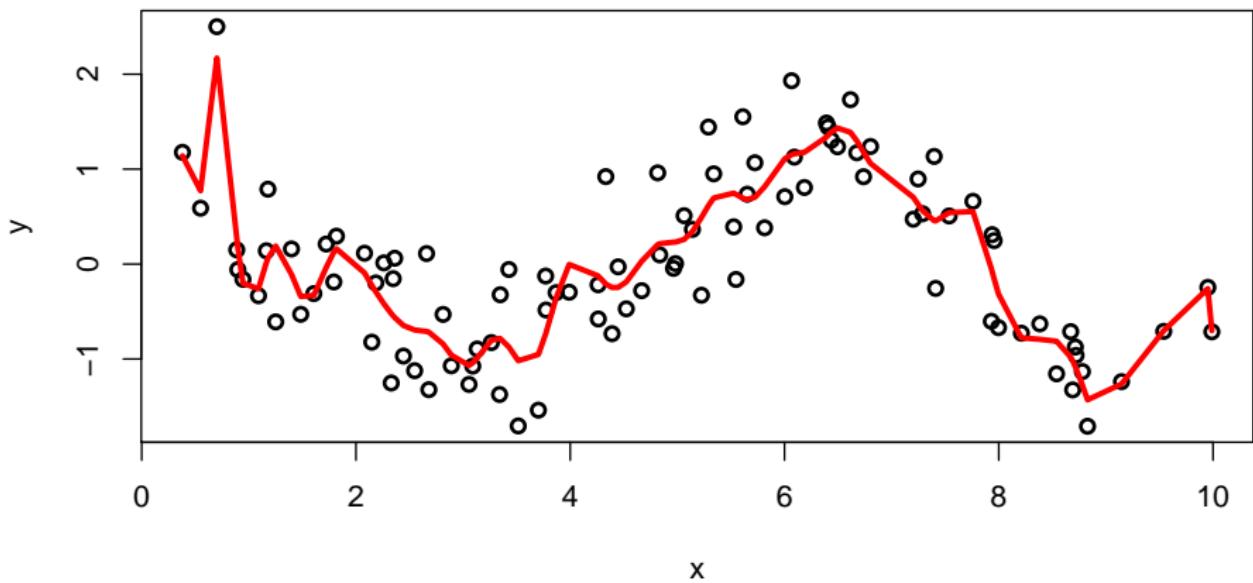
Example (KRR with Gaussian RBF kernel)

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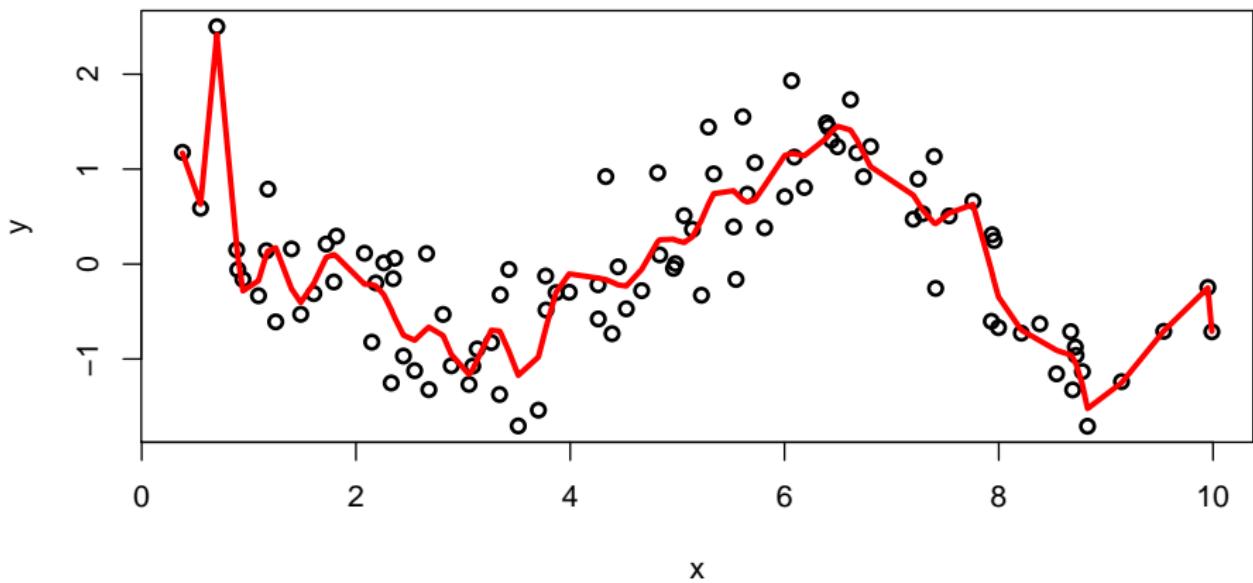
Example (KRR with Gaussian RBF kernel)

lambda = 0.000001



Example (KRR with Gaussian RBF kernel)

lambda = 0.0000001



Remark: uniqueness of the solution

Let us find *all* α 's that solve

$$\mathbf{K}[(\mathbf{K} + \lambda n \mathbf{I})\alpha - \mathbf{y}] = 0$$

- \mathbf{K} being a symmetric matrix, it can be diagonalized in an orthonormal basis and $\text{Ker}(\mathbf{K}) \perp \text{Im}(\mathbf{K})$.
- In this basis we see that $(\mathbf{K} + \lambda n \mathbf{I})^{-1}$ leaves $\text{Im}(\mathbf{K})$ and $\text{Ker}(\mathbf{K})$ invariant.
- The problem is therefore equivalent to:

$$\begin{aligned} & (\mathbf{K} + \lambda n \mathbf{I})\alpha - \mathbf{y} \in \text{Ker}(\mathbf{K}) \\ \Leftrightarrow & \alpha - (\mathbf{K} + \lambda n \mathbf{I})^{-1}\mathbf{y} \in \text{Ker}(\mathbf{K}) \\ \Leftrightarrow & \alpha = (\mathbf{K} + \lambda n \mathbf{I})^{-1}\mathbf{y} + \epsilon, \text{ with } \mathbf{K}\epsilon = 0. \end{aligned}$$

- However, if $\alpha' = \alpha + \epsilon$ with $\mathbf{K}\epsilon = 0$, then:

$$\|f - f'\|_{\mathcal{H}}^2 = (\alpha - \alpha')^\top \mathbf{K} (\alpha - \alpha') = 0,$$

therefore $f = f'$. KRR has a unique solution $f \in \mathcal{H}$, which can possibly be expressed by several α 's if K is singular.

Remark: link with "standard" ridge regression

- Take $\mathcal{X} = \mathbb{R}^d$ and the linear kernel $K(\mathbf{x}, \mathbf{x}') = \mathbf{x}^\top \mathbf{x}'$
- Let $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)^\top$ the $n \times d$ data matrix
- The kernel matrix is then $\mathbf{K} = \mathbf{XX}^\top$
- The function learned by KRR in that case is linear:

$$f_{KRR}(\mathbf{x}) = \mathbf{w}_{KRR}^\top \mathbf{x}$$

with

$$\mathbf{w}_{KRR} = \sum_{i=1}^n \alpha_i \mathbf{x}_i = \mathbf{X}^\top \boldsymbol{\alpha} = \mathbf{X}^\top \left(\mathbf{XX}^\top + \lambda n \mathbf{I} \right)^{-1} \mathbf{y}$$

Remark: link with "standard" ridge regression

- On the other hand, the RKHS is the set of linear functions $f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x}$ and the RKHS norm is $\|f\|_{\mathcal{H}} = \|\mathbf{w}\|$
- We can therefore directly rewrite the original KRR problem (2) as

$$\begin{aligned} \arg \min_{\mathbf{w} \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{w}^\top \mathbf{x}_i)^2 + \lambda \|\mathbf{w}\|^2 \\ = \arg \min_{\mathbf{w} \in \mathbb{R}^d} \frac{1}{n} (\mathbf{y} - \mathbf{X}\mathbf{w})^\top (\mathbf{y} - \mathbf{X}\mathbf{w}) + \lambda \mathbf{w}^\top \mathbf{w} \end{aligned}$$

- Setting the gradient to 0 gives the solution:

$$\mathbf{w}_{RR} = (\mathbf{X}^\top \mathbf{X} + \lambda n \mathbf{I})^{-1} \mathbf{X}^\top \mathbf{y}$$

- Oups, looks different from $\mathbf{w}_{KRR} = \mathbf{X}^\top (\mathbf{X}\mathbf{X}^\top + \lambda n \mathbf{I})^{-1} \mathbf{y}$...?

Remark: link with "standard" ridge regression

Matrix inversion lemma

For any matrices B and C , and $\gamma > 0$ the following holds (when it makes sense):

$$B(CB + \gamma \mathbf{I})^{-1} = (BC + \gamma \mathbf{I})^{-1} B$$

We deduce that (of course...):

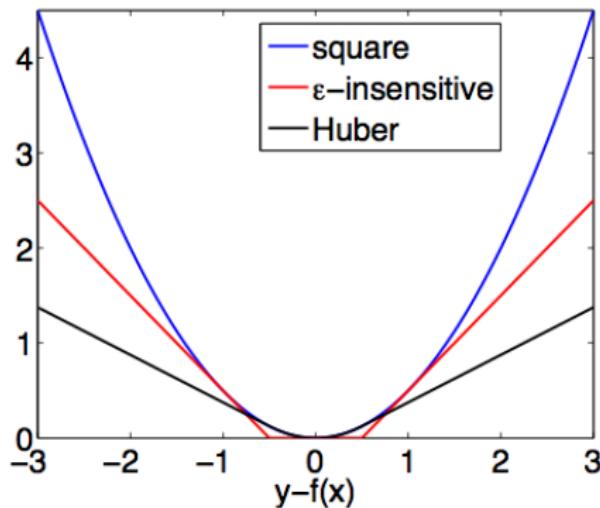
$$\mathbf{w}_{RR} = \underbrace{\left(\mathbf{X}^\top \mathbf{X} + \lambda n \mathbf{I} \right)^{-1}}_{d \times d} \mathbf{X}^\top \mathbf{y} = \mathbf{X}^\top \underbrace{\left(\mathbf{X} \mathbf{X}^\top + \lambda n \mathbf{I} \right)^{-1}}_{n \times n} \mathbf{y} = \mathbf{w}_{KRR}$$

Computationally, inverting the matrix is the expensive part, which suggest to implement:

- KRR when $d > n$ (high dimension)
- RR when $d < n$ (many points)

Robust regression

- The squared error $\ell(t, y) = (t - y)^2$ is arbitrary and sensitive to outliers
- Many other loss functions exist for regression, e.g.:



- Any loss function leads to a valid kernel method, which is usually solved by numerical optimization as there is usually no analytical solution beyond the squared error.

Weighted regression

- Given weights $W_1, \dots, W_n \in \mathbb{R}$, a variant of ridge regression is to weight differently the error at different points:

$$\arg \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n W_i (y_i - f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}}^2$$

- By the representer theorem the solution is $f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x})$ where $\boldsymbol{\alpha}$ solves, with $\mathbf{W} = \text{diag}(W_1, \dots, W_n)$:

$$\arg \min_{\boldsymbol{\alpha} \in \mathbb{R}^n} \frac{1}{n} (\mathbf{K}\boldsymbol{\alpha} - \mathbf{y})^\top \mathbf{W} (\mathbf{K}\boldsymbol{\alpha} - \mathbf{y}) + \lambda \boldsymbol{\alpha}^\top \mathbf{K}\boldsymbol{\alpha}$$

Weighted regression

- Setting the gradient to zero gives

$$\begin{aligned} 0 &= \frac{2}{n} (\mathbf{K} \mathbf{W} \mathbf{K} \boldsymbol{\alpha} - \mathbf{K} \mathbf{W} \mathbf{y}) + 2\lambda \mathbf{K} \boldsymbol{\alpha} \\ &= \frac{2}{n} \mathbf{K} \mathbf{W}^{\frac{1}{2}} \left[\left(\mathbf{W}^{\frac{1}{2}} \mathbf{K} \mathbf{W}^{\frac{1}{2}} + n\lambda \mathbf{I} \right) \mathbf{W}^{-\frac{1}{2}} \boldsymbol{\alpha} - \mathbf{W}^{\frac{1}{2}} \mathbf{y} \right] \end{aligned}$$

- A solution is therefore given by

$$\left(\mathbf{W}^{\frac{1}{2}} \mathbf{K} \mathbf{W}^{\frac{1}{2}} + n\lambda \mathbf{I} \right) \mathbf{W}^{-\frac{1}{2}} \boldsymbol{\alpha} - \mathbf{W}^{\frac{1}{2}} \mathbf{y} = 0$$

therefore

$$\boldsymbol{\alpha} = \mathbf{W}^{\frac{1}{2}} \left(\mathbf{W}^{\frac{1}{2}} \mathbf{K} \mathbf{W}^{\frac{1}{2}} + n\lambda \mathbf{I} \right)^{-1} \mathbf{W}^{\frac{1}{2}} \mathbf{Y}$$

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- 1 Kernels and RKHS
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 - Kernel ridge regression
 - **Kernel logistic regression**
 - Large-margin classifiers
 - Interlude: convex optimization and duality
 - Support vector machines
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Binary classification

Setup

- \mathcal{X} set of inputs
- $\mathcal{Y} = \{-1, 1\}$ binary outputs
- $\mathcal{S}_n = (\mathbf{x}_i, y_i)_{i=1, \dots, n} \in (\mathcal{X} \times \mathcal{Y})^n$ a training set of n pairs
- Goal = find a function $f : \mathcal{X} \rightarrow \mathbb{R}$ to predict y by $\text{sign}(f(\mathbf{x}))$



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The 0/1 loss

- The 0/1 loss measures if a prediction is correct or not:

$$\ell_{0/1}(f(\mathbf{x}), y) = \mathbf{1}(y f(\mathbf{x}) < 0) = \begin{cases} 0 & \text{if } y = \text{sign}(f(\mathbf{x})) \\ 1 & \text{otherwise.} \end{cases}$$

- It is then tempting to learn f by solving:

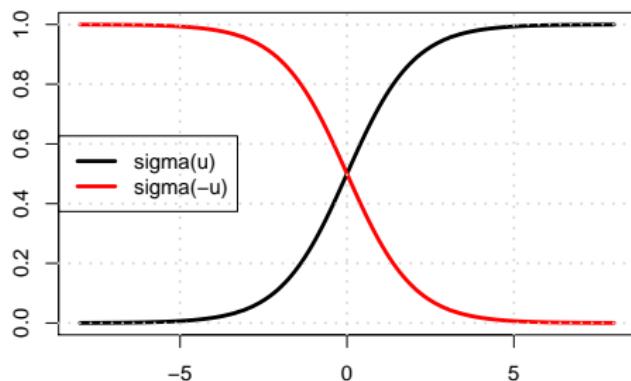
$$\min_{f \in \mathcal{H}} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell_{0/1}(f(\mathbf{x}_i), y_i)}_{\text{misclassification rate}} + \underbrace{\lambda \|f\|_{\mathcal{H}}^2}_{\text{regularization}}$$

- However:
 - The problem is non-smooth, and typically NP-hard to solve
 - The regularization has **no effect** since the 0/1 loss is invariant by scaling of f
 - In fact, no function achieves the minimum when $\lambda > 0$ (*why?*)

The logistic loss

- An alternative is to define a probabilistic model of y parametrized by $f(\mathbf{x})$, e.g.:

$$\forall y \in \{-1, 1\}, \quad p(y | f(\mathbf{x})) = \frac{1}{1 + e^{-yf(\mathbf{x})}} = \sigma(yf(\mathbf{x}))$$



- The **logistic loss** is the negative conditional likelihood:

$$\ell_{logistic}(f(\mathbf{x}), y) = -\ln p(y | f(\mathbf{x})) = \ln \left(1 + e^{-yf(\mathbf{x})} \right)$$

Kernel logistic regression (KLR)

$$\begin{aligned}\hat{f} &= \arg \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ell_{\text{logistic}}(f(\mathbf{x}_i), y_i) + \frac{\lambda}{2} \|f\|_{\mathcal{H}}^2 \\ &= \arg \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ln \left(1 + e^{-y_i f(\mathbf{x}_i)} \right) + \frac{\lambda}{2} \|f\|_{\mathcal{H}}^2\end{aligned}$$

- Can be interpreted as a regularized conditional maximum likelihood estimator
- No explicit solution, but smooth convex optimization problem that can be solved numerically

Solving KLR

- By the representer theorem, any solution of KLR can be expanded as

$$\hat{f}(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x})$$

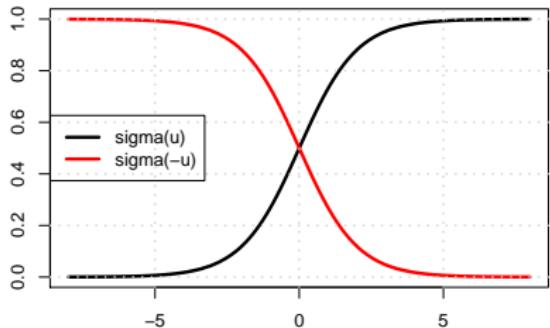
and as always we have:

$$\left(\hat{f}(\mathbf{x}_1), \dots, \hat{f}(\mathbf{x}_n) \right)^\top = \mathbf{K}\boldsymbol{\alpha} \quad \text{and} \quad \| \hat{f} \|^2_{\mathcal{H}} = \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}$$

- To find $\boldsymbol{\alpha}$ we therefore need to solve:

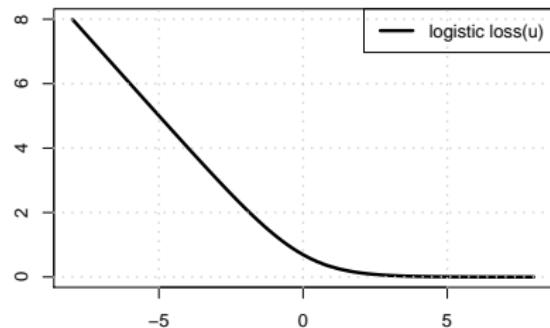
$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^n} \frac{1}{n} \sum_{i=1}^n \ln \left(1 + e^{-y_i [\mathbf{K}\boldsymbol{\alpha}]_i} \right) + \frac{\lambda}{2} \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}$$

Technical facts



Sigmoid:

- $\sigma(u) = \frac{1}{1+e^{-u}}$
- $\sigma(-u) = 1 - \sigma(u)$
- $\sigma'(u) = \sigma(u)\sigma(-u) \geq 0$



Logistic loss:

- $\ell_{logistic}(u) = \ln(1 + e^{-u})$
- $\ell'_{logistic}(u) = -\sigma(-u)$
- $\ell''_{logistic}(u) = \sigma(u)\sigma(-u) \geq 0$

Back to KLR

$$\min_{\alpha \in \mathbb{R}^n} J(\alpha) = \frac{1}{n} \sum_{i=1}^n \ell_{logistic}(y_i[\mathbf{K}\alpha]_i) + \frac{\lambda}{2} \alpha^\top \mathbf{K} \alpha$$

This is a smooth convex optimization problem, that can be solved by many numerical methods. Let us explicit one of them, **Newton's method**, which iteratively approximates J by a quadratic function and solves the quadratic problem.

The quadratic approximation near a point α_0 is the function:

$$J_q(\alpha) = J(\alpha_0) + (\alpha - \alpha_0)^\top \nabla J(\alpha_0) + \frac{1}{2} (\alpha - \alpha_0)^\top \nabla^2 J(\alpha_0) (\alpha - \alpha_0)$$

Let us compute the different terms...

Computing the quadratic approximation

$$\frac{\partial J}{\partial \alpha_j} = \frac{1}{n} \sum_{i=1}^n \underbrace{\ell'_{logistic}(y_i[\mathbf{K}\boldsymbol{\alpha}]_i)}_{P_i(\boldsymbol{\alpha})} y_i \mathbf{K}_{ij} + \lambda [\mathbf{K}\boldsymbol{\alpha}]_j$$

therefore

$$\nabla J(\boldsymbol{\alpha}) = \frac{1}{n} \mathbf{K} \mathbf{P}(\boldsymbol{\alpha}) \mathbf{y} + \lambda \mathbf{K} \boldsymbol{\alpha}$$

where $\mathbf{P}(\boldsymbol{\alpha}) = \text{diag}(P_1(\boldsymbol{\alpha}), \dots, P_n(\boldsymbol{\alpha}))$.

$$\frac{\partial^2 J}{\partial \alpha_j \partial \alpha_l} = \frac{1}{n} \sum_{i=1}^n \underbrace{\ell''_{logistic}(y_i[\mathbf{K}\boldsymbol{\alpha}]_i)}_{W_i(\boldsymbol{\alpha})} y_i \mathbf{K}_{ij} y_i \mathbf{K}_{il} + \lambda \mathbf{K}_{jl}$$

therefore

$$\nabla^2 J(\boldsymbol{\alpha}) = \frac{1}{n} \mathbf{K} \mathbf{W}(\boldsymbol{\alpha}) \mathbf{K} + \lambda \mathbf{K}$$

where $\mathbf{W}(\boldsymbol{\alpha}) = \text{diag}(W_1(\boldsymbol{\alpha}), \dots, W_n(\boldsymbol{\alpha}))$.

Computing the quadratic approximation

$$J_q(\alpha) = J(\alpha_0) + (\alpha - \alpha_0)^\top \nabla J(\alpha_0) + \frac{1}{2} (\alpha - \alpha_0)^\top \nabla^2 J(\alpha_0) (\alpha - \alpha_0)$$

Terms that depend on α , with $\mathbf{P} = \mathbf{P}(\alpha_0)$ and $\mathbf{W} = \mathbf{W}(\alpha_0)$:

- $\alpha^\top \nabla J(\alpha_0) = \frac{1}{n} \alpha^\top \mathbf{K} \mathbf{P} \mathbf{y} + \lambda \alpha^\top \mathbf{K} \alpha_0$
- $\frac{1}{2} \alpha^\top \nabla^2 J(\alpha_0) \alpha = \frac{1}{2n} \alpha^\top \mathbf{K} \mathbf{W} \mathbf{K} \alpha + \frac{\lambda}{2} \alpha^\top \mathbf{K} \alpha$
- $-\alpha^\top \nabla^2 J(\alpha_0) \alpha_0 = -\frac{1}{n} \alpha^\top \mathbf{K} \mathbf{W} \mathbf{K} \alpha_0 - \lambda \alpha^\top \mathbf{K} \alpha_0$

Putting it all together:

$$\begin{aligned} 2J_q(\alpha) &= -\frac{2}{n} \alpha^\top \mathbf{K} \mathbf{W} \underbrace{(\mathbf{K} \alpha_0 - \mathbf{W}^{-1} \mathbf{P} \mathbf{y})}_{:= \mathbf{z}} + \frac{1}{n} \alpha^\top \mathbf{K} \mathbf{W} \mathbf{K} \alpha + \lambda \alpha^\top \mathbf{K} \alpha + C \\ &= \frac{1}{n} (\mathbf{K} \alpha - \mathbf{z})^\top \mathbf{W} (\mathbf{K} \alpha - \mathbf{z}) + \lambda \alpha^\top \mathbf{K} \alpha + C \end{aligned}$$

This is a standard weighted kernel ridge regression (WKRR) problem!

Solving KLR by IRLS

In summary, one way to solve KLR is to iteratively solve a WKRR problem until convergence:

$$\alpha^{t+1} \leftarrow \text{solveWKRR}(\mathbf{K}, \mathbf{W}^t, \mathbf{z}^t)$$

where we update \mathbf{W}^t and \mathbf{z}^t from α^t as follows (for $i = 1, \dots, n$):

- $m_i \leftarrow [\mathbf{K}\alpha^t]_i$
- $P_i^t \leftarrow \ell'_{logistic}(y_i m_i) = -\sigma(-y_i m_i)$
- $W_i^t \leftarrow \ell''_{logistic}(y_i m_i) = \sigma(m_i)\sigma(-m_i)$
- $z_i^t \leftarrow m_i - P_i^t y_i / W_i^t = m_i + y_i / \sigma(-y_i m_i)$

This is the kernelized version of the famous *iteratively reweighted least-square* (IRLS) method to solve the standard linear logistic regression.

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
 - Kernel ridge regression
 - Kernel logistic regression
 - **Large-margin classifiers**
 - Interlude: convex optimization and duality
 - Support vector machines
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
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Loss functions for classifications

We already saw two loss functions for binary classification problems

- The 0/1 loss $\ell_{0/1}(f(\mathbf{x}), y) = \mathbf{1}(yf(\mathbf{x}) < 0)$
- The logistic loss $\ell_{logistic}(f(\mathbf{x}), y) = \ln(1 + e^{-yf(\mathbf{x})})$

In both cases, the loss is a function of the margin defined as follows

Definition

In binary classification ($\mathcal{Y} = \{-1, 1\}$), the **margin** of the function f for a pair (\mathbf{x}, y) is:

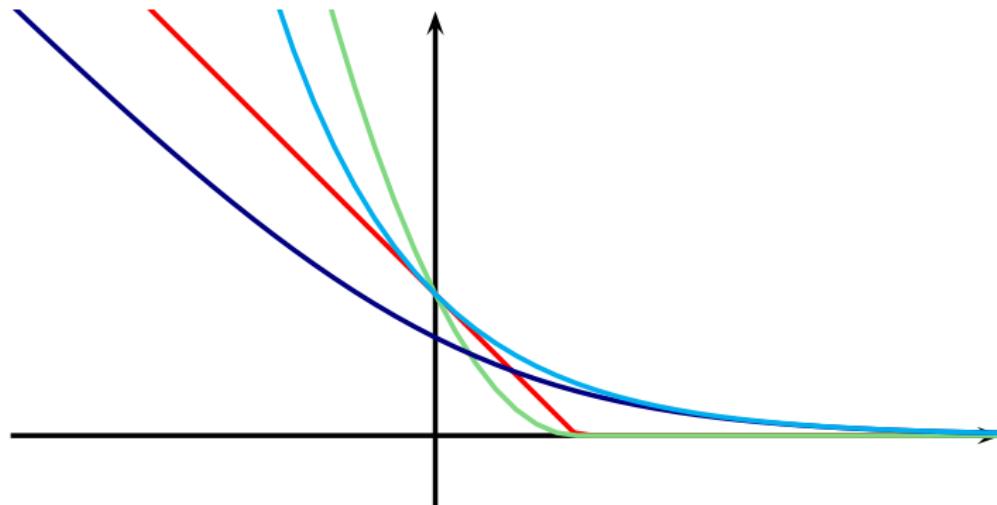
$$yf(\mathbf{x}).$$

In both cases the loss is a decreasing function of the margin, i.e.,

$$\ell(f(\mathbf{x}), y) = \varphi(yf(\mathbf{x})) , \quad \text{with } \varphi \text{ non-increasing}$$

What about other similar loss functions?

Loss function examples



Method	$\varphi(u)$
Kernel logistic regression	$\log(1 + e^{-u})$
Support vector machine (1-SVM)	$\max(1 - u, 0)$
Support vector machine (2-SVM)	$\max(1 - u, 0)^2$
Boosting	e^{-u}

Large-margin classifiers

Definition

Given a non-increasing function $\varphi : \mathbb{R} \rightarrow \mathbb{R}_+$, a (kernel) large-margin classifier is an algorithm that estimates a function $f : \mathcal{X} \rightarrow \mathbb{R}$ by solving

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \varphi(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2$$

Hence, KLR is a large-margin classifier, corresponding to $\varphi(u) = \ln(1 + e^{-u})$. Many more are possible.

Questions:

- ① Can we solve the optimization problem for other φ 's?
- ② Is it a good idea to optimize this objective function, if at the end of the day we are interested in the $\ell_{0/1}$ loss, i.e., learning models that make few errors?

Solving large-margin classifiers

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \varphi(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2$$

- By the representer theorem, the solution of the unconstrained problem can be expanded as:

$$f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}).$$

- Plugging into the original problem we obtain the following unconstrained and convex optimization problem in \mathbb{R}^n :

$$\min_{\alpha \in \mathbb{R}^n} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi(y_i [\mathbf{K}\alpha]_i) + \lambda \alpha^\top \mathbf{K} \alpha \right\}.$$

- When φ is convex, this can be solved using general tools for **convex optimization**, or specific algorithms (e.g., for SVM, see later).

A tiny bit of learning theory

Assumptions and notations

- Let \mathbb{P} be an (unknown) distribution on $\mathcal{X} \times \mathcal{Y}$, and $\eta(\mathbf{x}) = \mathbb{P}(Y = 1 | X = \mathbf{x})$ a measurable version of the conditional distribution of Y given X
- Assume the training set $\mathcal{S}_n = (X_i, Y_i)_{i=1,\dots,n}$ are i.i.d. random variables according to \mathbb{P} .
- The **risk** of a classifier $f : \mathcal{X} \rightarrow \mathbb{R}$ is $R(f) = \mathbb{P}(\text{sign}(f(X)) \neq Y)$
- The **Bayes risk** is

$$R^* = \inf_{f \text{ measurable}} R(f)$$

which is attained for $f^*(\mathbf{x}) = \eta(\mathbf{x}) - 1/2$

- The **empirical risk** of a classifier $f : \mathcal{X} \rightarrow \mathbb{R}$ is

$$R^n(f) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}(\text{sign}(f(X_i)) \neq Y_i)$$

φ -risk

- Let the **empirical φ -risk** be the empirical risk optimized by a large-margin classifier:

$$R_\varphi^n(f) = \frac{1}{n} \sum_{i=1}^n \varphi(Y_i f(X_i))$$

- It is the empirical version of the **φ -risk**

$$R_\varphi(f) = \mathbb{E}[\varphi(Y f(X))]$$

- Can we hope to have a small risk $R(f)$ if we focus instead on the φ -risk $R_\varphi(f)$?

A small φ -risk ensures a small 0/1 risk

Theorem (Bartlett et al., 2003)

Let $\varphi : \mathbb{R} \rightarrow \mathbb{R}_+$ be convex, non-increasing, differentiable at 0 with $\varphi'(0) < 0$. Let $f : \mathcal{X} \rightarrow \mathbb{R}$ measurable such that

$$R_\varphi(f) = \min_{g \text{ measurable}} R_\varphi(g) = R_\varphi^*.$$

Then

$$R(f) = \min_{g \text{ measurable}} R(g) = R^*.$$

Remarks:

- This tells us that, if we know \mathbb{P} , then minimizing the φ -risk is a good idea even if our focus is on the classification error.
- The assumptions on φ can be relaxed; it works for the broader class of *classification-calibrated* loss functions (Bartlett et al., 2003).
- More generally, we can show that if $R_\varphi(f) - R_\varphi^*$ is small, then $R(f) - R^*$ is small too (Bartlett et al., 2003).

A small φ -risk ensures a small 0/1 risk

Proof sketch: Show that $f(\mathbf{x})$ is necessarily consistent with $\eta(\mathbf{x}) = \mathbb{P}(Y = 1 | X = \mathbf{x})$, if f minimizes R_φ , and thus minimizes R .

Condition on $X = \mathbf{x}$:

$$R_\varphi(f | X = \mathbf{x}) = \mathbb{E}[\varphi(Yf(X)) | X = \mathbf{x}] = \eta(\mathbf{x})\varphi(f(\mathbf{x})) + (1 - \eta(\mathbf{x}))\varphi(-f(\mathbf{x}))$$

$$R_\varphi(-f | X = \mathbf{x}) = \mathbb{E}[\varphi(-Yf(X)) | X = \mathbf{x}] = \eta(\mathbf{x})\varphi(-f(\mathbf{x})) + (1 - \eta(\mathbf{x}))\varphi(f(\mathbf{x}))$$

Therefore:

$$R_\varphi(f | X = \mathbf{x}) - R_\varphi(-f | X = \mathbf{x}) = [2\eta(\mathbf{x}) - 1] \times [\varphi(f(\mathbf{x})) - \varphi(-f(\mathbf{x}))]$$

This must be a.s. ≤ 0 because $R_\varphi(f) \leq R_\varphi(-f)$, which implies:

- if $\eta(\mathbf{x}) > \frac{1}{2}$, $\varphi(f(\mathbf{x})) \leq \varphi(-f(\mathbf{x})) \implies f(\mathbf{x}) \geq 0$
- if $\eta(\mathbf{x}) < \frac{1}{2}$, $\varphi(f(\mathbf{x})) \geq \varphi(-f(\mathbf{x})) \implies f(\mathbf{x}) \leq 0$

These inequalities are in fact strict thanks to the assumptions we made on φ (*left as exercice*). □

Empirical risk minimization (ERM)

To find a function with a small φ -risk, the following is a good candidate:

Definition

The **ERM estimator** on a functional class \mathcal{F} is the solution (when it exists) of:

$$\hat{f}_n = \operatorname{argmin}_{f \in \mathcal{F}} R_\varphi^n(f).$$

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Questions

- Is $R_\varphi^n(f)$ a good estimate of the true risk $R_\varphi(f)$?
- Is $R_\varphi(\hat{f}_n)$ small?

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Questions

- Is $R_\varphi^n(f)$ a good estimate of the true risk $R_\varphi(f)$?
- Is $R_\varphi(\hat{f}_n)$ small?

$$R_\varphi(\hat{f}_n) - R_\varphi^* = \underbrace{R_\varphi(\hat{f}_n) - \inf_{f \in \mathcal{F}} R_\varphi(f)}_{\text{estimation error}} + \underbrace{\inf_{f \in \mathcal{F}} R_\varphi(f) - R_\varphi^*}_{\text{approximation error}}.$$

Class capacity

Motivations

- The ERM principle gives a good solution if $R_\varphi(\hat{f}_n)$ is similar to the minimum achievable risk $\inf_{f \in \mathcal{F}} R_\varphi(f)$.
- This can be ensured if \mathcal{F} is **not “too large”**.
- We need a measure of the “**capacity**” of \mathcal{F} .

Definition: Rademacher complexity

The **Rademacher complexity** of a class of functions \mathcal{F} is:

$$\text{Rad}_n(\mathcal{F}) = \mathbb{E}_{X,\sigma} \left[\sup_{f \in \mathcal{F}} \left| \frac{2}{n} \sum_{i=1}^n \sigma_i f(X_i) \right| \right],$$

where the expectation is over $(X_i)_{i=1,\dots,n}$ and the independent uniform $\{\pm 1\}$ -valued (Rademacher) random variables $(\sigma_i)_{i=1,\dots,n}$.

Basic learning bounds

Theorem

Suppose φ is Lipschitz with constant L_φ :

$$\forall u, u' \in \mathbb{R}, \quad |\varphi(u) - \varphi(u')| \leq L_\varphi |u - u'|.$$

Then the φ -risk of the ERM estimator satisfies (on average over the sampling of training set)

$$\underbrace{\mathbb{E}_{\mathcal{S}_n} R_\varphi(\hat{f}_n) - R_\varphi^*}_{\text{Excess } \varphi\text{-risk}} \leq \underbrace{4L_\varphi \text{Rad}_n(\mathcal{F})}_{\text{Estimation error}} + \underbrace{\inf_{f \in \mathcal{F}} R_\varphi(f) - R_\varphi^*}_{\text{Approximation error}}$$

This quantifies a trade-off between:

- \mathcal{F} "large" = overfitting (approximation error small, estimation error large)
- \mathcal{F} "small" = underfitting (estimation error small, approximation error large)

ERM in RKHS balls

Principle

- Assume \mathcal{X} is endowed with a p.d. kernel.
- We consider the ball of radius B in the RKHS as function class for the ERM:

$$\mathcal{F}_B = \{f \in \mathcal{H} : \|f\|_{\mathcal{H}} \leq B\} .$$

Theorem (capacity control of RKHS balls)

$$\text{Rad}_n(\mathcal{F}_B) \leq \frac{2B\sqrt{\mathbb{E}K(X, X)}}{\sqrt{n}} .$$

Proof (1/2)

$$\begin{aligned}
 \text{Rad}_n(\mathcal{F}_B) &= \mathbb{E}_{X,\sigma} \left[\sup_{f \in \mathcal{F}_B} \left| \frac{2}{n} \sum_{i=1}^n \sigma_i f(X_i) \right| \right] \\
 &= \mathbb{E}_{X,\sigma} \left[\sup_{f \in \mathcal{F}_B} \left| \left\langle f, \frac{2}{n} \sum_{i=1}^n \sigma_i K_{X_i} \right\rangle \right| \right] \quad (\text{RKHS}) \\
 &= \mathbb{E}_{X,\sigma} \left[B \left\| \frac{2}{n} \sum_{i=1}^n \sigma_i K_{X_i} \right\|_{\mathcal{H}} \right] \quad (\text{Cauchy-Schwarz}) \\
 &= \frac{2B}{n} \mathbb{E}_{X,\sigma} \left[\sqrt{\left\| \sum_{i=1}^n \sigma_i K_{X_i} \right\|_{\mathcal{H}}^2} \right] \\
 &\leq \frac{2B}{n} \sqrt{\mathbb{E}_{X,\sigma} \left[\sum_{i,j=1}^n \sigma_i \sigma_j K(X_i, X_j) \right]} \quad (\text{Jensen})
 \end{aligned}$$

Proof (2/2)

But $\mathbb{E}_\sigma [\sigma_i \sigma_j]$ is 1 if $i = j$, 0 otherwise. Therefore:

$$\begin{aligned}\text{Rad}_n(\mathcal{F}_B) &\leq \frac{2B}{n} \sqrt{\mathbb{E}_X \left[\sum_{i,j=1}^n \mathbb{E}_\sigma [\sigma_i \sigma_j] K(X_i, X_j) \right]} \\ &\leq \frac{2B}{n} \sqrt{\mathbb{E}_X \sum_{i=1}^n K(X_i, X_i)} \\ &= \frac{2B \sqrt{\mathbb{E}_X K(X, X)}}{\sqrt{n}}.\end{aligned}$$

□

Basic learning bounds in RKHS balls

Corollary

Suppose $K(X, X) \leq \kappa^2$ a.s. (e.g., Gaussian kernel and $\kappa = 1$). Then the ERM estimator in \mathcal{F}_B satisfies

$$\mathbb{E}R_\varphi(\hat{f}_n) - R_\varphi^* \leq \frac{8L_\varphi\kappa B}{\sqrt{n}} + \left[\inf_{f \in \mathcal{F}_B} R_\varphi(f) - R_\varphi^* \right].$$

Remarks

- B controls the trade-off between approximation and estimation error
- The bound on expression error is independent of \mathcal{P} and decreases with n
- The approximation error is harder to analyze in general
- In practice, B (or λ , next slide) is tuned by cross-validation

ERM as penalized risk minimization

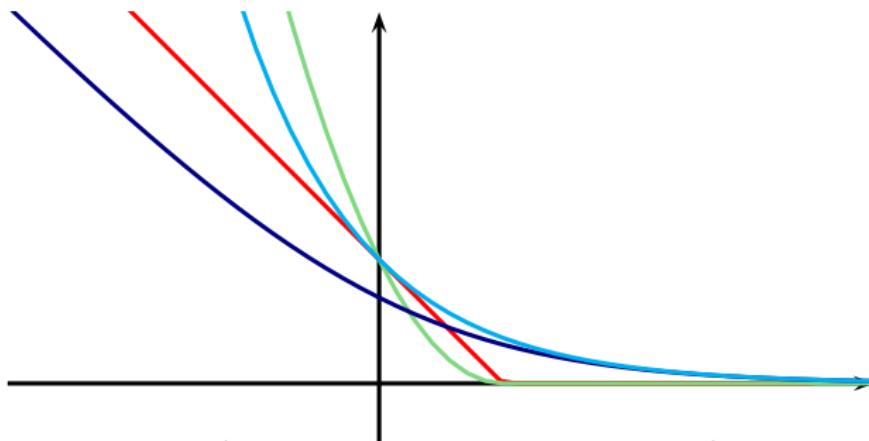
- ERM over \mathcal{F}_B solves the **constrained minimization problem**:

$$\begin{cases} \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \varphi(y_i f(\mathbf{x}_i)) \\ \text{subject to } \|f\|_{\mathcal{H}} \leq B. \end{cases}$$

- To make this practical we assume that φ is convex.
- The problem is then a **convex problem** in f for which **strong duality holds**. In particular f solves the problem if and only if it solves for some dual parameter λ the **unconstrained problem**:

$$\min_{f \in \mathcal{H}} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2 \right\}.$$

Summary: large margin classifiers



$$\min_{f \in \mathcal{H}} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2 \right\}$$

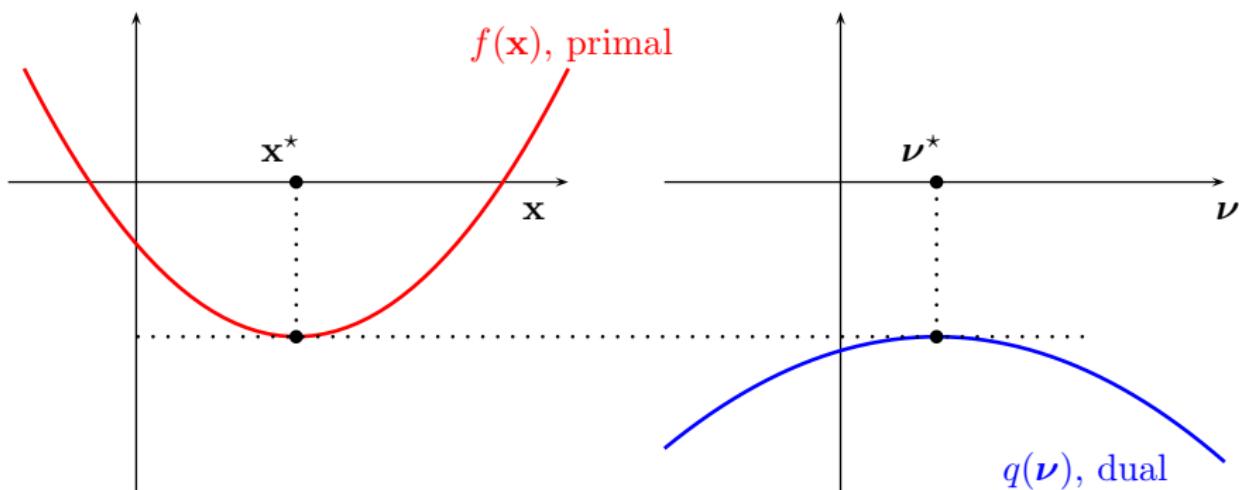
- φ calibrated (e.g., decreasing, $\varphi'(0) < 0$) \implies good proxy for classification error
- φ convex + representer theorem \implies efficient algorithms

Outline

- 1 Kernels and RKHS
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 - Kernel logistic regression
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A few slides on convex duality

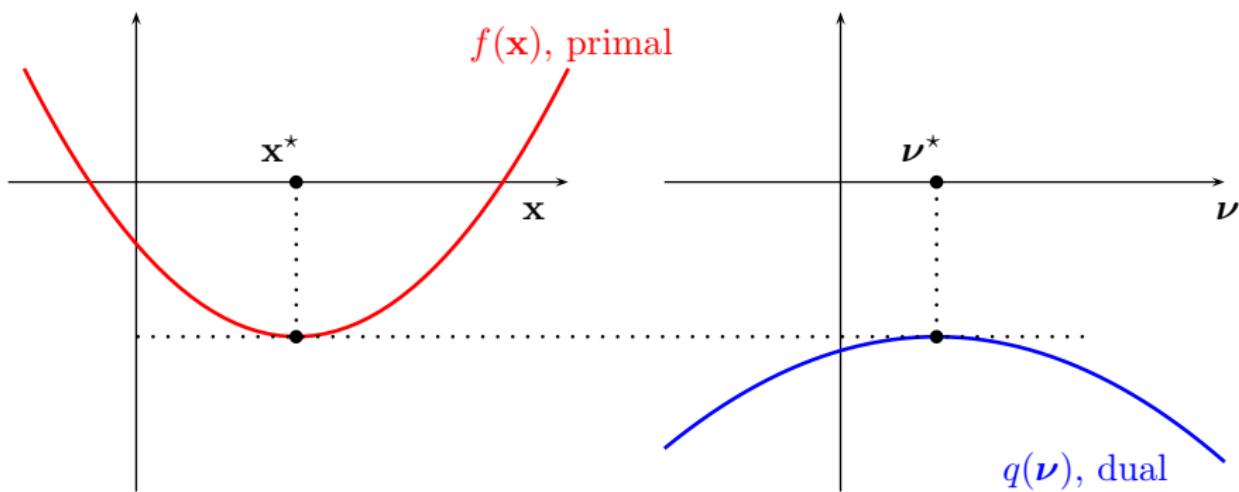
Strong Duality



- Strong duality means that $\max_{\nu} q(\nu) = \min_x f(x)$
- Strong duality holds in most “reasonable cases” for convex optimization (to be detailed soon).

A few slides on convex duality

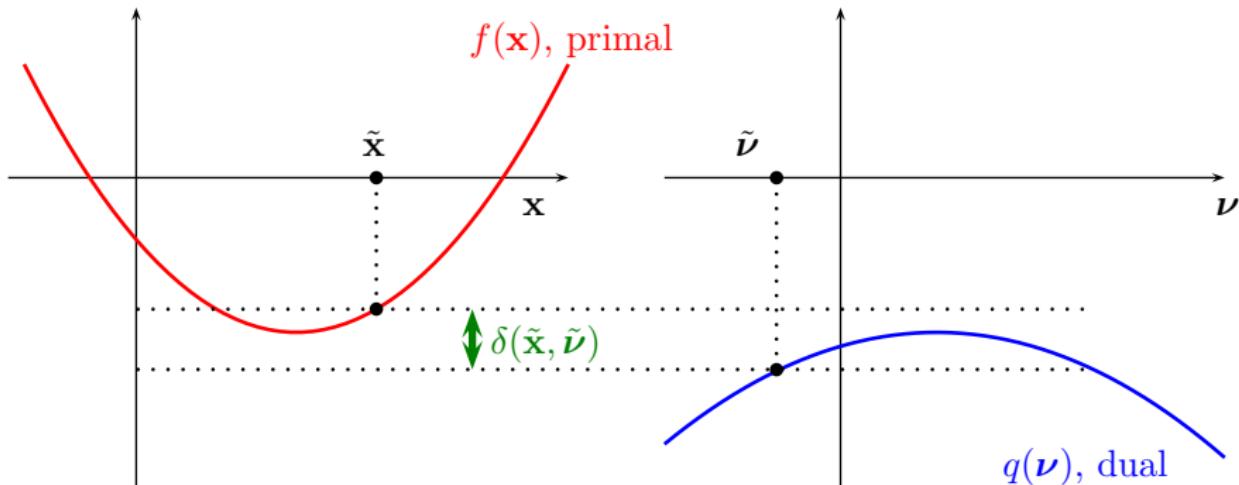
Strong Duality



- The relation between \mathbf{x}^* and ν^* is not always known a priori.

A few slides on convex duality

Parenthesis on duality gaps



- The duality gap guarantees us that $0 \leq f(\tilde{x}) - f(x^*) \leq \delta(\tilde{x}, \tilde{\nu})$.
- Dual problems are often obtained by Lagrangian or Fenchel duality.

A few slides on Lagrangian duality

Setting

- We consider an equality and inequality constrained optimization problem over a variable $\mathbf{x} \in \mathcal{X}$:

$$\begin{aligned} & \text{minimize} && f(\mathbf{x}) \\ & \text{subject to} && h_i(\mathbf{x}) = 0, \quad i = 1, \dots, m, \\ & && g_j(\mathbf{x}) \leq 0, \quad j = 1, \dots, r, \end{aligned}$$

making **no assumption** of f , g and h .

- Let us denote by f^* the optimal value of the decision function under the constraints, i.e., $f^* = f(\mathbf{x}^*)$ if the minimum is reached at a global minimum \mathbf{x}^* .

A few slides on Lagrangian duality

Lagrangian

The **Lagrangian** of this problem is the function $L : \mathcal{X} \times \mathbb{R}^m \times \mathbb{R}^r \rightarrow \mathbb{R}$ defined by:

$$L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) = f(\mathbf{x}) + \sum_{i=1}^m \lambda_i h_i(\mathbf{x}) + \sum_{j=1}^r \mu_j g_j(\mathbf{x}).$$

Lagrangian dual function

The **Lagrange dual function** $g : \mathbb{R}^m \times \mathbb{R}^r \rightarrow \mathbb{R}$ is:

$$\begin{aligned} q(\boldsymbol{\lambda}, \boldsymbol{\mu}) &= \inf_{\mathbf{x} \in \mathcal{X}} L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) \\ &= \inf_{\mathbf{x} \in \mathcal{X}} \left(f(\mathbf{x}) + \sum_{i=1}^m \lambda_i h_i(\mathbf{x}) + \sum_{j=1}^r \mu_j g_j(\mathbf{x}) \right). \end{aligned}$$

A few slides on convex Lagrangian duality

For the (primal) problem:

$$\begin{aligned} & \text{minimize} && f(\mathbf{x}) \\ & \text{subject to} && h(\mathbf{x}) = 0, \quad g(\mathbf{x}) \leq 0, \end{aligned}$$

the Lagrange dual problem is:

$$\begin{aligned} & \text{maximize} && q(\boldsymbol{\lambda}, \boldsymbol{\mu}) \\ & \text{subject to} && \boldsymbol{\mu} \geq 0, \end{aligned}$$

Proposition

- q is concave in $(\boldsymbol{\lambda}, \boldsymbol{\mu})$, even if the original problem is not convex.
- The dual function yields lower bounds on the optimal value f^* of the original problem when $\boldsymbol{\mu}$ is nonnegative:

$$q(\boldsymbol{\lambda}, \boldsymbol{\mu}) \leq f^*, \quad \forall \boldsymbol{\lambda} \in \mathbb{R}^m, \forall \boldsymbol{\mu} \in \mathbb{R}^r, \boldsymbol{\mu} \geq 0.$$

Proofs

- Remember that

$$L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) = f(\mathbf{x}) + \sum_{i=1}^m \lambda_i h_i(\mathbf{x}) + \sum_{j=1}^r \mu_j g_j(\mathbf{x}).$$

- For each \mathbf{x} , the function $(\boldsymbol{\lambda}, \boldsymbol{\mu}) \mapsto L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu})$ is linear, and therefore both convex and concave in $(\boldsymbol{\lambda}, \boldsymbol{\mu})$. The pointwise minimum of concave functions is concave, therefore q is concave.
- Let $\bar{\mathbf{x}}$ be any feasible point, i.e., $h(\bar{\mathbf{x}}) = 0$ and $g(\bar{\mathbf{x}}) \leq 0$. Then we have, for any $\boldsymbol{\lambda}$ and $\boldsymbol{\mu} \geq 0$:

$$\sum_{i=1}^m \lambda_i h_i(\bar{\mathbf{x}}) + \sum_{i=1}^r \mu_i g_i(\bar{\mathbf{x}}) \leq 0,$$

$$\implies L(\bar{\mathbf{x}}, \boldsymbol{\lambda}, \boldsymbol{\mu}) = f(\bar{\mathbf{x}}) + \sum_{i=1}^m \lambda_i h_i(\bar{\mathbf{x}}) + \sum_{i=1}^r \mu_i g_i(\bar{\mathbf{x}}) \leq f(\bar{\mathbf{x}}),$$

$$\implies q(\boldsymbol{\lambda}, \boldsymbol{\mu}) = \inf_{\mathbf{x}} L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) \leq L(\bar{\mathbf{x}}, \boldsymbol{\lambda}, \boldsymbol{\mu}) \leq f(\bar{\mathbf{x}}), \quad \forall \bar{\mathbf{x}}. \quad \square$$

Weak duality

- Let q^* the optimal value of the Lagrange dual problem. Each $q(\lambda, \mu)$ is a lower bound for f^* and by definition q^* is the best lower bound that is obtained. The following **weak duality inequality** therefore **always hold**:

$$q^* \leq f^*.$$

- This inequality holds when q^* or f^* are infinite. The difference $q^* - f^*$ is called the **optimal duality gap** of the original problem.

Strong duality

- We say that **strong duality** holds if the optimal duality gap is zero, i.e.:

$$q^* = f^*.$$

- If strong duality holds, then the best lower bound that can be obtained from the Lagrange dual function is **tight**
- Strong duality does **not hold** for general nonlinear problems.
- It usually holds for **convex problems**.
- Conditions that ensure strong duality for convex problems are called **constraint qualification**.
- In that case, we have for all feasible primal and dual points $\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}$,

$$q(\boldsymbol{\lambda}, \boldsymbol{\mu}) \leq q(\boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) = L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) = f(\mathbf{x}^*) \leq f(\mathbf{x}).$$

Slater's constraint qualification

Strong duality holds for a **convex** problem:

$$\begin{aligned} & \text{minimize} && f(\mathbf{x}) \\ & \text{subject to} && g_j(\mathbf{x}) \leq 0, \quad j = 1, \dots, r, \\ & && \mathbf{A}\mathbf{x} = \mathbf{b}, \end{aligned}$$

if it is **strictly feasible**, i.e., there exists at least one **feasible point** that satisfies:

$$g_j(\mathbf{x}) < 0, \quad j = 1, \dots, r, \quad \mathbf{A}\mathbf{x} = \mathbf{b}.$$

Remarks

- Slater's conditions also ensure that the maximum q^* (if $> -\infty$) is attained, i.e., there exists a point (λ^*, μ^*) with

$$q(\lambda^*, \mu^*) = q^* = f^*$$

- They can be sharpened. For example, strict feasibility is not required for affine constraints.
- There exist many other types of constraint qualifications

Dual optimal pairs

Suppose that strong duality holds, \mathbf{x}^* is primal optimal, $(\boldsymbol{\lambda}^*, \boldsymbol{\mu}^*)$ is dual optimal. Then we have:

$$f(\mathbf{x}^*) = q(\boldsymbol{\lambda}^*, \boldsymbol{\mu}^*)$$

$$= \inf_{\mathbf{x} \in \mathbb{R}^n} \left\{ f(\mathbf{x}) + \sum_{i=1}^m \lambda_i^* h_i(\mathbf{x}) + \sum_{j=1}^r \mu_j^* g_j(\mathbf{x}) \right\}$$

$$\leq f(\mathbf{x}^*) + \sum_{i=1}^m \lambda_i^* h_i(\mathbf{x}^*) + \sum_{j=1}^r \mu_j^* g_j(\mathbf{x}^*)$$

$$\leq f(\mathbf{x}^*)$$

Hence both inequalities are in fact **equalities**.

Complementary slackness

The first equality shows that:

$$L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) = \inf_{\mathbf{x} \in \mathbb{R}^n} L(\mathbf{x}, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) ,$$

showing that \mathbf{x}^* minimizes the Lagrangian at $(\boldsymbol{\lambda}^*, \boldsymbol{\mu}^*)$. The second equality shows the following important property:

Complementary slackness

Each optimal Lagrange multiplier is zero unless the corresponding constraint is active at the optimum:

$$\mu_j g_j(\mathbf{x}^*) = 0 , \quad j = 1, \dots, r .$$

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
 - Kernel ridge regression
 - Kernel logistic regression
 - Large-margin classifiers
 - Interlude: convex optimization and duality
 - Support vector machines
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics

Support vector machines (SVM)

- Historically the first “kernel method” for pattern recognition, still the **most popular**.
- Often **state-of-the-art** in performance.
- One particular choice of loss function (**hinge loss**).
- Leads to a **sparse solution**, i.e., not all points are involved in the decomposition (**compression**).
- Particular algorithm for fast optimization (**decomposition by chunking methods**).

Support vector machines (SVM)

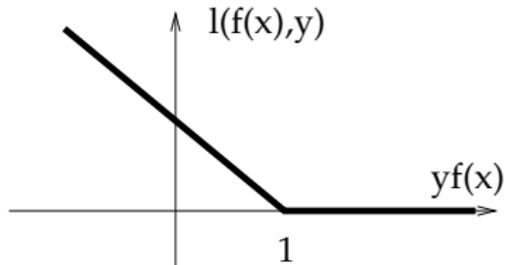
Definition

- The **hinge loss** is the function $\mathbb{R} \rightarrow \mathbb{R}_+$:

$$\varphi_{\text{hinge}}(u) = \max(1 - u, 0) = \begin{cases} 0 & \text{if } u \geq 1, \\ 1 - u & \text{otherwise.} \end{cases}$$

- SVM is the corresponding large-margin classifier, which solves:

$$\min_{f \in \mathcal{H}} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi_{\text{hinge}}(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2 \right\}.$$



Problem reformulation (1/3)

- By the representer theorem, the solution satisfies

$$\hat{f}(\mathbf{x}) = \sum_{i=1}^n \hat{\alpha}_i K(\mathbf{x}_i, \mathbf{x}),$$

where $\hat{\boldsymbol{\alpha}}$ solves

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^n} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi_{\text{hinge}}(y_i [\mathbf{K}\boldsymbol{\alpha}]_i) + \lambda \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha} \right\}$$

- This is a **convex** optimization problem
- But the objective function is not smooth (because of the hinge loss)

Problem reformulation (2/3)

- Let us introduce additional **slack variables** $\xi_1, \dots, \xi_n \in \mathbb{R}$. The problem is equivalent to:

$$\min_{\alpha \in \mathbb{R}^n, \xi \in \mathbb{R}^n} \left\{ \frac{1}{n} \sum_{i=1}^n \xi_i + \lambda \alpha^\top \mathbf{K} \alpha \right\},$$

subject to:

$$\xi_i \geq \varphi_{\text{hinge}}(y_i [\mathbf{K} \alpha]_i).$$

- The objective function is now smooth, but not the constraints
- However it is easy to replace the non-smooth constraint by a conjunction of two smooth constraints, because:

$$u \geq \varphi_{\text{hinge}}(v) \Leftrightarrow \begin{cases} u & \geq 1 - v \\ u & \geq 0 \end{cases}$$

Problem reformulation (3/3)

In summary, the SVM solution is

$$\hat{f}(\mathbf{x}) = \sum_{i=1}^n \hat{\alpha}_i K(\mathbf{x}_i, \mathbf{x}),$$

where $\hat{\boldsymbol{\alpha}}$ solves:

SVM (primal formulation)

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^n, \boldsymbol{\xi} \in \mathbb{R}^n} \frac{1}{n} \sum_{i=1}^n \xi_i + \lambda \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha},$$

subject to:

$$\begin{cases} y_i [\mathbf{K} \boldsymbol{\alpha}]_i + \xi_i - 1 \geq 0, & \text{for } i = 1, \dots, n, \\ \xi_i \geq 0, & \text{for } i = 1, \dots, n. \end{cases}$$

Solving the SVM problem

- This is a classical **quadratic program** (minimization of a convex quadratic function with linear constraints) for which any out-of-the-box optimization package can be used.
- The **dimension** of the problem and the **number of constraints**, however, are $2n$ where n is the number of points. General-purpose QP solvers will have difficulties when n exceeds a few thousands.
- Solving the **dual** of this problem (also a QP) will be more convenient and lead to faster algorithms (due to the sparsity of the final solution).

Lagrangian

- Let us introduce the **Lagrange multipliers** $\mu \in \mathbb{R}^n$ and $\nu \in \mathbb{R}^n$.
- The Lagrangian of the problem is:

$$\begin{aligned} L(\alpha, \xi, \mu, \nu) = & \frac{1}{n} \sum_{i=1}^n \xi_i + \lambda \alpha^\top \mathbf{K} \alpha \\ & - \sum_{i=1}^n \mu_i [y_i [\mathbf{K} \alpha]_i + \xi_i - 1] - \sum_{i=1}^n \nu_i \xi_i \end{aligned}$$

or, in matrix notations:

$$\begin{aligned} L(\alpha, \xi, \mu, \nu) = & \xi^\top \frac{\mathbf{1}}{n} + \lambda \alpha^\top \mathbf{K} \alpha \\ & - (\text{diag}(\mathbf{y})\mu)^\top \mathbf{K} \alpha - (\mu + \nu)^\top \xi + \mu^\top \mathbf{1} \end{aligned}$$

Minimizing $L(\alpha, \xi, \mu, \nu)$ w.r.t. α

- $L(\alpha, \xi, \mu, \nu)$ is a convex quadratic function in α . It is minimized whenever its gradient is null:

$$\nabla_{\alpha} L = 2\lambda \mathbf{K}\alpha - \mathbf{K} \operatorname{diag}(\mathbf{y})\mu = \mathbf{K} (2\lambda\alpha - \operatorname{diag}(\mathbf{y})\mu)$$

- The following solves $\nabla_{\alpha} L = 0$:

$$\alpha^* = \frac{\operatorname{diag}(\mathbf{y})\mu}{2\lambda}$$

Minimizing $L(\alpha, \xi, \mu, \nu)$ w.r.t. ξ

- $L(\alpha, \xi, \mu, \nu)$ is a linear function in ξ .
- Its minimum is $-\infty$ except when it is constant, i.e., when:

$$\nabla_{\xi} L = \frac{1}{n} - \mu - \nu = 0$$

or equivalently

$$\mu + \nu = \frac{1}{n}$$

Dual function

- We therefore obtain the **Lagrange dual function**:

$$\begin{aligned} q(\mu, \nu) &= \inf_{\alpha \in \mathbb{R}^n, \xi \in \mathbb{R}^n} L(\alpha, \xi, \mu, \nu) \\ &= \begin{cases} \mu^\top \mathbf{1} - \frac{1}{4\lambda} \mu^\top \text{diag}(\mathbf{y}) \mathbf{K} \text{diag}(\mathbf{y}) \mu & \text{if } \mu + \nu = \frac{1}{n}, \\ -\infty & \text{otherwise.} \end{cases} \end{aligned}$$

- The dual problem is:

$$\begin{aligned} &\text{maximize} && q(\mu, \nu) \\ &\text{subject to} && \mu \geq 0, \nu \geq 0. \end{aligned}$$

Dual problem

- If $\mu_i > 1/n$ for some i , then there is no $\nu_i \geq 0$ such that $\mu_i + \nu_i = 1/n$, hence $q(\boldsymbol{\mu}, \boldsymbol{\nu}) = -\infty$.
- If $0 \leq \mu_i \leq 1/n$ for all i , then the dual function takes finite values that depend only on $\boldsymbol{\mu}$ by taking $\nu_i = 1/n - \mu_i$.
- The dual problem is therefore equivalent to:

$$\max_{0 \leq \boldsymbol{\mu} \leq \mathbf{1}/n} \quad \boldsymbol{\mu}^\top \mathbf{1} - \frac{1}{4\lambda} \boldsymbol{\mu}^\top \text{diag}(\mathbf{y}) \mathbf{K} \text{diag}(\mathbf{y}) \boldsymbol{\mu}$$

or with indices:

$$\max_{0 \leq \boldsymbol{\mu} \leq \mathbf{1}/n} \quad \sum_{i=1}^n \mu_i - \frac{1}{4\lambda} \sum_{i,j=1}^n y_i y_j \mu_i \mu_j K(\mathbf{x}_i, \mathbf{x}_j).$$

Back to the primal

- Once the dual problem is solved in μ we get a solution of the primal problem by $\alpha = \text{diag}(\mathbf{y})\mu/2\lambda$.
- Because the link is so simple, we can therefore directly plug this into the dual problem to obtain the QP that α must solve:

SVM (dual formulation)

$$\max_{\alpha \in \mathbb{R}^n} 2 \sum_{i=1}^n \alpha_i y_i - \sum_{i,j=1}^n \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j) = 2\boldsymbol{\alpha}^\top \mathbf{y} - \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha},$$

subject to:

$$0 \leq y_i \alpha_i \leq \frac{1}{2\lambda n}, \quad \text{for } i = 1, \dots, n.$$

Complementary slackness conditions

- The complementary slackness conditions are, for $i = 1, \dots, n$:

$$\begin{cases} \mu_i [y_i f(\mathbf{x}_i) + \xi_i - 1] = 0, \\ \nu_i \xi_i = 0, \end{cases}$$

- In terms of α this can be rewritten as:

$$\begin{cases} \alpha_i [y_i f(\mathbf{x}_i) + \xi_i - 1] = 0, \\ (\alpha_i - \frac{y_i}{2\lambda n}) \xi_i = 0. \end{cases}$$

Analysis of KKT conditions

$$\begin{cases} \alpha_i [y_i f(\mathbf{x}_i) + \xi_i - 1] = 0, \\ (\alpha_i - \frac{y_i}{2\lambda n}) \xi_i = 0. \end{cases}$$

- If $\alpha_i = 0$, then the second constraint is active: $\xi_i = 0$. This implies $y_i f(\mathbf{x}_i) \geq 1$.
- If $0 < y_i \alpha_i < \frac{1}{2\lambda n}$, then both constraints are active: $\xi_i = 0$ et $y_i f(\mathbf{x}_i) + \xi_i - 1 = 0$. This implies $y_i f(\mathbf{x}_i) = 1$.
- If $\alpha_i = \frac{y_i}{2\lambda n}$, then the second constraint is not active ($\xi_i \geq 0$) while the first one is active: $y_i f(\mathbf{x}_i) + \xi_i = 1$. This implies $y_i f(\mathbf{x}_i) \leq 1$

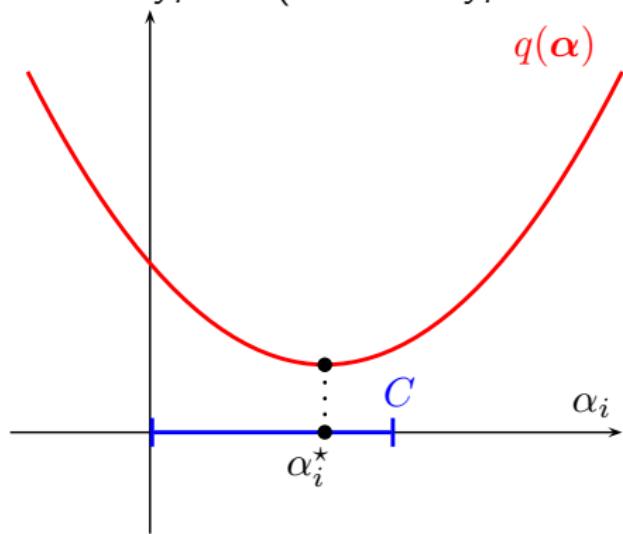
Another point of view without KKT

The dual can be rewritten as the minimization of **a quadratic function under box constraints**

$$\min_{\alpha \in \mathbb{R}^n} \left\{ q(\alpha) = \frac{1}{2} \alpha^\top \mathbf{K} \alpha - \alpha^\top \mathbf{y} \right\} \quad \text{s.t.} \quad \forall i, \quad 0 \leq y_i \alpha_i \leq C,$$

The gradient is $\nabla q(\alpha) = \mathbf{K}\alpha - \mathbf{y} = [f(\mathbf{x}_i) - y_i]_{i=1,\dots,n}$.

Assume $y_i = 1$ (case with $y_i = -1$ is similar) and consider three cases:



- Case 1: $0 < y_i \alpha_i^* < C$;
- $[\nabla q(\alpha^*)]_i = 0$;
- $\Rightarrow y_i f(\mathbf{x}_i) = 1$.

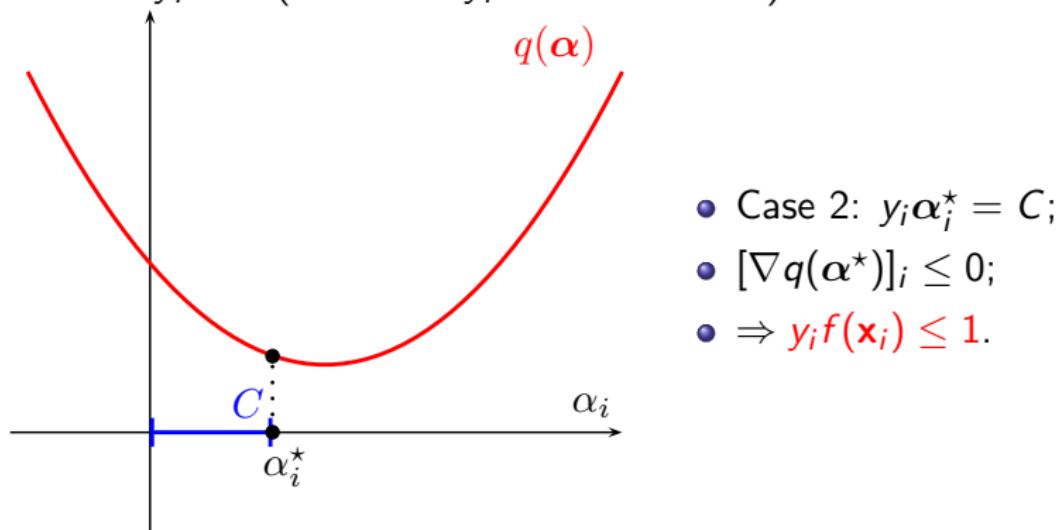
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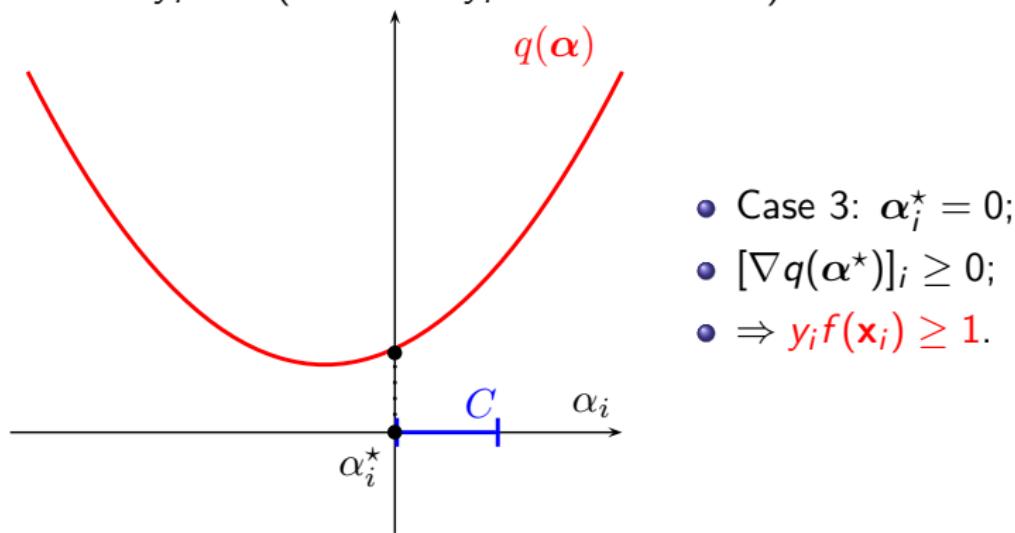
Another point of view without KKT

The dual can be rewritten as the minimization of **a quadratic function under box constraints**

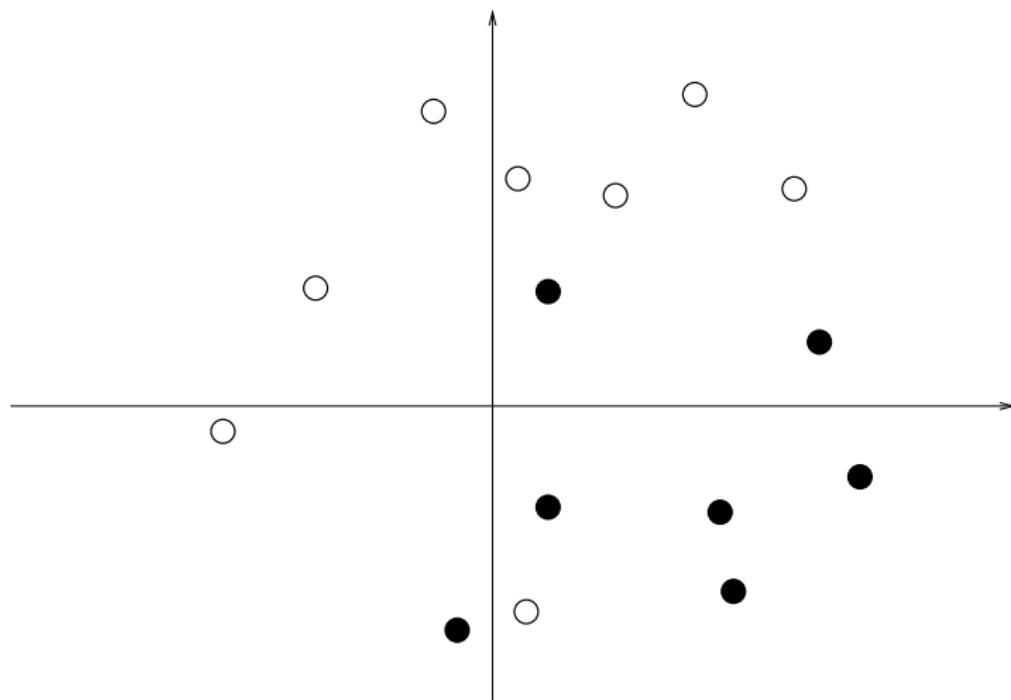
$$\min_{\alpha \in \mathbb{R}^n} \left\{ q(\alpha) = \frac{1}{2} \alpha^\top \mathbf{K} \alpha - \alpha^\top \mathbf{y} \right\} \quad \text{s.t.} \quad \forall i, \quad 0 \leq y_i \alpha_i \leq C,$$

The gradient is $\nabla q(\alpha) = \mathbf{K}\alpha - \mathbf{y} = [f(\mathbf{x}_i) - y_i]_{i=1,\dots,n}$.

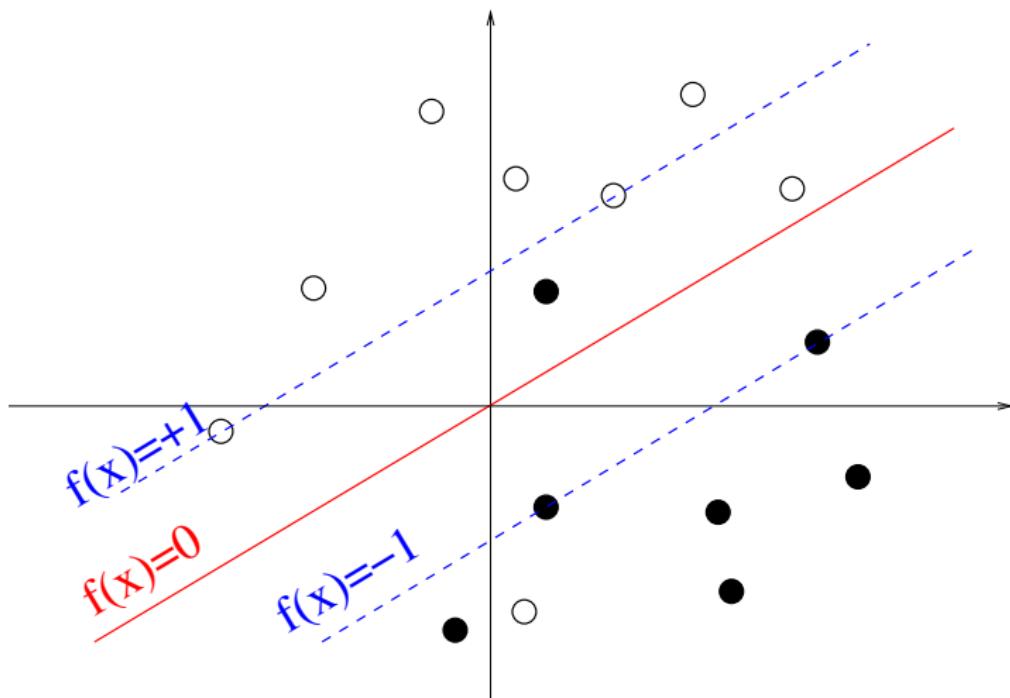
Assume $y_i = 1$ (case with $y_i = -1$ is similar) and consider three cases:



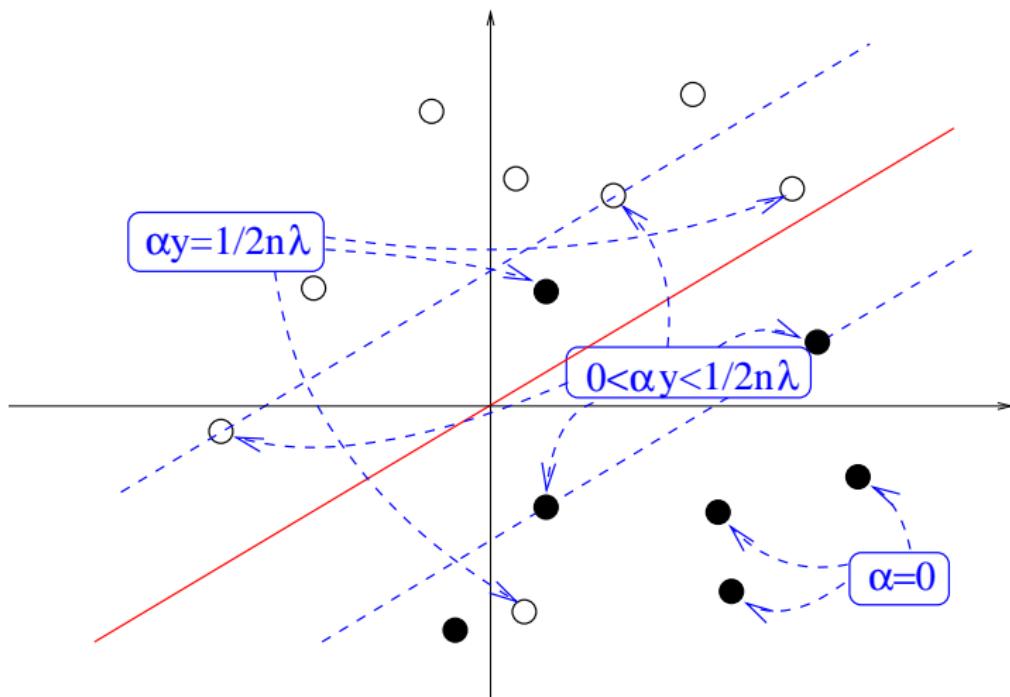
Geometric interpretation



Geometric interpretation



Geometric interpretation



Support vectors

Consequence of KKT conditions

- The training points with $\alpha_i \neq 0$ are called **support vectors**.
- Only support vectors are important for the classification of new points:

$$\forall \mathbf{x} \in \mathcal{X}, \quad f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}) = \sum_{i \in SV} \alpha_i K(\mathbf{x}_i, \mathbf{x}),$$

where SV is the set of support vectors.

Consequences

- The solution is **sparse** in α , leading to **fast algorithms** for training (use of decomposition methods).
- The **classification** of a new point only involves kernel evaluations with support vectors (fast).

Remark: C-SVM

- Often the SVM optimization problem is written in terms of a regularization parameter C instead of λ as follows:

$$\arg \min_{f \in \mathcal{H}} \frac{1}{2} \|f\|_{\mathcal{H}}^2 + C \sum_{i=1}^n L_{\text{hinge}}(f(\mathbf{x}_i), y_i).$$

- This is equivalent to our formulation with $C = \frac{1}{2n\lambda}$.
- The SVM optimization problem is then:

$$\max_{\alpha \in \mathbb{R}^d} 2 \sum_{i=1}^n \alpha_i y_i - \sum_{i,j=1}^n \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j),$$

subject to:

$$0 \leq y_i \alpha_i \leq C, \quad \text{for } i = 1, \dots, n.$$

- This formulation is often called **C-SVM**.

Remark: 2-SVM

- A variant of the SVM, sometimes called 2-SVM, is obtained by replacing the hinge loss by the square hinge loss:

$$\min_{f \in \mathcal{H}} \left\{ \frac{1}{n} \sum_{i=1}^n \varphi_{\text{hinge}}(y_i f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}}^2 \right\}.$$

- After some computation (left as exercice) we find that the dual problem of the 2-SVM is:

$$\max_{\alpha \in \mathbb{R}^d} 2\alpha^\top \mathbf{y} - \alpha^\top (\mathbf{K} + n\lambda I) \alpha,$$

subject to:

$$0 \leq y_i \alpha_i, \quad \text{for } i = 1, \dots, n.$$

- This is therefore **equivalent** to the previous SVM with the kernel $\mathbf{K} + n\lambda I$ and $C = +\infty$

Kernel Methods

Unsupervised Learning

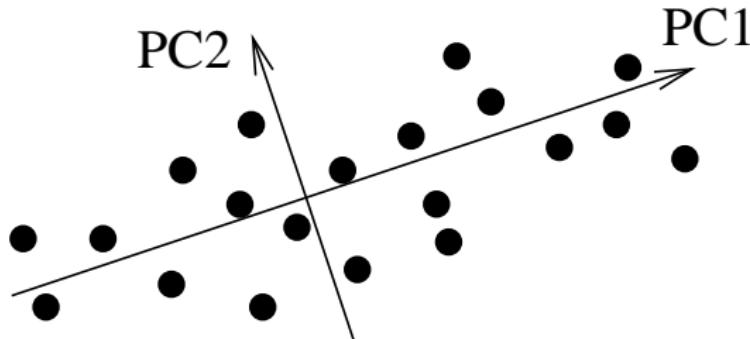
Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
 - Kernel PCA
 - Kernel K-means and spectral clustering
 - A quick note on kernel CCA
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics

Principal Component Analysis (PCA)

Classical setting

- Let $\mathcal{S} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$ be a set of vectors ($\mathbf{x}_i \in \mathbb{R}^d$)
- PCA is a classical algorithm in multivariate statistics to define a set of orthogonal directions that capture the maximum variance
- Applications: low-dimensional representation of high-dimensional points, visualization



Principal Component Analysis (PCA)

Formalization

- Assume that the data are **centered** (otherwise center them as preprocessing), i.e.:

$$\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i = 0.$$

- The **orthogonal projection** onto a direction $\mathbf{w} \in \mathbb{R}^d$ is the function $h_{\mathbf{w}} : \mathbb{R}^d \rightarrow \mathbb{R}$ defined by:

$$h_{\mathbf{w}}(\mathbf{x}) = \mathbf{x}^\top \frac{\mathbf{w}}{\|\mathbf{w}\|}.$$

Principal Component Analysis (PCA)

Formalization

- The empirical variance captured by $h_{\mathbf{w}}$ is:

$$\hat{\text{var}}(h_{\mathbf{w}}) := \frac{1}{n} \sum_{i=1}^n h_{\mathbf{w}}(\mathbf{x}_i)^2 = \frac{1}{n} \sum_{i=1}^n \frac{(\mathbf{x}_i^\top \mathbf{w})^2}{\|\mathbf{w}\|^2}.$$

- The i -th principal direction \mathbf{w}_i ($i = 1, \dots, d$) is defined by:

$$\mathbf{w}_i = \underset{\mathbf{w} \perp \{\mathbf{w}_1, \dots, \mathbf{w}_{i-1}\}}{\arg \max} \hat{\text{var}}(h_{\mathbf{w}}) \text{ s.t. } \|\mathbf{w}\| = 1.$$

Principal Component Analysis (PCA)

Solution

- Let \mathbf{X} be the $n \times d$ data matrix whose rows are the vectors $\mathbf{x}_1, \dots, \mathbf{x}_n$. We can then write:

$$\hat{\text{var}}(h_{\mathbf{w}}) = \frac{1}{n} \sum_{i=1}^n \frac{(\mathbf{x}_i^\top \mathbf{w})^2}{\|\mathbf{w}\|^2} = \frac{1}{n} \frac{\mathbf{w}^\top \mathbf{X}^\top \mathbf{X} \mathbf{w}}{\mathbf{w}^\top \mathbf{w}}.$$

- The solutions of:

$$\mathbf{w}_i = \underset{\mathbf{w} \perp \{\mathbf{w}_1, \dots, \mathbf{w}_{i-1}\}}{\arg \max} \mathbf{w}^\top \mathbf{X}^\top \mathbf{X} \mathbf{w} \text{ s.t. } \|\mathbf{w}\| = 1$$

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- The solutions of:

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are the **successive eigenvectors of $\mathbf{X}^\top \mathbf{X}$** , ranked by decreasing eigenvalues.

Kernel Principal Component Analysis (PCA)

Let $\mathbf{x}_1, \dots, \mathbf{x}_n$ be a set of data points in \mathcal{X} ; let $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a positive definite kernel and \mathcal{H} be its RKHS.

Formalization

- Assume that the data are **centered** (otherwise center by manipulating the kernel matrix), i.e.:

$$\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \implies \frac{1}{n} \sum_{i=1}^n \varphi(\mathbf{x}_i) = 0.$$

- The **orthogonal projection** onto a direction $f \in \mathcal{H}$ is the function $h_f : \mathcal{X} \rightarrow \mathbb{R}$ defined by:

$$h_w(\mathbf{x}) = \mathbf{x}^\top \frac{\mathbf{w}}{\|\mathbf{w}\|} \implies h_f(\mathbf{x}) = \left\langle \varphi(\mathbf{x}), \frac{f}{\|f\|_{\mathcal{H}}} \right\rangle_{\mathcal{H}}.$$

Kernel Principal Component Analysis (PCA)

Let $\mathbf{x}_1, \dots, \mathbf{x}_n$ be a set of data points in \mathcal{X} ; let $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a positive definite kernel and \mathcal{H} be its RKHS.

Formalization

- The empirical variance captured by h_f is:

$$\hat{\text{var}}(h_w) = \frac{1}{n} \sum_{i=1}^n \frac{(\mathbf{x}_i^\top \mathbf{w})^2}{\|\mathbf{w}\|^2} \implies \hat{\text{var}}(h_f) := \frac{1}{n} \sum_{i=1}^n \frac{\langle \varphi(\mathbf{x}_i), f \rangle_{\mathcal{H}}^2}{\|f\|_{\mathcal{H}}^2}.$$

- The i -th principal direction f_i ($i = 1, \dots, d$) is defined by:

$$f_i = \underset{f \perp \{f_1, \dots, f_{i-1}\}}{\arg \max} \hat{\text{var}}(h_f) \text{ s.t. } \|f\|_{\mathcal{H}} = 1.$$

Kernel Principal Component Analysis (PCA)

Let $\mathbf{x}_1, \dots, \mathbf{x}_n$ be a set of data points in \mathcal{X} ; let $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a positive definite kernel and \mathcal{H} be its RKHS.

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$$\hat{\text{var}}(h_w) = \frac{1}{n} \sum_{i=1}^n \frac{(\mathbf{x}_i^\top \mathbf{w})^2}{\|\mathbf{w}\|^2} \implies \hat{\text{var}}(h_f) := \frac{1}{n} \sum_{i=1}^n \frac{f(\mathbf{x}_i)^2}{\|f\|_{\mathcal{H}}^2}.$$

- The i -th principal direction f_i ($i = 1, \dots, d$) is defined by:

$$f_i = \underset{f \perp \{f_1, \dots, f_{i-1}\}}{\arg \max} \sum_{i=1}^n f(\mathbf{x}_i)^2 \text{ s.t. } \|f\|_{\mathcal{H}} = 1.$$

Sanity check: kernel PCA with linear kernel = PCA

- Let $K(\mathbf{x}, \mathbf{y}) = \mathbf{x}^\top \mathbf{y}$ be the linear kernel.
- The associated RKHS \mathcal{H} is the set of linear functions:

$$f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^\top \mathbf{x},$$

endowed with the norm $\| f_{\mathbf{w}} \|_{\mathcal{H}} = \| \mathbf{w} \|_{\mathbb{R}^d}$.

- Therefore we can write:

$$\hat{\text{var}}(h_{\mathbf{w}}) = \frac{1}{n} \sum_{i=1}^n \frac{(\mathbf{x}_i^\top \mathbf{w})^2}{\| \mathbf{w} \|^2} = \frac{1}{n \| f_{\mathbf{w}} \|^2} \sum_{i=1}^n f_{\mathbf{w}}(\mathbf{x}_i)^2.$$

- Moreover, $\mathbf{w} \perp \mathbf{w}' \Leftrightarrow f_{\mathbf{w}} \perp f_{\mathbf{w}'}$.

Kernel Principal Component Analysis (PCA)

Solution

- Kernel PCA solves, for $i = 1, \dots, d$:

$$f_i = \underset{f \perp \{f_1, \dots, f_{i-1}\}}{\arg \max} \sum_{i=1}^n f(\mathbf{x}_i)^2 \text{ s.t. } \|f\|_{\mathcal{H}} = 1.$$

- We can apply the representer theorem (*exercise: check that is is also valid in this case*): for $i = 1, \dots, d$, we have:

$$\forall \mathbf{x} \in \mathcal{X}, \quad f_i(\mathbf{x}) = \sum_{j=1}^n \alpha_{i,j} K(\mathbf{x}_j, \mathbf{x}),$$

with $\boldsymbol{\alpha}_i = (\alpha_{i,1}, \dots, \alpha_{i,n})^\top \in \mathbb{R}^n$.

Kernel Principal Component Analysis (PCA)

- Therefore we have:

$$\|f_i\|_{\mathcal{H}}^2 = \sum_{k,l=1}^n \alpha_{i,k} \alpha_{i,l} K(\mathbf{x}_k, \mathbf{x}_l) = \boldsymbol{\alpha}_i^\top \mathbf{K} \boldsymbol{\alpha}_i,$$

- Similarly:

$$\sum_{k=1}^n f_i(\mathbf{x}_k)^2 = \boldsymbol{\alpha}_i^\top \mathbf{K}^2 \boldsymbol{\alpha}_i.$$

- and

$$\langle f_i, f_j \rangle_{\mathcal{H}} = \boldsymbol{\alpha}_i^\top \mathbf{K} \boldsymbol{\alpha}_j.$$

Kernel Principal Component Analysis (PCA)

Solution

Kernel PCA maximizes in α the function:

$$\alpha_i = \arg \max_{\alpha \in \mathbb{R}^n} \alpha^\top \mathbf{K}^2 \alpha,$$

under the constraints:

$$\begin{cases} \alpha_i^\top \mathbf{K} \alpha_j &= 0 \quad \text{for } j = 1, \dots, i-1. \\ \alpha_i^\top \mathbf{K} \alpha_i &= 1 \end{cases}$$

Kernel Principal Component Analysis (PCA)

Solution

- Compute the eigenvalue decomposition of the kernel matrix $\mathbf{K} = \mathbf{U}\Delta\mathbf{U}^\top$, with eigenvalues $\Delta_1 \geq \dots \geq \Delta_n \geq 0$.
- After a change of variable $\beta = \mathbf{K}^{1/2}\alpha$ (with $\mathbf{K}^{1/2} = \mathbf{U}\Delta^{1/2}\mathbf{U}^\top$),

$$\beta_i = \arg \max_{\beta \in \mathbb{R}^n} \beta^\top \mathbf{K} \beta,$$

under the constraints:

$$\begin{cases} \beta_i^\top \beta_j = 0 & \text{for } j = 1, \dots, i-1. \\ \beta_i^\top \beta_i = 1 \end{cases}$$

- Thus, $\beta_i = \mathbf{u}_i$ (i -th eigenvector) is a solution!
- Finally, $\alpha_i = \frac{1}{\sqrt{\Delta_i}} \mathbf{u}_i$.

Kernel Principal Component Analysis (PCA)

Summary

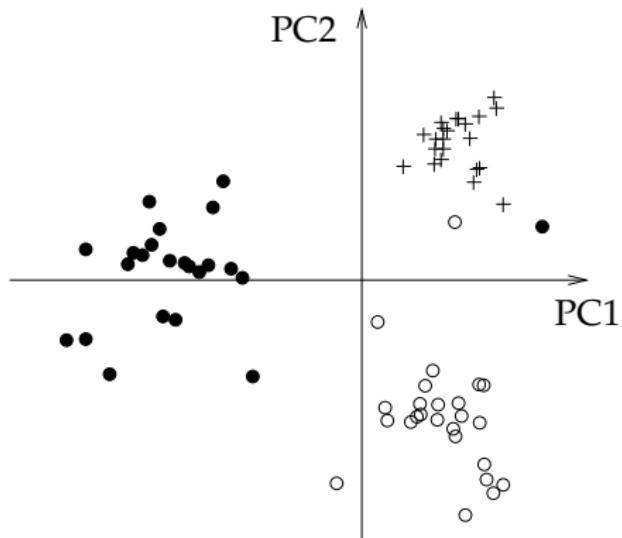
- ① Center the Gram matrix
- ② Compute the first eigenvectors (\mathbf{u}_i, Δ_i)
- ③ Normalize the eigenvectors $\alpha_i = \mathbf{u}_i / \sqrt{\Delta_i}$
- ④ The projections of the points onto the i -th eigenvector is given by $\mathbf{K}\alpha_i$

Kernel Principal Component Analysis (PCA)

Remarks

- In this formulation, we must **diagonalize the centered kernel Gram matrix**, instead of the covariance matrix in the classical setting
- *Exercise: check that $\mathbf{X}^\top \mathbf{X}$ and $\mathbf{X}\mathbf{X}^\top$ have the same spectrum (up to 0 eigenvalues) and that the eigenvectors are related by a simple relationship.*
- This formulation remains valid for any p.d. kernel: this is **kernel PCA**
- **Applications:** nonlinear PCA with nonlinear kernels for vectors, PCA of non-vector objects (strings, graphs..) with specific kernels...

Example



A set of 74 human tRNA sequences is analyzed using a kernel for sequences (the second-order marginalized kernel based on SCFG). This set of tRNAs contains three classes, called Ala-AGC (*white circles*), Asn-GTT (*black circles*) and Cys-GCA (*plus symbols*) (from Tsuda et al., 2003).

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
 - Kernel PCA
 - **Kernel K-means and spectral clustering**
 - A quick note on kernel CCA
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics

The K-means algorithm

K-means is probably the most popular algorithm for **clustering**.

Optimization point of view

Given data points $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathbb{R}^p , it consists of performing alternate minimization steps for optimizing the following cost function

$$\min_{\substack{\mu_j \in \mathbb{R}^p \text{ for } j=1, \dots, k \\ s_i \in \{1, \dots, k\}, \text{ for } i=1, \dots, n}} \sum_{i=1}^n \|\mathbf{x}_i - \mu_{s_i}\|_2^2.$$

K-means alternates between two steps:

1 cluster assignment:

Given fixed μ_1, \dots, μ_k , assign each \mathbf{x}_i to its closest centroid

$$\forall i, \quad s_i \in \operatorname{argmin}_{s \in \{1, \dots, k\}} \|\mathbf{x}_i - \mu_s\|_2^2.$$

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K-means alternates between two steps:

2 centroids update:

Given the previous assignments s_1, \dots, s_n , update the centroids

$$\forall j, \quad \boldsymbol{\mu}_j = \operatorname{argmin}_{\boldsymbol{\mu} \in \mathbb{R}^p} \sum_{i:s_i=j} \|\mathbf{x}_i - \boldsymbol{\mu}\|_2^2.$$

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K-means alternates between two steps:

2 centroids update:

Given the previous assignments s_1, \dots, s_n , update the centroids

$$\Leftrightarrow \forall j, \quad \boldsymbol{\mu}_j = \frac{1}{|C_j|} \sum_{i \in C_j} \mathbf{x}_i \quad \text{with} \quad C_j = \{i : s_i = j\}.$$

The kernel K-means algorithm

We may now modify the objective to operate in a RKHS. Given data points $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X} and a p.d. kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ with \mathcal{H} its RKHS, the new objective becomes

The kernel K-means algorithm

We may now modify the objective to **operate in a RKHS**. Given data points $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X} and a p.d. kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ with \mathcal{H} its RKHS, the new objective becomes

$$\min_{\substack{\mu_j \in \mathcal{H} \\ s_i \in \{1, \dots, k\}}} \sum_{j=1, \dots, k} \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu_{s_i}\|_{\mathcal{H}}^2.$$

To optimize the cost function, we will first use the following Proposition

Proposition

The center of mass $\varphi_n = \frac{1}{n} \sum_{i=1}^n \varphi(\mathbf{x}_i)$ solves the following optimization problem

$$\min_{\mu \in \mathcal{H}} \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu\|_{\mathcal{H}}^2.$$

The kernel K-means algorithm

Proof

$$\begin{aligned}\frac{1}{n} \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \boldsymbol{\mu}\|_{\mathcal{H}}^2 &= \frac{1}{n} \sum_{i=1}^n \|\varphi(\mathbf{x}_i)\|_{\mathcal{H}}^2 - \left\langle \frac{2}{n} \sum_{i=1}^n \varphi(\mathbf{x}_i), \boldsymbol{\mu} \right\rangle_{\mathcal{H}} + \|\boldsymbol{\mu}\|_{\mathcal{H}}^2 \\ &= \frac{1}{n} \sum_{i=1}^n \|\varphi(\mathbf{x}_i)\|_{\mathcal{H}}^2 - 2 \langle \varphi_n, \boldsymbol{\mu} \rangle_{\mathcal{H}} + \|\boldsymbol{\mu}\|_{\mathcal{H}}^2 \\ &= \frac{1}{n} \sum_{i=1}^n \|\varphi(\mathbf{x}_i)\|_{\mathcal{H}}^2 - \|\varphi_n\|_{\mathcal{H}}^2 + \|\varphi_n - \boldsymbol{\mu}\|_{\mathcal{H}}^2,\end{aligned}$$

which is minimum for $\boldsymbol{\mu} = \varphi_n$.

The kernel K-means algorithm

Given now the objective,

$$\min_{\substack{\mu_j \in \mathcal{H} \\ s_i \in \{1, \dots, k\}}} \sum_{j=1, \dots, k}^n \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu_{s_i}\|_{\mathcal{H}}^2,$$

we know that given assignments s_i , the optimal μ_j are the centers of mass of the respective clusters and we obtain

Greedy approach: kernel K-means

We alternate between two steps:

1 centroids update:

Given the previous assignments s_1, \dots, s_n , update the centroids

$$\forall j, \quad \mu_j = \operatorname{argmin}_{\mu \in \mathcal{H}} \sum_{i: s_i=j} \|\varphi(\mathbf{x}_i) - \mu\|_{\mathcal{H}}^2.$$

The kernel K-means algorithm

Given now the objective,

$$\min_{\substack{\mu_j \in \mathcal{H} \\ s_i \in \{1, \dots, k\}}} \sum_{j=1, \dots, k}^n \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu_{s_i}\|_{\mathcal{H}}^2,$$

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Given fixed μ_1, \dots, μ_k , assign each \mathbf{x}_i to its closest centroid: $\forall i$,

$$s_i \in \operatorname{argmin}_{s \in \{1, \dots, k\}} \|\varphi(\mathbf{x}_i) - \mu_s\|_{\mathcal{H}}^2.$$

The kernel K-means algorithm

Given now the objective,

$$\min_{\substack{\mu_j \in \mathcal{H} \text{ for } j=1, \dots, k \\ s_i \in \{1, \dots, k\} \text{ for } i=1, \dots, n}} \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu_{s_i}\|_{\mathcal{H}}^2,$$

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$$s_i \in \operatorname{argmin}_{s \in \{1, \dots, k\}} \left\| \varphi(\mathbf{x}_i) - \frac{1}{|C_s|} \sum_{i \in C_s} \varphi(\mathbf{x}_i) \right\|_{\mathcal{H}}^2 \quad (C_s \text{ is from step 1}).$$

The kernel K-means algorithm

Given now the objective,

$$\min_{\substack{\mu_j \in \mathcal{H} \text{ for } j=1,\dots,k \\ s_i \in \{1,\dots,k\} \text{ for } i=1,\dots,n}} \sum_{i=1}^n \|\varphi(\mathbf{x}_i) - \mu_{s_i}\|_{\mathcal{H}}^2,$$

we know that given assignments s_i , the optimal μ_j are the centers of mass of the respective clusters and we obtain

Greedy approach: kernel K-means

We alternate between two steps:

2 cluster assignment:

Given fixed μ_1, \dots, μ_k , assign each \mathbf{x}_i to its closest centroid: $\forall i$,

$$s_i \in \operatorname{argmin}_{s \in \{1,\dots,k\}} \left(K(\mathbf{x}_i, \mathbf{x}_i) - \frac{2}{|C_s|} \sum_{j \in C_s} K(\mathbf{x}_i, \mathbf{x}_j) + \frac{1}{|C_s|^2} \sum_{j, l \in C_s} K(\mathbf{x}_j, \mathbf{x}_l) \right).$$

The kernel K-means algorithm, equivalent objective

Note that all operations are performed by manipulating kernel values $K(\mathbf{x}_i, \mathbf{x}_j)$ only. Implicitly, we are optimizing in fact

$$\min_{\substack{s_i \in \{1, \dots, k\} \\ \text{for } i=1, \dots, n}} \sum_{i=1}^n \left\| \varphi(\mathbf{x}_i) - \frac{1}{|C_{s_i}|} \sum_{j \in C_{s_i}} \varphi(\mathbf{x}_j) \right\|_{\mathcal{H}}^2,$$

or, equivalently,

$$\min_{\substack{s_i \in \{1, \dots, k\} \\ \text{for } i=1, \dots, n}} \sum_{i=1}^n \left(K(\mathbf{x}_i, \mathbf{x}_i) - \frac{2}{|C_{s_i}|} \sum_{j \in C_{s_i}} K(\mathbf{x}_i, \mathbf{x}_j) + \frac{1}{|C_{s_i}|^2} \sum_{j, l \in C_{s_i}} K(\mathbf{x}_j, \mathbf{x}_l) \right).$$

Then, notice that

$$\sum_{i=1}^n \frac{1}{|C_{s_i}|^2} \sum_{j, l \in C_{s_i}} K(\mathbf{x}_j, \mathbf{x}_l) = \sum_{l=1}^k \frac{1}{|C_l|} \sum_{i, j \in C_l} K(\mathbf{x}_i, \mathbf{x}_j).$$

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and

$$\sum_{i=1}^n \frac{1}{|C_{s_i}|} \sum_{j \in C_{s_i}} K(\mathbf{x}_i, \mathbf{x}_j) = \sum_{l=1}^k \frac{1}{|C_l|} \sum_{i, j \in C_l} K(\mathbf{x}_i, \mathbf{x}_j).$$

The kernel K-means algorithm, equivalent objective

Then, after removing the constant terms $K(\mathbf{x}_i, \mathbf{x}_i)$, we obtain:

Proposition

The kernel K-means objective is equivalent to the following one:

$$\max_{\substack{s_i \in \{1, \dots, k\} \\ \text{for } i=1, \dots, n}} \sum_{l=1}^k \frac{1}{|C_l|} \sum_{i,j \in C_l} K(\mathbf{x}_i, \mathbf{x}_j).$$

This is a hard **combinatorial optimization problem**.

There are two types of algorithms to address it:

The kernel K-means algorithm, equivalent objective

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Proposition

The kernel K-means objective is equivalent to the following one:

$$\max_{\substack{s_i \in \{1, \dots, k\} \\ \text{for } i=1, \dots, n}} \sum_{l=1}^k \frac{1}{|C_l|} \sum_{i,j \in C_l} K(\mathbf{x}_i, \mathbf{x}_j).$$

This is a hard **combinatorial optimization problem**.

There are two types of algorithms to address it:

- ① **greedy algorithm: kernel K-means**
- ② **spectral relaxation: spectral clustering**

Spectral clustering algorithms

Instead of a greedy approach, we can relax the problem into a feasible one, which yields a class of algorithms called spectral clustering.

First, consider the objective

$$\max_{\substack{s_i \in \{1, \dots, k\} \\ \text{for } i=1, \dots, n}} \sum_{l=1}^k \frac{1}{|C_l|} \sum_{i,j \in C_l} K(\mathbf{x}_i, \mathbf{x}_j).$$

and we introduce

- (*) the **binary assignment matrix** \mathbf{A} in $\{0, 1\}^{n \times k}$ whose rows sum to one.
- (**) the **diagonal rescaling matrix** \mathbf{D} in $\mathbb{R}^{k \times k}$ with diagonal entries $[\mathbf{D}]_{jj}$ equal to $(\sum_{i=1}^n [\mathbf{A}]_{ij})^{-1}$: the inverse of the cardinality of cluster j .

and the objective can be rewritten (proof is easy and left as an exercise)

$$\max_{\mathbf{A}, \mathbf{D}} \left[\text{trace} (\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \right] \quad \text{s.t. } (*) \text{ and } (**).$$

Spectral clustering algorithms

$$\max_{\mathbf{A}, \mathbf{D}} \text{trace}(\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \text{ s.t. } (\star) \text{ and } (\star\star).$$

The constraints on \mathbf{A} , \mathbf{D} are such that $\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{A} \mathbf{D}^{1/2} = \mathbf{I}$ (exercise). A natural relaxation consists of dropping the constraints $(\star, \star\star)$ on \mathbf{A} and \mathbf{D} and instead optimize over $\mathbf{Z} = \mathbf{A} \mathbf{D}^{1/2}$:

$$\max_{\mathbf{Z} \in \mathbb{R}^{n \times k}} \text{trace}(\mathbf{Z}^\top \mathbf{K} \mathbf{Z}) \text{ s.t. } \mathbf{Z}^\top \mathbf{Z} = \mathbf{I}.$$

Spectral clustering algorithms

$$\max_{\mathbf{A}, \mathbf{D}} \text{trace}(\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \text{ s.t. } (\star) \text{ and } (\star\star).$$

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A solution \mathbf{Z}^* to this problem may be obtained by computing the eigenvectors of \mathbf{K} associated to the k -largest eigenvalues. This procedure is related to the **kernel PCA** algorithm!

Question

How do we obtain an **approximate** solution (\mathbf{A}, \mathbf{D}) of the original problem from the **exact solution of the relaxed one** \mathbf{Z}^* ?

Spectral clustering algorithms

$$\max_{\mathbf{A}, \mathbf{D}} \text{trace}(\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \text{ s.t. } (\star) \text{ and } (\star\star).$$

The constraints on \mathbf{A} , \mathbf{D} are such that $\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{A} \mathbf{D}^{1/2} = \mathbf{I}$ (exercise). A natural relaxation consists of dropping the constraints $(\star, \star\star)$ on \mathbf{A} and \mathbf{D} and instead optimize over $\mathbf{Z} = \mathbf{A} \mathbf{D}^{1/2}$:

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Answer 1

With the original constraints on \mathbf{A} , every row of \mathbf{A} has a single non-zero entry \Rightarrow compute the maximum entry of every row of \mathbf{Z}^* .

Spectral clustering algorithms

$$\max_{\mathbf{A}, \mathbf{D}} \text{trace}(\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \text{ s.t. } (\star) \text{ and } (\star\star).$$

The constraints on \mathbf{A} , \mathbf{D} are such that $\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{A} \mathbf{D}^{1/2} = \mathbf{I}$ (exercise). A natural relaxation consists of dropping the constraints $(\star, \star\star)$ on \mathbf{A} and \mathbf{D} and instead optimize over $\mathbf{Z} = \mathbf{A} \mathbf{D}^{1/2}$:

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A solution \mathbf{Z}^* to this problem may be obtained by computing the eigenvectors of \mathbf{K} associated to the k -largest eigenvalues. This procedure is related to the **kernel PCA** algorithm!

Answer 2

Normalize the rows of \mathbf{Z}^* to have unit ℓ_2 -norm, and apply the traditional K-means algorithm on the rows. This is called **spectral clustering**.

Spectral clustering algorithms

$$\max_{\mathbf{A}, \mathbf{D}} \text{trace}(\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{K} \mathbf{A} \mathbf{D}^{1/2}) \text{ s.t. } (\star) \text{ and } (\star\star).$$

The constraints on \mathbf{A} , \mathbf{D} are such that $\mathbf{D}^{1/2} \mathbf{A}^\top \mathbf{A} \mathbf{D}^{1/2} = \mathbf{I}$ (exercise). A natural relaxation consists of dropping the constraints $(\star, \star\star)$ on \mathbf{A} and \mathbf{D} and instead optimize over $\mathbf{Z} = \mathbf{A} \mathbf{D}^{1/2}$:

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Answer 3

Choose another variant of the previous procedures.

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Canonical Correlation Analysis (CCA)

Given two views $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]$ in $\mathbb{R}^{p \times n}$ and $\mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_n]$ in $\mathbb{R}^{d \times n}$ of the same dataset, the goal of canonical correlation analysis (CCA) is to find **pairs of directions** in the two views that are **maximally correlated**.

Formulation

Assuming that the datasets are centered, we want to maximize

$$\max_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} \frac{\frac{1}{n} \sum_{i=1}^n \mathbf{w}_a^\top \mathbf{x}_i \mathbf{y}_i^\top \mathbf{w}_b}{\left(\frac{1}{n} \sum_{i=1}^n \mathbf{w}_a^\top \mathbf{x}_i \mathbf{x}_i^\top \mathbf{w}_a \right)^{1/2} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{w}_b^\top \mathbf{y}_i \mathbf{y}_i^\top \mathbf{w}_b \right)^{1/2}}.$$

Assuming that the pairs $(\mathbf{x}_i, \mathbf{y}_i)$ are i.i.d. samples from an unknown distribution, CCA seeks to maximize

$$\max_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} \frac{\text{cov}(\mathbf{w}_a^\top \mathbf{X}, \mathbf{w}_b^\top \mathbf{Y})}{\sqrt{\text{var}(\mathbf{w}_a^\top \mathbf{X})} \sqrt{\text{var}(\mathbf{w}_b^\top \mathbf{Y})}}.$$

Canonical Correlation Analysis (CCA)

Given two views $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]$ in $\mathbb{R}^{p \times n}$ and $\mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_n]$ in $\mathbb{R}^{d \times n}$ of the same dataset, the goal of canonical correlation analysis (CCA) is to find **pairs of directions** in the two views that are **maximally correlated**.

Formulation

Assuming that the datasets are centered, we want to maximize

$$\max_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} \frac{\frac{1}{n} \sum_{i=1}^n \mathbf{w}_a^\top \mathbf{x}_i \mathbf{y}_i^\top \mathbf{w}_b}{\left(\frac{1}{n} \sum_{i=1}^n \mathbf{w}_a^\top \mathbf{x}_i \mathbf{x}_i^\top \mathbf{w}_a \right)^{1/2} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{w}_b^\top \mathbf{y}_i \mathbf{y}_i^\top \mathbf{w}_b \right)^{1/2}}.$$

It is possible to show that this is an **generalized eigenvalue problem** (see next slide or see Section 6.5 of Shawe-Taylor and Cristianini 2004b).

The above problem provides the **first pair of canonical directions**. Next directions can be obtained by solving the same problem under the constraint that they are **orthogonal to the previous canonical directions**.

Canonical Correlation Analysis (CCA)

Formulation

Assuming that the datasets are centered,

$$\max_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} \frac{\mathbf{w}_a^\top \mathbf{X}^\top \mathbf{Y} \mathbf{w}_b}{(\mathbf{w}_a^\top \mathbf{X}^\top \mathbf{X} \mathbf{w}_a)^{1/2} (\mathbf{w}_b^\top \mathbf{Y}^\top \mathbf{Y} \mathbf{w}_b)^{1/2}}.$$

can be formulated, after removing the scaling ambiguity, as

$$\max_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} \mathbf{w}_a^\top \mathbf{X}^\top \mathbf{Y} \mathbf{w}_b \text{ s.t. } \mathbf{w}_a^\top \mathbf{X}^\top \mathbf{X} \mathbf{w}_a = 1 \text{ and } \mathbf{w}_b^\top \mathbf{Y}^\top \mathbf{Y} \mathbf{w}_b = 1.$$

Then, there exists λ_a and λ_b such that the problem is equivalent to

$$\min_{\mathbf{w}_a \in \mathbb{R}^p, \mathbf{w}_b \in \mathbb{R}^d} -\mathbf{w}_a^\top \mathbf{X}^\top \mathbf{Y} \mathbf{w}_b + \frac{\lambda_a}{2} (\mathbf{w}_a^\top \mathbf{X}^\top \mathbf{X} \mathbf{w}_a - 1) + \frac{\lambda_b}{2} (\mathbf{w}_b^\top \mathbf{Y}^\top \mathbf{Y} \mathbf{w}_b - 1).$$

Canonical Correlation Analysis (CCA)

Taking the derivatives and setting the gradient to zero, we obtain

$$-\mathbf{X}^T \mathbf{Y} \mathbf{w}_b + \lambda_a \mathbf{X}^T \mathbf{X} \mathbf{w}_a = 0$$

$$-\mathbf{Y}^T \mathbf{X} \mathbf{w}_a + \lambda_b \mathbf{Y}^T \mathbf{Y} \mathbf{w}_b = 0$$

Multiply first equality by \mathbf{w}_a^T and second equality by \mathbf{w}_b^T ; subtract the two resulting equalities and we get

$$\lambda_a \mathbf{w}_a^T \mathbf{X}^T \mathbf{X} \mathbf{w}_a = \lambda_b \mathbf{w}_b^T \mathbf{Y}^T \mathbf{Y} \mathbf{w}_b = \lambda_a = \lambda_b = \lambda,$$

and then, we obtain the **generalized eigenvalue problem**:

$$\begin{bmatrix} 0 & \mathbf{X}^T \mathbf{Y} \\ \mathbf{Y}^T \mathbf{X} & 0 \end{bmatrix} \begin{bmatrix} \mathbf{w}_a \\ \mathbf{w}_b \end{bmatrix} = \lambda \begin{bmatrix} \mathbf{X}^T \mathbf{X} & 0 \\ 0 & \mathbf{Y}^T \mathbf{Y} \end{bmatrix} \begin{bmatrix} \mathbf{w}_a \\ \mathbf{w}_b \end{bmatrix}$$

Canonical Correlation Analysis (CCA)

Let us define

$$\boldsymbol{\Sigma}_A = \begin{bmatrix} 0 & \mathbf{X}^\top \mathbf{Y} \\ \mathbf{Y}^\top \mathbf{X} & 0 \end{bmatrix}, \quad \boldsymbol{\Sigma}_B = \begin{bmatrix} \mathbf{X}^\top \mathbf{X} & 0 \\ 0 & \mathbf{Y}^\top \mathbf{Y} \end{bmatrix} \quad \text{and} \quad \mathbf{w} = \begin{bmatrix} \mathbf{w}_a \\ \mathbf{w}_b \end{bmatrix}$$

Assuming the covariances are invertible, the generalized eigenvalue problem is equivalent to

$$\boldsymbol{\Sigma}_B^{-1/2} \boldsymbol{\Sigma}_A \mathbf{w} = \lambda \boldsymbol{\Sigma}_B^{1/2} \mathbf{w}$$

which is also equivalent to the eigenvalue problem

$$\boldsymbol{\Sigma}_B^{-1/2} \boldsymbol{\Sigma}_A \boldsymbol{\Sigma}_B^{-1/2} (\boldsymbol{\Sigma}_B^{1/2} \mathbf{w}) = \lambda (\boldsymbol{\Sigma}_B^{1/2} \mathbf{w}).$$

Kernel Canonical Correlation Analysis

Similar to kernel PCA, it is possible to operate in a RKHS. Given two p.d. kernels $K_a, K_b : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$, we can obtain two “views” of a dataset $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X}^n :

$$(\varphi_a(\mathbf{x}_1), \dots, \varphi_a(\mathbf{x}_n)) \quad \text{and} \quad (\varphi_b(\mathbf{x}_1), \dots, \varphi_b(\mathbf{x}_n)),$$

where $\varphi_a : \mathcal{X} \rightarrow \mathcal{H}_a$ and $\varphi_b : \mathcal{X} \rightarrow \mathcal{H}_b$ are the embeddings in the RKHSs \mathcal{H}_a of K_a and \mathcal{H}_b of K_b , respectively.

Formulation

Then, we may formulate **kernel CCA** as

$$\max_{f_a \in \mathcal{H}_a, f_b \in \mathcal{H}_b} \frac{\frac{1}{n} \sum_{i=1}^n \langle f_a, \varphi_a(\mathbf{x}_i) \rangle_{\mathcal{H}_a} \langle \varphi_b(\mathbf{x}_i), f_b \rangle_{\mathcal{H}_b}}{\left(\frac{1}{n} \sum_{i=1}^n \langle f_a, \varphi_a(\mathbf{x}_i) \rangle_{\mathcal{H}_a}^2 \right)^{1/2} \left(\frac{1}{n} \sum_{i=1}^n \langle f_b, \varphi_b(\mathbf{x}_i) \rangle_{\mathcal{H}_b}^2 \right)^{1/2}}.$$

Kernel Canonical Correlation Analysis

Similar to kernel PCA, it is possible to operate in a RKHS. Given two p.d. kernels $K_a, K_b : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$, we can obtain two “views” of a dataset $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X}^n :

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Formulation

Then, we may formulate **kernel CCA** as

$$\max_{f_a \in \mathcal{H}_a, f_b \in \mathcal{H}_b} \frac{\frac{1}{n} \sum_{i=1}^n f_a(\mathbf{x}_i) f_b(\mathbf{x}_i)}{\left(\frac{1}{n} \sum_{i=1}^n f_a(\mathbf{x}_i)^2 \right)^{1/2} \left(\frac{1}{n} \sum_{i=1}^n f_b(\mathbf{x}_i)^2 \right)^{1/2}}.$$

Kernel Canonical Correlation Analysis

Up to a few technical details (exercise), we can apply the **representer theorem** and look for solutions $f_a(.) = \sum_{i=1}^n \alpha_i K_a(\mathbf{x}_i, .)$ and $f_b(.) = \sum_{i=1}^n \beta_i K_b(\mathbf{x}_i, .)$. We finally obtain the formulation

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \frac{\frac{1}{n} \sum_{i=1}^n [\mathbf{K}_a \alpha]_i [\mathbf{K}_b \beta]_i}{\left(\frac{1}{n} \sum_{i=1}^n [\mathbf{K}_a \alpha]_i^2 \right)^{1/2} \left(\frac{1}{n} \sum_{i=1}^n [\mathbf{K}_b \beta]_i^2 \right)^{1/2}},$$

which is equivalent to

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \frac{\alpha^\top \mathbf{K}_a \mathbf{K}_b \beta}{(\alpha^\top \mathbf{K}_a^2 \alpha)^{1/2} (\beta^\top \mathbf{K}_b^2 \beta)^{1/2}},$$

or, after removing the scaling ambiguity for α and β ,

Equivalent formulation

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \alpha^\top \mathbf{K}_a \mathbf{K}_b \beta \text{ s.t. } \alpha^\top \mathbf{K}_a^2 \alpha = 1 \text{ and } \beta^\top \mathbf{K}_b^2 \beta = 1.$$

Kernel Canonical Correlation Analysis

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \alpha^\top \mathbf{K}_a \mathbf{K}_b \beta \text{ s.t. } \alpha^\top \mathbf{K}_a^2 \alpha = 1 \text{ and } \beta^\top \mathbf{K}_b^2 \beta = 1.$$

- This also leads to a generalized eigenvalue problem.
- The subsequent canonical directions are obtained by solving the same problem with additional orthogonality constraints.

Kernel Canonical Correlation Analysis

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What is wrong here?

Kernel Canonical Correlation Analysis

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- The subsequent canonical directions are obtained by solving the same problem with additional orthogonality constraints.

What is wrong here?

If \mathbf{K}_a and \mathbf{K}_b are invertible, make the change of variable $\alpha' = \mathbf{K}_a \alpha$ and $\beta' = \mathbf{K}_b \beta$, and we obtain the equivalent formulation

$$\max_{\alpha' \in \mathbb{R}^n, \beta' \in \mathbb{R}^n} \alpha'^\top \beta' \text{ s.t. } \alpha'^\top \alpha' = 1 \text{ and } \beta'^\top \beta' = 1.$$

The function is maximized for **any** $\alpha' = \beta'$ in \mathbb{R}^n .

Kernel Canonical Correlation Analysis

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \alpha^\top \mathbf{K}_a \mathbf{K}_b \beta \text{ s.t. } \alpha^\top \mathbf{K}_a^2 \alpha = 1 \text{ and } \beta^\top \mathbf{K}_b^2 \beta = 1.$$

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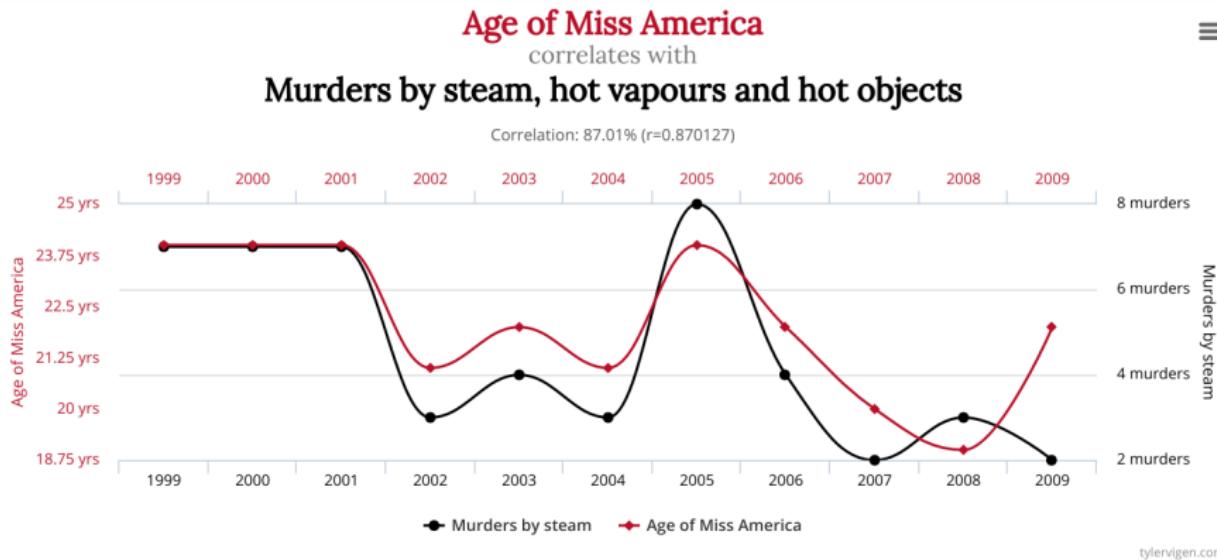
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The function is maximized for **any** $\alpha' = \beta'$ in \mathbb{R}^n . In high (or infinite) dimension, it is easy to find **spurious** correlations.

Spurious correlations

Spurious correlations are bad:

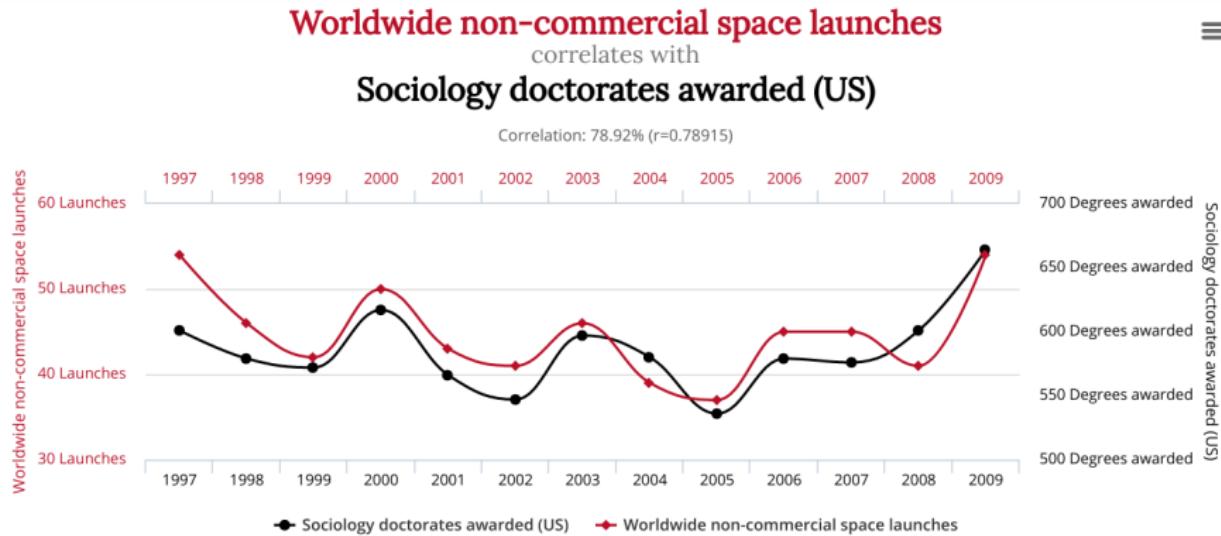


Data sources: Wikipedia and Centers for Disease Control & Prevention

Figure: <http://www.tylervigen.com/>.

Spurious correlations

Spurious correlations are bad:



Data sources: Federal Aviation Administration and National Science Foundation

tylervigen.com

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Kernel Canonical Correlation Analysis

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \alpha^\top \mathbf{K}_a \mathbf{K}_b \beta \text{ s.t. } \alpha^\top \mathbf{K}_a^2 \alpha = 1 \text{ and } \beta^\top \mathbf{K}_b^2 \beta = 1.$$

- spurious correlation is a problem of **overfitting**;
- it also a problem of **numerical instability**, due to the need to invert the kernel matrices;

Kernel Canonical Correlation Analysis

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^n} \alpha^\top \mathbf{K}_a \mathbf{K}_b \beta \text{ s.t. } \alpha^\top \mathbf{K}_a^2 \alpha = 1 \text{ and } \beta^\top \mathbf{K}_b^2 \beta = 1.$$

- spurious correlation is a problem of **overfitting**;
- it is also a problem of **numerical instability**, due to the need to invert the kernel matrices;

A solution to both problems: Regularize!

- Find **smooth** directions (f_a, f_b) by penalizing $\|f_a\|_{\mathcal{H}_a}$ and $\|f_b\|_{\mathcal{H}_b}$.
- it consists of replacing the constraints $\alpha^\top \mathbf{K}_a^2 \alpha = 1$ by

$$(1 - \tau) \alpha^\top \mathbf{K}_a^2 \alpha + \tau \underbrace{\alpha^\top \mathbf{K}_a \alpha}_{\|f_a\|_{\mathcal{H}_a}^2} = 1,$$

and do the same for $\beta^\top \mathbf{K}_b^2 \beta = 1$.

Application of kernel CCA

Finding a joint latent representation of text (tags) and images.

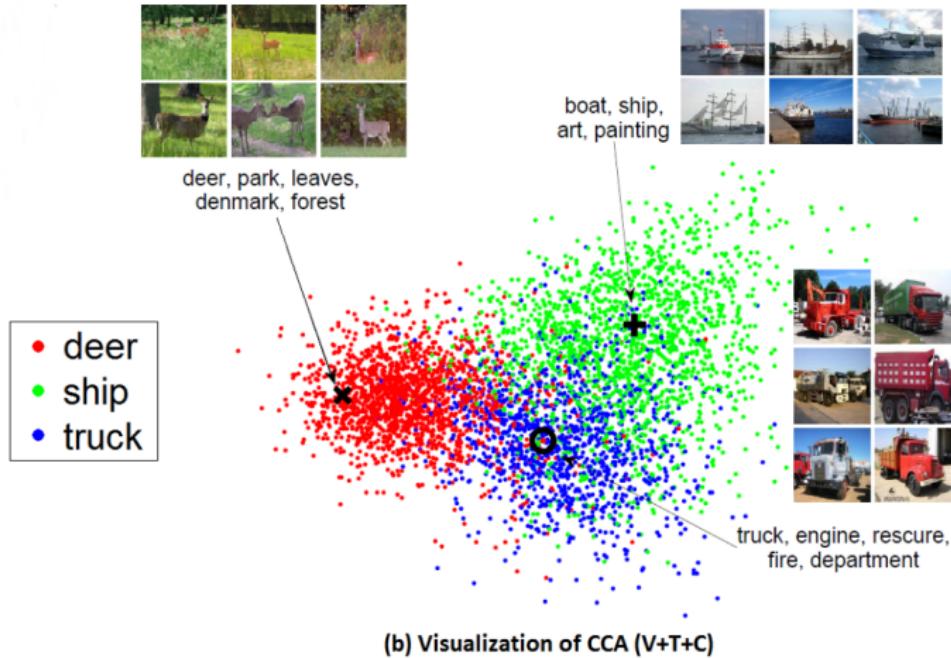


Figure: Figure from Gong and Lazebnik, 2014.

The Kernel Jungle

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
 - Green, Mercer, Herglotz, Bochner and friends
 - Kernels for probabilistic models
 - Kernels for biological sequences
 - Kernels for graphs
 - Kernels on graphs
- 6 Open Problems and Research Topics

Introduction

- The kernel function plays a critical role in the **performance** of kernel methods.
- It is the place where **prior knowledge** about the problem can be inserted, in particular by controlling the norm of functions in the RKHS.
- In this part we provide some intuition about the **link between kernels and smoothness functional** through several examples.
- Subsequent parts will focus on the **design** of kernels for particular types of data.

Outline

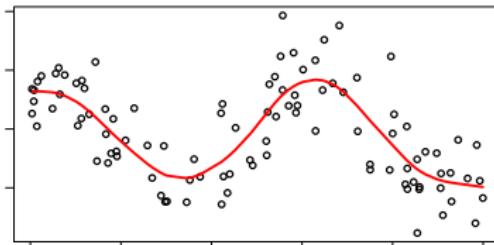
5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
 - Green kernels
 - Mercer kernels
 - Shift-invariant kernels
 - Generalization to semigroups
- Kernels for probabilistic models
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Motivations

- The RKHS norm is related to the **smoothness** of functions.
- Smoothness of a function is naturally quantified by **Sobolev norms** (in particular L_2 norms of derivatives).
- Example: spline regression

$$\min_f \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 + \lambda \int (f''(t))^2 dt$$



- In this section we make a general link between RKHS and **Green functions defined by differential operators**.

A simple example

Let

$$\mathcal{H} = \{f : [0, 1] \mapsto \mathbb{R}, \text{absolutely continuous, } f' \in L^2([0, 1]), f(0) = 0\},$$

endowed with the bilinear form:

$$\forall f, g \in \mathcal{H}, \quad \langle f, g \rangle_{\mathcal{H}} = \int_0^1 f'(u) g'(u) du.$$

Note that $\langle f, f \rangle_{\mathcal{H}}$ measures the smoothness of f :

$$\langle f, f \rangle_{\mathcal{H}} = \int_0^1 f'(u)^2 du = \|f'\|_{L^2([0,1])}^2.$$

The RKHs point of view

Theorem

\mathcal{H} is an RKHS with r.k. given by:

$$\forall (x, y) \in [0, 1]^2, \quad K(x, y) = \min(x, y).$$

Therefore, the RKHS norm is precisely the smoothness functional defined in the simple example:

$$\|f\|_{\mathcal{H}} = \|f'\|_{L^2}$$

In particular, the following problem

$$\min_{f \in \mathcal{H}} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 + \lambda \int_0^1 (f'(t))^2 dt$$

can be reformulated as a simple kernel ridge regression problem with kernel $K(x, y) = \min(x, y)$:

$$\min_{f \in \mathcal{H}_K} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}_K}^2$$

Technical remark

Definition

Let $I \subset \mathbb{R}$ an interval. A function $f : I \rightarrow \mathbb{R}$ is **absolutely continuous** (AC) on I if for any $\epsilon > 0$, there exists $\delta > 0$ such that for any finite sequence of pairwise disjoint sub-intervals $(u_k, v_k) \subset I$ such that $\sum_k (v_k - u_k) < \delta$, it holds that $\sum_k |f(v_k) - f(u_k)| < \epsilon$.

- AC \implies uniformly continuous \implies continuous
- f AC on $[a, b] \iff f$ has derivative f' almost everywhere, f' is Lebesgue integrable, and for all $x \in [a, b]$

$$f(x) = f(a) + \int_a^x f'(t)dt$$

\iff there exists a Lebesgue integrable function g on $[a, b]$ such that for all $x \in [a, b]$,

$$f(x) = f(a) + \int_a^x g(t)dt$$

in which case $g = f'$ almost everywhere.

Proof (1/5)

We need to show that

- ① \mathcal{H} is a Hilbert space of functions
- ② $\forall x \in [0, 1], K_x \in \mathcal{H},$
- ③ $\forall (x, f) \in [0, 1] \times \mathcal{H}, \langle f, K_x \rangle_{\mathcal{H}} = f(x).$

Proof (2/5)

\mathcal{H} is a pre-Hilbert space of functions

- \mathcal{H} is a vector space of functions, and $\langle f, g \rangle_{\mathcal{H}}$ a bilinear form that satisfies $\langle f, f \rangle_{\mathcal{H}} \geq 0$.
- f absolutely continuous implies differentiable almost everywhere, and

$$\forall x \in [0, 1], \quad f(x) = f(0) + \int_0^x f'(u) du.$$

- For any $f \in \mathcal{H}$, $f(0) = 0$ implies by Cauchy-Schwarz:

$$|f(x)| = \left| \int_0^x f'(u) du \right| \leq \sqrt{x} \left(\int_0^1 f'(u)^2 du \right)^{\frac{1}{2}} = \sqrt{x} \langle f, f \rangle_{\mathcal{H}}^{1/2}.$$

Therefore, $\langle f, f \rangle_{\mathcal{H}} = 0 \implies f = 0$, showing that $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ is an inner product. \mathcal{H} is thus a pre-Hilbert space.

Proof (3/5)

\mathcal{H} is a Hilbert space

- To show that \mathcal{H} is complete, let $(f_n)_{n \in \mathbb{N}}$ a Cauchy sequence in \mathcal{H}
- $(f'_n)_{n \in \mathbb{N}}$ is a Cauchy sequence in $L^2[0, 1]$, thus converges to $g \in L^2[0, 1]$
- By the previous inequality, $(f_n(x))_{n \in \mathbb{N}}$ is a Cauchy sequence and thus converges to a real number $f(x)$, for any $x \in [0, 1]$. Moreover:

$$f(x) = \lim_n f_n(x) = \lim_n \int_0^x f'_n(u) du = \int_0^x g(u) du,$$

showing that f is absolutely continuous and $f' = g$ almost everywhere; in particular, $f' \in L^2[0, 1]$.

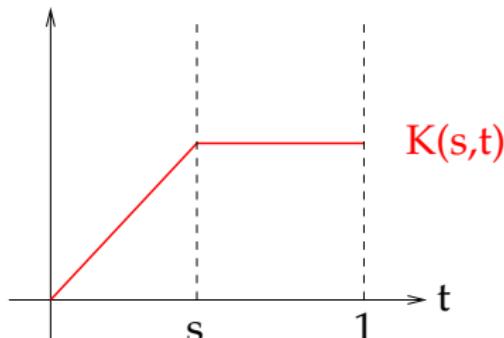
- Finally, $f(0) = \lim_n f_n(0) = 0$, therefore $f \in \mathcal{H}$ and

$$\lim_n \|f_n - f\|_{\mathcal{H}} = \|f' - g\|_{L^2[0,1]} = 0.$$

Proof (4/5)

$\forall x \in [0, 1], K_x \in \mathcal{H}$

- Let $K_x(y) = K(x, y) = \min(x, y)$ sur $[0, 1]^2$:



- K_x is differentiable except at s , has a square integrable derivative, and $K_x(0) = 0$, therefore $K_x \in \mathcal{H}$ for all $x \in [0, 1]$.

Proof (5/5)

For all x, f , $\langle f, K_x \rangle_{\mathcal{H}} = f(x)$

- For any $x \in [0, 1]$ and $f \in \mathcal{H}$ we have:

$$\langle f, K_x \rangle_{\mathcal{H}} = \int_0^1 f'(u) K'_x(u) du = \int_0^x f'(u) du = f(x),$$

- This shows that \mathcal{H} is a RKHS with K as r.k. \square

Generalization

Theorem

Let $\mathcal{X} = \mathbb{R}^d$ and D a differential operator on a class of functions \mathcal{H} such that, endowed with the inner product:

$$\forall (f, g) \in \mathcal{H}^2, \quad \langle f, g \rangle_{\mathcal{H}} = \langle Df, Dg \rangle_{L^2(\mathcal{X})},$$

it is a Hilbert space.

Then \mathcal{H} is a RKHS that admits as r.k. the Green function of the operator D^*D , where D^* denotes the adjoint operator of D .

Green function?

Definition

Let the differential equation on \mathcal{H} :

$$f = Dg ,$$

where g is unknown. In order to solve it we can look for g of the form:

$$g(x) = \int_{\mathcal{X}} k(x, y) f(y) dy$$

for some function $k : \mathcal{X}^2 \mapsto \mathbb{R}$. k must then satisfy, for all $x \in \mathcal{X}$,

$$f(x) = Dg(x) = \langle Dk_x, f \rangle_{L^2(\mathcal{X})} .$$

If such a k exists, it is called the **Green function** of the operator D .

Proof

- Let \mathcal{H} be a Hilbert space endowed with the inner product:

$$\langle f, g \rangle_{\mathcal{X}} = \langle Df, Dg \rangle_{L^2(\mathcal{X})},$$

and K be the Green function of the operator D^*D .

- For all $x \in \mathcal{X}$, $K_x \in \mathcal{H}$ because:

$$\langle DK_x, DK_x \rangle_{L^2(\mathcal{X})} = \langle D^*DK_x, K_x \rangle_{L^2(\mathcal{X})} = K_x(x) < \infty.$$

(caveat: sometimes other conditions must be fulfilled to be in \mathcal{H} , to be checked on a case by case basis).

- Moreover, for all $f \in \mathcal{H}$ and $x \in \mathcal{X}$, we have:

$$f(x) = \langle D^*DK_x, f \rangle_{L^2(\mathcal{X})} = \langle DK_x, Df \rangle_{L^2(\mathcal{X})} = \langle K_x, f \rangle_{\mathcal{H}}.$$

- This shows that \mathcal{H} is a RKHS with K as r.k. \square

Example

- Back to our example, take $\mathcal{X} = [0, 1]$ and $Df(u) = f'(u)$
- To find the r.k. of \mathcal{H} we need to solve in k :

$$\begin{aligned} f(x) &= \langle D^* D k_x, f \rangle_{L^2([0,1])} \\ &= \langle D k_x, Df \rangle_{L^2([0,1])} \\ &= \int_0^1 k'_x(u) f'(u) du \end{aligned}$$

- The solution is

$$k'_x(u) = \mathbf{1}_{[0,x]}(u)$$

which gives

$$k_x(u) = \begin{cases} u & \text{if } u \leq x, \\ x & \text{otherwise.} \end{cases}$$

and therefore

$$k(x, x') = \min(x, x')$$

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Mercer kernels

Definition

A kernel K on a set \mathcal{X} is called a **Mercer kernel** if:

- ① \mathcal{X} is a **compact metric space** (typically, a closed bounded subset of \mathbb{R}^d).
- ② $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a **continuous** p.d. kernel (w.r.t. the Borel topology)

Motivations

- We can exhibit an explicit and intuitive feature space for a large class of p.d. kernels
- Historically, provided the first proof that a p.d. kernel is an inner product for non-finite sets \mathcal{X} (Mercer, 1905).
- Can be thought of as the natural generalization of the factorization of positive semidefinite matrices over infinite spaces.

Sketch of the proof that a Mercer kernel is an inner product

- ① The kernel matrix when \mathcal{X} is finite becomes a **linear operator** when \mathcal{X} is a metric space.
- ② The matrix was positive semidefinite in the finite case, the linear operator is **self-adjoint** and **positive** in the metric case.
- ③ The **spectral theorem** states that any **compact** linear operator admits a complete orthonormal basis of eigenfunctions, with non-negative eigenvalues (just like positive semidefinite matrices can be diagonalized with nonnegative eigenvalues).
- ④ The kernel function can then be expanded over basis of eigenfunctions as:

$$K(\mathbf{x}, \mathbf{t}) = \sum_{k=1}^{\infty} \lambda_k \psi_k(\mathbf{x}) \psi_k(\mathbf{t}),$$

where $\lambda_i \geq 0$ are the non-negative eigenvalues.

In case of...

Definition

Let \mathcal{H} be a Hilbert space

- A **linear operator** is a continuous linear mapping from \mathcal{H} to itself.
- A linear operator L is called **compact** if, for any bounded sequence $\{f_n\}_{n=1}^{\infty}$, the sequence $\{Lf_n\}_{n=1}^{\infty}$ has a subsequence that converges.
- L is called **self-adjoint** if, for any $f, g \in \mathcal{H}$:

$$\langle f, Lg \rangle = \langle Lf, g \rangle .$$

- L is called **positive** if it is self-adjoint and, for any $f \in \mathcal{H}$:

$$\langle f, Lf \rangle \geq 0 .$$

An important lemma

The linear operator

- Let ν be any Borel measure on \mathcal{X} , and $L_2^\nu(\mathcal{X})$ the Hilbert space of square integrable functions on \mathcal{X} .
- For any function $K : \mathcal{X}^2 \mapsto \mathbb{R}$, let the transform:

$$\forall f \in L_2^\nu(\mathcal{X}), \quad (L_K f)(\mathbf{x}) = \int K(\mathbf{x}, \mathbf{t}) f(\mathbf{t}) d\nu(\mathbf{t}).$$

Lemma

If K is a Mercer kernel, then L_K is a compact and bounded linear operator over $L_2^\nu(\mathcal{X})$, self-adjoint and positive.

Proof (1/6)

L_K is a mapping from $L_2^\nu(\mathcal{X})$ to $L_2^\nu(\mathcal{X})$

For any $f \in L_2^\nu(\mathcal{X})$ and $(\mathbf{x}_1, \mathbf{x}_2) \in \mathcal{X}^2$:

$$\begin{aligned}|L_K f(\mathbf{x}_1) - L_K f(\mathbf{x}_2)| &= \left| \int (K(\mathbf{x}_1, \mathbf{t}) - K(\mathbf{x}_2, \mathbf{t})) f(\mathbf{t}) d\nu(\mathbf{t}) \right| \\&\leq \|K(\mathbf{x}_1, \cdot) - K(\mathbf{x}_2, \cdot)\| \|f\| \quad (\text{Cauchy-Schwarz}) \\&\leq \sqrt{\nu(\mathcal{X})} \max_{\mathbf{t} \in \mathcal{X}} |K(\mathbf{x}_1, \mathbf{t}) - K(\mathbf{x}_2, \mathbf{t})| \|f\|.\end{aligned}$$

K being continuous and \mathcal{X} compact, K is uniformly continuous, therefore $L_K f$ is continuous. In particular, $L_K f \in L_2^\nu(\mathcal{X})$ (with the slight abuse of notation $\mathcal{C}(\mathcal{X}) \subset L_2^\nu(\mathcal{X})$). \square

Proof (2/6)

L_K is linear and continuous

- Linearity is obvious (by definition of L_K and linearity of the integral).
- For continuity, we observe that for all $f \in L_2^\nu(\mathcal{X})$ and $\mathbf{x} \in \mathcal{X}$:

$$\begin{aligned}|(L_K f)(\mathbf{x})| &= \left| \int K(\mathbf{x}, \mathbf{t}) f(\mathbf{t}) d\nu(\mathbf{t}) \right| \\&\leq \sqrt{\nu(\mathcal{X})} \max_{\mathbf{t} \in \mathcal{X}} |K(\mathbf{x}, \mathbf{t})| \|f\| \\&\leq \sqrt{\nu(\mathcal{X})} C_K \|f\|.\end{aligned}$$

with $C_K = \max_{\mathbf{x}, \mathbf{t} \in \mathcal{X}} |K(\mathbf{x}, \mathbf{t})|$. Therefore:

$$\|L_K f\| = \left(\int L_K f(\mathbf{t})^2 d\nu(\mathbf{t}) \right)^{\frac{1}{2}} \leq \sqrt{\nu(\mathcal{X})} C_K \|f\|. \quad \square$$

Proof (3/6)

Criterion for compactness

In order to prove the compactness of L_K we need the following criterion.
Let $C(\mathcal{X})$ denote the set of continuous functions on \mathcal{X} endowed with infinite norm $\|f\|_\infty = \max_{x \in \mathcal{X}} |f(x)|$.

A set of functions $G \subset C(\mathcal{X})$ is called **equicontinuous** if:

$$\forall \epsilon > 0, \exists \delta > 0, \forall (\mathbf{x}, \mathbf{y}) \in \mathcal{X}^2,$$

$$\|\mathbf{x} - \mathbf{y}\| < \delta \implies \forall g \in G, |g(\mathbf{x}) - g(\mathbf{y})| < \epsilon.$$

Ascoli Theorem

A part $H \subset C(\mathcal{X})$ is **relatively compact** (i.e., its closure is compact) if and only if it is **uniformly bounded** and **equicontinuous**.

Proof (4/6)

L_K is compact

Let $(f_n)_{n \geq 0}$ be a bounded sequence of $L_2^\nu(\mathcal{X})$ ($\|f_n\| < M$ for all n).
The sequence $(L_K f_n)_{n \geq 0}$ is a sequence of continuous functions, uniformly bounded because:

$$\|L_K f_n\|_\infty \leq \sqrt{\nu(\mathcal{X})} C_K \|f_n\| \leq \sqrt{\nu(\mathcal{X})} C_K M.$$

It is equicontinuous because:

$$|L_K f_n(\mathbf{x}_1) - L_K f_n(\mathbf{x}_2)| \leq \sqrt{\nu(\mathcal{X})} \max_{\mathbf{t} \in \mathcal{X}} |K(\mathbf{x}_1, \mathbf{t}) - K(\mathbf{x}_2, \mathbf{t})| M.$$

By Ascoli theorem, we can extract a sequence uniformly convergent in $C(\mathcal{X})$, and therefore in $L_2^\nu(\mathcal{X})$. \square

Proof (5/6)

L_K is self-adjoint

K being symmetric, we have for all $f, g \in \mathcal{H}$:

$$\begin{aligned}\langle f, Lg \rangle &= \int f(\mathbf{x}) (Lg)(\mathbf{x}) \nu(d\mathbf{x}) \\ &= \int \int f(\mathbf{x}) g(\mathbf{t}) K(\mathbf{x}, \mathbf{t}) \nu(d\mathbf{x}) \nu(d\mathbf{t}) \quad (\text{Fubini}) \\ &= \langle Lf, g \rangle.\end{aligned}$$

Proof (6/6)

L_K is positive

We can approximate the integral by finite sums:

$$\begin{aligned}\langle f, Lf \rangle &= \int \int f(\mathbf{x}) f(\mathbf{t}) K(\mathbf{x}, \mathbf{t}) \nu(d\mathbf{x}) \nu(d\mathbf{t}) \\ &= \lim_{k \rightarrow \infty} \frac{\nu(\mathcal{X})}{k^2} \sum_{i,j=1}^k K(\mathbf{x}_i, \mathbf{x}_j) f(\mathbf{x}_i) f(\mathbf{x}_j) \\ &\geq 0,\end{aligned}$$

because K is positive definite. \square

Diagonalization of the operator

We need the following general result:

Spectral theorem

Let L be a **compact** linear operator on a Hilbert space \mathcal{H} . Then there exists in \mathcal{H} a **complete orthonormal system** (ψ_1, ψ_2, \dots) of eigenvectors of L . The eigenvalues $(\lambda_1, \lambda_2, \dots)$ are **real** if L is self-adjoint, and **non-negative** if L is positive.

Remark

This theorem can be applied to L_K . In that case the eigenfunctions ψ_k associated to the eigenfunctions $\lambda_k \neq 0$ can be considered as **continuous functions**, because:

$$\psi_k = \frac{1}{\lambda_k} L \psi_K .$$

Main result

Mercer Theorem

Let \mathcal{X} be a compact metric space, ν a Borel measure on \mathcal{X} , and K a continuous p.d. kernel. Let $(\lambda_1, \lambda_2, \dots)$ denote the nonnegative eigenvalues of L_K and (ψ_1, ψ_2, \dots) the corresponding eigenfunctions. Then all functions ψ_k are continuous, and for any $\mathbf{x}, \mathbf{t} \in \mathcal{X}$:

$$K(\mathbf{x}, \mathbf{t}) = \sum_{k=1}^{\infty} \lambda_k \psi_k(\mathbf{x}) \psi_k(\mathbf{t}),$$

where the convergence is absolute for each $\mathbf{x}, \mathbf{t} \in \mathcal{X}$, and uniform on $\mathcal{X} \times \mathcal{X}$.

Mercer kernels as inner products

Corollary

The mapping

$$\begin{aligned}\Phi : \mathcal{X} &\mapsto l^2 \\ \mathbf{x} &\mapsto \left(\sqrt{\lambda_k} \psi_k(\mathbf{x}) \right)_{k \in \mathbb{N}}\end{aligned}$$

is well defined, continuous, and satisfies

$$K(\mathbf{x}, \mathbf{t}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{t}) \rangle_{l^2}.$$

Proof of the corollary

- By Mercer theorem we see that for all $\mathbf{x} \in \mathcal{X}$, $\sum \lambda_k \psi_k^2(\mathbf{x})$ converges to $K(\mathbf{x}, \mathbf{x}) < \infty$, therefore $\Phi(\mathbf{x}) \in l^2$.
- The continuity of Φ results from:

$$\begin{aligned}\|\Phi(\mathbf{x}) - \Phi(\mathbf{t})\|_{l^2}^2 &= \sum_{k=1}^{\infty} \lambda_k (\psi_k(\mathbf{x}) - \psi_k(\mathbf{t}))^2 \\ &= K(\mathbf{x}, \mathbf{x}) + K(\mathbf{t}, \mathbf{t}) - 2K(\mathbf{x}, \mathbf{t})\end{aligned}$$

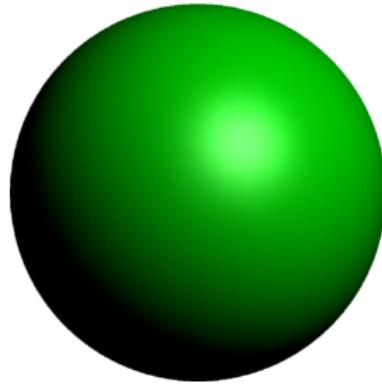
Summary

- This proof extends the proof valid when \mathcal{X} is finite.
- This is a **constructive** proof, developed by Mercer (1905).
- The eigensystem $(\lambda_k \text{ and } \psi_k)$ depend on the choice of the measure $\nu(dx)$: **different ν 's lead to different feature spaces** for a given kernel and a given space \mathcal{X}
- **Compactness** and **continuity** are required. For instance, for $\mathcal{X} = \mathbb{R}^d$, the eigenvalues of:

$$\int_{\mathcal{X}} K(\mathbf{x}, \mathbf{t}) \psi(\mathbf{t}) d\mathbf{t} = \lambda \psi(\mathbf{x})$$

are not necessarily countable, Mercer theorem does not hold. Other tools are thus required such as the Fourier transform for shift-invariant kernels.

Example (1/6)



- Consider the unit sphere in \mathbb{R}^d :

$$\mathcal{X} = S^{d-1} = \left\{ \mathbf{x} \in \mathbb{R}^d : \| \mathbf{x} \| = 1 \right\}$$

- Let ν be the Lebesgue measure on S^{d-1} . Note that:

$$\nu(S^{d-1}) = \frac{2\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2})}$$

Example (2/6)

- Let a p.d. kernel on S^{d-1} of the form:

$$K(\mathbf{x}, \mathbf{t}) = \varphi(\mathbf{x}^\top \mathbf{t}),$$

where $\varphi : [-1, 1] \rightarrow \mathbb{R}$ is continuous.

- To write Mercer's expansion we need to find the eigenfunctions by solving

$$\int_{S^{d-1}} \varphi(\mathbf{x}^\top \mathbf{t}) \psi(\mathbf{t}) d\nu(\mathbf{t}) = \lambda \psi(\mathbf{x})$$

- For that purpose study polynomials that solve the Laplace equation:

$$\Delta f = \frac{\partial^2 f}{\partial x_1^2} + \dots + \frac{\partial^2 f}{\partial x_d^2} = 0$$

where Δ is the Laplacian operator on \mathbb{R}^d .

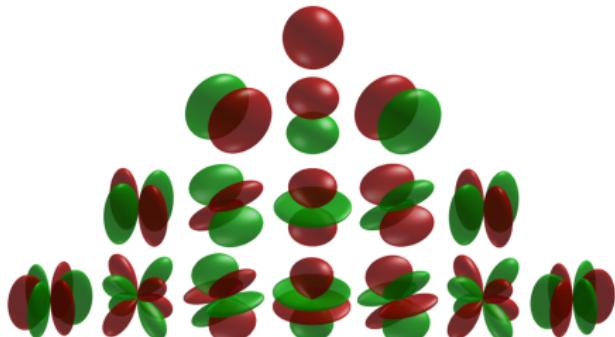
Example (3/6)

Definition (Spherical harmonics)

- A homogeneous polynomial of degree $k \geq 0$ in \mathbb{R}^d whose Laplacian vanishes is called a **homogeneous harmonic** of order k .
- A **spherical harmonic** of order k is a homogeneous harmonic of order k on the unit sphere S^{d-1}

The set $\mathcal{Y}_k(d)$ of spherical harmonics is a vector space of dimension

$$N(n, k) = \dim(\mathcal{Y}_k(d)) = \frac{(2k + d - 2)(k + d - 3)!}{k!(d - 2)!}.$$



Example (4/6)

Spherical harmonics form the Mercer's eigenfunctions, because:

Theorem (Funk-Hecke) (e.g., Müller, 1998, p.30)

For any $\mathbf{x} \in S^{d-1}$, $Y_k \in \mathcal{Y}_k(d)$ and $\varphi \in C([-1, 1])$,

$$\int_{S^{d-1}} \varphi(\mathbf{x}^\top \mathbf{t}) Y_k(\mathbf{t}) d\nu(\mathbf{t}) = \lambda_k Y_k(\mathbf{x})$$

where

$$\lambda_k = \nu(S^{d-2}) \int_{-1}^1 \varphi(t) P_k(d; t) (1 - t^2)^{\frac{d-3}{2}} dt$$

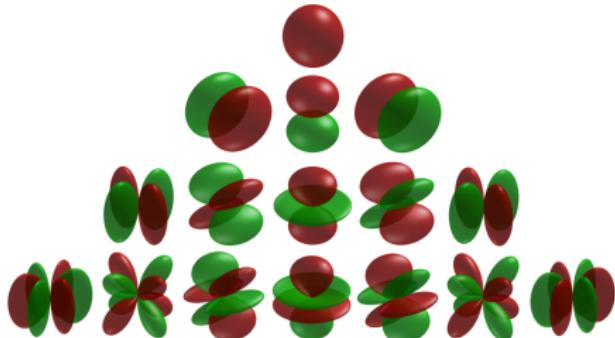
and $P_k(d; t)$ is the Legendre polynomial of degree k in dimension d .

When $\varphi \in C^k([-1, 1])$ we have Rodrigues rule (Müller, 1998, p.23):

$$\lambda_k = \nu(S^{d-2}) \frac{\Gamma\left(\frac{d-1}{2}\right)}{2^k \Gamma\left(k + \frac{d-1}{2}\right)} \int_{-1}^1 \varphi^{(k)}(t) (1 - t^2)^{k + \frac{d-3}{2}} dt$$

Example (5/6)

- For any $k \geq 0$, let $\{Y_{k,j}(d; \mathbf{x})\}_{j=1}^{N(d;k)}$ an orthonormal basis of $\mathcal{Y}_k(d)$
- Spherical harmonics $\left\{\{Y_{k,j}(d; \mathbf{x})\}_{j=1}^{N(d;k)}\right\}_{k=0}^{\infty}$ form an orthonormal basis for $L^2(S^{d-1})$
- Therefore, for any kernel $K(\mathbf{x}, \mathbf{t}) = \varphi(\mathbf{x}^\top \mathbf{t})$ on S^{d-1} the Mercer eigenvalues are exactly the λ_k 's, with corresponding orthonormal eigenfunctions $\{Y_{k,j}(d; \mathbf{x})\}_{j=1}^{N(d;k)}$.
- Note that eigenfunctions are the same for different φ 's, only the eigenvalues change



Example (6/6)

- Take $d = 2$ and $K(\mathbf{x}, \mathbf{t}) = (1 + \mathbf{x}^\top \mathbf{t})^2$ for $\mathbf{x}, \mathbf{t} \in S^1$
- Using Rodrigues rule we get 3 nonzero eigenvalues:

$$\lambda_0 = 3\pi, \quad \lambda_1 = 2\pi, \quad \lambda_2 = \frac{\pi}{2}$$

with multiplicities 1, 2 and 2

- Corresponding eigenfunctions:

$$\left(\frac{1}{\sqrt{2\pi}}, \frac{x_1}{\sqrt{\pi}}, \frac{x_2}{\sqrt{\pi}}, \frac{x_1 x_2}{\sqrt{\pi}}, \frac{x_1^2 - x_2^2}{\sqrt{\pi}} \right)$$

- The resulting Mercer feature map is

$$\Phi(\mathbf{x}) = \left(\sqrt{\frac{3}{2}}, \sqrt{2}x_1, \sqrt{2}x_2, \sqrt{2}x_1 x_2, \frac{x_1^2 - x_2^2}{\sqrt{2}} \right)$$

- Obviously, $\Phi(\mathbf{x})^\top \Phi(\mathbf{t}) = K(\mathbf{x}, \mathbf{t})$ for $\mathbf{x}, \mathbf{t} \in S^1$ (exercise)

RKHS of Mercer kernels

- Let \mathcal{X} be a compact metric space, and K a **Mercer kernel** on \mathcal{X} (symmetric, continuous and positive definite).
- We have expressed a decomposition of the kernel in terms of the **eigenfunctions** of the linear **convolution operator**.
- In some cases this provides an **intuitive** feature space.
- The kernel also has a **RKHS**, like any p.d. kernel.
- Can we get an **intuition of the RKHS norm** in terms of the **eigenfunctions and eigenvalues** of the convolution operator?

Reminder: expansion of Mercer kernel

Theorem

Denote by L_K the linear operator of $L_2^\nu(\mathcal{X})$ defined by:

$$\forall f \in L_2^\nu(\mathcal{X}), (L_K f)(\mathbf{x}) = \int K(\mathbf{x}, \mathbf{t}) f(\mathbf{t}) d\nu(\mathbf{t}).$$

Let $(\lambda_1, \lambda_2, \dots)$ denote the eigenvalues of L_K in decreasing order, and (ψ_1, ψ_2, \dots) the corresponding eigenfunctions. Then it holds that for any $\mathbf{x}, \mathbf{y} \in \mathcal{X}$:

$$K(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^{\infty} \lambda_k \psi_k(\mathbf{x}) \psi_k(\mathbf{y}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{l^2},$$

with $\Phi : \mathcal{X} \mapsto l^2$ defined par $\Phi(\mathbf{x}) = (\sqrt{\lambda_k} \psi_k(\mathbf{x}))_{k \in \mathbb{N}}$.

RKHS construction

Theorem

Assuming that all eigenvalues are positive, the RKHS is the Hilbert space:

$$H_K = \left\{ f \in L_2^\nu(\mathcal{X}) : f = \sum_{i=1}^{\infty} a_i \psi_i, \quad \text{with} \quad \sum_{k=1}^{\infty} \frac{a_k^2}{\lambda_k} < \infty \right\}$$

endowed with the inner product:

$$\langle f, g \rangle_K = \sum_{k=1}^{\infty} \frac{a_k b_k}{\lambda_k}, \quad \text{for } f = \sum_k a_k \psi_k, g = \sum_k b_k \psi_k.$$

Remark

If some eigenvalues are equal to zero, then the result and the proof remain valid on the subspace spanned by the eigenfunctions with positive eigenvalues.

Proof (1/6)

Sketch

In order to show that H_K is the RKHS of the kernel K we need to show that:

- ① it is a Hilbert space of functions from \mathcal{X} to \mathbb{R} ,
- ② for any $\mathbf{x} \in \mathcal{X}$, $K_{\mathbf{x}} \in H_K$,
- ③ for any $\mathbf{x} \in \mathcal{X}$ and $f \in H_K$, $f(\mathbf{x}) = \langle f, K_{\mathbf{x}} \rangle_{H_K}$.

Proof (2/6)

H_K is a Hilbert space

Indeed the function:

$$L_K^{\frac{1}{2}} : L_2^\nu(\mathcal{X}) \rightarrow H_K$$
$$\sum_{i=1}^{\infty} a_i \psi_i \mapsto \sum_{i=1}^{\infty} a_i \sqrt{\lambda_i} \psi_i$$

is an isomorphism, therefore H_K is a Hilbert space, like $L_2^\nu(\mathcal{X})$. □

Proof (3/6)

H_K is a space of continuous functions

For any $f = \sum_{i=1}^{\infty} a_i \psi_i \in H_K$, and $\mathbf{x} \in \mathcal{X}$, we have (if $f(\mathbf{x})$ makes sense):

$$\begin{aligned}|f(\mathbf{x})| &= \left| \sum_{i=1}^{\infty} a_i \psi_i(\mathbf{x}) \right| = \left| \sum_{i=1}^{\infty} \frac{a_i}{\sqrt{\lambda_i}} \sqrt{\lambda_i} \psi_i(\mathbf{x}) \right| \\&\leq \left(\sum_{i=1}^{\infty} \frac{a_i^2}{\lambda_i} \right)^{\frac{1}{2}} \cdot \left(\sum_{i=1}^{\infty} \lambda_i \psi_i(\mathbf{x})^2 \right)^{\frac{1}{2}} \\&= \|f\|_{H_K} K(\mathbf{x}, \mathbf{x})^{\frac{1}{2}} \\&= \|f\|_{H_K} \sqrt{C_K}.\end{aligned}$$

Therefore convergence in $\|\cdot\|_{H_K}$ implies uniform convergence for functions.

Proof (4/6)

H_K is a space of continuous functions (cont.)

Let now $f_n = \sum_{i=1}^n a_i \psi_i \in H_K$. The functions ψ_i are continuous functions, therefore f_n is also continuous, for all n . The f_n 's are convergent in H_K , therefore also in the (complete) space of continuous functions endowed with the uniform norm.

Let f_c the continuous limit function. Then $f_c \in L_2^\nu(\mathcal{X})$ and

$$\|f_n - f_c\|_{L_2^\nu(\mathcal{X})} \xrightarrow{n \rightarrow \infty} 0.$$

On the other hand,

$$\|f - f_n\|_{L_2^\nu(\mathcal{X})} \leq \lambda_1 \|f - f_n\|_{H_K} \xrightarrow{n \rightarrow \infty} 0,$$

therefore $f = f_c$. \square

Proof (5/6)

$$K_x \in H_K$$

For any $\mathbf{x} \in \mathcal{X}$ let, for all i , $a_i = \lambda_i \psi_i(\mathbf{x})$. We have:

$$\sum_{i=1}^{\infty} \frac{a_i^2}{\lambda_i} = \sum_{i=1}^{\infty} \lambda_i \psi_i(\mathbf{x})^2 = K(\mathbf{x}, \mathbf{x}) < \infty,$$

therefore $\varphi_x := \sum_{i=1}^{\infty} a_i \psi_i \in H_K$. As seen earlier the convergence in H_K implies pointwise convergence, therefore for any $\mathbf{t} \in \mathcal{X}$:

$$\varphi_x(\mathbf{t}) = \sum_{i=1}^{\infty} a_i \psi_i(\mathbf{t}) = \sum_{i=1}^{\infty} \lambda_i \psi_i(\mathbf{x}) \psi_i(\mathbf{t}) = K(\mathbf{x}, \mathbf{t}),$$

therefore $\varphi_x = K_x \in H_K$. \square

Proof (6/6)

$$f(\mathbf{x}) = \langle f, K_x \rangle_{H_K}$$

Let $f = \sum_{i=1}^{\infty} a_i \psi_i \in H_K$, et $\mathbf{x} \in \mathcal{X}$. We have seen that:

$$K_x = \sum_{i=1}^{\infty} \lambda_i \psi_i(\mathbf{x}) \psi_i,$$

therefore:

$$\langle f, K_x \rangle_{H_K} = \sum_{i=1}^{\infty} \frac{\lambda_i \psi_i(\mathbf{x}) a_i}{\lambda_i} = \sum_{i=1}^{\infty} a_i \psi_i(\mathbf{x}) = f(\mathbf{x}),$$

which concludes the proof. \square

Remarks

- Although H_K was built from the eigenfunctions of L_K , which depend on the choice of the measure $\nu(\mathbf{x})$, we know by uniqueness of the RKHS that H_K is independant of ν and L_K .
- Mercer theorem provides a **concrete way** to build the RKHS, by taking linear combinations of the eigenfunctions of L_K (with adequately chosen weights).
- The eigenfunctions $(\psi_i)_{i \in \mathbb{N}}$ form an **orthogonal basis** of the RKHS:

$$\langle \psi_i, \psi_j \rangle_{H_K} = 0 \quad \text{si } i \neq j, \quad \|\psi_i\|_{H_K} = \frac{1}{\sqrt{\lambda_i}}.$$

The RKHS is a well-defined **ellipsoid** with axes given by the eigenfunctions.

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
 - Green kernels
 - Mercer kernels
 - Shift-invariant kernels
 - Generalization to semigroups
- Kernels for probabilistic models
- Kernels for biological sequences
- Kernels for graphs
- Kernels on graphs

Motivation

- Let us suppose that \mathcal{X} is **not compact**, for example $\mathcal{X} = \mathbb{R}^d$.
- In that case, the eigenvalues of:

$$\int_{\mathcal{X}} K(\mathbf{x}, \mathbf{t}) \psi(\mathbf{t}) d\nu(\mathbf{t}) = \lambda \psi(\mathbf{t})$$

are not necessarily countable, Mercer theorem does not hold.

- Fourier transforms provide a convenient extension for **translation invariant kernels**, i.e., kernels of the form $K(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x} - \mathbf{y})$.
- Harmonic analysis also bring kernels **well beyond vector spaces**, e.g., groups and semigroups

Fourier-Stieltjes transform on the torus

- Let \mathbb{T} the torus $[0, 2\pi]$ with 0 and 2π identified
- $C(\mathbb{T})$ the set of continuous functions on \mathbb{T}
- $M(\mathbb{T})$ the finite complex Borel measures² on \mathbb{T}
- $M(\mathbb{T})$ can be identified as the dual space $(C(\mathbb{T}))^*$: for any continuous/bounded linear functional $\psi : C(\mathbb{T}) \rightarrow \mathbb{C}$ there exists $\mu \in M(\mathbb{T})$ such that $\psi(f) = \frac{1}{2\pi} \int_{\mathbb{T}} f(t) d\mu(t)$ (Riesz theorem).

Definition (Fourier-Stieltjes coefficients)

For any $\mu \in M(\mathbb{T})$, the Fourier-Stieltjes coefficients of μ is the sequence:

$$\forall n \in \mathbb{Z}, \quad \hat{\mu}(n) = \frac{1}{2\pi} \int_{\mathbb{T}} e^{-int} d\mu(t)$$

This extends the standard Fourier transform for integrable functions by taking $d\mu(t) = f(t)dt$.

²a measure defined on all open sets

Translation invariant kernels on \mathbb{Z}

Definition

A kernel $K : \mathbb{Z} \times \mathbb{Z} \mapsto \mathbb{R}$ is called **translation invariant** (t.i.), or **shift-invariant**, if it only depends on the difference between its argument, i.e.:

$$\forall \mathbf{x}, \mathbf{y} \in \mathbb{Z}, \quad K(\mathbf{x}, \mathbf{y}) = a_{\mathbf{x}-\mathbf{y}}$$

for some sequence $\{a_n\}_{n \in \mathbb{Z}}$. Such a sequence is called positive definite if the corresponding kernel K is p.d.

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Theorem (Herglotz)

A sequence $\{a_n\}_{n \in \mathbb{Z}}$ is p.d. if and only if it is the Fourier-Stieltjes transform of a positive measure $\mu \in M(\mathbb{T})$

Examples

- Diagonal kernel:

$$\mu = dt, \quad a_n = \hat{\mu}(n) = \frac{1}{2\pi} \int_{\mathbb{T}} e^{int} dt = \begin{cases} 1 & \text{if } n = 0, \\ 0 & \text{otherwise.} \end{cases}$$

The resulting kernel is $K(\mathbf{x}, \mathbf{t}) = \mathbf{1}(\mathbf{x} = \mathbf{t})$.

- Constant kernel: for $C \geq 0$,

$$\mu = 2\pi C \delta_0, \quad a_n = \hat{\mu}(n) = C \int_{\mathbb{T}} e^{int} \delta_0(t) = C,$$

resulting in $K(\mathbf{x}, \mathbf{t}) = C$

Proof of Herglotz's theorem: \Leftarrow

If $a_n = \hat{\mu}(n)$ for $\mu \in M(\mathbb{T})$ positive, then for any $n \in \mathbb{N}$, $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{Z}$ and $z_1, \dots, z_n \in \mathbb{R}$ (or \mathbb{C}) :

$$\begin{aligned} \sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j a_{\mathbf{x}_i - \mathbf{x}_j} &= \frac{1}{2\pi} \sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j \int_{\mathbb{T}} e^{-i(\mathbf{x}_i - \mathbf{x}_j)t} d\mu(t) \\ &= \frac{1}{2\pi} \sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j \int_{\mathbb{T}} e^{-i\mathbf{x}_i t} e^{i\mathbf{x}_j t} d\mu(t) \\ &= \frac{1}{2\pi} \int_{\mathbb{T}} \left| \sum_{j=1}^n z_j e^{-i\mathbf{x}_j t} \right|^2 d\mu(t) \\ &\geq 0. \end{aligned}$$



Proof of Herglotz's theorem: $\Rightarrow (1/4)$

- Let $\{a_n\}_{n \in \mathbb{Z}}$ a p.d. sequence
- For a given $t \in \mathbb{R}$ and $N \in \mathbb{N}$ let $\{z_n\}_{n \in \mathbb{Z}}$ be

$$z_n = \begin{cases} e^{int} & \text{if } |n| \leq N, \\ 0 & \text{otherwise.} \end{cases}$$

- Since $\{a_n\}_{n \in \mathbb{Z}}$ is p.d. we get:

$$\begin{aligned} 0 \leq \sum_{k=-N}^N \sum_{l=-N}^N a_{k-l} z_k \bar{z}_l &= \sum_{k=-N}^N \sum_{l=-N}^N a_{k-l} e^{i(k-l)t} \\ &= \sum_{k=-2N}^{2N} (2N+1 - |k|) a_k e^{ikt} \\ &= (2N+1) \underbrace{\sum_{k \in \mathbb{Z}} \max \left(0, 1 - \frac{|k|}{2N+1} \right) a_k e^{ikt}}_{\sigma_{2N}(t)} \end{aligned}$$

Proof of Herglotz's theorem: $\Rightarrow (2/4)$

- $d\mu_N = \sigma_N(t)dt$ is a positive measure (for N even) and satisfies

$$\hat{\mu}_N(n) = \sum_{j=-N}^N a_j \left(1 - \frac{|j|}{N+1}\right) \int_{\mathbb{T}} e^{i(n-j)t} dt = a_n \max \left(0, 1 - \frac{|n|}{N+1}\right)$$

- Moreover

$$\begin{aligned}\|\mu_N\|_{M(\mathbb{T})} &= \sup_{\|f\|_{\infty} \leq 1} \int_{\mathbb{T}} f(t) \sigma_N(t) dt \\ &= \int_{\mathbb{T}} \sigma_N(t) dt \quad (\text{take } f = 1 \text{ because } \sigma_N(t) \geq 0) \\ &= \sum_{n=-N}^N \int_{\mathbb{T}} a_n \left(1 - \frac{|n|}{N+1}\right) e^{int} dt \\ &= a_0\end{aligned}$$

Proof of Herglotz's theorem: $\Rightarrow (3/4)$

- For any trigonometric polynomial of the form

$P(t) = \sum_{k=-K}^K b_k e^{ikt}$, with Fourier coefficient $\hat{P}(n) = b_n$, we have

$$\lim_{N \rightarrow +\infty} \int_{\mathbb{T}} P(t) d\mu_N(t)$$

$$= \lim_{N \rightarrow +\infty} \sum_{k=-K}^K \sum_{n=-N}^N \int_{\mathbb{T}} a_n b_k \left(1 - \frac{|n|}{N+1}\right) e^{i(n-k)t} dt$$

$$= \sum_{k=-K}^K a_k b_k \lim_{N \rightarrow +\infty} \left(1 - \frac{|n|}{N+1}\right)$$

$$= \sum_{k=-K}^K a_k b_k$$

$$= \sum_{k \in \mathbb{Z}} a_k \hat{P}(k)$$

Proof of Herglotz's theorem: $\Rightarrow (4/4)$

- This shows that $\Psi(P) = \sum_{k \in \mathbb{Z}} a_k \hat{P}(k)$ is a linear functional over trigonometric polynomials, with norm $\leq a_0$
- It can be extended to all continuous functions because trigonometric polynomials are dense in $C(\mathbb{T})$
- By Riesz representation theorem, there exists a measure $\mu \in M(\mathbb{T})$ such that $\|\mu\|_{M(\mathbb{T})} \leq a_0$

$$\forall f \in C(\mathbb{T}), \quad \Psi(f) = \int_{\mathbb{T}} f(t) d\mu(t)$$

- Taking $f(t) = e^{int}$ gives

$$\hat{\mu}(n) = \int_{\mathbb{T}} e^{int} d\mu(t) = \Psi(e^{int}) = a_n$$

- Furthermore μ is a positive measure because if $f \geq 0$

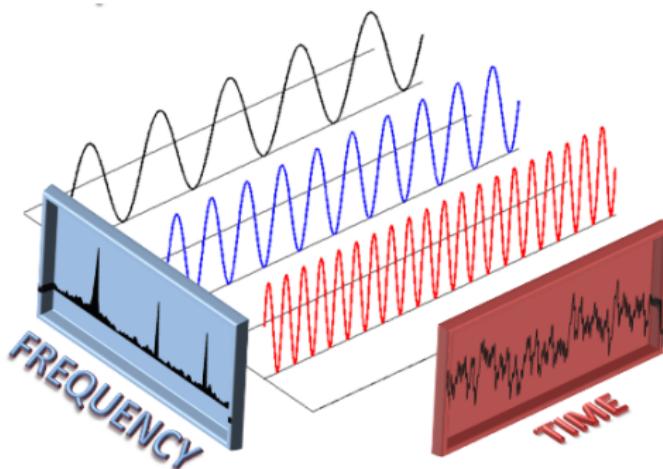
$$\int_{\mathbb{T}} f(t) d\mu(t) = \Psi(f) = \lim_{n \rightarrow +\infty} \Psi(P_n) = \lim_{n,k \rightarrow +\infty} \Psi_k(P_n) \geq 0 \quad \square$$

Fourier transform on \mathbb{R}^d

Definition

For any $f \in L^1(\mathbb{R}^d)$, the Fourier transform of f is the function:

$$\forall \omega \in \mathbb{R}^d, \quad \hat{f}(\omega) = \int_{\mathbb{R}^d} e^{-i\mathbf{x}^\top \omega} f(\mathbf{x}) d\mathbf{x}.$$



Fourier transform on \mathbb{R}^d

Properties

- \hat{f} is complex-valued, continuous, tends to 0 at infinity and $\|\hat{f}\|_{L^\infty} \leq \|f\|_{L^1}$.
- If $\hat{f} \in L^1(\mathbb{R}^d)$, then the **inverse Fourier formula** holds:

$$\forall \mathbf{x} \in \mathbb{R}^d, \quad f(\mathbf{x}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i\mathbf{x}^\top \omega} \hat{f}(\omega) d\omega.$$

- If $f \in L^1(\mathbb{R}^d)$ is square integrable, then **Parseval's formula** holds:

$$\int_{\mathbb{R}^d} |f(\mathbf{x})|^2 d\mathbf{x} = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} |\hat{f}(\omega)|^2 d\omega.$$

Fourier-Stieltjes transform on \mathbb{R}^d

- $C_0(\mathbb{R}^d)$ the set of continuous functions on \mathbb{R}^d that vanish at infinity
- $M(\mathbb{R}^d)$ the finite complex Borel measures on \mathbb{R}^d
- $M(\mathbb{R}^d)$ can be identified as the dual space $(C_0(\mathbb{R}^d))^*$: for any continuous/bounded linear functional $\psi : C_0(\mathbb{R}^d) \rightarrow \mathbb{C}$ there exists $\mu \in M(\mathbb{R}^d)$ such that $\psi(f) = \int_{\mathbb{R}^d} f(t) d\mu(t)$ (Riesz theorem).

Definition (Fourier-Stieltjes transform)

For any $\mu \in M(\mathbb{R}^d)$, the Fourier-Stieltjes transform of μ is the function:

$$\forall \omega \in \mathbb{R}^d, \quad \hat{\mu}(\omega) = \int_{\mathbb{R}^d} e^{-i\omega^\top x} d\mu(x)$$

Fourier-Stieltjes transform on \mathbb{R}^d

- This extends the standard Fourier transform for integrable functions by taking $d\mu(\mathbf{x}) = f(\mathbf{x})d\mathbf{x}$.
- For $\mu \in M(\mathbb{R}^d)$, $\hat{\mu}$ is still uniformly continuous, but $\hat{\mu}(\omega)$ does not necessarily go to 0 at infinity (e.g., take the Dirac $\mu = \delta_0$, then $\hat{\mu}(\omega) = 1$ for all ω)
- Parseval's formula becomes: if $\mu \in M(\mathbb{R}^d)$, and both g, \hat{g} are in $L^1(\mathbb{R}^d)$, then

$$\int_{\mathbb{R}^d} g(\mathbf{x})d\mu(\mathbf{x}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \hat{g}(\omega)\hat{\mu}(-\omega)d\omega$$

Translation invariant kernels on \mathbb{R}^d

Definition

A kernel $K : \mathbb{R}^d \times \mathbb{R}^d \mapsto \mathbb{R}$ is called **translation invariant** (t.i.), or **shift-invariant**, if it only depends on the difference between its argument, i.e.:

$$\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d, \quad K(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x} - \mathbf{y})$$

for some function $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$. Such a function φ is called positive definite if the corresponding kernel K is p.d.

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Theorem (Bochner)

A **continuous** function $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ is p.d. if and only if it is the Fourier-Stieltjes transform of a symmetric and positive finite Borel measure $\mu \in M(\mathbb{T})$

Proof of Bochner's theorem: \Leftarrow

If $\varphi = \hat{\mu}$ for some $\mu \in M(\mathbb{T})$ positive, then for any $n \in \mathbb{N}$, $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$ and $z_1, \dots, z_n \in \mathbb{R}$ (or \mathbb{C}) :

$$\begin{aligned}\sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j \varphi(\mathbf{x}_i - \mathbf{x}_j) &= \sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j \int_{\mathbb{R}^d} e^{-i(\mathbf{x}_i - \mathbf{x}_j)^T \mathbf{t}} d\mu(\mathbf{t}) \\ &= \sum_{i=1}^n \sum_{j=1}^n z_i \bar{z}_j \int_{\mathbb{R}^d} e^{-i\mathbf{x}_i^T \mathbf{t}} e^{i\mathbf{x}_j^T \mathbf{t}} d\mu(\mathbf{t}) \\ &= \int_{\mathbb{R}^d} \left| \sum_{j=1}^n z_j e^{-i\mathbf{x}_j^T \mathbf{t}} \right|^2 d\mu(\mathbf{t}) \\ &\geq 0.\end{aligned}$$

If μ is symmetric then, in addition, φ is real-valued.



Proof of Bochner's theorem: $\Rightarrow (1/5)$

Lemma

Let $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ continuous. If there exists $C \geq 0$ such that

$$\left| \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi \right| \leq C \sup_{x \in \mathbb{R}} |g(x)|$$

for every continuous function $g \in L^1(\mathbb{R})$ such that \hat{g} is continuous and has compact support, then φ is the Fourier-Stieljes transform of a measure $\mu \in M(\mathbb{R})$.

Proof: Let $\mathcal{G} \subset C_0(\mathbb{R})$ be the set of functions $g \in L^1(\mathbb{R})$ such that \hat{g} is continuous and has compact support. $\Psi : g \mapsto \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi$ is linear and continuous on \mathcal{G} , and can be extended to $C_0(\mathbb{R})$ by density of \mathcal{G} . By Riesz theorem, there exists $\mu \in M(\mathbb{R})$ such that

$\Psi(g) = \int_{\mathbb{R}} g(x) d\mu(x) = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \hat{\mu}(-\xi) d\xi$, using Parseval's formula for the second equality. This must hold for all g , so $\varphi = \hat{\mu}$. \square

Note: the converse is also true.

Proof of Bochner's theorem: \Rightarrow (2/5)

- We consider $d = 1$. Generalization to $d > 1$ is trivial.
- Let $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ continuous and p.d.
- For any $\lambda > 0$, the sequence $\{\varphi(n\lambda)\}_{n \in \mathbb{Z}}$ is p.d., so by Herglotz's theorem there exists a positive measure $\mu_\lambda \in M(\mathbb{T})$ such that

$$\varphi(\lambda n) = \hat{\mu}_\lambda(n),$$

and $\|\mu_\lambda\|_{M(\mathbb{T})} = \hat{\mu}_\lambda(0) = \varphi(0)$.

- Let $g \in L^1(\mathbb{R})$ continuous such that \hat{g} is continuous and has compact support.
- For any $\epsilon > 0$ there exists $\lambda > 0$ such that

$$\left| \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi \right| < \left| \frac{\lambda}{2\pi} \sum_{n \in \mathbb{Z}} \hat{g}(\lambda n) \varphi(-\lambda n) \right| + \epsilon,$$

by approximating the integral by its Riemann sums (where the width of each rectangle is λ).

Proof of Bochner's theorem: $\Rightarrow (3/5)$

- For $t \in \mathbb{T}$ let:

$$G_\lambda(t) = \sum_{m \in \mathbb{Z}} g\left(\frac{t + 2\pi m}{\lambda}\right)$$

- Given the regularity and decay of g , we can find a sufficiently small λ to ensure

$$\sup_{t \in \mathbb{T}} |G_\lambda(t)| \leq \sup_{x \in \mathbb{R}} |g(x)| + \epsilon$$

Proof of Bochner's theorem: $\Rightarrow (3/5)$

- In addition, for any $n \in \mathbb{Z}$:

$$\begin{aligned}\hat{G}_\lambda(n) &= \frac{1}{2\pi} \int_{\mathbb{T}} e^{-int} G_\lambda(t) dt \\ &= \frac{1}{2\pi} \sum_{m \in \mathbb{Z}} \int_0^{2\pi} e^{-int} g\left(\frac{t + 2\pi m}{\lambda}\right) dt \\ &= \frac{\lambda}{2\pi} \sum_{m \in \mathbb{Z}} \int_{\frac{2\pi m}{\lambda}}^{\frac{2\pi(m+1)}{\lambda}} e^{-in(\lambda u + 2\pi m)} g(u) du \\ &= \frac{\lambda}{2\pi} \sum_{m \in \mathbb{Z}} \int_{\frac{2\pi m}{\lambda}}^{\frac{2\pi(m+1)}{\lambda}} e^{-in\lambda u} g(u) du \\ &= \frac{\lambda}{2\pi} \int_{\mathbb{R}} e^{-in\lambda u} g(u) du \\ &= \frac{\lambda}{2\pi} \hat{g}(\lambda n)\end{aligned}$$

Proof of Bochner's theorem: \Rightarrow (4/5)

- This gives:

$$\begin{aligned} \left| \frac{\lambda}{2\pi} \sum_{n \in \mathbb{Z}} \hat{g}(\lambda n) \varphi(-\lambda n) \right| &= \left| \sum_{n \in \mathbb{Z}} \hat{G}_\lambda(n) \overline{\hat{\mu}_\lambda(-n)} \right| \\ &= \left| \frac{1}{2\pi} \int_{\mathbb{T}} G_\lambda(t) \overline{d\mu_\lambda(t)} \right| \quad (\text{Parseval}) \\ &\leq \| \mu_\lambda \|_{M(\mathbb{T})} \sup_{t \in \mathbb{T}} | G_\lambda(t) | \\ &\leq C \sup_{t \in \mathbb{T}} | G_\lambda(t) | \\ &\leq C \sup_{x \in \mathbb{R}} | g(x) | + C\epsilon \end{aligned}$$

with $C = \varphi(0)$.

Proof of Bochner's theorem: $\Rightarrow (5/5)$

- Putting it all together gives:

$$\left| \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi \right| < C \sup_{x \in \mathbb{R}} |g(x)| + (C+1)\epsilon$$

- This is true for all $\epsilon > 0$ which implies

$$\left| \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi \right| \leq C \sup_{x \in \mathbb{R}} |g(x)|$$

- We conclude from the lemma that $\varphi = \hat{\mu}$ for some $\mu \in M(\mathbb{R})$, which satisfies

$$\frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}(\xi) \varphi(-\xi) d\xi = \int_{\mathbb{R}} g(x) d\mu(x)$$

- When $g \geq 0$, this is approximated by $\frac{1}{2\pi} \int_{\mathbb{T}} G_{\lambda}(t) \overline{d\mu_{\lambda}(t)}$ for small λ , which is ≥ 0 because μ_{λ} is a positive measure and $G_{\lambda} \geq 0$ like g . Consequently, μ is a positive measure. □

RKHS of translation invariant kernels

Theorem

Let $K(\mathbf{x}, \mathbf{t}) = \varphi(\mathbf{x} - \mathbf{t})$ be a translation invariant p.d. kernel, such that φ is integrable on \mathbb{R}^d as well as its Fourier transform $\hat{\varphi}$. The subset \mathcal{H} of $L_2(\mathbb{R}^d)$ that consists of integrable and continuous functions f such that:

$$\|f\|_K^2 := \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \frac{|\hat{f}(\omega)|^2}{\hat{\varphi}(\omega)} d\omega < +\infty,$$

endowed with the inner product:

$$\langle f, g \rangle := \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \frac{\hat{f}(\omega) \overline{\hat{g}(\omega)}}{\hat{\varphi}(\omega)} d\omega$$

is a RKHS with K as r.k.

Proof

- \mathcal{H} is a Hilbert space: exercise.
- For $\mathbf{x} \in \mathbb{R}^d$, $K_{\mathbf{x}}(\mathbf{y}) = K(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x} - \mathbf{y})$ therefore:

$$\hat{K}_{\mathbf{x}}(\omega) = \int e^{-i\omega^T \mathbf{u}} \varphi(\mathbf{u} - \mathbf{x}) d\mathbf{u} = e^{-i\omega^T \mathbf{x}} \hat{\varphi}(\omega).$$

- This leads to $K_{\mathbf{x}} \in \mathcal{H}$, because:

$$\int_{\mathbb{R}^d} \frac{|\hat{K}_{\mathbf{x}}(\omega)|^2}{\hat{\varphi}(\omega)} \leq \int_{\mathbb{R}^d} |\hat{\varphi}(\omega)| < \infty,$$

- Moreover, if $f \in \mathcal{H}$ and $\mathbf{x} \in \mathbb{R}^d$, we have:

$$\begin{aligned} \langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}} &= \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \frac{\hat{K}_{\mathbf{x}}(\omega) \overline{\hat{f}(\omega)}}{\hat{\varphi}(\omega)} d\omega = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \overline{\hat{f}(\omega)} e^{-i\omega \cdot \mathbf{x}} d\omega \\ &= f(\mathbf{x}) \end{aligned}$$

□

Example

Gaussian kernel

$$K(x, y) = e^{-\frac{(x-y)^2}{2\sigma^2}}$$

corresponds to:

$$\hat{\varphi}(\omega) = e^{-\frac{\sigma^2 \omega^2}{2}}$$

and

$$\mathcal{H} = \left\{ f : \int \left| \hat{f}(\omega) \right|^2 e^{\frac{\sigma^2 \omega^2}{2}} d\omega < \infty \right\}.$$

In particular, all functions in \mathcal{H} are **infinitely differentiable** with all derivatives in L^2 .

Example

Laplace kernel

$$K(x, y) = \frac{1}{2} e^{-\gamma|x-y|}$$

corresponds to:

$$\hat{\varphi}(\omega) = \frac{\gamma}{\gamma^2 + \omega^2}$$

and

$$\mathcal{H} = \left\{ f : \int \left| \hat{f}(\omega) \right|^2 \frac{(\gamma^2 + \omega^2)}{\gamma} d\omega < \infty \right\},$$

the set of functions L^2 differentiable with derivatives in L^2 (Sobolev norm).

Example

Low-frequency filter

$$K(x, y) = \frac{\sin(\Omega(x - y))}{\pi(x - y)}$$

corresponds to:

$$\hat{\varphi}(\omega) = U(\omega + \Omega) - U(\omega - \Omega)$$

and

$$\mathcal{H} = \left\{ f : \int_{|\omega| > \Omega} |\hat{f}(\omega)|^2 d\omega = 0 \right\},$$

the set of functions whose spectrum is included in $[-\Omega, \Omega]$.

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
 - Green kernels
 - Mercer kernels
 - Shift-invariant kernels
 - Generalization to semigroups
- Kernels for probabilistic models
- Kernels for biological sequences
- Kernels for graphs
- Kernels on graphs

Generalization to semigroups (cf Berg et al., 1983)

Definition

- A **semigroup** (S, \circ) is a nonempty set S equipped with an associative composition \circ and a neutral element e .
- A **semigroup with involution** $(S, \circ, *)$ is a semigroup (S, \circ) together with a mapping $* : S \rightarrow S$ called **involution** satisfying:
 - ① $(s \circ t)^* = t^* \circ s^*$, for $s, t \in S$.
 - ② $(s^*)^* = s$ for $s \in S$.

Examples

- Any **group** (G, \circ) is a semigroup with involution when we define $s^* = s^{-1}$.
- Any **abelian semigroup** $(S, +)$ is a semigroup with involution when we define $s^* = s$, the **identical involution**.

Positive definite functions on semigroups

Definition

Let $(S, \circ, *)$ be a semigroup with involution. A function $\varphi : S \rightarrow \mathbb{R}$ is called **positive definite** if the function:

$$\forall s, t \in S, \quad K(s, t) = \varphi(s^* \circ t)$$

is a p.d. kernel on S .

Example: translation invariant kernels

$(\mathbb{R}^d, +, -)$ is an abelian group with involution. A function $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ is p.d. if the function

$$K(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x} - \mathbf{y})$$

is p.d. on \mathbb{R}^d (translation invariant kernels).

Semicharacters

Definition

A function $\rho : S \rightarrow \mathbb{C}$ on an **abelian** semigroup with involution $(S, +, *)$ is called a **semicharacter** if

- ① $\rho(0) = 1$,
- ② $\rho(s + t) = \rho(s)\rho(t)$ for $s, t \in S$,
- ③ $\rho(s^*) = \overline{\rho(s)}$ for $s \in S$.

The set of semicharacters on S is denoted by S^* .

Remarks

- If $*$ is the **identity**, a semicharacter is automatically **real-valued**.
- If $(S, +)$ is an **abelian group** and $s^* = -s$, a semicharacter has its values in the circle group $\{z \in \mathbb{C} \mid |z| = 1\}$ and is a **group character**.

Semicharacters are p.d.

Lemma

Every semicharacter is p.d., in the sense that:

- $K(s, t) = \overline{K(t, s)}$,
- $\sum_{i,j=1}^n a_i \overline{a_j} K(x_i, x_j) \geq 0$.

Proof

Direct from definition, e.g.,

$$\sum_{i,j=1}^n a_i \overline{a_j} \rho(x_i + x_j^*) = \sum_{i,j=1}^n a_i \overline{a_j} \rho(x_i) \overline{\rho(x_j)} \geq 0.$$

Examples

- $\varphi(t) = e^{\beta t}$ on $(\mathbb{R}, +, Id)$.
- $\varphi(t) = e^{i\omega t}$ on $(\mathbb{R}, +, -)$.

Integral representation of p.d. functions

Definition

- An function $\alpha : S \rightarrow \mathbb{R}$ on a semigroup with involution is called an **absolute value** if (i) $\alpha(e) = 1$, (ii) $\alpha(s \circ t) \leq \alpha(s)\alpha(t)$, and (iii) $\alpha(s^*) = \alpha(s)$.
- A function $f : S \rightarrow \mathbb{R}$ is called **exponentially bounded** if there exists an absolute value α and a constant $C > 0$ s.t. $|f(s)| \leq C\alpha(s)$ for $s \in S$.

Theorem

Let $(S, +, *)$ an abelian semigroup with involution. A function $\varphi : S \rightarrow \mathbb{R}$ is p.d. and exponentially bounded (resp. bounded) if and only if it has a representation of the form:

$$\varphi(s) = \int_{S^*} \rho(s)d\mu(\rho).$$

where μ is a Radon measure with compact support on S^* (resp. on \hat{S} , the set of bounded semicharacters).

Proof

Sketch (details in Berg et al., 1983, Theorem 4.2.5)

- For an absolute value α , the set P_1^α of α -bounded p.d. functions that satisfy $\varphi(0) = 1$ is a **compact convex set** whose **extreme points are precisely the α -bounded semicharacters**.
- If φ is p.d. and exponentially bounded then there exists an absolute value α such that $\varphi(0)^{-1}\varphi \in P_1^\alpha$.
- By the **Krein-Milman theorem** there exists a Radon probability measure on P_1^α having $\varphi(0)^{-1}\varphi$ as **barycentre**.

Remarks

- The result is **not true** without the assumption of **exponentially bounded** semicharacters.
- In the case of abelian groups with $s^* = -s$ this reduces to **Bochner's theorem** for discrete abelian groups, cf. Rudin (1962).

Example 1: $(R_+, +, Id)$

Semicharacters

- $S = (\mathbb{R}_+, +, Id)$ is an **abelian semigroup**.
- P.d. functions are **nonnegative**, because $\varphi(x) = \varphi(\sqrt{x})^2$.
- The set of **bounded semicharacters** is exactly the set of functions:

$$s \in \mathbb{R}_+ \mapsto \rho_a(s) = e^{-as},$$

for $a \in [0, +\infty]$ (left as exercise).

- **Non-bounded** semicharacters are more difficult to characterize; in fact there exist nonmeasurable solutions of the equation $h(x+y) = h(x)h(y)$.

Example 1: $(R_+, +, Id)$ (cont.)

P.d. functions

- By the integral representation theorem for bounded semi-characters we obtain that a function $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}$ is p.d. and bounded if and only if it has the form:

$$\varphi(s) = \int_0^\infty e^{-as} d\mu(a) + b\rho_\infty(s)$$

where $\mu \in \mathcal{M}_+^b(\mathbb{R}_+)$ and $b \geq 0$.

- The first term is the Laplace transform of μ . φ is p.d., bounded and continuous iff it is the Laplace transform of a measure in $\mathcal{M}_+^b(\mathbb{R})$.

Example 2: Semigroup kernels for finite measures (1/6)

Setting

- We assume that data to be processed are “**bags-of-points**”, i.e., sets of points (with repeats) of a space \mathcal{U} .
- **Example** : a finite-length string as a set of k -mers.
- How to define a p.d. kernel between any two bags that only depends on the **union of the bags**?
- See details and proofs in Cuturi et al. (2005).

Example 2: Semigroup kernels for finite measures (2/6)

Semigroup of bounded measures

- We can represent any bag-of-point \mathbf{x} as a finite measure on \mathcal{U} :

$$\mathbf{x} = \sum_i a_i \delta_{x_i},$$

where a_i is the number of occurrences on x_i in the bag.

- The measure that represents the union of two bags is the **sum of the measures** that represent each individual bag.
- This suggests to look at the semigroup $(\mathcal{M}_+^b(\mathcal{U}), +, \text{Id})$ of bounded Radon measures on \mathcal{U} and to search for p.d. functions φ on this semigroup.

Example 2: Semigroup kernels for finite measures (3/6)

Semicharacters

- For any Borel measurable function $f : \mathcal{U} \rightarrow \mathbb{R}$ the function $\rho_f : \mathcal{M}_+^b(\mathcal{U}) \rightarrow \mathbb{R}$ defined by:

$$\rho_f(\mu) = e^{\mu[f]}$$

is a semicharacter on $(\mathcal{M}_+^b(\mathcal{U}), +)$.

- Conversely, ρ is **continuous** semicharacter (for the topology of weak convergence) if and only if there exists a continuous function $f : \mathcal{U} \rightarrow \mathbb{R}$ such that $\rho = \rho_f$.
- No such characterization for non-continuous characters, even bounded.

Example 2: Semigroup kernels for finite measures (4/6)

Corollary

Let \mathcal{U} be a Hausdorff space. For any Radon measure $\mu \in \mathcal{M}_+^c(C(\mathcal{U}))$ with compact support on the Hausdorff space of continuous real-valued functions on \mathcal{U} endowed with the topology of pointwise convergence, the following function K is a continuous p.d. kernel on $\mathcal{M}_+^b(\mathcal{U})$ (endowed with the topology of weak convergence):

$$K(\mu, \nu) = \int_{C(X)} e^{\mu[f] + \nu[f]} d\mu(f).$$

Remarks

The converse is not true: there exist continuous p.d. kernels that do not have this integral representation (it might include non-continuous semicharacters)

Example 2: Semigroup kernels for finite measures (5/6)

Example : entropy kernel

- Let \mathcal{X} be the set of probability densities (w.r.t. some reference measure) on \mathcal{U} with finite entropy:

$$h(\mathbf{x}) = - \int_{\mathcal{U}} \mathbf{x} \ln \mathbf{x}.$$

- Then the following **entropy kernel** is a p.d. kernel on \mathcal{X} for all $\beta > 0$:

$$K(\mathbf{x}, \mathbf{x}') = e^{-\beta h\left(\frac{\mathbf{x}+\mathbf{x}'}{2}\right)}.$$

- Remark: only valid for **densities** (e.g., for a kernel density estimator from a bag-of-parts)

Example 2: Semigroup kernels for finite measures (6/6)

Examples : inverse generalized variance kernel

- Let $\mathcal{U} = \mathbb{R}^d$ and $\mathcal{M}_+^V(\mathcal{U})$ be the set of finite measure μ with second order moment and non-singular variance

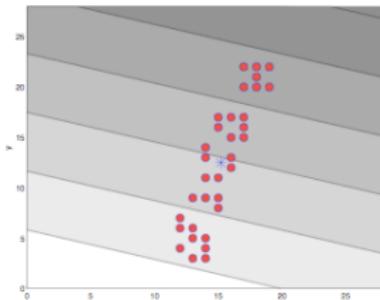
$$\Sigma(\mu) = \mu [xx^\top] - \mu [x]\mu [x]^\top.$$

- Then the following function is a p.d. kernel on $\mathcal{M}_+^V(\mathcal{U})$, called the **inverse generalized variance kernel**:

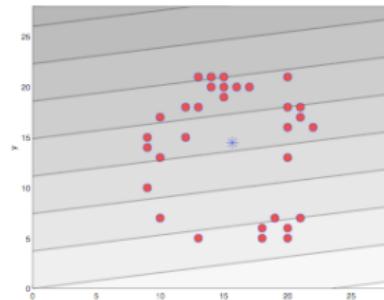
$$K(\mu, \mu') = \frac{1}{\det \Sigma\left(\frac{\mu+\mu'}{2}\right)}.$$

- Generalization possible with **regularization** and **kernel trick**.

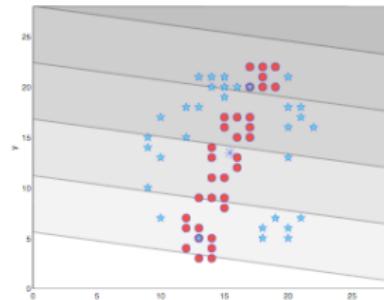
Application of semigroup kernel



$$\Sigma_{1,1} = 0.0552$$
$$\Sigma_{2,2} = 0.0013$$



$$\Sigma'_{1,1} = 0.0441$$
$$\Sigma'_{2,2} = 0.0237$$



$$\Sigma''_{1,1} = 0.0497$$
$$\Sigma''_{2,2} = 0.0139$$

Weighted linear PCA of two different measures, with the first PC shown. Variances captured by the first and second PC are shown. The generalized variance kernel is the inverse of the product of the two values.

Kernelization of the IGV kernel

Motivations

- Gaussian distributions may be poor models.
- The method fails in large dimension

Solution

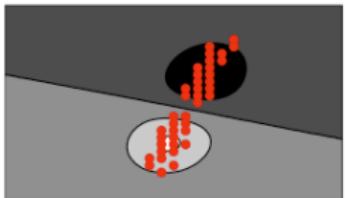
- ① Regularization:

$$K_\lambda(\mu, \mu') = \frac{1}{\det\left(\Sigma\left(\frac{\mu+\mu'}{2}\right) + \lambda I_d\right)}.$$

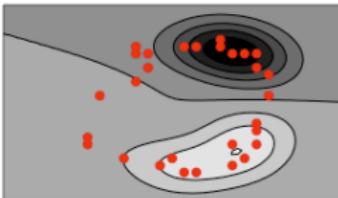
- ② Kernel trick: the non-zero eigenvalues of UU^\top and $U^\top U$ are the same \implies replace the covariance matrix by the centered Gram matrix (technical details in Cuturi et al., 2005).

Illustration of kernel IGV kernel

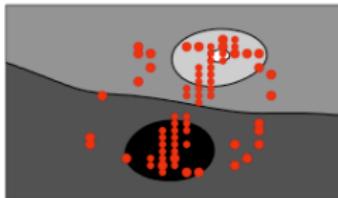
0.276



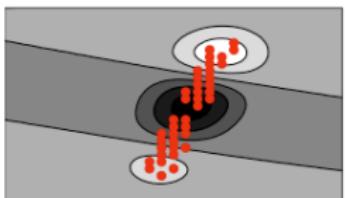
0.168



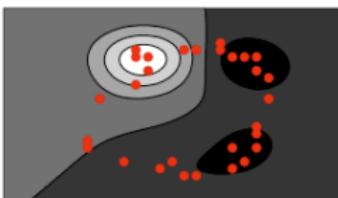
0.184



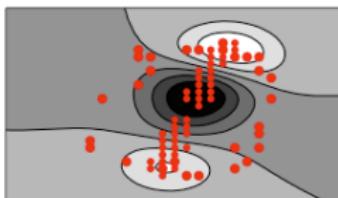
0.169



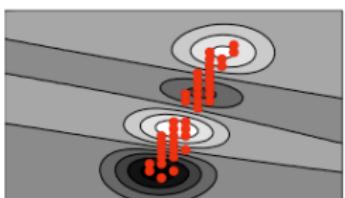
0.142



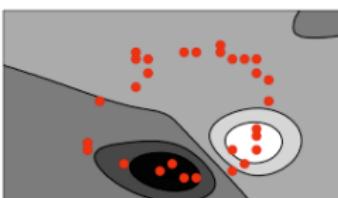
0.122



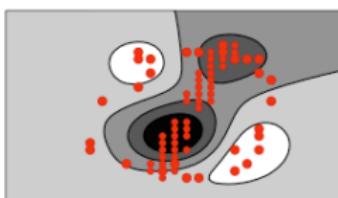
0.124



0.119



0.0934



Semigroup kernel remarks

Motivations

- A **very general formalism** to exploit an **algebraic structure** of the data.
- Kernel IVG kernel has given good results for character recognition from a subsampled image.
- The main motivation is more generally to develop kernels for **complex objects** from which **simple “patches”** can be extracted.
- The extension to **nonabelian groups** (e.g., permutation in the symmetric group) might find natural applications.

Kernel examples: Summary

- Many notions of **smoothness** can be translated as **RKHS norms** for particular kernels (eigenvalues convolution operator, Sobolev norms and Green operators, Fourier transforms...).
- There is **no “uniformly best kernel”**, but rather a large **toolbox** of methods and tricks to **encode prior knowledge** and exploit the **nature or structure** of the data.
- In the following sections we focus on **particular data and applications** to illustrate the process of **kernel design**.

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
 - Green, Mercer, Herglotz, Bochner and friends
 - **Kernels for probabilistic models**
 - Kernels for biological sequences
 - Kernels for graphs
 - Kernels on graphs
- 6 Open Problems and Research Topics

Motivation

Kernel methods are sometimes criticized for their **lack of flexibility**: a large effort is spent in designing by hand the kernel.

Question

How do we design a kernel **adapted** to the data?

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Kernel methods are sometimes criticized for their **lack of flexibility**: a large effort is spent in designing by hand the kernel.

Question

How do we design a kernel **adapted** to the data?

Answer

A successful strategy is given by kernels for generative models, which are/have been the state of the art in many fields, including representation of image and sequence data representation.

Parametric model

A **model** is a family of distributions

$$\{P_\theta, \theta \in \Theta \subset \mathbb{R}^m\} \subseteq \mathcal{M}_1^+(\mathcal{X}).$$

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
 - Fisher kernel
 - Mutual information kernels
 - Marginalized kernels
- Kernels for biological sequences
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- Kernels on graphs

Fisher kernel

Definition

- Fix a parameter $\theta_0 \in \Theta$ (obtained for instance by maximum likelihood over a training set).
- For each sequence \mathbf{x} , compute the Fisher score vector:

$$\Phi_{\theta_0}(\mathbf{x}) = \nabla_{\theta} \log P_{\theta}(\mathbf{x})|_{\theta=\theta_0},$$

which can be interpreted as the local contribution of each parameter.

- Form the kernel (Jaakkola et al., 2000):

$$K(\mathbf{x}, \mathbf{x}') = \Phi_{\theta_0}(\mathbf{x})^{\top} \mathbf{I}(\theta_0)^{-1} \Phi_{\theta_0}(\mathbf{x}'),$$

where $\mathbf{I}(\theta_0) = \mathbb{E} [\Phi_{\theta_0}(\mathbf{x}) \Phi_{\theta_0}(\mathbf{x})^{\top}]$ is the Fisher information matrix.

Note: when θ_0 is the ML estimator, $\mathbb{E}[\Phi_{\theta_0}(\mathbf{x})] = 0$ and $\mathbf{I}(\theta_0)$ is a covariance matrix.

Fisher kernel properties (1/2)

- The Fisher score describes how **each parameter contributes** to the process of generating a particular example
- A kernel classifier employing the Fisher kernel derived from a model that contains the label as a latent variable is, asymptotically, **at least as good as the MAP labelling** based on the model (Jaakkola and Haussler, 1999).
- A variant of the Fisher kernel (called the Tangent of Posterior kernel) can also improve over the direct posterior classification by helping to **correct the effect of estimation errors** in the parameter (Tsuda et al., 2002).

Fisher kernel properties (2/2)

Lemma

The Fisher kernel is **invariant** under change of parametrization.

- Consider indeed a different parametrization given by some diffeomorphism $\lambda = f(\theta)$. The **Jacobian** matrix relating the parametrization is denoted by $[\mathbf{J}]_{ij} = \frac{\partial \theta_j}{\partial \lambda_i}$.
- The gradient of log-likelihood w.r.t. to the new parameters is

$$\Phi_{\lambda_0}(\mathbf{x}) = \nabla_{\lambda} \log P_{\lambda_0}(\mathbf{x}) = \mathbf{J} \nabla_{\theta} \log P_{\theta_0}(\mathbf{x}) = \mathbf{J} \Phi_{\theta_0}(\mathbf{x}).$$

- The Fisher information matrix is

$$\mathbf{I}(\lambda_0) = \mathbb{E} \left[\Phi_{\lambda_0}(\mathbf{x}) \Phi_{\lambda_0}(\mathbf{x})^\top \right] = \mathbf{J} \mathbf{I}(\theta_0) \mathbf{J}^\top.$$

- We conclude by noticing that $\mathbf{I}(\lambda_0)^{-1} = \mathbf{J}^{-1} \mathbf{I}(\theta_0)^{-1} \mathbf{J}^{\top -1}$:

$$K(\mathbf{x}, \mathbf{x}') = \Phi_{\theta_0}(\mathbf{x})^\top \mathbf{I}(\theta_0)^{-1} \Phi_{\theta_0}(\mathbf{x}') = \Phi_{\lambda_0}(\mathbf{x})^\top \mathbf{I}(\lambda_0)^{-1} \Phi_{\lambda_0}(\mathbf{x}').$$

Fisher kernel in practice

- $\Phi_{\theta_0}(\mathbf{x})$ can be computed explicitly for many models (e.g., HMMs), where the model is **first estimated from data**.
- $\mathbf{I}(\theta_0)$ is often replaced by the identity matrix for simplicity.
- Several different models (i.e., different θ_0) can be trained and combined.
- The **Fisher vectors** are defined as $\varphi_{\theta_0}(\mathbf{x}) = \mathbf{I}(\theta_0)^{-1/2}\Phi_{\theta_0}(\mathbf{x})$. They are explicitly computed and correspond to an explicit embedding:
 $K(\mathbf{x}, \mathbf{x}') = \varphi_{\theta_0}(\mathbf{x})^\top \varphi_{\theta_0}(\mathbf{x}')$.

Fisher kernels: example with Gaussian data model (1/2)

Consider a normal distribution $\mathcal{N}(\mu, \sigma^2)$ and denote by $\alpha = 1/\sigma^2$ the inverse variance, i.e., precision parameter. With $\theta = (\mu, \alpha)$, we have

$$\log P_\theta(x) = \frac{1}{2} \log \alpha - \frac{1}{2} \log(2\pi) - \frac{1}{2} \alpha(x - \mu)^2,$$

and thus

$$\frac{\partial \log P_\theta(x)}{\partial \mu} = \alpha(x - \mu), \quad \frac{\partial \log P_\theta(x)}{\partial \alpha} = \frac{1}{2} \left[\frac{1}{\alpha} - (x - \mu)^2 \right],$$

and (exercise)

$$\mathbf{I}(\theta) = \begin{pmatrix} \alpha & 0 \\ 0 & (1/2)\alpha^{-2} \end{pmatrix}.$$

The **Fisher vector** is then

$$\varphi_\theta(x) = \begin{pmatrix} (x - \mu)/\sigma \\ (1/\sqrt{2})(1 - (x - \mu)^2/\sigma^2) \end{pmatrix}.$$

Fisher kernels: example with Gaussian data model (2/2)

Now consider an i.i.d. data model over a set of data points x_1, \dots, x_n all distributed according to $\mathcal{N}(\mu, \sigma^2)$:

$$P_\theta(x_1, \dots, x_n) = \prod_{i=1}^n P_\theta(x_i).$$

Then, the Fisher vector is given by the sum of Fisher vectors of the points.

- Encodes the **discrepancy in the first and second order moment** of the data w.r.t. those of the model.

$$\varphi(x_1, \dots, x_n) = \sum_{i=1}^n \varphi(x_i) = n \begin{pmatrix} (\hat{\mu} - \mu)/\sigma \\ (\sigma^2 - \hat{\sigma}^2)/(\sqrt{2}\sigma^2) \end{pmatrix},$$

- where

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i \quad \text{and} \quad \hat{\sigma} = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2.$$

Application: Aggregation of visual words (1/5)

- **Patch extraction and description stage:**

In various contexts, images may be described as a set of patches $\mathbf{x}_1, \dots, \mathbf{x}_n$ computed at interest points. For example, SIFT, HOG, LBP, color histograms, convolutional features...

- **Coding stage:** The set of patches is then encoded into a single representation $\varphi(\mathbf{x}_i)$, typically in a high-dimensional space.

- **Pooling stage:** For example, sum pooling

$$\varphi(\mathbf{x}_1, \dots, \mathbf{x}_n) = \sum_{i=1}^n \varphi(\mathbf{x}_i).$$

Fisher vectors with a Gaussian Mixture Model (GMM) is a simple and effective aggregation technique (Perronnin and Dance, 2007).

Application: Aggregation of visual words (2/5)

Let $\theta = (\pi_j, \mu_j, \Sigma_j)_{j=1,\dots,k}$ be the parameters of a GMM with k Gaussian components. Then, the probabilistic model is given by

$$P_\theta(\mathbf{x}) = \sum_{j=1}^k \pi_j \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j).$$

Remarks

- Each mixture component corresponds to a **visual word**, with a mean, variance, and mixing weight.
- Diagonal covariances $\boldsymbol{\Sigma}_j = \text{diag}(\sigma_{j1}, \dots, \sigma_{jp}) = \text{diag}(\boldsymbol{\sigma}_j)$ are often used for simplicity.
- This is a richer model than the traditional “bag of words” approach.
- The probabilistic model is learned offline beforehand.

Application: Aggregation of visual words (3/5)

After cumbersome calculations (exercise), we obtain $\varphi_{\theta}(\mathbf{x}_1, \dots, \mathbf{x}_n) = [\varphi_{\pi_1}(\mathbf{X}), \dots, \varphi_{\pi_p}(\mathbf{X}), \varphi_{\mu_1}(\mathbf{X})^\top, \dots, \varphi_{\mu_p}(\mathbf{X})^\top, \varphi_{\sigma_1}(\mathbf{X})^\top, \dots, \varphi_{\sigma_p}(\mathbf{X})^\top]^\top$,

with

$$\varphi_{\mu_j}(\mathbf{X}) = \frac{1}{n\sqrt{\pi_j}} \sum_{i=1}^n \gamma_{ij} (\mathbf{x}_i - \boldsymbol{\mu}_j) / \sigma_j$$

$$\varphi_{\sigma_j}(\mathbf{X}) = \frac{1}{n\sqrt{2\pi_j}} \sum_{i=1}^n \gamma_{ij} [(x_i - \mu_j)^2 / \sigma_j^2 - 1],$$

where, with an abuse of notation, the division between two vectors is meant elementwise and the scalars γ_{ij} can be interpreted as the **soft-assignment** of word i to component j :

$$\gamma_{ij} = \frac{\pi_j \mathcal{N}(\mathbf{x}_i; \boldsymbol{\mu}_j, \boldsymbol{\sigma}_j)}{\sum_{l=1}^k \pi_l \mathcal{N}(\mathbf{x}_i; \boldsymbol{\mu}_l, \boldsymbol{\sigma}_l)}.$$

Application: Aggregation of visual words (4/5)

Finally, we also have the following interpretation of encoding first and second-order statistics:

$$\varphi_{\mu_j}(\mathbf{X}) = \frac{\gamma_j}{\sqrt{\pi_j}} (\hat{\mu}_j - \mu_j) / \sigma_j$$

$$\varphi_{\sigma_j}(\mathbf{X}) = \frac{\gamma_j}{\sqrt{2\pi_j}} (\hat{\sigma}_j^2 - \sigma_j^2) / \sigma_j^2,$$

with

$$\gamma_j = \sum_{i=1}^n \gamma_{ij} \quad \text{and} \quad \hat{\mu}_j = \frac{1}{\gamma_j} \sum_{i=1}^n \gamma_{ij} \mathbf{x}_i \quad \text{and} \quad \hat{\sigma}_j = \frac{1}{\gamma_j} \sum_{i=1}^n \gamma_{ij} (\mathbf{x}_i - \mu_j)^2.$$

The component $\varphi_{\pi}(\mathbf{X})$ is often dropped due to its negligible contribution in practice, and the resulting representation is of dimension $2kp$ where p is the dimension of the \mathbf{x}_i 's.

Application: Aggregation of visual words (5/5)

- FVs were state-of-the-art image representations before the revival of convolutional neural networks in 2012.

Application: Aggregation of visual words (5/5)

- FVs were state-of-the-art image representations before the revival of convolutional neural networks in 2012.
- This is an **unsupervised** image representation of high dimension. They remain competitive among unsupervised methods, see the following table from Bojanowski and Joulin, 2017.

Method	Acc@1
Random (Noroozi & Favaro, 2016)	12.0
SIFT+FV (Sánchez et al., 2013)	55.6
Wang & Gupta (2015)	29.8
Doersch et al. (2015)	30.4
Zhang et al. (2016)	35.2
¹ Noroozi & Favaro (2016)	38.1
BiGAN (Donahue et al., 2016)	32.2
NAT	36.0

Table 3. Comparison of the proposed approach to state-of-the-art unsupervised feature learning on ImageNet. A full multi-layer perceptron is retrained on top of the features. We compare to several self-supervised approaches and an unsupervised approach, *i.e.*, BiGAN (Donahue et al., 2016). ¹Noroozi & Favaro (2016)

Relation to classification with generative models (1/3)

Assume that we have a **generative probabilistic model** P_θ to model random variables (X, Y) where Y is a label in $\{1, \dots, p\}$.

Assume that the marginals $P_\theta(Y = k) = \pi_k$ are among the model parameters θ , which we can also parametrize as

$$P_\theta(Y = k) = \pi_k = \frac{e^{\alpha_k}}{\sum_{k'=1}^p e^{\alpha_{k'}}}.$$

The classification of a new point x can be obtained via **Bayes' rule**:

$$\hat{y}(x) = \operatorname{argmax}_{k=1,\dots,p} P_\theta(Y = k|x),$$

where $P_\theta(Y = k|x)$ is short for $P_\theta(Y = k|X = x)$ and

$$\begin{aligned} P_\theta(Y = k|x) &= P_\theta(x|Y = k)P_\theta(Y = k)/P_\theta(x) \\ &= P_\theta(x|Y = k)\pi_k / \sum_{k'=1}^p P_\theta(x|Y = k')\pi_{k'} \end{aligned}$$

Relation to classification with generative models (2/3)

Then, consider the Fisher score

$$\begin{aligned}\nabla_{\theta} \log P_{\theta}(x) &= \frac{1}{P_{\theta}(x)} \nabla_{\theta} P_{\theta}(x) \\&= \frac{1}{P_{\theta}(x)} \nabla_{\theta} \sum_{k=1}^p P_{\theta}(x, Y = k) \\&= \frac{1}{P_{\theta}(x)} \sum_{k=1}^p P_{\theta}(x, Y = k) \nabla_{\theta} \log P_{\theta}(x, Y = k) \\&= \sum_{k=1}^p P_{\theta}(Y = k|x) [\nabla_{\theta} \log \pi_k + \nabla_{\theta} \log P_{\theta}(x|Y = k)].\end{aligned}$$

In particular (exercise)

$$\frac{\partial \log P_{\theta}(x)}{\partial \alpha_k} = P_{\theta}(Y = k|x) - \pi_k.$$

Relation to classification with generative models (3/3)

The first p elements in the Fisher score are given by class posteriors minus a constant

$$\varphi_{\theta}(x) = [P_{\theta}(Y = 1|x) - \pi_1, \dots, P_{\theta}(Y = p|x) - \pi_p, \dots].$$

Consider a multi-class linear classifier on $\varphi_{\theta}(x)$ such that for class k

- The weights are zero except one for the k -th position;
- The intercept b_k be π_k ;

Then,

$$\hat{y}(x) = \operatorname{argmax}_{k=1,\dots,p} \varphi_{\theta}(x)^{\top} \mathbf{w}_k + b_k$$

$$\hat{y}(x) = \operatorname{argmax}_{k=1,\dots,p} P_{\theta}(Y = k|x).$$

Bayes' rule is implemented via this simple classifier using Fisher kernel.

Outline

5 The Kernel Jungle

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Mutual information kernels

Definition

- Choose a prior $w(d\theta)$ on the measurable set Θ .
- Form the kernel (Seeger, 2002):

$$K(\mathbf{x}, \mathbf{x}') = \int_{\theta \in \Theta} P_\theta(\mathbf{x})P_\theta(\mathbf{x}')w(d\theta).$$

- No explicit computation of a finite-dimensional feature vector.
- $K(\mathbf{x}, \mathbf{x}') = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle_{L_2(w)}$ with

$$\varphi(\mathbf{x}) = (P_\theta(\mathbf{x}))_{\theta \in \Theta}.$$

Example: coin toss

- Let $P_\theta(X = 1) = \theta$ and $P_\theta(X = 0) = 1 - \theta$ a model for random coin toss, with $\theta \in [0, 1]$.
- Let $d\theta$ be the Lebesgue measure on $[0, 1]$
- The mutual information kernel between $\mathbf{x} = 001$ and $\mathbf{x}' = 1010$ is:

$$\begin{cases} P_\theta(\mathbf{x}) &= \theta(1-\theta)^2, \\ P_\theta(\mathbf{x}') &= \theta^2(1-\theta)^2, \end{cases}$$

$$K(\mathbf{x}, \mathbf{x}') = \int_0^1 \theta^3(1-\theta)^4 d\theta = \frac{3!4!}{8!} = \frac{1}{280}.$$

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Marginalized kernels

Definition

- For any observed data $\mathbf{x} \in \mathcal{X}$, let a latent variable $\mathbf{y} \in \mathcal{Y}$ be associated probabilistically through a conditional probability $P_{\mathbf{x}}(d\mathbf{y})$.
- Let $K_{\mathcal{Z}}$ be a kernel for the complete data $\mathbf{z} = (\mathbf{x}, \mathbf{y})$
- Then, the following kernel is a valid kernel on \mathcal{X} , called a marginalized kernel (Tsuda et al., 2002):

$$\begin{aligned} K_{\mathcal{X}}(\mathbf{x}, \mathbf{x}') &:= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') \\ &= \int \int K_{\mathcal{Z}}((\mathbf{x}, \mathbf{y}), (\mathbf{x}', \mathbf{y}')) P_{\mathbf{x}}(d\mathbf{y}) P_{\mathbf{x}'}(d\mathbf{y}') . \end{aligned}$$

Marginalized kernels: proof of positive definiteness

- $K_{\mathcal{Z}}$ is p.d. on \mathcal{Z} . Therefore, there exists a Hilbert space \mathcal{H} and $\Phi_{\mathcal{Z}} : \mathcal{Z} \rightarrow \mathcal{H}$ such that:

$$K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') = \langle \Phi_{\mathcal{Z}}(\mathbf{z}), \Phi_{\mathcal{Z}}(\mathbf{z}') \rangle_{\mathcal{H}}.$$

- Marginalizing therefore gives:

$$\begin{aligned} K_{\mathcal{X}}(\mathbf{x}, \mathbf{x}') &= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') \\ &= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} \langle \Phi_{\mathcal{Z}}(\mathbf{z}), \Phi_{\mathcal{Z}}(\mathbf{z}') \rangle_{\mathcal{H}} \\ &= \langle E_{P_{\mathbf{x}}(d\mathbf{y})} \Phi_{\mathcal{Z}}(\mathbf{z}), E_{P_{\mathbf{x}'}(d\mathbf{y}')} \Phi_{\mathcal{Z}}(\mathbf{z}') \rangle_{\mathcal{H}}, \end{aligned}$$

therefore $K_{\mathcal{X}}$ is p.d. on \mathcal{X} . \square

Marginalized kernels: proof of positive definiteness

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- Marginalizing therefore gives:

$$\begin{aligned} K_{\mathcal{X}}(\mathbf{x}, \mathbf{x}') &= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') \\ &= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} \langle \Phi_{\mathcal{Z}}(\mathbf{z}), \Phi_{\mathcal{Z}}(\mathbf{z}') \rangle_{\mathcal{H}} \\ &= \langle E_{P_{\mathbf{x}}(d\mathbf{y})} \Phi_{\mathcal{Z}}(\mathbf{z}), E_{P_{\mathbf{x}'}(d\mathbf{y}')} \Phi_{\mathcal{Z}}(\mathbf{z}') \rangle_{\mathcal{H}}, \end{aligned}$$

therefore $K_{\mathcal{X}}$ is p.d. on \mathcal{X} . \square

Of course, we make the right assumptions such that each operation above is valid, and all quantities are well defined.

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5 The Kernel Jungle

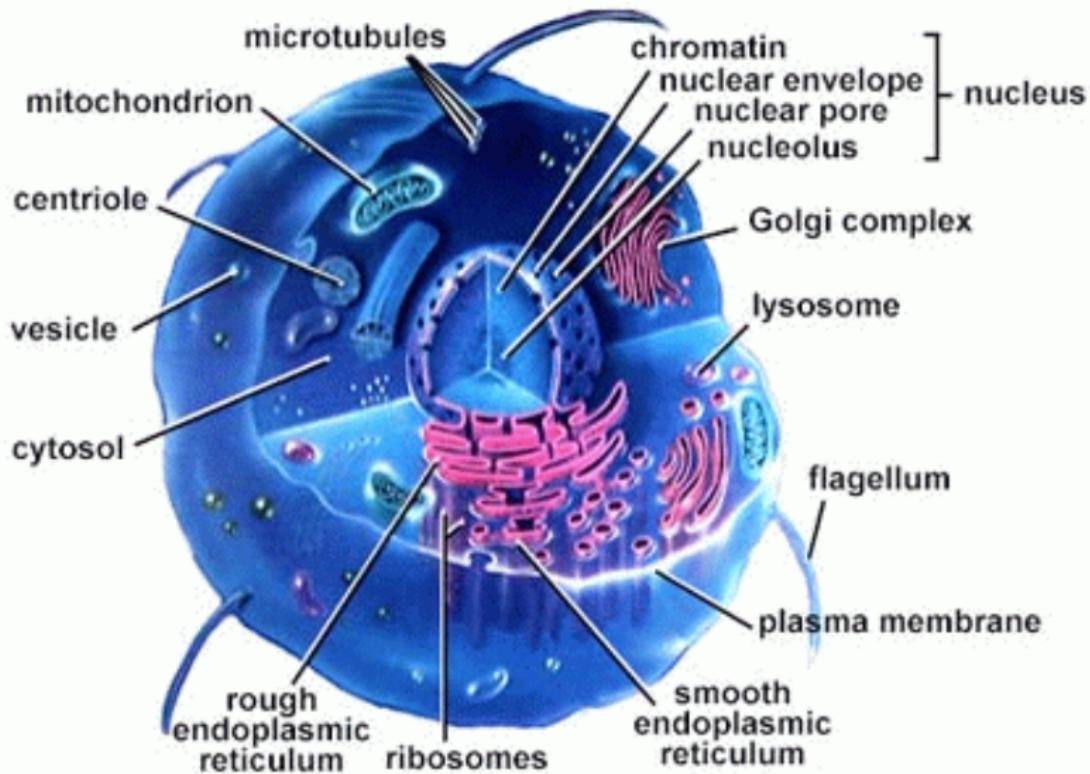
- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- **Kernels for biological sequences**
 - Motivations and history of genomics
 - Kernels derived from large feature spaces
 - Kernels derived from generative models
 - Kernels derived from a similarity measure
 - Application to remote homology detection
- Kernels for graphs
- Kernels on graphs

Short history of genomics

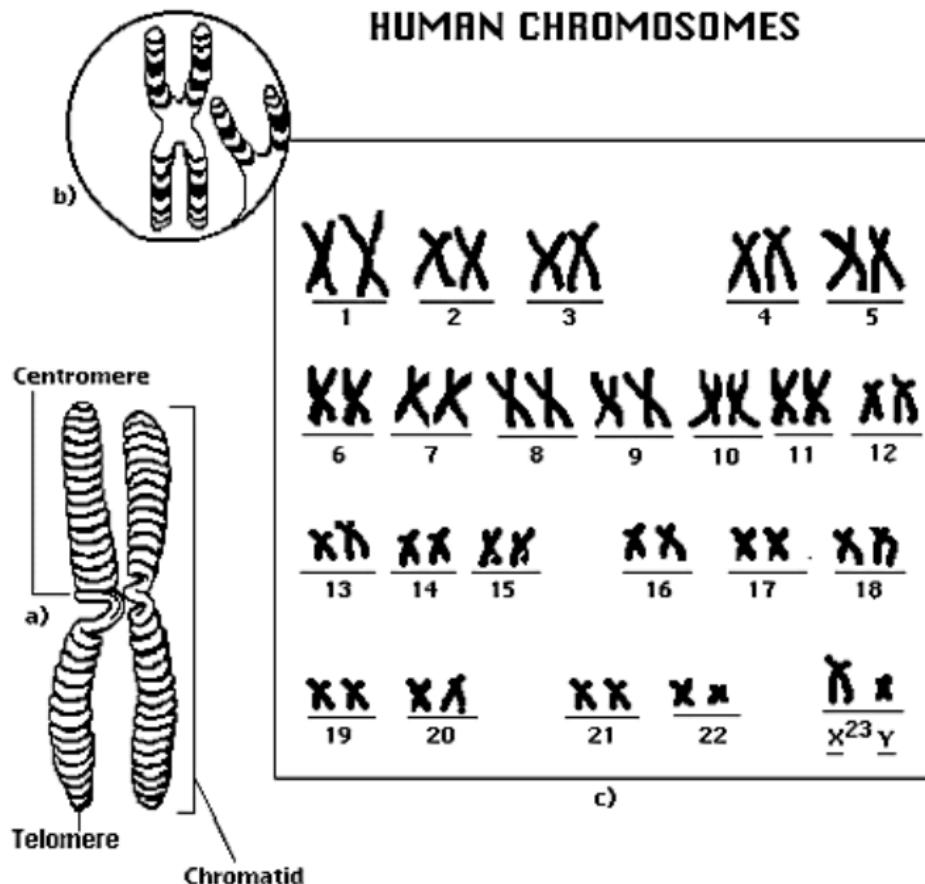


- 1866 : Laws of heredity (Mendel)
- 1909 : Morgan and the drosophilists
- 1944 : DNA supports heredity (Avery)
- 1953 : Structure of DNA (Crick, Watson, Wilkins and Franklin)**
- 1966 : Genetic code (Nirenberg)
- 1960-70 : Genetic engineering
- 1977 : Method for sequencing (Sanger)
- 1982 : Creation of Genbank
- 1990 : Human genome project launched
- 2003 : Human genome project completed**

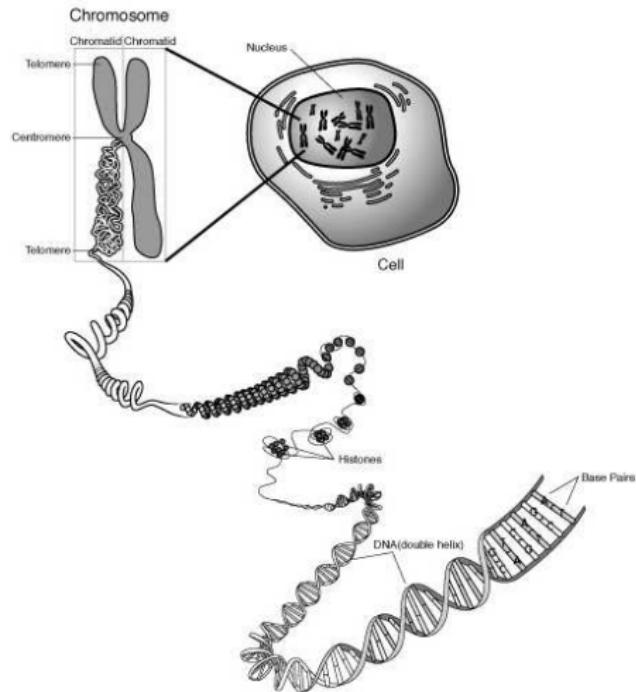
A cell



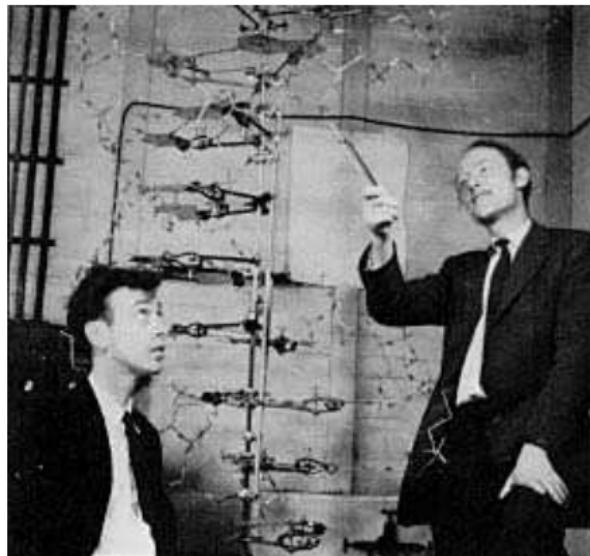
Chromosomes



Chromosomes and DNA



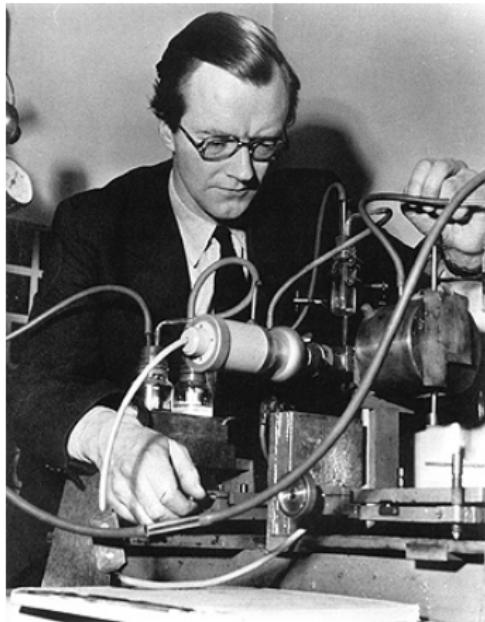
Structure of DNA



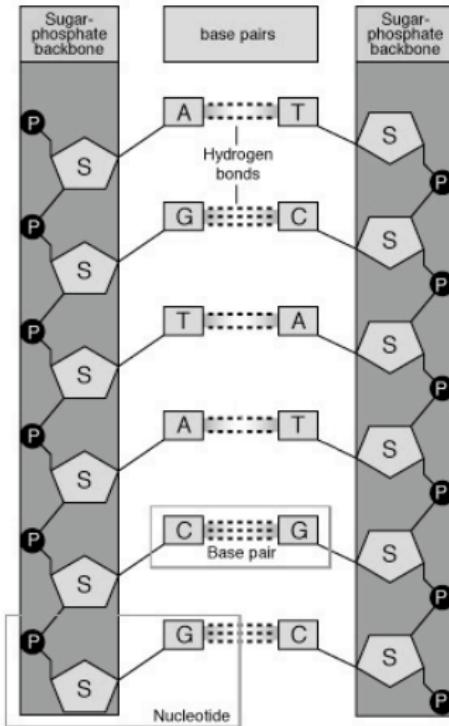
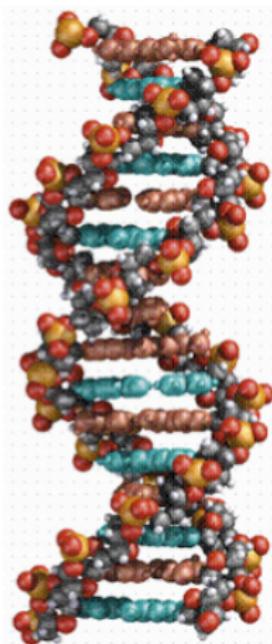
“We wish to suggest a structure for the salt of deoxyribose nucleic acid (D.N.A.). This structure have novel features which are of considerable biological interest” (Watson and Crick, 1953).

James Watson, Francis Crick, and Maurice Wilkins received the Nobel prize for this discovery in 1962. Key to this discovery were the X-ray crystallography images obtained by Rosalind Franklin.

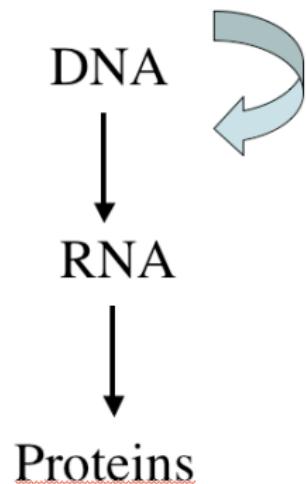
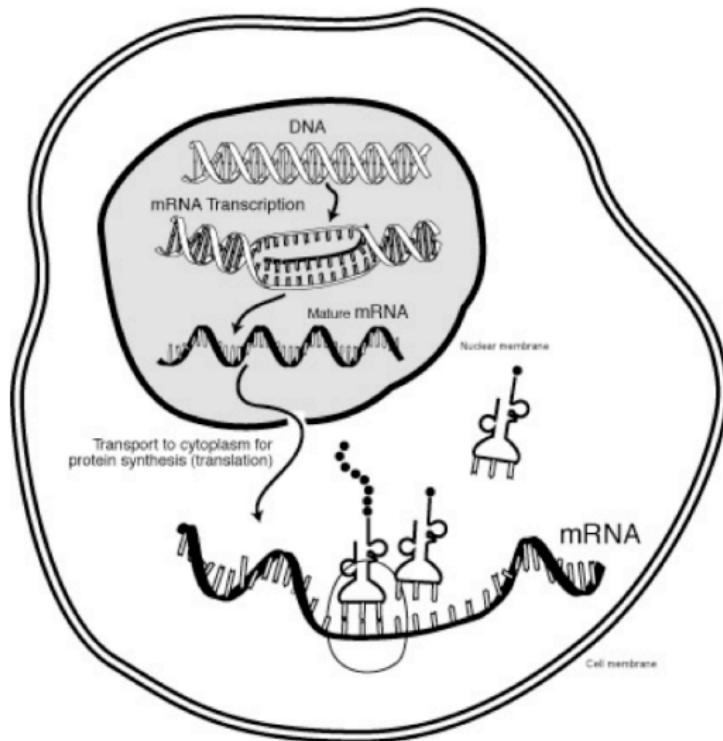
Structure of DNA



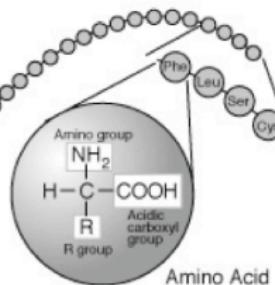
The double helix



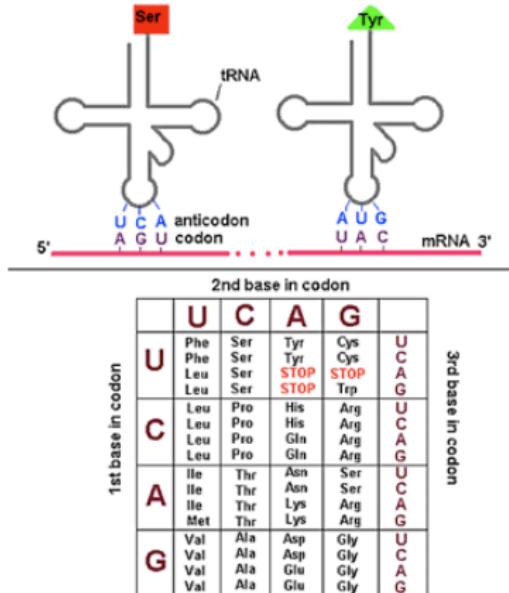
Central dogma



Proteins



Genetic code



The Genetic Code

DNA = 4 letters (ATCG)

RNA = 4 letters (AUCG)

Protein = 20 letters (amino acids)

1 amino acid

=

3 nucleotides

Human genome project

- Goal : sequence the 3,000,000,000 bases of the human genome
- Consortium with 20 labs, 6 countries
- Cost : between 0.5 and 1 billion USD



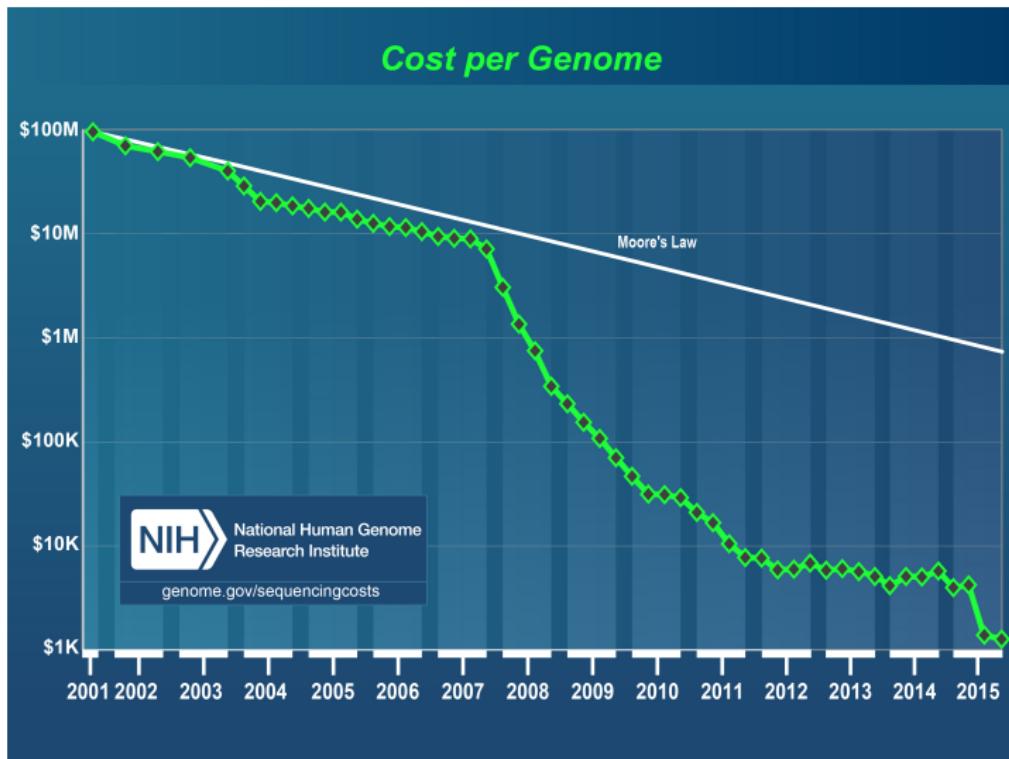
2003: End of genomics era



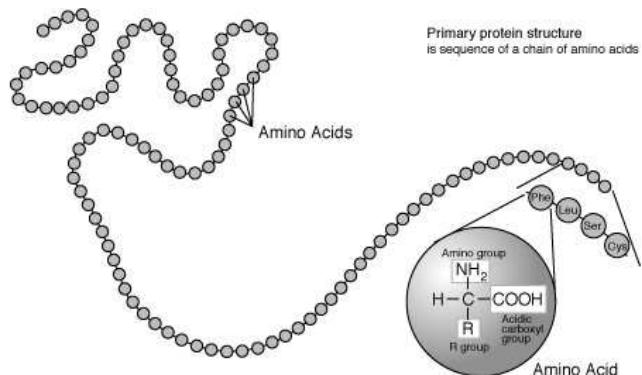
Findings

- About 25,000 genes only (representing 1.2% of the genome).
- Automatic gene finding with graphical models.
- 97% of the genome is considered “junk DNA”.
- Superposition of a variety of signals (many to be discovered).

Cost of human genome sequencing



Protein sequence



A : Alanine	V : Valine	L : Leucine
F : Phenylalanine	P : Proline	M : Methionine
E : Glutamic acid	K : Lysine	R : Arginine
T : Threonine	C : Cysteine	N : Asparagine
H : Histidine	Y : Tyrosine	W : Tryptophane
I : Isoleucine	S : Serine	Q : Glutamine
D : Aspartic acid	G : Glycine	

Challenges with protein sequences

- A protein sequences can be seen as a **variable-length sequence** over the **20-letter alphabet** of amino-acids, e.g., insulin:
FVNQHLCGSHLVEALYLVCGERGFFYTPKA
- These sequences are produced at a fast rate (result of the **sequencing programs**)
- Need for algorithms to **compare, classify, analyze** these sequences
- Applications: classification into **functional or structural** classes, prediction of **cellular localization** and **interactions**, ...

Example: supervised sequence classification

Data (training)

- Secreted proteins:

MASKATLLLAF~~TLLFATCIARHQQRQQQNQCQLQNIEA~~...

MARSSLFTFLCLAVFINGCLSQIEQQSPWEFQGSEVW...

MALHTVLIMLSLLPMLEAQNPEHANITIGEPI~~TNETLGWL~~...

...

- Non-secreted proteins:

MAPPSVFAEV~~PQAQPVLVF~~KLIADFREDPDRKVNLGVG...

MAHTLGLTQP~~NSTEPHKISFTA~~EIDVIEWKGDI~~L~~VVG...

MSI~~SESYAKEIKTA~~RQFTDFPIEGEQFEDFLPIIGNP...

...

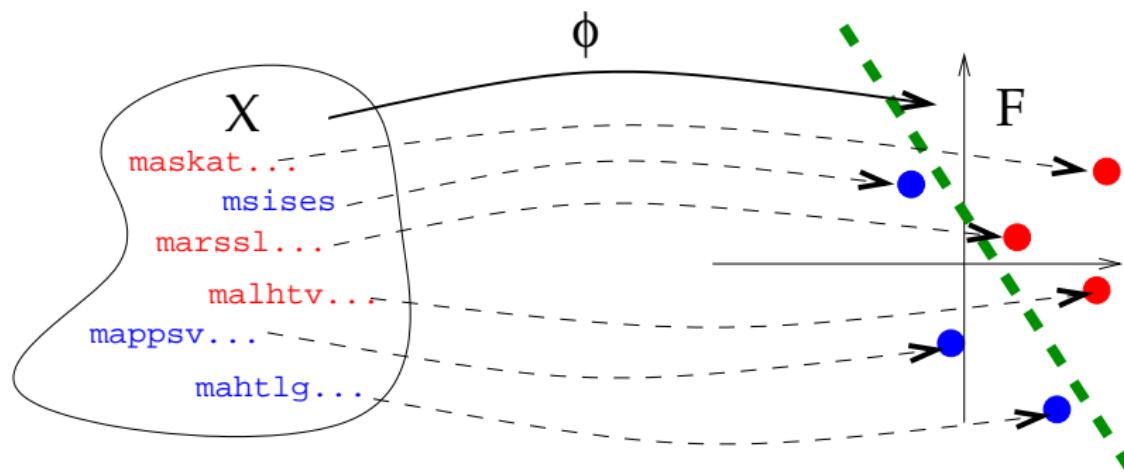
Goal

- Build a **classifier** to **predict** whether new proteins are secreted or not.

Supervised classification with vector embedding

The idea

- Map each string $x \in \mathcal{X}$ to a vector $\Phi(x) \in \mathcal{F}$.
- Train a **classifier for vectors** on the images $\Phi(x_1), \dots, \Phi(x_n)$ of the training set (nearest neighbor, linear perceptron, logistic regression, support vector machine...)



Kernels for protein sequences

- Kernel methods have been widely investigated since Jaakkola et al.'s seminal paper (1998).
- What is a good kernel?
 - it should be mathematically valid (symmetric, p.d. or c.p.d.)
 - fast to compute
 - adapted to the problem (gives good performances)

Kernel engineering for protein sequences

- Define a (possibly high-dimensional) **feature space** of interest
 - Physico-chemical kernels
 - Spectrum, mismatch, substring kernels
 - Pairwise, motif kernels

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- Derive a kernel from a **generative model**
 - Fisher kernel
 - Mutual information kernel
 - Marginalized kernel

Kernel engineering for protein sequences

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 - Marginalized kernel
- Derive a kernel from a **similarity measure**
 - Local alignment kernel

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- **Kernels for biological sequences**
 - Motivations and history of genomics
 - **Kernels derived from large feature spaces**
 - Kernels derived from generative models
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 - Application to remote homology detection
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- Kernels on graphs

Vector embedding for strings

The idea

Represent each sequence x by a **fixed-length numerical vector**
 $\Phi(x) \in \mathbb{R}^n$. How to perform this embedding?

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Physico-chemical kernel

Extract **relevant features**, such as:

- length of the sequence
- time series analysis of numerical physico-chemical properties of amino-acids along the sequence (e.g., polarity, hydrophobicity), using for example:
 - Fourier transforms (Wang et al., 2004)
 - Autocorrelation functions (Zhang et al., 2003)

$$r_j = \frac{1}{n-j} \sum_{i=1}^{n-j} h_i h_{i+j}$$

Substring indexation

The approach

Alternatively, index the feature space by fixed-length strings, i.e.,

$$\Phi(\mathbf{x}) = (\Phi_u(\mathbf{x}))_{u \in \mathcal{A}^k}$$

where $\Phi_u(\mathbf{x})$ can be:

- the number of occurrences of u in \mathbf{x} (without gaps) : **spectrum kernel** (Leslie et al., 2002)
- the number of occurrences of u in \mathbf{x} up to m mismatches (without gaps) : **mismatch kernel** (Leslie et al., 2004)
- the number of occurrences of u in \mathbf{x} allowing gaps, with a weight decaying exponentially with the number of gaps : **substring kernel** (Lohdi et al., 2002)

Example: Spectrum kernel (1/4)

Kernel definition

- The 3-spectrum of

$$\mathbf{x} = \text{CGGSLIAMMWFGV}$$

is:

$(\text{CGG}, \text{GGS}, \text{GSL}, \text{SLI}, \text{LIA}, \text{IAM}, \text{AMM}, \text{MMW}, \text{MWF}, \text{WFG}, \text{FGV})$.

- Let $\Phi_u(\mathbf{x})$ denote the number of occurrences of u in \mathbf{x} . The k -spectrum kernel is:

$$K(\mathbf{x}, \mathbf{x}') := \sum_{u \in \mathcal{A}^k} \Phi_u(\mathbf{x}) \Phi_u(\mathbf{x}')$$

Example: Spectrum kernel (2/4)

Implementation

- The computation of the kernel is formally a sum over $|\mathcal{A}|^k$ terms, but at most $|\mathbf{x}| - k + 1$ terms are non-zero in $\Phi(\mathbf{x}) \implies$ Computation in $O(|\mathbf{x}| + |\mathbf{x}'|)$ with pre-indexation of the strings.
- Fast classification of a sequence \mathbf{x} in $O(|\mathbf{x}|)$:

$$f(\mathbf{x}) = \mathbf{w} \cdot \Phi(\mathbf{x}) = \sum_u w_u \Phi_u(\mathbf{x}) = \sum_{i=1}^{|\mathbf{x}|-k+1} w_{x_i \dots x_{i+k-1}}.$$

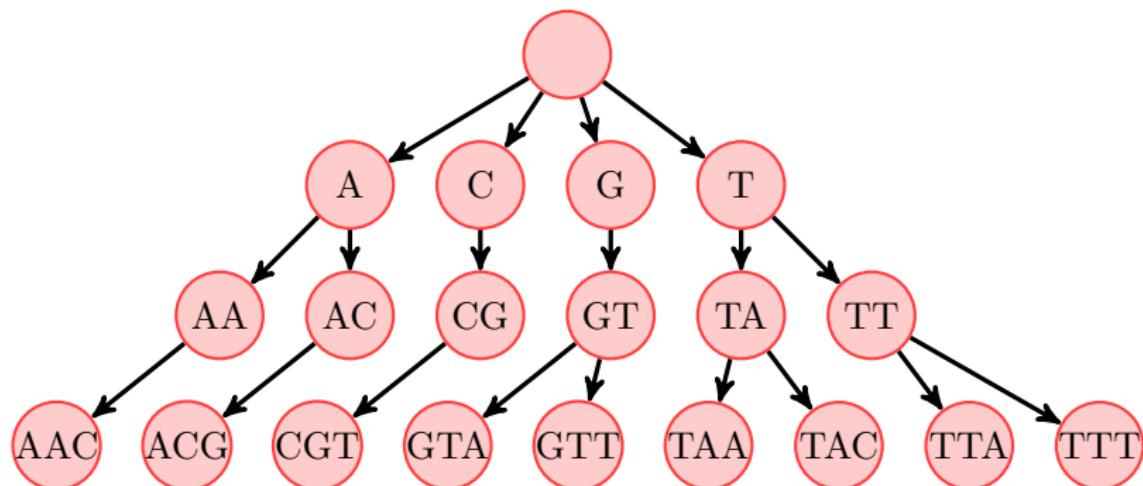
Remarks

- Work with any string (natural language, time series...)
- Fast and scalable, a good default method for string classification.
- Variants allow matching of k -mers up to m mismatches.

Example: Spectrum kernel (3/4)

If pre-indexation is not possible: retrieval tree (trie)

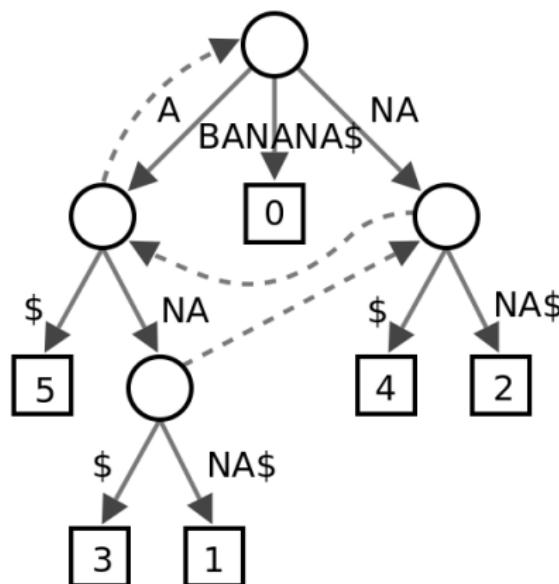
Consider the sequence ACGTTAACGTAC.



The complexity for computing $K(\mathbf{x}, \mathbf{x}')$ becomes $O(k(|\mathbf{x}| + |\mathbf{x}'|))$.

Example: Spectrum kernel (4/4)

If pre-indexation is not possible: use a suffix tree



The complexity for computing $K(\mathbf{x}, \mathbf{x}')$ becomes $O(|\mathbf{x}| + |\mathbf{x}'|)$, but with a larger constant than with pre-indexation.

Example 2: Substring kernel (1/12)

Definition

- For $1 \leq k \leq n \in \mathbb{N}$, we denote by $\mathcal{I}(k, n)$ the set of sequences of indices $\mathbf{i} = (i_1, \dots, i_k)$, with $1 \leq i_1 < i_2 < \dots < i_k \leq n$.
- For a string $\mathbf{x} = x_1 \dots x_n \in \mathcal{X}$ of length n , for a sequence of indices $\mathbf{i} \in \mathcal{I}(k, n)$, we define a **substring** as:

$$\mathbf{x}(\mathbf{i}) := x_{i_1} x_{i_2} \dots x_{i_k}.$$

- The **length** of the substring is:

$$l(\mathbf{i}) = i_k - i_1 + 1.$$

Example 2: Substring kernel (2/12)

Example

ABRACADABRA

- $\mathbf{i} = (3, 4, 7, 8, 10)$
- $\mathbf{x}(\mathbf{i}) = \text{RADAR}$
- $l(\mathbf{i}) = 10 - 3 + 1 = 8$

Example 2: Substring kernel (3/12)

The kernel

- Let $k \in \mathbb{N}$ and $\lambda \in \mathbb{R}^+$ fixed. For all $\mathbf{u} \in \mathcal{A}^k$, let $\Phi_{\mathbf{u}} : \mathcal{X} \rightarrow \mathbb{R}$ be defined by:

$$\forall \mathbf{x} \in \mathcal{X}, \quad \Phi_{\mathbf{u}}(\mathbf{x}) = \sum_{\mathbf{i} \in \mathcal{I}(k, |\mathbf{x}|) : \mathbf{x}(\mathbf{i}) = \mathbf{u}} \lambda^{l(\mathbf{i})}.$$

- The **substring kernel** is the p.d. kernel defined by:

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K_{k,\lambda}(\mathbf{x}, \mathbf{x}') = \sum_{\mathbf{u} \in \mathcal{A}^k} \Phi_{\mathbf{u}}(\mathbf{x}) \Phi_{\mathbf{u}}(\mathbf{x}').$$

Example 2: Substring kernel (4/12)

Example

u	ca	ct	at	ba	bt	cr	ar	br
$\Phi_u(\text{cat})$	λ^2	λ^3	λ^2	0	0	0	0	0
$\Phi_u(\text{car})$	λ^2	0	0	0	0	λ^3	λ^2	0
$\Phi_u(\text{bat})$	0	0	λ^2	λ^2	λ^3	0	0	0
$\Phi_u(\text{bar})$	0	0	0	λ^2	0	0	λ^2	λ^3

$$\begin{cases} K(\text{cat}, \text{cat}) = K(\text{car}, \text{car}) = 2\lambda^4 + \lambda^6 \\ K(\text{cat}, \text{car}) = \lambda^4 \\ K(\text{cat}, \text{bar}) = 0 \end{cases}$$

Example 2: Substring kernel (5/12)

Kernel computation

- We need to compute, for any pair $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$, the kernel:

$$\begin{aligned} K_{k,\lambda}(\mathbf{x}, \mathbf{x}') &= \sum_{\mathbf{u} \in \mathcal{A}^k} \Phi_{\mathbf{u}}(\mathbf{x}) \Phi_{\mathbf{u}}(\mathbf{x}') \\ &= \sum_{\mathbf{u} \in \mathcal{A}^k} \sum_{i: x(i) = \mathbf{u}} \sum_{i': x'(i') = \mathbf{u}} \lambda^{l(i)+l(i')} . \end{aligned}$$

- Enumerating the substrings is **too slow** (of order $|\mathbf{x}|^k$).

Example 2: Substring kernel (6/12)

Kernel computation (cont.)

- For $\mathbf{u} \in \mathcal{A}^k$ remember that:

$$\Phi_{\mathbf{u}}(\mathbf{x}) = \sum_{\mathbf{i}: \mathbf{x}(\mathbf{i}) = \mathbf{u}} \lambda^{i_k - i_1 + 1}.$$

- Let now:

$$\Psi_{\mathbf{u}}(\mathbf{x}) = \sum_{\mathbf{i}: \mathbf{x}(\mathbf{i}) = \mathbf{u}} \lambda^{|\mathbf{x}| - i_1 + 1}.$$

Example 2: Substring kernel (7/12)

Kernel computation (cont.)

Let us note $\mathbf{x}_{[1,j]} = x_1 \dots x_j$. A simple rewriting shows that, if we note $a \in \mathcal{A}$ the last letter of \mathbf{u} ($\mathbf{u} = \mathbf{v}a$):

$$\Phi_{\mathbf{v}a}(\mathbf{x}) = \sum_{j \in [1, |\mathbf{x}|]: x_j = a} \Psi_{\mathbf{v}}(\mathbf{x}_{[1,j-1]}) \lambda,$$

and

$$\Psi_{\mathbf{v}a}(\mathbf{x}) = \sum_{j \in [1, |\mathbf{x}|]: x_j = a} \Psi_{\mathbf{v}}(\mathbf{x}_{[1,j-1]}) \lambda^{|\mathbf{x}|-j+1}.$$

Example 2: Substring kernel (8/12)

Kernel computation (cont.)

Moreover we observe that if the string is of the form xa (i.e., the last letter is $a \in \mathcal{A}$), then:

- If the last letter of \mathbf{u} is not a :

$$\begin{cases} \Phi_{\mathbf{u}}(xa) = \Phi_{\mathbf{u}}(x) , \\ \Psi_{\mathbf{u}}(xa) = \lambda \Psi_{\mathbf{u}}(x) . \end{cases}$$

- If the last letter of \mathbf{u} is a (i.e., $\mathbf{u} = \mathbf{v}a$ with $\mathbf{v} \in \mathcal{A}^{k-1}$):

$$\begin{cases} \Phi_{\mathbf{v}a}(xa) = \Phi_{\mathbf{v}a}(x) + \lambda \Psi_{\mathbf{v}}(x) , \\ \Psi_{\mathbf{v}a}(xa) = \lambda \Psi_{\mathbf{v}a}(x) + \lambda \Psi_{\mathbf{v}}(x) . \end{cases}$$

Example 2: Substring kernel (9/12)

Kernel computation (cont.)

Let us now show how the function:

$$B_k(\mathbf{x}, \mathbf{x}') := \sum_{\mathbf{u} \in \mathcal{A}^k} \Psi_{\mathbf{u}}(\mathbf{x}) \Psi_{\mathbf{u}}(\mathbf{x}')$$

and the kernel:

$$K_k(\mathbf{x}, \mathbf{x}') := \sum_{\mathbf{u} \in \mathcal{A}^k} \Phi_{\mathbf{u}}(\mathbf{x}) \Phi_{\mathbf{u}}(\mathbf{x}')$$

can be computed recursively. We note that:

$$\begin{cases} B_0(\mathbf{x}, \mathbf{x}') = K_0(\mathbf{x}, \mathbf{x}') = 1 & \text{for all } \mathbf{x}, \mathbf{x}' \\ B_k(\mathbf{x}, \mathbf{x}') = K_k(\mathbf{x}, \mathbf{x}') = 0 & \text{if } \min(|\mathbf{x}|, |\mathbf{x}'|) < k \end{cases}$$

Example 2: Substring kernel (10/12)

Recursive computation of B_k

$$\begin{aligned} & B_k(\mathbf{x}a, \mathbf{x}') \\ &= \sum_{\mathbf{u} \in \mathcal{A}^k} \Psi_{\mathbf{u}}(\mathbf{x}a) \Psi_{\mathbf{u}}(\mathbf{x}') \\ &= \lambda \sum_{\mathbf{u} \in \mathcal{A}^k} \Psi_{\mathbf{u}}(\mathbf{x}) \Psi_{\mathbf{u}}(\mathbf{x}') + \lambda \sum_{\mathbf{v} \in \mathcal{A}^{k-1}} \Psi_{\mathbf{v}}(\mathbf{x}) \Psi_{\mathbf{v}a}(\mathbf{x}') \\ &= \lambda B_k(\mathbf{x}, \mathbf{x}') + \\ &\quad \lambda \sum_{\mathbf{v} \in \mathcal{A}^{k-1}} \Psi_{\mathbf{v}}(\mathbf{x}) \left(\sum_{j \in [1, |\mathbf{x}'|]: x'_j = a} \Psi_{\mathbf{v}}(\mathbf{x}'_{[1, j-1]}) \lambda^{|\mathbf{x}'|-j+1} \right) \\ &= \lambda B_k(\mathbf{x}, \mathbf{x}') + \sum_{j \in [1, |\mathbf{x}'|]: x'_j = a} B_{k-1}(\mathbf{x}, \mathbf{x}'_{[1, j-1]}) \lambda^{|\mathbf{x}'|-j+2} \end{aligned}$$

Example 2: Substring kernel (11/12)

Recursive computation of B_k

$$B_k(\mathbf{x}a, \mathbf{x}'b)$$

$$\begin{aligned} &= \lambda B_k(\mathbf{x}, \mathbf{x}'b) + \lambda \sum_{j \in [1, |\mathbf{x}'|] : x'_j = a} B_{k-1}\left(\mathbf{x}, \mathbf{x}'_{[1, j-1]}\right) \lambda^{|\mathbf{x}'|-j+2} \\ &\quad + \delta_{a=b} B_{k-1}(\mathbf{x}, \mathbf{x}') \lambda^2 \end{aligned}$$

$$\begin{aligned} &= \lambda B_k(\mathbf{x}, \mathbf{x}'b) + \lambda(B_k(\mathbf{x}a, \mathbf{x}') - \lambda B_k(\mathbf{x}, \mathbf{x}')) + \delta_{a=b} B_{k-1}(\mathbf{x}, \mathbf{x}') \lambda^2 \\ &= \lambda B_k(\mathbf{x}, \mathbf{x}'b) + \lambda B_k(\mathbf{x}a, \mathbf{x}') - \lambda^2 B_k(\mathbf{x}, \mathbf{x}') + \delta_{a=b} B_{k-1}(\mathbf{x}, \mathbf{x}') \lambda^2. \end{aligned}$$

The dynamic programming table can be filled in $O(k|\mathbf{x}||\mathbf{x}'|)$ operations.

Example 2: Substring kernel (12/12)

Recursive computation of K_k

$$\begin{aligned} K_k(\mathbf{x}a, \mathbf{x}') &= \sum_{\mathbf{u} \in \mathcal{A}^k} \Phi_{\mathbf{u}}(\mathbf{x}a) \Phi_{\mathbf{u}}(\mathbf{x}') \\ &= \sum_{\mathbf{u} \in \mathcal{A}^k} \Phi_{\mathbf{u}}(\mathbf{x}) \Phi_{\mathbf{u}}(\mathbf{x}') + \lambda \sum_{\mathbf{v} \in \mathcal{A}^{k-1}} \Psi_{\mathbf{v}}(\mathbf{x}) \Phi_{\mathbf{v}a}(\mathbf{x}') \\ &= K_k(\mathbf{x}, \mathbf{x}') + \\ &\quad \lambda \sum_{\mathbf{v} \in \mathcal{A}^{k-1}} \Psi_{\mathbf{v}}(\mathbf{x}) \left(\sum_{j \in [1, |\mathbf{x}'|] : x'_j = a} \Psi_{\mathbf{v}}(\mathbf{x}'_{[1, j-1]}) \right) \lambda \\ &= K_k(\mathbf{x}, \mathbf{x}') + \lambda^2 \sum_{j \in [1, |\mathbf{x}'|] : x'_j = a} B_{k-1}(\mathbf{x}, \mathbf{x}'_{[1, j-1]}) \end{aligned}$$

Summary: Substring indexation

- Implementation in $O(|\mathbf{x}| + |\mathbf{x}'|)$ in memory and time for the spectrum and mismatch kernels (with suffix trees)
- Implementation in $O(k(|\mathbf{x}| + |\mathbf{x}'|))$ in memory and time for the spectrum and mismatch kernels (with tries)
- Implementation in $O(k|\mathbf{x}| \times |\mathbf{x}'|)$ in memory and time for the substring kernels
- The feature space has high dimension ($|\mathcal{A}|^k$), so learning requires **regularized methods** (such as SVM)

Dictionary-based indexation

The approach

- Choose a **dictionary** of sequences $\mathcal{D} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$
- Choose a **measure of similarity** $s(\mathbf{x}, \mathbf{x}')$
- Define the mapping $\Phi_{\mathcal{D}}(\mathbf{x}) = (s(\mathbf{x}, \mathbf{x}_i))_{\mathbf{x}_i \in \mathcal{D}}$

Dictionary-based indexation

The approach

- Chose a **dictionary** of sequences $\mathcal{D} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$
- Chose a **measure of similarity** $s(\mathbf{x}, \mathbf{x}')$
- Define the mapping $\Phi_{\mathcal{D}}(\mathbf{x}) = (s(\mathbf{x}, \mathbf{x}_i))_{\mathbf{x}_i \in \mathcal{D}}$

Examples

This includes:

- **Motif kernels** (Logan et al., 2001): the dictionary is a library of motifs, the similarity function is a matching function
- **Pairwise kernel** (Liao & Noble, 2003): the dictionary is the training set, the similarity is a classical measure of similarity between sequences.

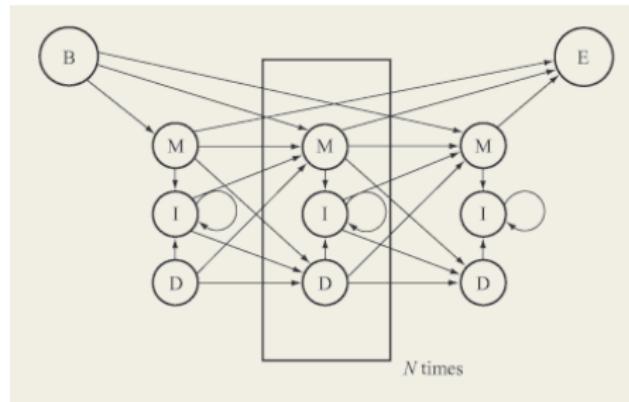
Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- **Kernels for biological sequences**
 - Motivations and history of genomics
 - Kernels derived from large feature spaces
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Probabilistic models for sequences

Probabilistic modeling of biological sequences is older than kernel designs. Important models include HMM for protein sequences, SCFG for RNA sequences.



Recall: parametric model

A **model** is a family of distributions

$$\{P_\theta, \theta \in \Theta \subset \mathbb{R}^m\} \subset \mathcal{M}_1^+(\mathcal{X})$$

Context-tree model

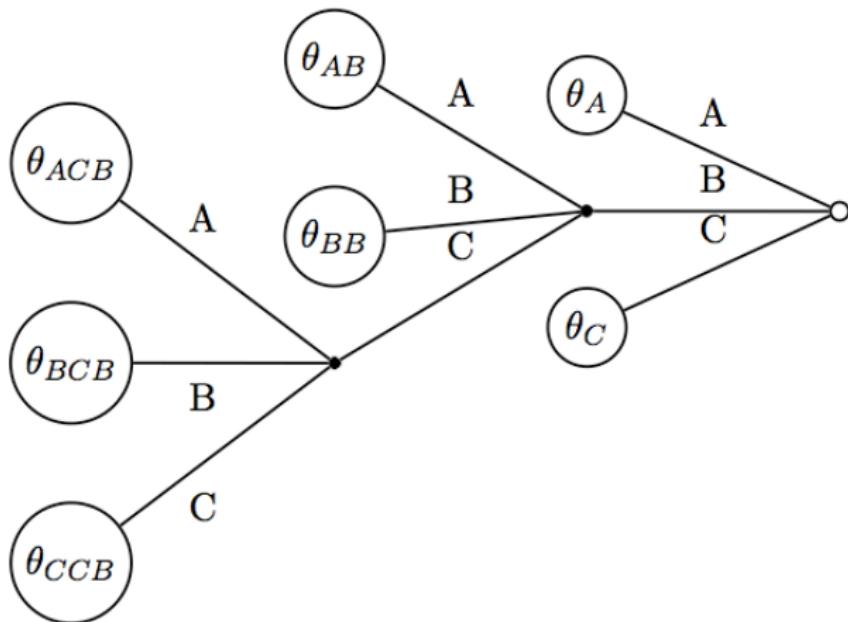
Definition

A context-tree model is a **variable-memory Markov chain**:

$$P_{\mathcal{D}, \theta}(\mathbf{x}) = P_{\mathcal{D}, \theta}(x_1 \dots x_D) \prod_{i=D+1}^n P_{\mathcal{D}, \theta}(x_i | x_{i-D} \dots x_{i-1})$$

- \mathcal{D} is a suffix tree
- $\theta \in \Sigma^{\mathcal{D}}$ is a set of conditional probabilities (multinomials)

Context-tree model: example



$$P(AABACBACC) = P(AAB)\theta_{AB}(A)\theta_A(C)\theta_C(B)\theta_{ACB}(A)\theta_A(C)\theta_C(A).$$

The context-tree kernel

Theorem (Cuturi et al., 2005)

- For particular choices of priors, the context-tree kernel:

$$K(\mathbf{x}, \mathbf{x}') = \sum_{\mathcal{D}} \int_{\theta \in \Sigma^{\mathcal{D}}} P_{\mathcal{D}, \theta}(\mathbf{x}) P_{\mathcal{D}, \theta}(\mathbf{x}') w(d\theta | \mathcal{D}) \pi(\mathcal{D})$$

can be computed in $O(|\mathbf{x}| + |\mathbf{x}'|)$ with a variant of the Context-Tree Weighting algorithm.

- This is a valid mutual information kernel.
- The similarity is related to information-theoretical measure of mutual information between strings.

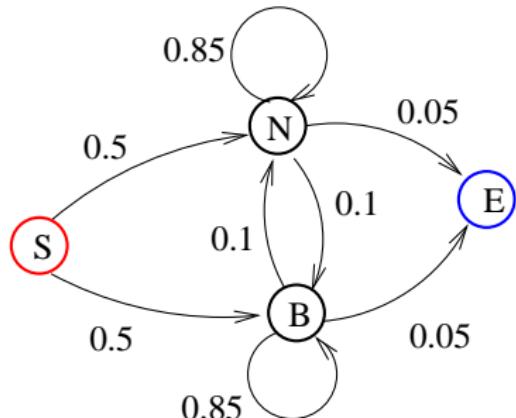
Marginalized kernels

Recall: Definition

- For any observed data $\mathbf{x} \in \mathcal{X}$, let a latent variable $\mathbf{y} \in \mathcal{Y}$ be associated probabilistically through a conditional probability $P_{\mathbf{x}}(d\mathbf{y})$.
- Let $K_{\mathcal{Z}}$ be a kernel for the complete data $\mathbf{z} = (\mathbf{x}, \mathbf{y})$
- Then the following kernel is a valid kernel on \mathcal{X} , called a marginalized kernel (Tsuda et al., 2002):

$$\begin{aligned} K_{\mathcal{X}}(\mathbf{x}, \mathbf{x}') &:= E_{P_{\mathbf{x}}(d\mathbf{y}) \times P_{\mathbf{x}'}(d\mathbf{y}')} K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') \\ &= \int \int K_{\mathcal{Z}}((\mathbf{x}, \mathbf{y}), (\mathbf{x}', \mathbf{y}')) P_{\mathbf{x}}(d\mathbf{y}) P_{\mathbf{x}'}(d\mathbf{y}') . \end{aligned}$$

Example: HMM for normal/biased coin toss



- Normal (N) and biased (B) coins (not observed)
- Observed output are 0/1 with probabilities:

$$\begin{cases} \pi(0|N) = 1 - \pi(1|N) = 0.5, \\ \pi(0|B) = 1 - \pi(1|B) = 0.2. \end{cases}$$

- Example of realization (complete data):

NNNNNNBBBBBBBBBBNNNNNNNNNNNNBBBBBB
1001011101111010010111001111011

1-spectrum kernel on complete data

- If both $\mathbf{x} \in \mathcal{A}^*$ and $\mathbf{y} \in \mathcal{S}^*$ were observed, we might rather use the 1-spectrum kernel on the complete data $\mathbf{z} = (\mathbf{x}, \mathbf{y})$:

$$K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') = \sum_{(a,s) \in \mathcal{A} \times \mathcal{S}} n_{a,s}(\mathbf{z}) n_{a,s}(\mathbf{z}'),$$

where $n_{a,s}(\mathbf{x}, \mathbf{y})$ for $a = 0, 1$ and $s = N, B$ is the number of occurrences of s in \mathbf{y} which emit a in \mathbf{x} .

- Example:

$$\begin{aligned}\mathbf{z} &= 1001011101111010010111001111011, \\ \mathbf{z}' &= 0011010110011111011010111101100101,\end{aligned}$$

$$\begin{aligned}K_{\mathcal{Z}}(\mathbf{z}, \mathbf{z}') &= n_1(\mathbf{z}) n_1(\mathbf{z}') + n_1(\mathbf{z}) n_1(\mathbf{z}') + n_0(\mathbf{z}) n_0(\mathbf{z}') + n_0(\mathbf{z}) n_0(\mathbf{z}') \\ &= 7 \times 15 + 13 \times 6 + 9 \times 12 + 2 \times 1 = 293.\end{aligned}$$

1-spectrum marginalized kernel on observed data

- The marginalized kernel for observed data is:

$$\begin{aligned} K_{\mathcal{X}}(\mathbf{x}, \mathbf{x}') &= \sum_{\mathbf{y}, \mathbf{y}' \in \mathcal{S}^*} K_{\mathcal{Z}}((\mathbf{x}, \mathbf{y}), (\mathbf{x}', \mathbf{y}')) P(\mathbf{y}|\mathbf{x}) P(\mathbf{y}'|\mathbf{x}') \\ &= \sum_{(a,s) \in \mathcal{A} \times \mathcal{S}} \Phi_{a,s}(\mathbf{x}) \Phi_{a,s}(\mathbf{x}'), \end{aligned}$$

with

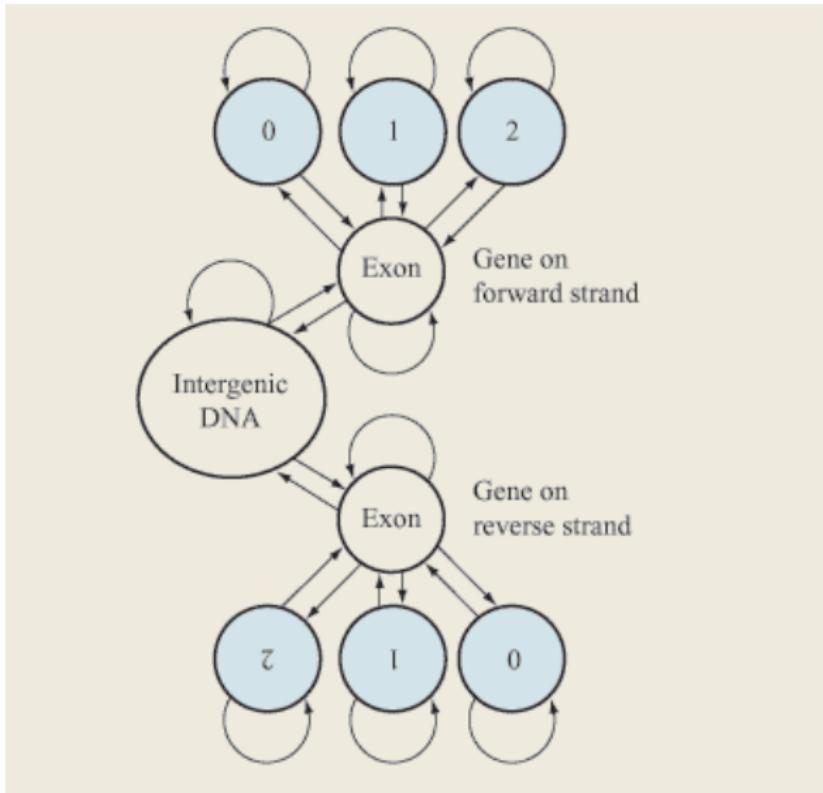
$$\Phi_{a,s}(\mathbf{x}) = \sum_{\mathbf{y} \in \mathcal{S}^*} P(\mathbf{y}|\mathbf{x}) n_{a,s}(\mathbf{x}, \mathbf{y})$$

Computation of the 1-spectrum marginalized kernel

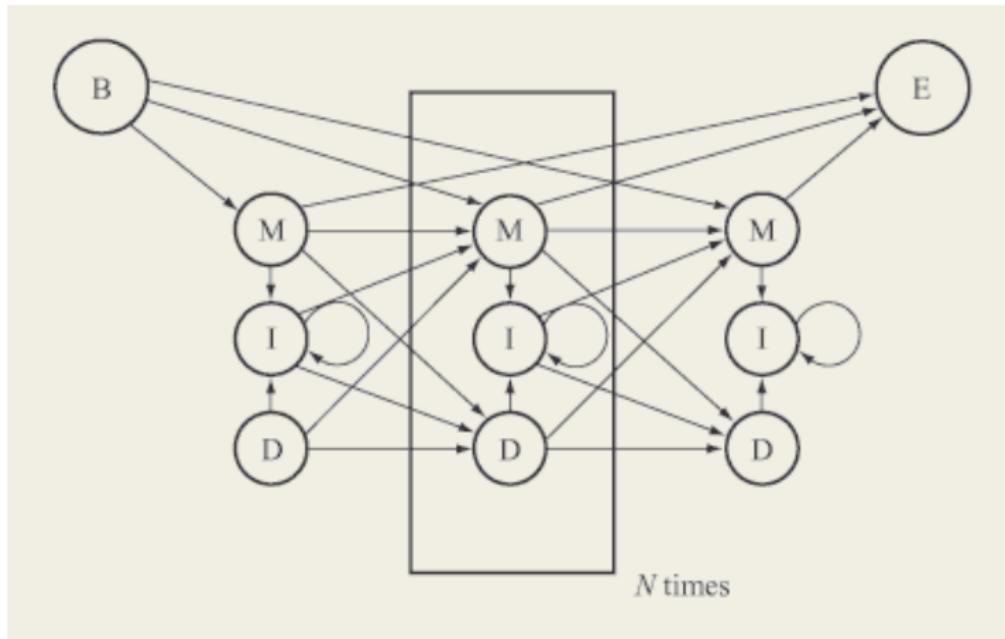
$$\begin{aligned}\Phi_{a,s}(\mathbf{x}) &= \sum_{\mathbf{y} \in \mathcal{S}^*} P(\mathbf{y}|\mathbf{x}) n_{a,s}(\mathbf{x}, \mathbf{y}) \\&= \sum_{\mathbf{y} \in \mathcal{S}^*} P(\mathbf{y}|\mathbf{x}) \left\{ \sum_{i=1}^n \delta(x_i, a) \delta(y_i, s) \right\} \\&= \sum_{i=1}^n \delta(x_i, a) \left\{ \sum_{\mathbf{y} \in \mathcal{S}^*} P(\mathbf{y}|\mathbf{x}) \delta(y_i, s) \right\} \\&= \sum_{i=1}^n \delta(x_i, a) P(y_i = s|\mathbf{x}).\end{aligned}$$

and $P(y_i = s|\mathbf{x})$ can be computed efficiently by forward-backward algorithm!

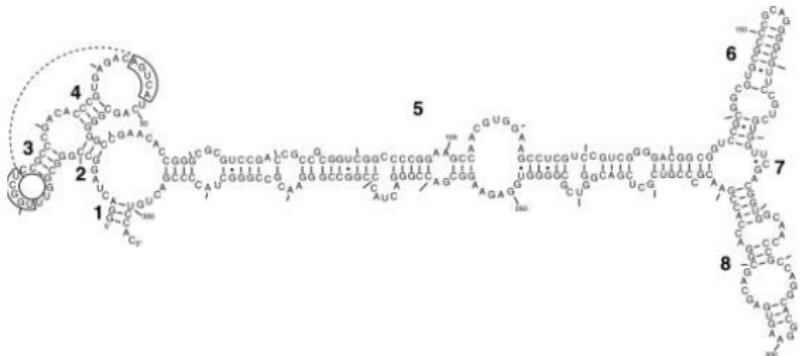
HMM example (DNA)



HMM example (protein)



SCFG for RNA sequences



SCFG rules

- $S \rightarrow SS$
- $S \rightarrow aSa$
- $S \rightarrow aS$
- $S \rightarrow a$

Marginalized kernel (Kin et al., 2002)

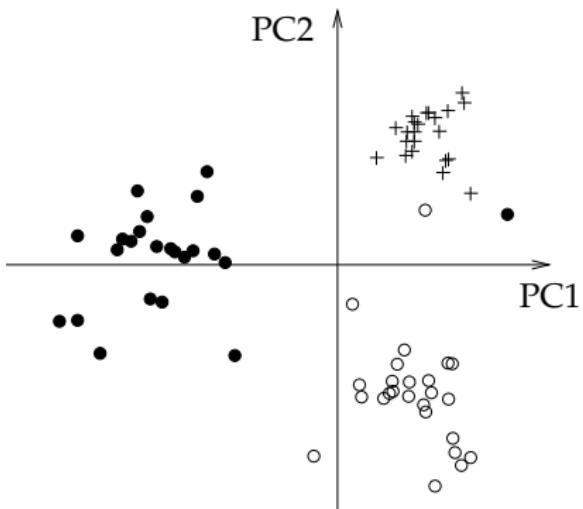
- Feature: number of occurrences of each (base,state) combination
- Marginalization using classical inside/outside algorithm

Marginalized kernels in practice

Examples

- Spectrum kernel on the hidden states of a HMM for **protein sequences** (Tsuda et al., 2002)
- Kernels for **RNA sequences** based on SCFG (Kin et al., 2002)
- Kernels for **graphs** based on random walks on graphs (Kashima et al., 2004)
- Kernels for **multiple alignments** based on phylogenetic models (Vert et al., 2006)

Marginalized kernels: example



A set of 74 human tRNA sequences is analyzed using a kernel for sequences (the second-order marginalized kernel based on SCFG). This set of tRNAs contains three classes, called Ala-AGC (*white circles*), Asn-GTT (*black circles*) and Cys-GCA (*plus symbols*) (from Tsuda et al., 2002).

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- **Kernels for biological sequences**
 - Motivations and history of genomics
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 - Kernels on graphs

Sequence alignment

Motivation

How to compare 2 sequences?

$$x_1 = \text{CGGSLIAMMWFGV}$$

$$x_2 = \text{CLIVMMNRLMWFGV}$$

Find a good **alignment**:

CGGSLIAMM	-----	WFGV
.		
C-----LIVMMNRLMWFGV		

Alignment score

In order to quantify the relevance of an alignment π , define:

- a substitution matrix $S \in \mathbb{R}^{\mathcal{A} \times \mathcal{A}}$
- a gap penalty function $g : \mathbb{N} \rightarrow \mathbb{R}$

Any alignment is then scored as follows

CGGSLIAMM-----WFGV
...
C----LIVMMNRLMWFGV

$$\begin{aligned}s_{S,g}(\pi) = & S(C, C) + S(L, L) + S(I, I) + S(A, V) + 2S(M, M) \\ & + S(W, W) + S(F, F) + S(G, G) + S(V, V) - g(3) - g(4)\end{aligned}$$

Local alignment kernel

Smith-Waterman score (Smith and Waterman, 1981)

- The widely-used Smith-Waterman local alignment score is defined by:

$$SW_{S,g}(x, y) := \max_{\pi \in \Pi(x, y)} s_{S,g}(\pi).$$

- It is symmetric, but not positive definite...

Local alignment kernel

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LA kernel (Saigo et al., 2004)

The local alignment kernel:

$$K_{LA}^{(\beta)}(\mathbf{x}, \mathbf{y}) = \sum_{\pi \in \Pi(\mathbf{x}, \mathbf{y})} \exp(\beta s_{S,g}(\mathbf{x}, \mathbf{y}, \pi)),$$

is symmetric positive definite.

LA kernel is p.d.: proof (1/11)

Lemma

- If K_1 and K_2 are p.d. kernels, then:

$$K_1 + K_2,$$

$$K_1 K_2, \text{ and}$$

$$cK_1, \text{ for } c \geq 0,$$

are also p.d. kernels

- If $(K_i)_{i \geq 1}$ is a sequence of p.d. kernels that converges pointwisely to a function K :

$$\forall (\mathbf{x}, \mathbf{x}') \in \mathcal{X}^2, \quad K(\mathbf{x}, \mathbf{x}') = \lim_{n \rightarrow \infty} K_i(\mathbf{x}, \mathbf{x}'),$$

then K is also a p.d. kernel.

LA kernel is p.d.: proof (2/11)

Proof of lemma

Let A and B be $n \times n$ positive semidefinite matrices. By diagonalization of A :

$$A_{i,j} = \sum_{p=1}^n f_p(i) f_p(j)$$

for some vectors f_1, \dots, f_n . Then, for any $\alpha \in \mathbb{R}^n$:

$$\sum_{i,j=1}^n \alpha_i \alpha_j A_{i,j} B_{i,j} = \sum_{p=1}^n \sum_{i,j=1}^n \alpha_i f_p(i) \alpha_j f_p(j) B_{i,j} \geq 0.$$

The matrix $C_{i,j} = A_{i,j} B_{i,j}$ is therefore p.d. Other properties are obvious from definition. \square

LA kernel is p.d.: proof (3/11)

Lemma (direct sum and product of kernels)

Let $\mathcal{X} = \mathcal{X}_1 \times \mathcal{X}_2$. Let K_1 be a p.d. kernel on \mathcal{X}_1 , and K_2 be a p.d. kernel on \mathcal{X}_2 . Then the following functions are p.d. kernels on \mathcal{X} :

- the **direct sum**,

$$K((\mathbf{x}_1, \mathbf{x}_2), (\mathbf{y}_1, \mathbf{y}_2)) = K_1(\mathbf{x}_1, \mathbf{y}_1) + K_2(\mathbf{x}_2, \mathbf{y}_2),$$

- The **direct product**:

$$K((\mathbf{x}_1, \mathbf{x}_2), (\mathbf{y}_1, \mathbf{y}_2)) = K_1(\mathbf{x}_1, \mathbf{y}_1) K_2(\mathbf{x}_2, \mathbf{y}_2).$$

LA kernel is p.d.: proof (4/11)

Proof of lemma

If K_1 is a p.d. kernel, let $\Phi_1 : \mathcal{X}_1 \mapsto \mathcal{H}$ be such that:

$$K_1(\mathbf{x}_1, \mathbf{y}_1) = \langle \Phi_1(\mathbf{x}_1), \Phi_1(\mathbf{y}_1) \rangle_{\mathcal{H}}.$$

Let $\Phi : \mathcal{X}_1 \times \mathcal{X}_2 \rightarrow \mathcal{H}$ be defined by:

$$\Phi((\mathbf{x}_1, \mathbf{x}_2)) = \Phi_1(\mathbf{x}_1).$$

Then for $\mathbf{x} = (\mathbf{x}_1, \mathbf{x}_2)$ and $\mathbf{y} = (\mathbf{y}_1, \mathbf{y}_2) \in \mathcal{X}$, we get

$$\langle \Phi((\mathbf{x}_1, \mathbf{x}_2)), \Phi((\mathbf{y}_1, \mathbf{y}_2)) \rangle_{\mathcal{H}} = K_1(\mathbf{x}_1, \mathbf{x}_2),$$

which shows that $K(\mathbf{x}, \mathbf{y}) := K_1(\mathbf{x}_1, \mathbf{y}_1)$ is p.d. on $\mathcal{X}_1 \times \mathcal{X}_2$. The lemma follows from the properties of sums and products of p.d. kernels. \square

LA kernel is p.d.: proof (5/11)

Lemma: kernel for sets

Let K be a p.d. kernel on \mathcal{X} , and let $\mathcal{P}(\mathcal{X})$ be the set of finite subsets of \mathcal{X} . Then the function K_P on $\mathcal{P}(\mathcal{X}) \times \mathcal{P}(\mathcal{X})$ defined by:

$$\forall A, B \in \mathcal{P}(\mathcal{X}), \quad K_P(A, B) := \sum_{x \in A} \sum_{y \in B} K(x, y)$$

is a p.d. kernel on $\mathcal{P}(\mathcal{X})$.

LA kernel is p.d.: proof (6/11)

Proof of lemma

Let $\Phi : \mathcal{X} \mapsto \mathcal{H}$ be such that

$$K(\mathbf{x}, \mathbf{y}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{\mathcal{H}}.$$

Then, for $A, B \in \mathcal{P}(\mathcal{X})$, we get:

$$\begin{aligned} K_P(A, B) &= \sum_{\mathbf{x} \in A} \sum_{\mathbf{y} \in B} \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{\mathcal{H}} \\ &= \left\langle \sum_{\mathbf{x} \in A} \Phi(\mathbf{x}), \sum_{\mathbf{y} \in B} \Phi(\mathbf{y}) \right\rangle_{\mathcal{H}} \\ &= \langle \Phi_P(A), \Phi_P(B) \rangle_{\mathcal{H}}, \end{aligned}$$

with $\Phi_P(A) := \sum_{\mathbf{x} \in A} \Phi(\mathbf{x})$. \square

LA kernel is p.d.: proof (7/11)

Definition: Convolution kernel (Haussler, 1999)

Let K_1 and K_2 be two p.d. kernels for strings. The **convolution** of K_1 and K_2 , denoted $K_1 \star K_2$, is defined for any $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$ by:

$$K_1 \star K_2(\mathbf{x}, \mathbf{y}) := \sum_{\mathbf{x}_1 \mathbf{x}_2 = \mathbf{x}, \mathbf{y}_1 \mathbf{y}_2 = \mathbf{y}} K_1(\mathbf{x}_1, \mathbf{y}_1) K_2(\mathbf{x}_2, \mathbf{y}_2).$$

Lemma

If K_1 and K_2 are p.d. then $K_1 \star K_2$ is p.d..

LA kernel is p.d.: proof (8/11)

Proof of lemma

Let \mathcal{X} be the set of finite-length strings. For $\mathbf{x} \in \mathcal{X}$, let

$$R(\mathbf{x}) = \{(\mathbf{x}_1, \mathbf{x}_2) \in \mathcal{X} \times \mathcal{X} : \mathbf{x} = \mathbf{x}_1 \mathbf{x}_2\} \subset \mathcal{X} \times \mathcal{X}.$$

We can then write

$$K_1 * K_2(\mathbf{x}, \mathbf{y}) = \sum_{(\mathbf{x}_1, \mathbf{x}_2) \in R(\mathbf{x})} \sum_{(\mathbf{y}_1, \mathbf{y}_2) \in R(\mathbf{y})} K_1(\mathbf{x}_1, \mathbf{y}_1) K_2(\mathbf{x}_2, \mathbf{y}_2)$$

which is a p.d. kernel by the previous lemmas. \square

LA kernel is p.d.: proof (9/11)

3 basic string kernels

- The constant kernel:

$$K_0(\mathbf{x}, \mathbf{y}) := 1.$$

- A kernel for letters:

$$K_a^{(\beta)}(\mathbf{x}, \mathbf{y}) := \begin{cases} 0 & \text{if } |\mathbf{x}| \neq 1 \text{ where } |\mathbf{y}| \neq 1, \\ \exp(\beta S(\mathbf{x}, \mathbf{y})) & \text{otherwise.} \end{cases}$$

- A kernel for gaps:

$$K_g^{(\beta)}(\mathbf{x}, \mathbf{y}) = \exp[\beta(g(|\mathbf{x}|) + g(|\mathbf{y}|))].$$

LA kernel is p.d.: proof (10/11)

Remark

- $S : \mathcal{A}^2 \rightarrow \mathbb{R}$ is the similarity function between letters used in the alignment score. $K_a^{(\beta)}$ is only p.d. when the matrix:

$$(\exp(\beta s(a, b)))_{(a,b) \in \mathcal{A}^2}$$

is positive semidefinite (this is true for all β when s is **conditionally p.d.**)

- g is the gap penalty function used in alignment score. **The gap kernel is always p.d.** (with no restriction on g) because it can be written as:

$$K_g^{(\beta)}(\mathbf{x}, \mathbf{y}) = \exp(\beta g(|\mathbf{x}|)) \times \exp(\beta g(|\mathbf{y}|)) .$$

LA kernel is p.d.: proof (11/11)

Lemma

The local alignment kernel is a (limit) of convolution kernel:

$$K_{LA}^{(\beta)} = \sum_{n=0}^{\infty} K_0 \star \left(K_a^{(\beta)} \star K_g^{(\beta)} \right)^{(n-1)} \star K_a^{(\beta)} \star K_0.$$

As such it is p.d..

Proof (sketch)

- By induction on n (simple but long to write).
- See details in Vert et al. (2004).

LA kernel computation

- We assume an **affine gap penalty**:

$$\begin{cases} g(0) &= 0, \\ g(n) &= d + e(n - 1) \text{ si } n \geq 1, \end{cases}$$

- The LA kernel can then be computed by **dynamic programming** by:

$$K_{LA}^{(\beta)}(\mathbf{x}, \mathbf{y}) = 1 + X_2(|\mathbf{x}|, |\mathbf{y}|) + Y_2(|\mathbf{x}|, |\mathbf{y}|) + M(|\mathbf{x}|, |\mathbf{y}|),$$

where $M(i, j)$, $X(i, j)$, $Y(i, j)$, $X_2(i, j)$, and $Y_2(i, j)$ for $0 \leq i \leq |\mathbf{x}|$, and $0 \leq j \leq |\mathbf{y}|$ are defined recursively.

LA kernel is p.d.: proof (/)

Initialization

$$\begin{cases} M(i, 0) = M(0, j) = 0, \\ X(i, 0) = X(0, j) = 0, \\ Y(i, 0) = Y(0, j) = 0, \\ X_2(i, 0) = X_2(0, j) = 0, \\ Y_2(i, 0) = Y_2(0, j) = 0, \end{cases}$$

LA kernel is p.d.: proof (/)

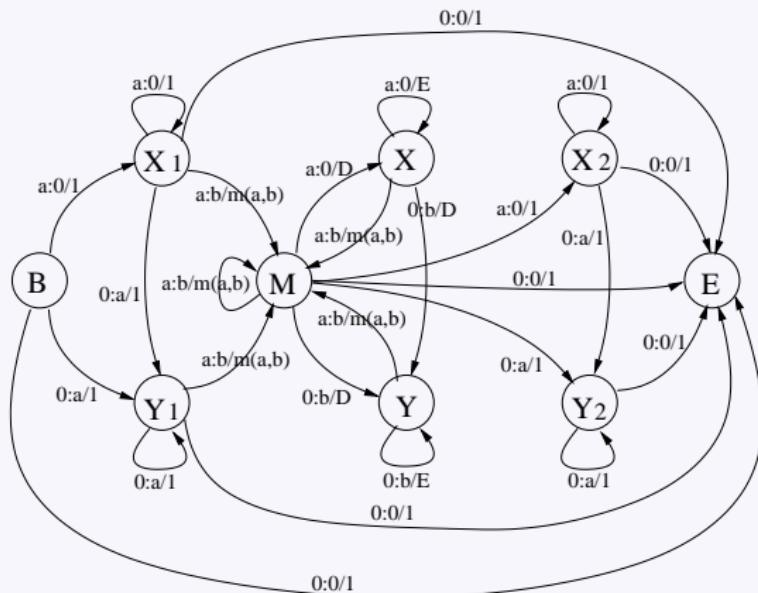
Recursion

For $i = 1, \dots, |\mathbf{x}|$ and $j = 1, \dots, |\mathbf{y}|$:

$$\begin{cases} M(i,j) &= \exp(\beta S(x_i, y_j)) \left[1 + X(i-1, j-1) \right. \\ &\quad \left. + Y(i-1, j-1) + M(i-1, j-1) \right], \\ X(i,j) &= \exp(\beta d) M(i-1, j) + \exp(\beta e) X(i-1, j), \\ Y(i,j) &= \exp(\beta d) [M(i, j-1) + X(i, j-1)] \\ &\quad + \exp(\beta e) Y(i, j-1), \\ X_2(i,j) &= M(i-1, j) + X_2(i-1, j), \\ Y_2(i,j) &= M(i, j-1) + X_2(i, j-1) + Y_2(i, j-1). \end{cases}$$

LA kernel in practice

- Implementation by a finite-state transducer in $O(|x| \times |x'|)$



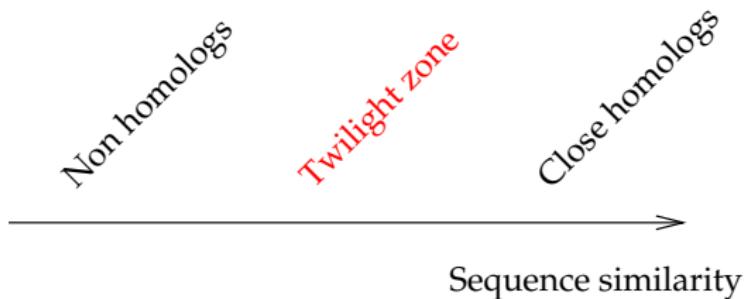
- In practice, values are too large (exponential scale) so taking its logarithm is a safer choice (but not p.d. anymore!)

Outline

5 The Kernel Jungle

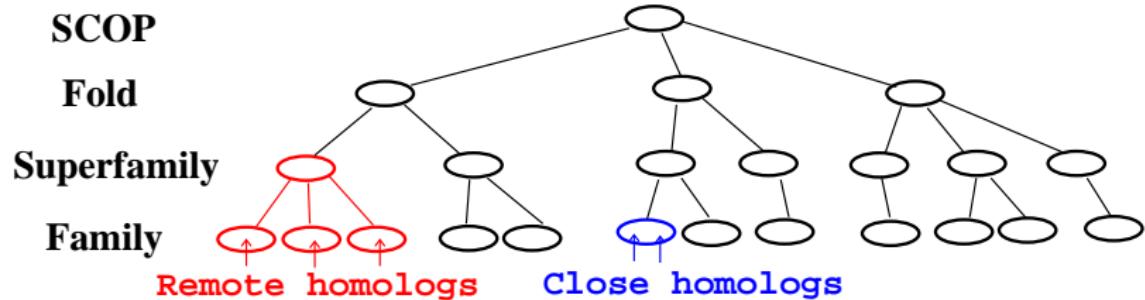
- Green, Mercer, Herglotz, Bochner and friends
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Remote homology



- Homologs have **common ancestors**
- Structures and functions are more conserved than sequences
- **Remote homologs** can not be detected by direct sequence comparison

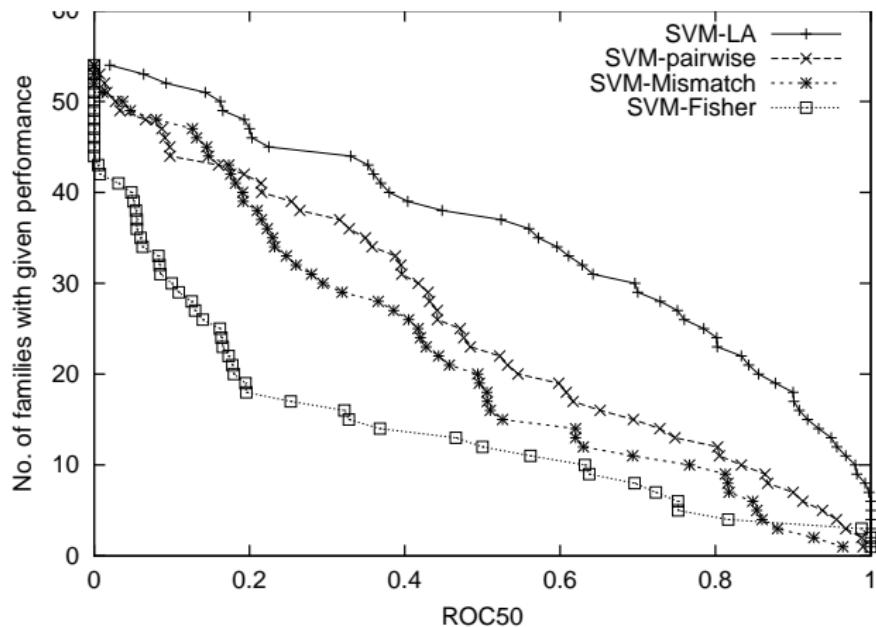
SCOP database



A benchmark experiment

- **Goal:** recognize directly the superfamily
- **Training:** for a sequence of interest, positive examples come from the same superfamily, but different families. Negative from other superfamilies.
- **Test:** predict the superfamily.

Difference in performance



Performance on the SCOP superfamily recognition benchmark (from Saigo et al., 2004).

String kernels: Summary

- A variety of principles for string kernel design have been proposed.
- Good **kernel design** is **important** for each data and each task.
Performance is not the only criterion.
- Still an **art**, although principled ways have started to emerge.
- **Fast implementation** with string algorithms is often possible.
- Their application goes well beyond computational biology.

Outline

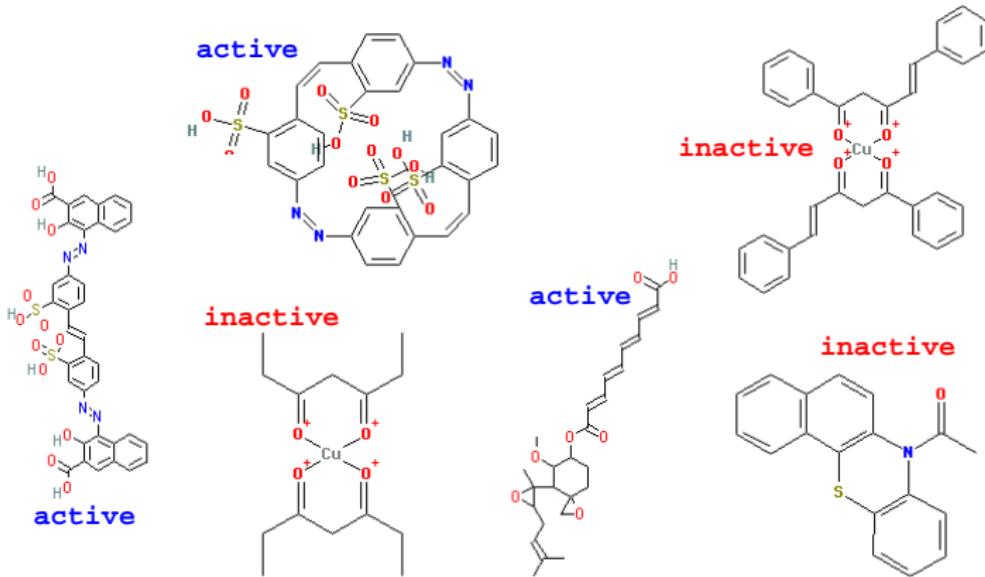
- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
 - Green, Mercer, Herglotz, Bochner and friends
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 - **Kernels for graphs**
 - Kernels on graphs
- 6 Open Problems and Research Topics

Outline

5 The Kernel Jungle

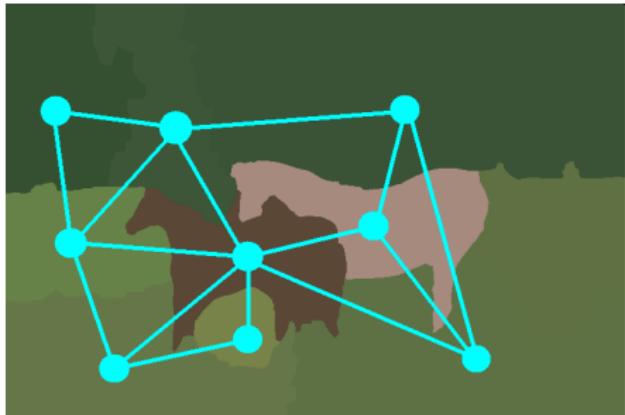
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Virtual screening for drug discovery



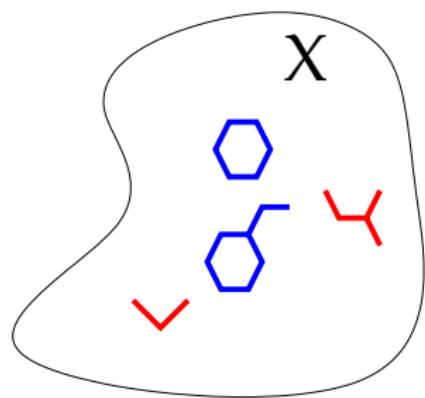
NCI AIDS screen results (from <http://cactus.nci.nih.gov>).

Image retrieval and classification



From Harchaoui and Bach (2007).

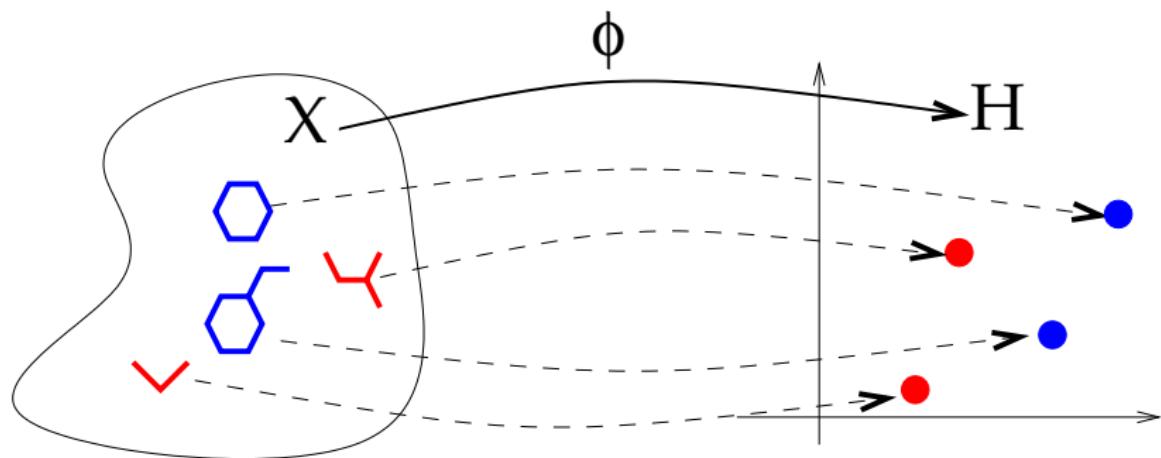
Our approach



Our approach

- ① Represent each graph \mathbf{x} in \mathcal{X} by a vector $\Phi(\mathbf{x}) \in \mathcal{H}$, either **explicitly** or **implicitly** through the kernel

$$K(\mathbf{x}, \mathbf{x}') = \Phi(\mathbf{x})^\top \Phi(\mathbf{x}').$$

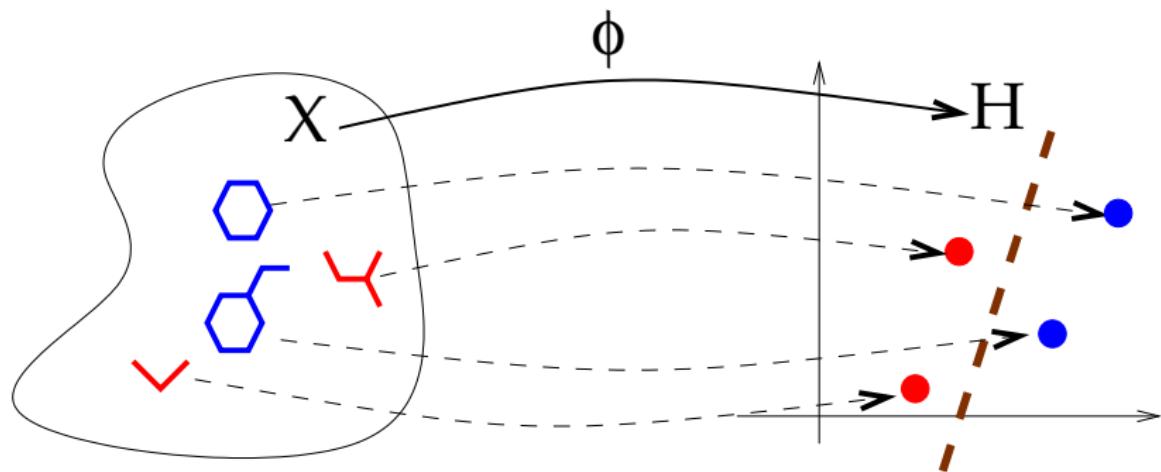


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$$K(\mathbf{x}, \mathbf{x}') = \Phi(\mathbf{x})^\top \Phi(\mathbf{x}').$$

- ② Use a linear method for classification in \mathcal{H} .



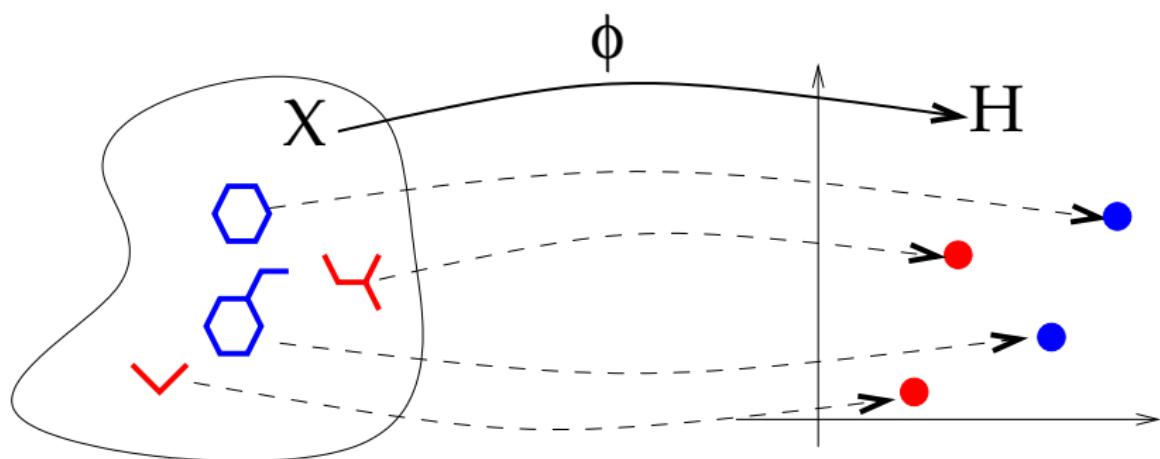
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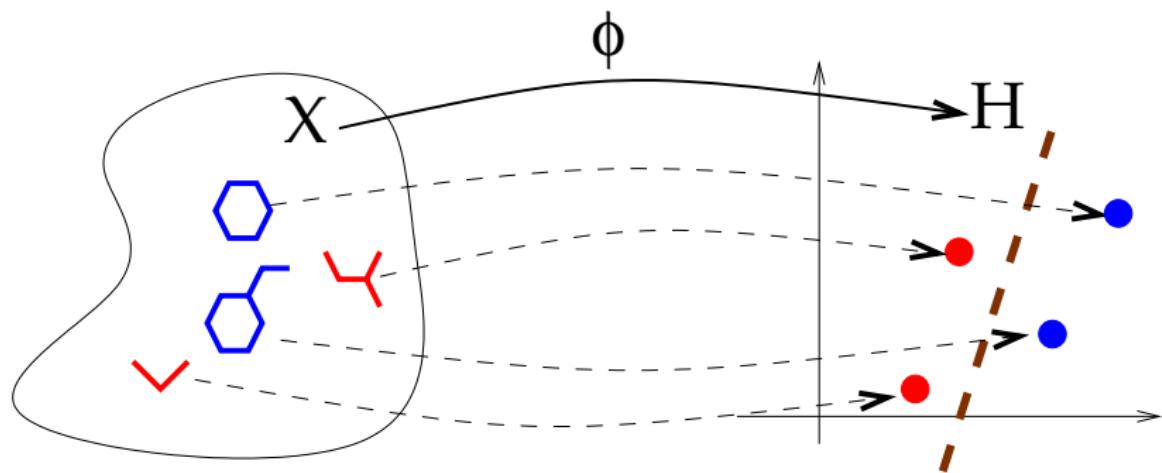
The approach

- ① Represent explicitly each graph x by a **vector of fixed dimension** $\Phi(x) \in \mathbb{R}^p$.



The approach

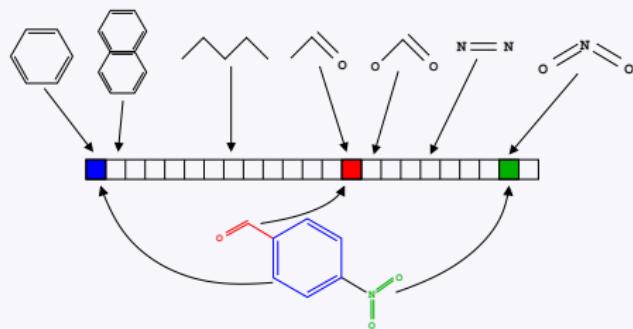
- ① Represent explicitly each graph x by a vector of fixed dimension $\Phi(x) \in \mathbb{R}^p$.
- ② Use an algorithm for regression or pattern recognition in \mathbb{R}^p .



Example

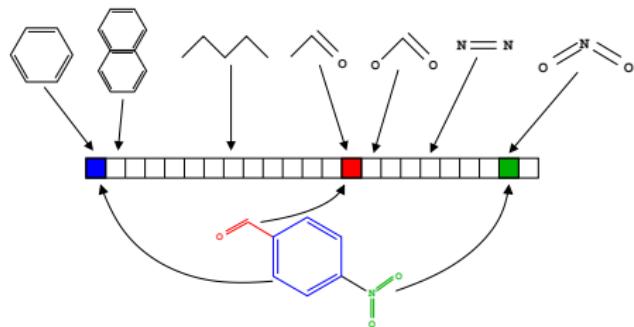
2D structural keys in chemoinformatics

- Index a molecule by a binary fingerprint defined by a limited set of **predefined** structures



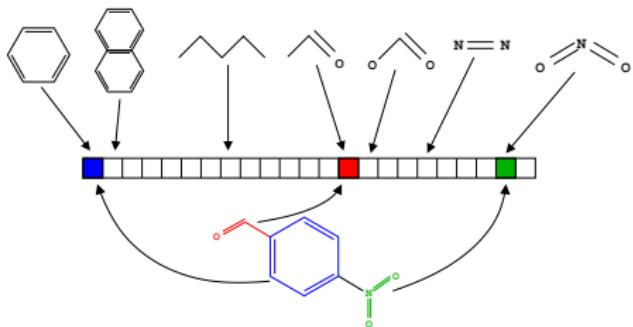
- Use a machine learning algorithm such as SVM, k NN, PLS, decision tree, etc.

Challenge: which descriptors (patterns)?



- **Expressiveness:** they should retain as much information as possible from the graph
- **Computation:** they should be fast to compute
- **Large dimension** of the vector representation: memory storage, speed, statistical issues

Indexing by substructures

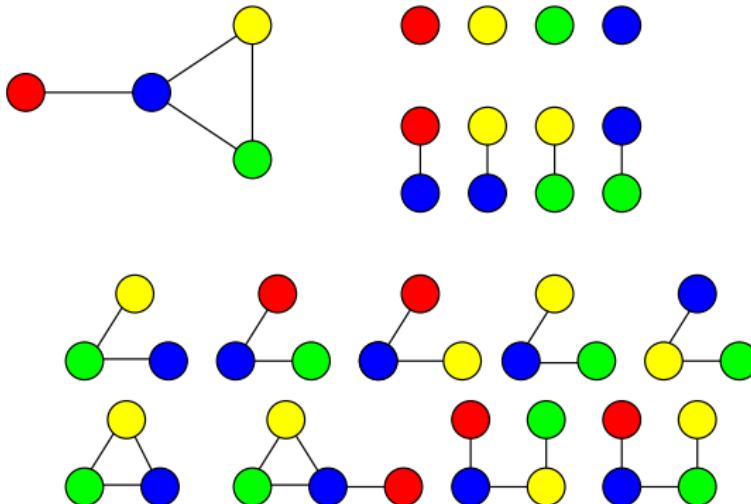


- Often we believe that **the presence or absence of particular substructures** may be important predictive patterns
- Hence it makes sense to represent a graph by **features** that indicate the presence (or the number of occurrences) of these substructures
- However, detecting the presence of particular substructures may be **computationally challenging**...

Subgraphs

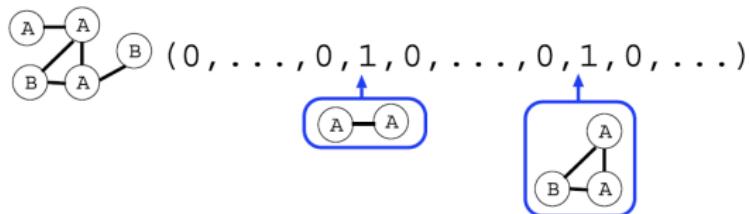
Definition

A **subgraph** of a graph (V, E) is a graph (V', E') with $V' \subset V$ and $E' \subset E$.

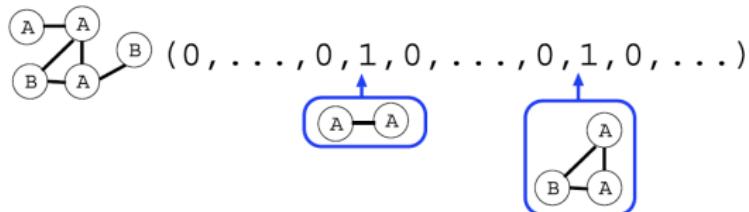


A graph and all its connected subgraphs.

Indexing by all subgraphs?



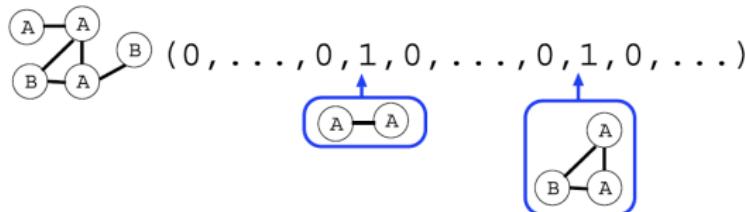
Indexing by all subgraphs?



Theorem

Computing all subgraph occurrences is NP-hard.

Indexing by all subgraphs?



Theorem

Computing all subgraph occurrences is **NP-hard**.

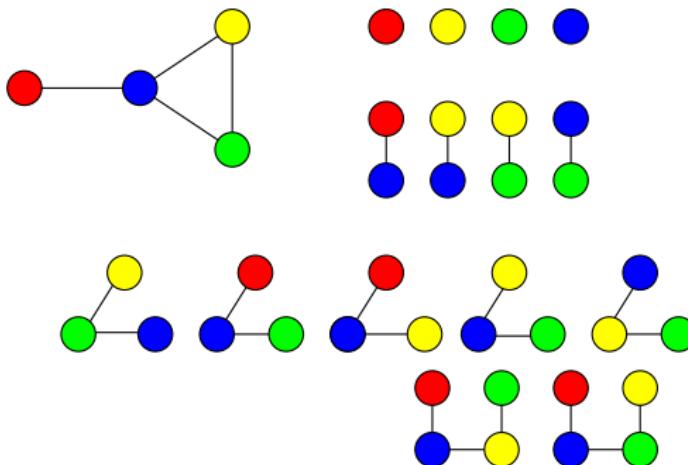
Proof

- The linear graph of size n is a subgraph of a graph X with n vertices iff X has a Hamiltonian path;
- The decision problem whether a graph has a Hamiltonian path is NP-complete.

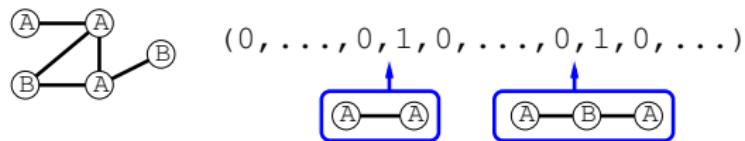
Paths

Definition

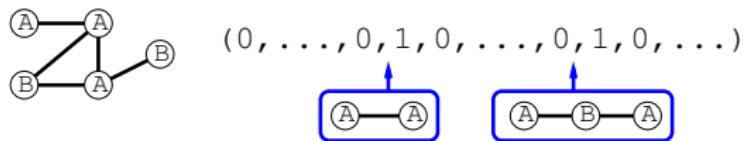
- A **path** of a graph (V, E) is a sequence of **distinct vertices** $v_1, \dots, v_n \in V$ ($i \neq j \implies v_i \neq v_j$) such that $(v_i, v_{i+1}) \in E$ for $i = 1, \dots, n - 1$.
- Equivalently the paths are the **linear subgraphs**.



Indexing by all paths?



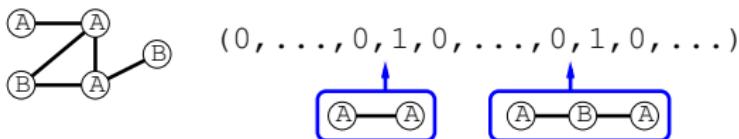
Indexing by all paths?



Theorem

Computing all path occurrences is NP-hard.

Indexing by all paths?



Theorem

Computing all path occurrences is **NP-hard**.

Proof

Same as for subgraphs.

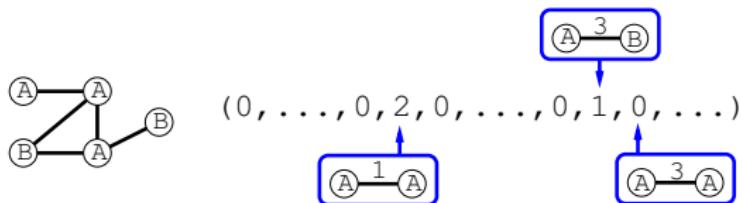
Indexing by what?

Substructure selection

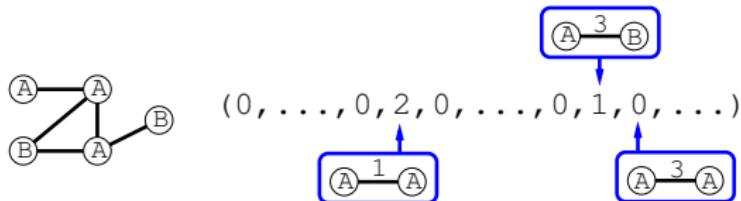
We can imagine more limited sets of substructures that lead to more computationnally efficient indexing (non-exhaustive list)

- substructures selected by domain knowledge (MDL fingerprint)
- all paths up to length k (Openeye fingerprint, Nicholls 2005)
- all shortest path lengths (Borgwardt and Kriegel, 2005)
- all subgraphs up to k vertices (graphlet kernel, Shervashidze et al., 2009)
- all frequent subgraphs in the database (Helma et al., 2004)

Example: Indexing by all shortest path lengths and their endpoint labels



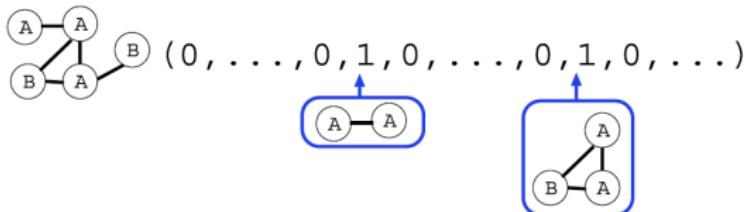
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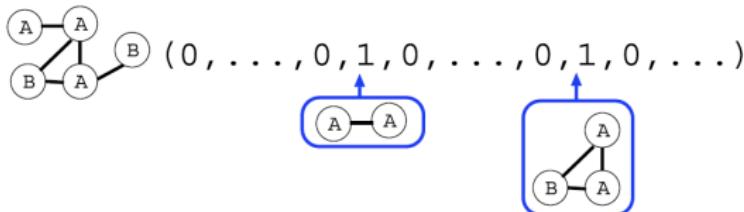
Properties (Borgwardt and Kriegel, 2005)

- There are $O(n^2)$ shortest paths.
- The vector of counts can be computed in $O(n^3)$ with the Floyd-Warshall algorithm.

Example: Indexing by all subgraphs up to k vertices



Example: Indexing by all subgraphs up to k vertices



Properties (Shervashidze et al., 2009)

- Naive enumeration scales as $O(n^k)$.
- Enumeration of connected graphlets in $O(nd^{k-1})$ for graphs with degree $\leq d$ and $k \leq 5$.
- Randomly sample subgraphs if enumeration is infeasible.

Summary

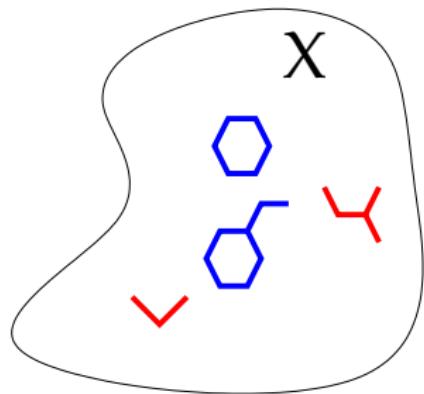
- Explicit computation of substructure occurrences can be **computationnally prohibitive** (subgraphs, paths);
- Several ideas to **reduce** the set of substructures considered;
- In practice, NP-hardness may not be so prohibitive (e.g., graphs with small degrees), the strategy followed should depend on the data considered.

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- Kernels for biological sequences
- **Kernels for graphs**
 - Motivation
 - Explicit enumeration of features
 - **Challenges**
 - Walk-based kernels
 - Applications
 - Kernels on graphs

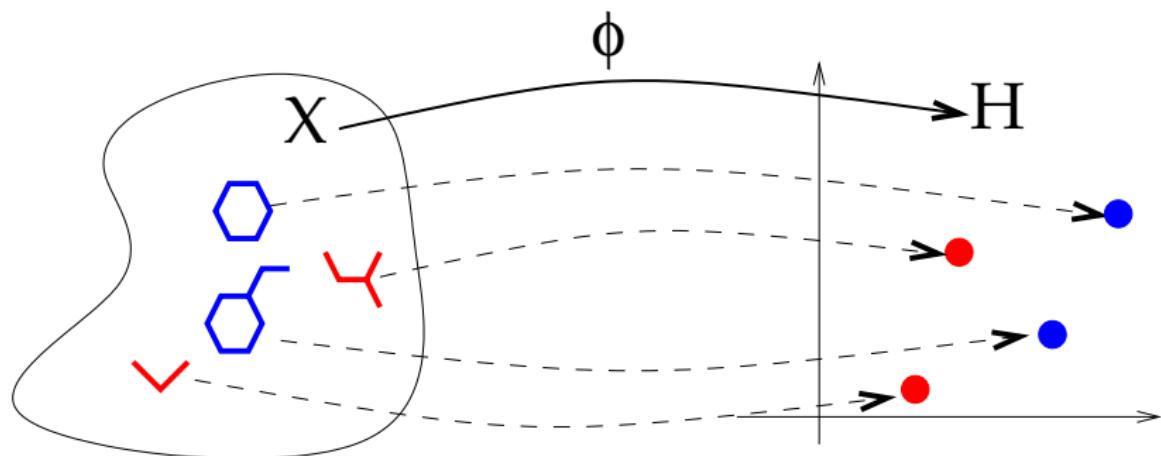
The idea



The idea

- ① Represent **implicitly** each graph \mathbf{x} in \mathcal{X} by a vector $\Phi(\mathbf{x}) \in \mathcal{H}$ through the kernel

$$K(\mathbf{x}, \mathbf{x}') = \Phi(\mathbf{x})^\top \Phi(\mathbf{x}').$$

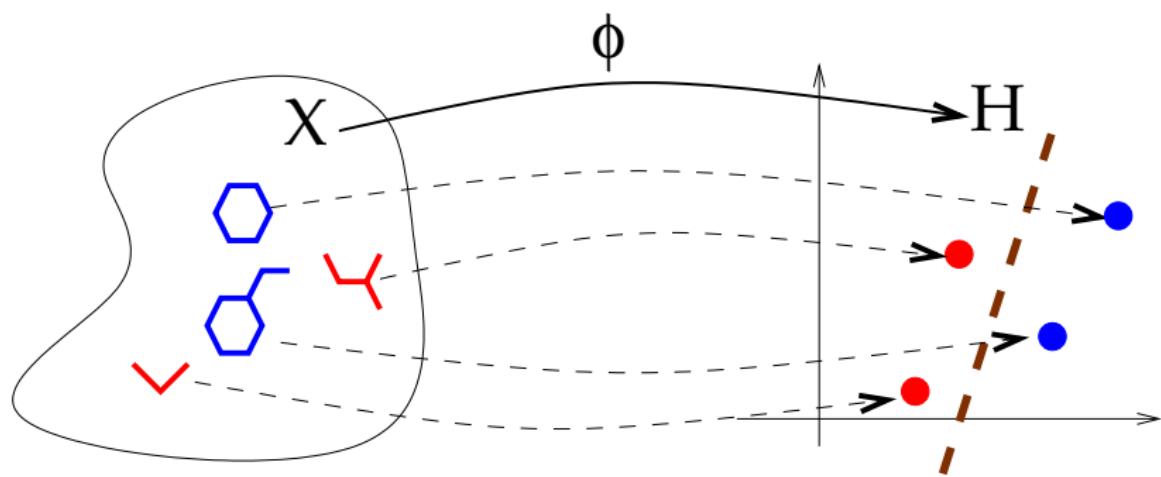


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$$K(\mathbf{x}, \mathbf{x}') = \Phi(\mathbf{x})^\top \Phi(\mathbf{x}').$$

- ② Use a kernel method for classification in \mathcal{H} .



Expressiveness vs Complexity

Definition: Complete graph kernels

A graph kernel is **complete** if it distinguishes non-isomorphic graphs, i.e.:

$$\forall G_1, G_2 \in \mathcal{X}, \quad d_K(G_1, G_2) = 0 \implies G_1 \simeq G_2.$$

Equivalently, $\Phi(G_1) \neq \Phi(G_2)$ if G_1 and G_2 are not isomorphic.

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Equivalently, $\Phi(G_1) \neq \Phi(G_2)$ if G_1 and G_2 are not isomorphic.

Expressiveness vs Complexity trade-off

- If a graph kernel is not complete, then there is **no hope** to learn all possible functions over \mathcal{X} : the kernel is not **expressive** enough.
- On the other hand, kernel **computation** must be **tractable**, i.e., no more than polynomial (with small degree) for practical applications.
- Can we define **tractable** and **expressive** graph kernels?

Complexity of complete kernels

Proposition (Gärtner et al., 2003)

Computing **any complete graph kernel** is at least as hard as the graph isomorphism problem.

Complexity of complete kernels

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Proof

- For any kernel K the complexity of computing d_K is the same as the complexity of computing K , because:

$$d_K(G_1, G_2)^2 = K(G_1, G_1) + K(G_2, G_2) - 2K(G_1, G_2).$$

- If K is a complete graph kernel, then computing d_K solves the graph isomorphism problem ($d_K(G_1, G_2) = 0$ iff $G_1 \simeq G_2$). \square

Subgraph kernel

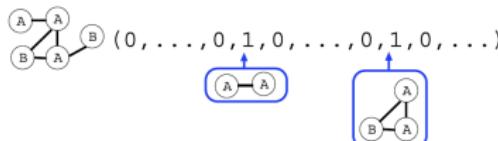
Definition

- Let $(\lambda_G)_{G \in \mathcal{X}}$ be a set or **nonnegative** real-valued weights
- For any graph $G \in \mathcal{X}$ and any connected graph $H \in \mathcal{X}$, let

$$\Phi_H(G) = |\{G' \text{ is a subgraph of } G : G' \simeq H\}|.$$

- The **subgraph kernel** between any two graphs G_1 and $G_2 \in \mathcal{X}$ is defined by:

$$K_{\text{subgraph}}(G_1, G_2) = \sum_{\substack{H \in \mathcal{X} \\ H \text{ connected}}} \lambda_H \Phi_H(G_1) \Phi_H(G_2).$$



Subgraph kernel complexity

Proposition (Gärtner et al., 2003)

Computing the subgraph kernel is **NP-hard**.

Subgraph kernel complexity

Proposition (Gärtner et al., 2003)

Computing the subgraph kernel is **NP-hard**.

Proof (1/2)

- Let P_n be the path graph with n vertices.
- Subgraphs of P_n are path graphs:

$$\Phi(P_n) = ne_{P_1} + (n - 1)e_{P_2} + \dots + e_{P_n}.$$

- The vectors $\Phi(P_1), \dots, \Phi(P_n)$ are linearly independent, therefore:

$$e_{P_n} = \sum_{i=1}^n \alpha_i \Phi(P_i),$$

where the coefficients α_i can be found in polynomial time (solving an $n \times n$ triangular system).

Subgraph kernel complexity

Proposition (Gärtner et al., 2003)

Computing the subgraph kernel is **NP-hard**.

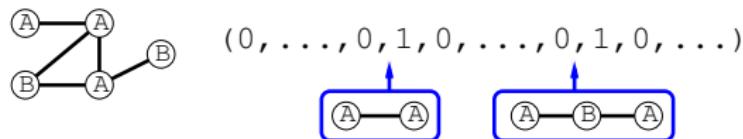
Proof (2/2)

- If G is a graph with n vertices, then it has a path that visits each node exactly once (Hamiltonian path) if and only if $\Phi(G)^\top e_{P_n} > 0$, i.e.,

$$\Phi(G)^\top \left(\sum_{i=1}^n \alpha_i \Phi(P_i) \right) = \sum_{i=1}^n \alpha_i K_{\text{subgraph}}(G, P_i) > 0.$$

- The decision problem whether a graph has a Hamiltonian path is NP-complete. \square

Path kernel



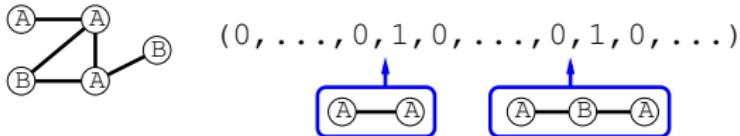
Definition

The **path kernel** is the subgraph kernel restricted to paths, i.e.,

$$K_{\text{path}}(G_1, G_2) = \sum_{H \in \mathcal{P}} \lambda_H \Phi_H(G_1) \Phi_H(G_2),$$

where $\mathcal{P} \subset \mathcal{X}$ is the set of path graphs.

Path kernel



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Proposition (Gärtner et al., 2003)

Computing the path kernel is **NP-hard**.

Summary

Expressiveness vs Complexity trade-off

- It is **intractable** to compute **complete graph kernels**.
- It is **intractable** to compute the **subgraph kernels**.
- Restricting subgraphs to be linear does not help: it is also **intractable** to compute the **path kernel**.
- One approach to define polynomial time computable graph kernels is to have the feature space be made up of graphs **homomorphic** to subgraphs, e.g., to consider **walks** instead of paths.

Outline

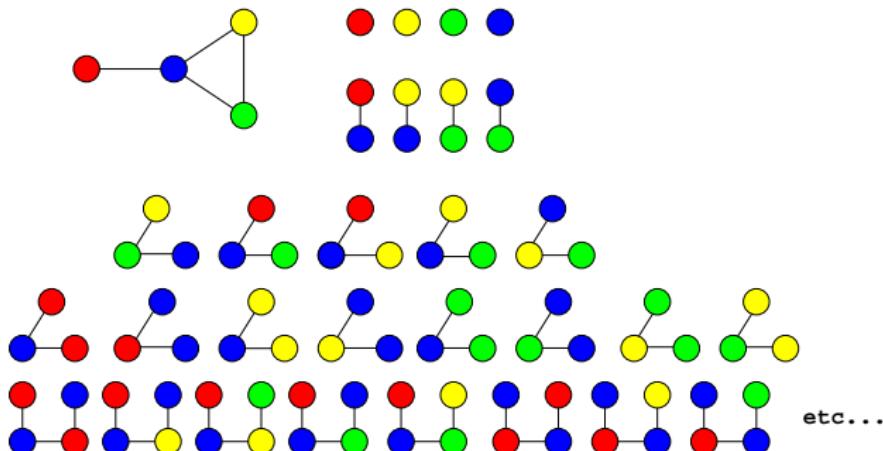
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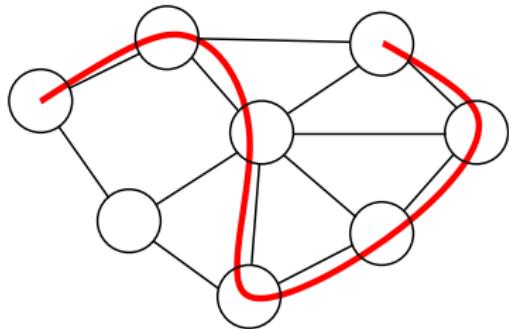
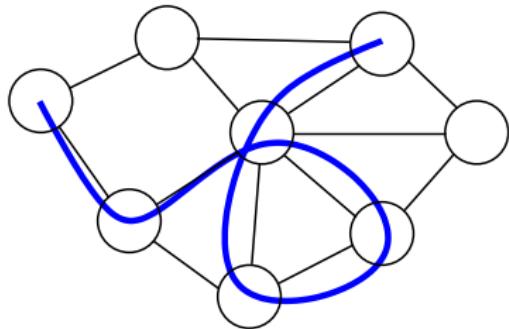
Walks

Definition

- A **walk** of a graph (V, E) is sequence of $v_1, \dots, v_n \in V$ such that $(v_i, v_{i+1}) \in E$ for $i = 1, \dots, n - 1$.
- We note $\mathcal{W}_n(G)$ the set of walks with n vertices of the graph G , and $\mathcal{W}(G)$ the set of all walks.



Walks \neq paths



Walk kernel

Definition

- Let \mathcal{S}_n denote the set of all possible **label sequences** of walks of length n (including vertex and edge labels), and $\mathcal{S} = \cup_{n \geq 1} \mathcal{S}_n$.
- For any graph \mathcal{X} let a **weight** $\lambda_G(w)$ be associated to each walk $w \in \mathcal{W}(G)$.
- Let the feature vector $\Phi(G) = (\Phi_s(G))_{s \in \mathcal{S}}$ be defined by:

$$\Phi_s(G) = \sum_{w \in \mathcal{W}(G)} \lambda_G(w) \mathbf{1} (s \text{ is the label sequence of } w).$$

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- A walk kernel is a graph kernel defined by:

$$K_{\text{walk}}(G_1, G_2) = \sum_{s \in \mathcal{S}} \Phi_s(G_1) \Phi_s(G_2).$$

Walk kernel examples

Examples

- The n th-order walk kernel is the walk kernel with $\lambda_G(w) = 1$ if the length of w is n , 0 otherwise. It compares two graphs through their common walks of length n .

Walk kernel examples

Examples

- The *n*th-order walk kernel is the walk kernel with $\lambda_G(w) = 1$ if the length of w is n , 0 otherwise. It compares two graphs through their common walks of length n .
- The random walk kernel is obtained with $\lambda_G(w) = P_G(w)$, where P_G is a Markov random walk on G . In that case we have:

$$K(G_1, G_2) = P(\text{label}(W_1) = \text{label}(W_2)),$$

where W_1 and W_2 are two independent random walks on G_1 and G_2 , respectively (Kashima et al., 2003).

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- The geometric walk kernel is obtained (when it converges) with $\lambda_G(w) = \beta^{\text{length}(w)}$, for $\beta > 0$. In that case the feature space is of infinite dimension (Gärtner et al., 2003).

Computation of walk kernels

Proposition

These three kernels (n th-order, random and geometric walk kernels) can be computed efficiently in **polynomial time**.

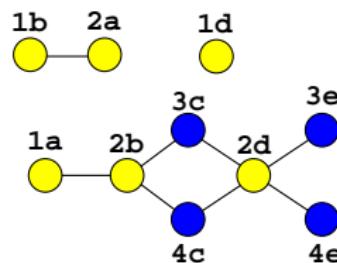
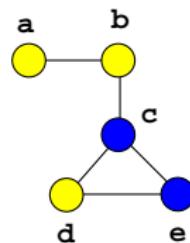
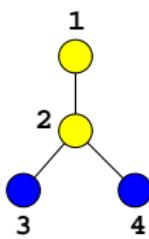
Product graph

Definition

Let $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ be two graphs with labeled vertices.

The **product graph** $G = G_1 \times G_2$ is the graph $G = (V, E)$ with:

- ① $V = \{(v_1, v_2) \in V_1 \times V_2 : v_1 \text{ and } v_2 \text{ have the same label}\}$,
- ② $E = \{((v_1, v_2), (v'_1, v'_2)) \in V \times V : (v_1, v'_1) \in E_1 \text{ and } (v_2, v'_2) \in E_2\}$.



G_1

G_2

$G_1 \times G_2$

Walk kernel and product graph

Lemma

There is a **bijection** between:

- ① The **pairs of walks** $w_1 \in \mathcal{W}_n(G_1)$ and $w_2 \in \mathcal{W}_n(G_2)$ with the **same label sequences**,
- ② The **walks on the product graph** $w \in \mathcal{W}_n(G_1 \times G_2)$.

Walk kernel and product graph

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Corollary

$$\begin{aligned} K_{\text{walk}}(G_1, G_2) &= \sum_{s \in \mathcal{S}} \Phi_s(G_1) \Phi_s(G_2) \\ &= \sum_{(w_1, w_2) \in \mathcal{W}(G_1) \times \mathcal{W}(G_2)} \lambda_{G_1}(w_1) \lambda_{G_2}(w_2) \mathbf{1}(l(w_1) = l(w_2)) \\ &= \sum_{w \in \mathcal{W}(G_1 \times G_2)} \lambda_{G_1 \times G_2}(w). \end{aligned}$$

Computation of the n th-order walk kernel

- For the n th-order walk kernel we have $\lambda_{G_1 \times G_2}(w) = 1$ if the length of w is n , 0 otherwise.
- Therefore:

$$K_{n\text{th-order}}(G_1, G_2) = \sum_{w \in \mathcal{W}_n(G_1 \times G_2)} 1.$$

- Let A be the adjacency matrix of $G_1 \times G_2$. Then we get:

$$K_{n\text{th-order}}(G_1, G_2) = \sum_{i,j} [A^n]_{i,j} = \mathbf{1}^\top A^n \mathbf{1}.$$

- Computation in $O(n|V_1||V_2|d_1 d_2)$, where d_i is the maximum degree of G_i .

Computation of random and geometric walk kernels

- In both cases $\lambda_G(w)$ for a walk $w = v_1 \dots v_n$ can be decomposed as:

$$\lambda_G(v_1 \dots v_n) = \lambda^i(v_1) \prod_{i=2}^n \lambda^t(v_{i-1}, v_i).$$

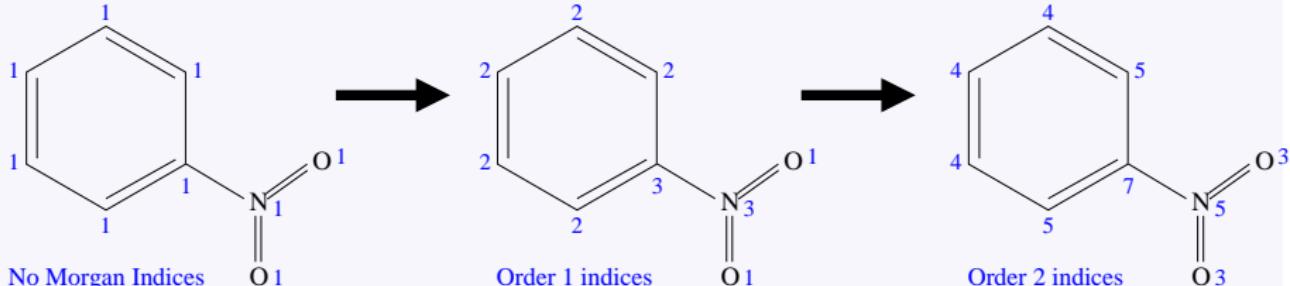
- Let Λ_i be the vector of $\lambda^i(v)$ and Λ_t be the matrix of $\lambda^t(v, v')$:

$$\begin{aligned} K_{\text{walk}}(G_1, G_2) &= \sum_{n=1}^{\infty} \sum_{w \in \mathcal{W}_n(G_1 \times G_2)} \lambda^i(v_1) \prod_{i=2}^n \lambda^t(v_{i-1}, v_i) \\ &= \sum_{n=0}^{\infty} \Lambda_i \Lambda_t^n \mathbf{1} \\ &= \color{red} \Lambda_i (I - \Lambda_t)^{-1} \mathbf{1} \end{aligned}$$

- Computation in $O(|V_1|^3 |V_2|^3)$.

Extensions 1: Label enrichment

Atom relabeling with the Morgan index (Mahé et al., 2004)

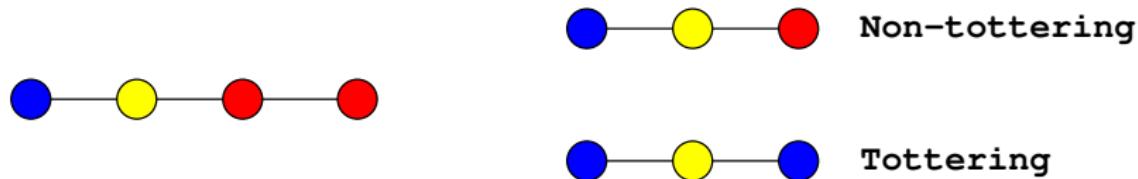


- Compromise between **fingerprints** and **structural keys**.
- Other **relabeling** schemes are possible.
- Faster computation with more labels (less matches implies a smaller product graph).

Extension 2: Non-tottering walk kernel

Tottering walks

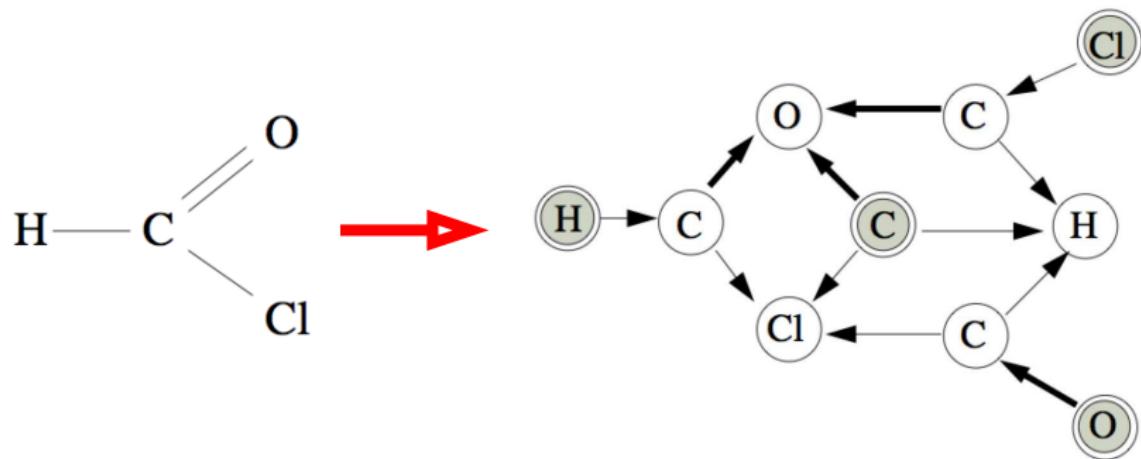
A **tottering walk** is a walk $w = v_1 \dots v_n$ with $v_i = v_{i+2}$ for some i .



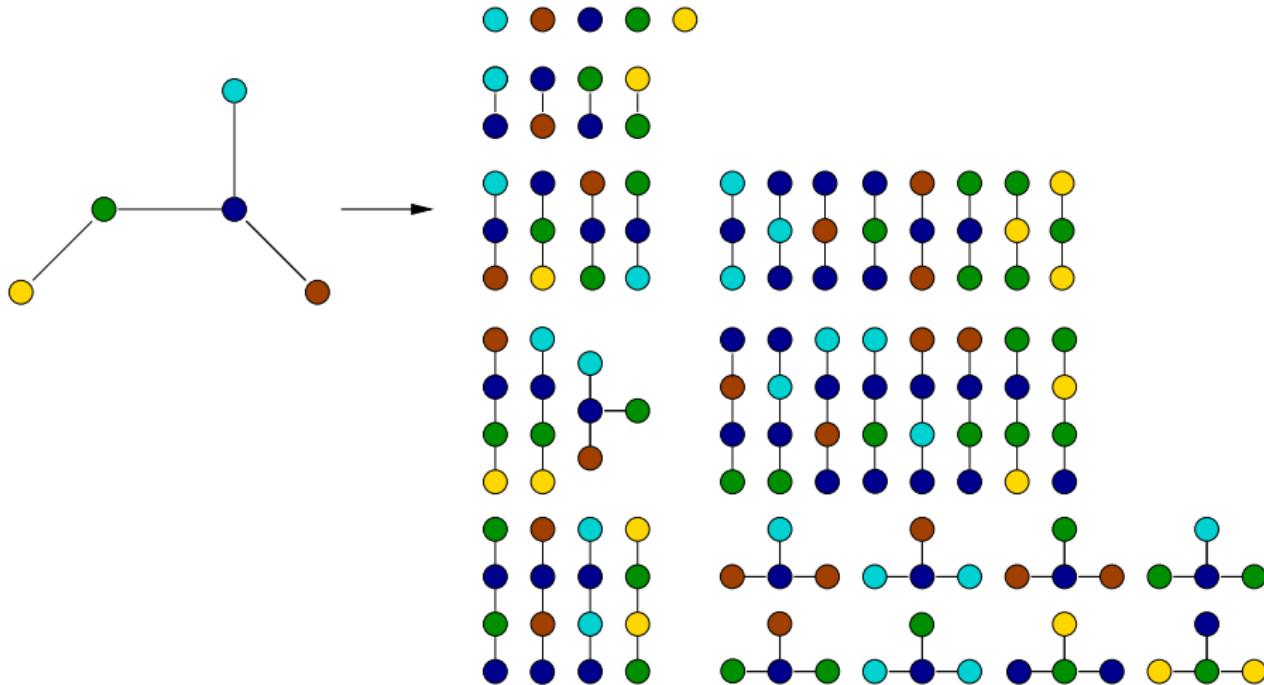
- Tottering walks seem **irrelevant** for many applications.
- Focusing on non-tottering walks is a way to get closer to the **path kernel** (e.g., equivalent on trees).

Computation of the non-tottering walk kernel (Mahé et al., 2005)

- Second-order Markov random walk to prevent tottering walks
- Written as a first-order Markov random walk on an augmented graph
- Normal walk kernel on the augmented graph (which is always a directed graph).

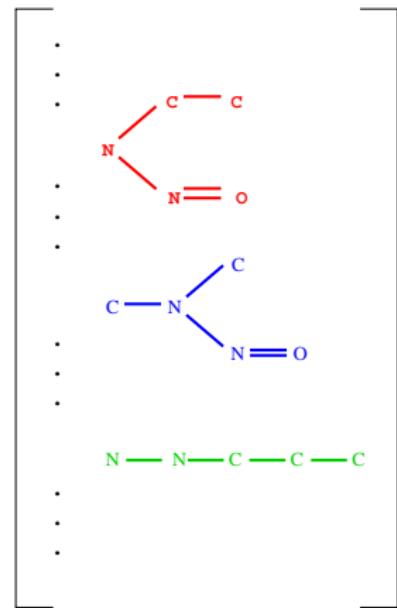
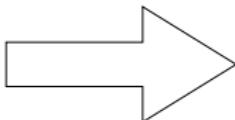
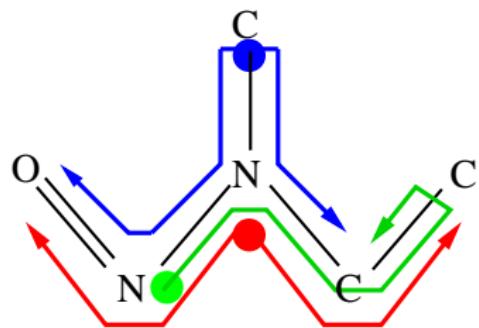


Extension 3: Subtree kernels



Remark: Here and in subsequent slides by *subtree* we mean a tree-like pattern with potentially repeated nodes and edges.

Example: Tree-like fragments of molecules



Computation of the subtree kernel (Ramon and Gärtner, 2003; Mahé and Vert, 2009)

- Like the walk kernel, amounts to computing the (weighted) number of subtrees in the **product graph**.
- Recursion: if $\mathcal{T}(v, n)$ denotes the weighted number of subtrees of depth n rooted at the vertex v , then:

$$\mathcal{T}(v, n+1) = \sum_{R \subset \mathcal{N}(v)} \prod_{v' \in R} \lambda_t(v, v') \mathcal{T}(v', n),$$

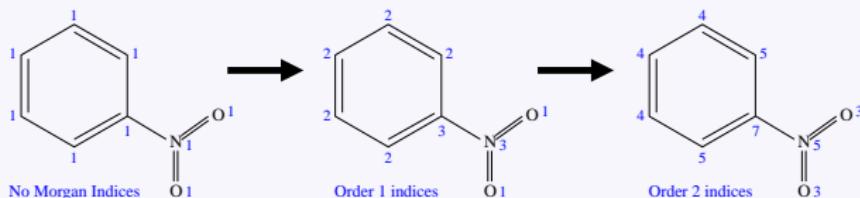
where $\mathcal{N}(v)$ is the set of neighbors of v .

- Can be combined with the non-tottering graph transformation as preprocessing to obtain the **non-tottering subtree kernel**.

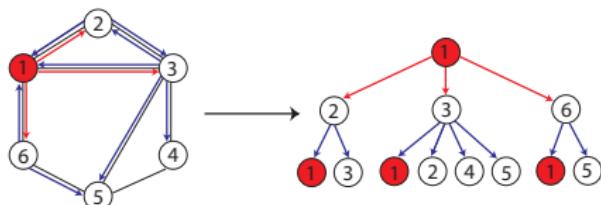
Back to label enrichment

Link between the Morgan index and subtrees

Recall the Morgan index:



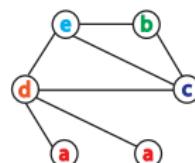
The Morgan index of order k at a node v in fact corresponds to the number of leaves in the k -th order full subtree pattern rooted at v .



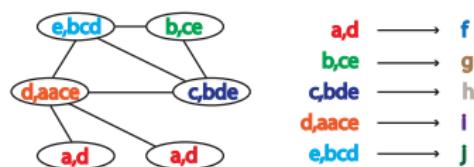
Label enrichment via the Weisfeiler-Lehman algorithm

A slightly more involved label enrichment strategy (Weisfeiler and Lehman, 1968) is exploited in the definition and computation of the Weisfeiler-Lehman subtree kernel (Shervashidze and Borgwardt, 2009).

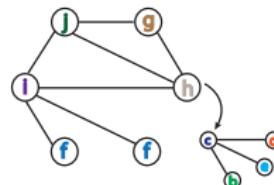
- ➊ Multiset-label determination and sorting



- ➋ Label compression



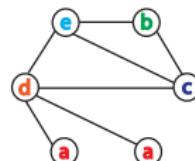
- ➌ Relabeling



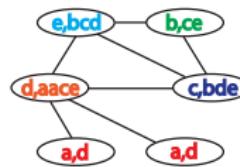
Label enrichment via the Weisfeiler-Lehman algorithm

A slightly more involved label enrichment strategy (Weisfeiler and Lehman, 1968) is exploited in the definition and computation of the Weisfeiler-Lehman subtree kernel (Shervashidze and Borgwardt, 2009).

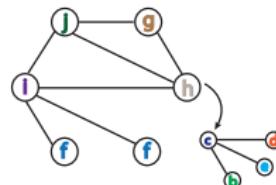
- ➊ Multiset-label determination and sorting



- ➋ Label compression

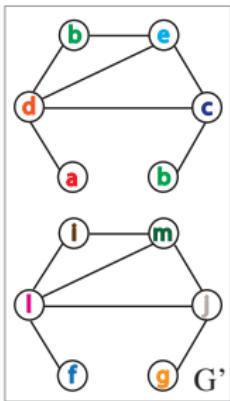
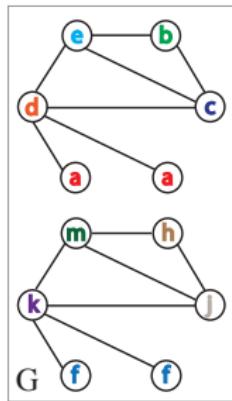


- ➌ Relabeling



Compressed labels represent full subtree patterns.

Weisfeiler-Lehman (WL) subtree kernel



$$\varphi_{WLsubtree}^{(1)}(G) = (2, 1, 1, 1, 1, 2, 0, 1, 0, 1, 1, 0, 1)$$

a b c d e f g h i j k l m

$$\varphi_{WLsubtree}^{(1)}(G') = (1, 2, 1, 1, 1, 1, 1, 1, 0, 1, 1, 0, 1)$$

a b c d e f g h i j k l m

Counts of
original
node labels

Counts of
compressed
node labels

Properties

- The WL features up to the k -th order are computed in $O(|E|k)$.
- Similarly to the Morgan index, the WL relabeling can be exploited in combination with any graph kernel (that takes into account categorical node labels) to make it more expressive (Shervashidze et al., 2011).

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- Kernels for biological sequences
- **Kernels for graphs**
 - Motivation
 - Explicit enumeration of features
 - Challenges
 - Walk-based kernels
 - **Applications**
- Kernels on graphs

Application in chemoinformatics (Mahé et al., 2005)

MUTAG dataset

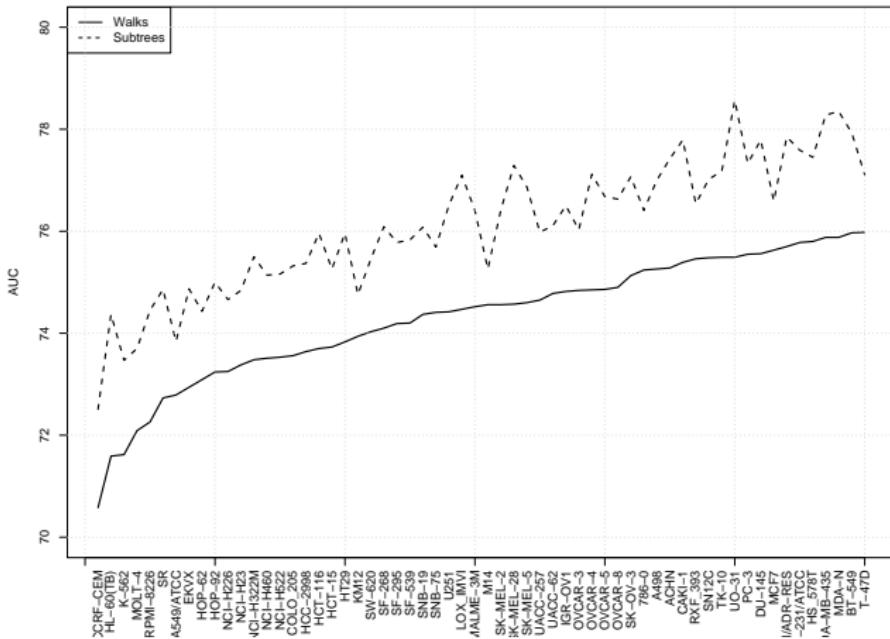
- aromatic/hetero-aromatic compounds
- high mutagenic activity / no mutagenic activity, assayed in *Salmonella typhimurium*.
- 188 compounds: 125 + / 63 -

Results

10-fold cross-validation accuracy

Method	Accuracy
Progol1	81.4%
2D kernel	91.2%

2D subtree vs walk kernels



Screening of inhibitors for 60 cancer cell lines.

Comparison of several graph feature extraction methods/kernels (Shervashidze et al., 2011)

10-fold cross-validation accuracy on graph classification problems in chemo- and bioinformatics:

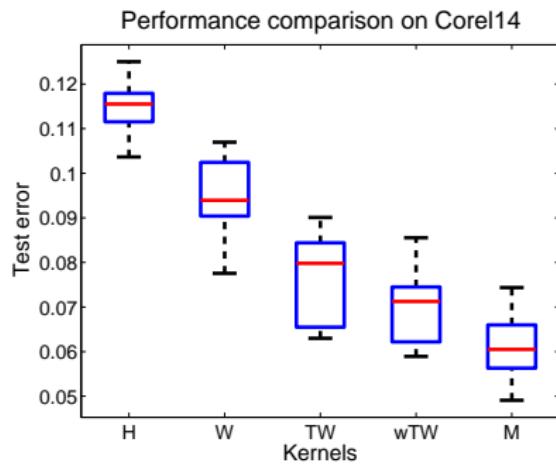
- NCI1 and NCI109 - active/inactive compounds in an anti-cancer screen
- ENZYMES - 6 types of enzymes from the BRENDA database

Method/Data Set	NCI1	NCI109	ENZYMES
WL subtree	82.19 (± 0.18)	82.46 (± 0.24)	52.22 (± 1.26)
WL shortest path	84.55 (± 0.36)	83.53 (± 0.30)	59.05 (± 1.05)
Ramon & Gärtner	61.86 (± 0.27)	61.67 (± 0.21)	13.35 (± 0.87)
Geometric p -walk	58.66 (± 0.28)	58.36 (± 0.94)	27.67 (± 0.95)
Geometric walk	64.34 (± 0.27)	63.51 (± 0.18)	21.68 (± 0.94)
Graphlet count	66.00 (± 0.07)	66.59 (± 0.08)	32.70 (± 1.20)
Shortest path	73.47 (± 0.11)	73.07 (± 0.11)	41.68 (± 1.79)

Image classification (Harchaoui and Bach, 2007)

COREL14 dataset

- 1400 natural images in 14 classes
- Compare kernel between histograms (H), walk kernel (W), subtree kernel (TW), weighted subtree kernel (wTW), and a combination (M).



Summary: graph kernels

What we saw

- Kernels do **not allow** to overcome the NP-hardness of subgraph patterns.
- They allow to work with approximate subgraphs (walks, subtrees) in infinite dimension, thanks to the **kernel trick**.
- However: using kernels makes it difficult to **come back to patterns** after the learning stage.

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
 - Green, Mercer, Herglotz, Bochner and friends
 - Kernels for probabilistic models
 - Kernels for biological sequences
 - Kernels for graphs
 - Kernels on graphs
- 6 Open Problems and Research Topics

Outline

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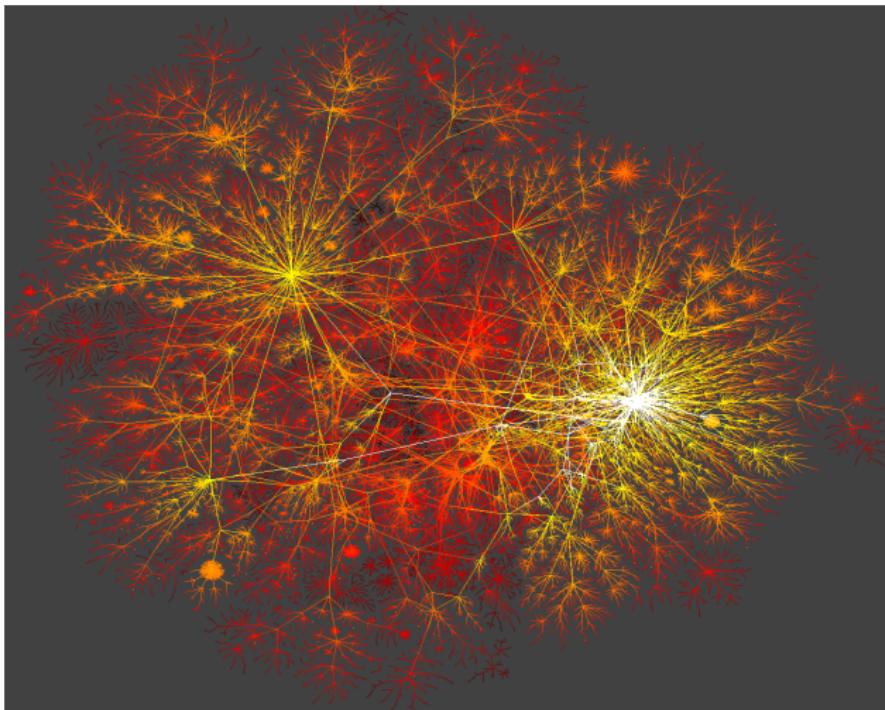
Graphs

Motivation

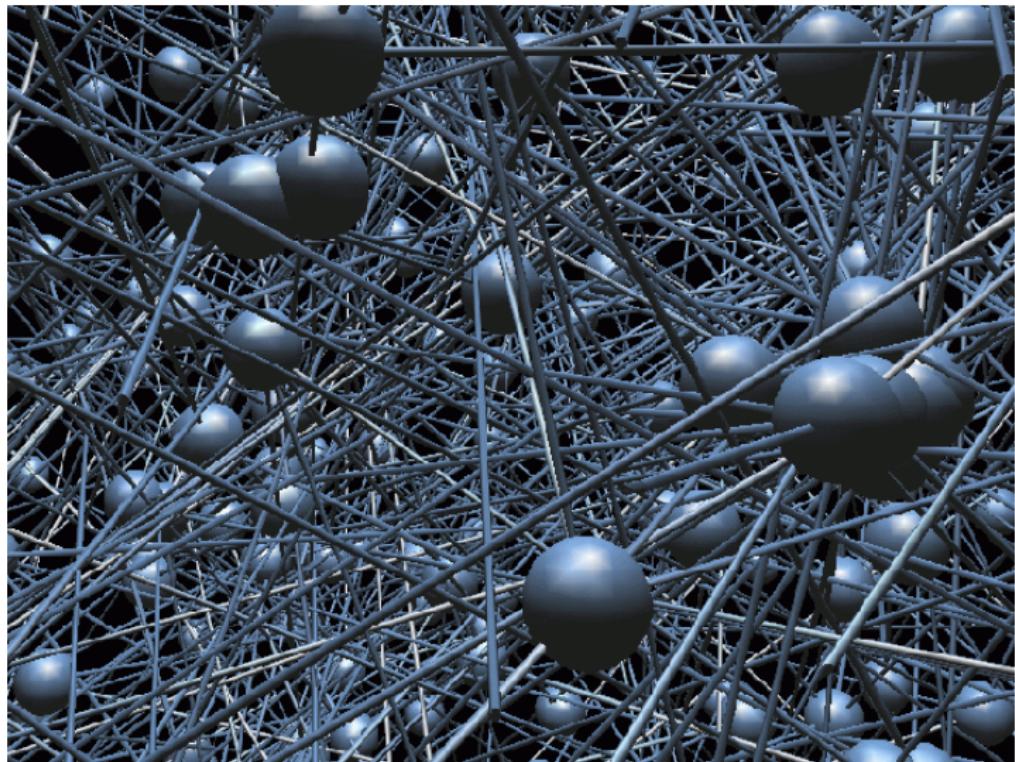
Data often come in the form of **nodes in a graph** for different reasons:

- by **definition** (interaction network, internet...)
- by **discretization**/sampling of a continuous domain
- by **convenience** (e.g., if only a similarity function is available)

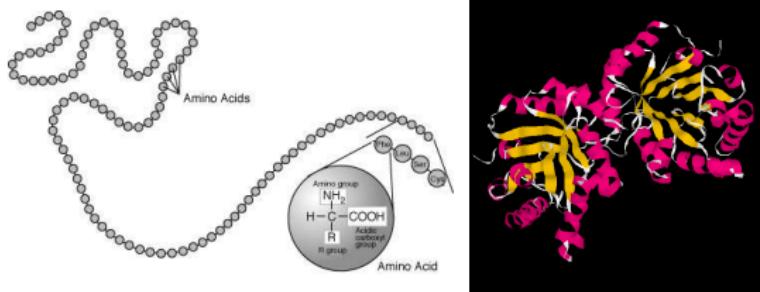
Example: web



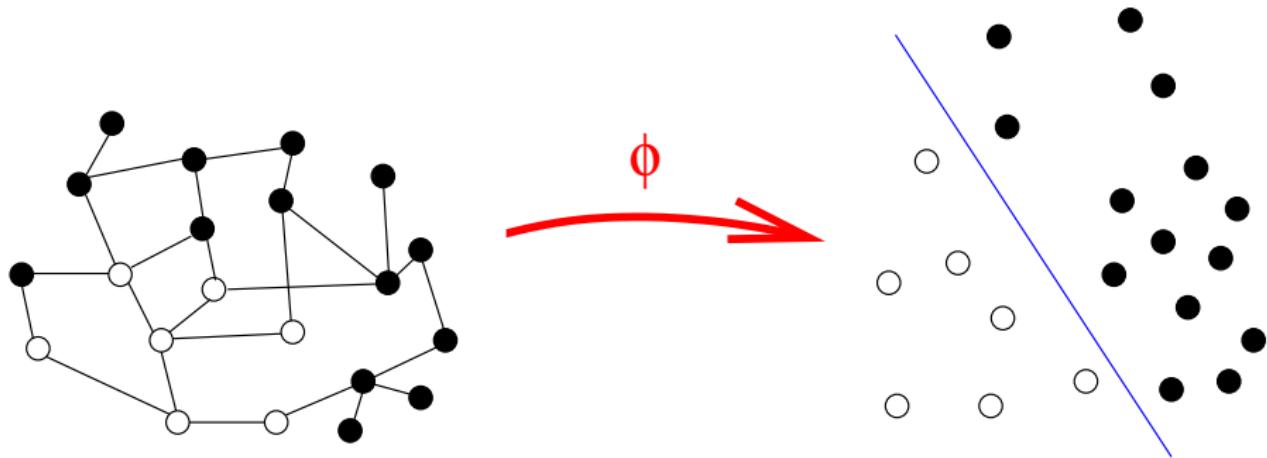
Example: social network



Example: protein-protein interaction



Kernel on a graph



- We need a kernel $K(\mathbf{x}, \mathbf{x}')$ between nodes of the graph.
- Example: predict protein functions from high-throughput protein-protein interaction data.

General remarks

Strategies to design a kernel on a graph

- \mathcal{X} being finite, any symmetric semi-definite matrix K defines a valid p.d. kernel on \mathcal{X} .

General remarks

Strategies to design a kernel on a graph

- \mathcal{X} being finite, any symmetric semi-definite matrix K defines a valid p.d. kernel on \mathcal{X} .
- How to “translate” the graph topology into the kernel?
 - Direct geometric approach: $K_{i,j}$ should be “large” when \mathbf{x}_i and \mathbf{x}_j are “close” to each other on the graph?
 - Functional approach: $\|f\|_K$ should be “small” when f is “smooth” on the graph?
 - Link discrete/continuous: is there an equivalent to the continuous Gaussian kernel on the graph (e.g., limit by fine discretization)?

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Conditionally p.d. kernels

Hilbert distance

- Any p.d. kernel is an inner product in a Hilbert space

$$K(\mathbf{x}, \mathbf{x}') = \langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle_{\mathcal{H}}.$$

- It defines a Hilbert distance:

$$d_K(\mathbf{x}, \mathbf{x}')^2 = K(\mathbf{x}, \mathbf{x}) + K(\mathbf{x}', \mathbf{x}') - 2K(\mathbf{x}, \mathbf{x}').$$

- $-d_K^2$ is **conditionally positive definite (c.p.d.)**, i.e.:

$$\forall t > 0, \quad \exp(-td_K(\mathbf{x}, \mathbf{x}')^2) \text{ is p.d.}$$

Example

A direct approach

- For $\mathcal{X} = \mathbb{R}^n$, the inner product is p.d.:

$$K(\mathbf{x}, \mathbf{x}') = \mathbf{x}^\top \mathbf{x}'.$$

- The corresponding Hilbert distance is the Euclidean distance:

$$d_K(\mathbf{x}, \mathbf{x}')^2 = \mathbf{x}^\top \mathbf{x} + \mathbf{x}'^\top \mathbf{x}' - 2\mathbf{x}^\top \mathbf{x}' = \|\mathbf{x} - \mathbf{x}'\|^2.$$

- $-d_K^2$ is **conditionally positive definite (c.p.d.)**, i.e.:

$$\forall t > 0, \quad \exp(-t\|\mathbf{x} - \mathbf{x}'\|^2) \text{ is p.d.}$$

Graph distance

Graph embedding in a Hilbert space

- Given a graph $G = (V, E)$, the **graph distance** $d_G(x, x')$ between any two vertices is the **length of the shortest path** between x and x' .
- We say that the graph $G = (V, E)$ can be **embedded** (exactly) in a Hilbert space if $-d_G$ is **c.p.d.**, which implies in particular that $\exp(-td_G(x, x'))$ is p.d. for all $t > 0$.

Graph distance

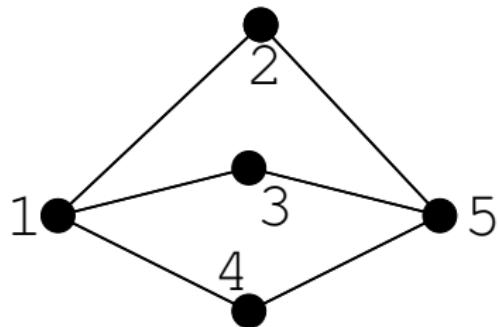
Graph embedding in a Hilbert space

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Lemma

- In general graphs cannot** be embedded exactly in Hilbert spaces.
- In some cases exact embeddings exist**, e.g.:
 - trees** can be embedded exactly,
 - closed chains** can be embedded exactly.

Example: non-c.p.d. graph distance



$$d_G = \begin{pmatrix} 0 & 1 & 1 & 1 & 2 \\ 1 & 0 & 2 & 2 & 1 \\ 1 & 2 & 0 & 2 & 1 \\ 1 & 2 & 2 & 0 & 1 \\ 2 & 1 & 1 & 1 & 0 \end{pmatrix}$$

$$\lambda_{\min} \left(\left[e^{(-0.2d_G(i,j))} \right] \right) = -0.028 < 0.$$

Graph distances on trees are c.p.d.

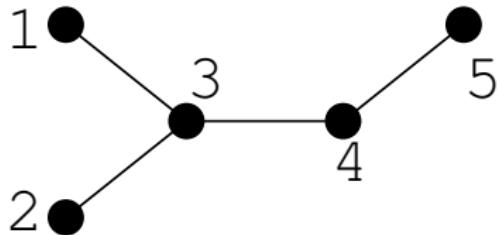
Proof

- Let $G = (V, E)$ be a tree;
- Fix a root $x_0 \in V$;
- Represent any vertex $x \in V$ by a vector $\Phi(x) \in \mathbb{R}^{|E|}$, where $\Phi(x)_i = 1$ if the i -th edge is part of the (unique) path between x and x_0 , 0 otherwise.
- Then

$$d_G(x, x') = \| \Phi(x) - \Phi(x') \|^2,$$

and therefore $-d_G$ is c.p.d., in particular $\exp(-td_G(x, x'))$ is p.d. for all $t > 0$.

Example

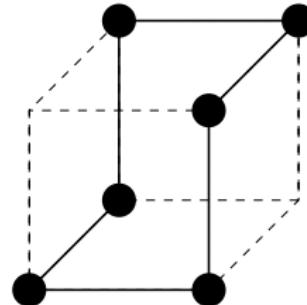
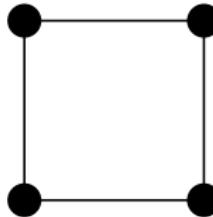


$$\left[e^{-d_G(i,j)} \right] = \begin{pmatrix} 1 & 0.14 & 0.37 & 0.14 & 0.05 \\ 0.14 & 1 & 0.37 & 0.14 & 0.05 \\ 0.37 & 0.37 & 1 & 0.37 & 0.14 \\ 0.14 & 0.14 & 0.37 & 1 & 0.37 \\ 0.05 & 0.05 & 0.14 & 0.37 & 1 \end{pmatrix}$$

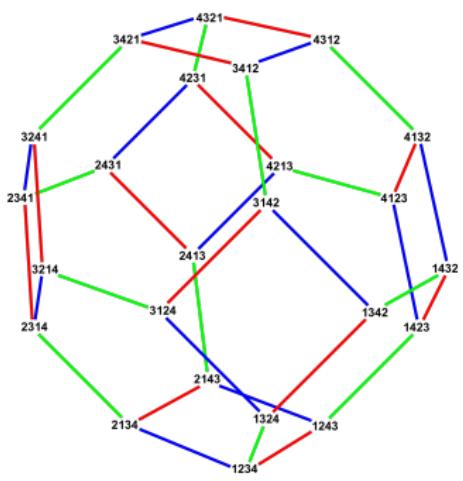
Graph distances on closed chains are c.p.d.

Proof: case $|V| = 2p$

- Let $G = (V, E)$ be a directed cycle with an even number of vertices $|V| = 2p$.
- Fix a root $x_0 \in V$, number the $2p$ edges from x_0 to x_0 ;
- Label the $2p$ edges with $e_1, \dots, e_p, -e_1, \dots, -e_p$ (vectors in \mathbb{R}^p);
- For a vertex v , take $\Phi(v)$ to be the sum of the labels of the edges in the shortest directed path between x_0 and v .



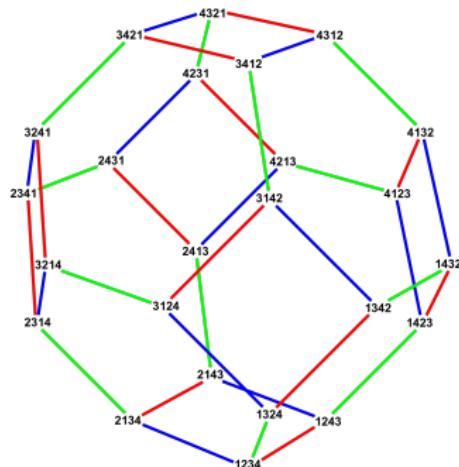
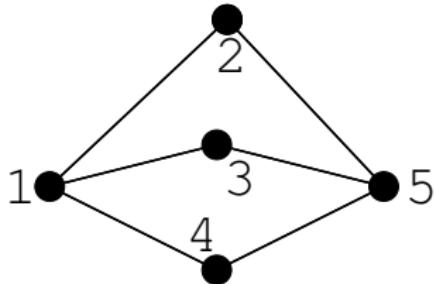
Another interesting graph



Cayley graph of S_4

- Let \mathbb{S}_n the set of permutations of n items (symmetric group)
- Cayley graph G : connect two permutations when they differ by one adjacent transposition
- d_G can be computed in $O(n \log n)$ how?
- d_G is c.p.d. why?
- See Jiao and Vert (2017)

Summary on graph distance



- Some graph distances are c.p.d, some are not
- There is a large literature in mathematics on how to "approximately" embed a graph; maybe this could be useful for machine learning?
- Graph distance is very sensitive to "noise" in edges
- We need other approaches to define a p.d. kernel that would work for all graphs, and be less sensitive to noise in the edges.

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Functional approach

Motivation

- How to design a p.d. kernel on **general graphs**?
- Designing a kernel is equivalent to defining an **RKHS**.
- There are intuitive notions of **smoothness** on a graph.

Idea

- Define a priori a **smoothness functional** on the functions $f : \mathcal{X} \rightarrow \mathbb{R}$;
- Show that **it defines an RKHS** and identify the corresponding kernel.

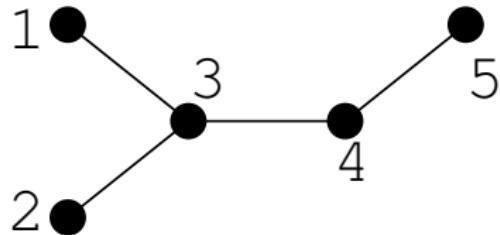
Notations

- $\mathcal{X} = (\mathbf{x}_1, \dots, \mathbf{x}_m)$ is finite.
- For $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$, we note $\mathbf{x} \sim \mathbf{x}'$ to indicate the existence of an edge between \mathbf{x} and \mathbf{x}' .
- We assume that there is no self-loop $\mathbf{x} \sim \mathbf{x}$, and that there is a single connected component.
- The adjacency matrix is $A \in \mathbb{R}^{m \times m}$:

$$A_{i,j} = \begin{cases} 1 & \text{if } i \sim j, \\ 0 & \text{otherwise.} \end{cases}$$

- D is the diagonal matrix where $D_{i,i}$ is the number of neighbors of \mathbf{x}_i ($D_{i,i} = \sum_{j=1}^m A_{i,j}$).

Example

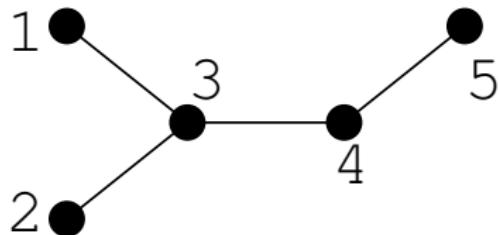


$$A = \begin{pmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad D = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Graph Laplacian

Definition

The Laplacian of the graph is the matrix $L = D - A$.



$$L = D - A = \begin{pmatrix} 1 & 0 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ -1 & -1 & 3 & -1 & 0 \\ 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & 1 \end{pmatrix}$$

Properties of the Laplacian

Lemma

Let $L = D - A$ be the Laplacian of a **connected** graph:

- For any $f : \mathcal{X} \rightarrow \mathbb{R}$,

$$\Omega(f) := \sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2 = f^\top L f$$

- L is a **symmetric positive semi-definite** matrix
- 0 is an **eigenvalue** with multiplicity 1 associated to the constant eigenvector $\mathbf{1} = (1, \dots, 1)$
- The **image** of L is

$$Im(L) = \left\{ f \in \mathbb{R}^m : \sum_{i=1}^m f_i = 0 \right\}$$

Proof: link between $\Omega(f)$ and L

$$\begin{aligned}\Omega(f) &= \sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2 \\&= \sum_{i \sim j} \left(f(\mathbf{x}_i)^2 + f(\mathbf{x}_j)^2 - 2f(\mathbf{x}_i)f(\mathbf{x}_j) \right) \\&= \sum_{i=1}^m D_{i,i} f(\mathbf{x}_i)^2 - 2 \sum_{i \sim j} f(\mathbf{x}_i)f(\mathbf{x}_j) \\&= \mathbf{f}^\top D \mathbf{f} - \mathbf{f}^\top A \mathbf{f} \\&= \mathbf{f}^\top L \mathbf{f}\end{aligned}$$

Proof: eigenstructure of L

- L is symmetric because A and D are symmetric.
- For any $f \in \mathbb{R}^m$, $f^\top L f = \Omega(f) \geq 0$, therefore the (real-valued) eigenvalues of L are ≥ 0 : L is therefore positive semi-definite.
- f is an eigenvector associated to eigenvalue 0
iff $f^\top L f = 0$
iff $\sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2 = 0$,
iff $f(\mathbf{x}_i) = f(\mathbf{x}_j)$ when $i \sim j$,
iff f is constant (because the graph is connected).
- L being symmetric, $Im(L)$ is the orthogonal supplement of $Ker(L)$, that is, the set of functions orthogonal to $\mathbf{1}$. \square

Our first graph kernel

Theorem

The set $\mathcal{H} = \{f \in \mathbb{R}^m : \sum_{i=1}^m f_i = 0\}$ endowed with the norm

$$\Omega(f) = \sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2$$

is a RKHS whose reproducing kernel is L^* , the pseudo-inverse of the graph Laplacian.

In case of...

Pseudo-inverse of L

Remember the pseudo-inverse L^* of L is the linear application that is equal to:

- 0 on $\text{Ker}(L)$
- L^{-1} on $\text{Im}(L)$, that is, if we write:

$$L = \sum_{i=1}^m \lambda_i u_i u_i^\top$$

the eigendecomposition of L :

$$L^* = \sum_{\lambda_i \neq 0} (\lambda_i)^{-1} u_i u_i^\top.$$

- In particular it holds that $L^* L = LL^* = \Pi_{\mathcal{H}}$, the projection onto $\text{Im}(L) = \mathcal{H}$.

Proof (1/2)

- Restricted to \mathcal{H} , the symmetric bilinear form:

$$\langle f, g \rangle = f^\top L g$$

is positive definite (because L is positive semi-definite, and $\mathcal{H} = \text{Im}(L)$). It is therefore a scalar product, making of \mathcal{H} a **Hilbert space** (in fact Euclidean).

- The norm in this Hilbert space \mathcal{H} is:

$$\|f\|^2 = \langle f, f \rangle = f^\top L f = \Omega(f) .$$

Proof (2/2)

To check that \mathcal{H} is a RKHS with reproducing kernel $K = L^*$, it suffices to show that:

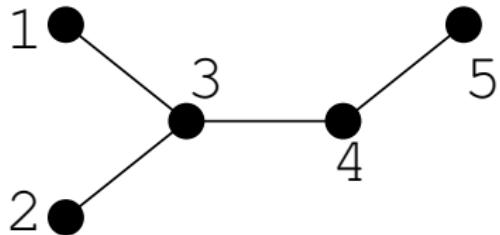
$$\begin{cases} \forall \mathbf{x} \in \mathcal{X}, & K_{\mathbf{x}} \in \mathcal{H}, \\ \forall (\mathbf{x}, f) \in \mathcal{X} \times \mathcal{H}, & \langle f, K_{\mathbf{x}} \rangle = f(\mathbf{x}) . \end{cases}$$

- $\text{Ker}(K) = \text{Ker}(L^*) = \text{Ker}(L)$, implying $K\mathbf{1} = 0$. Therefore, each row/column of K is in \mathcal{H} .
- For any $f \in \mathcal{H}$, if we note $g_i = \langle K(i, \cdot), f \rangle$ we get:

$$g = KLf = L^*Lf = \Pi_{\mathcal{H}}(f) = f .$$

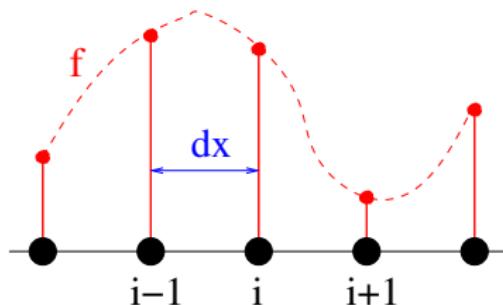
As a conclusion $K = L^*$ is the reproducing kernel of \mathcal{H} . \square

Example



$$L^* = \begin{pmatrix} 0.88 & -0.12 & 0.08 & -0.32 & -0.52 \\ -0.12 & 0.88 & 0.08 & -0.32 & -0.52 \\ 0.08 & 0.08 & 0.28 & -0.12 & -0.32 \\ -0.32 & -0.32 & -0.12 & 0.48 & 0.28 \\ -0.52 & -0.52 & -0.32 & 0.28 & 1.08 \end{pmatrix}$$

Interpretation of the Laplacian



$$\begin{aligned}\Delta f(x) &= f''(x) \\ &\sim \frac{f'(x + dx/2) - f'(x - dx/2)}{dx} \\ &\sim \frac{f(x + dx) - f(x) - f(x) + f(x - dx)}{dx^2} \\ &= \frac{f_{i-1} + f_{i+1} - 2f(i)}{dx^2} \\ &= -\frac{Lf(i)}{dx^2}.\end{aligned}$$

Interpretation of regularization

For $f = [0, 1] \rightarrow \mathbb{R}$ and $x_i = i/m$, we have:

$$\begin{aligned}\Omega(f) &= \sum_{i=1}^m \left(f\left(\frac{i+1}{m}\right) - f\left(\frac{i}{m}\right) \right)^2 \\ &\sim \sum_{i=1}^m \left(\frac{1}{m} \times f'\left(\frac{i}{m}\right) \right)^2 \\ &= \frac{1}{m} \times \frac{1}{m} \sum_{i=1}^m f'\left(\frac{i}{m}\right)^2 \\ &\sim \frac{1}{m} \int_0^1 f'(t)^2 dt.\end{aligned}$$

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Motivation

- Consider the normalized Gaussian kernel on \mathbb{R}^d :

$$K_t(\mathbf{x}, \mathbf{x}') = \frac{1}{(4\pi t)^{\frac{d}{2}}} \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}'\|^2}{4t}\right).$$

- In order to transpose it to the graph, replacing the Euclidean distance by the shortest-path distance does not work.
- In this section we provide a characterization of the Gaussian kernel as the **solution of a partial differential equation** involving the Laplacian, which we can transpose to the graph: the **diffusion equation**.
- The solution of the discrete diffusion equation will be called the **diffusion kernel** or **heat kernel**.

The diffusion equation

Lemma

For any $\mathbf{x}_0 \in \mathbb{R}^d$, the function:

$$K_{\mathbf{x}_0}(\mathbf{x}, t) = K_t(\mathbf{x}_0, \mathbf{x}) = \frac{1}{(4\pi t)^{\frac{d}{2}}} \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}_0\|^2}{4t}\right)$$

is solution of the *diffusion equation*:

$$\frac{\partial}{\partial t} K_{\mathbf{x}_0}(\mathbf{x}, t) = \Delta K_{\mathbf{x}_0}(\mathbf{x}, t)$$

with initial condition $K_{\mathbf{x}_0}(\mathbf{x}, 0) = \delta_{\mathbf{x}_0}(\mathbf{x})$

(proof by direct computation).

Discrete diffusion equation

For finite-dimensional $f_t \in \mathbb{R}^m$, the diffusion equation becomes:

$$\frac{\partial}{\partial t} f_t = -L f_t$$

which admits the following solution:

$$f_t = f_0 e^{-tL}$$

with

$$e^{tL} = I - tL + \frac{t^2}{2!} L^2 - \frac{t^3}{3!} L^3 + \dots$$

Diffusion kernel (Kondor and Lafferty, 2002)

This suggest to consider:

$$K = e^{-tL}$$

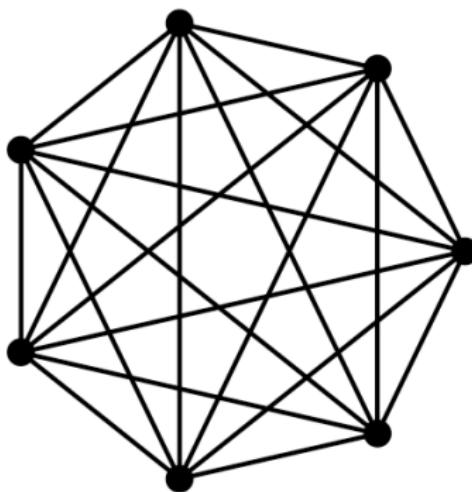
which is indeed symmetric positive semi-definite because if we write:

$$L = \sum_{i=1}^m \lambda_i u_i u_i^\top \quad (\lambda_i \geq 0)$$

we obtain:

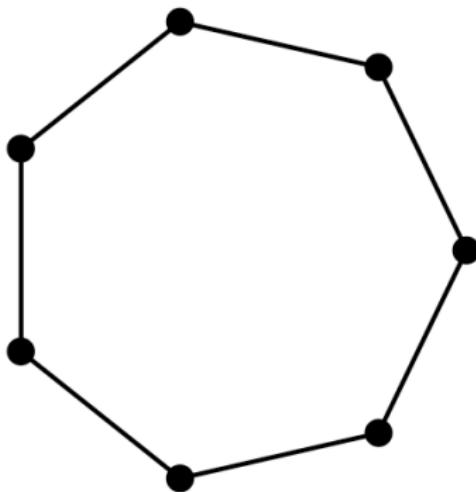
$$K = e^{-tL} = \sum_{i=1}^m e^{-t\lambda_i} u_i u_i^\top$$

Example: complete graph



$$K_{i,j} = \begin{cases} \frac{1+(m-1)e^{-tm}}{m} & \text{for } i = j, \\ \frac{1-e^{-tm}}{m} & \text{for } i \neq j. \end{cases}$$

Example: closed chain



$$K_{i,j} = \frac{1}{m} \sum_{\nu=0}^{m-1} \exp \left[-2t \left(1 - \cos \frac{2\pi\nu}{m} \right) \right] \cos \frac{2\pi\nu(i-j)}{m}.$$

Outline

5 The Kernel Jungle

- Green, Mercer, Herglotz, Bochner and friends
- Kernels for probabilistic models
- Kernels for biological sequences
- Kernels for graphs
- **Kernels on graphs**
 - Motivation
 - Graph distance and p.d. kernels
 - Construction by regularization
 - The diffusion kernel
- **Harmonic analysis on graphs**
- Applications

Motivation

- In this section we show that the diffusion and Laplace kernels can be interpreted in the **frequency domain** of functions
- This shows that our strategy to design kernels on graphs was based on **(discrete) harmonic analysis** on the graph
- This follows the approach we developed for semigroup kernels!

Spectrum of the diffusion kernel

- Let $0 = \lambda_1 < \lambda_2 \leq \dots \leq \lambda_m$ be the eigenvalues of the Laplacian:

$$L = \sum_{i=1}^m \lambda_i u_i u_i^\top \quad (\lambda_i \geq 0)$$

- The diffusion kernel K_t is an **invertible** matrix because its eigenvalues are strictly positive:

$$K_t = \sum_{i=1}^m e^{-t\lambda_i} u_i u_i^\top$$

Norm in the diffusion RKHS

- Any function $f \in \mathbb{R}^m$ can be written as $f = K(K^{-1}f)$, therefore its norm in the diffusion RKHS is:

$$\|f\|_{K_t}^2 = (f^\top K^{-1}) K (K^{-1}f) = f^\top K^{-1} f.$$

- For $i = 1, \dots, m$, let:

$$\hat{f}_i = u_i^\top f$$

be the projection of f onto the eigenbasis of K .

- We then have:

$$\|f\|_{K_t}^2 = f^\top K^{-1} f = \sum_{i=1}^m e^{t\lambda_i} \hat{f}_i^2.$$

- This looks similar to $\int |\hat{f}(\omega)|^2 e^{\sigma^2 \omega^2} d\omega \dots$

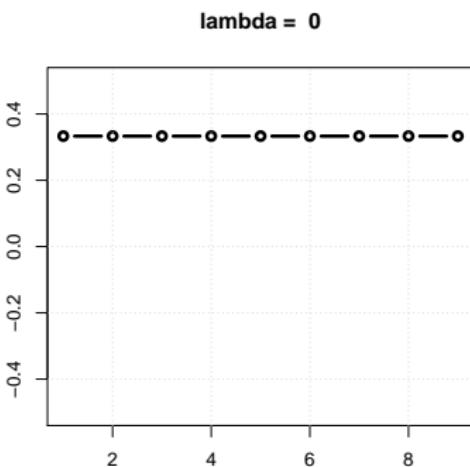
Discrete Fourier transform

Definition

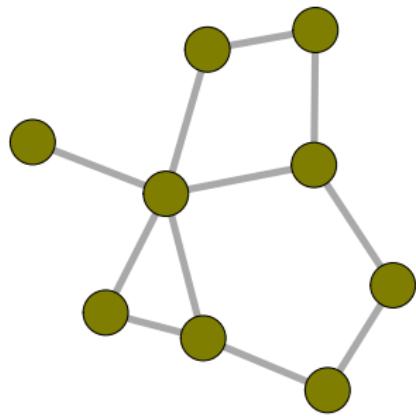
The vector $\hat{f} = (\hat{f}_1, \dots, \hat{f}_m)^\top$ is called the **discrete Fourier transform** of $f \in \mathbb{R}^n$

- The eigenvectors of the Laplacian are the discrete equivalent to the sine/cosine Fourier basis on \mathbb{R}^n .
- The eigenvalues λ_i are the equivalent to the frequencies ω^2
- Successive eigenvectors “oscillate” increasingly as eigenvalues get more and more negative.

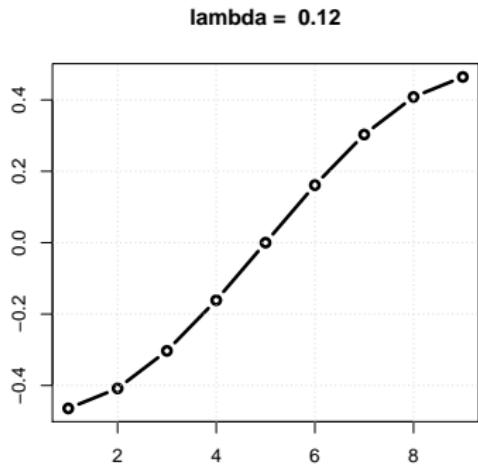
Examples



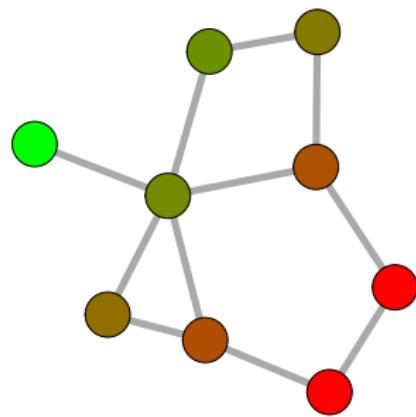
Lambda = 0



Examples

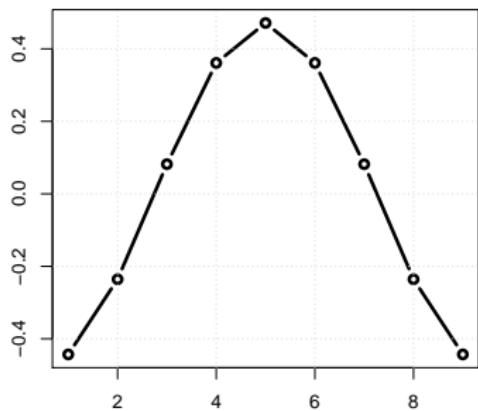


Lambda = 0.76

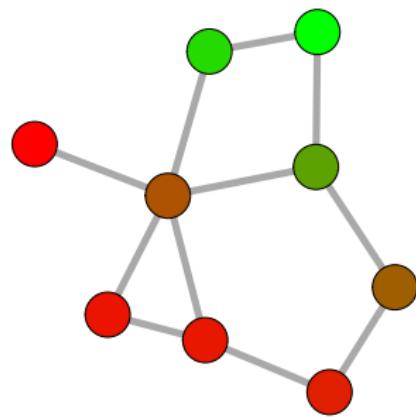


Examples

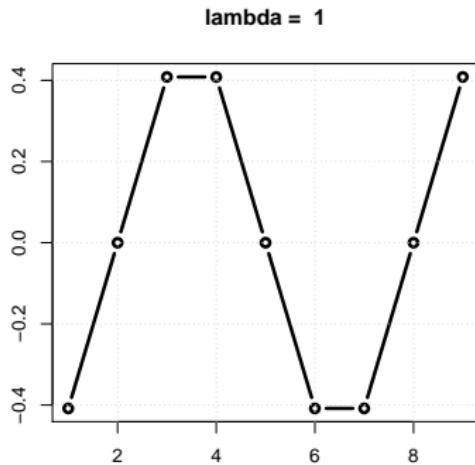
lambda = 0.47



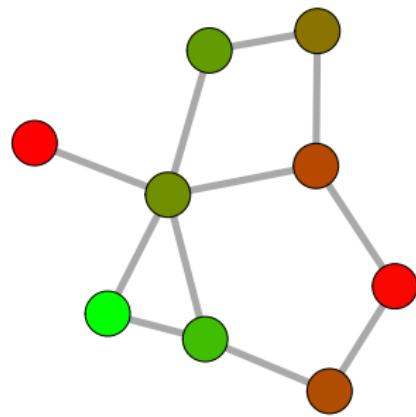
Lambda = 0.83



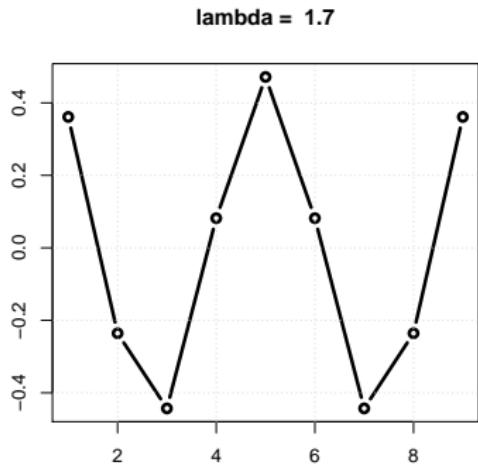
Examples



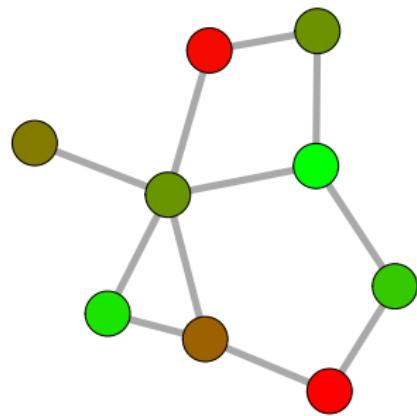
Lambda = 1.3



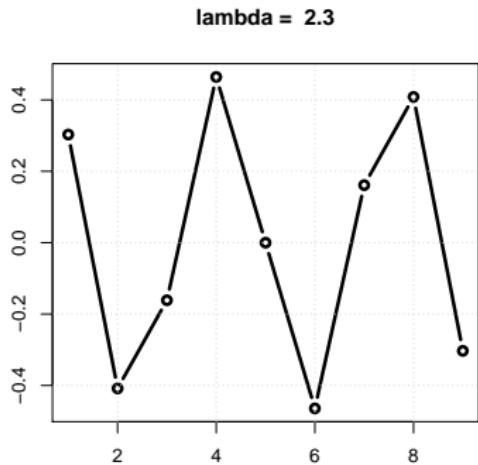
Examples



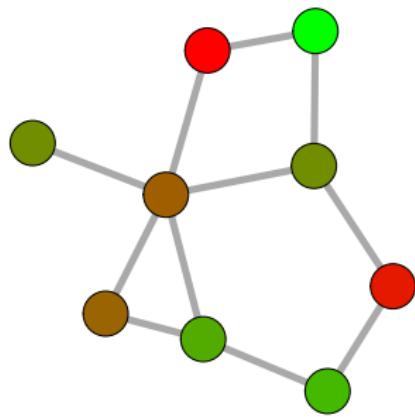
Lambda = 2.2



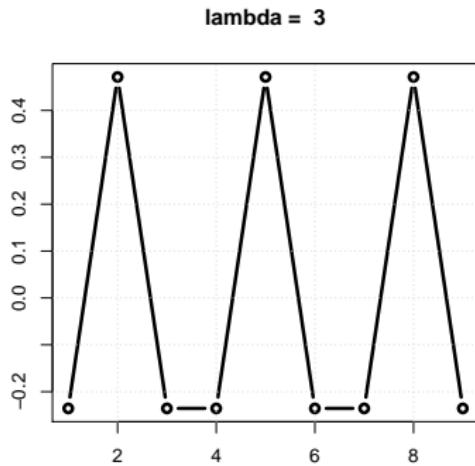
Examples



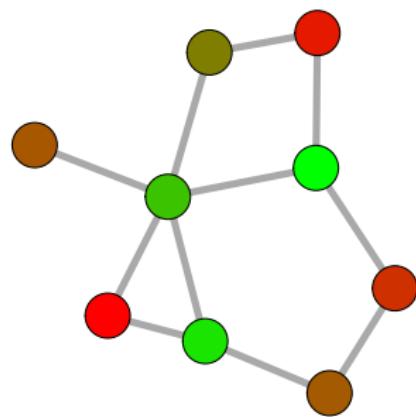
Lambda = 2.8



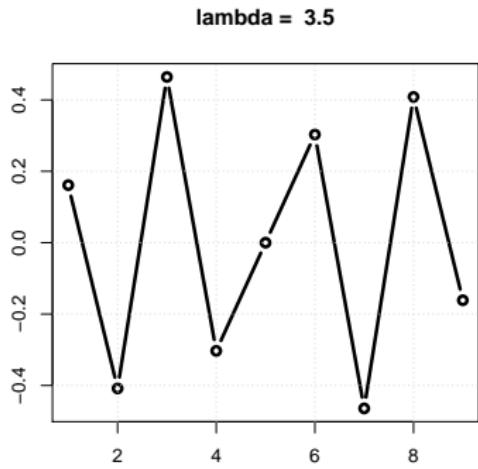
Examples



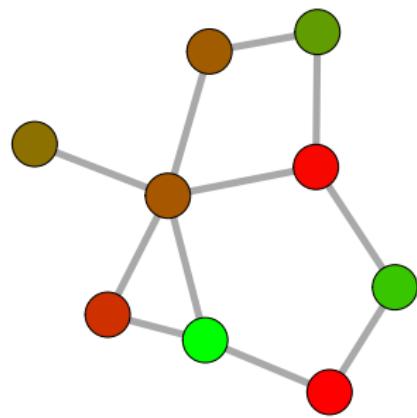
Lambda = 3.6



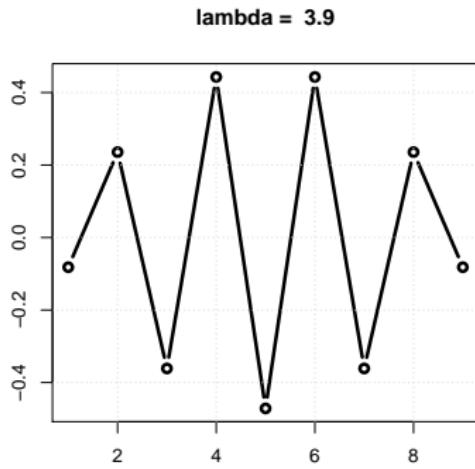
Examples



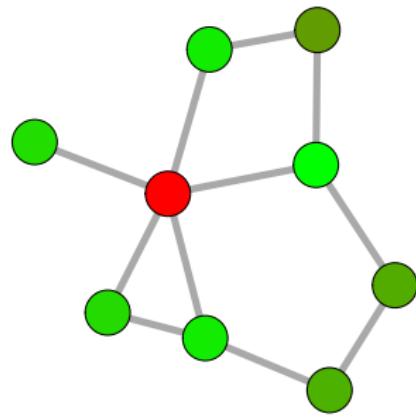
Lambda = 4.2



Examples



Lambda = 6.3



Generalization

This observation suggests to define a whole family of kernels:

$$K_r = \sum_{i=1}^m r(\lambda_i) u_i u_i^\top$$

associated with the following RKHS norms:

$$\|f\|_{K_r}^2 = \sum_{i=1}^m \frac{\hat{f}_i^2}{r(\lambda_i)}$$

where $r : \mathbb{R}^+ \rightarrow \mathbb{R}_*^+$ is a **non-increasing** function.

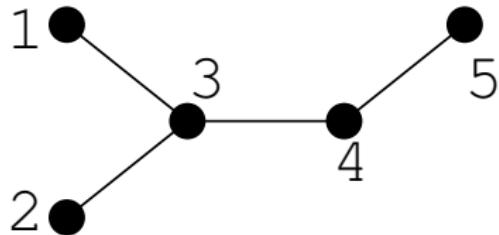
Example : regularized Laplacian

$$r(\lambda) = \frac{1}{\lambda + \epsilon}, \quad \epsilon > 0$$

$$K = \sum_{i=1}^m \frac{1}{\lambda_i + \epsilon} u_i u_i^\top = (L + \epsilon I)^{-1}$$

$$\| f \|_K^2 = f^\top K^{-1} f = \sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2 + \epsilon \sum_{i=1}^m f(\mathbf{x}_i)^2.$$

Example



$$(L + I)^{-1} = \begin{pmatrix} 0.60 & 0.10 & 0.19 & 0.08 & 0.04 \\ 0.10 & 0.60 & 0.19 & 0.08 & 0.04 \\ 0.19 & 0.19 & 0.38 & 0.15 & 0.08 \\ 0.08 & 0.08 & 0.15 & 0.46 & 0.23 \\ 0.04 & 0.04 & 0.08 & 0.23 & 0.62 \end{pmatrix}$$

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- **Applications**

Applications 1: graph partitioning

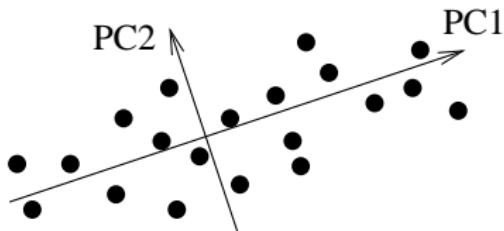
- A classical relaxation of graph partitioning is:

$$\min_{f \in \mathbb{R}^X} \sum_{i \sim j} (f_i - f_j)^2 \quad \text{s.t. } \sum_i f_i^2 = 1$$

- This can be rewritten

$$\max_f \sum_i f_i^2 \text{ s.t. } \|f\|_{\mathcal{H}} \leq 1$$

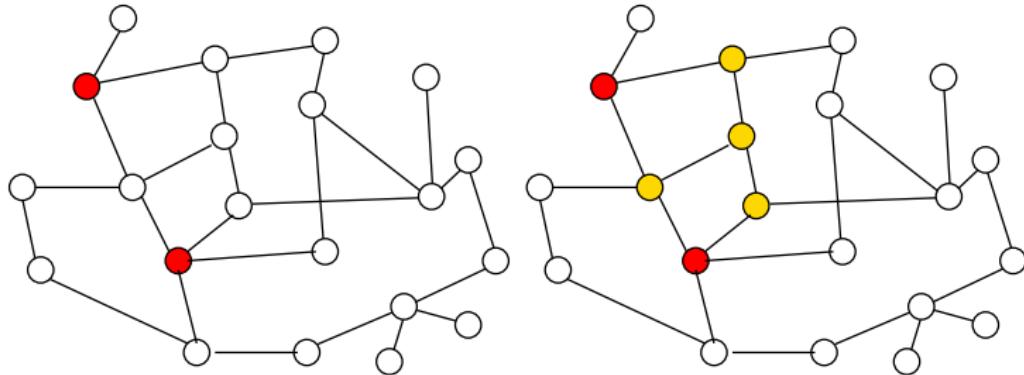
- This is **principal component analysis** in the RKHS (“kernel PCA”)



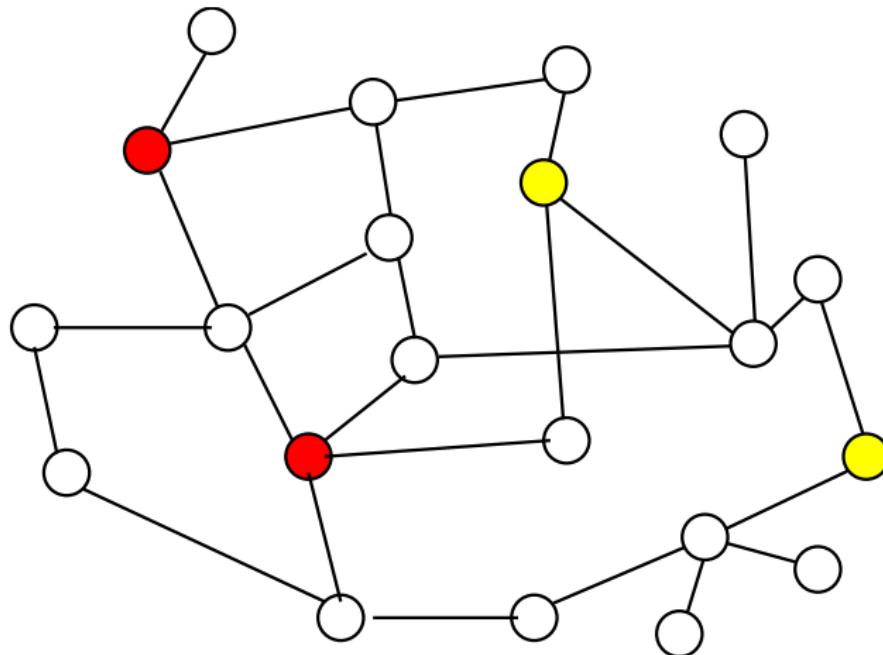
Applications 2: search on a graph

- Let x_1, \dots, x_q be a set of q nodes (the **query**). How to find “similar” nodes (and rank them)?
- One solution:

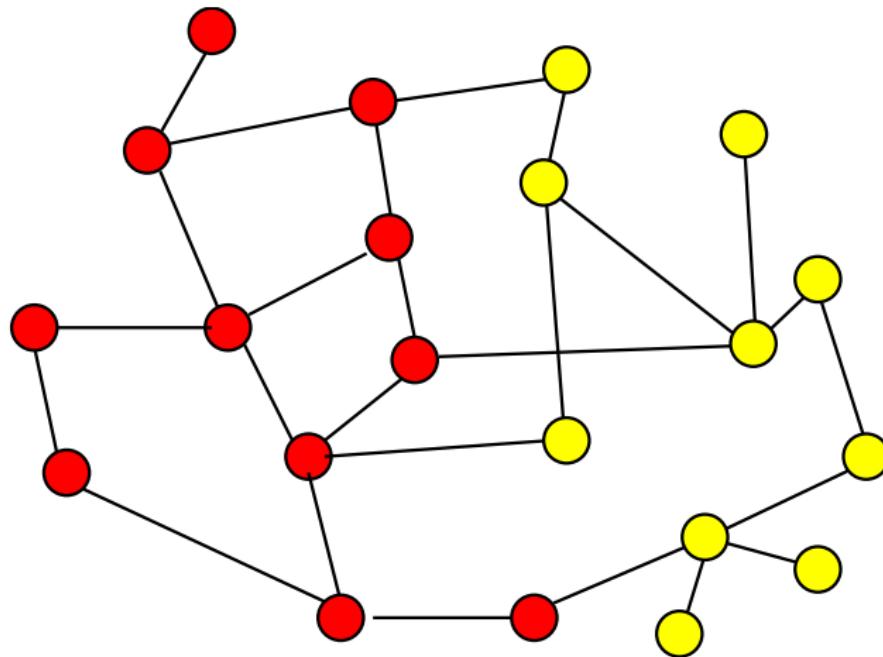
$$\min_f \|f\|_{\mathcal{H}} \quad \text{s.t.} \quad f(x_i) \geq 1 \text{ for } i = 1, \dots, q.$$



Application 3: Semi-supervised learning



Application 3: Semi-supervised learning



Application 4: Tumor classification from microarray data (Rapaport et al., 2006)

Data available

- Gene expression measures for **more than 10k genes**
- Measured on **less than 100 samples** of two (or more) different classes (e.g., different tumors)

Application 4: Tumor classification from microarray data (Rapaport et al., 2006)

Data available

- Gene expression measures for **more than 10k genes**
- Measured on **less than 100 samples** of two (or more) different classes (e.g., different tumors)

Goal

- Design a **classifier** to automatically assign a class to future samples from their expression profile
- **Interpret** biologically the differences between the classes

Linear classifiers

The approach

- Each sample is represented by a vector $x = (x_1, \dots, x_p)$ where $p > 10^5$ is the number of probes
- **Classification:** given the set of labeled sample, learn a linear decision function:

$$f(x) = \sum_{i=1}^p \beta_i x_i + \beta_0 ,$$

that is positive for one class, negative for the other

- **Interpretation:** the weight β_i quantifies the influence of gene i for the classification

Linear classifiers

Pitfalls

- No robust estimation procedure exist for 100 samples in 10^5 dimensions!
- It is necessary to reduce the complexity of the problem with prior knowledge.

Example : Norm Constraints

The approach

A common method in statistics to learn with few samples in high dimension is to **constrain the norm of β** , e.g.:

- Euclidean norm (support vector machines, ridge regression):
$$\|\beta\|_2 = \sum_{i=1}^p \beta_i^2$$
- L_1 -norm (lasso regression) :
$$\|\beta\|_1 = \sum_{i=1}^p |\beta_i|$$

Pros

- Good performance in classification

Cons

- Limited interpretation (small weights)
- No prior biological knowledge

Example 2: Feature Selection

The approach

Constrain most weights to be 0, i.e., **select a few genes** (< 20) whose expression are enough for classification. Interpretation is then about the selected genes.

Pros

- Good performance in classification
- Useful for **biomarker** selection
- Apparently easy interpretation

Cons

- The gene selection process is usually **not robust**
- Wrong interpretation is the rule (too much correlation between genes)

Pathway interpretation

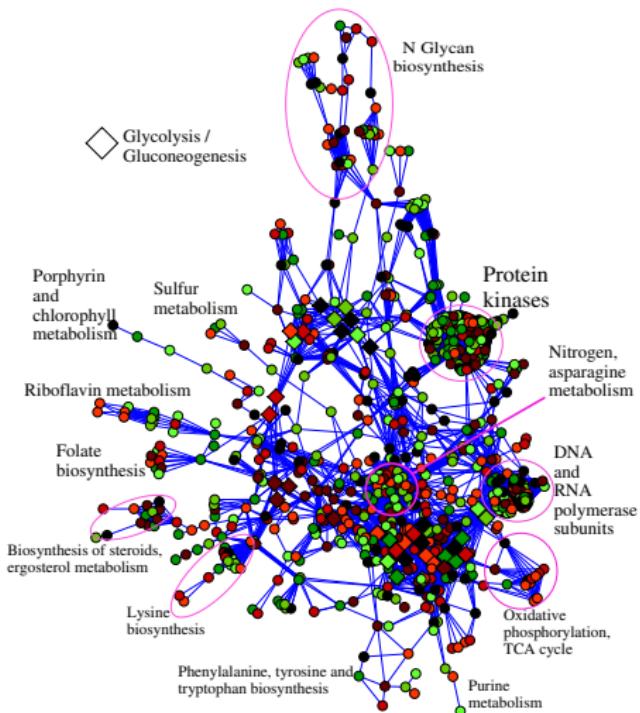
Motivation

- Basic biological functions are usually expressed in terms of **pathways** and not of single genes (metabolic, signaling, regulatory)
- Many pathways are already known
- How to use this prior knowledge to **constrain the weights to have an interpretation at the level of pathways?**

Solution (Rapaport et al., 2006)

- **Constrain the diffusion RKHS norm of β**
- Relevant if the true decision function is indeed smooth w.r.t. the biological network

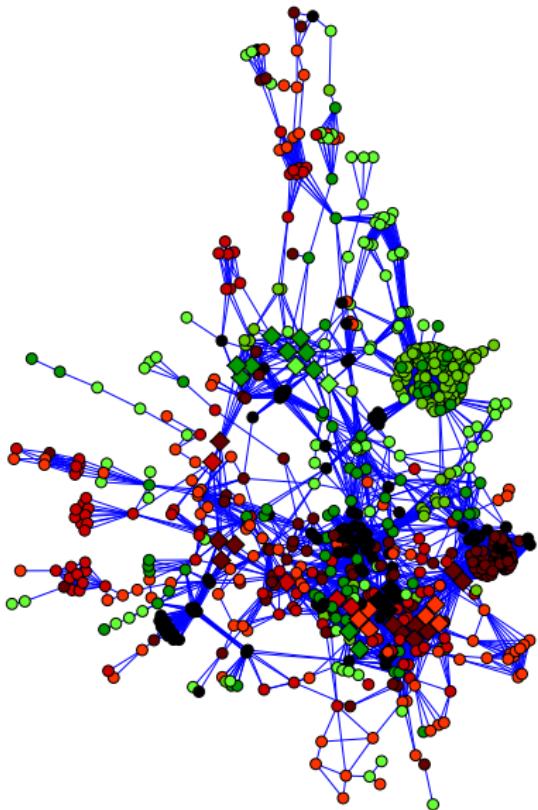
Pathway interpretation



Bad example

- The graph is the complete known **metabolic network** of the budding yeast (from KEGG database)
- We project the **classifier weight** learned by a SVM
- Good classification accuracy, but **no possible interpretation!**

Pathway interpretation



Good example

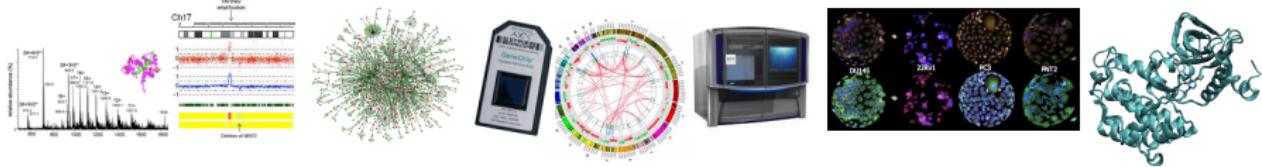
- The graph is the complete known **metabolic network** of the budding yeast (from KEGG database)
- We project the **classifier weight** learned by a spectral SVM
- Good classification accuracy, **and good interpretation!**

Open Problems and Research Topics

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics
 - Multiple Kernel Learning (MKL)
 - Large-scale learning with kernels
 - Foundations of deep learning from a kernel point of view

Motivation



- We have seen how to make learning algorithms given a kernel K on some data space \mathcal{X}
- Often we may have **several possible kernels**:
 - by **varying the kernel type or parameters** on a given description of the data (eg, linear, polynomial, Gaussian kernels with different bandwidths...)
 - because we have **different views of the same data**, eg, a protein can be characterized by its sequence, its structure, its mass spectrometry profile...
- How to **choose or integrate** different kernels in a learning task?

Setting: learning with one kernel

- For any $f : \mathcal{X} \rightarrow \mathbb{R}$, let $f^n = (f(\mathbf{x}_1), \dots, f(\mathbf{x}_n)) \in \mathbb{R}^n$
- Given a p.d. kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$, we learn with K by solving:

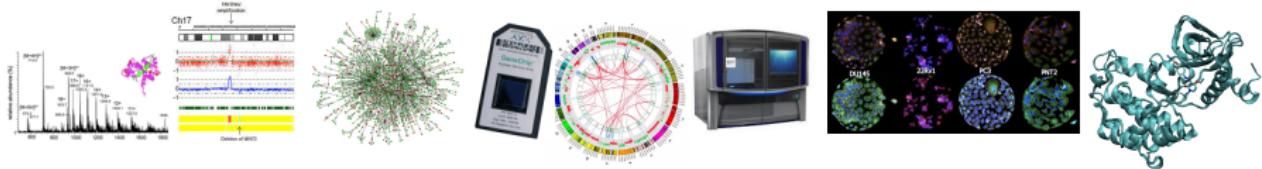
$$\min_{f \in \mathcal{H}} R(f^n) + \lambda \|f\|_{\mathcal{H}}^2, \quad (3)$$

where $\lambda > 0$ and $R : \mathbb{R}^n \rightarrow \mathbb{R}$ is an **closed**³ and **convex** empirical risk:

- $R(u) = \frac{1}{n} \sum_{i=1}^n (u_i - y_i)^2$ for kernel ridge regression
- $R(u) = \frac{1}{n} \sum_{i=1}^n \max(1 - y_i u_i, 0)$ for SVM
- $R(u) = \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-y_i u_i))$ for kernel logistic regression

³ R is closed if, for each $A \in \mathbb{R}$, the sublevel set $\{u \in \mathbb{R}^n : R(u) \leq A\}$ is closed. For example, if R is continuous then it is closed.

Sum kernel



Definition

Let K_1, \dots, K_M be M kernels on \mathcal{X} . The sum kernel K_S is the kernel on \mathcal{X} defined as

$$\forall \mathbf{x}, \mathbf{x}' \in \mathcal{X}, \quad K_S(\mathbf{x}, \mathbf{x}') = \sum_{i=1}^M K_i(\mathbf{x}, \mathbf{x}').$$

Sum kernel and vector concatenation

Theorem

For $i = 1, \dots, M$, let $\Phi_i : \mathcal{X} \rightarrow \mathcal{H}_i$ be a feature map such that

$$K_i(\mathbf{x}, \mathbf{x}') = \langle \Phi_i(\mathbf{x}), \Phi_i(\mathbf{x}') \rangle_{\mathcal{H}_i}.$$

Then $K_S = \sum_{i=1}^M K_i$ can be written as:

$$K_S(\mathbf{x}, \mathbf{x}') = \langle \Phi_S(\mathbf{x}), \Phi_S(\mathbf{x}') \rangle_{\mathcal{H}_S},$$

where $\Phi_S : \mathcal{X} \rightarrow \mathcal{H}_S = \mathcal{H}_1 \oplus \dots \oplus \mathcal{H}_M$ is the **concatenation** of the feature maps Φ_i :

$$\Phi_S(\mathbf{x}) = (\Phi_1(\mathbf{x}), \dots, \Phi_M(\mathbf{x}))^\top.$$

Therefore, summing kernels amounts to concatenating their feature space representations, which is a quite natural way to integrate different features.

Proof

For $\Phi_S(\mathbf{x}) = (\Phi_1(\mathbf{x}), \dots, \Phi_M(\mathbf{x}))^\top$, we easily compute:

$$\begin{aligned}\langle \Phi_S(\mathbf{x}), \Phi_S(\mathbf{x}') \rangle_{\mathcal{H}_S} &= \sum_{i=1}^M \langle \Phi_i(\mathbf{x}), \Phi_i(\mathbf{x}') \rangle_{\mathcal{H}_i} \\ &= \sum_{i=1}^M K_i(\mathbf{x}, \mathbf{x}') \\ &= K_S(\mathbf{x}, \mathbf{x}').\end{aligned}$$

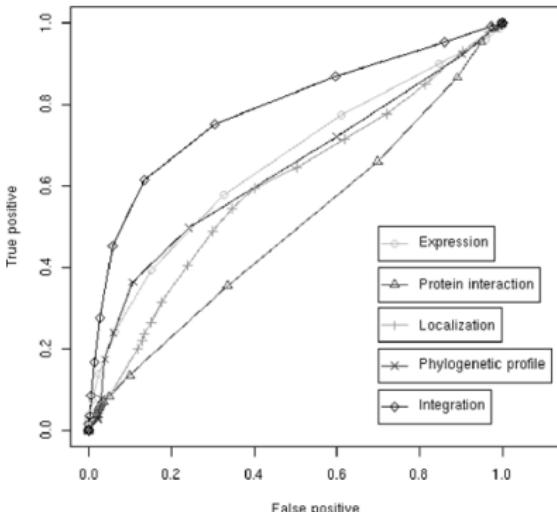
Example: data integration with the sum kernel



Protein network inference from multiple genomic data: a supervised approach

Y. Yamanishi^{1,*}, J.-P. Vert² and M. Kanehisa¹

¹Bioinformatics Center, Institute for Chemical Research, Kyoto University, Gokasho, Uji, Kyoto 611-0011, Japan and ²Computational Biology group, Ecole des Mines de Paris, 35 rue Saint-Honoré, 77305 Fontainebleau cedex, France



K_{exp} (Expression)

K_{ppi} (Protein interaction)

K_{loc} (Localization)

K_{phy} (Phylogenetic profile)

$K_{\text{exp}} + K_{\text{ppi}} + K_{\text{loc}} + K_{\text{phy}}$
(Integration)

The sum kernel: functional point of view

Theorem

The solution $f^* \in \mathcal{H}_{K_S}$ when we learn with $K_S = \sum_{i=1}^M K_i$ is equal to:

$$f^* = \sum_{i=1}^M f_i^*,$$

where $(f_1^*, \dots, f_M^*) \in \mathcal{H}_{K_1} \times \dots \times \mathcal{H}_{K_M}$ is the solution of:

$$\min_{f_1, \dots, f_M} R \left(\sum_{i=1}^M f_i^n \right) + \lambda \sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}}^2.$$

Generalization: The weighted sum kernel

Theorem

The solution f^* when we learn with $K_{\eta} = \sum_{i=1}^M \eta_i K_i$, with $\eta_1, \dots, \eta_M \geq 0$, is equal to:

$$f^* = \sum_{i=1}^M f_i^*,$$

where $(f_1^*, \dots, f_M^*) \in \mathcal{H}_{K_1} \times \dots \times \mathcal{H}_{K_M}$ is the solution of:

$$\min_{f_1, \dots, f_M} R \left(\sum_{i=1}^M f_i^n \right) + \lambda \sum_{i=1}^M \frac{\| f_i \|_{\mathcal{H}_{K_i}}^2}{\eta_i}.$$

Proof (1/4)

$$\min_{f_1, \dots, f_M} R \left(\sum_{i=1}^M f_i^n \right) + \lambda \sum_{i=1}^M \frac{\| f_i \|_{\mathcal{H}_{K_i}}^2}{\eta_i}.$$

- R being convex, the problem is strictly convex and has a **unique solution** $(f_1^*, \dots, f_M^*) \in \mathcal{H}_{K_1} \times \dots \times \mathcal{H}_{K_M}$.
- By the representer theorem, there exists $\alpha_1^*, \dots, \alpha_M^* \in \mathbb{R}^n$ such that

$$f_i^*(\mathbf{x}) = \sum_{j=1}^n \alpha_{ij}^* K_i(\mathbf{x}_j, \mathbf{x}).$$

- $(\alpha_1^*, \dots, \alpha_M^*)$ is the solution of

$$\min_{\alpha_1, \dots, \alpha_M \in \mathbb{R}^n} R \left(\sum_{i=1}^M \mathbf{K}_i \alpha_i \right) + \lambda \sum_{i=1}^M \frac{\alpha_i^\top \mathbf{K}_i \alpha_i}{\eta_i}.$$

Proof (2/4)

- This is equivalent to

$$\min_{\mathbf{u}, \alpha_1, \dots, \alpha_M \in \mathbb{R}^n} R(\mathbf{u}) + \lambda \sum_{i=1}^M \frac{\alpha_i^\top \mathbf{K}_i \alpha_i}{\eta_i} \quad \text{s.t.} \quad \mathbf{u} = \sum_{i=1}^M \mathbf{K}_i \alpha_i.$$

- This is equivalent to the saddle point problem:

$$\min_{\mathbf{u}, \alpha_1, \dots, \alpha_M \in \mathbb{R}^n} \max_{\gamma \in \mathbb{R}^n} R(\mathbf{u}) + \lambda \sum_{i=1}^M \frac{\alpha_i^\top \mathbf{K}_i \alpha_i}{\eta_i} + 2\lambda \gamma^\top (\mathbf{u} - \sum_{i=1}^M \mathbf{K}_i \alpha_i).$$

- By Slater's condition, strong duality holds, meaning we can invert min and max:

$$\max_{\gamma \in \mathbb{R}^n} \min_{\mathbf{u}, \alpha_1, \dots, \alpha_M \in \mathbb{R}^n} R(\mathbf{u}) + \lambda \sum_{i=1}^M \frac{\alpha_i^\top \mathbf{K}_i \alpha_i}{\eta_i} + 2\lambda \gamma^\top (\mathbf{u} - \sum_{i=1}^M \mathbf{K}_i \alpha_i).$$

Proof (3/4)

- Minimization in \mathbf{u} :

$$\min_{\mathbf{u}} R(\mathbf{u}) + 2\lambda\gamma^\top \mathbf{u} = -\max_{\mathbf{u}} \left\{ -2\lambda\gamma^\top \mathbf{u} - R(\mathbf{u}) \right\} = -R^*(-2\lambda\gamma),$$

where R^* is the Fenchel dual of R :

$$\forall \mathbf{v} \in \mathbb{R}^n \quad R^*(\mathbf{v}) = \sup_{\mathbf{u} \in \mathbb{R}^n} \mathbf{u}^\top \mathbf{v} - R(\mathbf{u}).$$

- Minimization in α_i for $i = 1, \dots, M$:

$$\min_{\alpha_i} \left\{ \lambda \frac{\alpha_i^\top \mathbf{K}_i \alpha_i}{\eta_i} - 2\lambda\gamma^\top \mathbf{K}_i \alpha_i \right\} = -\lambda\eta_i \gamma^\top \mathbf{K}_i \gamma,$$

where the minimum in α_i is reached for $\alpha_i^* = \eta_i \gamma$.

Proof (4/4)

- The dual problem is therefore

$$\max_{\gamma \in \mathbb{R}^n} \left\{ -R^*(-2\lambda\gamma) - \lambda\gamma^\top \left(\sum_{i=1}^M \eta_i \mathbf{K}_i \right) \gamma \right\}.$$

- Note that if learn from a single kernel \mathbf{K}_η , we get the same dual problem

$$\max_{\gamma \in \mathbb{R}^n} \left\{ -R^*(-2\lambda\gamma) - \lambda\gamma^\top \mathbf{K}_\eta \gamma \right\}.$$

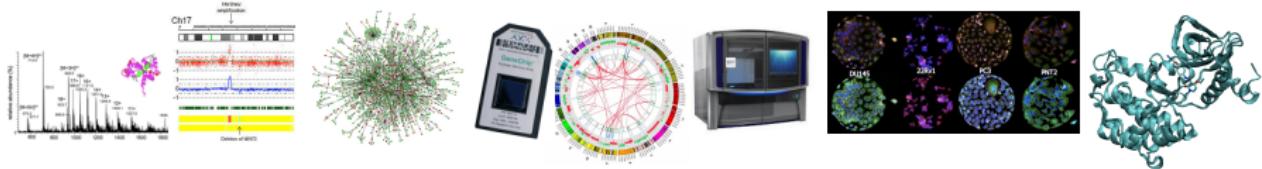
- If γ^* is a solution of the dual problem, then $\alpha_i^* = \eta_i \gamma^*$ leading to:

$$\forall \mathbf{x} \in \mathcal{X}, \quad f_i^*(\mathbf{x}) = \sum_{j=1}^n \alpha_{ij}^* \mathbf{K}_i(\mathbf{x}_j, \mathbf{x}) = \sum_{j=1}^n \eta_i \gamma_j^* \mathbf{K}_i(\mathbf{x}_j, \mathbf{x})$$

- Therefore, $f^* = \sum_{i=1}^M f_i^*$ satisfies

$$f^*(\mathbf{x}) = \sum_{i=1}^M \sum_{j=1}^n \eta_i \gamma_j^* \mathbf{K}_i(\mathbf{x}_j, \mathbf{x}) = \sum_{j=1}^n \gamma_j^* \mathbf{K}_\eta(\mathbf{x}_j, \mathbf{x}). \quad \square$$

Learning the kernel



Motivation

- If we know how to weight each kernel, then we can learn with the weighted kernel

$$\mathbf{K}_\eta = \sum_{i=1}^M \eta_i \mathbf{K}_i$$

- However, usually we don't know...
- Perhaps we can optimize the weights η_i during learning?

An objective function for K

Theorem

For any p.d. kernel K on \mathcal{X} , let

$$J(K) = \min_{f \in \mathcal{H}} \{ R(f^n) + \lambda \|f\|_{\mathcal{H}}^2 \} .$$

The function $K \mapsto J(K)$ is **convex**.

This suggests a principled way to "learn" a kernel: define a convex set of candidate kernels, and minimize $J(K)$ by convex optimization.

Proof

- We have shown by strong duality that

$$J(K) = \max_{\gamma \in \mathbb{R}^n} \left\{ -R^*(-2\lambda\gamma) - \lambda\gamma^\top \mathbf{K}\gamma \right\}.$$

- For each γ fixed, this is an affine function of K , hence convex
- A supremum of convex functions is convex. □

MKL (Lanckriet et al., 2004)

- We consider the set of **convex combinations**

$$K_{\boldsymbol{\eta}} = \sum_{i=1}^M \eta_i K_i \quad \text{with} \quad \boldsymbol{\eta} \in \Sigma_M = \left\{ \boldsymbol{\eta}_i \geq 0, \sum_{i=1}^M \eta_i = 1 \right\}$$

- We optimize both $\boldsymbol{\eta}$ and f^* by solving:

$$\min_{\boldsymbol{\eta} \in \Sigma_M} J(K_{\boldsymbol{\eta}}) = \min_{\boldsymbol{\eta} \in \Sigma_M} \min_{f \in \mathcal{H}_{K_{\boldsymbol{\eta}}}} \left\{ R(f^n) + \lambda \| f \|_{\mathcal{H}_{K_{\boldsymbol{\eta}}}}^2 \right\}$$

- The problem is **jointly convex** in $(\boldsymbol{\eta}, \boldsymbol{\alpha})$ and can be solved efficiently.
- The output is both a set of weights $\boldsymbol{\eta}$, and a predictor corresponding to the kernel method trained with kernel $K_{\boldsymbol{\eta}}$.
- This method is usually called **Multiple Kernel Learning (MKL)**.

Example: protein annotation



A statistical framework for genomic data fusion

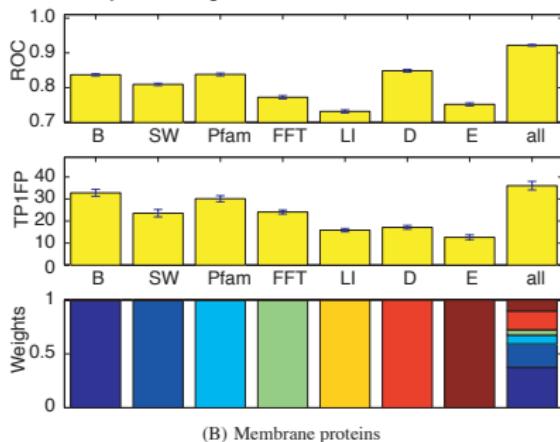
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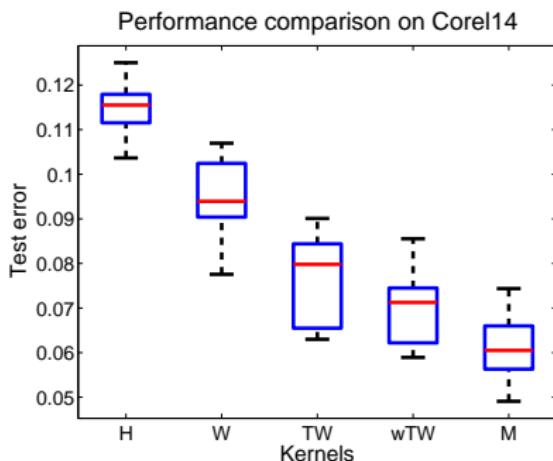


Kernel	Data	Similarity measure
K_{SW}	protein sequences	Smith-Waterman
K_B	protein sequences	BLAST
K_{Pfam}	protein sequences	Pfam HMM
K_{FFT}	hydrophathy profile	FFT
K_{LI}	protein interactions	linear kernel
K_D	protein interactions	diffusion kernel
K_E	gene expression	radial basis kernel
K_{RND}	random numbers	linear kernel

Example: Image classification (Harchaoui and Bach, 2007)

COREL14 dataset

- 1400 natural images in 14 classes
- Compare kernel between histograms (H), walk kernel (W), subtree kernel (TW), weighted subtree kernel (wTW), and a combination by MKL (M).



MKL revisited (Bach et al., 2004)

$$K_{\boldsymbol{\eta}} = \sum_{i=1}^M \eta_i K_i \quad \text{with} \quad \boldsymbol{\eta} \in \Sigma_M = \left\{ \boldsymbol{\eta} \geq 0, \sum_{i=1}^M \eta_i = 1 \right\}$$

Theorem

The solution f^* of

$$\min_{\boldsymbol{\eta} \in \Sigma_M} \min_{f \in \mathcal{H}_{K_{\boldsymbol{\eta}}}} \left\{ R(f^n) + \lambda \| f \|_{\mathcal{H}_{K_{\boldsymbol{\eta}}}}^2 \right\}$$

is $f^* = \sum_{i=1}^M f_i^*$, where $(f_1^*, \dots, f_M^*) \in \mathcal{H}_{K_1} \times \dots \times \mathcal{H}_{K_M}$ is the solution of:

$$\min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \left(\sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}} \right)^2 \right\}.$$

Proof (1/2)

$$\begin{aligned} & \min_{\eta \in \Sigma_M} \min_{f \in \mathcal{H}_{K_\eta}} \left\{ R(f^n) + \lambda \| f \|_{\mathcal{H}_{K_\eta}}^2 \right\} \\ &= \min_{\eta \in \Sigma_M} \min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \sum_{i=1}^M \frac{\| f_i \|_{\mathcal{H}_{K_i}}^2}{\eta_i} \right\} \\ &= \min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \min_{\eta \in \Sigma_M} \left\{ \sum_{i=1}^M \frac{\| f_i \|_{\mathcal{H}_{K_i}}^2}{\eta_i} \right\} \right\} \\ &= \min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \left(\sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}} \right)^2 \right\}, \end{aligned}$$

Proof (2/2)

where the last equality results from:

$$\forall \mathbf{a} \in \mathbb{R}_+^M, \quad \left(\sum_{i=1}^M a_i \right)^2 = \inf_{\boldsymbol{\eta} \in \Sigma_M} \sum_{i=1}^M \frac{a_i^2}{\eta_i},$$

which is a direct consequence of the Cauchy-Schwarz inequality:

$$\sum_{i=1}^M a_i = \sum_{i=1}^M \frac{a_i}{\sqrt{\eta_i}} \times \sqrt{\eta_i} \leq \left(\sum_{i=1}^M \frac{a_i^2}{\eta_i} \right)^{\frac{1}{2}} \left(\sum_{i=1}^M \eta_i \right)^{\frac{1}{2}}.$$

Algorithm: simpleMKL (Rakotomamonjy et al., 2008)

- We want to minimize in $\eta \in \Sigma_M$:

$$\min_{\eta \in \Sigma_M} J(K_\eta) = \min_{\eta \in \Sigma_M} \max_{\gamma \in \mathbb{R}^n} \left\{ -R^*(-2\lambda\gamma) - \lambda\gamma^\top K_\eta \gamma \right\}.$$

- For a fixed $\eta \in \Sigma_M$, we can compute $f(\eta) = J(K_\eta)$ by using a standard solver for a single kernel to find γ^* :

$$J(K_\eta) = -R^*(-2\lambda\gamma^*) - \lambda\gamma^{*\top} K_\eta \gamma^*.$$

- From γ^* we can also compute the gradient of $J(K_\eta)$ with respect to η :

$$\frac{\partial J(K_\eta)}{\partial \eta_i} = -\lambda\gamma^{*\top} K_i \gamma^*.$$

- $J(K_\eta)$ can then be minimized on Σ_M by a projected gradient or reduced gradient algorithm.

Sum kernel vs MKL

- Learning with the sum kernel (uniform combination) solves

$$\min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}}^2 \right\}.$$

- Learning with MKL (best convex combination) solves

$$\min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \left(\sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}} \right)^2 \right\}.$$

- Although MKL can be thought of as optimizing a convex combination of kernels, it is more correct to think of it as a penalized risk minimization estimator with the **group lasso** penalty:

$$\Omega(f) = \min_{f_1 + \dots + f_M = f} \sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}}.$$

Example: ridge vs LASSO regression

- Take $\mathcal{X} = \mathbb{R}^d$, and for $\mathbf{x} = (x_1, \dots, x_d)^\top$ consider the **rank-1 kernels**:

$$\forall i = 1, \dots, d, \quad K_i(\mathbf{x}, \mathbf{x}') = x_i x'_i.$$

- A function $f_i \in \mathcal{H}_{K_i}$ has the form $f_i(\mathbf{x}) = \beta_i x_i$, with $\|f_i\|_{\mathcal{H}_{K_i}} = |\beta_i|$
- The sum kernel is $K_S(\mathbf{x}, \mathbf{x}') = \sum_{i=1}^d x_i x'_i = \mathbf{x}^\top \mathbf{x}$, a function \mathcal{H}_{K_S} is of the form $f(\mathbf{x}) = \boldsymbol{\beta}^\top \mathbf{x}$, with norm $\|f\|_{\mathcal{H}_{K_S}} = \|\boldsymbol{\beta}\|_{\mathbb{R}^d}$.
- Learning with the **sum kernel** solves a **ridge regression** problem:

$$\min_{\boldsymbol{\beta} \in \mathbb{R}^d} \left\{ R(\mathbf{X}\boldsymbol{\beta}) + \lambda \sum_{i=1}^d \beta_i^2 \right\}.$$

- Learning with **MKL** solves a **LASSO regression** problem:

$$\min_{\boldsymbol{\beta} \in \mathbb{R}^d} \left\{ R(\mathbf{X}\boldsymbol{\beta}) + \lambda \left(\sum_{i=1}^d |\beta_i| \right)^2 \right\}.$$

Extensions (Micchelli et al., 2005)

For $r > 0$, $K_\eta = \sum_{i=1}^M \eta_i K_i$ with $\eta \in \Sigma_M^r = \left\{ \eta_i \geq 0, \sum_{i=1}^M \eta_i^r = 1 \right\}$

Theorem

The solution f^* of

$$\min_{\eta \in \Sigma_M^r} \min_{f \in \mathcal{H}_{K_\eta}} \left\{ R(f^n) + \lambda \| f \|_{\mathcal{H}_{K_\eta}}^2 \right\}$$

is $f^* = \sum_{i=1}^M f_i^*$, where $(f_1^*, \dots, f_M^*) \in \mathcal{H}_{K_1} \times \dots \times \mathcal{H}_{K_M}$ is the solution of:

$$\min_{f_1, \dots, f_M} \left\{ R \left(\sum_{i=1}^M f_i^n \right) + \lambda \left(\sum_{i=1}^M \| f_i \|_{\mathcal{H}_{K_i}}^{\frac{2r}{r+1}} \right)^{\frac{r+1}{r}} \right\}.$$

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics
 - Multiple Kernel Learning (MKL)
 - Large-scale learning with kernels
 - Foundations of deep learning from a kernel point of view

Outline

6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
 - Motivation
 - Interlude: Large-scale learning with linear models
 - Nyström approximations
 - Random Fourier features
- Foundations of deep learning from a kernel point of view

Motivation

Main problem

All methods we have seen require computing the $n \times n$ Gram matrix, which is infeasible when n is significantly greater than 100 000 both in terms of memory and computation.

Solutions

- low-rank approximation of the kernel;
- random Fourier features.

The goal is to find an approximate embedding $\psi : \mathcal{X} \rightarrow \mathbb{R}^d$ such that

$$K(\mathbf{x}, \mathbf{x}') \approx \langle \psi(\mathbf{x}), \psi(\mathbf{x}') \rangle_{\mathbb{R}^d}.$$

and use large-scale optimization techniques dedicated to linear models!

Motivation

Then, functions f in \mathcal{H} may be approximated by linear ones in \mathbb{R}^d , e.g.,.

$$f(\mathbf{x}) = \sum_{i=1}^n \alpha_i K(\mathbf{x}_i, \mathbf{x}) \approx \left\langle \sum_{i=1}^n \alpha_i \psi(\mathbf{x}_i), \psi(\mathbf{x}) \right\rangle_{\mathbb{R}^d} = \langle \mathbf{w}, \psi(\mathbf{x}) \rangle_{\mathbb{R}^d}.$$

Then, the ERM problem

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2,$$

becomes, approximately,

$$\min_{\mathbf{w} \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n L(y_i, \mathbf{w}^\top \psi(\mathbf{x}_i)) + \lambda \|\mathbf{w}\|_2^2,$$

which we know how to solve when n is large.

Outline

6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
 - Motivation
 - Interlude: Large-scale learning with linear models
 - Nyström approximations
 - Random Fourier features
- Foundations of deep learning from a kernel point of view

Interlude: Large-scale learning with linear models

Let us study for a while optimization techniques for minimizing large sums of functions

$$\min_{\mathbf{w} \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(\mathbf{w}).$$

Good candidates are

- **stochastic** optimization techniques;
- **randomized incremental** optimization techniques;

We will see a couple of such algorithms with their convergence rates and start with the (batch) gradient descent method.

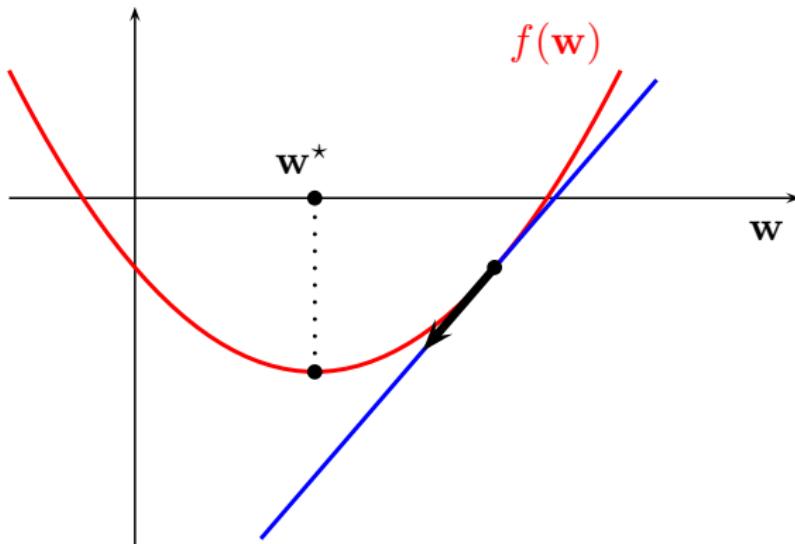
Introduction of a few optimization principles

Why do we care about convexity?

Introduction of a few optimization principles

Why do we care about convexity?

Local observations give information about the global optimum

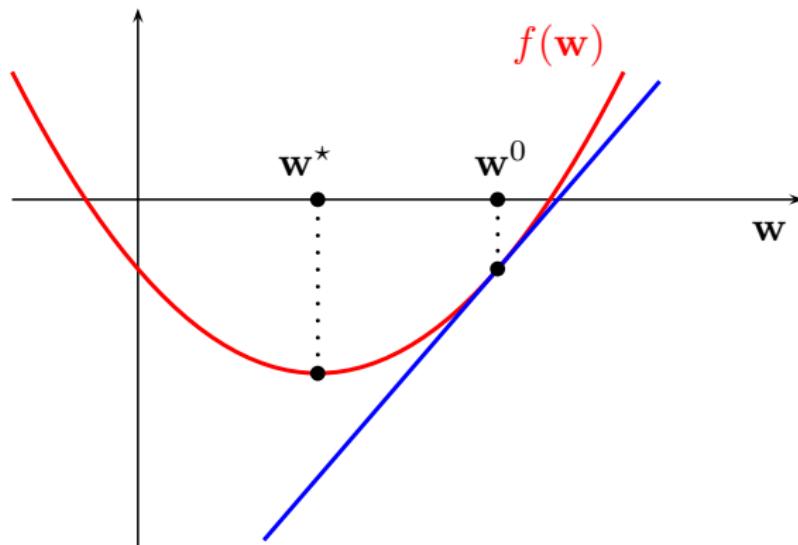


- $\nabla f(\mathbf{w}) = \mathbf{0}$ is a necessary and sufficient optimality condition for differentiable convex functions;
- it is often easy to upper-bound $f(\mathbf{w}) - f^*$.

Introduction of a few optimization principles

An important inequality for smooth convex functions

If f is convex

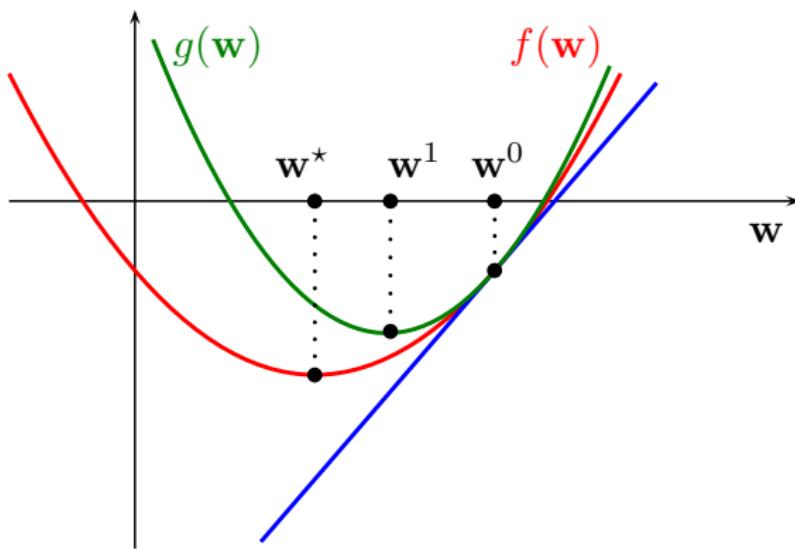


- $f(\mathbf{w}) \geq \underbrace{f(\mathbf{w}^0) + \nabla f(\mathbf{w}^0)^\top (\mathbf{w} - \mathbf{w}^0)}_{\text{linear approximation}};$
- this is an equivalent definition of convexity for smooth functions.

Introduction of a few optimization principles

An important inequality for smooth functions

If ∇f is L -Lipschitz continuous (f does not need to be convex)

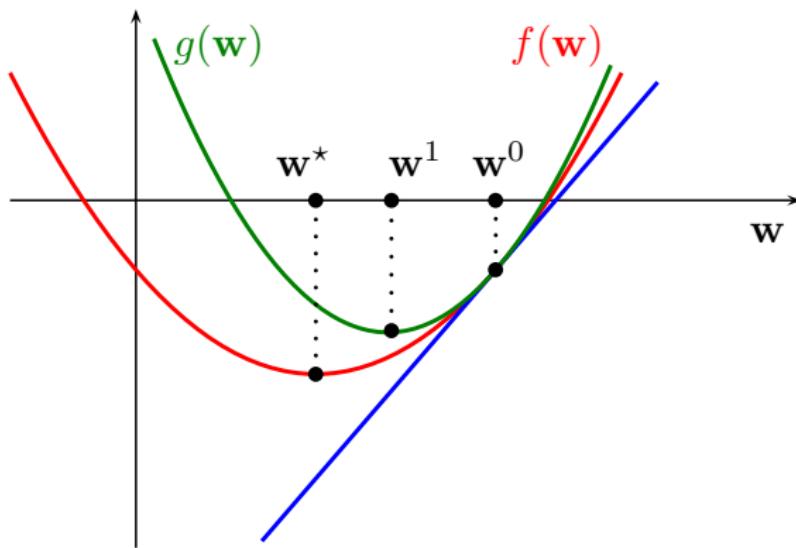


- $f(\mathbf{w}) \leq g(\mathbf{w}) = f(\mathbf{w}^0) + \nabla f(\mathbf{w}^0)^\top (\mathbf{w} - \mathbf{w}^0) + \frac{L}{2} \|\mathbf{w} - \mathbf{w}^0\|_2^2;$
- $g(\mathbf{w}) = C_{\mathbf{w}^0} + \frac{L}{2} \|\mathbf{w}^0 - (1/L)\nabla f(\mathbf{w}^0) - \mathbf{w}\|_2^2.$

Introduction of a few optimization principles

An important inequality for smooth functions

If ∇f is L -Lipschitz continuous (f does not need to be convex)



- $f(\mathbf{w}) \leq g(\mathbf{w}) = f(\mathbf{w}^0) + \nabla f(\mathbf{w}^0)^\top (\mathbf{w} - \mathbf{w}^0) + \frac{L}{2} \|\mathbf{w} - \mathbf{w}^0\|_2^2;$
- $\boxed{\mathbf{w}^1 = \mathbf{w}^0 - \frac{1}{L} \nabla f(\mathbf{w}^0)}$ (gradient descent step).

Introduction of a few optimization principles

Gradient Descent Algorithm

Assume that f is convex and differentiable, and that ∇f is L -Lipschitz.

Theorem

Consider the algorithm

$$\mathbf{w}^t \leftarrow \mathbf{w}^{t-1} - \frac{1}{L} \nabla f(\mathbf{w}^{t-1}).$$

Then,

$$f(\mathbf{w}^t) - f^* \leq \frac{L \|\mathbf{w}^0 - \mathbf{w}^*\|_2^2}{2t}.$$

Remarks

- the convergence rate improves under additional assumptions on f (strong convexity);
- some variants have a $O(1/t^2)$ convergence rate (Nesterov, 2004).

Proof (1/2)

Proof of the main inequality for smooth functions

We want to show that for all \mathbf{w} and \mathbf{z} ,

$$f(\mathbf{w}) \leq f(\mathbf{z}) + \nabla f(\mathbf{z})^\top (\mathbf{w} - \mathbf{z}) + \frac{L}{2} \|\mathbf{w} - \mathbf{z}\|_2^2.$$

Proof (1/2)

Proof of the main inequality for smooth functions

We want to show that for all \mathbf{w} and \mathbf{z} ,

$$f(\mathbf{w}) \leq f(\mathbf{z}) + \nabla f(\mathbf{z})^\top (\mathbf{w} - \mathbf{z}) + \frac{L}{2} \|\mathbf{w} - \mathbf{z}\|_2^2.$$

By using Taylor's theorem with integral form,

$$f(\mathbf{w}) - f(\mathbf{z}) = \int_0^1 \nabla f(t\mathbf{w} + (1-t)\mathbf{z})^\top (\mathbf{w} - \mathbf{z}) dt.$$

Then,

$$\begin{aligned} f(\mathbf{w}) - f(\mathbf{z}) - \nabla f(\mathbf{z})^\top (\mathbf{w} - \mathbf{z}) &\leq \int_0^1 (\nabla f(t\mathbf{w} + (1-t)\mathbf{z}) - \nabla f(\mathbf{z}))^\top (\mathbf{w} - \mathbf{z}) dt \\ &\leq \int_0^1 |(\nabla f(t\mathbf{w} + (1-t)\mathbf{z}) - \nabla f(\mathbf{z}))^\top (\mathbf{w} - \mathbf{z})| dt \\ &\leq \int_0^1 \|\nabla f(t\mathbf{w} + (1-t)\mathbf{z}) - \nabla f(\mathbf{z})\|_2 \|\mathbf{w} - \mathbf{z}\|_2 dt \quad (\text{C.-S.}) \\ &\leq \int_0^1 Lt \|\mathbf{w} - \mathbf{z}\|_2^2 dt = \frac{L}{2} \|\mathbf{w} - \mathbf{z}\|_2^2. \end{aligned}$$

Proof (2/2)

Proof of the theorem

We have shown that for all \mathbf{w} ,

$$f(\mathbf{w}) \leq g_t(\mathbf{w}) = f(\mathbf{w}^{t-1}) + \nabla f(\mathbf{w}^{t-1})^\top (\mathbf{w} - \mathbf{w}^{t-1}) + \frac{L}{2} \|\mathbf{w} - \mathbf{w}^{t-1}\|_2^2.$$

g_t is minimized by \mathbf{w}^t ; it can be rewritten $g_t(\mathbf{w}) = g_t(\mathbf{w}^t) + \frac{L}{2} \|\mathbf{w} - \mathbf{w}^t\|_2^2$. Then,

$$\begin{aligned} f(\mathbf{w}^t) &\leq g_t(\mathbf{w}^t) = g_t(\mathbf{w}^*) - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2 \\ &= f(\mathbf{w}^{t-1}) + \nabla f(\mathbf{w}^{t-1})^\top (\mathbf{w}^* - \mathbf{w}^{t-1}) + \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2 - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2 \\ &\leq f^* + \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2 - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2. \end{aligned}$$

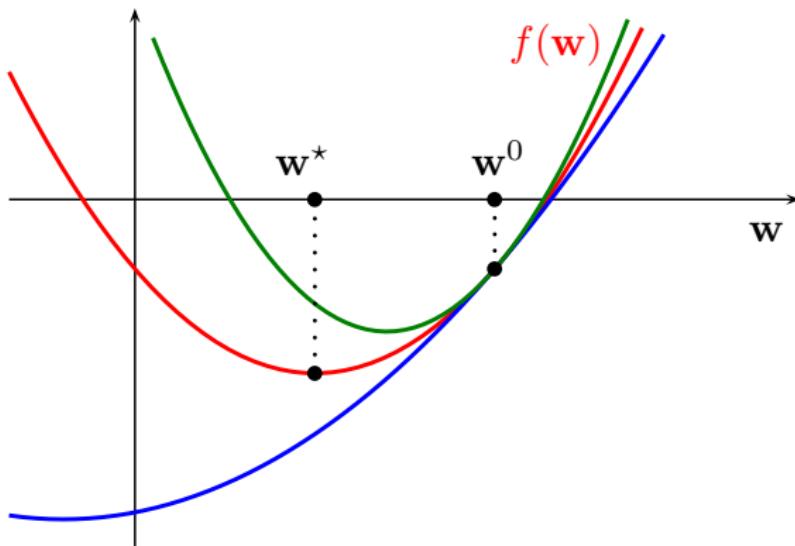
By summing from $t = 1$ to T , we have a telescopic sum

$$T(f(\mathbf{w}^T) - f^*) \leq \sum_{t=1}^T f(\mathbf{w}^t) - f^* \leq \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^0\|_2^2 - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^T\|_2^2.$$

Introduction of a few optimization principles

An important inequality for smooth and μ -strongly convex functions

If ∇f is L -Lipschitz continuous and f μ -strongly convex



- $f(\mathbf{w}) \leq f(\mathbf{w}^0) + \nabla f(\mathbf{w}^0)^\top (\mathbf{w} - \mathbf{w}^0) + \frac{L}{2} \|\mathbf{w} - \mathbf{w}^0\|_2^2;$
- $f(\mathbf{w}) \geq f(\mathbf{w}^0) + \nabla f(\mathbf{w}^0)^\top (\mathbf{w} - \mathbf{w}^0) + \frac{\mu}{2} \|\mathbf{w} - \mathbf{w}^0\|_2^2;$

Introduction of a few optimization principles

Proposition

When f is μ -strongly convex, differentiable and ∇f is L -Lipschitz, the gradient descent algorithm with step-size $1/L$ produces iterates such that

$$f(\mathbf{w}^t) - f^* \leq \left(1 - \frac{\mu}{L}\right)^t \frac{L\|\mathbf{w}^0 - \mathbf{w}^*\|_2^2}{2}.$$

We call that a **linear** convergence rate.

Proof

We start from an inequality from the previous proof

$$\begin{aligned} f(\mathbf{w}^t) &\leq f(\mathbf{w}^{t-1}) + \nabla f(\mathbf{w}^{t-1})^\top (\mathbf{w}^* - \mathbf{w}^{t-1}) + \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2 - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2 \\ &\leq f^* + \frac{L-\mu}{2} \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2 - \frac{L}{2} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2. \end{aligned}$$

In addition, we have that $f(\mathbf{w}^t) \geq f^* + \frac{\mu}{2} \|\mathbf{w}^t - \mathbf{w}^*\|_2^2$, and thus

$$\begin{aligned} \|\mathbf{w}^* - \mathbf{w}^t\|_2^2 &\leq \frac{L-\mu}{L+\mu} \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2 \\ &\leq \left(1 - \frac{\mu}{L}\right) \|\mathbf{w}^* - \mathbf{w}^{t-1}\|_2^2. \end{aligned}$$

Finally,

$$\begin{aligned} f(\mathbf{w}^t) - f^* &\leq \frac{L}{2} \|\mathbf{w}^t - \mathbf{w}^*\|_2^2 \\ &\leq \left(1 - \frac{\mu}{L}\right)^t \frac{L \|\mathbf{w}^* - \mathbf{w}^0\|_2^2}{2} \end{aligned}$$

The stochastic (sub)gradient descent algorithm

Consider now the minimization of an expectation

$$\min_{\mathbf{w} \in \mathbb{R}^p} f(\mathbf{w}) = \mathbb{E}_{\mathbf{x}}[\ell(\mathbf{x}, \mathbf{w})],$$

To simplify, we assume that for all \mathbf{x} , $\mathbf{w} \mapsto \ell(\mathbf{x}, \mathbf{w})$ is differentiable, but everything here is true for nonsmooth functions.

Algorithm

At iteration t ,

- Randomly draw one example \mathbf{x}_t from the training set;
- Update the current iterate

$$\mathbf{w}^t \leftarrow \mathbf{w}^{t-1} - \eta_t \nabla_{\mathbf{w}} \ell(\mathbf{x}_t, \mathbf{w}_{t-1}).$$

- Perform online averaging of the iterates (optional)

$$\tilde{\mathbf{w}}^t \leftarrow (1 - \gamma_t) \tilde{\mathbf{w}}^{t-1} + \gamma_t \mathbf{w}^t.$$

The stochastic (sub)gradient descent algorithm

There are various learning rates strategies (constant, varying step-sizes), and averaging strategies. Depending on the problem assumptions and choice of η_t , γ_t , classical convergence rates may be obtained:

- $f(\tilde{\mathbf{w}}^t) - f^* = O(1/\sqrt{t})$ for convex problems;
- $f(\tilde{\mathbf{w}}^t) - f^* = O(1/t)$ for strongly-convex ones;

Remarks

- The convergence rates are not that great, but the complexity **per-iteration** is small (1 gradient evaluation for minimizing an empirical risk versus n for the batch algorithm).
- When the amount of data is infinite, the method **minimizes the expected risk**.
- Choosing a good learning rate automatically is an open problem.

Randomized incremental algorithms (1/2)

Consider now the minimization of a large finite sum of smooth convex functions:

$$\min_{\mathbf{w} \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^n f_i(\mathbf{w}),$$

A class of algorithms with low per-iteration complexity have been recently introduced that enjoy **exponential** (aka, linear) convergence rates for strongly-convex problems, e.g., SAG (Schmidt et al., 2016).

SAG algorithm

$$\mathbf{w}^t \leftarrow \mathbf{w}^{t-1} - \frac{\gamma}{Ln} \sum_{i=1}^n \mathbf{y}_i^t \quad \text{with} \quad \mathbf{y}_i^t = \begin{cases} \nabla f_i(\mathbf{w}^{t-1}) & \text{if } i = i_t \\ \mathbf{y}_i^{t-1} & \text{otherwise} \end{cases}.$$

See also SAGA (Defazio et al., 2014), SVRG (Xiao and Zhang, 2014), SDCA (Shalev-Shwartz and Zhang, 2015), MISO (Mairal, 2015);

Randomized incremental algorithms (2/2)

Many of these techniques are in fact performing SGD-types of steps

$$\mathbf{w}^t \leftarrow \mathbf{w}^{t-1} - \eta_t \mathbf{g}_t,$$

where $\mathbb{E}[\mathbf{g}_t | \mathbf{w}_{t-1}] = \nabla f(\mathbf{w}_{t-1})$, but where the estimator of the gradient has **lower variance** than in SGD, see SVRG (Xiao and Zhang, 2014).

Typically, these methods have the convergence rate

$$f(\mathbf{w}_t) - f^* = O\left(\left(1 - C \max\left(\frac{1}{n}, \frac{\mu}{L}\right)\right)^t\right)$$

Remarks

- their complexity per-iteration is independent of n !
- unlike SGD, they are often almost parameter-free.
- besides, they can be accelerated (Lin et al., 2015).

Large-scale learning with linear models

Conclusion

- we know how to deal with huge-scale **linear** problems;
- **this is also useful to learn with kernels!**

Outline

6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
 - Motivation
 - Interlude: Large-scale learning with linear models
 - Nyström approximations
 - Random Fourier features
- Foundations of deep learning from a kernel point of view

Nyström approximations: principle

Consider a p.d. kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ and RKHS \mathcal{H} , with the mapping $\varphi : \mathcal{X} \rightarrow \mathcal{H}$ such that

$$K(\mathbf{x}, \mathbf{x}') = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle_{\mathcal{H}}.$$

The Nyström method consists of replacing any point $\varphi(\mathbf{x})$ in \mathcal{H} , for \mathbf{x} in \mathcal{X} by its orthogonal projection onto a **finite-dimensional subspace**

$$\mathcal{F} := \text{Span}(f_1, \dots, f_p) \quad \text{with } p \ll n,$$

where the f_i 's are **anchor points** in \mathcal{H} (to be defined later).

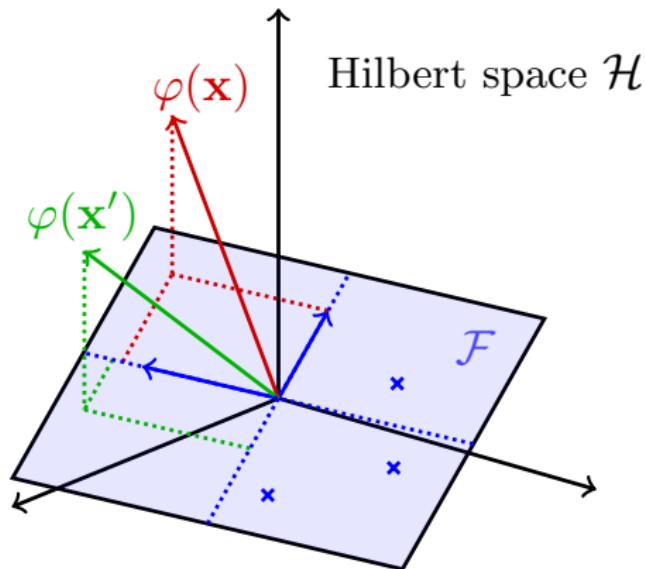
Motivation

- This principle allows us to work explicitly in a **finite-dimensional space**; it was introduced several times in the kernel literature [Williams and Seeger, 2002], [Smola and Schölkopf, 2000], [Fine and Scheinberg, 2001].

Nyström approximations: principle

The orthogonal projection is defined as

$$\Pi_{\mathcal{F}}[\mathbf{x}] := \operatorname{argmin}_{f \in \mathcal{F}} \|\varphi(\mathbf{x}) - f\|_{\mathcal{H}}^2,$$



Nyström approximations: principle

The projection is equivalent to

$$\Pi_{\mathcal{F}}[\mathbf{x}] := \sum_{j=1}^p \beta_j^* f_j \quad \text{with} \quad \beta^* \in \operatorname{argmin}_{\beta \in \mathbb{R}^p} \left\| \varphi(\mathbf{x}) - \sum_{j=1}^p \beta_j f_j \right\|_{\mathcal{H}}^2,$$

and β^* is the solution of the problem

$$\min_{\beta \in \mathbb{R}^p} -2 \sum_{j=1}^p \beta_j \langle f_j, \varphi(\mathbf{x}) \rangle_{\mathcal{H}} + \sum_{j,l=1}^p \beta_j \beta_l \langle f_j, f_l \rangle_{\mathcal{H}},$$

or also

$$\min_{\beta \in \mathbb{R}^p} -2 \sum_{j=1}^p \beta_j f_j(\mathbf{x}) + \sum_{j,l=1}^p \beta_j \beta_l \langle f_j, f_l \rangle_{\mathcal{H}}.$$

Nyström approximations: principle

Then, call $[\mathbf{K}_f]_{jl} = \langle f_j, f_l \rangle_{\mathcal{H}}$ and $\mathbf{f}(\mathbf{x}) = [f_1(\mathbf{x}), \dots, f_p(\mathbf{x})]$ in \mathbb{R}^p . The problem may be rewritten as

$$\min_{\beta \in \mathbb{R}^p} -2\beta^\top \mathbf{f}(\mathbf{x}) + \beta^\top \mathbf{K}_f \beta,$$

and, assuming \mathbf{K}_f to be non-singular for simplicity, the solution is $\beta^*(\mathbf{x}) = \mathbf{K}_f^{-1}\mathbf{f}(\mathbf{x})$. Then,

$$\varphi(\mathbf{x}) \approx \sum_{j=1}^p \beta_j^*(\mathbf{x}) f_j,$$

and

$$\begin{aligned} \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle_{\mathcal{H}} &\approx \left\langle \sum_{j=1}^p \beta_j^*(\mathbf{x}) f_j, \sum_{j=1}^p \beta_j^*(\mathbf{x}') f_j \right\rangle_{\mathcal{H}} \\ &= \sum_{j,l=1}^p \beta_j^*(\mathbf{x}) \beta_l^*(\mathbf{x}') \langle f_j, f_l \rangle_{\mathcal{H}} = \beta^*(\mathbf{x})^\top \mathbf{K}_f \beta^*(\mathbf{x}'). \end{aligned}$$

Nyström approximations: principle

This allows us to define the mapping

$$\psi(\mathbf{x}) = \mathbf{K}_f^{1/2} \beta^*(\mathbf{x}) = \mathbf{K}_f^{-1/2} \mathbf{f}(\mathbf{x}),$$

and we have the approximation $K(\mathbf{x}, \mathbf{x}') \approx \langle \psi(\mathbf{x}), \psi(\mathbf{x}') \rangle_{\mathbb{R}^p}$.

Remarks

- the mapping provides low-rank approximations of the kernel matrix.
Given an $n \times n$ Gram matrix \mathbf{K} computed on a training set
 $\mathcal{S} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$, we have

$$\mathbf{K} \approx \psi(\mathcal{S})^\top \psi(\mathcal{S}),$$

where $\psi(\mathcal{S}) := [\psi(\mathbf{x}_1), \dots, \psi(\mathbf{x}_n)]$.

- the approximation has a **geometric interpretation**.
- We need to **define a good strategy** for choosing the f_j 's.

Nyström approximation via kernel PCA

Let us now try to **learn** the f_j 's given training data $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X} :

$$\min_{\substack{f_1, \dots, f_p \in \mathcal{H} \\ \beta_{ij} \in \mathbb{R}}} \sum_{i=1}^n \left\| \varphi(\mathbf{x}_i) - \sum_{j=1}^p \beta_{ij} f_j \right\|_{\mathcal{H}}^2.$$

Using similar calculation as before, the objective is equivalent to

$$\min_{\substack{f_1, \dots, f_p \in \mathcal{H} \\ \beta_i \in \mathbb{R}^p}} \sum_{i=1}^n -2\beta_i^\top \mathbf{f}(\mathbf{x}_i) + \beta_i^\top \mathbf{K}_f \beta_i,$$

and, by minimizing with respect to all β_i with \mathbf{f} fixed, we have that $\beta_i = \mathbf{K}_f^{-1} \mathbf{f}(\mathbf{x}_i)$ (assuming \mathbf{K}_f to be invertible), which leads to

$$\max_{f_1, \dots, f_p \in \mathcal{H}} \sum_{i=1}^n \mathbf{f}(\mathbf{x}_i)^\top \mathbf{K}_f^{-1} \mathbf{f}(\mathbf{x}_i).$$

Nyström approximation via kernel PCA

Remember the objective:

$$\max_{f_1, \dots, f_p \in \mathcal{H}} \sum_{i=1}^n \mathbf{f}(\mathbf{x}_i)^\top \mathbf{K}_{\mathbf{f}}^{-1} \mathbf{f}(\mathbf{x}_i).$$

Consider an optimal solution \mathbf{f}^* and compute the eigenvalue decomposition of $\mathbf{K}_{\mathbf{f}^*} = \mathbf{U}\Delta\mathbf{U}^\top$. Then, define the functions

$$\mathbf{g}^*(\mathbf{x}) := [g_1^*(\mathbf{x}), \dots, g_p^*(\mathbf{x})] = \Delta^{-1/2} \mathbf{U}^\top \mathbf{f}^*(\mathbf{x}).$$

The functions g_j^* are points in the RKHS \mathcal{H} since they are linear combinations of the functions f_j^* in \mathcal{H} .

Nyström approximation via kernel PCA

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Exercise: check that all we do here and in the next slides can be extended to deal with singular Gram matrices $\mathbf{K}_{\mathbf{f}^}$ and $\mathbf{K}_{\mathbf{f}}$.*

Nyström approximation via kernel PCA

Besides, by construction

$$\begin{aligned} [\mathbf{K}_{\mathbf{g}^*}]_{jl} &:= \langle g_j^*, g_l^* \rangle_{\mathcal{H}} \\ &= \left\langle \frac{1}{\sqrt{\Delta_{jj}}} \sum_{k=1}^p [\mathbf{U}]_{kj} f_k^*, \frac{1}{\sqrt{\Delta_{ll}}} \sum_{k=1}^p [\mathbf{U}]_{kl} f_k^* \right\rangle_{\mathcal{H}} \\ &= \frac{1}{\sqrt{\Delta_{jj}}} \frac{1}{\sqrt{\Delta_{ll}}} \sum_{k,k'=1}^p [\mathbf{U}]_{kj} [\mathbf{U}]_{k'l} \langle f_k^*, f_{k'}^* \rangle_{\mathcal{H}} \\ &= \frac{1}{\sqrt{\Delta_{jj}}} \frac{1}{\sqrt{\Delta_{ll}}} \sum_{k,k'=1}^p [\mathbf{U}]_{kj} [\mathbf{U}]_{k'l} [\mathbf{K}_{f^*}]_{kk'} \\ &= \frac{1}{\sqrt{\Delta_{jj}}} \frac{1}{\sqrt{\Delta_{ll}}} \mathbf{u}_j^\top \mathbf{K}_{f^*} \mathbf{u}_l \\ &= \delta_{j=l}. \end{aligned}$$

Nyström approximation via kernel PCA

Then, $\mathbf{K}_{\mathbf{g}^*} = \mathbf{I}$ and \mathbf{g}^* is also a solution of the problem

$$\max_{f_1, \dots, f_p \in \mathcal{H}} \sum_{i=1}^n \mathbf{f}(\mathbf{x}_i)^\top \mathbf{K}_{\mathbf{f}}^{-1} \mathbf{f}(\mathbf{x}_i),$$

since

$$\begin{aligned}\mathbf{f}^*(\mathbf{x}_i)^\top \mathbf{K}_{\mathbf{f}^*}^{-1} \mathbf{f}^*(\mathbf{x}_i) &= \mathbf{f}^*(\mathbf{x}_i)^\top \mathbf{U} \mathbf{\Delta}^{-1} \mathbf{U}^\top \mathbf{f}^*(\mathbf{x}_i) \\ &= \mathbf{g}^*(\mathbf{x}_i)^\top \mathbf{g}^*(\mathbf{x}_i) = \mathbf{g}^*(\mathbf{x}_i)^\top \mathbf{K}_{\mathbf{g}^*}^{-1} \mathbf{g}^*(\mathbf{x}_i),\end{aligned}$$

and also a solution of the problem

$$\max_{g_1, \dots, g_p \in \mathcal{H}} \sum_{j=1}^p \sum_{i=1}^n g_j(\mathbf{x}_i)^2 \quad \text{s.t. } g_j \perp g_k \text{ for } k \neq j \text{ and } \|g_j\|_{\mathcal{H}} = 1.$$

Nyström approximation via kernel PCA

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and also a solution of the problem

$$\max_{g_1, \dots, g_p \in \mathcal{H}} \sum_{j=1}^p \sum_{i=1}^n g_j(\mathbf{x}_i)^2 \quad \text{s.t. } g_j \perp g_k \text{ for } k \neq j \text{ and } \|g_j\|_{\mathcal{H}} = 1.$$

This is the kernel PCA formulation!

Nyström approximation via kernel PCA

Our first recipe with kernel PCA

Given a dataset of n training points $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X} ,

- randomly choose a subset $\mathcal{Z} = [\mathbf{x}_{z_1}, \dots, \mathbf{x}_{z_m}]$ of $m \leq n$ training points;
- compute the $m \times m$ kernel matrix $\mathbf{K}_{\mathcal{Z}}$.
- **perform kernel PCA** to find the $p \leq m$ largest principal directions (parametrized by p vectors α_j in \mathbb{R}^m);

Then, every point \mathbf{x} in \mathcal{X} may be approximated by

$$\begin{aligned}\psi(\mathbf{x}) &= \mathbf{K}_{\mathbf{g}^*}^{-1/2} \mathbf{g}^*(\mathbf{x}) = \mathbf{g}^*(\mathbf{x}) = [g_1^*(\mathbf{x}), \dots, g_p^*(\mathbf{x})]^\top \\ &= \left[\sum_{i=1}^m \alpha_{1i} K(\mathbf{x}_{z_i}, \mathbf{x}), \dots, \sum_{i=1}^m \alpha_{pi} K(\mathbf{x}_{z_i}, \mathbf{x}) \right]^\top.\end{aligned}$$

Nyström approximation via kernel PCA

Remarks

- The vector $\psi(\mathbf{x})$ can be interpreted as coordinates of the projection of $\varphi(\mathbf{x})$ onto the (orthogonal) PCA basis.
- The complexity of training is $O(m^3)$ (eig decomposition of $\mathbf{K}_{\mathcal{Z}}$) + $O(m^2)$ kernel evaluations.
- The complexity of encoding a new point \mathbf{x} is $O(mp)$ (matrix vector multiplication) + $O(m)$ kernel evaluations.

Nyström approximation via kernel PCA

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The main issue is the encoding time, which depends linearly on $m > p$.

Nyström approximation via random sampling

A popular alternative is instead to select the anchor points among the training data points $\mathbf{x}_1, \dots, \mathbf{x}_n$ —that is,

$$\mathcal{F} := \text{span}(\varphi(\mathbf{x}_{z_1}), \dots, \varphi(\mathbf{x}_{z_p})).$$

In other words, choose $f_1 = \varphi(\mathbf{x}_{z_1}), \dots, f_p = \varphi(\mathbf{x}_{z_p})$.

Second recipe with random point sampling

Given a dataset of n training points $\mathbf{x}_1, \dots, \mathbf{x}_n$ in \mathcal{X} ,

- randomly choose a subset $\mathcal{Z} = [\mathbf{x}_{z_1}, \dots, \mathbf{x}_{z_p}]$ of p training points;
- compute the $p \times p$ kernel matrix $\mathbf{K}_{\mathcal{Z}}$.

Then, a new point \mathbf{x} is encoded as

$$\begin{aligned}\psi(\mathbf{x}) &= \mathbf{K}_{\mathcal{Z}}^{-1/2} \mathbf{f}_{\mathcal{Z}}(\mathbf{x}) \\ &= \mathbf{K}_{\mathcal{Z}}^{-1/2} [K(\mathbf{x}_{z_1}, \mathbf{x}), \dots, K(\mathbf{x}_{z_p}, \mathbf{x})]^\top\end{aligned}$$

Nyström approximation via random sampling

- The complexity of training is $O(p^3)$ (eig decomposition) + $O(p^2)$ kernel evaluations.
- The complexity of encoding a point \mathbf{x} is $O(p^2)$ (matrix vector multiplication) + $O(p)$ kernel evaluations.

Nyström approximation via random sampling

- The complexity of training is $O(p^3)$ (eig decomposition) + $O(p^2)$ kernel evaluations.
- The complexity of encoding a point \mathbf{x} is $O(p^2)$ (matrix vector multiplication) + $O(p)$ kernel evaluations.

The main issue complexity is better, but we lose the “optimality” of the PCA basis and the random choice of anchor points is not clever.

Nyström approximation via greedy approach

Better approximation can be obtained with a **greedy algorithm** that iteratively selects one column at a time with largest residual (Bach and Jordan, 2002; Smola and Shölkopf, 2000, Fine and Scheinberg, 2000).

At iteration k , assume that $\mathcal{Z} = \{\mathbf{x}_{z_1}, \dots, \mathbf{x}_{z_k}\}$; then, the residual for a data point \mathbf{x} encoded with k anchor points f_1, \dots, f_k is

$$\min_{\beta \in \mathbb{R}^k} \left\| \varphi(\mathbf{x}) - \sum_{j=1}^k \beta_j \varphi(\mathbf{x}_j) \right\|_{\mathcal{H}}^2,$$

which is equal to

$$\|\varphi(\mathbf{x})\|_{\mathcal{H}}^2 - \mathbf{f}_{\mathcal{Z}}(\mathbf{x})^\top \mathbf{K}_{\mathcal{Z}}^{-1} \mathbf{f}_{\mathcal{Z}}(\mathbf{x}),$$

and since $f_j = \varphi(\mathbf{x}_{z_j})$ for all j , the data point \mathbf{x}_i with largest residual is the one that maximizes

$$K(\mathbf{x}_i, \mathbf{x}_i) - \mathbf{f}_{\mathcal{Z}}(\mathbf{x}_i) \mathbf{K}_{\mathcal{Z}}^{-1} \mathbf{f}_{\mathcal{Z}}(\mathbf{x}_i) \quad \text{with} \quad \mathbf{f}_{\mathcal{Z}}(\mathbf{x}_i) = [K(\mathbf{x}_{z_1}, \mathbf{x}_i), \dots, K(\mathbf{x}_{z_k}, \mathbf{x}_i)]^\top.$$

Nyström approximation via greedy approach

This brings us to the following algorithm

Third recipe with greedy anchor point selection

Initialize $Z = \emptyset$. For $k = 1, \dots, p$ do

- **data point selection**

$$z_k \leftarrow \operatorname{argmax}_{i \in \{1, \dots, n\}} K(\mathbf{x}_i, \mathbf{x}_i) - \mathbf{f}_Z(\mathbf{x}_i) \mathbf{K}_Z^{-1} \mathbf{f}_Z(\mathbf{x}_i);$$

- **update the set \mathcal{Z}**

$$\mathcal{Z} \leftarrow \mathcal{Z} \cup \{\mathbf{x}_{z_k}\}.$$

Remarks

- A naive implementation costs $(O(k^2n + k^3))$ at every iteration.
- To get a reasonable complexity, one has to use simple linear algebra tricks (see next slide).

Nyström approximation via greedy approach

If $\mathcal{Z}' = \mathcal{Z} \cup \{\mathbf{z}\}$,

$$\mathbf{K}_{\mathcal{Z}'}^{-1} = \begin{bmatrix} \mathbf{K}_{\mathcal{Z}} & \mathbf{f}_{\mathcal{Z}}(\mathbf{z}) \\ \mathbf{f}_{\mathcal{Z}}(\mathbf{z})^\top & K(\mathbf{z}, \mathbf{z}) \end{bmatrix}^{-1} = \begin{bmatrix} \mathbf{K}_{\mathcal{Z}}^{-1} + \frac{1}{s} \mathbf{b} \mathbf{b}^\top & -\frac{1}{s} \mathbf{b} \\ -\frac{1}{s} \mathbf{b}^\top & \frac{1}{s} \end{bmatrix},$$

where s is the Schur complement $s = K(\mathbf{z}, \mathbf{z}) - \mathbf{f}_{\mathcal{Z}}(\mathbf{z}) \mathbf{K}_{\mathcal{Z}}^{-1} \mathbf{f}_{\mathcal{Z}}(\mathbf{z})$, and $\mathbf{b} = \mathbf{K}_{\mathcal{Z}}^{-1} \mathbf{f}_{\mathcal{Z}}(\mathbf{z})$.

Complexity analysis

- $\mathbf{K}_{\mathcal{Z}'}^{-1}$ can be obtained from $\mathbf{K}_{\mathcal{Z}}^{-1}$ and $\mathbf{f}_{\mathcal{Z}}(\mathbf{z})$ in $O(k^2)$ float operations; for that we need to always keep into memory the n vectors $\mathbf{f}_{\mathcal{Z}}(\mathbf{x}_i)$.
- updating the $\mathbf{f}_{\mathcal{Z}'}(\mathbf{x}_i)$'s from $\mathbf{f}_{\mathcal{Z}}(\mathbf{x}_i)$ requires n kernel evaluations;

The total training complexity is $O(p^2n)$ float operations and $O(pn)$ kernel evaluations

Nyström approximation via K-means

When $\mathcal{X} = \mathbb{R}^d$, it is also possible to synthesize points $\mathbf{z}_1, \dots, \mathbf{z}_p$ such that they represented well some training data $\mathbf{x}_1, \dots, \mathbf{x}_n$, leading to the **Clustred Nyström approximation** (Zhang and Kwok, 2008).

Fourth recipe with K-means

- ① Perform the regular K-means algorithm on the training data, to obtain p centroids $\mathbf{z}_1, \dots, \mathbf{z}_p$ in \mathbb{R}^p .
- ② Define the anchor points $f_j = \varphi(\mathbf{z}_j)$ for $j = 1, \dots, p$, and perform the classical Nyström approximation.

Remarks

- The complexity is the same as Nyström with random selection (except for the K-means step);
- The method is data-dependent and can significantly outperform the other variants in practice.

Nyström approximation: conclusion

Concluding remarks

- The greedy selection rule is equivalent to computing an **incomplete Cholesky factorization** of the kernel matrix (Bach and Jordan, 2002; Schölkopf and Smola, 2000, Fine and Scheinberg, 2001);
- The techniques we have seen produce low-rank approximations of the kernel matrix $\mathbf{K} \approx \mathbf{L}\mathbf{L}^\top$;
- The method admits a **geometric interpretation** in terms of orthogonal projection onto a finite-dimensional subspace.
- The approximation **provides points in the RKHS**. As such, many operations on the mapping are valid (translations, linear combinations, projections), unlike the method that will come next.

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Random Fourier features [Rahimi and Recht, 2007] (1/5)

A large class of approximations for shift-invariant kernels are based on sampling techniques. Consider a real-valued positive-definite continuous translation-invariant kernel $K(\mathbf{x}, \mathbf{y}) = \kappa(\mathbf{x} - \mathbf{y})$ with $\kappa : \mathbb{R}^d \rightarrow \mathbb{R}$. Then, if $\kappa(0) = 1$, Bochner theorem tells us that κ is a **valid characteristic function for some probability measure**

$$\kappa(\mathbf{z}) = \mathbb{E}_{\mathbf{w}}[e^{i\mathbf{w}^\top \mathbf{z}}].$$

Remember indeed that, with the right assumptions on κ ,

$$\kappa(\mathbf{x} - \mathbf{y}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \hat{\kappa}(\mathbf{w}) e^{i\mathbf{w}^\top \mathbf{x}} e^{-i\mathbf{w}^\top \mathbf{y}} d\mathbf{w},$$

and the probability measure admits a density $q(\mathbf{w}) = \frac{1}{(2\pi)^d} \hat{\kappa}(\mathbf{w})$ (non-negative, real-valued, sum to 1 since $\kappa(0) = 1$).

Random Fourier features (2/5)

Then,

$$\begin{aligned}\kappa(\mathbf{x} - \mathbf{y}) &= \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \hat{\kappa}(\mathbf{w}) e^{i\mathbf{w}^\top \mathbf{x}} e^{-i\mathbf{w}^\top \mathbf{y}} d\mathbf{w} \\ &= \int_{\mathbb{R}^d} q(\mathbf{w}) \cos(\mathbf{w}^\top \mathbf{x} - \mathbf{w}^\top \mathbf{y}) d\mathbf{w} \\ &= \int_{\mathbb{R}^d} q(\mathbf{w}) \left(\cos(\mathbf{w}^\top \mathbf{x}) \cos(\mathbf{w}^\top \mathbf{y}) + \sin(\mathbf{w}^\top \mathbf{x}) \sin(\mathbf{w}^\top \mathbf{y}) \right) d\mathbf{w} \\ &= \int_{\mathbb{R}^d} \int_{b=0}^{2\pi} \frac{q(\mathbf{w})}{2\pi} 2 \cos(\mathbf{w}^\top \mathbf{x} + b) \cos(\mathbf{w}^\top \mathbf{y} + b) d\mathbf{w} db \quad (\text{exercise}) \\ &= \mathbb{E}_{\mathbf{w} \sim q(\mathbf{w}), b \sim \mathcal{U}[0, 2\pi]} \left[\sqrt{2} \cos(\mathbf{w}^\top \mathbf{x} + b) \sqrt{2} \cos(\mathbf{w}^\top \mathbf{y} + b) \right]\end{aligned}$$

Random Fourier features (3/5)

Random Fourier features recipe

- Compute the Fourier transform of the kernel $\hat{\kappa}$ and define the probability density $q(\mathbf{w}) = \hat{\kappa}(\mathbf{w})/(2\pi)^d$;
- Draw p i.i.d. samples $\mathbf{w}_1, \dots, \mathbf{w}_p$ from q and p i.i.d. samples b_1, \dots, b_p from the uniform distribution on $[0, 2\pi]$;
- define the mapping

$$\mathbf{x} \mapsto \psi(\mathbf{x}) = \sqrt{\frac{2}{d}} \begin{bmatrix} \cos(\mathbf{w}_1^\top \mathbf{x} + b_1), \dots, \cos(\mathbf{w}_p^\top \mathbf{x} + b_p) \end{bmatrix}^\top.$$

Then, we have that

$$\kappa(\mathbf{x} - \mathbf{y}) \approx \langle \psi(\mathbf{x}), \psi(\mathbf{y}) \rangle_{\mathbb{R}^p}.$$

The two quantities are equal in expectation.

Random Fourier features (4/5)

Theorem, [Rahimi and Recht, 2007]

On any compact subset \mathcal{X} of \mathbb{R}^m , for all $\varepsilon > 0$,

$$\mathbb{P} \left[\sup_{\mathbf{x}, \mathbf{y} \in \mathcal{X}} |\kappa(\mathbf{x} - \mathbf{y}) - \langle \psi(\mathbf{x}), \psi(\mathbf{y}) \rangle_{\mathbb{R}^p}| \geq \varepsilon \right] \leq 2^8 \left(\frac{\sigma_q \text{diam}(\mathcal{X})}{\varepsilon} \right)^2 e^{-\frac{p\varepsilon^2}{4(m+2)}},$$

where $\sigma_q^2 = \mathbb{E}_{\mathbf{w} \sim q(\mathbf{w})} [\mathbf{w}^\top \mathbf{w}]$ is the second moment of the Fourier transform of κ .

Remarks

- The convergence is uniform, **not data dependent**;
- Take the sequence $\varepsilon_p = \sqrt{\frac{\log(p)}{p}} \sigma_q \text{diam}(\mathcal{X})$; Then the term on the right converges to zero when p grows to infinity;
- **Prediction functions with Random Fourier features are not in \mathcal{H} .**

Random Fourier features (5/5)

Ingredients of the proof

- For a *fixed* pair of points \mathbf{x}, \mathbf{y} , Hoeffding's inequality says that

$$\mathbb{P}\left[\underbrace{|\kappa(\mathbf{x} - \mathbf{y}) - \langle \psi(\mathbf{x}), \psi(\mathbf{y}) \rangle_{\mathbb{R}^d}|}_{f(\mathbf{x}, \mathbf{y})} \geq \varepsilon\right] \leq 2e^{-\frac{p\varepsilon^2}{4}}.$$

- Consider a net (set of balls of radius r) that covers $\mathcal{X}_\Delta = \{\mathbf{x} - \mathbf{y} : (\mathbf{x}, \mathbf{y}) \in \mathcal{X}\}$ with at most $T = (4\text{diam}(\mathcal{X})/r)^m$ balls.
- Apply the Hoeffding's inequality to the centers $\mathbf{x}_i - \mathbf{y}_i$ of the balls;
- Use a basic union bound

$$\mathbb{P}\left[\sup_i f(\mathbf{x}_i, \mathbf{y}_i) \geq \frac{\varepsilon}{2}\right] \leq \sum_i \mathbb{P}\left[f(\mathbf{x}_i, \mathbf{y}_i) \geq \frac{\varepsilon}{2}\right] \leq 2Te^{-\frac{p\varepsilon^2}{8}}.$$

- Glue things together: control the probability for points (\mathbf{x}, \mathbf{y}) inside each ball, and adjust the radius r (a bit technical).

Outline

- 1 Kernels and RKHS
- 2 Kernel tricks
- 3 Kernel Methods: Supervised Learning
- 4 Kernel Methods: Unsupervised Learning
- 5 The Kernel Jungle
- 6 Open Problems and Research Topics
 - Multiple Kernel Learning (MKL)
 - Large-scale learning with kernels
 - Foundations of deep learning from a kernel point of view

Outline

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- Large-scale learning with kernels
- Foundations of deep learning from a kernel point of view
 - Motivation
 - Deep kernel machines
 - Deep learning theory
 - Application to biological sequences

Motivation

Theoretical tools for understanding deep neural networks

- Can we define a functional space \mathcal{H} and a mapping $\Phi : \mathcal{X} \rightarrow \mathcal{H}$ for deep neural networks.
- What are the properties of Φ ? Does it preserve signal information?
Is it stable to input perturbations?

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Regularization mechanisms for deep neural networks

- Can we find a norm $\|f\|_{\mathcal{H}}$ for regularizing these models?

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Regularization mechanisms for deep neural networks

- Can we find a norm $\|f\|_{\mathcal{H}}$ for regularizing these models?

New models and algorithms

- Does a new point of view lead to better models and algorithms?

Success of deep learning



ENGLISH - DETECTED ENGLISH CHI FRENCH CHINESE (TRADITIONAL)

where is the train station? × où est la gare?

Microphone icon 27/5000 Pen icon Speaker icon

In the context of supervised learning

The goal is to learn a **prediction function** $f : \mathcal{X} \rightarrow \mathcal{Y}$ given labeled training data $(x_i, y_i)_{i=1,\dots,n}$ with x_i in \mathcal{X} , and y_i in \mathcal{Y} :

$$\min_{f \in \mathcal{F}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, f(x_i))}_{\text{empirical risk, data fit}} + \underbrace{\lambda \Omega(f)}_{\text{regularization}}.$$

What is specific to multilayer neural networks?

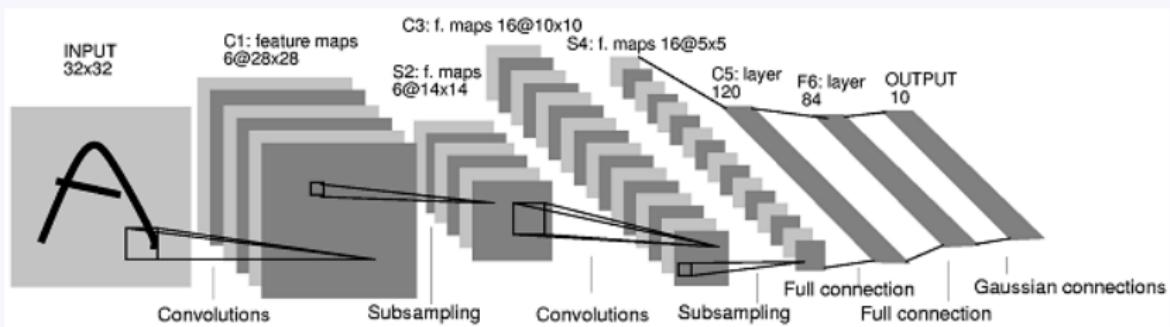
- The “neural network” space \mathcal{F} is explicitly parametrized by:

$$f(\mathbf{x}) = \sigma_k(\mathbf{A}_k \sigma_{k-1}(\mathbf{A}_{k-1} \dots \sigma_2(\mathbf{A}_2 \sigma_1(\mathbf{A}_1 \mathbf{x})) \dots)).$$

- Linear operations are either unconstrained (fully connected) or involve parameter sharing (e.g., convolutions).
- Finding the optimal $\mathbf{A}_1, \mathbf{A}_2, \dots, \mathbf{A}_k$ yields a **non-convex** optimization problem.

Convolutional Neural Networks

Picture from LeCun et al. (1998)

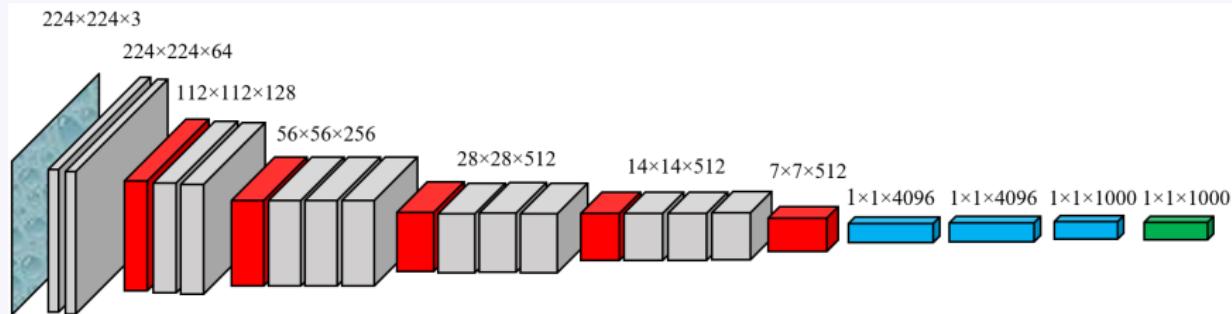


What are the main features of CNNs?

- they capture **compositional** and **multiscale** structures in images;
- they provide some **invariance**;
- they model the **local stationarity** of images at several scales;

Convolutional Neural Networks

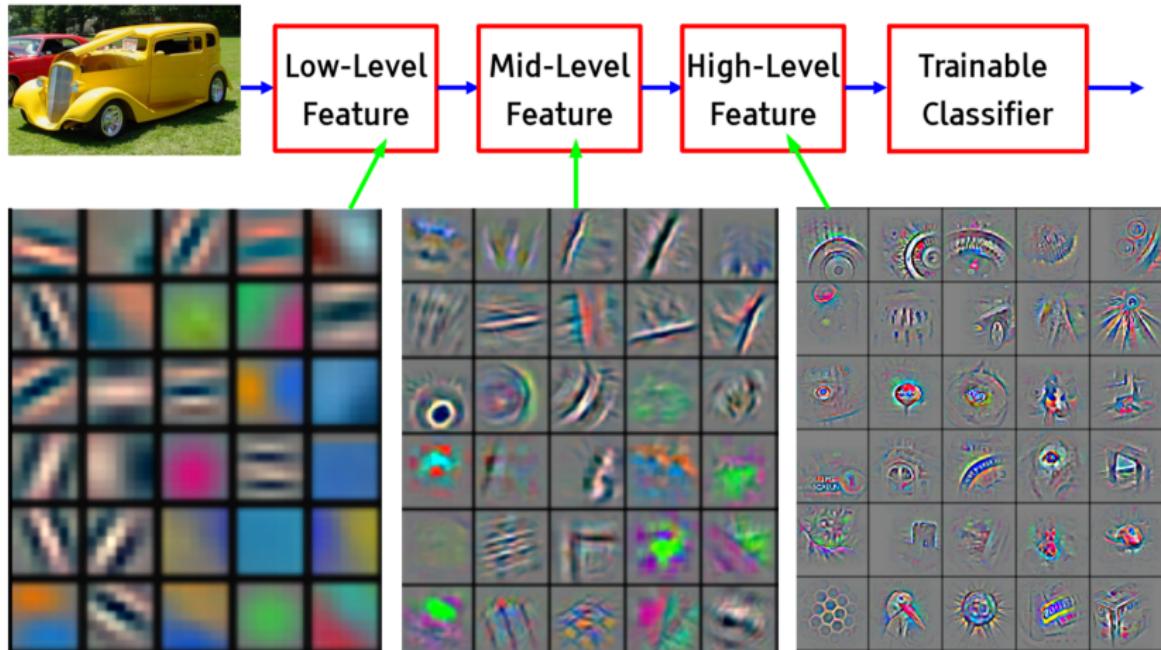
(Simonyan and Zisserman, 2014)



What are the main features of CNNs?

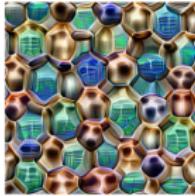
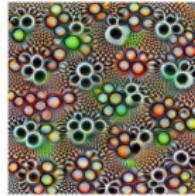
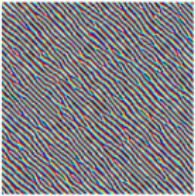
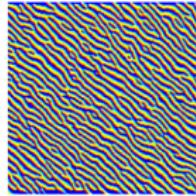
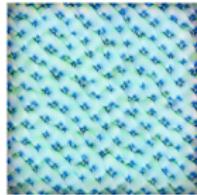
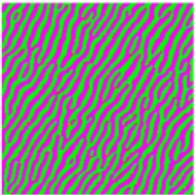
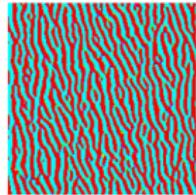
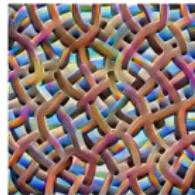
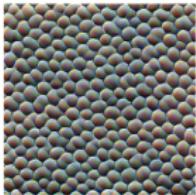
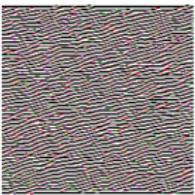
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CNNs (Picture from Y. LeCun's tutorial)



Feature visualization of convolutional net trained on ImageNet from [Zeiler & Fergus 2013]

CNNs (Picture from Olah et al. (2017))



Edges (layer conv2d0)

Textures (layer mixed3a)

Patterns (layer mixed4a)

Part

CNNs (Picture from Olah et al. (2017))



Parts (layers mixed4b & mixed4c)

Objects (layers mixed4d & mixed4e)

CNNs (Picture from unknown source)

ImageNet: 1000 image categories, 10M hand-labeled images; top-5 error rate.

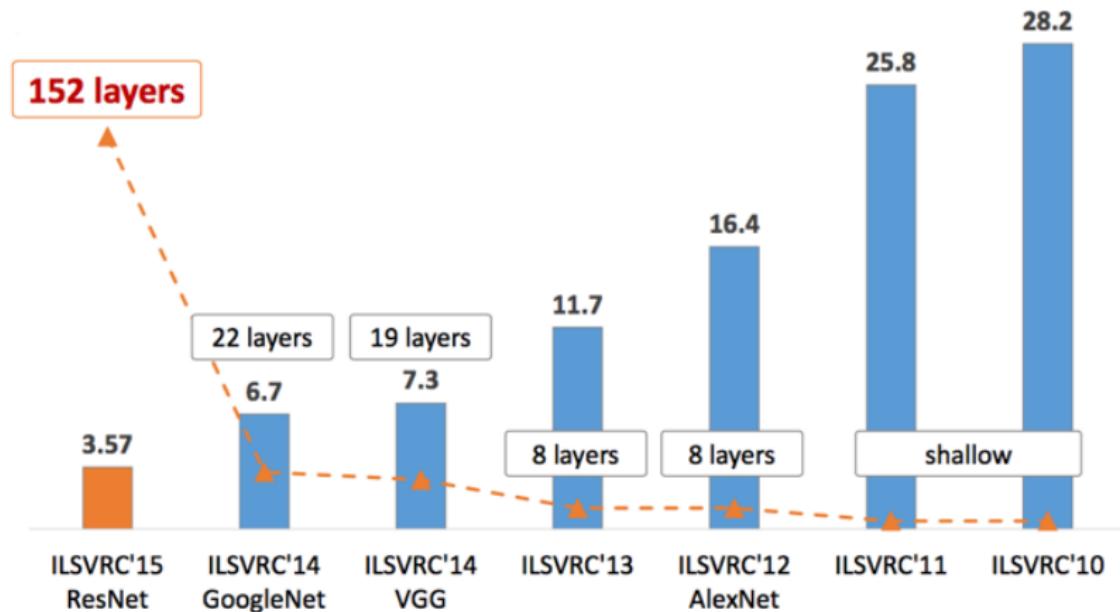


Figure: Top-5 error rate

Convolutional neural networks for biological sequences

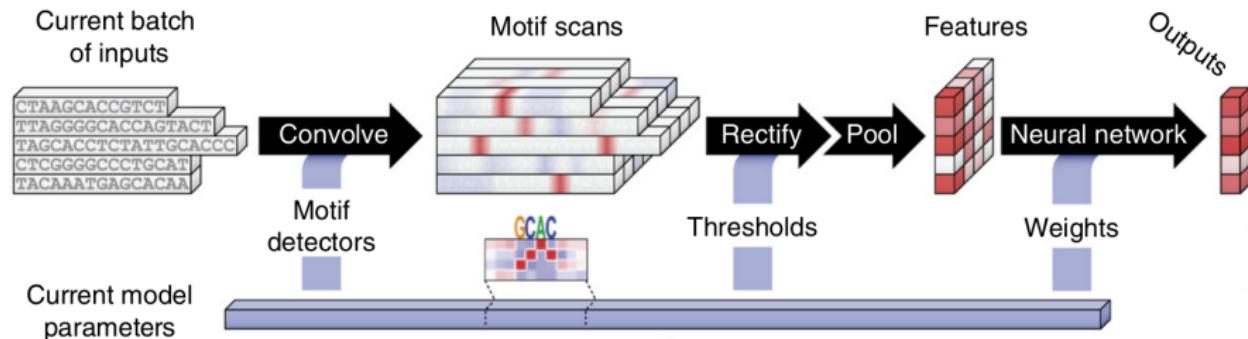


Figure: two-layer CNN architecture from Alipanahi et al. (2015)

- Sequences are represented by one-hot encoding ($A=(1,0,0,0), C=(0,1,0,0), \dots$).
- Single convolution layer followed by linear classifier.

Convolutional Neural Networks

What are current important problems to solve?

- ① lack of **stability** (see next slide).
- ② learning with **few labeled data**.
- ③ learning with **no supervision** (see Tab. from Bojanowski and Joulin, 2017).

Method	Acc@1
Random (Noroozi & Favaro, 2016)	12.0
SIFT+FV (Sánchez et al., 2013)	55.6
Wang & Gupta (2015)	29.8
Doersch et al. (2015)	30.4
Zhang et al. (2016)	35.2
¹ Noroozi & Favaro (2016)	38.1
BiGAN (Donahue et al., 2016)	32.2
NAT	36.0

Table 3. Comparison of the proposed approach to state-of-the-art unsupervised feature learning on ImageNet. A full multi-layer perceptron is retrained on top of the features. We compare to several self-supervised approaches and an unsupervised approach,

Adversarial examples, Picture from Kurakin et al. (2016)

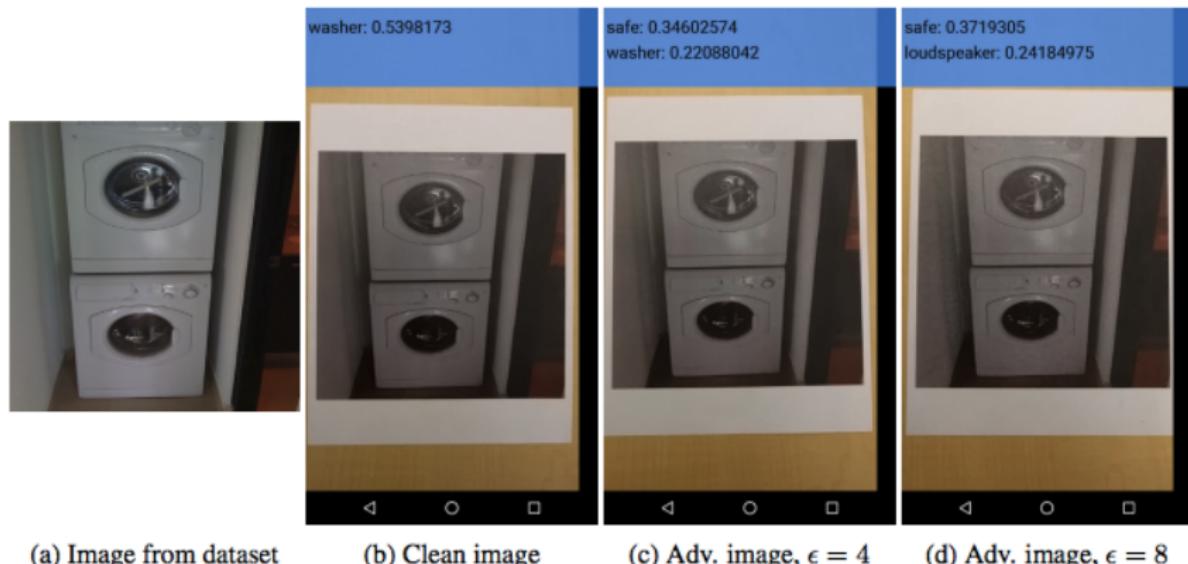
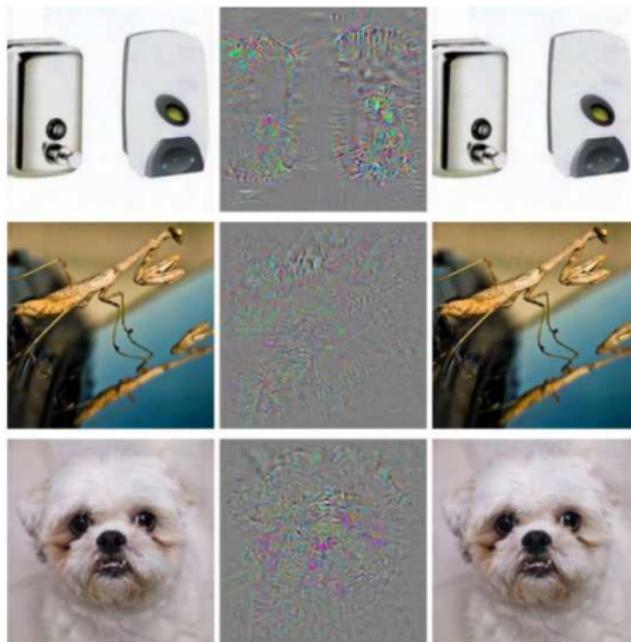


Figure: Adversarial examples are generated by computer; then printed on paper; a new picture taken on a smartphone fools the classifier.

Adversarial examples



(b)

clean + noise → “**ostrich**” (Szegedy et al., 2013).

Adversarial examples



(a real ostrich)

Adversarial examples



adversarial
perturbation



88% **tabby cat**

99% **guacamole**

<https://github.com/anishathalye/obfuscated-gradients>

Convolutional Neural Networks

$$\min_{f \in \mathcal{F}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\lambda \Omega(f)}_{\text{regularization}}.$$

The issue of regularization

- today, heuristics are used (DropOut, weight decay, early stopping)...
- ...but they are not sufficient.
- how to **control variations of prediction functions?**

$|f(\mathbf{x}) - f(\mathbf{x}')|$ should be close if \mathbf{x} and \mathbf{x}' are “similar”.

- what does it mean for x and x' to be “similar”?
- what should be a good **regularization function** Ω ?

Understanding deep learning

The challenge of deep learning theory

- **Over-parameterized** (millions of parameters)
- **Expressive** (can approximate any function)
- Complex **architectures** for exploiting problem structure
- Yet, **easy to optimize** with (stochastic) gradient descent!

Understanding deep learning

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A functional space viewpoint

- View deep networks as functions in some functional space;
- Non-parametric models, natural measures of complexity (e.g., norms).

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A functional space viewpoint

- View deep networks as functions in some functional space;
- Non-parametric models, natural measures of complexity (e.g., norms).

What is an appropriate functional space?

Outline

6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
- Foundations of deep learning from a kernel point of view
 - Motivation
 - Deep kernel machines
 - Deep learning theory
 - Application to biological sequences

Kernels for deep models: deep kernel machines

Hierarchical kernels (Cho and Saul, 2009)

- Kernels can be constructed **hierarchically**

$$K(x, x') = \langle \Phi(x), \Phi(x') \rangle \text{ with } \Phi(x) = \varphi_2(\varphi_1(x))$$

- e.g., dot-product kernels on the sphere

$$K(x, x') = \kappa_2(\langle \varphi_1(x), \varphi_1(x') \rangle) = \kappa_2(x^\top x')$$

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A classical old result (Schoenberg, 1942)

Let $\mathcal{X} = \mathbb{S}$ be the unit sphere of some Hilbert space \mathcal{H}_0 . The kernel $K : \mathcal{X}^2 \rightarrow \mathbb{R}$

$$K(\mathbf{x}, \mathbf{y}) = \kappa(\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{H}_0}),$$

is positive definite for all \mathcal{H}_0 if and only if κ is smooth and admits an expansion $\kappa(u) = \sum_i a_i u^i$ with non-negative coefficients a_i .

Kernels for deep models: dot-product kernels

linear kernel	$\langle z, z' \rangle$
exponential kernel	$e^{\alpha(\langle z, z' \rangle - 1)}$
inverse polynomial kernel	$\frac{1}{2 - \langle z, z' \rangle}$
polynomial kernel of degree p	$(c + \langle z, z' \rangle)^p$
arc-cosine kernel of degree 1	$\frac{1}{\pi} (\sin(\theta) + (\pi - \theta) \cos(\theta))$ with $\theta = \arccos(\langle z, z' \rangle)$
Vovk's kernel of degree 3	$\frac{1}{3} \left(\frac{1 - \langle z, z' \rangle^3}{1 - \langle z, z' \rangle} \right) = \frac{1}{3} (1 + \langle z, z' \rangle + \langle z, z' \rangle^2)$

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Remark

if $\|z\| = \|z'\| = 1$, the exponential kernel recovers the Gaussian kernel

$$\kappa_{\text{exp}}(\langle z, z' \rangle) = e^{\alpha(\langle z, z' \rangle - 1)} = e^{-\frac{\alpha}{2} \|z - z'\|^2},$$

Kernels for deep models: infinite-width networks

$$f_\theta(x) = \frac{1}{\sqrt{m}} \sum_{i=1}^m v_i \sigma(w_i^\top x), \quad m \rightarrow \infty$$

Random feature kernels (RF, Neal, 1996; Rahimi and Recht, 2007)

- $\theta = (v_i)_i$, fixed random weights $w_i \sim N(0, I)$

$$K_{RF}(x, x') = \mathbb{E}_{w \sim N(0, I)} [\sigma(w^\top x) \sigma(w^\top x')]$$

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Neural tangent kernels (NTK, Jacot et al., 2018)

- $\theta = (v_i, w_i)_i$, initialization $\theta_0 \sim N(0, I)$
- **Lazy training** (Chizat et al., 2019): θ stays close to θ_0 when training with large m

$$f_\theta(x) \approx f_{\theta_0}(x) + \langle \theta - \theta_0, \nabla_\theta f_\theta(x)|_{\theta=\theta_0} \rangle.$$

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- Gradient descent for $m \rightarrow \infty \approx$ kernel ridge regression with **neural tangent kernel**

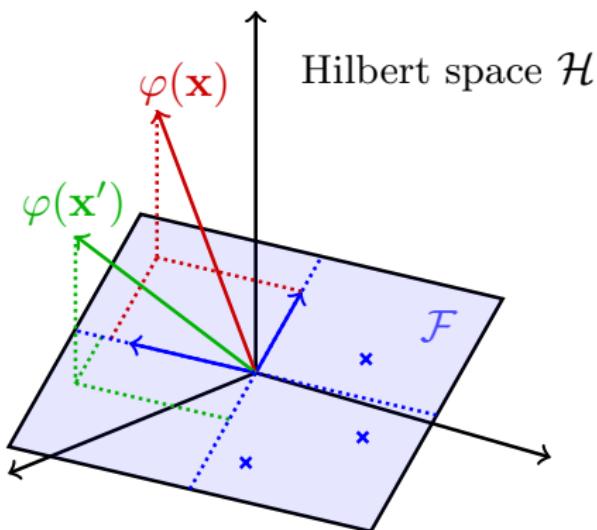
$$K_{NTK}(x, x') = \lim_{m \rightarrow \infty} \langle \nabla_\theta f_{\theta_0}(x), \nabla_\theta f_{\theta_0}(x') \rangle$$

Kernels for deep models: dot-product kernels + Nyström

The Nyström method consists of replacing any point $\varphi(\mathbf{x})$ in \mathcal{H} , for \mathbf{x} in \mathcal{X} by its orthogonal projection onto a **finite-dimensional subspace**

$$\mathcal{F} = \text{span}(\varphi(\mathbf{z}_1), \dots, \varphi(\mathbf{z}_p)),$$

for some anchor points $\mathbf{Z} = [\mathbf{z}_1, \dots, \mathbf{z}_p]$ in $\mathbb{R}^{d \times p}$



Kernels for deep models: dot-product kernels + Nyström

The projection is equivalent to

$$\Pi_{\mathcal{F}}[\mathbf{x}] := \sum_{j=1}^p \beta_j^* \varphi(\mathbf{z}_j) \quad \text{with} \quad \boldsymbol{\beta}^* \in \operatorname{argmin}_{\boldsymbol{\beta} \in \mathbb{R}^p} \left\| \varphi(\mathbf{x}) - \sum_{j=1}^p \beta_j \varphi(\mathbf{z}_j) \right\|_{\mathcal{H}}^2,$$

Then, it is possible to show that with $K(\mathbf{x}, \mathbf{y}) = \langle \varphi(\mathbf{x}), \varphi(\mathbf{y}) \rangle_{\mathcal{H}}$,

$$K(\mathbf{x}, \mathbf{y}) \approx \langle \Pi_{\mathcal{F}}[\mathbf{x}], \Pi_{\mathcal{F}}[\mathbf{y}] \rangle_{\mathcal{H}} = \langle \psi(\mathbf{x}), \psi(\mathbf{y}) \rangle_{\mathbb{R}^p},$$

with

$$\psi(\mathbf{x}) = \kappa(\mathbf{Z}^\top \mathbf{Z})^{-1/2} \kappa(\mathbf{Z}^\top \mathbf{x}),$$

where the function κ is applied pointwise to its arguments. The resulting ψ can be interpreted as a neural network performing (i) linear operation, (ii) pointwise non-linearity, (iii) linear operation.

(Williams and Seeger, 2001; Smola and Schölkopf, 2000; Fine and Scheinberg, 2001).

Kernels for deep models: Convolutional Kernel Networks (CKNs)

What is the relation?

- it is possible to design functional spaces \mathcal{H} where deep neural networks live (Mairal, 2016).

$$f(\mathbf{x}) = \sigma_k(\mathbf{A}_k \sigma_{k-1}(\mathbf{A}_{k-1} \dots \sigma_2(\mathbf{A}_2 \sigma_1(\mathbf{A}_1 \mathbf{x})) \dots)) = \langle f, \Phi(\mathbf{x}) \rangle_{\mathcal{H}}.$$

- we call the construction “**convolutional kernel networks**” (in short, replace $u \mapsto \sigma(\langle a, u \rangle)$ by a kernel mapping $u \mapsto \varphi_k(u)$).

Why do we care?

- $\Phi(\mathbf{x})$ is related to the **network architecture** and is **independent of training data**. Is it stable? Does it lose signal information?

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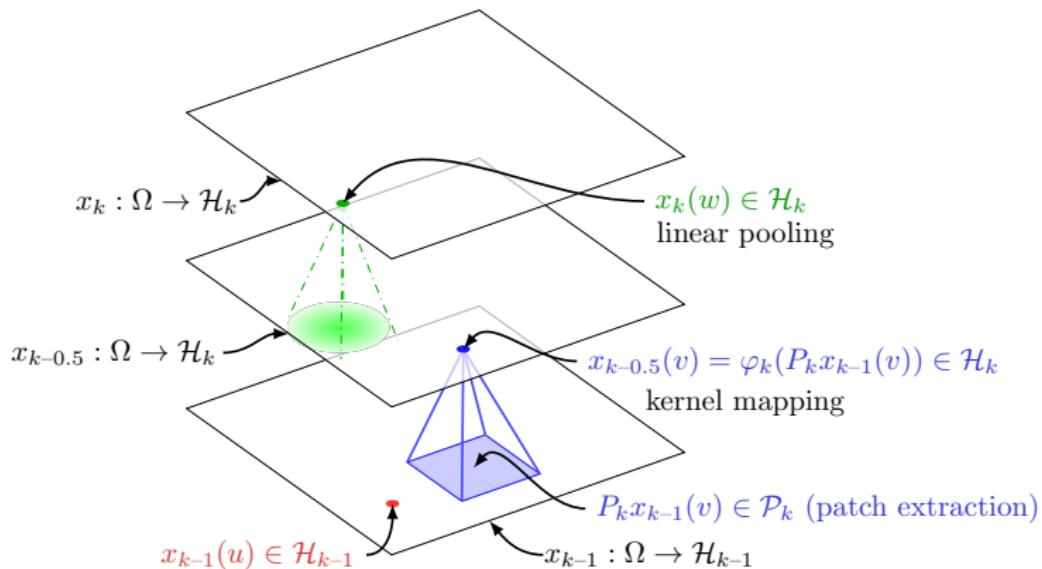
Why do we care?

- $\Phi(x)$ is related to the **network architecture** and is **independent of training data**. Is it stable? Does it lose signal information?
- f is a **predictive model**. Can we control its stability?

$$|f(x) - f(x')| \leq \|f\|_{\mathcal{H}} \|\Phi(x) - \Phi(x')\|_{\mathcal{H}}.$$

Convolutional Kernel Networks (CKNs)

Convolutional kernels networks (CKNs) for images (Mairal et al., 2014; Mairal, 2016)



- Good empirical performance with tractable approximations (Nyström)

Summary of the results from Bietti and Mairal (2019a)

Multi-layer construction of the RKHS \mathcal{H}

- Contains CNNs with smooth homogeneous activation functions.

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Signal representation: Conditions for

- **Signal preservation** of the multi-layer kernel mapping Φ .
- **Stability to deformations and non-expansiveness** for Φ .
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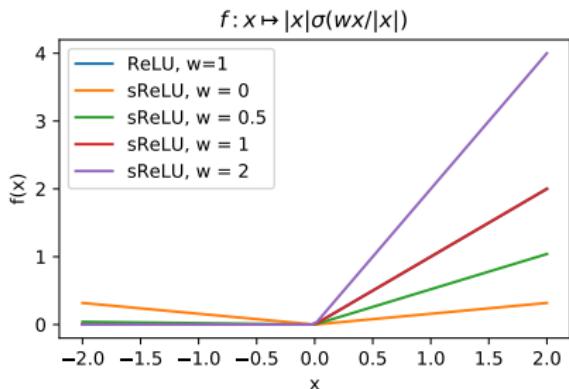
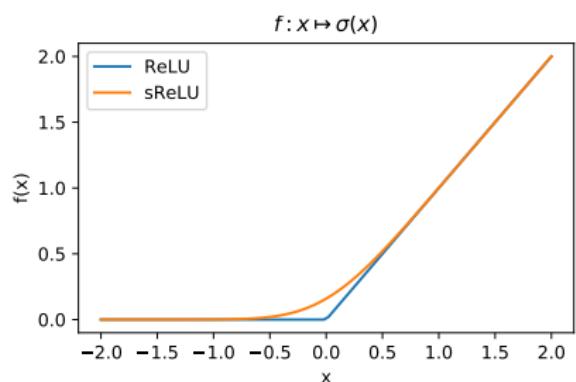
On learning

- Bounds on the RKHS norm $\|.\|_{\mathcal{H}}$ to control **stability and generalization** of a predictive model f .

$$|f(x) - f(x')| \leq \|f\|_{\mathcal{H}} \|\Phi(x) - \Phi(x')\|_{\mathcal{H}}.$$

Smooth homogeneous activations functions

$$z \mapsto \text{ReLU}(w^\top z) \quad \Rightarrow \quad z \mapsto \|z\| \sigma(w^\top z / \|z\|).$$



Construction of the RKHS for continuous signals

Initial map x_0 in $L^2(\Omega, \mathcal{H}_0)$

$x_0 : \Omega \rightarrow \mathcal{H}_0$: **continuous** signal, with $\Omega = \mathbb{R}^d$ ($d = 2$ for images).

- $x_0(u) \in \mathcal{H}_0$: input value at location u ($\mathcal{H}_0 = \mathbb{R}^3$ for RGB images).

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Building map x_k in $L^2(\Omega, \mathcal{H}_k)$ from x_{k-1} in $L^2(\Omega, \mathcal{H}_{k-1})$

$x_k : \Omega \rightarrow \mathcal{H}_k$: **feature map** at layer k

$$P_k x_{k-1}.$$

- P_k : **patch extraction** operator, extract small patch of feature map x_{k-1} around each point u ($P_k x_{k-1}(u)$ is a patch centered at u).

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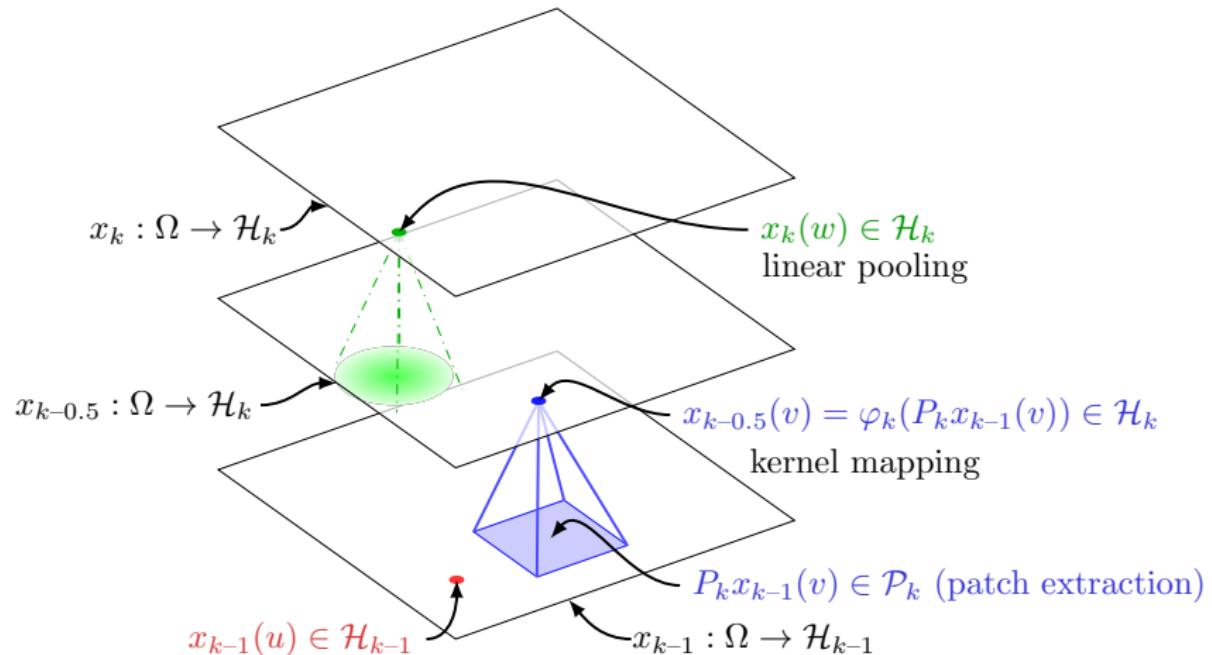
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$$x_k = A_k M_k P_k x_{k-1}.$$

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- M_k : **non-linear mapping** operator, maps each patch to a new Hilbert space \mathcal{H}_k with a **pointwise** non-linear function $\varphi_k(\cdot)$.
- A_k : (linear) **pooling** operator at scale σ_k .

Construction of the RKHS for continuous signals



Construction of the RKHS for continuous signals

Multilayer representation

$$\Phi_n(x) = A_n M_n P_n A_{n-1} M_{n-1} P_{n-1} \cdots A_1 M_1 P_1 x_0 \in L^2(\Omega, \mathcal{H}_n).$$

- σ_k grows exponentially in practice (i.e., fixed with subsampling).

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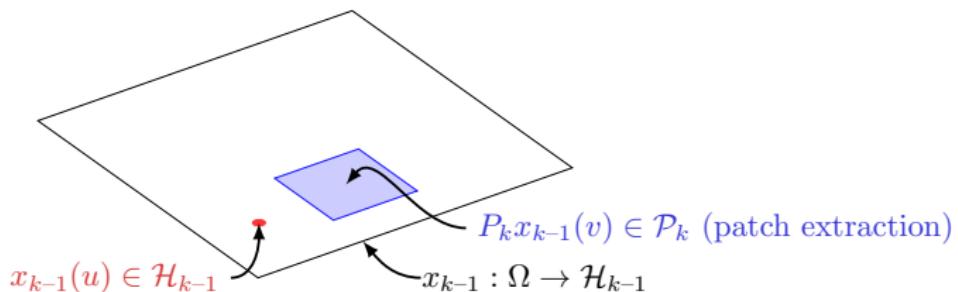
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Prediction layer

- e.g., linear $f(x) = \langle w, \Phi_n(x) \rangle$.
- “linear kernel” $\mathcal{K}(x, x') = \langle \Phi_n(x), \Phi_n(x') \rangle = \int_{\Omega} \langle x_n(u), x'_n(u) \rangle du$.

Patch extraction operator P_k

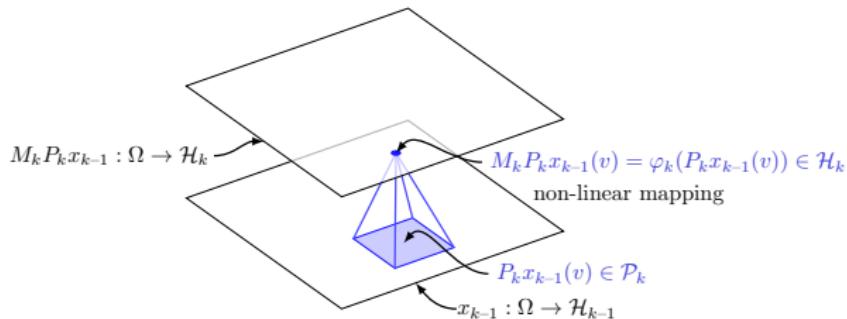
$$P_k x_{k-1}(u) := (x_{k-1}(u + v))_{v \in S_k} \in \mathcal{P}_k = \mathcal{H}_{k-1}^{S_k}$$



- S_k : patch shape, e.g. box

Non-linear mapping operator M_k

$$M_k P_k x_{k-1}(u) := \varphi_k(P_k x_{k-1}(u)) \in \mathcal{H}_k$$



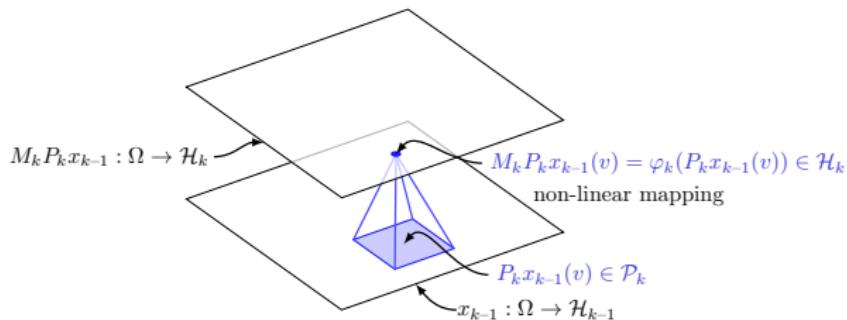
Kernel mapping of **homogeneous dot-product kernels**:

$$K_k(z, z') = \|z\| \|z'\| \kappa_k \left(\frac{\langle z, z' \rangle}{\|z\| \|z'\|} \right) = \langle \varphi_k(z), \varphi_k(z') \rangle.$$

$$\kappa_k(u) = \sum_{j=0}^{\infty} b_j u^j \text{ with } b_j \geq 0, \kappa_k(1) = 1$$

Non-linear mapping operator M_k

$$M_k P_k x_{k-1}(u) := \varphi_k(P_k x_{k-1}(u)) \in \mathcal{H}_k$$

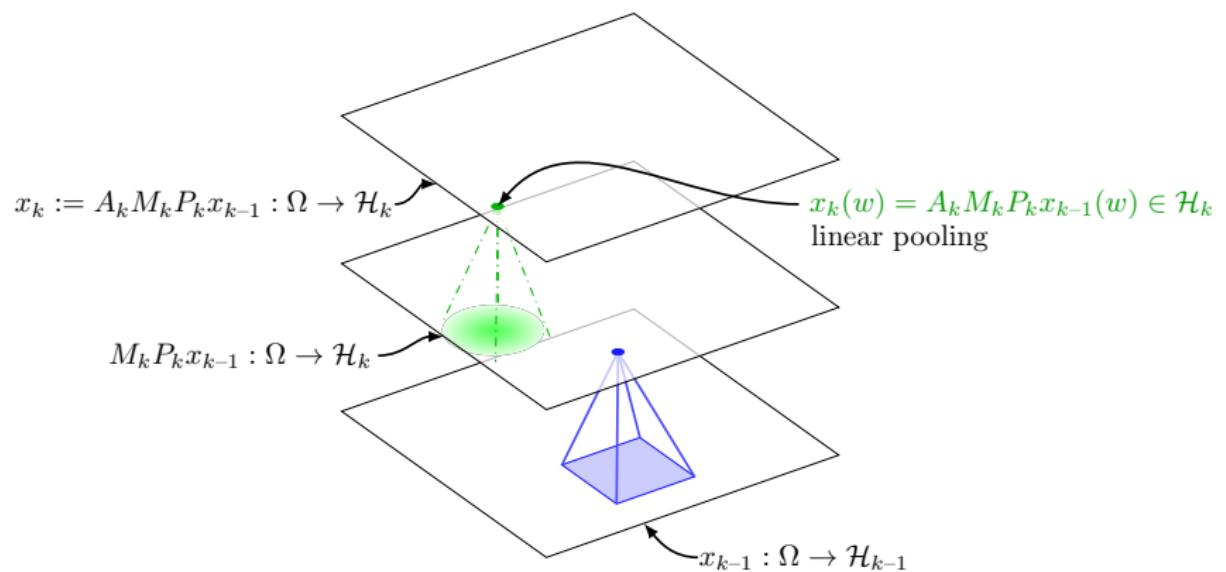


Examples

- $\kappa_{\text{exp}}(\langle z, z' \rangle) = e^{\langle z, z' \rangle - 1}$ (Gaussian kernel on the sphere)
- $\kappa_{\text{inv-poly}}(\langle z, z' \rangle) = \frac{1}{2 - \langle z, z' \rangle}$

Pooling operator A_k

$$x_k(u) = A_k M_k P_k x_{k-1}(u) = \int_{\mathbb{R}^d} h_{\sigma_k}(u - v) M_k P_k x_{k-1}(v) dv \in \mathcal{H}_k$$



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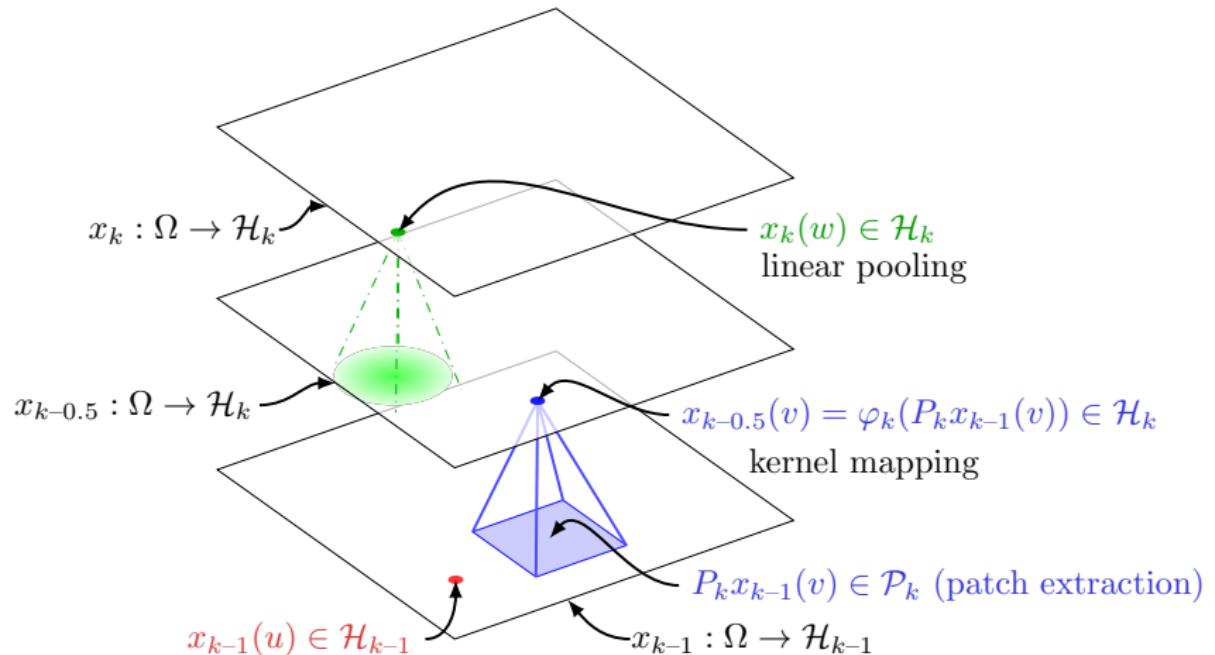
- h_{σ_k} : pooling filter at scale σ_k
- $h_{\sigma_k}(u) := \sigma_k^{-d} h(u/\sigma_k)$ with $h(u)$ **Gaussian**
- **linear, non-expansive operator**: $\|A_k\| \leq 1$

Pooling operator A_k

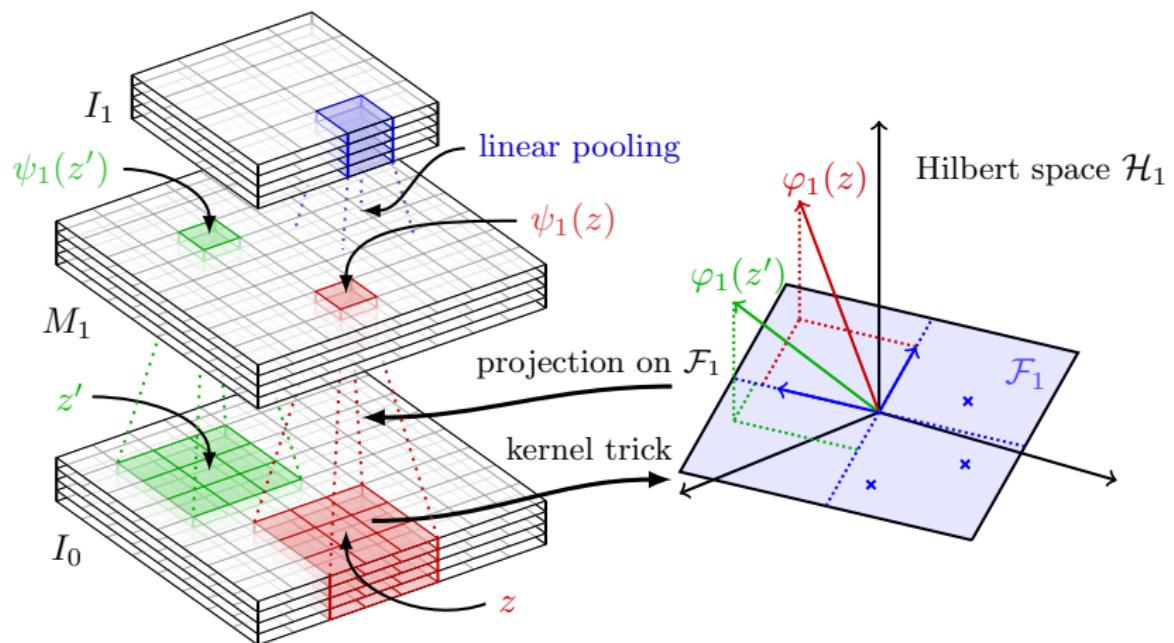
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- h_{σ_k} : pooling filter at scale σ_k
- $h_{\sigma_k}(u) := \sigma_k^{-d} h(u/\sigma_k)$ with $h(u)$ **Gaussian**
- **linear, non-expansive operator**: $\|A_k\| \leq 1$
- In practice: **discretization**, sampling at resolution σ_k after pooling
- “Preserves information” when **subsampling \leq patch size**

Recap: P_k , M_k , A_k



Convolutional Kernel Networks in practice



Learning mechanism of CKNs between layers 0 and 1.

Convolutional Kernel Networks in Practice

Formally, this means using the Nyström approximation

- We now manipulate **finite-dimensional maps**.
- Every linear subspace is parametrized by anchor points

$$\mathcal{F}_j := \text{Span} (\varphi(\mathbf{z}_{j,1}), \dots, \varphi(\mathbf{z}_{j,p_j})) ,$$

where the $\mathbf{z}_{1,j}$'s are in $\mathbb{R}^{p_{j-1}e_{j-1}^2}$ for patches of size $e_{j-1} \times e_{j-1}$.

- The encoding function at layer j is

$$\psi_j(\mathbf{x}) := \|\mathbf{x}\| \kappa_j (\mathbf{Z}_j^\top \mathbf{Z}_j)^{-1/2} \kappa_1 \left(\mathbf{Z}_j^\top \frac{\mathbf{x}}{\|\mathbf{x}\|} \right) \text{ if } \mathbf{x} \neq 0 \text{ and } 0 \text{ otherwise,}$$

where $\mathbf{Z}_j = [\mathbf{z}_{j,1}, \dots, \mathbf{z}_{j,p_j}]$ and $\|\cdot\|$ is the Euclidean norm.

- The interpretation is **convolution** with filters \mathbf{Z}_j , **pointwise non-linearity**, 1×1 **convolution**, **homogenization**.

Convolutional Kernel Networks in Practice

What is the difference with a CNN?

- Given a patch x , a CNN computes $\psi_{CNN}(x) = \sigma(\mathbf{Z}^\top x)$.
- Given a patch x , a CKN computes
$$\psi_{CKN}(x) = \|x\| \kappa(\mathbf{Z}^\top \mathbf{Z})^{-1/2} \kappa(\mathbf{Z}^\top x / \|x\|).$$

Convolutional Kernel Networks in Practice

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Consequences

- we have a geometric interpretation in terms of subspace learning.
- it provides unsupervised learning mechanisms (kernel approximation).
- supervised learning is still feasible (which requires backpropagation through $\kappa(\mathbf{Z}^\top \mathbf{Z})^{-1/2}$).
- the kernel interpretation provides regularization mechanisms.
- kernel representations can possibly be used in other contexts (statistical testing? kernel PCA? CCA? K-means?).

Unsupervised learning for convolutional kernel networks

How do we learn the filters with no supervision?

we learn one layer at a time, starting from the bottom one.

- we **extract a large number**—say 100 000 patches from layers $j - 1$ computed on an image database and normalize them;
- perform a **spherical K-means algorithm** to learn the filters \mathbf{Z}_j ;
- **compute the projection matrix** $\kappa_j(\mathbf{Z}_j^\top \mathbf{Z}_j)^{-1/2}$.

Remarks

- with kernels, we map **patches in infinite dimension**; with the projection, we **manipulate finite-dimensional objects**.
- we obtain an **unsupervised** convolutional net with a **geometric interpretation**, where we perform projections in the RKHSs.

Convolutional kernel networks with supervised learning

How do we learn the filters with supervision?

- Given a kernel K and RKHS \mathcal{H} , the ERM objective is

$$\min_{f \in \mathcal{H}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\frac{\lambda}{2} \|f\|_{\mathcal{H}}^2}_{\text{regularization}}.$$

- With the CKN formulation, it becomes

$$\min_{W, \mathcal{Z}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, W^\top \psi_{\mathcal{Z}}(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\frac{\lambda}{2} \|W\|_F^2}_{\text{regularization}}.$$

Convolutional kernel networks with supervised learning

How do we learn the filters with supervision?

- we **jointly optimize** w.r.t. \mathcal{Z} (set of filters) and \mathbf{W} .
- we **alternate** between the optimization of \mathcal{Z} and of \mathbf{W} ;
- for \mathbf{W} , the problem is strongly-convex and can be tackled with recent algorithms that are much faster than SGD;
- for \mathcal{Z} , we derive **backpropagation rules** and use classical tricks for learning CNNs (SGD+momentum);

Outline

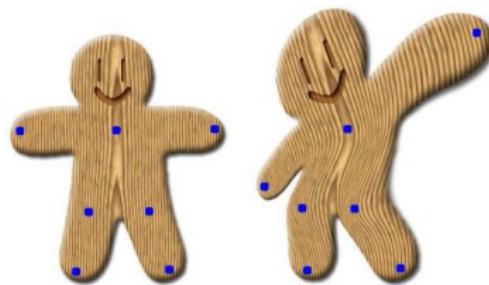
6 Open Problems and Research Topics

- Multiple Kernel Learning (MKL)
- Large-scale learning with kernels
- Foundations of deep learning from a kernel point of view
 - Motivation
 - Deep kernel machines
 - Deep learning theory
 - Application to biological sequences

Stability to deformations

Deformations

- $\tau : \Omega \rightarrow \Omega$: C^1 -diffeomorphism
- $L_\tau x(u) = x(u - \tau(u))$: action operator
- Much richer group of transformations than translations



4 4 4 4 4 4 4 4 4
5 5 5 5 5 5 5 5 5
7 7 7 7 7 1 7 7 7
8 8 8 8 8 8 8 8 8

- Studied for wavelet-based scattering transform (Mallat, 2012; Bruna and Mallat, 2013)

Stability to deformations

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Definition of stability

- Representation $\Phi(\cdot)$ is **stable** (Mallat, 2012) if:

$$\|\Phi(L_\tau x) - \Phi(x)\| \leq (C_1 \|\nabla \tau\|_\infty + C_2 \|\tau\|_\infty) \|x\|$$

- $\|\nabla \tau\|_\infty = \sup_u \|\nabla \tau(u)\|$ controls deformation
- $\|\tau\|_\infty = \sup_u |\tau(u)|$ controls translation
- $C_2 \rightarrow 0$: translation invariance

Smoothness and stability with kernels

Geometry of the kernel mapping: $f(x) = \langle f, \Phi(x) \rangle$

$$|f(x) - f(x')| \leq \|f\|_{\mathcal{H}} \cdot \|\Phi(x) - \Phi(x')\|_{\mathcal{H}}$$

- $\|f\|_{\mathcal{H}}$ controls **complexity** of the model
- $\Phi(x)$ encodes CNN **architecture** independently of the model (smoothness, invariance, stability to deformations)

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Useful kernels in practice:

- Convolutional kernel networks (**CKNs**, Mairal, 2016) with efficient approximations
- Extends to neural tangent kernels (**NTKs**, Jacot et al., 2018) of infinitely wide CNNs (Bietti and Mairal, 2019b)

Recap: multilayer construction

Multilayer representation

$$\Phi(x_0) = A_n M_n P_n A_{n-1} M_{n-1} P_{n-1} \cdots A_1 M_1 P_1 x_0 \in L^2(\Omega, \mathcal{H}_n).$$

- S_k, σ_k grow exponentially in practice (i.e., fixed with subsampling).

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- x_0 is typically a **discrete** signal acquired with physical device.
- Natural assumption: $x_0 = A_0 x$, with x the original continuous signal, A_0 local integrator with scale σ_0 (**anti-aliasing**).

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Final kernel

$$K_{CKN}(x, x') = \langle \Phi(x), \Phi(x') \rangle_{L^2(\Omega)} = \int_{\Omega} \langle x_n(u), x'_n(u) \rangle du$$

Stability to deformations

Theorem (Stability of CKN (Bietti and Mairal, 2019a))

Let $\Phi_n(x) = \Phi(A_0 x)$ and assume $\|\nabla \tau\|_\infty \leq 1/2$,

$$\|\Phi_n(L_\tau x) - \Phi_n(x)\| \leq \left(C_\beta (n+1) \|\nabla \tau\|_\infty + \frac{C}{\sigma_n} \|\tau\|_\infty \right) \|x\|$$

- Translation invariance: large σ_n
- Stability: small patch sizes ($\beta \approx$ patch size, $C_\beta = O(\beta^3)$ for images)
- Signal preservation: subsampling factor \approx patch size

⇒ need several layers with small
patches $n = O(\log(\sigma_n/\sigma_0)/\log \beta)$

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- Achieved by controlling norm of **commutator** $[L_\tau, P_k A_{k-1}]$
 - Extend result by Mallat (2012) for controlling $\|[L_\tau, A]\|$
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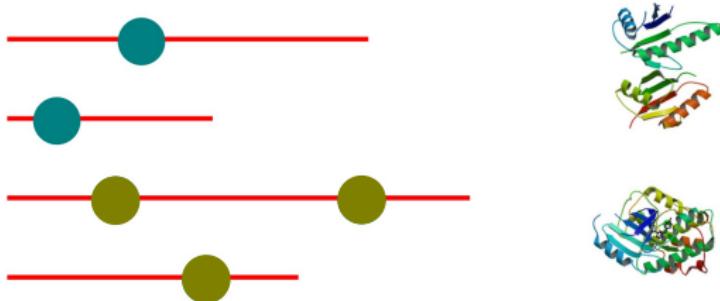
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 - Need patches S_k adapted to resolution σ_{k-1} : $\text{diam } S_k \leq \beta \sigma_{k-1}$
- Extensions to other transformation groups, e.g. **roto-translations**

Outline

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Sequence modeling as a supervised learning problem



Supervised learning for sequences

- Biological sequences $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathcal{X}$ and their labels y_1, \dots, y_n .
- Goal: learning a **predictive** and **interpretable** function $f : \mathcal{X} \rightarrow \mathbb{R}$

$$\min_{f \in \mathcal{F}} \underbrace{\frac{1}{n} \sum_{i=1}^n L(y_i, f(\mathbf{x}_i))}_{\text{empirical risk, data fit}} + \underbrace{\mu \Omega(f)}_{\text{regularization}}$$

- How do we define the functional space \mathcal{F} ?

Recap: String kernels

A classical approach for modeling biological sequences relies on string kernels.

$$K(x, x') = \sum_{u \in \mathcal{A}^k} \delta_u(x) \delta_u(x'),$$

where u is a k -mer over an alphabet \mathcal{A} and $\delta_u(x)$ can be:

- the number of occurrences of u in x : **spectrum kernel** (Leslie et al., 2002)
- the number of occurrences of u in x up to m mismatches: **mismatch kernel** (Leslie and Kuang, 2004)
- the number of occurrences of u in x allowing gaps, with a weight decaying exponentially with the number of gaps : **substring kernel** (Lodhi et al., 2002)

Convolutional kernel networks for sequence modeling

Continuous relaxation of the mismatch kernel (Chen et al., 2019)

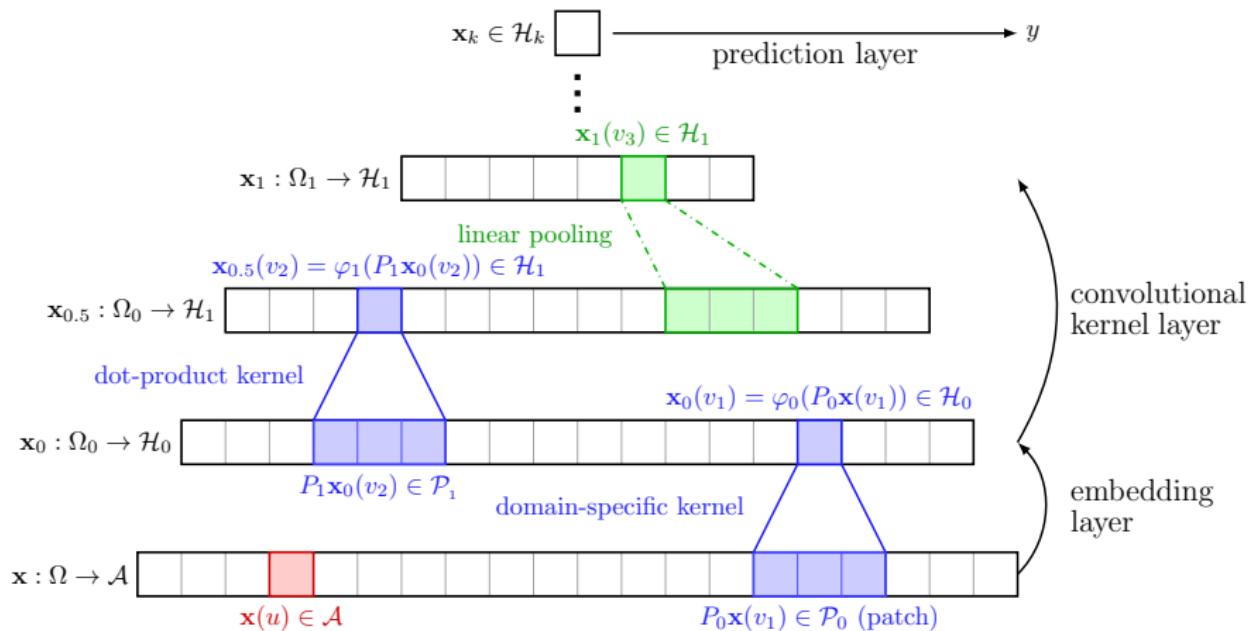
$$K_{\text{CKN}}(\mathbf{x}, \mathbf{x}') = \sum_{i=1}^{|\mathbf{x}|} \sum_{j=1}^{|\mathbf{x}'|} K_0(\underbrace{\mathbf{x}[i : i+k]}_{\text{one k-mer}}, \underbrace{\mathbf{x}'[j : j+k]}_{})$$

- Use one-hot encoding

$$\mathbf{x}[i : i+5] := \text{TTGAG} \mapsto \begin{array}{l} \text{A} \\ \text{T} \\ \text{C} \\ \text{G} \end{array} \begin{bmatrix} 0 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

- K_0 is a Gaussian kernel over **one-hot** representations of k-mers (in $\mathbb{R}^{k \times d}$).
- $\Phi(\mathbf{x}) := \sum_{i=1}^{|\mathbf{x}|} \varphi_0(\mathbf{x}[i : i+k])$ with $\varphi_0 : z \mapsto e^{-\alpha/2\|z - \cdot\|^2}$.

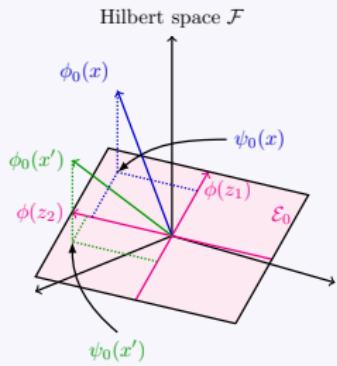
Convolutional kernel networks for sequence modeling



Convolutional kernel networks (Nyström approximation)

Nyström approximation

- **Finite-dimensional** projection of the kernel map: given a set of anchor points $Z := (z_1, \dots, z_q)$, we project $\varphi_0(x)$ for any k-mer x orthogonally onto \mathcal{E}_0 such that $K_0(x, x') \approx \langle \psi_0(x), \psi_0(x') \rangle_{\mathbb{R}^q}$.
- Approximate feature map of x :



$$\psi(\mathbf{x}) = \sum_{i=1}^{|\mathbf{x}|} \psi_0(\mathbf{x}[i : i+k]) \in \mathbb{R}^q$$

- Then solve the **linear** classification problem

$$\mathcal{E}_0 = \text{span}(\varphi_0(z_1), \dots, \varphi_0(z_q))$$

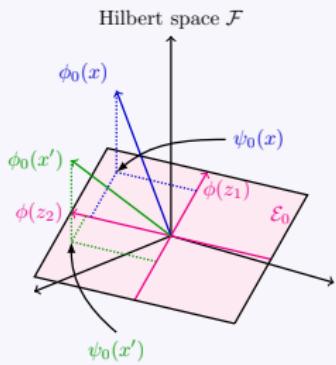
$$\min_{\mathbf{w} \in \mathbb{R}^p} \sum_{i=1}^n L(\mathbf{w}^\top \psi(\mathbf{x}_i), y_i) + \mu \|\mathbf{w}\|^2.$$

(Williams and Seeger, 2001; Zhang et al., 2008)

Convolutional kernel networks (end-to-end kernel learning)

Nyström approximation and end-to-end training

- **Finite-dimensional** projection of the kernel map: given a set of anchor points $Z := (z_1, \dots, z_q)$, we project $\varphi_0(x)$ for any k-mer x orthogonally onto \mathcal{E}_0 such that $K_0(x, x') \approx \langle \psi_0(x), \psi_0(x') \rangle_{\mathbb{R}^q}$.
- Approximate feature map of \mathbf{x} :



$$\psi(\mathbf{x}) = \sum_{i=1}^{|\mathbf{x}|} \psi_0(\mathbf{x}[i : i+k]) \in \mathbb{R}^q$$

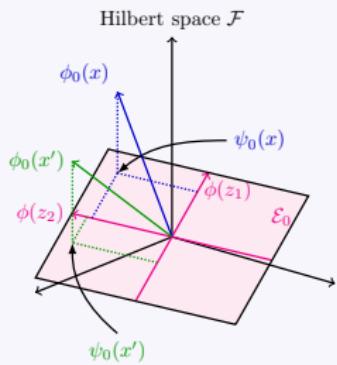
- Then solve

$$\mathcal{E}_0 = \text{span}(\varphi_0(z_1), \dots, \varphi_0(z_q))$$

$$\min_{\mathbf{w} \in \mathbb{R}^p, Z} \sum_{i=1}^n L(\mathbf{w}^\top \psi(\mathbf{x}_i), y_i) + \mu \|\mathbf{w}\|^2.$$

Convolutional kernel networks (end-to-end kernel learning)

Nyström approximation and end-to-end training



- Then solve

$$\min_{\mathbf{w} \in \mathbb{R}^p, \mathbf{Z}} \sum_{i=1}^n L(\mathbf{w}^\top \psi(\mathbf{x}_i), y_i) + \mu \|\mathbf{w}\|^2.$$

- CKN kernels only take contiguous k-mers into account.
- Limitation: unable to capture **gapped motifs** (e.g. useful for genetic insertions).

$$\mathcal{E}_0 = \text{span}(\varphi_0(z_1), \dots, \varphi_0(z_q))$$

From k-mers to gapped k-mers

Gap-allowed k-mers

- For a sequence $\mathbf{x} = x_1 \dots x_n \in \mathcal{X}$ of length n , for a sequence of ordered indices $\mathbf{i} \in \mathbb{I}(k, n)$, we define a k-substring as:

$$\mathbf{x}[\mathbf{i}] = x_{i_1} x_{i_2} \dots x_{i_k}.$$

- The length of the gaps in the substring is

$$\text{gaps}(\mathbf{i}) = \text{number of gaps in the indices.}$$

- Example: $\mathbf{x} = \text{BAARACADACRB}$

$$\mathbf{i} = (4, 5, 8, 9, 11) \quad \mathbf{x}[\mathbf{i}] = \text{RADAR} \quad \text{gaps}(\mathbf{i}) = 3$$

Recurrent kernel networks

Comparing all the k-mers between a pair of sequences

$$K_{CKN}(\mathbf{x}, \mathbf{x}') = \sum_{i=1}^{|\mathbf{x}|} \sum_{j=1}^{|\mathbf{x}'|} K_0 (\mathbf{x}[i : i + k], \mathbf{x}'[j : j + k])$$

(Lodhi et al., 2002; Lei et al., 2017)

Recurrent kernel networks

Comparing all the gapped k-mers between a pair of sequences

$$K_{\text{RKN}}(\mathbf{x}, \mathbf{x}') = \sum_{i \in I(k, |\mathbf{x}|)} \sum_{j \in I(k, |\mathbf{x}'|)} \lambda^{\text{gaps}(i)} \lambda^{\text{gaps}(j)} K_0(\mathbf{x}[i], \mathbf{x}'[j])$$

- Larger set of partial patterns (i.e. gapped k-mers) is taken into account. $\lambda^{\text{gaps}(i)}$ penalizes the gaps.
- $\Phi(\mathbf{x}) = \sum_{i \in I(k, |\mathbf{x}|)} \lambda^{\text{gaps}(i)} \varphi_0(\mathbf{x}[i]).$
- A continuous relaxation of substring kernel.

Approximation and recursive computation of RKN

Approximate feature map of RKN kernel

The approximate feature map of K_{RKN} via Nyström approximation is

$$\psi(\mathbf{x}) = \sum_{i \in I(k,t)} \lambda^{\text{gaps}(i)} \psi_0(\mathbf{x}[i]),$$

- Exhaustive enumeration of all substrings can be **exponentially** costly.
- But the sum can be computed fast using **dynamic programming** (Lodhi et al., 2002; Lei et al., 2017).
- Leads to a **particular** recurrent neural network with a kernel interpretation.

Computation of recurrent kernel networks

The approximate feature map of K_{RKN} via Nyström approximation is

$$\begin{aligned}\psi_j(\mathbf{x}_{1:t}) &= \sum_{\mathfrak{l} \in \mathbb{I}(j,t)} \lambda^{\text{gaps}(\mathfrak{l})} \psi_0(\mathbf{x}_{1:t}[\mathfrak{l}]) \\ &= K_{Z_j Z_j}^{-1/2} \sum_{\mathfrak{l} \in \mathbb{I}(j,t)} \lambda^{\text{gaps}(\mathfrak{l})} K_{Z_j}(\mathbf{x}[\mathfrak{l}]) := K_{Z_j Z_j}^{-1/2} \mathbf{h}_j[t],\end{aligned}$$

for any $j \in \{1, \dots, k\}$ and $t \in \{1, \dots, |\mathbf{x}|\}$. Z_j is a matrix in $\mathbb{R}^{d \times q}$ whose i -th column is the j -th vector of z_i .

A feature map of RKN

A feature vector of \mathbf{x} for RKN is a mixture of Gaussians centered at $\mathbf{x}[i]$, weighted by the corresponding penalization $\lambda^{\text{gap}(i)}$.

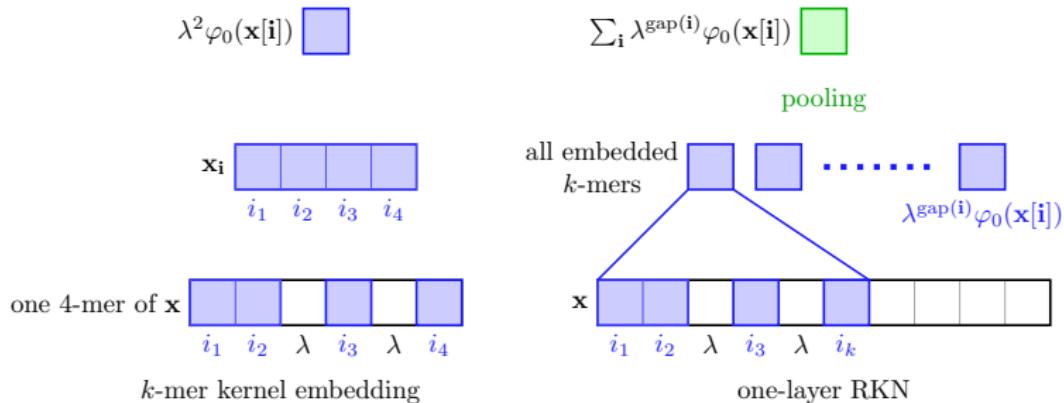
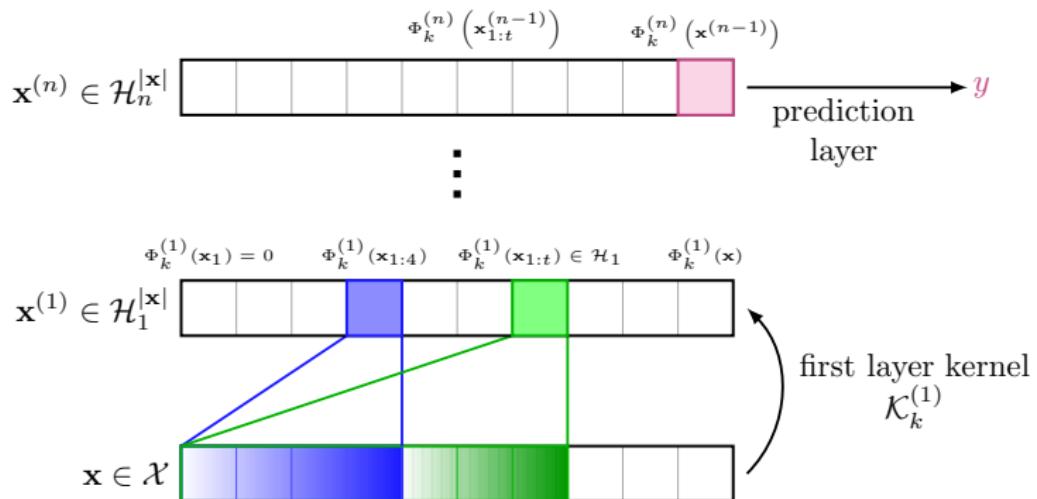


Figure: Example of K_{RKN} for $k = 4$

Multilayer construction of RKNs



Results

Protein fold classification on SCOP 2.06 (Hou et al., 2017) (multi-class classification, using more informative sequence features including PSSM, secondary structure and solvent accessibility)

Method	#Params	Accuracy		Level-stratified accuracy (top1/top5)		
		top 1	top 5	family	superfamily	fold
PSI-BLAST	-	84.53	86.48	82.20/84.50	86.90/88.40	18.90/35.100
DeepSF	920k	73.00	90.25	75.87/91.77	72.23/90.08	51.35/67.57
CKN (128 filters)	211k	76.30	92.17	83.30/94.22	74.03/91.83	43.78/67.03
CKN (512 filters)	843k	84.11	94.29	90.24/95.77	82.33/94.20	45.41/69.19
RKN (128 filters)	211k	77.82	92.89	76.91/93.13	78.56/92.98	60.54/83.78
RKN (512 filters)	843k	85.29	94.95	84.31/94.80	85.99/95.22	71.35/84.86

Note: More experiments with statistical tests have been conducted in our paper.

(Hou et al., 2017; Chen et al., 2019)

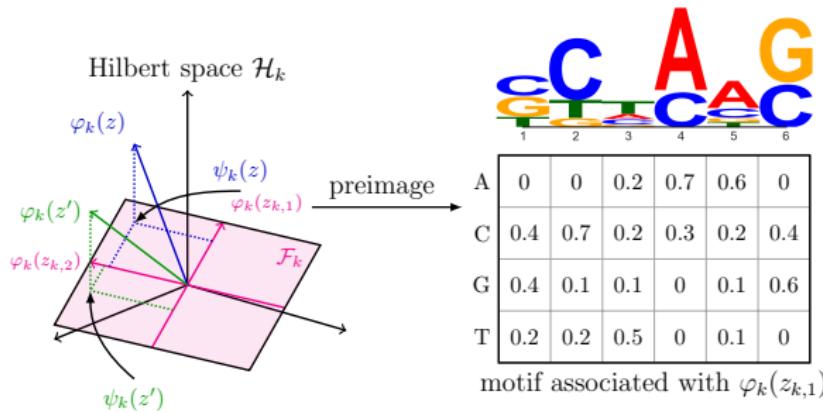
Motifs in CKN

- Find the preimage of each filter at the last layer, by optimizing

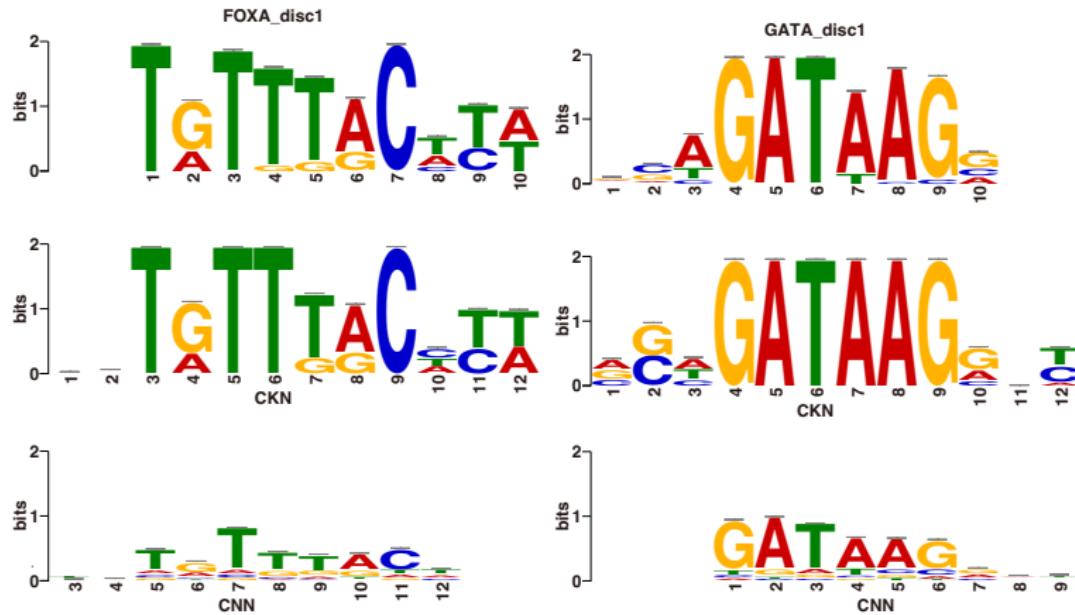
$$\min_{\mathbf{y} \in \mathcal{M}} \|\varphi_k(P_k \mathbf{y}_{k-1}) - \varphi_k(z_{k,i})\|_{\mathcal{H}_k}^2,$$

where \mathcal{M} is the appropriate set of motifs.

- Projection onto the simplex induces sparsity thus more informative motif.



Logos



Results

Protein fold recognition on SCOP 1.67 (widely used benchmark)

Method	pooling	one-hot		BLOSUM62	
		auROC	auROC50	auROC	auROC50
SVM-pairwise		0.724	0.359		
Mismatch		0.814	0.467		
LA-kernel		–	–	0.834	0.504
LSTM		0.830	0.566	–	–
CKN		0.837	0.572	0.866	0.621
RKN	mean	0.829	0.541	0.840	0.571
RKN	max	0.844	0.587	0.871	0.629
RKN (unsup)	mean	0.805	0.504	0.833	0.570

(Liao and Noble, 2003; Leslie et al., 2003; Vert et al., 2004b; Hochreiter et al., 2007; Chen et al., 2019)

Conclusion of the course

What we saw

- Basic definitions of p.d. kernels and RKHS
- How to use RKHS in machine learning
- The importance of the choice of kernels, and how to include “prior knowledge” there.
- Several approaches for kernel design (there are many!)
- Review of kernels for strings and on graphs
- Recent research topics about kernel methods

What we did not see

- How to **automatize** the process of kernel design (kernel selection? kernel optimization?)
- How to deal with **non p.d. kernels**
- Bayesian view of kernel methods, called **Gaussian processes**.
- How do do statistical testing with kernels with the kernel mean embedding.

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