Homework 4 Spring 2023

Due Date - 04/19/2023, 11:59PM

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▼ PART-1: Neural Network from the scratch

For this part, you are not allowed to use any library other than numpy.

In this part, you will will implement the forward pass and backward pass (i.e. the derivates of each parameter wrt to the loss) with the network image uploaded

The weight matrix for the hidden layer is W1 and has bias b1.

The weight matrix for the ouput layer is W2 and has bias b2.

Activatation function is sigmoid for both hidden and output layer

Loss function is the MSE loss

Refer to the below dictionary for dimensions for each matrix

```
import numpy as np
import matplotlib.pyplot as plt
import pprint
pp = pprint.PrettyPrinter(indent=4)
import warnings
warnings.filterwarnings("ignore")
np.random.seed(0) # don't change this
weights = {
    'W1': np.random.randn(3, 2),
    'b1': np.zeros(3),
    'W2': np.random.randn(3),
    'b2': 0.
X = np.random.rand(1000,2)
Y = np.random.randint(low=0, high=2, size=(1000,))
#Sigmoid Function
def sigmoid(z):
    return 1/(1 + np.exp(-z))
#Implement the forward pass
def forward_propagation(X, weights):
   \# Z1 -> output of the hidden layer before applying activation
   \# H -> output of the hidden layer after applying activation
    \# Z2 -> output of the final layer before applying activation
    \# Y -> output of the final layer after applying activation
    Z1 = np.dot(X, weights['W1'].T) + weights['b1']
    H = sigmoid(Z1)
    Z2 = np.dot(H, weights['W2']) + weights['b2']
    Y = sigmoid(Z2)
    return Y, Z2, H, Z1
# Implement the backward pass
# Y T are the ground truth labels
def back_propagation(X, Y_T, weights):
    N_points = X.shape[0]
    # forward propagation
    Y, Z2, H, Z1 = forward_propagation(X, weights)
```

```
L = (1/(2*N_points)) * np.sum(np.square(Y - Y_T))
   # back propagation
   dLdY = 1/N points * (Y - Y T)
    dLdZ2 = np.multiply(dLdY, (sigmoid(Z2)*(1-sigmoid(Z2))))
    dLdW2 = np.dot(H.T, dLdZ2)
   dLdb2 = np.sum(dLdZ2, axis=0)
   dLdH = np.outer(dLdZ2, weights['W2'])
    dLdZ1 = np.multiply(dLdH, (sigmoid(Z1) * (1 - sigmoid(Z1))))
    dLdW1 = np.dot(dLdZ1.T, X)
   dLdb1 = np.sum(dLdZ1, axis=0)
    gradients = {
        'W1': dLdW1,
        'b1': dLdb1,
        'W2': dLdW2,
        'b2': dLdb2,
    }
    return gradients, L
gradients, L = back_propagation(X, Y, weights)
print(L)
    0.1332476222330792
pp.pprint(gradients)
       'W1': array([[ 0.00244596, 0.00262019],
           [-0.00030765, -0.00024188],
           [-0.00034768, -0.000372 ]])
         'W2': array([0.02216011, 0.02433097, 0.01797174]),
         'b1': array([ 0.00492577, -0.00058023, -0.00065977]),
         'b2': 0.029249230265318685}
```

Your answers should be close to L = 0.133 and 'b1': array([0.00492, -0.000581, -0.00066])

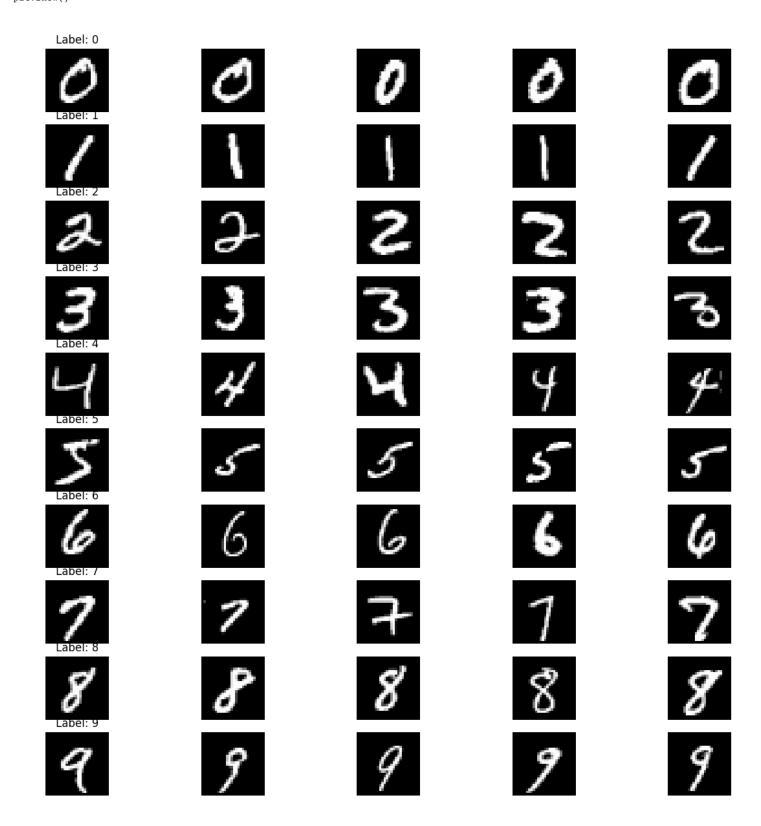
▼ PART 2 MNIST Dataset

Description: The MNIST dataset is a widely-used benchmark dataset in the field of machine learning and computer vision. It consists of 70,000 grayscale images of handwritten digits (0-9), with 60,000 images in the training set and 10,000 images in the test set. The images are 28x28 pixels in size, and each pixel is represented by an integer value between 0 and 255, with 0 representing a white pixel and 255 representing a black pixel.

```
break
fig, axes = plt.subplots(10, 5, figsize=(15, 15))

for i, label in enumerate(LABELS):
    for j, sample in enumerate(samples[label]):
        axes[i, j].imshow(sample, cmap='gray')
        axes[i, j].axis('off')
    if j == 0:
        axes[i, j].set_title(f"Label: {label}")

plt.show()
```



2.2 Preparing the dataset

- 1) Print the shapes x_{dev} , y_{dev} , x_{test} , y_{test}
- 2) Flatten the images into one-dimensional vectors and again print the shapes of x_{dev} , x_{test}
- 3) Standardize the development and test sets.
- 4) Train-test split your development set into train and validation sets (8:2 ratio).

```
# shapes
print("x_dev shape:", x_dev.shape)
print("y_dev shape:", y_dev.shape)
print("x_test shape:", x_test.shape)
print("y_test shape:", y_test.shape)
x_dev_flat = x_dev.reshape(x_dev.shape[0], -1)
x_test_flat = x_test.reshape(x_test.shape[0], -1)
print("x_dev_flat shape:", x_dev_flat.shape)
print("x_test_flat shape:", x_test_flat.shape)
# step 3
x_dev_std = x_dev_flat.astype('float32') / 255
x_test_std = x_test_flat.astype('float32') / 255
# train-test split
from sklearn.model selection import train test split
x_train, x_val, y_train, y_val = train_test_split(x_dev_std, y_dev, test_size=0.2, random_state=42)
print("x_train shape:", x_train.shape)
print("y train shape:", y train.shape)
print("x_val shape:", x_val.shape)
print("y_val shape:", y_val.shape)
    x dev shape: (60000, 28, 28)
    y_dev shape: (60000,)
    x_test shape: (10000, 28, 28)
    y_test shape: (10000,)
    x_dev_flat shape: (60000, 784)
    x_test_flat shape: (10000, 784)
    x_train shape: (48000, 784)
    y_train shape: (48000,)
    x_val shape: (12000, 784)
    y_val shape: (12000,)
2.3 Build the feed forward network
First hidden layer size - 128
Second hidden layer size - 64
Third and last layer size - You should know this
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense
model = Sequential([
```

2.3.1) Comment briefly on importance of activation functions used.

Dense(128, activation='relu', input shape=(x train.shape[1],)),

Activation functions are important in neural networks because they introduce non-linear properties, allowing network to learn complex patterns and approximate non-linear functions.

we use two activation functions:

])

Dense(64, activation='relu'),
Dense(10, activation='softmax')

- ReLU: used in hidden layers. Advantage in its simplicity and ability to solve the vanishing gradient problem which arises when gradients become too small during backpropagation. ReLU accelerates training and enhances network performance.
- Softmax: used in the output layer for multi-class classification; Softmax transforms the network's output into a probability distribution, ensuring the sum of all output probabilities equals 1. This helps predict and choose the most likely class.

2.4) Print out the model summary

model.summary()

Model: "sequential"

Layer (type)	Output	Shape	Param #
dense (Dense)	(None,	128)	100480
dense_1 (Dense)	(None,	64)	8256
dense_2 (Dense)	(None,	10)	650
Total params: 109,386 Trainable params: 109,386 Non-trainable params: 0			

2.5) Do you think this number is dependent on the image height and width?

The neural network input features depend on image height and width. We flattened 28x28 pixel images into one-dimensional vectors, giving each image 784 input features (28 * 28 = 784). The number of input features changed with image dimensions. When constructing a neural network, the size of the input layer must correspond to the number of input features. Thus, if the image height and width changed, the input shape specified in the first hidden layer would also need to change.

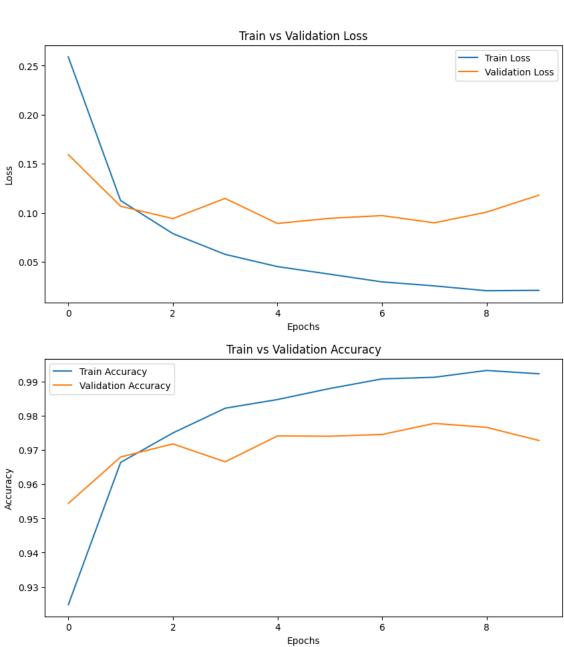
2.6) Use the right metric and the right loss function and batch size, with Adam as the optimizer, train your model for 10 epochs.

```
# Compile the model
model.compile(loss='sparse categorical crossentropy',
          optimizer='adam'
          metrics=['accuracy'])
# Train the model
batch size = 32
epochs = 10
history = model.fit(x_train, y_train, validation_data=(x_val, y_val), batch_size=batch_size, epochs=epochs)
   Epoch 1/10
   1500/1500 [============= ] - 9s 5ms/step - loss: 0.2590 - accuracy: 0.9248 - val_loss: 0.1594 - val_accuracy:
   Epoch 2/10
   1500/1500 [============= ] - 7s 5ms/step - loss: 0.1126 - accuracy: 0.9664 - val loss: 0.1068 - val accuracy:
   Epoch 3/10
   1500/1500 [==============] - 8s 5ms/step - loss: 0.0789 - accuracy: 0.9750 - val loss: 0.0942 - val accuracy:
   Epoch 4/10
   1500/1500 [===========] - 7s 5ms/step - loss: 0.0578 - accuracy: 0.9823 - val loss: 0.1148 - val accuracy:
   Epoch 5/10
   1500/1500 [============] - 8s 5ms/step - loss: 0.0453 - accuracy: 0.9848 - val loss: 0.0892 - val accuracy:
   Epoch 6/10
   1500/1500 r=
               Epoch 7/10
   1500/1500 [===========] - 8s 5ms/step - loss: 0.0297 - accuracy: 0.9909 - val loss: 0.0973 - val accuracy:
   Epoch 8/10
   1500/1500 [============ ] - 8s 5ms/step - loss: 0.0256 - accuracy: 0.9913 - val loss: 0.0899 - val accuracy:
   Epoch 9/10
   1500/1500 [============== ] - 7s 5ms/step - loss: 0.0207 - accuracy: 0.9933 - val loss: 0.1008 - val accuracy:
   Epoch 10/10
```

- 2.7) Plot a separate plots for:
- a. displaying train vs validation loss over each epoch

b. displaying train vs validation accuracy over each epoch

```
# train vs validation loss
plt.figure(figsize=(10, 5))
plt.plot(history.history['loss'], label='Train Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.title('Train vs Validation Loss')
plt.legend()
plt.show()
# train vs validation accuracy
plt.figure(figsize=(10, 5))
plt.plot(history.history['accuracy'], label='Train Accuracy')
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.title('Train vs Validation Accuracy')
plt.legend()
plt.show()
```



2.8) Finally, report the metric chosen on test set

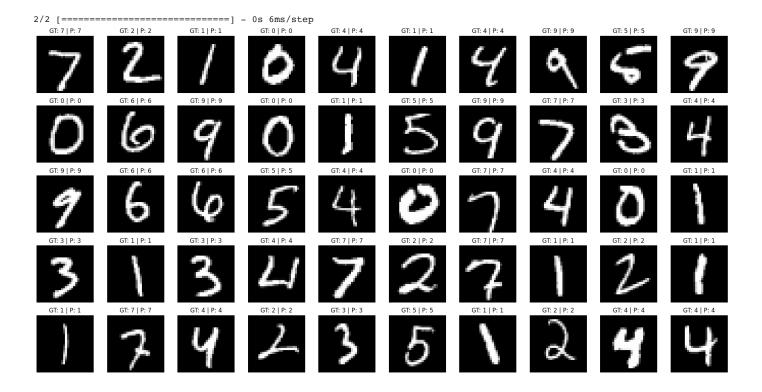
2.9 Plot the first 50 samples of test dataset on a 10*5 subplot and this time label the images with both the ground truth (GT) and predicted class (P).

```
predictions = model.predict(x_test_standardized[:50])
predicted_labels = np.argmax(predictions, axis=1)

plt.figure(figsize=(20, 10))

for i in range(50):
    plt.subplot(5, 10, i + 1)
    plt.imshow(x_test[i], cmap='gray')
    plt.axis('off')
    plt.title("GT: {} | P: {}".format(y_test[i], predicted_labels[i]))

plt.tight_layout()
plt.show()
```



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