

MICRO-453

**Robotics practicals**

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| Cursus                                    | Sem.     | Type |
|---|----------|------|
| Robotics, Control and Intelligent Systems |          | Opt. |
| Robotics                                  | MA2, MA4 | Obl. |

|                     |                     |
|---------------------|---------------------|
| Language            | English             |
| Credits             | 4                   |
| Withdrawal Session  | Unauthorized Summer |
| Semester Exam       | Spring              |
|                     | During the semester |
| Workload            | 120h                |
| Weeks               | 14                  |
| Hours               | <b>4 weekly</b>     |
| Practical work      | 4 weekly            |
| Number of positions |                     |

**Summary**

The goal of this lab series is to practice the various theoretical frameworks acquired in the courses on a variety of robots, ranging from industrial robots to autonomous mobile robots, to robotic devices, all the way to interactive robots.

**Content**

The practicals can include the following topics:

- Application of Bayes filters to mobile robot localization
- Teaching Robots to Accomplish a Manipulation Task
- Constructing and testing a rimless wheel walker
- Programming of an industrial SCARA Robot Adept
- Experimenting with haptics interfaces
- Controlling a serial robot ABB IRB 120
- Control of the Micro Delta Direct Drive robot
- Programming and characterization of a modular fish robot
- Tangible Human-Swarm Interaction using ROS
- Artificial Muscles
- ROS basics
- Integrated barometer/GNSS height determination on a UAV
- Visual Navigation: A Deep Learning Perspective

**WARNING: These practicals have a limited number of places, due to the heavy equipment used, students following the master in robotics will have priority in the attribution of places.**

**Keywords**

industrial robotics, haptics, autonomous robots, manipulation, navigation

**Learning Prerequisites****Required courses**

Basics of mobile robotics  
Introduction to automatic control  
Introduction to signal processing

**Important concepts to start the course**

Robotics  
Programming  
Automatic control  
Signal processing

### Learning Outcomes

By the end of the course, the student must be able to:

- Assess / Evaluate the performances of a robotic system
- Synthesize a control system
- Discuss the performances of a system
- Elaborate the model of a system

### Transversal skills

- Plan and carry out activities in a way which makes optimal use of available time and other resources.
- Use a work methodology appropriate to the task.
- Collect data.
- Write a scientific or technical report.

### Teaching methods

Students attend a set of practicals by groups of two or three, supervised by an assistant.

### Expected student activities

Preparation of the practicals before attending it, writing of the report after the practical.

### Assessment methods

Written report and oral feedback during the practical

### Supervision

|              |     |
|--------------|-----|
| Office hours | No  |
| Assistants   | Yes |
| Forum        | No  |

### Resources

#### Moodle Link

- <http://moodle.epfl.ch/course/view.php?id=524>