

MSBRDM - Group Project

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1. Motivation

- Ever waited too long for your drink in a bar?
- Ever got a awful mixture from your barkeeper?
- → Here comes "Bartender's Little Helper"
- Fast & customized drinks
- Transparent pricing
- Safe human-robot interaction utilizing robot skin



Image source: https://www.augsburger-allgemeine.de/wirtschaft/Hat-Kuka-die-Zukunft-verschlafen-id52970466.html [Accessed: 01/13/2019]



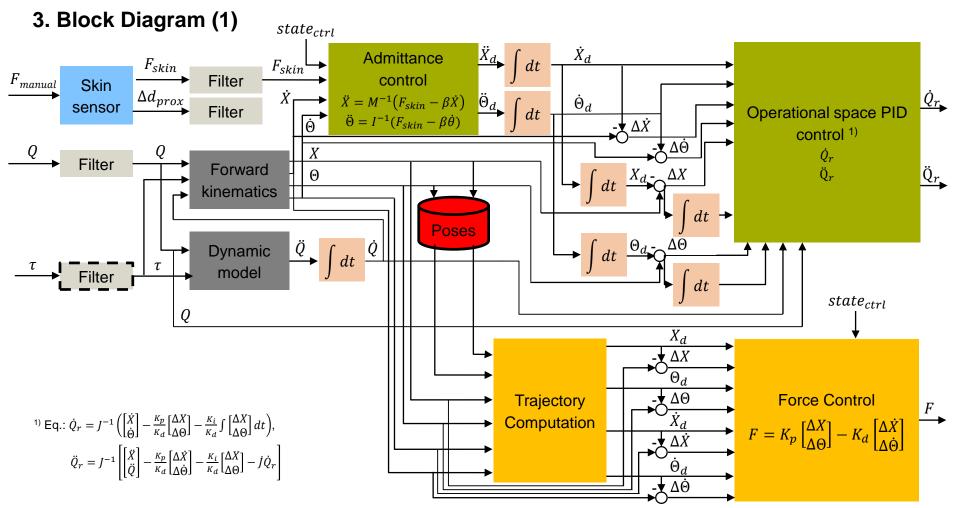
2. Functionalities

- Teaching task
 - Moving end effector to desired position & orientation (separate adjustability)
 - Switching between states by intuitive skin handling
 - Storing of grasping position & orientation
- Movement task
 - Movement along trajectory to stored position
 - Compensation of outer force influences
- Pouring task
 - Grasp bottle & pour drink into cup (position & orientation fixed)
- Advanced option: Computer vision
 - Improved robustness (e.g. visual based detection of orientation & position)



Image source: http://www.abb.de/cawp/seitp202/143b844927 b6e0bcc125738b00348d1b.aspx [Accessed: 01/13/2019]







3. Block Diagram (2)

