

Important: The Joint values q_2 and q_4 contain offsets of $-\pi/2$ in this drawing

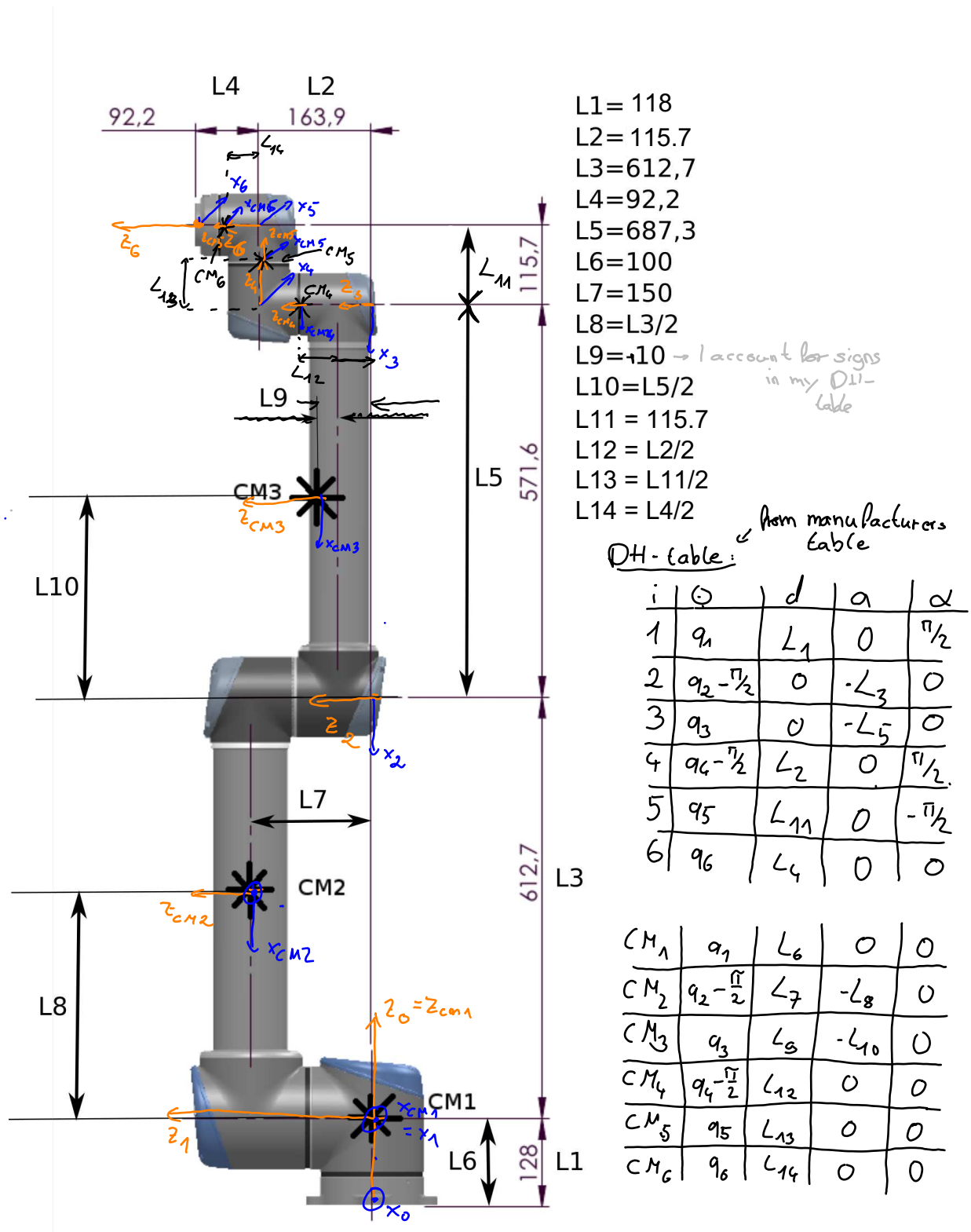


Figure 5.1: Universal Robot UR-10 with dimensions and kinematic parameters.