

## 資料進行預處理

### 1.匯入所需模組

```
from keras.datasets import cifar10      #從keras.datasets匯入cifar10資料集
import numpy as np                      #匯入numpy模組，NumPy是Python語言的擴充程式庫。支援維度陣
np.random.seed(10)                     #設定seed可以讓每次需要隨機產生的資料，都有相同的輸出
```

### 2讀取cifar10資料

```
(X_img_train,Y_label_train),(X_img_test,Y_label_test)=cifar10.load_data()

Downloading data from https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
170500096/170498071 [=====] - 2s 0us/step
170508288/170498071 [=====] - 2s 0us/step
```

### 3.顯示訓練與驗證資料的shape

```
print("train data:",'images:',X_img_train.shape,"labels:",Y_label_train.shape)
print("test data:",'images:',X_img_test.shape,"labels:",Y_label_test.shape)

train data: images: (50000, 32, 32, 3) labels: (50000, 1)
test data: images: (10000, 32, 32, 3) labels: (10000, 1)
```

### 4.將features(照片影像特徵值)標準化

```
X_img_train_normalize = X_img_train.astype('float32')/255.0
X_img_test_normalize = X_img_test.astype('float32')/255.0
```

### 5.label(照片影像的真實的值)以Onehot encoding 轉換

```
from keras.utils import np_utils
Y_label_train_OneHot = np_utils.to_categorical(Y_label_train)
Y_label_test_OneHot = np_utils.to_categorical(Y_label_test)
```

## 建立模型

### 1.匯入所需模組

```
from keras.models import Sequential      #匯入keras的Sequential模組
from keras.layers import Dense,Dropout,Activation,Flatten  #匯入keras的layers模組
from keras.layers import Conv2D,MaxPooling2D,ZeroPadding2D  #匯入keras的layers模組
```

### 2.建立keras的Sequential模型

```
model = Sequential()
```

### 3.建立卷積層1

```
model.add(Conv2D(filters=32,
                  kernel_size=(3, 3),
                  input_shape=(32, 32, 3),
                  activation='relu',
                  padding='same'))
```

#設定隨機產生32個濾鏡filter weight  
#每一個濾鏡3\*3大小  
#第1, 2維度:代表輸入的影像形狀32\*32大小, 第3個維度:因為  
#設定ReLU激活函數  
#此設定讓卷積運算, 產生的卷積影像大小不變

### 4.加入Dropout避免overfitting

```
model.add(Dropout(rate=0.25))
```

### 5.建立池化層1建立池化層1

```
model.add(MaxPooling2D(pool_size=(2, 2)))
```

### 6.建立卷積層2

```
model.add(Conv2D(filters=64,
                  kernel_size=(3, 3),
                  activation='relu',
                  padding='same'))
```

#建立64鏡filter weight  
#每一個濾鏡3\*3大小  
#設定ReLU激活函數  
#此設定讓卷積運算並不會改變影像大小

### 7.加入Dropout避免overfitting

```
model.add(Dropout(0.25))
```

### 8.建立池化層2

```
model.add(MaxPooling2D(pool_size=(2, 2)))
```

### 9.建立平坦層

```
model.add(Flatten())
model.add(Dropout(rate=0.25))
```

### 10.建立隱藏層

```
model.add(Dense(1024, activation='relu'))
model.add(Dropout(rate=0.25))
```

11.建立輸出層

```
model.add(Dense(10, activation='softmax'))
```

12.查看模型的摘要

```
print(model.summary())
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 32, 32, 32)	896
dropout (Dropout)	(None, 32, 32, 32)	0
max_pooling2d (MaxPooling2D)	(None, 16, 16, 32)	0
conv2d_1 (Conv2D)	(None, 16, 16, 64)	18496
dropout_1 (Dropout)	(None, 16, 16, 64)	0
max_pooling2d_1 (MaxPooling2D)	(None, 8, 8, 64)	0
flatten (Flatten)	(None, 4096)	0
dropout_2 (Dropout)	(None, 4096)	0
dense (Dense)	(None, 1024)	4195328
dropout_3 (Dropout)	(None, 1024)	0
dense_1 (Dense)	(None, 10)	10250

Total params: 4,224,970  
Trainable params: 4,224,970  
Non-trainable params: 0

None

進行訓練

1.定義訓練方式

```
model.compile(loss='categorical_crossentropy', optimizer='adam', metrics=['accuracy'])
```

2.開始訓練

```
train_history=model.fit(X_img_train_normalize,Y_label_train_OneHot,validation_split=0.2, epochs=10, b
```

```

Epoch 1/10
313/313 [=====] - 47s 12ms/step - loss: 1.8507 - accuracy: 0.3353 - v
Epoch 2/10
313/313 [=====] - 3s 10ms/step - loss: 1.2275 - accuracy: 0.5639 - v
Epoch 3/10
313/313 [=====] - 3s 10ms/step - loss: 1.0687 - accuracy: 0.6219 - v
Epoch 4/10
313/313 [=====] - 3s 10ms/step - loss: 0.9390 - accuracy: 0.6665 - v
Epoch 5/10
313/313 [=====] - 3s 10ms/step - loss: 0.8525 - accuracy: 0.6979 - v
Epoch 6/10
313/313 [=====] - 3s 10ms/step - loss: 0.7594 - accuracy: 0.7308 - v
Epoch 7/10
313/313 [=====] - 3s 10ms/step - loss: 0.6937 - accuracy: 0.7554 - v
Epoch 8/10
313/313 [=====] - 3s 10ms/step - loss: 0.6182 - accuracy: 0.7853 - v
Epoch 9/10
313/313 [=====] - 3s 10ms/step - loss: 0.5566 - accuracy: 0.8070 - v
Epoch 10/10
313/313 [=====] - 3s 10ms/step - loss: 0.4937 - accuracy: 0.8260 - v

```



### 3.定義show\_train\_history函式

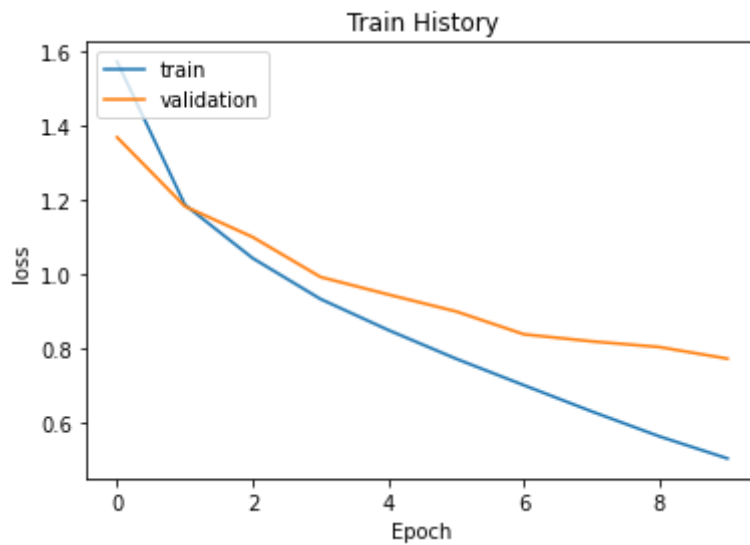
import matplotlib.pyplot as plt	#匯入matplotlib.pyplot模組，後續會使用
def show_train_history(train_history, train, validation):	#定義show_train_history函數，輸入下列
plt.plot(train_history.history[train])	
plt.plot(train_history.history[validation])	
plt.title('Train History')	#顯示圖的標題
plt.ylabel(train)	#顯示y軸的標籤
plt.xlabel('Epoch')	#設定x軸標籤是'Epoch'
plt.legend(['train', 'validation'], loc='upper left')	#設定圖例是顯示'train', 'validation', 在
plt.show()	

### 4.畫出accuracy執行結果

```
show_train_history(train_history, 'accuracy', 'val_accuracy')
```

## 5. 畫出loss誤差執行結果

```
show_train_history(train_history, 'loss', 'val_loss')
```



## 評估模型準確率

### 1. 評估模型準確率

```
scores = model.evaluate(X_img_test_normalize, Y_label_test_OneHot, verbose=0)
scores[1]
```

```
0.7325999736785889
```

## 進行預測

### 1. 執行預測

```
prediction = model.predict_classes(X_img_test_normalize)
```

```
/usr/local/lib/python3.7/dist-packages/keras/engine/sequential.py:450: UserWarning: `model.pr
warnings.warn("`model.predict_classes()` is deprecated and '
```

### 2. 執行結果

```
prediction[:10]

array([3, 8, 8, 0, 6, 6, 1, 6, 3, 1])
```

### 3. 建立plot\_images\_labels\_prediction函數

```

import matplotlib.pyplot as plt
def plot_images_labels_prediction(images, labels, prediction, idx, num=10):
    fig = plt.gcf()
    fig.set_size_inches(12, 14)
    if num>25:num=25
    for i in range(0, num):
        ax=plt.subplot(5, 5, 1+i)
        ax.imshow (images[idx], cmap='binary')

        title=str(i)+' ,'+label_dict[labels[i][0]]
        if len(prediction)>0:
            title+='=>'+label_dict[prediction[i]]
        ax.set_title(title, fontsize=10)
        ax.set_xticks([]);ax.set_yticks([])
        idx+=1
    plt.show()

```

#### 4.定義label\_dict字典

```
label_dict={0:"airplane",1:"automobile",2:"bird",3:"cat",4:"deer",5:"dog",6:"frog",7:"horse",8:"ship"
```

#### 5.預測結果

```
plot_images_labels_prediction(X_img_test,Y_label_test,prediction,0,10)
```

### 查看預測機率

#### 1.使用測試資料進行預測

```
Predicted_Probability = model.predict(X_img_test_normalize)
```

#### 2.建立show\_Predicted\_Probability函數

```

def show_Predicted_Probability(y, prediction, X_img, Predicted_Probability, i):
    print('label:', label_dict[y[i][0]], 'predict', label_dict[prediction[i]])
    plt.figure(figsize=(2, 2))
    plt.imshow(np.reshape(X_img_test[i], (32, 32, 3)))
    plt.show()
    for j in range(10):
        print(label_dict[j]+' Probability:%1.9f'%(Predicted_Probability[i][j]))

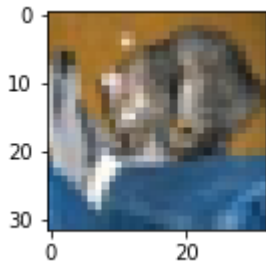
```

#顯示y(真實值)  
#設定顯示影像  
#設定顯示影像  
#設定顯示影像  
#使用for迴圈,

#### 3.查看第0筆資料預測的機率

```
show_Predicted_Probability(Y_label_test, prediction, X_img_test, Predicted_Probability, 0)
```

label: cat predict cat

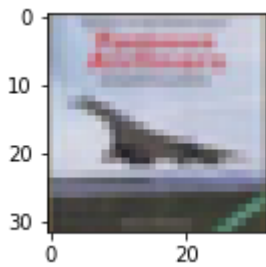


airplaneProbability:0.012357773  
automobileProbability:0.000820371  
birdProbability:0.005125463  
catProbability:0.565821171  
deerProbability:0.023896364  
dogProbability:0.306629539  
frogProbability:0.005355667  
horseProbability:0.002768110  
shipProbability:0.075222761

#### 4.查看第3筆資料預測的機率

show\_Predicted\_Probability(Y\_label\_test,prediction,X\_img\_test,Predicted\_Probability,3)

label: airplane predict airplane



airplaneProbability:0.573551536  
automobileProbability:0.009738880  
birdProbability:0.060519915  
catProbability:0.012868146  
deerProbability:0.023497602  
dogProbability:0.000437201  
frogProbability:0.001981785  
horseProbability:0.002172791  
shipProbability:0.309087425  
truckProbability:0.006144671

### 顯示混淆矩陣(confusion matrix)

#### 1查看prediction預測結果的形狀

prediction.shape

(10000,)

#### 2.查看y\_label\_test真實值的shape形狀

Y\_label\_test.shape

(10000, 1)

### 3.將y\_label\_test真實值，轉換為1維陣列

```
Y_label_test.reshape(-1)
```

```
array([3, 8, 8, ..., 5, 1, 7], dtype=uint8)
```

### 4.使用pandas crosstab建立混淆矩陣(confusion matrix)

```
import pandas as pd
print(label_dict)
pd.crosstab(
    Y_label_test.reshape(-1),
    prediction,
    rownames=['label'],
    colnames=['predict'])
```

```
#匯入pandas模組，後續會以
#顯示label_dict字典，方便
#顯示pd.crosstab建立混淆
#測試資料的真實值，使用
#測試資料的預測結果
#設定行的名稱label
#設定列的名稱predict
```

```
{0: 'airplane', 1: 'automobile', 2: 'bird', 3: 'cat', 4: 'deer', 5: 'dog', 6: 'frog',
```

predict	0	1	2	3	4	5	6	7	8	9
label										
0	807	10	33	24	17	2	11	12	51	33
1	19	837	12	14	6	4	12	6	12	78
2	57	4	615	59	108	42	77	22	10	6
3	27	4	70	556	92	134	65	41	5	6
4	16	2	50	55	755	12	39	60	9	2
5	15	2	56	202	73	575	26	44	3	4
6	6	3	27	56	51	16	827	7	6	1
7	15	0	41	35	72	38	8	784	0	7
8	81	41	20	20	12	10	5	5	776	30
9	30	73	12	32	6	5	10	18	20	794

## 建立3次的卷積運算神經網路

### 1.匯入所需模組

```
from keras.models import Sequential
from keras.layers import Dense, Flatten
from keras.layers import Dropout
from keras.layers import Conv2D, MaxPooling2D
```



## 2.建立keras的Sequential模型

```
model = Sequential()
```

## 3.建立卷積層1與池化層1與池化層1

```
model.add(Conv2D(filters=32,
                  kernel_size=(3, 3),
                  input_shape=(32, 32, 3),
                  padding='same',
                  activation='relu'))
model.add(Dropout(0.3))
model.add(Conv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool_size=(2, 2)))
```

## 4.建立卷積層2與池化層2建立卷積層2與池化層2

```
model.add(Conv2D(filters=64,
                  kernel_size=(3, 3),
                  padding='same',
                  activation='relu'))
model.add(Dropout(0.3))
model.add(Conv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool_size=(2, 2)))
```

## 5.新增加卷積層3與池化層3與池化層3

```
model.add(Conv2D(filters=128,
                  kernel_size=(3, 3),
                  padding='same',
                  activation='relu'))
model.add(Dropout(0.3))
model.add(Conv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool_size=(2, 2)))
```

## 6.建立神經網路(平坦層、隱藏層1(2500個神經元)、隱藏層2(1500個神經元)、輸出層)

```
model.add(Flatten())
model.add(Dropout(0.3))
model.add(Dense(2500, activation='relu'))
model.add(Dropout(0.3))
model.add(Dense(1500, activation='relu'))
model.add(Dropout(0.3))
model.add(Dense(10, activation='softmax'))
```

## 7.定義訓練方式

```
model.compile(loss='categorical_crossentropy', #loss:設定損失函數(loss function)
              optimizer='adam',              #optimizer:設定訓練時的最優化方法，在深度學習使用
              metrics=['accuracy'])         #設定評估模型的方式是accuracy準確率
```

## 8.訓練模型

```
train_history=model.fit(X_img_train_normalize,Y_label_train_OneHot,validation_split=0.2,epochs=50,b
```

```
Epoch 1/50
134/134 [=====] - 8s 43ms/step - loss: 2.2042 - accuracy: 0.1607
Epoch 2/50
134/134 [=====] - 5s 36ms/step - loss: 1.6467 - accuracy: 0.3876
Epoch 3/50
134/134 [=====] - 5s 36ms/step - loss: 1.3796 - accuracy: 0.4983
Epoch 4/50
134/134 [=====] - 5s 36ms/step - loss: 1.2368 - accuracy: 0.5531
Epoch 5/50
134/134 [=====] - 5s 36ms/step - loss: 1.0776 - accuracy: 0.6112
Epoch 6/50
134/134 [=====] - 5s 36ms/step - loss: 0.9814 - accuracy: 0.6494
Epoch 7/50
134/134 [=====] - 5s 36ms/step - loss: 0.8982 - accuracy: 0.6775
Epoch 8/50
134/134 [=====] - 5s 36ms/step - loss: 0.8186 - accuracy: 0.7085
Epoch 9/50
134/134 [=====] - 5s 36ms/step - loss: 0.7781 - accuracy: 0.7237
Epoch 10/50
134/134 [=====] - 5s 36ms/step - loss: 0.7113 - accuracy: 0.7459
Epoch 11/50
134/134 [=====] - 5s 36ms/step - loss: 0.6657 - accuracy: 0.7607
Epoch 12/50
134/134 [=====] - 5s 36ms/step - loss: 0.6013 - accuracy: 0.7832
Epoch 13/50
134/134 [=====] - 5s 36ms/step - loss: 0.5658 - accuracy: 0.7985
Epoch 14/50
134/134 [=====] - 5s 37ms/step - loss: 0.5286 - accuracy: 0.8111
Epoch 15/50
134/134 [=====] - 5s 36ms/step - loss: 0.4902 - accuracy: 0.8262
Epoch 16/50
134/134 [=====] - 5s 37ms/step - loss: 0.4798 - accuracy: 0.8262
Epoch 17/50
134/134 [=====] - 5s 37ms/step - loss: 0.4267 - accuracy: 0.8461
Epoch 18/50
134/134 [=====] - 5s 37ms/step - loss: 0.4070 - accuracy: 0.8540
Epoch 19/50
134/134 [=====] - 5s 37ms/step - loss: 0.3825 - accuracy: 0.8639
Epoch 20/50
134/134 [=====] - 5s 37ms/step - loss: 0.3569 - accuracy: 0.8725
Epoch 21/50
134/134 [=====] - 5s 37ms/step - loss: 0.3468 - accuracy: 0.8763
Epoch 22/50
134/134 [=====] - 5s 37ms/step - loss: 0.3223 - accuracy: 0.8846
Epoch 23/50
134/134 [=====] - 5s 37ms/step - loss: 0.3028 - accuracy: 0.8937
Epoch 24/50
134/134 [=====] - 5s 37ms/step - loss: 0.2817 - accuracy: 0.9003
```

```
Epoch 25/50
134/134 [=====] - 5s 37ms/step - loss: 0.2741 - accuracy: 0.9028
Epoch 26/50
134/134 [=====] - 5s 37ms/step - loss: 0.2565 - accuracy: 0.9097
Epoch 27/50
134/134 [=====] - 5s 37ms/step - loss: 0.2477 - accuracy: 0.9121
Epoch 28/50
134/134 [=====] - 5s 37ms/step - loss: 0.2332 - accuracy: 0.9185
Epoch 29/50
```

## 9.評估模型準確率

```
scores = model.evaluate(X_img_test_normalize, Y_label_test_OneHot, verbose=0)
scores[1]
```

```
0.7940000295639038
```

## 模型的儲存與載入

**尚未成功!!!!尚未成功!!!!**

```
train_history=model.fit(X_img_train_normalize, Y_label_train_OneHot, validation_split=0.2, epochs=5, ba
```

```
Epoch 1/5
313/313 [=====] - 6s 19ms/step - loss: 0.2961 - accuracy: 0.8975 - v
Epoch 2/5
313/313 [=====] - 6s 18ms/step - loss: 0.2887 - accuracy: 0.9004 - v
Epoch 3/5
313/313 [=====] - 6s 19ms/step - loss: 0.2578 - accuracy: 0.9133 - v
Epoch 4/5
313/313 [=====] - 6s 18ms/step - loss: 0.2505 - accuracy: 0.9146 - v
Epoch 5/5
313/313 [=====] - 6s 18ms/step - loss: 0.2457 - accuracy: 0.9158 - v
```

try:

```
model.load_weights("SaveModel/cifarCnnModel.h5")
```

```
print("載入模型成功!繼續訓練模型")
```

except :

```
print("載入模型失敗!開始訓練一個新模型")
```

```
載入模型失敗!開始訓練一個新模型
```

```
pip install h5py
```

```
Requirement already satisfied: h5py in /usr/local/lib/python3.7/dist-packages (3.1.0)
```

```
Requirement already satisfied: numpy>=1.14.5; python_version == "3.7" in /usr/local/lib/python3.7/dist-packages (1.19.2)
```

```
Requirement already satisfied: cached-property; python_version < "3.8" in /usr/local/lib/python3.7/dist-packages (1.5.2)
```

```
model.save_weights("SaveModel/cifarCnnModel.h5")
print("Saved model to disk")
```

```
-----  
OSError                                Traceback (most recent call last)  
<ipython-input-49-8f30d07ddf20> in <module>()  
----> 1 model.save_weights("SaveModel/cifarCnnModel.h5")  
      2 print("Saved model to disk")
```

2 frames

```
/usr/local/lib/python3.7/dist-packages/h5py/_hl/files.py in make_fid(name, mode,  
userblock_size, fapl, fcpl, swmr)  
    194     fid = h5f.create(name, h5f.ACC_EXCL, fapl=fapl, fcpl=fcpl)  
    195     elif mode == 'w':  
--> 196     fid = h5f.create(name, h5f.ACC_TRUNC, fapl=fapl, fcpl=fcpl)  
    197     elif mode == 'a':  
    198         # Open in append mode (read/write).
```

```
h5py/_objects.pyx in h5py._objects.with_phil.wrapper()
```

```
h5py/_objects.pyx in h5py._objects.with_phil.wrapper()
```

```
h5py/h5f.pyx in h5py.h5f.create()
```

```
OSError: Unable to create file (unable to open file: name =  
'SaveModel/cifarCnnModel.h5', errno = 2, error message = 'No such file or  
directory', flags = 13, o_flags = 242)
```