



# 统计机器学习实验报告

实验名称：多种模型的葡萄酒品种分类任务

姓名：王恒

---

学院：数学与统计学院

---

专业：计算数学

---

学号：220220934161

---

2023 年 6 月 11 日

### 摘要

本文中,我们实现了朴素贝叶斯、逻辑斯谛回归、线性支持向量机、基于高斯核函数的非线性支持向量机、多层非线性感知机(神经网络)模型及其相应的学习算法,并用以上模型对葡萄酒品种进行分类,六种模型分别得到了 95.83%, 97.22%, 94.44%, 95.83%, 97.22% 的准确率.

具体的,我们将数据集按照 6 : 4 的比例划分为训练集和测试集,并进行归一化. 其中,由于某些特征是连续型数据,我们在实现朴素贝叶斯模型时,将所有特征归一化到  $[-1, 1]$ , 并将其划分为固定的小区间,模型中的概率均为特征值所处区间的概率. 对于其他四种回归模型,我们在输入数据后先采用了批量归一化技术,自动学习归一化参数,相应的,均采用小批量随机梯度下降算法在训练集上进行优化,在测试集上测试准确率. 我们将本实验报告的所有内容开源:

<https://github.com/WANGH950/Statistical-Machine-Learning/tree/main/2ND>.

**关键词:** 朴素贝叶斯, 逻辑斯谛回归, 支持向量机, 神经网络, 葡萄酒品种分类

# 目录

|          |                              |           |
|----------|------------------------------|-----------|
| <b>1</b> | <b>实验代码</b>                  | <b>1</b>  |
| 1.1      | 感知机学习算法 . . . . .            | 1         |
| 1.2      | k-近邻算法 . . . . .             | 3         |
| <b>2</b> | <b>实验结果分析</b>                | <b>6</b>  |
| 2.1      | 感知机学习算法结果分析 . . . . .        | 7         |
| 2.2      | k-近邻算法结果分析 . . . . .         | 8         |
| <b>A</b> | <b>模型及算法源码</b>               | <b>10</b> |
| A.1      | 朴素贝叶斯模型及其训练算法 . . . . .      | 10        |
| A.2      | Logistic 模型及相应学习算法 . . . . . | 12        |
| A.3      | 支持向量机 . . . . .              | 13        |
| A.4      | 全连接神经网络 . . . . .            | 16        |

# 1 实验代码

## 1.1 感知机学习算法

Listing 1: 感知机原型算法实现

```
1 class Perception():
2     def __init__(self, dim) -> None:
3         # 构造函数
4         # dim: 特征维度
5         # w: 权重
6         # b: 偏置项
7
8         self.dim = dim
9         self.w = np.zeros([dim])
10        self.b = 0
11
12    def train(self, data_set, epoch, learning_rate):
13        # 训练模型
14
15        for i in range(epoch):
16            for (x,y) in data_set:
17                if self.predict(x)*y <= 0:
18                    self.w = self.w + learning_rate*x*y
19                    self.b = self.b + learning_rate*y
20
21            # 计算准确率
22            acc = self.accuracy(data_set)
23            print('epoch: ',i+1, 'accuracy: ', acc)
24            # 早停条件
25            if acc == 1:
26                break
27            print('Trining complete.')
28
29    def predict(self, x):
30        # 预测
31
32        return np.sign(np.dot(self.w,x) + self.b)
```

```
33     def accuracy(self, data_set):
34         # 计算精度
35
36         acc = 0
37         for (x,y) in data_set:
38             if self.predict(x)*y > 0:
39                 acc += 1
40         return acc/len(data_set)
```

Listing 2: 感知机对偶算法实现

```
1 class PerceptionDual():
2     def __init__(self, data) -> None:
3         # 构造函数
4         # data:      训练数据
5
6         self.data = data
7         self.N = len(data)
8         self.x = np.array([xx for (xx,_) in data])
9         self.y = np.array([yy for (_,yy) in data])
10        self.alpha = np.zeros([self.N])
11        self.b = 0
12
13    def train(self, epoch, learning_rate):
14        # 训练模型
15
16        for i in range(epoch):
17            for j in range(len(self.data)):
18                if self.predict(self.data[j][0])*self.data[j]
19                    ][1] <= 0:
20                    self.alpha[j] = self.alpha[j] +
21                        learning_rate
22                    self.b = self.b + learning_rate*self.data[j]
23                        ][1]
24
25                # 计算准确率
26                acc = self.accuracy(self.data)
27                print('epoch: ',i+1, 'accuracy: ', acc)
28
29                # 早停条件
```

```
25         if acc == 1:
26             break
27         print('Trining complete.')
28
29     def predict(self, x):
30         # 预测
31         return np.sign(np.dot(np.dot(self.x,x),self.alpha*self.
32                               y) + self.b)
33
34     def accuracy(self, data_set):
35         # 计算精度
36
37         acc = 0
38         for (x,y) in data_set:
39             if self.predict(x)*y > 0:
40                 acc += 1
41         return acc/len(data_set)
```

## 1.2 k-近邻算法

Listing 3: kd-树构造算法和搜索算法实现

```
1     class Node():
2     def __init__(self, value, data, label) -> None:
3         # 构造函数
4         # value:         节点的划分超平面参数
5         # data:         落在超平面上的数据点
6         # label:        落在超平面上的数据点对应的标签
7
8         self.value = value
9         self.data = data
10        self.label = label
11        self.left = None
12        self.right = None
13
14    def set_left(self, node):
15        # 设置左子节点
16
```

```
17         if node != None:
18             self.left = node
19
20     def set_right(self, node):
21         # 设置右子节点
22
23         if node != None:
24             self.right = node
25
26 class KDTree():
27     def __init__(self) -> None:
28         # 构造函数
29         # 用于存储KDTree, 支持直接实例化对象时直接输入一个kd-树
30         self.root = None
31
32     def create(self, data, label, j = 0):
33         # 递归构造平衡KD树
34
35         num, k = data.shape
36         if num == 0:
37             return None
38         else:
39             l = j % k
40             ind_sorted = np.argsort(data[:,l])
41             ind_median = ind_sorted[num//2]
42             value_ = int(np.median(data[ind_median,l]))
43             data_ = data[data[:,l]==value_]
44             label_ = label[data[:,l]==value_]
45             node = Node(
46                 value=value_,
47                 data=data_,
48                 label=label_
49             )
50             node.set_left(
51                 self.create(
52                     data=data[data[:,l]<value_],
53                     label=label[data[:,l]<value_],
```

```
54         j=j+1
55     )
56 )
57 node.set_right(
58     self.create(
59         data=data[data[:,1]>value_],
60         label=label[data[:,1]>value_],
61         j=j+1
62     )
63 )
64 if j == 0:
65     self.root = node
66 else:
67     return node
68
69 def search(self, x, j = 0, node = None):
70     # 递归搜索KD树
71
72     if self.root == None:
73         print("You haven't created a KDTree yet.")
74         return None
75     if j == 0:
76         node = self.root
77     k = x.shape[0]
78     l = j % k
79     # 叶子节点停止条件
80     if self.is_leaf(node):
81         distance = np.linalg.norm(x-node.data,2,1)
82         index = np.argmin(distance)
83         return node.data[index], node.label[index]
84     else:
85         # 计算当前节点中的最近数据点
86         distance = np.linalg.norm(x-node.data,2,1)
87         min_distance = np.min(distance)
88         index = np.argmin(distance)
89         nearest = node.data[index]
90         label = node.label[index]
```



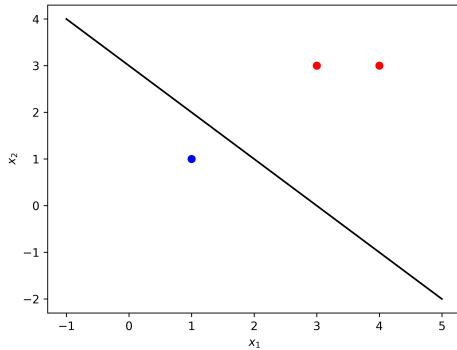
```
91         # 递归计算子节点的最近数据点，并比较
92         if x[l] < node.value and node.left != None:
93             nearest_, label_ = self.search(
94                 x = x,
95                 j = j+1,
96                 node = node.left
97             )
98             if np.linalg.norm(x-nearest_,2) < min_distance:
99                 nearest = nearest_
100                 label = label_
101         elif x[l] > node.value and node.right != None:
102             nearest_, label_ = self.search(
103                 x = x,
104                 j = j+1,
105                 node = node.right
106             )
107             if np.linalg.norm(x-nearest_,2) < min_distance:
108                 nearest = nearest_
109                 label = label_
110         return nearest, label
111
112     def is_leaf(self, node: Node):
113         # 判断是否是叶子节点
114
115         if node.left != None or node.right != None:
116             return False
117         else:
118             return True
```

## 2 实验结果分析

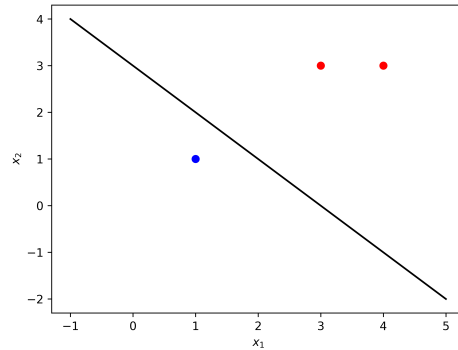
MNIST 数据集通过 torchvision 加载,所有算法基于 python 的 numpy 实现,数据预处理的一部分地方借助 pytorch 实现. 细节请参考:

<https://github.com/WANGH950/Statistical-Machine-Learning/tree/main/1ST>

## 2.1 感知机学习算法结果分析



(a) 感知机原型算法训练结果



(b) 感知机对偶算法训练结果

图 1: 感知机模型训练结果, 其中红点表示正类, 蓝点表示负类, 黑色实线表示感知机分割超平面.

以 0.01 的学习率, 感知机原型算法在题目给定的数据上, 经过 5 次训练后收敛, 得到结果. 以 0.01 的学习率, 感知机对偶算法在题目给定的数据上, 经过 5 次训练后收敛, 得到结果. (图 1)

Listing 4: MNIST 数据加载

```
1 import torchvision
2 data=torchvision.datasets.MNIST(
3     root='MNIST',
4     train=True,
5     transform=torchvision.transforms.ToTensor(),
6     download=True
7 )
```

Listing 5: MNIST 数据预处理

```
1 train_data = data.train_data
2 train_label = data.train_labels
3 # 转化为二分类
4 data_set = []
5 for i in range(train_data.shape[0]):
6     if train_label[i] < 5:
7         y = 1
8     else:
```

```
9         y = -1
10     data_set.append(
11         (train_data[i].reshape([28*2]).numpy()/255,y)
12     )
```

Listing 6: 使用对偶感知机算法处理 MNIST 数据

```
1 model = PerceptionDual(data_set[:1000])
2 model.train(
3     epoch=30,
4     learning_rate=0.001
5 )
```

如 Listing 6 所示, 我们使用 1,000 条数据, 在 0.001 的学习率下训练了 30 次, 最后在训练数据上得到了 0.923 的准确率.

## 2.2 k-近邻算法结果分析

Listing 7: MNIST 数据预处理

```
1 data_num,dimx,dimy = train_data.shape
2 data = train_data.reshape([data_num,dimx*dimy])+torch.randint
   (0,10,[data_num,dimx*dimy])
3 label = train_label.unsqueeze(-1)
```

如 Listing 7 所示, 由于手写数字是稀疏矩阵, 我们通过对其添加随机噪声以保证构造的 kd-树是好的 (不加噪声会导致数据都分布在一个节点上). 这里, 我们添加  $U(0, 10)$  的均匀整数噪声.

Listing 8: 构造 kd-树

```
1 model = KDTree()
2 tree = model.create(
3     data=data[:30000],
4     label=label[:30000]
5 )
```

如 Listing 8 所示, 我们使用前 30,000 条数据构造 kd-树. 我们选取第 40,000 条数据进行预测, 图 1 展示了预测结果和真实结果.

同时, 我们还使用后 30,000 条数据作为测试集进行测试 (listing 9), 得到了 93.223% 的准确率. 结果表明, 我们的算法实现准确.

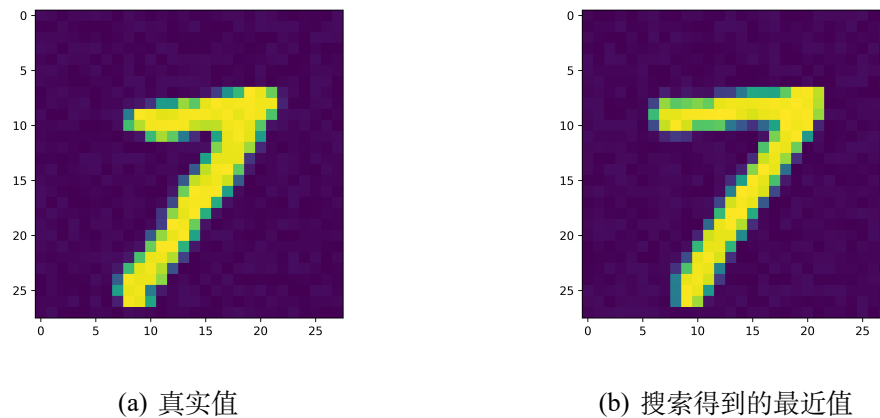


图 2: kd-树搜索结果.

Listing 9: 使用 kd-树分类测试数据

```
1 k = 30000
2 acc = 0
3 data_test = data[-k:]
4 label_test = label[-k:]
5 for i in range(k):
6     data_rel = data_test[i]
7     label_rel = label_test[i]
8     data_pre, label_pre = model.search(data_rel)
9     if label_pre == label_rel:
10         acc += 1
11 acc /= k
```

所有实验结果和运行效率以源码为准:

<https://github.com/WANGH950/Statistical-Machine-Learning/tree/main/1ST>

## A 模型及算法源码

### A.1 朴素贝叶斯模型及其训练算法

Listing 10: 朴素贝叶斯模型及其训练算法实现

```
1 # 定义模型
2 class NaiveBayes(nn.Module):
3     def __init__(self, n, full_labels, S, lamb) -> None:
4         super(NaiveBayes, self).__init__()
5         # 归一化参数
6         self.max = None
7         self.min = None
8         self.n = n # 特征数量
9         self.full_labels = full_labels # 所有标签
10        self.K = len(full_labels) # 标签数量
11        self.lamb = lamb # 贝叶斯估计参数 lambda
12        self.S = S # 每个特征分划区间数, 这里默认都为 S
13        self.cond_prob = torch.zeros([self.K, self.n, S]) # 条件
        # 概率
14        self.pre_prob = torch.zeros([self.K]) # 先验概率
15
16    def forward(self, features):
17        B, n = features.shape
18        assert n == self.n
19        post_prob = torch.ones([B, 1]) * self.pre_prob
20        # 归一化
21        features = (features - self.min) / (self.max - self.min
        ) * 2 - 1
22        delta_x = 2 / (self.S - 2)
23        for i in range(B):
24            for j in range(self.K):
25                for k in range(n):
26                    # (-\infty, -1) 和 (1, \infty) 的概率
27                    if features[i, k] < -1: post_prob[i, j] *=
                        self.cond_prob[j, k, 0]
28                    elif features[i, k] >= 1: post_prob[i, j] *=
                        self.cond_prob[j, k, -1]
```

```

29         else:
30             for h in range(self.S-2):
31                 l = -1 + h * delta_x
32                 r = l + delta_x
33                 if features[i,k] >= l and features[
34                     i,k] < r:
35                     post_prob[i,j] *= self.
36                         cond_prob[j,k,h+1]
37                     break
38     return self.full_labels[torch.argmax(post_prob,dim=1)]
39
40 def fit(self, train_data):
41     # 计算先验概率
42     N,_ = train_data.shape
43     self.max = torch.max(train_data[:,:,:-1],dim=0).values
44     self.min = torch.min(train_data[:,:,:-1],dim=0).values
45     train_data[:,:,:-1] = (train_data[:,:,:-1] - self.min) / (
46         self.max - self.min) * 2 - 1
47     features = train_data[:,:,:-1] # 特征
48     labels = train_data[:,-1:].int() # 标签
49     delta_x = 2 / (self.S - 2)
50     for i in range(self.K):
51         labels_i = labels == self.full_labels[i]
52         self.pre_prob[i] = (labels_i.sum() + self.lamb) / (
53             N + self.K*self.lamb)
54         for j in range(self.n):
55             self.cond_prob[i,j,0] = 1 / self.S
56             for k in range(self.S-1):
57                 l = -1 + k * delta_x
58                 r = l + delta_x
59                 features_ij = features[labels_i[:],0],j]
60                 features_ijk = features_ij[(features_ij>=1)
61                     *(features_ij<r)]
62                 self.cond_prob[i,j,k+1] = (features_ijk.
63                     shape[0] + self.lamb) / (labels_i.sum()
64                     + self.S*self.lamb)
65     return self.pre_prob, self.cond_prob

```

## A.2 Logistic 模型及相应学习算法

Listing 11: 逻辑斯谛回归模型及损失函数和训练方法

```
1 # 定义模型
2 class Logistic(nn.Module):
3     def __init__(self, feature_num, class_num) -> None:
4         super(Logistic, self).__init__()
5         self.feature_num = feature_num
6         self.class_num = class_num
7         self.linear = nn.Sequential(
8             nn.BatchNorm1d(feature_num), # 批量归一化
9             nn.Linear(feature_num, class_num-1, bias=False)
10        )
11
12    def forward(self, x):
13        B, d = x.shape
14        assert d == self.feature_num and B > 0
15        y = torch.cat([torch.exp(self.linear(x)), torch.ones([B
16            , 1])], dim=1)
17        y = y / torch.sum(y, dim=1, keepdim=True)
18        return y
19
20 # 负对数似然损失函数
21 class NLLLoss(nn.Module):
22     def __init__(self) -> None:
23         super().__init__()
24
25     def forward(self, y_pre, y_rel):
26         assert y_pre.shape == y_rel.shape
27         loss = -torch.log(y_pre)*y_rel
28         return torch.sum(loss)
29
30 # 定义模型训练函数
31 def train(model, data_set, batch_size, epoch = 1000,
32         learning_rate = 1e-3):
33     N, _ = data_set.shape
34     criterion = NLLLoss()
```

```
33     optim = torch.optim.SGD(model.parameters(), learning_rate,
34                               momentum=0) # 动量设置为0
35
36     start = time.time()
37     loss_values = torch.zeros(epoch)
38     for i in range(epoch):
39         model.train()
40         optim.zero_grad()
41         index = torch.randint(0, N, [batch_size]) # 随机选取batch
42             条数据
43         data_i = data_set[index, :]
44         x_i = data_i[:, :-1].to(torch.float32)
45         y_i = nn.functional.one_hot(data_i[:, -1].to(torch.int64),
46                                     num_classes=model.class_num)
47         outputs = model(x_i)
48         loss = criterion(outputs, y_i)
49         loss.backward()
50         optim.step()
51
52         model.eval()
53         loss_values[i] = loss.item()
54
55         print('\r%5d/{}|{}{}|{:.2f}s   [Loss: %e]'.format(
56             epoch,
57             "#" * int((i+1)/epoch*50),
58             " " * (50 - int((i+1)/epoch*50)),
59             time.time() - start) %
60             (i+1,
61              loss_values[i]), end = ' ', flush=True)
61     print("\nTraining has been completed.")
62     return loss_values
```

### A.3 支持向量机

Listing 12: 线性支持向量机

```
1 # 定义模型
2 class SVMLinear(nn.Module):
```



```
3     def __init__(self, feature_num) -> None:
4         super(SVMLLinear, self).__init__()
5         self.feature_num = feature_num
6         self.batch_norm = nn.BatchNorm1d(feature_num) # 特征批
           量归一化, 学习归一化参数
7         self.linear = nn.Linear(feature_num, 1)
8
9     def forward(self, x, signed = True):
10        B, d = x.shape
11        assert B > 0 and d == self.feature_num
12        normed = self.batch_norm(x)
13        outputs = self.linear(normed)
14        if signed:
15            return torch.sign(outputs)
16        else:
17            return outputs
18
19 # 合页损失函数
20 class HingeLoss(nn.Module):
21     def __init__(self, lamb) -> None:
22         super(HingeLoss, self).__init__()
23         self.lamb = lamb
24
25     def forward(self, res_pre_linear_values, res_rel, parameters):
26         return torch.sum(torch.relu(1 - res_rel *
           res_pre_linear_values)) + self.lamb * torch.norm(
           parameters) ** 2
27
28 # 定义训练函数
29 def train_svm(model, data_set, batch_size, lamb=1, epoch =
   1000, learning_rate = 1e-3):
30     N, _ = data_set.shape
31     criterion = HingeLoss(lamb)
32     optim = torch.optim.SGD(model.parameters(), learning_rate,
           momentum=0) # 动量设置为0
33
34     start = time.time()
```

```
35     loss_values = torch.zeros(epoch)
36     for i in range(epoch):
37         model.train()
38         optim.zero_grad()
39         index = torch.randint(0,N,[batch_size]) # 随机选取batch
           条数据
40         data_i = data_set[index,:]
41         x_i = data_i[:, :-1].to(torch.float32)
42         y_i = data_i[:, -1:].to(torch.int32)
43         outputs = model(x_i, signed=False)
44         loss = criterion(outputs, y_i, model.linear.weight)
45         loss.backward()
46         optim.step()
47
48         model.eval()
49         loss_values[i] = loss.item()
50
51         print('\r%5d/{}|{}{}|{: .2f}s   [Loss: %e]'.format(
52             epoch,
53             "#"*int((i+1)/epoch*50),
54             " "*(50-int((i+1)/epoch*50)),
55             time.time() - start) %
56             (i+1,
57             loss_values[i]), end = ' ', flush=True)
58     print("\nTraining has been completed.")
59     return loss_values
```

Listing 13: 非线性支持向量机

```
1 # 高斯核非线性SVM
2 class SVMNonLinear(nn.Module):
3     def __init__(self, feature_num, kernel_data) -> None:
4         super(SVMNonLinear, self).__init__()
5         self.feature_num = feature_num
6         self.kernel_features = kernel_data[:, :-1].to(torch.
           float32)
7         self.kernel_labels = kernel_data[:, -1].to(torch.int32)
8         self.batch_norm = nn.BatchNorm1d(feature_num)
```

```
9         self.linear = nn.Linear(feature_num+kernel_data.shape
10                                   [0],1)
11
12         self.kernel_params = nn.Parameter(torch.rand(1)+5,
13                                             requires_grad=True) # 核函数标准差
14
15     def forward(self, x, signed = True):
16         B,d = x.shape
17         assert B > 0 and d == self.feature_num
18         # 归一化特征
19         normed_data = self.batch_norm(x)
20         normed_kernel_data = self.batch_norm(self.
21                                             kernel_features)
22         kernel_features = torch.exp(-torch.mm(normed_data,
23                                             normed_kernel_data.T) / self.kernel_params**2) *
24         self.kernel_labels
25         outputs = self.linear(torch.cat([normed_data,
26                                         kernel_features],dim=1)) # 核方法特征和原特征结合
27         if signed:
28             return torch.sign(outputs)
29         else:
30             return outputs
```

## A.4 全连接神经网络

Listing 14: 全连接神经网络模型实现

```
1 class MLP(nn.Module):
2     def __init__(self,feature_num,class_num,hidden_dim=20,layer_num
3         =2) -> None:
4         super(MLP,self).__init__()
5         self.feature_num = feature_num
6         self.class_num = class_num
7         self.hidden_dim = hidden_dim
8         self.layer_num = layer_num
9         self.model = nn.Sequential(
10             OrderedDict(
11                 [("input_layer",
12                 nn.Sequential(
```

```
12         nn.BatchNorm1d(feature_num),
13         nn.Linear(feature_num,hidden_dim),
14         nn.Tanh()
15     )]) +
16     [("hidden_layer_"+str(i+1),
17      nn.Sequential(
18          nn.Linear(hidden_dim,hidden_dim),
19          nn.Tanh()
20      )) for i in range(layer_num-1)] +
21     [("output_layer",
22      nn.Sequential(
23          nn.Linear(hidden_dim,class_num),
24          nn.Softmax(dim=1)
25      ))]
26 )
27 )
28
29 # 前向传播
30 def forward(self,x):
31     return self.model(x)
```