

Fair Orientations: Beyond Envy-Freeness

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Abstract

We study the fair allocation of indivisible items, where each agent has a set of relevant items and can only receive items that are relevant to them. While the relevance constraint has been studied in recent years, existing work has largely focused on envy-freeness. In this paper, we complement the literature by providing a relatively complete understanding of other key fairness criteria – such as proportionality, equitability, and their relaxations – in settings where the items may be goods, chores, or a mixture of both.

1 Introduction

Fair division is a fundamental and challenging problem in both AI and economics. It involves allocating resources or tasks among participants while ensuring that participants are treated fairly. There is no single fairness criterion universally applicable. Among the various proposed fairness notions, envy-freeness (Varian 1974) and proportionality (Steinhaus 1949) are two of the most prominent and well-studied. Envy-freeness requires that no participant prefers the allocation of another over their own, while proportionality requires that each participant receives a value at least their proportional share, a threshold determined by the total number of participants and the agent’s valuation.

In the classical setting, any item can be allocated to any participant. However, in practical allocation problems, there are often relevance relationships between resources and participants, which restricts an item to be assigned only to a subset of agents. Relevance describes common situations in the real world when certain items are only available to certain agents due to geographic restrictions or demand requirements. For example, in the allocation of railway maintenance jobs between cities A and B, the jobs are typically managed by the local authorities of either city. In sports leagues such as the NBA and NFL, matches are held on the home court of one of the competing teams. Motivated by these examples, we study the allocation of indivisible items where relevance relationships between

agents and items are represented through graphs. In this framework, vertices correspond to agents, edges to items, and an agent is incident to an edge if the item is relevant to that agent. An agent can only receive the edges incident to her, and such an outcome is called an orientation.

The allocation model with relevance relationship, also referred to as the orientation model in this paper, has been studied in machine scheduling (Ebenlendr, Krčál, and Sgall 2014) and has recently gained popularity in fair division (Christodoulou et al. 2023; Deligkas et al. 2025; Kaviani, Seddighin, and Shahrezaei 2024; Amanatidis, Filos-Ratsikas, and Sgouritsa 2024). Most of these works on the fair division problem focus on the case where an item is relevant to two agents and consider envy-freeness. However, proportionality, another well-studied fairness notion in the classical setting, has been largely overlooked. The proportionality has been widely adopted as a golden fairness criterion in, for example, cake cutting (Chen et al. 2013; Procaccia 2013), clustering (Chen et al. 2019; Kellershals and Peters 2024), committee selection (Kalayci, Kempe, and Kher 2024), participatory budgeting (Peters, Pierczynski, and Skowron 2021), matching (Amanatidis et al. 2022), sortition (Flanigan et al. 2021; Ebadian and Micha 2025), and bargaining (Kalai 1977).

In the classical setting, an allocation is called proportional (PROP) if, informally, each agent gets at least as much value as they would if all the resources were evenly distributed. That is, each agent receives a value at least $\frac{1}{n}$ fraction of her total value of all items, where n refers to the number of agents. When the relevance relationship is introduced, we refine the threshold so that each agent expects her relevant items to be evenly distributed among the agents relevant to the underlying item. Another fairness criterion that has not been studied in the orientation model is equitability (Brams and Taylor 1996), which requires that each agent receives the same level of value.

In this paper, we investigate the notions of proportionality and equitability and also their relaxations, within a model where relevance relationships between agents and items are considered. Our goal is to provide a picture of the existence of computational results for

these fairness notions.

1.1 Our Contribution

We consider the problem of allocating a set E of m indivisible items among n agents, where items can be goods (providing positive value), chores (imposing negative value), and a mixture of both. Each agent i is associated with a set of relevant items $E_i \subseteq E$. We say an allocation is an orientation if each agent i receives only her relevant items. Throughout the paper, we focus on the case where all items are allocated, and all resulting allocations are orientations.

Proportionality Assume that agent i has an additive valuation function $v_i(\cdot) : 2^{E_i} \rightarrow \mathbb{R}$, mapping a subset of her relevant items to a real number. The original definition of the proportional share for agent i is $\frac{1}{n}v_i(E)$, which is widely adopted in the literature. One can set agent i 's value for each irrelevant item to 0, an approach applied in the literature (on envy-based notions, e.g., Deligkas et al. (2025)), and use the original definition of the proportional share.

However, in the orientation model, whether irrelevant items should be included in an agent's proportional share is a matter of discretion. For example, if a good e is only relevant to agents i and j , then e would be allocated to one of them. If agent i is aware that e will never be allocated to the other $n - 2$ agents, she might be unhappy if her entitlement is merely $\frac{1}{n}$ of e . Instead, she may reasonably expect to receive a $\frac{1}{2}$ share of e . Similarly, if a chore or task e is relevant only to agents i, j , it would be overly optimistic for agent i to assume she needs to undertake only a $\frac{1}{n}$ portion of e , as the task will ultimately be assigned to one of these two agents.

We now propose a refined definition of proportional share based on the relevance of each item. For each item $e \in E$, let n_e be the number of agents to whom e is relevant. The proportional share of i is

$$\text{PROP}_i = \sum_{e \in E_i} \frac{1}{n_e} v_i(e),$$

which means that, for each $e \in E_i$, agent i 's entitlement is $\frac{1}{n_e}$ of the value of e . This definition reduces to the original definition if each item e is relevant to all agents. An orientation is called PROP if every agent i 's value is at least PROP_i .

Next, we summarize our results and begin with PROP. First, the PROP orientations do not always exist. We are then interested in the problem of deciding whether an instance admits a PROP orientation and have the following results.

- The decision problem is NP-complete when items are all goods (or all chores) and agents have (1,2) or (-1,-2) bi-valued valuations and the relevance can be represented by simple graphs, i.e., every item is relevant to exactly two agents and $|E_i \cap E_j| \leq 1$ for all i, j .

- When valuations are binary (the absolute marginal value of any item being 1), the decision problem can be answered in polynomial time for arbitrary relevance.

We then consider the up to one or any relaxation of PROP. Informally, an orientation is PROP up to one (resp., any) item, abbreviated as PROP1 (resp., PROPX), if each agent would satisfy PROP after hypothetically adding or removing one (resp., any) item from her bundle. For the weaker criterion of PROP1, we show that

- PROP1 and fractional Pareto optimality (fPO) orientations exist and can be computed in polynomial time for mixed items and arbitrary relevance.

Possibly surprisingly, this is the strongest positive result in the orientation model, and as we will see, PROP1 appears to be the only fairness concept (among the most widely studied ones) that can be guaranteed. Further, this result also strengthens the unweighted result in (Aziz, Moulin, and Sandomirskiy 2020), where each item can be allocated to every agent. We also consider PROPX, of which the results are more negative.

- PROPX orientations do not always exist.
- It is NP-complete to decide whether an instance admits a PROPX orientation, even for simple graphs containing only goods (or only chores) and agents with (0,1)- or (0,-1)-binary valuations.

These results show a sharp contrast to the unconstrained setting, where PROPX allocations always exist for chores (Li, Li, and Wu 2022).

Equitability An allocation is equitable (EQ) if the subjective values of all agents are the same. For indivisible items, EQ allocations do not always exist, and hence, we consider relaxations such as EQ1 and EQX. Their formal definitions are provided in the next section. In contrast to the results in the unconstrained setting, where EQ1 and EQX allocations are guaranteed to exist, we prove that

- EQ1/EQX orientations do not always exist.
- It is NP-complete to decide whether an instance admits an EQ, EQ1, or EQX orientation, even when the relevance can be represented through simple graphs.

Envy-freeness Although envy-freeness has been studied within the orientation model in the literature, its relaxation, envy-free up to one item (EF1), remains poorly understood for chores. To address this gap, we complement the existing results by examining EF1 orientations for chores. In stark contrast to goods for which an EF1 orientation always exists even in the orientation model (Deligkas et al. 2025), we prove that EF1 orientations may not exist for chores, even when the relevance relationships are represented by simple

graphs. Moreover, for such simple graphs, we characterize the necessary and sufficient conditions that guarantee the existence of EF1 orientations and show that it can be decided in polynomial time whether a given instance admits one. However, when relevance is modeled using multigraphs, i.e., each item is relevant to two agents and multiple items can be relevant to a pair of agents, the decision problem becomes NP-complete.

1.2 Other Related Work

We refer to surveys (Moulin 2019; Amanatidis et al. 2023) for a comprehensive coverage of recent results on fair allocation of indivisible items, and (Suksompong 2021) for various constraints that have been studied. In the following, we recall the most relevant work to our paper. Without constraints, EF1 and PROP1 allocations always exist and can be computed in polynomial time for goods, chores and the mixture of goods and chores (Bhaskar, Sricharan, and Vaish 2021). Furthermore, PROP1 and Pareto optimal are known to be compatible in the mixed setting (Barman and Krishnamurthy 2019; Aziz, Moulin, and Sandomirskiy 2020). PROPX allocations exist for chores but not for goods (Aziz, Moulin, and Sandomirskiy 2020; Li, Li, and Wu 2022). The existence of EFX allocation remains unknown, except for several special cases (Chaudhury, Garg, and Mehlhorn 2024).

Initiated by Christodoulou et al. (2023), EFX orientations of relevant items have been extensively studied. Zeng and Mehta (2024) characterized the graph structures for which EFX orientations always exist. Kaviani, Seddighin, and Shahrezaei (2024) and Amanatidis, Filos-Ratsikas, and Sgouritsa (2024) respectively proved the existence of approximate EFX orientations. Afshinmehr et al. (2025) and Hsu (2024) extended the study to multi-graphs, and Zhou et al. (2024) and Hsu and King (2025) generalized the results to chores, the mixture of goods and chores, and other variants of the EFX concept. In contrast to EFX, when the items are goods, Deligkas et al. (2025) proved that an EF1 orientation always exists even in the general orientation model.

2 Preliminaries

2.1 The Orientation Model

For any $k \in \mathbb{N}^+$, let $[k] = \{1, \dots, k\}$. We study the model of allocating a set $E = \{e_1, \dots, e_m\}$ of m indivisible items to a set $N = \{1, \dots, n\}$ of n agents. Each agent i has an additive valuation function $v_i : 2^E \rightarrow \mathbb{R}$, that is, for any $S \subseteq E$, $v_i(S) = \sum_{e \in S} v_i(\{e\})$. For ease of notation, we write $v_i(e)$ instead of $v_i(\{e\})$. We call a valuation binary if $v_i(e) \in \{0, a\}$ for all items $e \in E$, where $a = 1$ or -1 . For any $S \subseteq E$, let $|S|$ be the number of items in S . An item is a good (resp., a chore) for an agent if it yields a non-negative (resp., non-positive) value. If the value of an item is zero for an agent, then the item can be a good or a chore. In this paper, we say an instance is a goods-instance (resp., chores-instance)

if all items are goods (resp., chores) for all agents. We call it a mixed-instance if an item can yield a positive value for one agent but a negative value for another.

In the general orientation model, each agent i has a non-empty set of relevant items $E_i \subseteq E$. For each item $e \in E$, let $N_e = \{i \in N \mid e \in E_i\}$ be the set of agents to whom e is relevant, and let $n_e = |N_e|$. We assume that N_e is non-empty for every e , as otherwise, this item can be removed. The orientation model is general and incorporates the classic unconstrained setting, where $E_i = E$ and $N_e = N$ for all $i \in N$ and $e \in E$. We are also interested in two structured cases. In the simple graph orientation model, $n_e = 2$ for all e and $|E_i \cap E_j| \leq 1$ for all $i \neq j$. That is, the model can be described as a simple graph $G = (N, E)$, where each vertex is an agent and each edge is an item that is relevant to the two agents incident to this edge. Similarly, in the multigraph orientation model, $n_e = 2$ for every e but the number of items in $E_i \cap E_j$ is not limited. That is, there may be multiple edges between any two agents (vertices). In this paper, when the instance is a graph or multigraph, we use the terminologies vertex i and agent i , and edge e and item e , interchangeably.

2.2 Solution Concepts

In the orientation model, each item can only be allocated to an agent to whom the item is relevant. Formally, an orientation is denoted by $\pi = (\pi_1, \dots, \pi_n)$, where $\pi_i \subseteq E_i$, and for any $i \neq j$, $\pi_i \cap \pi_j = \emptyset$ and $\bigcup_{i \in N} \pi_i = E$. Below, we introduce proportional fairness for mixed instances. Let $\text{PROP}_i = \sum_{e \in E_i} \frac{1}{n_e} \cdot v_i(e)$ be the (refined) proportional share for agent i .

Definition 1 An orientation $\pi = (\pi_1, \dots, \pi_n)$ is proportional (PROP) if for every agent $i \in N$, $v_i(\pi_i) \geq \text{PROP}_i$.

Definition 2 An orientation $\pi = (\pi_1, \dots, \pi_n)$ is proportional up to any item (PROPX) if for every agent $i \in N$, either (1) $v_i(\pi_i) \geq \text{PROP}_i$, or (2) $v_i(\pi_i \cup \{e\}) \geq \text{PROP}_i$ for any $e \in E_i \setminus \pi_i$ such that $v_i(e) \geq 0$ and $v_i(\pi_i \setminus \{e\}) \geq \text{PROP}_i$ for any $e \in \pi_i$ such that $v_i(e) \leq 0$.

Definition 3 An orientation $\pi = (\pi_1, \dots, \pi_n)$ is proportional up to one item (PROP1) if for every agent $i \in N$, one of the following three holds: (1) $v_i(\pi_i) \geq \text{PROP}_i$, (2) $v_i(\pi_i \cup \{e\}) \geq \text{PROP}_i$ for some item $e \in E_i \setminus \pi_i$, or (3) $v_i(\pi_i \setminus \{e\}) \geq \text{PROP}_i$ for some item $e \in \pi_i$.

A PROP orientation is PROPX, which is PROP1. The above definition can be directly applied to goods- and chores- instances. For example, for goods-instances, an orientation is PROPX if for every agent i , $v_i(\pi_i \cup \{e\}) \geq \text{PROP}_i$ for any $e \in E_i \setminus \pi_i$; For chores-instances, an orientation is PROPX if for every agent i , $v_i(\pi_i \setminus \{e\}) \geq \text{PROP}_i$ for any $e \in \pi_i$. Regarding PROP1, the quantifier of e in the prior two definitions is changed to existence.

In this paper, we also consider equitability (EQ) and envy-freeness (EF). An orientation $\pi = (\pi_1, \dots, \pi_n)$ is equitable (EQ) if $v_i(\pi_i) = v_j(\pi_j)$ for any two agents $i, j \in N$, and envy-free (EF) if $v_i(\pi_i) \geq v_i(\pi_j)$. That is, in EQ orientations, the agents have the same value, while in EF orientations, every agent has the largest value in their own allocations. EFX has been studied in, e.g., (Christodoulou et al. 2023; Zhou et al. 2024), and thus we omit the corresponding discussion in the current paper.

Definition 4 (EQX) An orientation $\pi = (\pi_1, \dots, \pi_n)$ is equitable up to any item (EQX) if for any two agents $i, j \in N$, either (1) $v_i(\pi_i) = v_j(\pi_j)$, or (2) $v_i(\pi_i) \geq v_j(\pi_j \setminus \{e\})$ holds for every item $e \in \pi_j$ with $v_j(e) > 0$, and $v_i(\pi_i \setminus \{e\}) \geq v_j(\pi_j)$ holds for every item $e \in \pi_i$ with $v_i(e) < 0$.

Definition 5 (EQ1) An orientation $\pi = (\pi_1, \dots, \pi_n)$ is equitable up to one item (EQ1) if for any two agents $i, j \in N$, one of the following three holds: (1) $v_i(\pi_i) = v_j(\pi_j)$, (2) there exists $e \in \pi_j$ such that $v_i(\pi_i) \geq v_j(\pi_j \setminus \{e\})$, or (3) there exists $e \in \pi_i$ such that $v_i(\pi_i \setminus \{e\}) \geq v_j(\pi_j)$.

Definition 6 (EF1) An orientation $\pi = (\pi_1, \dots, \pi_n)$ is envy-free up to one item (EF1) if for any two agents $i, j \in N$, one of the following three holds: (1) $v_i(\pi_i) \geq v_i(\pi_j)$, (2) there exists $e \in \pi_j$ such that $v_i(\pi_i) \geq v_i(\pi_j \setminus \{e\})$, or (3) there exists $e \in \pi_i$ such that $v_i(\pi_i \setminus \{e\}) \geq v_i(\pi_j)$.

3 Proportionality and Its Relaxations

In this section, we study PROP fairness and its relaxations, namely PROP1 and PROPX.

3.1 PROP Fairness

Similar to the classical fair division of indivisible items, PROP is not always satisfiable even for simple graph instances. Consider an item and two agents, and the item is relevant and yields positive value to both agents. A natural question is whether one can efficiently compute a PROP orientation when it exists. Unfortunately, the answer is no even for restricted instances. In the following, if agents' total value of their relevant items are identical, we say the valuations are normalized.

We derive the reduction from 2P2N-3SAT problem, known to be NP-complete (Berman, Karpinski, and Scott 2003; Yoshinaka 2005). A 2P2N-3SAT instance contains a Boolean formula in conjunctive normal form consisting of the set of variables $X = \{x_1, \dots, x_s\}$ and the set of clauses $C = \{C_1, \dots, C_t\}$. Each variable appears exactly twice as a positive literal and exactly twice as a negative literal in the formula, and each clause contains three distinct literals, i.e., $3t = 4s$. Denote by $L = \bigcup_{j=1}^s \{x_j^1, x_j^2, \bar{x}_j^1, \bar{x}_j^2\}$ the set of literals and by $C(\ell)$ the clause that contains literal ℓ .

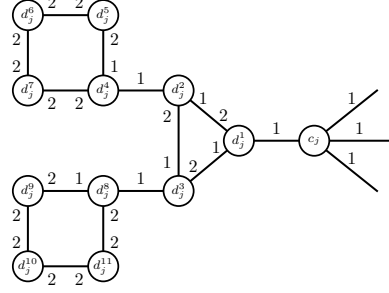


Figure 1: The illustration for goods-instance of the clause gadget for C_j . For each edge, if there is only one label, it represents the value of the edge to both endpoints. If there are two labels, the label closer to a vertex represents that vertex's value for the edge.

Theorem 1 Deciding the existence of PROP orientations is NP-complete, even for simple graphs where (1) all items are goods, valuations are normalized, and $v_i(e) \in \{1, 2\}$ for all i and $e \in E_i$; or all items are chores, valuations are normalized and $v_i(e) \in \{-1, -2\}$ for all i and $e \in E_i$.

Proof. [Proof for the goods-instance] The problem is in NP as given an orientation, one can verify whether it is PROP or not in polynomial time. Next, we derive the NP-completeness by a reduction from 2P2N-3SAT.

Given a 2P2N-3SAT instance, we create a goods-instance as follows:

- for each variable x_i , create two vertices i and \bar{i} and one edge (i, \bar{i}) with value 2 to both of them, as illustrated in Figure 2;
- for each clause C_j , create a vertex c_j and 11 dummy vertices d_j^1, \dots, d_j^{11} . Create edge (d_j^1, c_j) with value 1 for d_j^1 and c_j . Moreover, the construction of edges with two endpoints being dummy vertices and their values are illustrated in Figure 1;
- for each clause C_j , create 3 edges based on the following rule: if C_j includes literal x_i^k (resp., $\bar{x}_i^{k'}$), create edge (c_j, i) (resp., (c_j, \bar{i})) with value 1 for both incident agents, as illustrated in Figures 1 and 2 (edges without an endpoint).

The created instance has $2s + 12t$ vertices and $s + 17t$ edges. For any i and $e \in E_i$, $v_i(e) \in \{1, 2\}$ holds. Moreover, each agent has a total value of 4 for her incident edges (normalized valuations), and thus, the proportional share of each agent is 2.

Suppose that there exists a truth assignment that satisfies all clauses in C . For $c_j, d_j^1, \dots, d_j^{11}$, observe that we can satisfy each d_j^r with her proportional share even when (d_j^1, c_j) is allocated to c_j ; allocate edges in the cycle with 3 vertices d_j^1, d_j^2, d_j^3 in a clockwise manner, and allocate edges in the cycles with 4 vertices in an

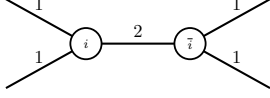


Figure 2: The illustration for goods-instance of the variable gadget for x_i . The label on each edge represents the value of the edge to both endpoints

anticlockwise manner. Edges (d_j^2, d_j^4) and (d_j^3, d_j^8) are arbitrarily allocated to their incident vertices. Thus, we create a partial assignment where each d_j^r receives value at least 2 and each c_j receives 1.

For each variable x_i , if x_i is True, allocate (i, \bar{i}) to vertex i . Then allocate the other two edges incident to i to the vertices corresponding to $C(x_i^1)$ and $C(x_i^2)$; recall that $C(x_i^1)$ refers to the clause that contains literal x_i^1 . For vertex \bar{i} , allocate her the two edges with value 1. Similarly, if \bar{x}_i is True, allocate (i, \bar{i}) to vertex \bar{i} and allocate the other two edges incident to \bar{i} to the vertices corresponding to $C(\bar{x}_i^1)$ and $C(\bar{x}_i^2)$, and for vertex i , allocate her the two edges with value 1. At this point, for any $i \in [s]$, both i and \bar{i} receive value 2.

For each vertex c_j , as clause C_j is satisfied, c_j receives one additional incident edge besides (d_j^1, c_j) , resulting in a value of at least 2. Therefore, we create a PROP orientation.

Next, for the reserve direction, suppose that there exists a PROP orientation π . We now create a truth assignment of $\{x_i\}_{i \in [t]}$ as follows: if (i, \bar{i}) is allocated to vertex i , then set x_i to True; and otherwise, if (i, \bar{i}) is allocated to vertex \bar{i} , set \bar{x}_i to True. Such a truth assignment ensures that exactly one of x_i, \bar{x}_i is set to True, and hence, the truth assignment is valid. Next, we prove that the assignment satisfies all clauses.

For a contradiction, suppose that there exists a clause $C_{j'}$ not satisfied. By the created truth assignment, each of the three vertices corresponding to the three literals in $C_{j'}$ does not receive the edge with value 2. Consequently, the three edges connecting $c_{j'}$ to variable vertices must not be allocated to $c_{j'}$ so that the three vertices corresponding to the three literals in $C_{j'}$ can satisfy PROP. Hence, the value of $c_{j'}$ is at most 1, meaning that the orientation is not PROP, deriving the desired contradiction. Therefore, the created truth assignment satisfies all clauses.

The proof for the chores-instance can be found in Appendix A.1. \blacksquare

To complement the hardness result, we show that for binary valuations and goods-instance (or chores-instance), one can compute in polynomial time a PROP orientation when it exists.

Theorem 2 For the general orientation model with binary additive valuations, one can in polynomial time determine whether a PROP orientation exists or not, and compute one if it exists.

Proof. [Proof Sketch] For the goods-instance, if some item has value zero for all relevant agents, arbitrarily allocate the item to the relevant agents. If some item has value one for exactly one relevant agent, allocate the item to that agent. At this point, let π' be the current partial assignment, and for each i , let a_i be the current value of agent i . Moreover, each of the unallocated items has value one for at least two agents relevant to that item.

Next, create a bipartite graph with two parts of vertices X and Y . For each unallocated item with respect to π' , create a vertex in X . For each agent i , create a number $\lceil \text{PROP}_i \rceil - a_i$ of vertices in Y . For each such a vertex, connect it to the vertex $x \in X$ if agent i is relevant to the item corresponding to x and has value one for it. We can show that a PROP orientation exists if and only if there exists a Y -perfect matching in the created bipartite graph. Then by applying the matching algorithm, one can determine whether a PROP orientation exists or not and compute one when it exists in time polynomial in n and m .

The idea is similar for chores-instances. The complete proof can be found in Appendix A.2. \blacksquare

3.2 PROP1 and PROPX Fairness

Motivated by the above impossibility results, we now consider the relaxations of PROP. We begin with PROP1 and show that PROP1 orientations always exist and are compatible with fractional Pareto optimal (fPO). An orientation $\pi = (\pi_1, \dots, \pi_n)$ Pareto dominates another orientation $\pi' = (\pi'_1, \dots, \pi'_n)$ if for any $i \in [n]$, $v_i(\pi_i) \geq v_i(\pi'_i)$ and at least one inequality is strict. An orientation π is Pareto optimal (PO) if no integral orientation Pareto dominates it, and is fPO if no fractional orientation Pareto dominates it, where in an integral orientation, each item is fully allocated to one agent, and in a fractional orientation, a fraction of item can be assigned to some agent. Formally, in a fractional orientation $\pi = (\pi_1, \dots, \pi_n)$, $\pi_i = (\pi_{i,e})_{e \in E}$ where $0 \leq \pi_{i,e} \leq 1$ represents the portion of e allocated to agent i .

Theorem 3 For the general orientation model and the mixed-instance, we can compute a PROP1 and fPO orientation in polynomial time.

Proof. [Proof Sketch] We start from a fractional proportional orientation created as follows: for any e and any $i \in N_e$, let $\pi_{i,e} = \frac{1}{n_e}$. In this fractional orientation, each agent receives her proportional share. Then we compute another fPO fractional orientation that Pareto improves the initial proportional orientation. Moreover, the new fractional orientation has acyclic undirected consumption graph: a bipartite graph in which vertices on one side are the agents and vertices on the other side are the items, and there is an edge between agent i and item e if and only if $\pi_{i,e} > 0$. To show the existence of such an fPO fractional orientation, we adapt the techniques in (Sandmirskiy and Segal-Halevi 2022) to the

orientation model. Last, we round the fractional orientation to a PROP1 and fPO integral orientation. The formal proof can be found in Appendix A.3. ■

We next study PROPX, a notion stricter than PROP1. In sharp contrast, the results for PROPX are mostly negative. Particularly, a PROPX orientation is not guaranteed to exist even in the case of simple graphs with binary valuations, and determining whether such an orientation exists is computationally intractable.

Proposition 1 PROPX orientations may not exist, even for simple graphs and binary valuations.

Proof. Let us begin with the goods-instance and consider the instance illustrated in Figure 3. Fix an arbitrary orientation π , and due to symmetry, assume that $(1, 2)$ is allocated to agent 2. Now we focus on agents 1, 3, and 4. To ensure that agent 1 satisfies PROPX, both edges $(1, 3)$ and $(1, 4)$ must be allocated to agent 1. As a consequence, one of agents 3 and 4 receives \emptyset and violates PROPX.

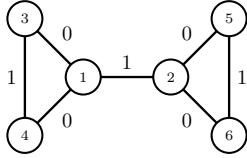


Figure 3: The illustration of the goods-instance where PROPX orientations do not exist. The label on each edge represents the value of the edge to both endpoints

As for chores-instance, we consider the same graph construction and transform agents' valuations into their negative. By arguments similar to that of goods, one can verify that no orientation is PROPX. ■

Theorem 4 For both goods- and chores-instances, deciding the existence of PROPX orientations is NP-complete, even for simple graphs and binary valuations.

Proof. [Partial proof for the goods-instance] The decision problem is clearly in NP. We next derive the NP-completeness by a reduction from 2P2N-3SAT.

Given a 2P2N-3SAT instance, we create a goods-instance as follows:

- for each clause C_j , create vertex c_j and 6 dummy vertices d_j^1, \dots, d_j^6 . Create edges (c_j, d_j^1) and (c_j, d_j^4) , and moreover, create edges with both endpoints being dummy vertices, as illustrated in Figure 4;
- for each clause C_j , create three more edges: if C_j includes literal x_i^k (resp., $\bar{x}_i^{k'}$), add edge (c_j, i) (resp. (c_j, \bar{i})) with value 1 for both incident agents, as illustrated in Figure 4.

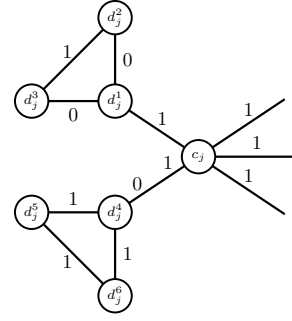


Figure 4: The illustration for goods-instance of the clause gadget for C_j . For each edge, if there is only one label, it represents the value of the edge to both endpoints. If there are two labels, the label closer to a vertex represents that vertex's value for the edge.

- for each variable x_i , create two vertices i and \bar{i} , and an edge (i, \bar{i}) with value 1 for both i, \bar{i} . Moreover, apart from (i, \bar{i}) , each i and \bar{i} values all other incident edges at 0.

The created instance has $2s + 7t$ vertices and $s + 11t$ edges, and moreover, each agent's valuation is binary. We first claim that in a PROPX orientation (if exists), for each c_j , edge (c_j, d_j^1) must be allocated to d_j^1 . For a contradiction, assume that this is not the case. We now focus on agents d_j^1, d_j^2, d_j^3 . Without loss of generality, assume edge (d_j^2, d_j^3) is allocated to d_j^2 in the orientation. Then in order to make d_j^3 satisfy PROPX, we need to allocate (d_j^1, d_j^3) to her, which then makes d_j^1 violates PROPX, as d_j^1 has value zero in the orientation and edge (d_j^1, d_j^3) (with value zero) is not allocated to her but her proportional share is $\frac{1}{2}$. One can verify that there exists a truth assignment satisfying all clauses if and only if there exists a PROPX orientation. The formal arguments can be found in Appendix A.4

The proof for the chores-instance is deferred to Appendix A.5 ■

4 Equitability and Its Relaxations

In this section, we consider equitability-related notions that have been widely studied in the unconstrained setting (Freeman et al. 2019; Barman et al. 2024), but remain underdeveloped in the orientation model.

In the unconstrained setting, EQX/1 allocations can be achieved through the greedy algorithm. However, our results indicate that neither EQ1 nor EQX is guaranteed to be satisfiable in the orientation model, and even worse, deciding their existence is NP-complete. For completeness, we also provide the complexity results on the notion of EQ.

Theorem 5 Determining whether an EQ orientation exists on a simple graph in both goods- and chores-instance is NP-complete.

The proof of the theorem can be found in Appendix B.1.

Proposition 2 An EQ1 orientation is not guaranteed to exist even for simple graphs.

Proof. Consider the example with identical valuations shown in Figure 5.

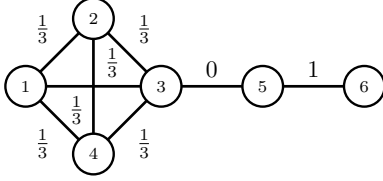


Figure 5: The illustration of the goods-instance where EQ1 does not exist. The label on each edge represents the value of the edge to both endpoints.

In any orientation, one of agents 5 and 6 receives value 0; suppose that this agent is 5. However, as there are 6 edges among 1, 2, 3, and 4, by the pigeonhole principle, at least one of them will receive two or more edges. Suppose this agent is 1, then we have $v_1(\pi_1 \setminus \{e\}) = \frac{1}{3} > v_5(\pi_5) = 0$ for all $e \in \pi_1$, which means that EQ1 does not hold between 1 and 5. As for the chores-instance, we use the same graph while changing each agent's value on each edge to the corresponding negative value. In that case, we have $v_1(\pi_1 \setminus \{e\}) = -\frac{1}{3} < v_5(\pi_5) = 0$ for all $e \in \pi_1$, which violates EQ1. ■

Theorem 6 Determining whether an EQ1 orientation exists on a simple graph in both goods- and chores-instance is NP-complete.

The proof is deferred to Appendix B.2. The non-existence of EQ1 orientations directly implies that EQX orientations are not guaranteed to exist, as EQX is a notion stricter than EQ1. Below we provide the hardness of the decision problem regarding EQX.

Theorem 7 Determining whether an EQX orientation exists on a simple graph in both goods- and chores-instances is NP-complete, even for instances with additive valuations.

Proof. [Partial proof for goods-instance] The decision problem is clearly in NP. We derive the reduction from the Partition problem: whether a set of integers x_1, \dots, x_n can be divided into two subsets with equal sums.

We create a goods-instance of a simple graph, as illustrated in Figure 6:

- create vertices $1, \dots, n$ and vertices p, q ; for each $j \in [n] \cup \{p, q\}$, create two dummy vertices k_j, k'_j ;

- for each $j \in [n] \cup \{p, q\}$, create edges $(j, k_j), (j, k'_j), (k_j, k'_j)$, and moreover, for each $j \in [n]$, create edges (j, p) and (j, q) .

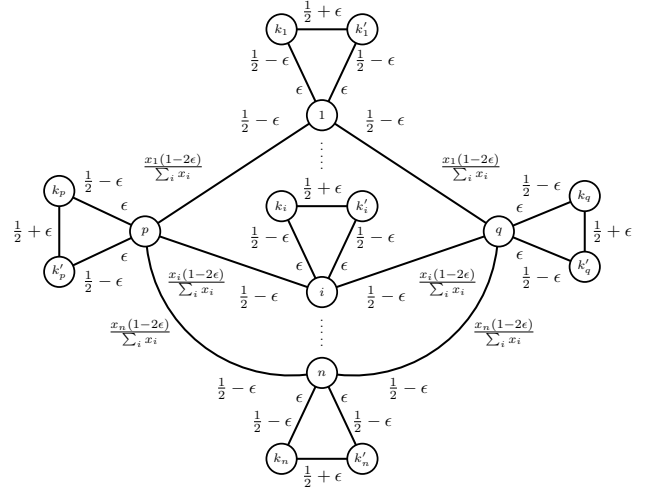


Figure 6: Illustration of the goods-instance for reduction from EQX. The label closer to a vertex represents that vertex's value for the edge.

We define the agents' valuations as follows:

- for each $j \in [n] \cup \{p, q\}$, let $v_j((j, k_j)) = v_j((j, k'_j)) = \epsilon$, $v_{k_j}((j, k_j)) = v_{k'_j}((j, k'_j)) = \frac{1}{2} - \epsilon$, and $v_{k_j}((k_j, k'_j)) = v_{k'_j}((k_j, k'_j)) = \frac{1}{2} + \epsilon$;
- for each $i \in [n]$, let $v_i((p, i)) = v_i((q, i)) = \frac{1}{2} - \epsilon$;
- for p and q , let $v_p((p, i)) = v_q((q, i)) = \frac{x_i}{\sum_{i \in [n]} x_i} (1 - 2\epsilon)$ for all $i \in [n]$,

where $\epsilon > 0$ is arbitrarily small. As the total value of each agent is 1, the created instance is normalized.

We claim that in an EQX orientation π , each $j \in [n] \cup \{p, q\}$ must receive exactly one of edges (j, k_j) and (j, k'_j) . Suppose not. If j receives neither (j, k_j) nor (j, k'_j) , then EQX is violated between k_j and k'_j ; assume without loss of generality that (k_j, k'_j) is allocated to k_j , then k'_j violates EQX when compared to k_j as $v_{k_j}(\pi_{k_j} \setminus \{(p, k_j)\}) = \frac{1}{2} + \epsilon > v_{k'_j}(\pi_{k'_j}) = v_{k'_j}((j, k'_j)) = \frac{1}{2} - \epsilon$. If j receives both of (j, k_j) and (j, k'_j) , then one of k_j and k'_j receives no edges and violates EQX when compared to j .

Given the above claim, we further show that in an EQX orientation π , each agent $i \in [n]$ must receive exactly one of the edges (p, i) and (q, i) . Suppose not. If i receives both of (p, i) and (q, i) , then k_i, k'_i violate EQX when compared to i , as after removing the edge with value ϵ for i (such an edge exists due to the above claim), the value of i is still $1 - 2\epsilon > \frac{1}{2} + \epsilon$. If i receives neither (p, i) nor (q, i) , then i violates EQX when compared to p as after removing the edge with value ϵ for

p , the value of p is greater than 2ϵ .

One can verify that there exists an EQX orientation if and only if the Partition instance is a yes-instance. The formal argument can be found in Appendix B.3.

The proof for the chores-instance is deferred to Appendix B.4. ■

We remark that all hardness results in this section hold for normalized instances, where the total values of items for agents are identical.

5 EF1 Orientation for Chores

In this section, we focus on the EF1 orientation for chores that have not been covered in the literature. For goods, it is known that an EF1 orientation exists in the general orientation model (Deligkas et al. 2025). However, for chores, EF1 orientations may not exist, even for simple graphs.

Theorem 8 For the chores-instance with simple graphs, EF1 orientations do not always exist. For simple graphs, one can compute in polynomial time an EF1 orientation when such an orientation exists.

The proof is deferred to Appendix C.1. On the contrary, the decision problem becomes computationally intractable for multigraphs, with the formal proof in Appendix C.2.

Theorem 9 For the chores-instance, determining whether an EF1 orientation exists in a multigraph is NP-complete.

6 Conclusion

In this paper, we studied proportionality, equitability and their relaxations in the fair orientation problem and presented a picture of existence and computational results on these fairness notions. We also addressed the previously unexplored question of EF1 orientations for chores. We hope these results contribute to a deeper understanding of these widely studied fairness notions in the orientation model.

Looking forward, as hardness results in Section 4 are derived from Partition, it remains unknown whether pseudo-polynomial time algorithms exist. For proportionality, it is worthwhile to consider PROPm (Baklanov et al. 2021), a notion lying between PROP1 and PROPX, and investigate whether PROPm orientations always exist. The non-existence example for PROPX presented in this paper does not imply the non-existence of PROPm orientations.

From a broader perspective, developing new fairness notions applicable in the general orientation model, with no restrictions on the number of relevant agents per item, is a promising and valuable direction. Our work has provided some negative results of existing fairness notions and can serve as a foundation for the development of new fairness concepts.

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Appendix

A Missing Materials in Section 3

A.1 Proof of Theorem 1 for Chores-Instance

As for the chores-instance, we use the same graph construction, but each agent’s value on the edges are mapped to the corresponding negative values. If an edge has value 1 (resp., 2) for a vertex in the reduction for goods, we now change it to -1 (resp., -2). For any i and $e \in E_i$, $v_i(e) \in \{-1, -2\}$ holds. Moreover, each agent has a total value of -4 for her incident edges (normalized valuations), and thus, the proportional share of each agent is -2 .

Suppose there is a truth assignment that satisfies all clauses in C . For $c_j, d_j^1, \dots, d_j^{l_j^1}$, observe that we can satisfy each d_j^r her proportional share even when (d_j^1, c_j) is allocated to d_j^1 ; allocate edges in the cycle with 3 vertices d_j^1, d_j^2, d_j^3 in an anticlockwise direction, and allocate edges in cycles with 4 vertices in a clockwise direction. Edges (d_j^2, d_j^4) and (d_j^3, d_j^8) are arbitrarily allocated to their incident vertices. At this point, each d_j^r satisfies her proportional share, and her value is unchanged thereafter.

For each x_i , if x_i is True, allocate (i, \bar{i}) to \bar{i} , and allocate i the other two edges incident to her; if \bar{x}_i is True, allocate (i, \bar{i}) to i , and allocate \bar{i} the other two edges incident to her. At this point, for any $i \in [s]$, both i and \bar{i} receive value -2 . For each vertex c_j , since clause C_j is satisfied, at least one incident edge other than (d_j^1, c_j) is not allocated to her, which implies that her

value is at least -2 . Therefore, the created orientation is PROP.

Next, for the reverse direction, suppose that there exists a PROP orientation π . We create a truth assignment of $\{x_i\}_{i \in [t]}$ as follows: if (i, \bar{i}) is allocated to vertex i , then set \bar{x}_i to True, and otherwise, set x_i to True. Such a truth assignment ensures that exactly one of x_i, \bar{x}_i is set to True, and hence, the truth assignment is valid. Moreover, if some clause $C_{j'}$ is not satisfied, then in π , $c_{j'}$ receives value at most -3 , violating PROP. Therefore, the created truth assignment satisfies all clauses.

A.2 Proof of Theorem 2

We begin with the goods-instance. If some item has value zero for all relevant agents, arbitrarily allocate the item to the relevant agents. If some item has value one for exactly one relevant agent, allocate the item to that agent. At this point, let π' be the current partial assignment, and for each i , let a_i be the current value of agent i . Moreover, each of the unallocated items has value one for at least two agents relevant to that item.

Next, create a bipartite graph with two parts of vertices X and Y . For each unallocated item with respect to π' , create a vertex in X . For each agent i , create a number $\lceil \text{PROP}_i \rceil - a_i$ of vertices in Y . For each such a vertex, connect it to the vertex $x \in X$ if agent i is relevant to the item corresponding to x and has value one for it. We below prove that a PROP orientation exists if and only if there exists a Y -perfect matching in the created bipartite graph.

For the “if” direction, based on the Y -perfect matching, one can extend π' to another (possibly partial) assignment where each agent i receives her proportional share. Moreover, unallocated items (if any) make agents weakly better off as items are goods. Thus, a PROP orientation exists. For the “only if” direction, denote by $Q \subseteq E$ the set of items with value one for at least two of their relevant agents. In the PROP orientation, each agent i must receive value at least $\lceil \text{PROP}_i \rceil - a_i$ when restricting to Q as items $E \setminus Q$ can increase the value of agent i by at most a_i . Hence, one can convert the assignment of Q in the PROP to a Y -perfect matching.

By applying the matching algorithm, one can determine whether a PROP orientation exists or not and compute one when it exists in time polynomial in n and m .

As for the chores-instance, the idea is similar. First, if some item has value zero for some relevant agent, then allocate it to that agent. At this point, each of the unallocated items has value -1 for every relevant agent. Next, we create a bipartite graph $(X \cup Y)$. For each unallocated item, create a vertex in X . For each agent i , create a number $\lfloor |\text{PROP}_i| \rfloor$ of vertices in Y . For each such agent vertex, connect it to the vertex $x \in X$ if agent i is relevant to the item corresponding to x . By the arguments similar to those for the goods-instance, one can verify that a PROP orientation exists if and

only if there exists a X -perfect matching in the created bipartite graph. Moreover, when a X -perfect matching exists, we can convert the matching to a PROP orientation.

A.3 Proof of Theorem 3

First, we present a key lemma.

Lemma 1 For any orientation π , one can compute in polynomial time a fPO orientation π^* such that: (i) π^* either Pareto dominates π or gives every agent the same value as π , and (ii) the undirected consumption graph \mathcal{CG}_{π^*} is acyclic.

To prove the lemma, we need extra notations. In the following, we say that an item e is:

- a chore if $v_i(e) < 0$ for all $i \in N_e$;
- neutral if $v_i(e) = 0$ for at least one $i \in N_e$ and $v_j(e) \leq 0$ for all $j \in N_e$;
- a good if $v_i(e) > 0$ for at least one $i \in N_e$;
- a pure good if $v_i(e) > 0$ for all $i \in N_e$.

An orientation π is non-malicious if each good e is consumed by agents $i \in N_e$ with $v_i(e) > 0$ and each neutral item e is consumed by agents $i \in N_e$ with $v_i(e) = 0$. Every fPO orientation is clearly non-malicious.

We will consider the agent-object graphs – bipartite graphs in which the nodes on one side are the agents and the nodes on the other side are the objects. In the (undirected) consumption-graph \mathcal{CG}_π of an orientation π , there is an edge between agent $i \in [n]$ and an item $e \in E$ if and only if $\pi_{i,e} > 0$; note as π is an orientation, if there is an edge between i and e , then $i \in N_e$ and $e \in E_i$.

The weighted directed consumption-graph $\vec{\mathcal{CG}}_\pi$ of an orientation π is constructed as follows. There is an edge $(i \rightarrow e)$ with weight $w_{i \rightarrow e} = |v_i(e)|$ if one of the two conditions holds:

- $\pi_{i,e} > 0, v_i(e) \geq 0$ and $e \in E_i$;
- $\pi_{i,e} < 1, v_i(e) < 0$ and $e \in E_i$.

The opposite edge $(e \rightarrow i)$ with weight $w_{e \rightarrow i} = \frac{1}{|v_i(e)|}$ is included in $\vec{\mathcal{CG}}_\pi$ in one of the two cases:

- $\pi_{i,e} > 0, v_i(e) < 0$ and $e \in E_i$;
- $\pi_{i,e} < 1, v_i(e) > 0$ and $e \in E_i$.

The product of a directed path P in $\vec{\mathcal{CG}}_\pi$, denoted $\Pi(P)$, is the product of weights of edges in P . In particular, the product of a cycle $C = (i_1 \rightarrow e_1 \rightarrow \dots \rightarrow e_L \rightarrow i_{L+1} = i_1)$ is

$$\Pi(C) = \prod_{k=1}^L (w_{i_k \rightarrow e_k} \cdot w_{e_k \rightarrow i_{k+1}}).$$

Closely following steps by steps the proofs in (Sandomirskiy and Segal-Halevi 2022), we present the characterization of fPO orientation.

Lemma 2 Given an orientation π , the following three properties are equivalent

- (i) π is fPO;
- (ii) π is non-malicious and its directed consumption graph $\vec{\mathcal{CG}}_\pi$ has no cycle C with $\Pi(C) < 1$.
- (iii) there is a vector of weights $\lambda = (\lambda_i)_{i \in [n]}$ with $\lambda_i > 0$, $i \in [n]$, such that $\pi_{i,e} > 0$ implies $\lambda_i v_i(e) \geq \lambda_j v_j(e)$ for all $i, j \in [n]$ and $e \in E$.

Proof. (i) \implies (ii). If π is fPO but malicious, then reallocating items in a non-malicious way strictly improves the value of some agents without harming the others. Thus, an fPO orientation π must be non-malicious.

We now show that there are no directed cycles $C = (i_1 \rightarrow e_1 \rightarrow i_2 \rightarrow e_2 \rightarrow \dots \rightarrow i_L \rightarrow e_L \rightarrow i_{L+1} = i_1)$ in $\vec{\mathcal{CG}}_\pi$ with $\Pi(C) < 1$. For the sake of contradiction, assume that C is such a cycle. We show how to construct an exchange of items among the agents in C such that their value strictly increases without affecting the other agents. This will contradict the Pareto-optimality of π .

Define $R := \Pi(C)^{\frac{1}{L}}$. As $\Pi(C) < 1$, then $R < 1$ holds. For each $k \in [L]$, there are edges $i_k \rightarrow e_k$ and $e_k \rightarrow i_{k+1}$. Then by the definition of $\vec{\mathcal{CG}}_\pi$,

- either i_k receives a positive amount of e_k and both i_k and i_{k+1} have positive value for e_k ,
- or i_{k+1} has positive amount of e_{k+1} and both i_k and i_{k+1} have negative value for e_k .

Now we describe the reallocation. For each $k \in [L]$, agent i_k give a small positive amount ϵ_k of e_k to i_{k+1} in the case of good or i_{k+1} gives ϵ_k fraction of e_k to i_k in the case of chore where $\epsilon_k \in (0, h_k]$ and $h_k = \pi_{i_k, e_k}$ for a good and $h_k = \pi_{i_{k+1}, e_k}$ for a chore. Then each i_k loses a value of $\epsilon_k \cdot |v_{i_k}(e_k)|$ and gains a value of $\epsilon_{k-1} \cdot |v_{i_k}(e_{k-1})|$, resulting in a net change of $\epsilon_{k-1} \cdot |v_{i_k}(e_{k-1})| - \epsilon_k \cdot |v_{i_k}(e_k)|$ in the value of agent i_k . In order to guarantee that every agent in C strictly gains from the reallocation, it is sufficient to choose $\epsilon_1, \dots, \epsilon_k$ such that the following inequalities hold for all $k \in [L]$:

$$\epsilon_{k-1} \cdot |v_{i_k}(e_{k-1})| - \epsilon_k \cdot |v_{i_k}(e_k)| > 0 \iff \frac{\epsilon_{k-1}}{\epsilon_k} > \frac{|v_{i_k}(e_k)|}{|v_{i_k}(e_{k-1})|}.$$

For any $\epsilon_1 > 0$, define $\epsilon_k = \epsilon_{k-1} \cdot R \cdot \frac{|v_{i_k}(e_{k-1})|}{|v_{i_k}(e_k)|}$ for every $k \in \{2, \dots, L\}$. Since $R < 1$, the above inequality is satisfied for each $k \in \{2, \dots, L\}$. It remains to show

that it is also satisfied for $k = 1$. Note that

$$\begin{aligned} \epsilon_L &= \epsilon_1 R^{L-1} \prod_{k=2}^L \frac{|v_{i_k}(e_{k-1})|}{|v_{i_k}(e_k)|} \\ &= \epsilon_1 R^{L-1} \frac{|v_{i_1}(e_1)|}{|v_{i_1}(e_L)|} \prod_{k=1}^L \frac{|v_{i_k}(e_{k-1})|}{|v_{i_k}(e_k)|} \\ &= \epsilon_1 \frac{R^{L-1}}{\Pi(C)} \frac{|v_{i_1}(e_1)|}{|v_{i_1}(e_L)|} = \epsilon_1 R^{-1} \frac{|v_{i_1}(e_1)|}{|v_{i_1}(e_L)|}, \end{aligned}$$

which implies

$$\frac{\epsilon_1}{\epsilon_L} = R \cdot \frac{|v_{i_1}(e_L)|}{|v_{i_1}(e_1)|} < \frac{|v_{i_1}(e_L)|}{|v_{i_1}(e_1)|},$$

as required. Therefore, we can choose ϵ_1 sufficiently small so that $\epsilon_k \leq h_k$ for all $k \in [L]$ and such a reallocation is feasible.

(ii) \implies (iii).

We assume that $\vec{\mathcal{CG}}_\pi$ contains no directed cycles C with $\Pi(C) < 1$ and π is non-malicious. We prove below the existence of weights λ_i 's satisfying (iii).

Starting from $\vec{\mathcal{CG}}_\pi$, for each pair of distinct agents $i, j \in [n]$, add directed edges $i \rightarrow j$ with weight

$$w_{i \rightarrow j} = \left(\max_{e \in E, k \in N_e, v_k(e) \neq 0} \left\{ 1, |v_k(e)|, \frac{1}{|v_k(e)|} \right\} \right)^{2(n-1)}$$

Note that each new edge has the same weight. Let the resulting new graph be \vec{G} , and we claim that \vec{G} has no cycle C with weight $\pi(C) < 1$. For the sake of contradiction, assume that C be such a cycle in \vec{G} with $\pi(C) < 1$. Then C must contain at least one new edge. Each agent vertex appears once in C , the cycle C contains at most $2n - 2$ old edges. If none of the old edges in C has weight zero, then by the definition of the weight of the new edge, $\pi(C) \geq 1$ holds, a contradiction. Old edges with weight zero are only possible from an agent to an item (suppose from some agent i to some item e), and moreover, $\pi_{i,e} > 0$ and $v_i(e) = 0$. However, as π is non-malicious, such e has no outgoing edges, and thus, edge $i \rightarrow e$ cannot be a part of any cycle.

Fix an arbitrary agent (suppose agent 1). For every other agent $j \in [n]$, let $P_{1,j}$ be a directed path from 1 to j in \vec{G} , for which the product $\Pi(P_{1,j})$ is minimal. Note that the minimum is well-defined and is attained on an acyclic path, as by the construction, there are no cycles with a product smaller than 1.

Define $\lambda_j := \Pi(P_{1,j})$ for all $j \neq 1$ and $\lambda_1 := 1$. We now prove that these weights satisfy (iii), i.e., $\pi_{i,e} > 0$ implies $\lambda_i v_i(e) \geq \lambda_j v_j(e)$ for all $j \in N_e$. Fix i, e with $\pi_{i,e} > 0$ and some j with $j \in N_e$. As π is non-malicious, we can, without loss of generality, assume that both i, j agree whether e is a good or a chore, i.e., $v_i(e) \cdot v_j(e) > 0$; if i, j disagree, then by the non-maliciousness, $\lambda_i v_i(e) \geq \lambda_j v_j(e)$ holds for any $\lambda_i, \lambda_j > 0$.

If e is a good (i.e., $v_i(e) > 0$ and $v_j(e) > 0$), then there is an edge $i \rightarrow e$ (as $\pi_{i,e} > 0$, $v_i(e) > 0$, and

$i \in N_e$) and an edge $e \rightarrow j$ (as $\pi_{j,e} < 1$, $v_j(e) > 0$, and $j \in N_e$). Consider the optimal path $P_{1,i}$ and the concatenated path $Q_{1,j} = P_{1,i} \rightarrow e \rightarrow j$. The path $Q_{1,j}$ has the minimal product among all paths from 1 to j , we have

$$\begin{aligned} \Pi(Q_{1,j}) \geq \Pi(P_{1,j}) &\iff \Pi(P_{1,i}) \cdot \frac{v_i(e)}{v_j(e)} \geq \Pi(P_{1,j}) \\ &\iff \lambda_i v_i(e) \geq \lambda_j v_j(e). \end{aligned}$$

If e is a chore (i.e., $v_i(e) < 0$ and $v_j(e) < 0$), then there is an edge $j \rightarrow e$ (as $v_j(e) < 0$, $\pi_{j,e} < 1$, and $j \in N_e$) and an edge $e \rightarrow i$ (as $\pi_{i,e} > 0$, $v_i(e) < 0$, and $i \in N_e$). Define $Q_{1,i}$ as $P_{1,j} \rightarrow e \rightarrow i$ and get

$$\begin{aligned} \Pi(Q_{1,i}) \geq \Pi(P_{1,i}) &\iff \Pi(P_{1,j}) \cdot \frac{|v_j(e)|}{|v_i(e)|} \geq \Pi(P_{1,i}) \\ &\iff \lambda_j |v_j(e)| \geq \lambda_i |v_i(e)| \\ &\iff \lambda_i v_i(e) \geq \lambda_j v_j(e). \end{aligned}$$

(iii) \implies (i).

As in π , each item e is allocated to the agent i with the highest $\lambda_i v_i(e)$ among all agents in N_e , then π maximizes $\sum_{e \in E} \sum_{i \in N_e} \lambda_i v_i(e)$ over all (fractional) orientations. Since λ_i 's are positive, π is fPO because any Pareto-improvement must increase the weighted sum. ■

We are now ready to prove Lemma 1.

Proof. [Proof of Lemma 1] If π is malicious, implement the following reallocation:

- for each $e \in E$ with $\max_{i \in N_e} v_i(e) > 0$, reallocate the share of agents with $v_j(e) \leq 0$ to an agent $i \in N_e$ with $v_i(e) > 0$;
- for each $e \in E$ with $\max_{i \in N_e} v_i(e) = 0$, reallocate the share of agents with $v_j(e) < 0$ to an agent i with $v_i(e) = 0$.

Let the resulting non-malicious orientation be π' .

We now describe reallocation items that eliminates the cycle (if any). Let us call a cycle $C = (i_1 \rightarrow e_1 \rightarrow i_2 \rightarrow e_2 \rightarrow \dots \rightarrow i_L \rightarrow e_L \rightarrow i_{L+1} = i_1)$ in the directed graph $\vec{\mathcal{CG}}_{\pi'}$ simple if each node is visited at most once and for any $i \in [n]$ and $e \in E_i$, only one of edges $i \rightarrow e$ or $e \rightarrow i$ is contained in the cycle.

We claim that if there is a simple cycle C in $\vec{\mathcal{CG}}_{\pi'}$ with $\Pi(C) \leq 1$, then C can be eliminated by reallocation of items. The idea of eliminating the cycle is similar to the reallocation in the proof of Lemma 2. As edges $i_k \rightarrow e_k$ and $e_k \rightarrow i_{k+1}$ exist in $\vec{\mathcal{CG}}_{\pi'}$, the values $v_{i_k}(e_k)$ and $v_{i_{k+1}}(e_k)$ are both non-zero and have the same sign due to the construction of $\vec{\mathcal{CG}}_{\pi'}$. We implement the following reallocation of items:

- if $v_{i_k}(e_k) > 0$ and $v_{i_{k+1}}(e_k) > 0$, then take ϵ_k amount of e_k from i_k and give it to i_{k+1} , where $0 < \epsilon \leq h_k$ with $h_k = \pi'_{i_k, e_k}$;

- if $v_{i_k}(e_k) < 0$ and $v_{i_{k+1}}(e_k) < 0$, then transfer ϵ_k of e_k from i_{k+1} to i_k where $0 < \epsilon \leq h_k$ with $h_k = \pi'_{i_{k+1}, e_k}$.

Then amounts ϵ_k 's are selected in a way such that $\epsilon_k |v_{i_k}(e_k)| = \epsilon_{k+1} |v_{i_{k+1}}(e_k)|$ for every $k \in [L-1]$. Thus for each $k = 2, \dots, L$, the value of agent i_k remains indifferent after the reallocation, while agent i_1 is weakly better off because the condition of $\Pi(C) \leq 1$. Note that after reallocating items, the resulting allocation is still an orientation. It is not hard to verify that we can select ϵ_k 's as large as possible so that one of edges $i_k \rightarrow e_k$ in $\vec{\mathcal{CG}}_{\pi'}$ can be removed.

Repeat this reallocation until there are no simple cycles with $\Pi(C) \leq 1$. As at least one edge is removed each time in the undirected graph of the underlying orientation and there are at most mn edges, we need to most $(n-1)m$ repetitions for achieving the orientation where no simple cycle has product at most 1. Let the resulting orientation be π^* .

By the construction, π^* weakly improves the value of each agent in π ; is non-malicious; has no cycle C in $\vec{\mathcal{CG}}_{\pi^*}$ with $\Pi(C) < 1$. By Lemma 2, π^* is fPO.

We now prove that \mathcal{CG}_{π^*} is acyclic. For a contradiction, assume that there is a cycle C in \mathcal{CG}_{π^*} . Then in the directed graph $\vec{\mathcal{CG}}_{\pi^*}$, there are two cycles: C passed in one direction and in the opposite direction. Let them be \vec{C} and \overleftarrow{C} . As $\Pi(\vec{C}) \cdot \Pi(\overleftarrow{C}) = 1$, one of them has the product of at most 1, and indeed, by fPO it must hold that $\Pi(\vec{C}) = \Pi(\overleftarrow{C}) = 1$. However, all such cycles were eliminated in the previous stages.

For the running time of the algorithm, constructing the non-malicious orientation, finding the cycles with $\Pi(C) \leq 1$, and resolving/eliminating the cycle takes time polynomial in m and n . As cycle-elimination repeats at most $(n-1)m$ times, the total running time is polynomial in n and m . ■

We are now ready to prove Theorem 3.

Proof. [Proof of Theorem 3] Let π be the orientation where $\pi_{i,e} = \frac{1}{n_e}$ for all $i \in [n]$ and all $e \in E_i$. One can verify that in π , each agent i receives exactly her proportional share. Based on Lemma 1, we find another orientation π^* where every agent is weakly better off, and hence, each agent i receives at least her proportional share. Moreover, π^* is fPO and the undirected consumption graph \mathcal{CG}_{π^*} is acyclic.

We round π^* to an integral orientation that is fPO and PROP1. Consider an undirected shared graph \mathcal{SG}_{π^*} defined as follows: create a vertex for each agent, and there is an edge between vertices i and j if and only if there exists e such that $\pi_{i,e}^*, \pi_{j,e}^* > 0$. In other words, the existence of an edge between i and j in \mathcal{SG}_{π^*} means agents i and j share an item in π^* . Moreover, as π^* is fPO, each shared item must result in the value with the same sign (positive, negative, or zero) for both its endpoints; otherwise, we can increase the value of an agent without harming others, contradicting fPO.

As \mathcal{CG}_{π^*} is acyclic, it is not hard to verify that \mathcal{SG}_{π^*} is also acyclic, and hence, \mathcal{SG}_{π^*} is a forest. For each component of \mathcal{SG}_{π^*} , we form it into a rooted tree. Then starting from the leaves to the root, we visit every vertex. For each vertex i , we let agent i receive fully the item with non-negative value shared with the agent having a higher depth than that of agent i , and let agent i receive fully the item with negative value shared with the agent having lower depth than that of agent i .

Let π' be the resulting integral orientation. We claim that π' is PROP1, as compared to π^* , the value of each agent i for non-negative item weakly increases and there exists at most one item with negative value that is partially allocated to i in π^* but is fully allocated to i in π' . After removing such a negative-valued item, agent i has value at least her proportional share, and therefore, π' is PROP1.

Finally, we prove that π' is fPO. Varian (Varian 1976) proved that an allocation π is fPO if and only if there exist strictly positive weights $\{\lambda_i\}_{i \in [n]}$ of agents such that π maximizes weighted welfare $\sum_{i \in [n]} \lambda_i v_i(\pi_i)$. We show that this characterization holds for the general orientation model and the mixed-instance in the appendix. Since orientation π^* is fPO, π^* maximizes weighted welfare $\sum_{i \in [n]} \lambda_i^* v_i(\pi_i^*)$ for some strictly positive weight $\{\lambda_i^*\}_{i \in [n]}$ of agents. Hence in π^* , each item is always allocated to the agent with the highest weighted value with respect to $\{\lambda_i^*\}_{i \in [n]}$. After rounding π^* to π' , it is still the case that every item is allocated to the agent with the highest weighted value, and thus, π' maximizes the weighted welfare for the weights $\{\lambda_i^*\}_{i \in [n]}$ and is fPO. ■

A.4 Continued proof of Theorem 4 for Goods-Instance

We now show that there exists a truth assignment satisfying all clauses if and only if there exists a PROPX orientation.

Suppose that there exists a truth assignment satisfying all clauses. If x_i is set to be True, we allocate (i, \bar{i}) to i . Then, we allocate \bar{i} all edges, currently unallocated, incident to her. Moreover, assign the two unallocated edges incident to i to the vertices corresponding to $C(x_i^1)$ and $C(x_i^2)$. Similarly, if \bar{x}_i is set to be True, we orient these edges in the reverse direction. Then agents i and \bar{i} satisfy PROPX.

For each vertex c_j and its dummy vertices, allocate (c_j, d_j^1) to d_j^1 and allocate (c_j, d_j^4) to c_j . One can allocate the edge with both endpoints being dummy vertices in a way such that each d_j^r satisfies PROPX. At this point, c_j should receive at least one more edge to achieve PROPX. Note that the truth assignment satisfying clause C_j , and thus, the edge connecting c_j to the vertex corresponding the true literal in C_j is allocated to c_j . Therefore, the created orientation is PROPX.

Next, for the reverse direction, suppose that there exists a PROPX orientation π . We now create a truth assignment as follows: if (i, \bar{i}) is allocated to vertex i , we

set x_i to True; otherwise we set \bar{x}_i to True. Such a truth assignment ensures that exactly one of x_i and \bar{x}_i is set to True, and hence, the truth assignment is valid. For a contradiction, we suppose that there exists a clause C_j that is not satisfied. Then since we have proved that (c_j, d_j^1) must be allocated to d_j^1 , vertex c_j has value at most 1 in π , as C_j is not satisfied. Accordingly, c_j does not satisfy PROPX, deriving the desired contradiction.

A.5 Proof of Theorem 4 for Chores-Instance

We now prove Theorem 4 for the case of chores. Create the graph identical to that for the goods-instance. For agents' valuations, let edge (c_j, d_j^1) result in value -1 for d_j^1 and value zero for c_j for all j . For each of the other edges, if their value for a vertex is one in the goods-instance, change it to -1 ; if their value for a vertex is zero in the goods-instance, it remains the same.

We first claim that in a PROPX orientation (if it exists), for each c_j , edge (c_j, d_j^1) must be allocated to c_j . Assume for the contradiction that this is not the case. We now focus on agents d_j^1, d_j^2, d_j^3 . Without loss of generality, assume edge (d_j^2, d_j^3) is allocated to d_j^2 in the orientation. Then in order to make d_j^2 satisfy PROPX, we need to allocated (d_j^2, d_j^1) to d_j^1 , which means that d_j^1 cannot receive (c_j, d_j^1) . Then in a PROPX orientation, the value of c_j must be at most -2 as her proportional share is -2 and she always receives an edge with value zero. We prove below that there exists a truth assignment satisfying all clauses if and only if there exists a PROPX orientation.

Suppose that there exists a truth assignment satisfying all clauses. If x_i is set to True, we allocate (i, \bar{i}) to \bar{i} . Then we allocate i the two edges with value zero for her and allocate the two unallocated edges incident to \bar{i} to the vertices corresponding to $C(\bar{x}_i^1)$ and $C(\bar{x}_i^2)$. Similarly, if \bar{x}_i is set True, we orient these edges in the reverse direction. Then at this point, both agents i and \bar{i} satisfy PROPX.

For each vertex c_j and its dummy vertices, allocate (c_j, d_j^1) to c_j and allocate (c_j, d_j^4) to d_j^4 . One can allocate the edges with both endpoints being dummy vertices in a way such that each d_j^r satisfies PROPX. Then all edges are allocated and c_j has value at least -2 as the edge connecting c_j to the vertex corresponding to the true literal in C_j is not allocated to c_j . Therefore, the created orientation is PROPX.

Next for the reverse direction, suppose that there exists a PROPX orientation π . We now create a truth assignment as follows: if (i, \bar{i}) is allocated to i , set \bar{x}_i to True; otherwise, set x_i to True. Such a truth assignment ensures that exactly one of x_i and \bar{x}_i is set to True, and hence, the truth assignment is valid. For a contradiction, suppose that there exists a clause C_j that is not satisfied. Then c_j has value at most -3 as each edge connecting c_j to the variable vertices with literals in C_j must be allocated to c_j . As edge (c_j, d_j^1) is allocated to c_j , vertex c_j violates PROPX, a contradiction.

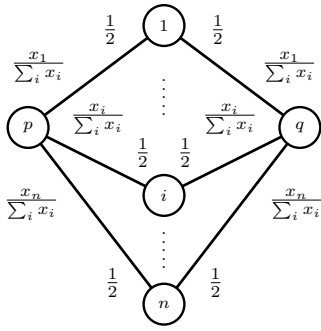


Figure 7: The illustration of the goods-instance for the reduction from EQ. The label closer to a vertex represents that vertex’s value for the edge.

B Missing Materials in Section 4

We derive reductions from the Partition problem: given a set $\{x_1, \dots, x_n\}$ of n integers whose sum is $2T$, can $[n]$ be partitioned into two sets I_1 and I_2 such that $\sum_{j \in I_1} x_j = \sum_{j \in I_2} x_j = T$?

B.1 Proof of Theorem 5

The decision problem is in NP as given an orientation, one can decide whether it is EQ in polynomial time. We derive the reduction from the Partition problem and begin with the goods-instance. We create a simple graph with $n + 2$ vertices $\{1, \dots, n, p, q\}$ and $2n$ edges. The created graph and the valuations of agents are illustrated in Figure 7. One can verify that the instance is normalized as the total value of items for each agent is equal to one.

We claim that in an EQ orientation, each vertex i with $i \in [n]$ must receive exactly one incident edge. If some vertex $i' \in [n]$ receives two incident edges, the value of agent i' is one, but the value of p is less than 1, violating EQ. If some vertex $i' \in [n]$ receives no edge, then the value of agent i' is zero, but the value of p is positive, violating EQ. Thus in an EQ orientation, the value of each agent must be $\frac{1}{2}$. Then the set of items received by p and q in an EQ orientation map a solution of the Partition problem. Therefore, an EQ orientation exists if and only if the answer to the Partition instance is a yes-instance.

For the reduction of the chores-instance, we create the same graph but negate agents' valuations. By similar arguments, we can prove that in an EQ orientation, each vertex $i \in [n]$ must receive exactly one incident edge. Therefore, an EQ orientation exists if and only if the answer to the Partition instance is a yes-instance.

B.2 Proof of Theorem 6

The decision problem is in NP as given an orientation, one can decide whether it is EQ1 in polynomial time. We derive the reduction from the Partition problem and begin with the goods-instance.

We create a goods-instance of a simple graph, as illustrated in Figure 8:

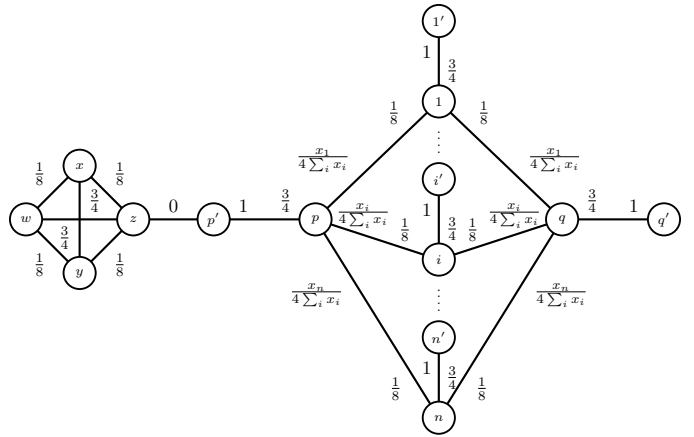


Figure 8: Illustration of the goods-instance for reduction from EQ1. For the edge with one label, the label is the value of that edge for both endpoints. If an edge has two labels, the label closer to a vertex represents that vertex’s value for the edge.

- create vertices $1, \dots, n$ and vertices $1', \dots, n'$, and for each $i \in [n]$, create edge (i, i') ;
- create vertices p, p', q, q' , and create edges (p, p') and (q, q') . Moreover, for each $i \in [n]$, create edges (p, i) and (q, i) ;
- create vertices w, x, y, z and edges such that these four vertices form K_4 (i.e., a complete graph with 4 vertices). Moreover, create edge (z, p') .

We define the agents' valuations as follows:

- for each agent $i \in [n]$, $v_i((i, i')) = \frac{3}{4}$, $v_{i'}((i, i')) = 1$, $v_i((p, i)) = v_i((q, i)) = \frac{1}{8}$, and $v_p((p, i)) = v_q((q, i)) = \frac{x_i}{4 \sum_i x_i}$;
- $v_p((p, p')) = v_q((q, q')) = \frac{3}{4}$, $v_{p'}((p, p')) = v_{q'}((q, q')) = 1$, and $v_{p'}((z, p')) = 0$;
- $v_w((w, z)) = v_z((w, z)) = v_x((x, y)) = v_y((x, y)) = \frac{3}{4}$, and $v_a((a, b)) = v_b((a, b)) = \frac{1}{8}$ for every pairs of vertices $(a, b) \in \{(w, x), (x, z), (z, y), (y, w)\}$.

We first claim that in an EQ1 orientation π , each agent has a value at least $\frac{1}{8}$. Let us focus on w, x, y, z , and in any orientation (and hence in π), there must be an agent receive two edges, with one having value $\frac{1}{8}$ and the other one having value $\frac{3}{4}$. Thus, after removing the edge with value $\frac{3}{4}$, that agent still has value $\frac{1}{8}$, which makes that in EQ1 orientation π , each agent should receive value at least $\frac{1}{8}$. Then edges (p', p) and (q', q) must be allocated to p' and q' respectively, and for each $i \in [n]$, edge (i', i) should be allocated to i' . Moreover, for each $i \in [n]$, vertex i should receive at least one (indeed exactly one) of (i, p) and (i, q) . Then the total value of edges can be allocated to p and q is $\frac{1}{4}$, which

makes in π , the value of p and q should be $\frac{1}{8}$. Thus, there exists a subset of $\{x_1, \dots, x_n\}$ with total value T . Therefore, there exists an EQ1 orientation if and only if the Partition instance is a yes-instance.

As for the chores-instance, we consider the same graph creation but negate agents' valuations. Similarly, in any orientation, there must be an agent among w, x, y, z receiving at least one edge with value $-\frac{1}{8}$ and one edge with value $-\frac{3}{4}$. Thus in an EQ1 orientation π , every agent should receive value at most $-\frac{1}{8}$. Then edges (p', p) and (q', q) must be allocated to p' and q' respectively. Moreover, for each $i \in [n]$, edge (i', i) should be allocated to i' . Then one can verify that the unallocated edges can make both of p, q have value no greater than $-\frac{1}{8}$ if and only if the Partition instance is a yes-instance. Therefore, we establish an equivalence between the existence of EQ1 orientation and a yes-instance of the Partition problem.

B.3 Continued proof of Theorem 7 for Goods-Instance

Suppose that the Partition instance is a yes-instance and I_1 and I_2 are a solution. For each $i \in [n]$, if $i \in I_1$, allocate (i, p) to p and if $i \in I_2$, allocate (i, q) to q . Next for each $i \in [n]$, allocate i the other incident edge with value $\frac{1}{2} - \epsilon$ for her. For each $j \in [n] \cup \{p, q\}$, allocate (k_j, j) to j , (k'_j, j) to k'_j , and (k'_j, k_j) to k_j . At this point, all edges are allocated, and the orientation is EQX, as I_1 and I_2 are a solution to the Partition instance.

For the reverse direction, suppose that there exists an EQX orientation π . Let $S_p := \{i \in [n] \mid (i, p) \in \pi_p\}$ and $S_q := \{i \in [n] \mid (i, q) \in \pi_q\}$. We prove that S_p and S_q must be a solution to the Partition instance. First, as each i receives exactly one from edges (i, p) and (i, q) , it holds that $S_p \cup S_q = [n]$. Assume for the contradiction that S_p and S_q are not a solution, and then, assume $\sum_{i \in S_p} x_i < \sum_{i \in S_q} x_i$. Moreover, as x_i 's are integers, we have $\sum_{i \in S_p} x_i \leq T - 1$, and thus, $v_p(\pi_p) \leq \frac{T-1}{2T}(1-2\epsilon) + \epsilon = \frac{1}{2} + \frac{\epsilon}{T} - \frac{1}{2T} < \frac{1}{2} - \epsilon$, where the last inequality transition is due to that $\epsilon \ll \frac{1}{T}$. For any $i \in [n]$, as π_i contains an edge with value ϵ and an edge with value $\frac{1}{2} - \epsilon$, agent p violates EQX when compared to i , contradicting that π is an EQX orientation.

B.4 Proof of Theorem 7 for Chores-Instance

As for the chores-instance, we consider the same graph creation but negate agents' valuations. We claim that in an EQX orientation π , each $j \in [n] \cup \{p, q\}$ must receive exactly one of edges (j, k_j) and (j, k'_j) . If j receives both of (j, k_j) and (j, k'_j) , then one of k_j and k'_j receives no edges in π (let k_j be such a vertex), and j violates EQX when compared to k_j . If j receives neither (j, k_j) nor (j, k'_j) , then EQX is violated when comparing k_j and k'_j . Based on the claim, we further show that in an EQX orientation π , each $i \in [n]$ should receive exactly one of edges (p, i) and (q, i) ; otherwise, i violates EQX when

compared to the vertex with larger value between k_i and k'_i . Then by the argument similar to that of goods, one can verify that there exists an EQX orientation in the created instance if and only if the Partition instance is a yes-instance.

C EF1 Orientations for Chores

C.1 Proof of Theorem 8

When verifying EF1, agent i compares the value of her bundle with her value for the bundles of other agents. For item $e \notin E_i$, v_i is defined to be 0 in (Christodoulou et al. 2023; Zhou et al. 2024). When considering EF1, we follow this definition. Moreover, we say an edge is objectively negative if the edge results in negative values for both their endpoints. We first present a necessary and sufficient condition for an instance with simple graphs to admit EF1 orientations.

Proposition 3 In a chores-instance, there is an EF1 orientation on a simple graph if and only if the number of objectively negative edges is no greater than the number of vertices in the graph.

Proof. We begin with a claim that if there exists an EF1 orientation π , then each agent should receive at most one objectively negative edge. Suppose not, and assume that i receives two objectively negative edges (i, j) and (i, k) in π . Then i violates EF1 when compared to j , as after removing any edge in π , the value of i is negative but i values π_j at zero (as (i, j) is in π_i , then $\pi_j \cap E_i = \emptyset$); recall that i values e at zero for all $e \notin E_i$. Thus based on the claim, if there exists an EF1 orientation, then the number of the objective negative edges is at most the number of vertices.

For the "if" direction, when the number of objectively negative edges is at most the number of vertices, we can compute an EF1 orientation. First, allocate all edges incident to an agent having zero value on it to such an agent. Then, if there are edges remaining unallocated, they must be objectively negative; they will form one or more components. If a component formed by the objectively negative edges contains no cycle, i.e., is a tree, we can allocate every edge downwards to the corresponding child vertex by selecting an arbitrary vertex as the root of the tree. If a component contains a cycle, we can allocate every edge in the cycle to an endpoint in the same direction, and the remaining edges. Repeat the process until all edges are allocated. The procedures terminate in at most m rounds, as in each round, at least one edge is allocated. ■

The above characterization indicates that if, in a simple graph instance, the number of objectively negative edges exceeds the number of vertices, then no EF1 orientation exists. Such an instance clearly exists, demonstrating that EF1 orientations do not always exist for chores. Moreover, the characterization directly leads to a polynomial time algorithm for deciding the existence

of EF1 orientation for simple graphs and computing one when it exists.

C.2 Proof of Theorem 9

The decision problem is in NP as given an orientation, one can decide whether it is EF1 in polynomial time. We below derive the reduction from the Partition problem. Create a chores-instance with 3 vertices and $n + 4$ edges as follows:

- create vertices 1, 2, 3;
- create n edges e_1, \dots, e_n between 1 and 2. Moreover, create two edges e_{n+1}, e_{n+2} (resp., e_{n+3}, e_{n+4}) between 1 and 3 (resp., between 2 and 3);
- for each $k \in [4]$, the value of e_{n+k} is $-2T - 1$ for both of its endpoints, and for each $i \in [n]$, the value of e_i is $-x_i$ for both of its endpoints.

We claim that in an EF1 orientation π , agent 3 cannot receive both e_{n+1}, e_{n+2} or both e_{n+3}, e_{n+4} . Suppose that 3 receives both e_{n+1}, e_{n+2} , then agent 3 would value 1's bundle at zero and violates EF1. The same reasoning applies to e_{n+3}, e_{n+4} . Similarly, agent 1 (resp., agent 2) cannot receive both e_{n+1}, e_{n+2} (resp., e_{n+3}, e_{n+4}). Therefore, in an EF1 orientation π , agent 1 (resp., agent 2) must receive exactly one of e_{n+1}, e_{n+2} (resp., e_{n+3}, e_{n+4}). Then at this point, 3 satisfies EF1 no matter how the remaining edges are allocated.

For agent 1 and 2, they do not violate EF1 when compared to agent 3, as the total value of e_1, \dots, e_n is greater than $-2T - 1$. When verifying the EF1 condition between agents 1 and 2, edge e_{n+k} for some k would always be hypothetically removed. Therefore, there exists an EF1 orientation if and only if the Partition instance is a yes-instance.