CanAdaptor

- funcsmap_
- handler_vcr
- handler_rcs
- handler_rci
- handler_ds
- handler_vdr
- handler_mtf
- isBigEndian_
- ptr_can_dump_
- ptr_can_send_
- psotmsg_tm_

+ CanAdaptor()
+ ~CanAdaptor()
+ Initialize()
+ Release()
+ Open()
+ RunControlFlag()
+ IsConnected()
+ CheckSocketStatus()
+ StopPostMessage()
+ SetHandler()
and 7 more...
+ getInstance()
- Send()
- Receive()
- CanOpen()
- PrintMapState()
- MakeFramebody()
- PostMessageByType()
- PostMessageByType()
- PostMessageByType()
- PostMessageByType()
- PostMessageByType()
- PostMessageByType()
- PostMessageByType()
- SOpen()
- ROpen()

-instance

-canlib_

DataRelayer

- faultCallback
- rpmCallback
- system_endian_
- magMap_
- channelMap_

+ DataRelayer()
+ ~DataRelayer()
+ ControlSteering()
+ ControlVel()
+ ControlHardware()
+ StopPostMessage()
+ HeartBeat()
+ RegistRpmCallback()
+ RegistFaultCallback()
+ RegistRpmCallback()
+ RegistFaultCallback()
+ Run()
+ SendTest()
- SetmsgMap()
- SendMessageControlSteering()
- SendMessageControlAccelerate()
- SendMessageControlHardware()
- Handler_VCU_EPS_Control
_Request()
- Handler_Remote_Control
_Shake()
- Handler_Remote_Control_IO()
- Handler_DBS_Status()
- Handler_VCU_DBS_Request()
- Handler_MCU_Torque
_Feedback()
- ConvertSpeedUnits()
- is_big_endian()