IMotionColleague

- # m i motion mediator
- + IMotionColleague()
- + fn_recv_value()
- + fn_send_value()

CanMGR

- obj_
- callback_time_
- old_time_
- + fn_can_run()
- + fn_send_control_hardware()
- + fn_send_control_steering()
- + fn send control vel()
- + fn_send_value()
- + fn_recv_value()
- + CanMGR()
- + ~CanMGR()
- fn_can_init()
- faultCallback()
- rpmCallback()

WmMotionController

- m_steer_max_angm tp queue size
- m tp cmdvel
- m tp can chw
- m timer
- m cb group cmd vel
- m cb group can chw
- m sub cmdvel
- m sub can chw
- m_can_manager
- + WmMotionController()
- + ~WmMotionController()
- + fn_send_value()
- + fn_recv_value()
 fn can chw callback()
- fn cmdvel callback()
- fn_mps2kmph()
- fn kmph2mps()