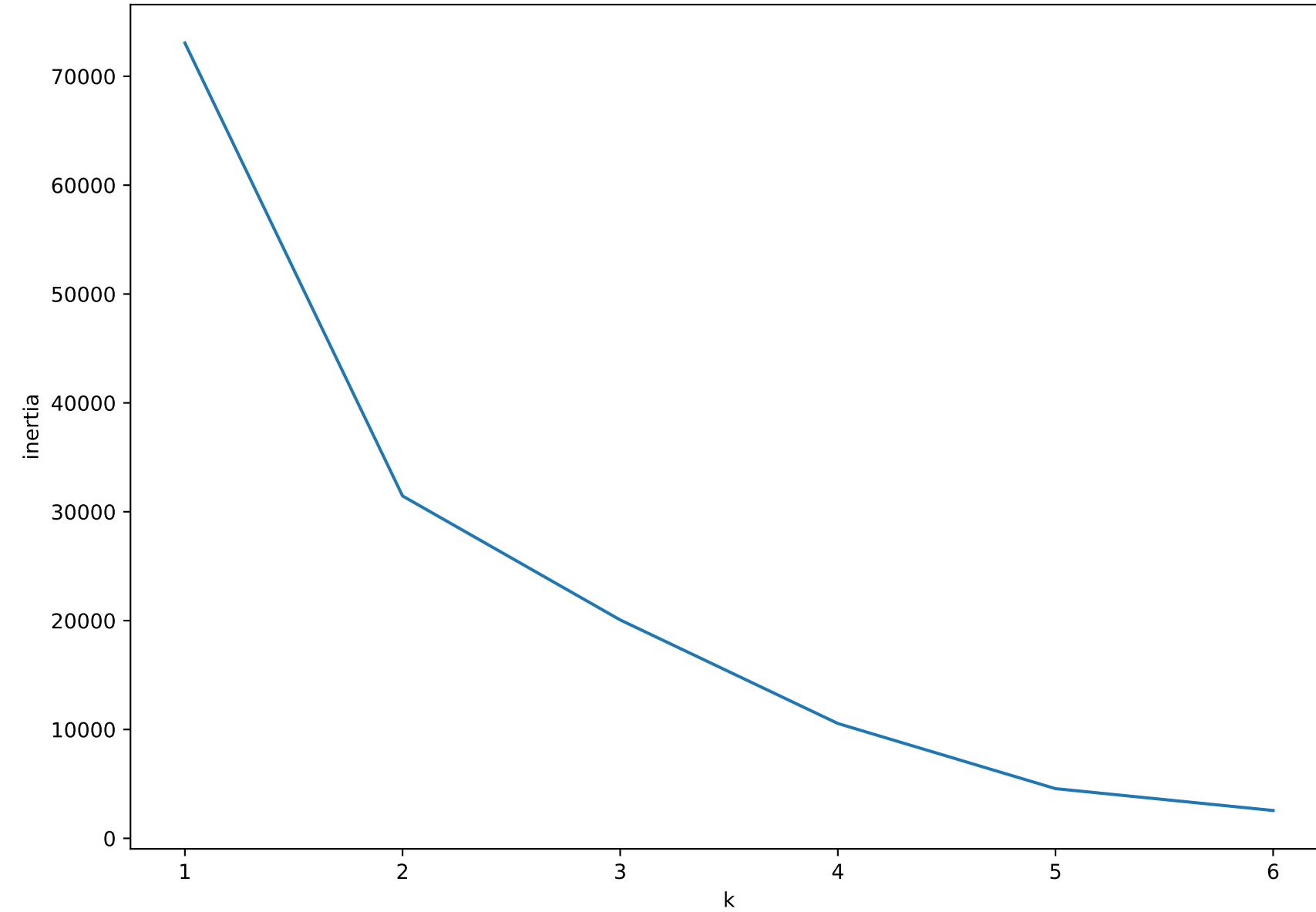


Elbow method for dataset 4b

Elbow method with Kmeans and inertia



Elbow method with Kmedoids and inertia

