

Wrinkling of Liquid-infused Membranes

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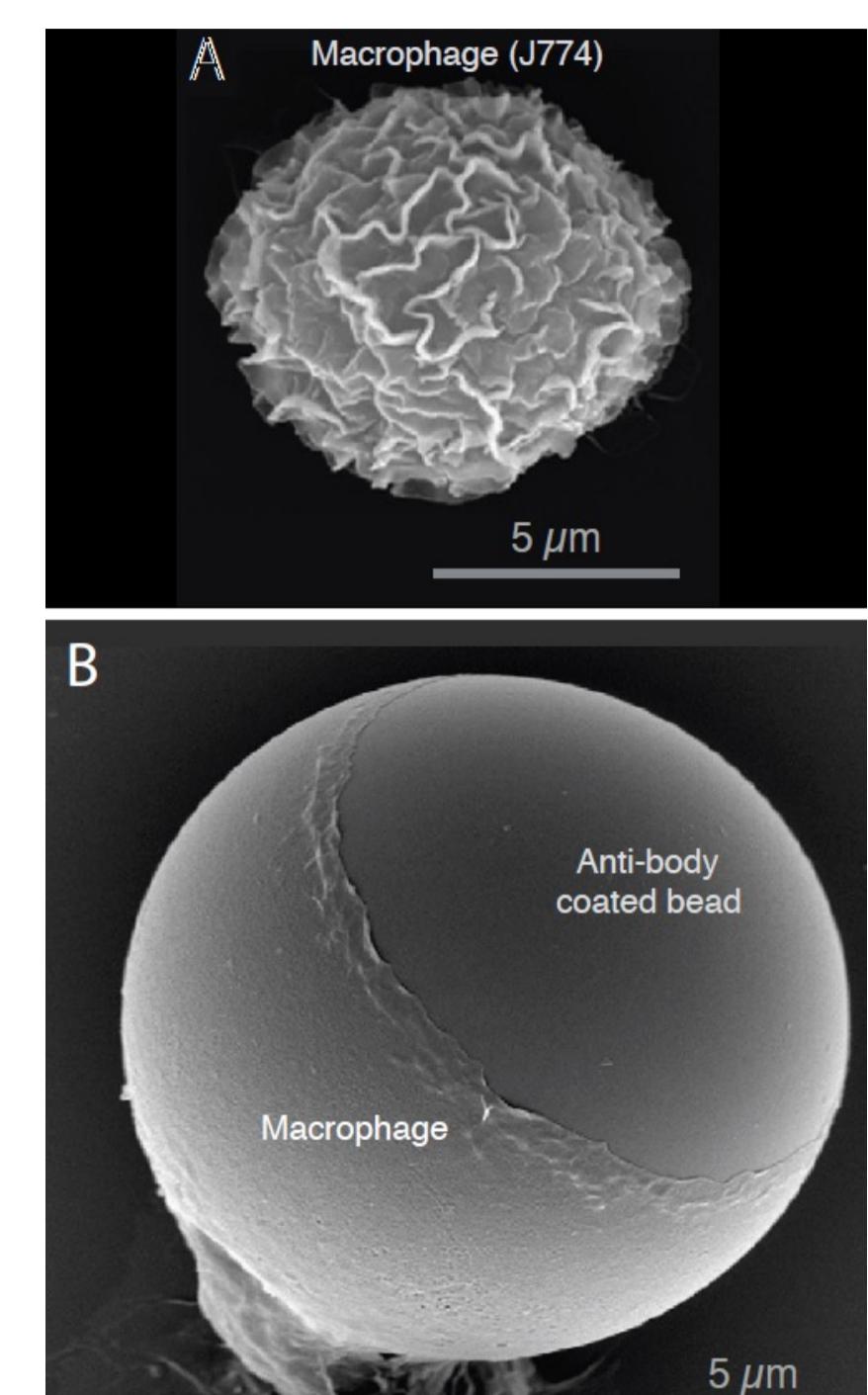
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Context

- Deformation of a synthetic elastic membrane under capillary forces
- Analogy : deformation of biological tissues
- Applications : stretchable electronics, smart textiles, soft biomedical devices...

Key words

- Elastocapillarity
- Thin structures
- Wrinkling
- Surface tension
- Phase transformation



Deformation of a macrophage
Lam et al. Biophys. J (2009)

Experiment

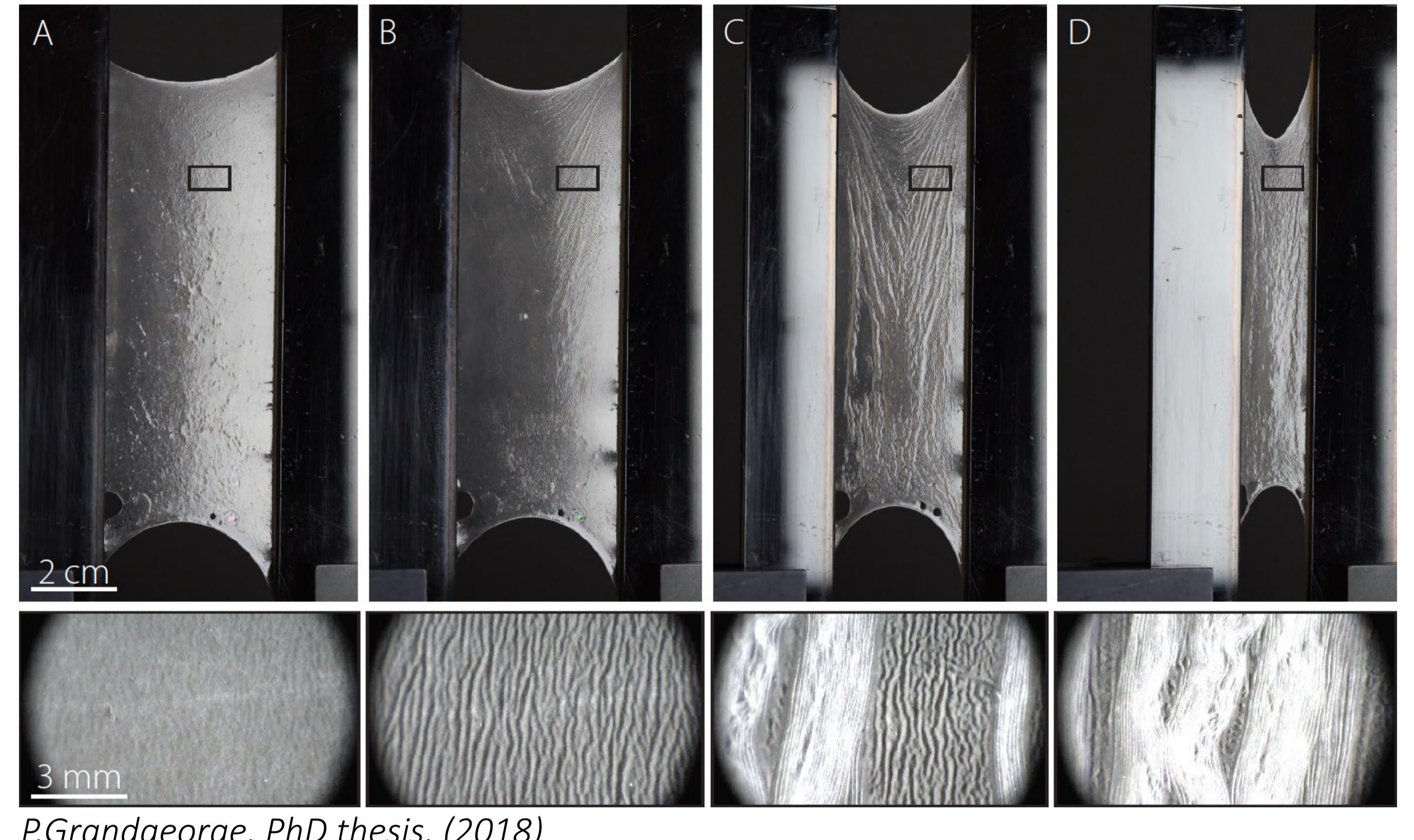
(Top view)

The membrane is clamped at both ends.

Observation :

- Small displacement : homogeneous wrinkles.
- Large displacement : Two zones, the percentage of which changes with the displacement

How do wrinkles form?
Phase transformation?



Basic idea :

Energy minimization

Total energy :

$$\mathcal{E}_{tot} = \mathcal{E}_{elas} + \mathcal{E}_\gamma$$

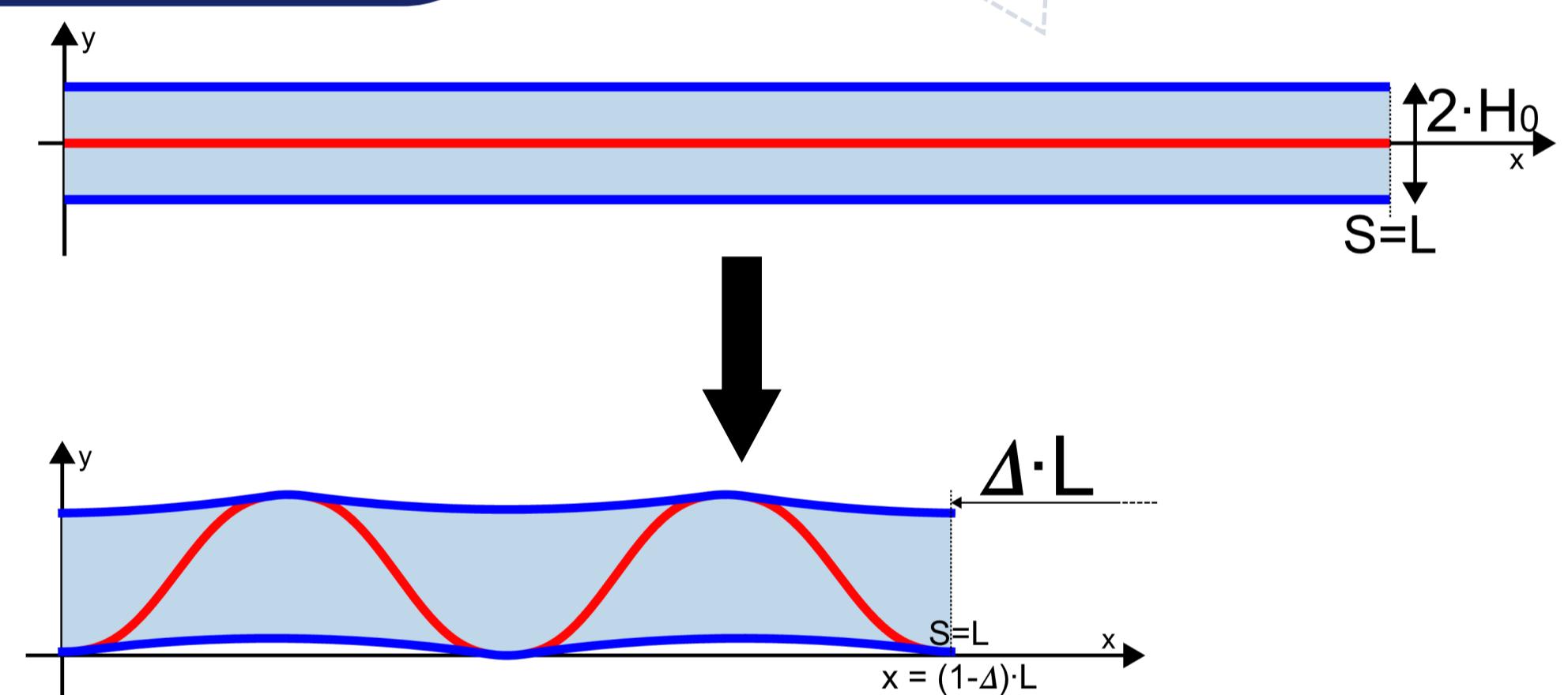
\mathcal{E}_{elas} : Elastic bending energy

\mathcal{E}_γ : Surface energy

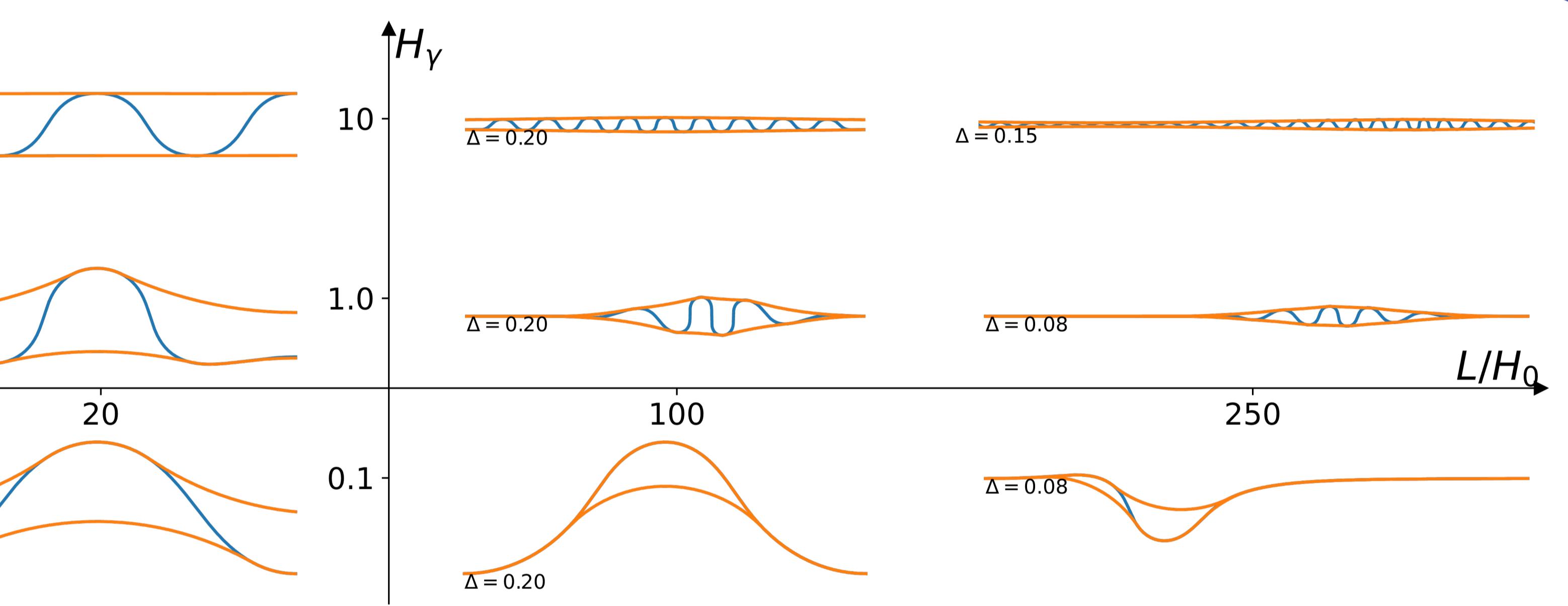
Hypothesis :

- Inextensible membrane
- No interface penetration
- Liquid volume keeps constant

Whole system simulation



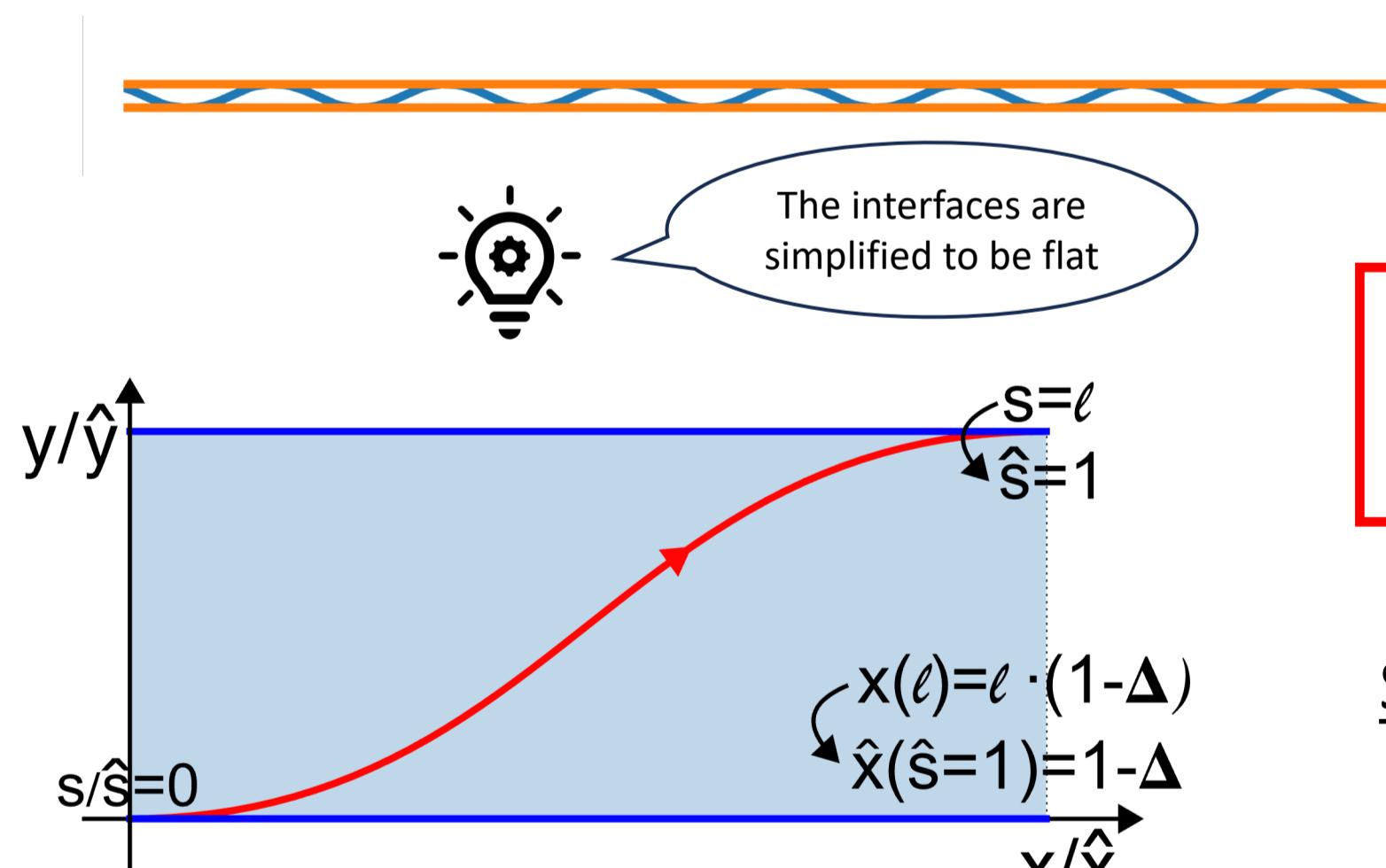
The problem is solved as an optimization problem, discretized and implemented in a python optimizer
CasADI



Parameters :
End shortening : Δ
Initial liquid thickness : H_0
Total length of the membrane : L
Properties :
Bending stiffness : $D = \frac{1}{12}Et^3$
surface tension : γ

Dimensional analysis :
Elasto-capillary length $\sqrt{\frac{D}{\gamma}}$
Magnitude of capillary effects $H_\gamma = \sqrt{\frac{\gamma}{D}}H_0$
Membrane length vs. liquid volume L/H_0

Cell model



Unknown & Variables :

$$l, \theta(s), x(s), y(s)$$

Self-similar variables :

$$\hat{s} = \frac{s}{l}, \hat{x} = \frac{x}{l}, \hat{y} = \frac{y}{l},$$

$$\hat{n}_x = \frac{n_x}{l^2}, \hat{n}_y = \frac{n_y}{l^2}$$

Self-similar system :

$$\hat{\theta}'(\hat{s}) = \kappa(\hat{s})$$

$$\hat{x}'(\hat{s}) = \cos \hat{\theta}(\hat{s})$$

$$\hat{y}'(\hat{s}) = \sin \hat{\theta}(\hat{s})$$

$$\hat{\theta}''(\hat{s}) = \hat{n}_x \sin \hat{\theta}(\hat{s}) - \hat{n}_y \cos \hat{\theta}(\hat{s})$$

$$\frac{1}{2} \hat{\theta}'^2(1) + \hat{n}_x \cdot \Delta = \frac{\hat{n}_y}{2} \hat{y}(1)$$

Solution of self-similar system :

$$\text{Cell energy : } \hat{E} = \int_0^1 \frac{1}{2} \hat{\theta}'^2(\hat{s}) d\hat{s},$$

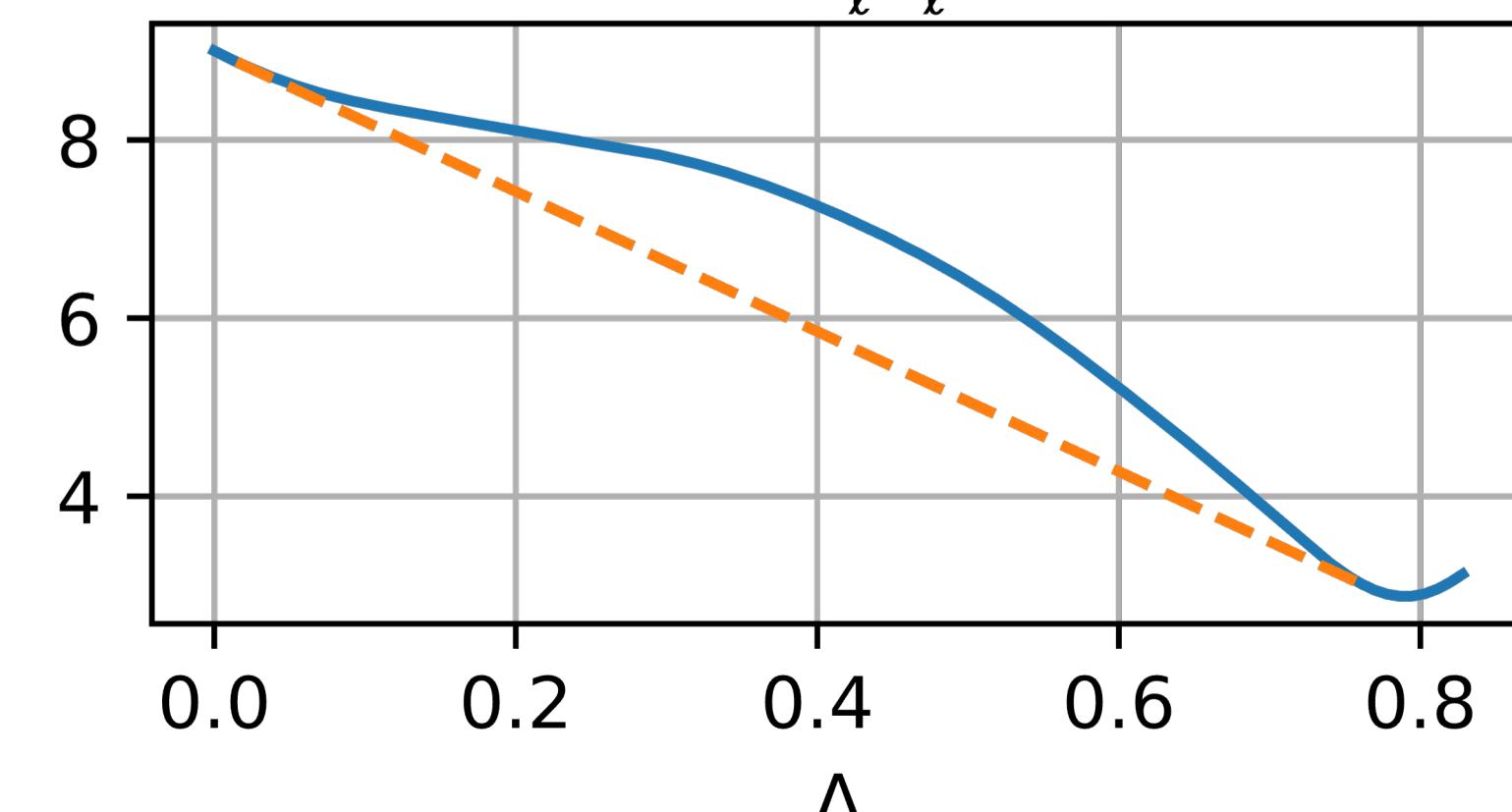
$$\text{Cell height : } \hat{y}_{end} = \hat{y}(1) = \frac{2H_0}{(1-\Delta)l}$$

which are functions of Δ

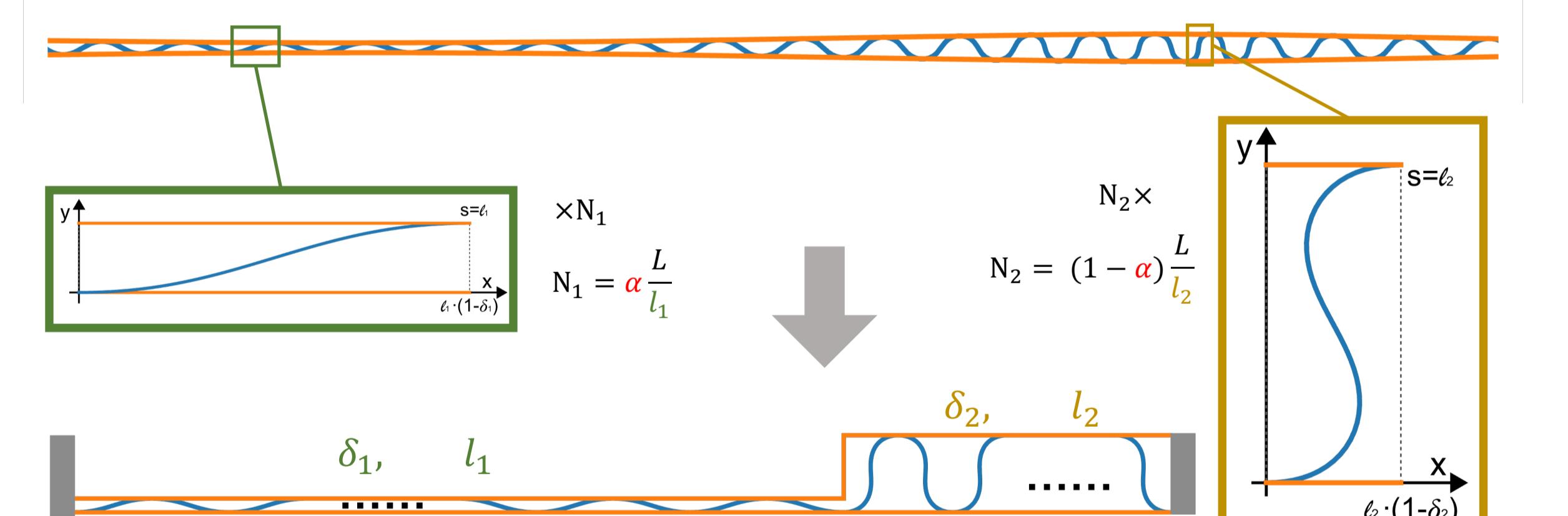
Finding the variable length l :

$$l = \frac{2H_0}{(1-\Delta) \cdot \hat{y}_{end}(\Delta)}$$

$$\text{Total Energy : } \frac{L}{l} \hat{E} + 2L(1-\Delta)$$



Two phases cell model



Energy :

$$\mathcal{E}_{tot} = N_1 E_1 + N_2 E_2 + 2L(1-\Delta)$$

Objective :

$$\min_{(\alpha, l_i, \delta_i)} \alpha \frac{L}{l_1} \frac{\hat{E}(\delta_1)}{l_1} + (1-\alpha) \frac{L}{l_2} \frac{\hat{E}(\delta_2)}{l_2}$$

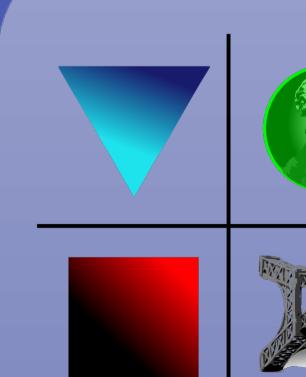
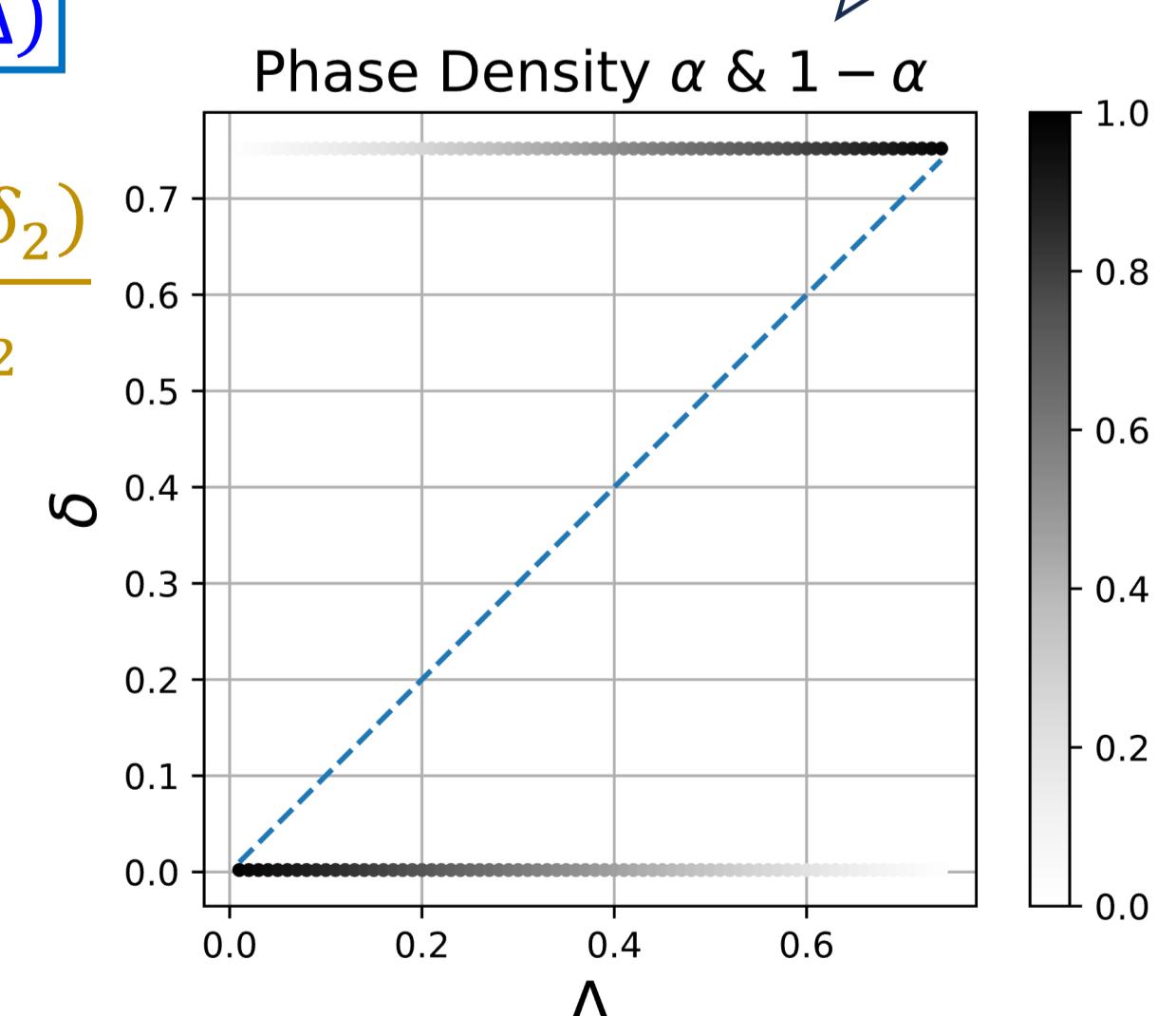
Constraints :

$$\text{Displacement control : } \alpha \delta_1 + (1-\alpha) \delta_2 = \Delta$$

Fixed volume :

$$\alpha h_1 + (1-\alpha) h_2 = H_0$$

$$h_i = l_i \cdot \hat{y}_{end}(\delta_i)(1-\delta_i)$$



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