

1. Conversion to 1st order.

2. Bordenlines 边界线

3. Qualitative 定性.

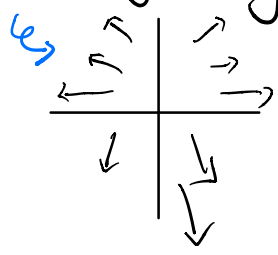
1. Conversion to 1st order

2)

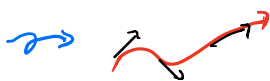
⊙ non-linear

⊙ autonomous

$$\begin{cases} \frac{dx}{dt} = f(x, y) \\ \frac{dy}{dt} = g(x, y) \end{cases}$$

$$\Rightarrow \vec{F} = f\hat{i} + g\hat{j}$$


Solns: $\begin{cases} x = x(t) \\ y = y(t) \end{cases}$



"trajectory"

⊙ Eliminate t . (消去 t)

$$\frac{dy}{dx} = \frac{g(x, y)}{f(x, y)}$$

⊙ - 阶常微分方程

Picture:



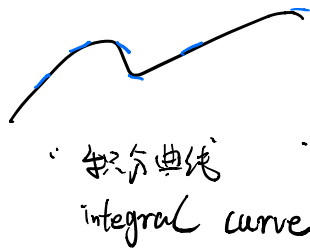
↪ slope field / direction field

① → solns.

$$y = y(x) \quad \text{or} \quad \ln(x, y) = 0.$$

↓

Picture:



↪ 只有斜率, 没有大小方向.

↓
对上式斜
一种 轨迹.

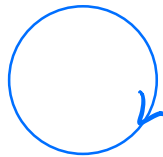
⇓

例 ①

$$\begin{cases} x' = y \\ y' = -x \end{cases}$$

$$\text{soln: } \begin{pmatrix} x \\ y \end{pmatrix} = C_1 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + C_2 \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

"trajectory" ↪



② → 1/4 t.

$$\frac{dy}{dx} = -\frac{x}{y} \quad \rightsquigarrow \quad y dy = -x dx$$

$$\Rightarrow x^2 + y^2 = C \quad \Rightarrow \quad \text{circle}$$

例② predator-prey equation.
捕食者 - 猎物.

$$\begin{array}{l} \text{predator} \\ \text{prey} \end{array} \quad \begin{cases} x' = -ax + bxy \\ y' = cy - dxy \end{cases} \quad a, b, c, d > 0.$$

解 \Rightarrow 找 crit pts.

$$x(-a + by) = 0$$

$$y(c - dx) = 0$$

$$\begin{cases} x=0 \\ y=0 \end{cases}, \quad \begin{cases} x = \frac{c}{d} \\ y = \frac{a}{b} \end{cases} \quad \text{eq } (0,0), \quad (\frac{c}{d}, \frac{a}{b})$$

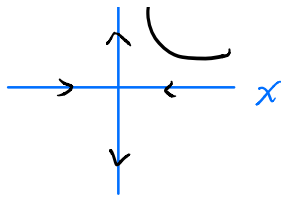
② 在 $(0,0)$ 处线性化.

$$\begin{cases} x' = -ax \\ y' = cy \end{cases}$$

$$\Rightarrow A = \begin{bmatrix} -a & 0 \\ 0 & c \end{bmatrix} \Rightarrow \lambda_1 = -a, \lambda_2 = c$$

y
↑

saddle
鞍部.



②, 设 $a=b=c=d=1$.

$$\begin{cases} x' = -x + xy \\ y' = y - xy \end{cases}$$

$$J = \begin{pmatrix} -1+xy & x \\ -y & 1-x \end{pmatrix}$$

$$J_{(1,1)} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

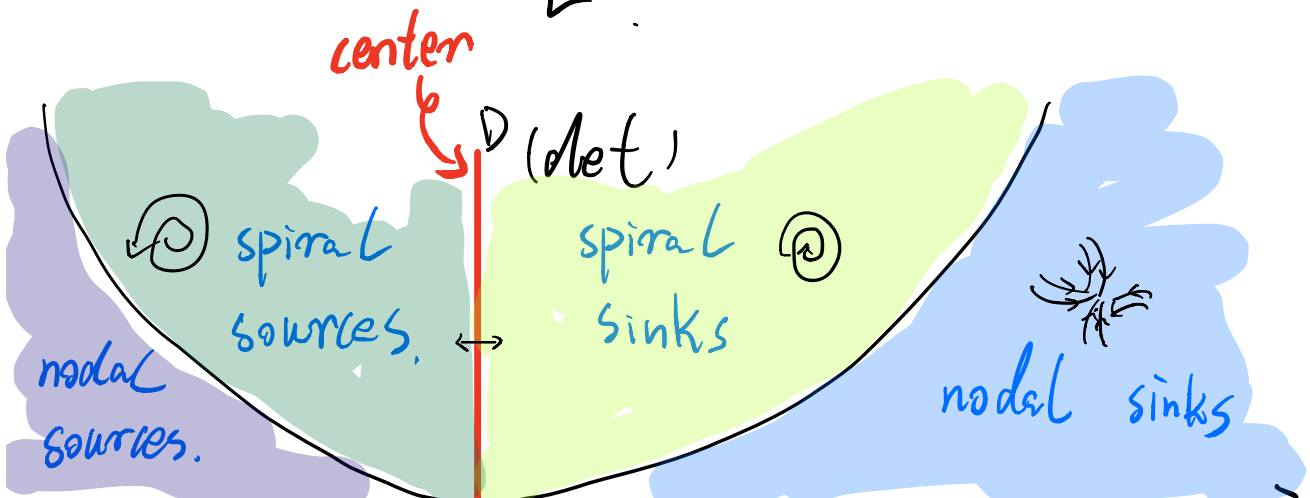
linear system.

$$\begin{cases} x' = y \\ y' = -x \end{cases} \rightarrow \text{center}$$



引出第二个问题, 边界线情形
border line cases

6.57



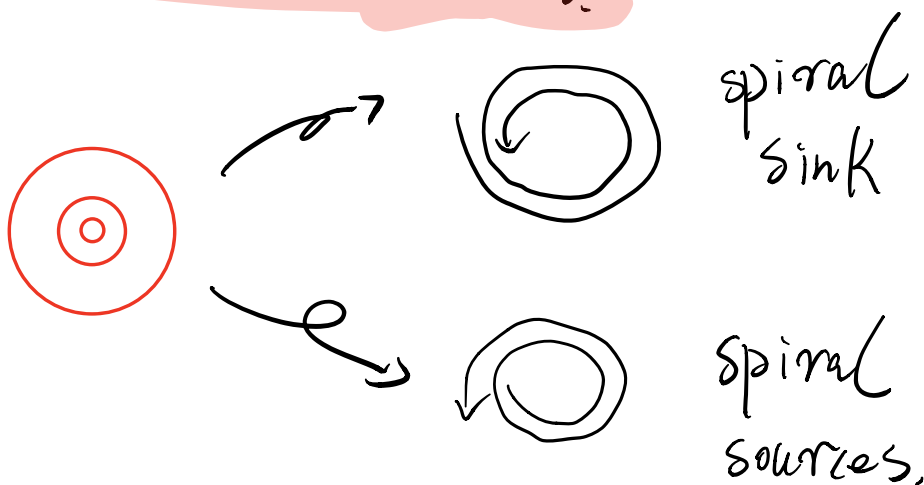
SADDLES

(traj)

$$\lambda^2 - T\lambda + D = 0,$$

↓

在边界线上，一个参数的微小变化可以改变它的变化方式。



即 nonlinear system at (1,1) 可能是
是 center^① , spiral sink^② , spiral sources^③
= 3种之一。

$$\begin{cases} x' = -x + xy \\ y' = y - xy \end{cases}$$

\rightarrow elim t .

$$\frac{dy}{dx} = \frac{y(1-x)}{x(-1+y)}$$

$$\Rightarrow \frac{y-1}{y} dy = \frac{1-x}{x} dx$$

$$\Rightarrow (1 - \frac{1}{y}) dy = (\frac{1}{x} - 1) dx$$

$$\Rightarrow y - \ln y = \ln x - x + C_1$$

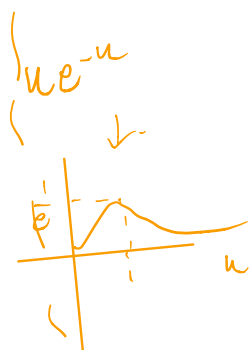
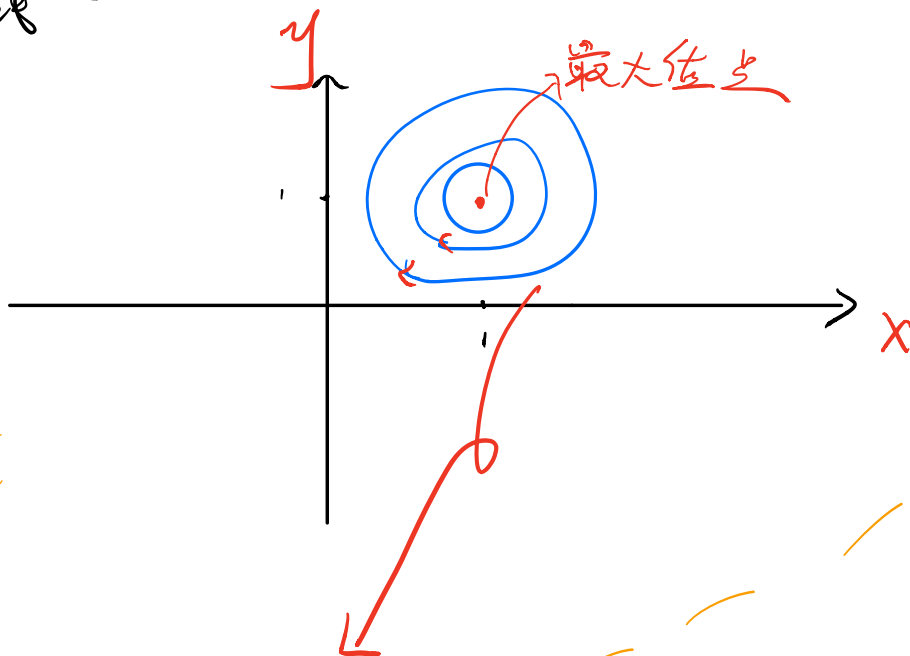
$$\Rightarrow e^y \cdot \frac{1}{y} = x \frac{1}{e^x} \cdot C_2$$

$$\Rightarrow \frac{x}{e^x} \cdot \frac{y}{e^y} = C$$

$$\Rightarrow x \cdot e^{-x} \cdot y \cdot e^{-y} = h(x, y)$$

积分曲线

↳



3. 定性行为. ☆☆☆

以恒定速率 k 捕鱼的 影响 "effect"

$$\begin{cases} x' = -ax + bxy - kx \\ y' = cy - dxy - ky \end{cases}$$

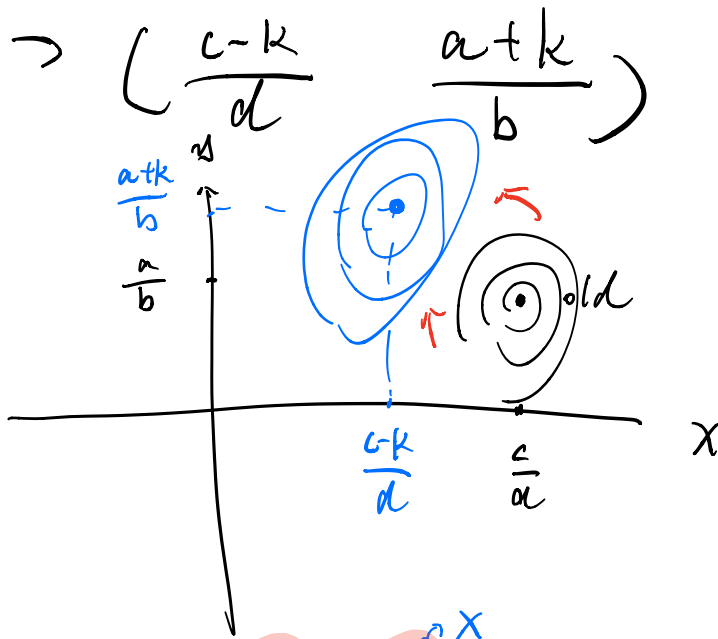
↓

$$\begin{cases} x' = -(a+k)x + bxy \\ y' = (c-k)y - dxy \end{cases}$$

old crit. point:

$$\rightarrow \left(\frac{c}{d}, \frac{a}{b} \right)$$

New ---



即: 捕魚降低了鯉魚的數量.

$x \downarrow$

增加了魚的數量.

$y \uparrow$

↓ Volterra's principle

☆! “沃尔泰拉法则”