

$$\vec{X}' = A \vec{X}$$

① 基础矩阵知识

fundamental <sup>基础矩阵</sup> mx. of  $A$

$$X = [\vec{x}_1 \ \vec{x}_2] \quad , \quad \vec{x}_1, \vec{x}_2 \text{ 线性无关.}$$

→ Basic properties. of  $X$ ,

①.  $|X| \neq 0$ , for any  $t$ .

②  $X' = AX$  : 每列均为 system 的 soln.

② 写出 system 的通解

$$\vec{x}' = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

$$\Rightarrow \vec{x} = \underbrace{X \cdot \vec{c}}_{\text{gen soln.}} = [\vec{x}_1 \ \vec{x}_2] \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

→ what do all fundamental mx. look like.

$$[X \vec{c}_1 \quad X \vec{c}_2] = X [\vec{c}_1 \ \vec{c}_2]$$

$$= X \cdot C \quad , \quad \text{most general FM. 1430.}$$

① → 进入正题:

formal

特例, 工程,  
给予明确例范围.

method

思路! 过程!

→ 1x1 case:

$$x' = ax$$

soln:  $x = C \cdot e^{at}$

如何推广到  $n \times n$ ?

"无穷级数的指数函数定义"

$$e^{at} = 1 + at + \frac{a^2 t^2}{2!} + \frac{a^3 t^3}{3!} + \dots + \dots$$

↓

$$\frac{de^{at}}{dt} = 0 + a + a^2 t + \frac{a^3 t^2}{2!} + \dots$$

$$= a \cdot e^{at}$$

② a fund  $M_x$  for  $\vec{x}' = A \vec{x}$

$$e^{At} := I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots$$

单位矩阵.

③ 证明  $e^{At}$  为 fundamental  $M_x$  of system.

① satisfy  $\vec{x}' = A \vec{x}$  , ( $\vec{x} = e^{At}$ )

$$de^{At}$$

$$\begin{aligned} \overline{dt} &= 0 + A + A^2 \cdot t + \dots \\ &= A \cdot e^{At} \quad \checkmark \text{ Yes.} \end{aligned}$$

②  $|A| \neq 0$

$$|e^{A(0)}| = 1 \neq 0$$

Ex:  $\begin{cases} x' = y \\ y' = x \end{cases} \Rightarrow \vec{x}' = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{x}, \quad A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$$\begin{aligned} e^{At} &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} t + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{t^2}{2!} + \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \frac{t^3}{3!} \\ &= \begin{bmatrix} 1 + \frac{t^2}{2!} + \frac{t^4}{4!} + \dots & t + \frac{t^3}{3!} + \dots \\ t + \frac{t^3}{3!} + \dots & 1 + \frac{t^2}{2!} + \dots \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \rightarrow e^{At} &= \begin{bmatrix} \cosh t & \sinh t \\ \sinh t & \cosh t \end{bmatrix} \\ &= \begin{bmatrix} \frac{e^t + e^{-t}}{2} & \frac{e^t - e^{-t}}{2} \\ \frac{e^t - e^{-t}}{2} & \frac{e^t + e^{-t}}{2} \end{bmatrix} \end{aligned}$$

$\rightarrow$  "init. value"  $\vec{x}' = A \vec{x}, \quad \vec{x}(0) = \vec{x}_0, \text{ find } \vec{x}(t)$

$\rightarrow$  gen soln:  $\vec{x} = e^{At} \cdot \vec{C}$

$$\Rightarrow \vec{x}(0) = e^{A \cdot 0} \cdot \vec{c}$$

$$\Rightarrow \vec{x}_0 = I_2 \vec{c}$$

~~\*\*\*~~ 证:  $\vec{x} = e^{At} \cdot \vec{x}_0$

①  $e^{A+B} \neq e^A \cdot e^B$ . True is special case.  
 "AB = BA", 很少见,  
 ✓ = 特殊情况

①.  $A = c \cdot I = \begin{pmatrix} c & 0 \\ 0 & c \end{pmatrix}$

→ ②.  $B = -A \Rightarrow e^{A-A} = e^A \cdot e^{-A}$

③.  $B = A^{-1}$

或  $I = e^A \cdot e^{-A}$

故  $(e^A)^{-1} = e^{-A}$

② 如何计算  $e^{At}$

① 无穷级数 (太麻烦)

use exp law ②.  $\begin{pmatrix} a & b \\ b & a \end{pmatrix} = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} + \begin{pmatrix} 0 & b \\ b & 0 \end{pmatrix}$

other ③.  $\underline{X} \cdot \underline{X}(0)^{-1}$  1) FM still  
 2) value at 0,  $\underline{X}(0) \underline{X}(0)^{-1} = \underline{I}$

~~☆~~ ~~☆~~  $e^{At} = \underline{X} \underline{X}(0)^{-1}$

Def.  $\underline{\bar{\Phi}}(t) = \underline{\bar{Q}}(t) \cdot \underline{\bar{Q}}(0)^{-1} \cdot \underline{\bar{Q}}(0)$   
 $\quad \quad \quad \underline{x(t)} \quad \quad \quad \underline{x_0}$

例 1,  $x' = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} x$ ,  $x(0) = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$

$$\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$e^{At} = \begin{bmatrix} e^{2t} & 0 \\ 0 & e^{2t} \end{bmatrix} + \begin{bmatrix} 0 & e^t \\ e^t & 0 \end{bmatrix}$$

$$e^{At} = e^{Bt} e^{Ct}$$

Example A:  $A = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$ ,  $e^A = \begin{pmatrix} e^a & 0 \\ 0 & e^b \end{pmatrix}$   $e^{At} = \begin{pmatrix} e^{at} & 0 \\ 0 & e^{bt} \end{pmatrix}$

Example 3B. Let  $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ , show:  $e^A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  and  $e^{At} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$ .

What's the point of the exponential matrix? The answer is given by the theorem below, which says that the exponential matrix provides a royal road to the solution of a square system with constant coefficients: no eigenvectors, no eigenvalues, you just write down the answer!

**Theorem 3** Let  $A$  be a square constant matrix. Then

- (1) (a)  $e^{At} = \tilde{\Phi}_0(t)$ , the normalized fundamental matrix at 0;
- (2) (b) the unique solution to the IVP  $\mathbf{x}' = A\mathbf{x}$ ,  $\mathbf{x}(0) = \mathbf{x}_0$  is  $\mathbf{x} = e^{At}\mathbf{x}_0$ .

Example 3C. Let  $A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$ . Solve  $\mathbf{x}' = A\mathbf{x}$ ,  $\mathbf{x}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ , using  $e^{At}$ .

**Solution.** We set  $B = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$  and  $C = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ ; then (7) is satisfied, and

$$e^{At} = \begin{pmatrix} e^{2t} & 0 \\ 0 & e^{2t} \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = e^{2t} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix},$$

by (8) and Examples 3A and 3B. Therefore, by Theorem 3 (2), we get

$$\mathbf{x} = e^{At}\mathbf{x}_0 = e^{2t} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = e^{2t} \begin{pmatrix} 1+2t \\ 2 \end{pmatrix}.$$

$$A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$e^{At} = \begin{pmatrix} e^{2t} & 0 \\ 0 & e^{2t} \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = e^{2t} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

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