

1. For a regression problem with 2 features, consider the effect of different regularizers and different amounts of regularization, graphically as described below. You may do this by hand, or you may use a computer to assist you if you prefer.

Assume the unconstrained objective function is  $f_{obj}(\underline{w}) = \frac{1}{N} \text{RSS}(\underline{w}, \mathcal{D}_i)$ . For simplicity, in this problem we assume  $w_0 = 0$ , consistent with a dataset that has been standardized in both  $x$  and  $y$ . Consider 10 different datasets  $\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_{10}$ , each resulting in an unconstrained (unregularized) minimum at  $\hat{\underline{w}}_{\text{lin}}^{(i)}$  given by:

$$\begin{aligned} \mathcal{D}_1 : \hat{\underline{w}}_{\text{lin}}^{(1)} &= (10, 0), & \mathcal{D}_2 : \hat{\underline{w}}_{\text{lin}}^{(2)} &= (10, 2), & \mathcal{D}_3 : \hat{\underline{w}}_{\text{lin}}^{(3)} &= (10, 4), \\ \mathcal{D}_4 : \hat{\underline{w}}_{\text{lin}}^{(4)} &= (10, 6), & \mathcal{D}_5 : \hat{\underline{w}}_{\text{lin}}^{(5)} &= (8, 6), & \mathcal{D}_6 : \hat{\underline{w}}_{\text{lin}}^{(6)} &= (8, 8), \\ \mathcal{D}_7 : \hat{\underline{w}}_{\text{lin}}^{(7)} &= (6, 8), & \mathcal{D}_8 : \hat{\underline{w}}_{\text{lin}}^{(8)} &= (6, 10), & \mathcal{D}_9 : \hat{\underline{w}}_{\text{lin}}^{(9)} &= (4, 10), & \mathcal{D}_{10} : \hat{\underline{w}}_{\text{lin}}^{(10)} &= (2, 10) \end{aligned}$$

Assume the shape of  $\text{RSS}(\underline{w}, \mathcal{D}_i) = \text{constant}$  curves in 2D weight space are circles (special case of ellipses), for simplicity.

In each regularizer case given below, make a plot in 2D weight space, showing:

- (i) the 10 unregularized-minimum points  $\hat{\underline{w}}_{\text{lin}}^{(i)}$  given above,
- (ii) the region that satisfies the given regularizer constraint, and
- (iii) the resulting 10 regularized minimum points, i.e., solution of

$$\hat{\underline{w}}_{\text{reg}}^{(i)} = \arg \min_{\underline{w}} f_{obj}(\underline{w}, \mathcal{D}_i) \quad \text{s.t.} \quad \Omega(\underline{w}) \leq C.$$

for each  $i$ . Also show or justify how you found the resulting  $\hat{\underline{w}}_{\text{reg}}^{(i)}$ . (Showing your method for one or two points in each regularizer case, should be sufficient.)

- (iv) Also, answer: how many of the resulting  $\hat{\underline{w}}_{\text{reg}}^{(i)}$ ,  $i = 1, 2, \dots, 10$ , are more sparse than the corresponding  $\hat{\underline{w}}_{\text{lin}}^{(i)}$ ? For the purpose of this problem, define sparsity as the number of components  $\hat{w}_j^{(i)}$  that have value 0, for a given  $i$ .

**Tip:** For cases in which there are more than one possible  $\hat{\underline{w}}_{\text{reg}}^{(i)}$  for a given dataset and a given constraint, pick any one.

- (a) L2 regularization:  $\Omega(\underline{w}) = \|\underline{w}\|_2^2$ ,  $C = 2^2$ .
- (b) L1 regularization:  $\Omega(\underline{w}) = \|\underline{w}\|_1$ ,  $C = 2$ .
- (c)  $L_p$  regularization (based on  $p$ -norm):  $\Omega(\underline{w}) = \|\underline{w}\|_p^p$ , as  $p \rightarrow \infty$ ,  $C = 1$ .

**Hint:** if you're not sure of the shape of  $\|\underline{w}\|_p^p = 1$ , try plotting it numerically for increasing  $p$ , e.g.  $p = 4, 10, 100$ .

- (d) Repeat (a), except with  $C = 5^2$ .
- (e) Repeat (b), except with  $C = 5$ .

2. Suppose you develop and optimize a machine learning system, starting with setting aside a test dataset  $\mathcal{D}_{Test}$ , and using the remaining data points as the set  $\mathcal{D}'$ . Your hypothesis set is  $\mathcal{H}_1$ , and you use  $\mathcal{D}'$  as a training set to find its best hypothesis  $h_{g1}$ . Let  $d_{VC}(\mathcal{H}_1) = d_{VC}^{(1)}$ ,  $N' = |\mathcal{D}'|$ , and  $N_{Test} = |\mathcal{D}_{Test}|$ . When you are finished, you pull out the test set and calculate  $E_{Test}(h_{g1})$ . In this problem, all generalization bounds are with tolerance  $\delta$  (with probability  $\geq 1 - \delta$ ).

- (a) Draw a flow chart (like we did in Lecture 15, p. 6, and like AML Fig. 4.11), that shows the dataset usage, hypothesis set, and procedure.
- (b) Give an inequality for the generalization bound based on the training error  $E_{\mathcal{D}'}(h_{g1})$ , and the generalization bound based on the test-set error  $E_{Test}(h_{g1})$ .

Suppose that after the above procedure, independently of the results you got above, you think of a different approach that you also want to try. So you start the process all over again, setting aside the same test set  $\mathcal{D}_{Test}$ . You define a hypothesis set  $\mathcal{H}_2$  for your model. Let  $d_{VC}(\mathcal{H}_2) = d_{VC}^{(2)}$ .

In this case, however, you also use some model selection to choose the optimum number of features in a feature selection process. So you split  $\mathcal{D}'$  into a training set  $\mathcal{D}_{Tr}$  and a validation set  $\mathcal{D}_{Val}$ , that are disjoint. You use  $\mathcal{D}_{Tr}$  to train each model (based on a given number of features  $d$ ), and use model selection to compare different values of  $d$ , with  $d = 1, 2, 3, \dots, d_{\max}$ , in which  $d_{\max}$  is the maximum number

of features you try. You choose the best number of features by comparing  $E_{Val}\left(h_{g2}^{(d)}\right)$  for each value of  $d$ . Let  $N_{Tr} = |\mathcal{D}_{Tr}|$ , and  $N_{Val} = |\mathcal{D}_{Val}|$ .

- (c) Draw a flow chart (like we did in Lecture 15, p. 6, and like AML Fig. 4.11), that shows the dataset usage, hypothesis sets, parameter values  $d$ , and procedure, for this second approach only.
- (d) Give:
  - (i) An inequality for the generalization bound based on the training-set error  $E_{Tr}\left(h_{g2}^{(d)}\right)$  for a given number of features  $d$ ;
  - (ii) An inequality for the generalization bound based on the validation-set error  $E_{Val}\left(h_{g2}^{(d^*)}\right)$  for the optimal number of features  $d^*$ ;
  - (iii) An inequality for the generalization bound based on the test-set error  $E_{\mathcal{D}_{Test}}\left(h_{g2}^{(d^*)}\right)$  for the best hypothesis  $h_{g2}^{(d^*)}$ .

Finally, you compare the best results from the 2 systems you developed, and pick the one with the lower test-set error.

- (e) Give an inequality for the generalization bound based on the test-set error  $E_{Test}\left(h_g^*\right)$  for the best hypothesis  $h_g^*$ .

**Hint:** what is the effective hypothesis set used by  $\mathcal{D}_{Test}$  to pick between the two machine-learning systems you developed?