# EE 660

# MACHINE LEARNING FROM SIGNALS: FOUNDATIONS AND METHODS

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Lecture 4

## Lecture 4 **EE 660** Sep 3, 2020

#### **Announcements**

- Class projects and quizzes
  - There will be 1 end-of-semester quiz and no midterm quiz
  - There will be 2 projects a (smaller) midterm project and a (larger) final project
  - The above were preferred by a large margin of students
- End-of-semester quiz
  - Tuesday, 11/24/2020, 5:30 7:00 PM
  - (will end earlier if the quiz is shorter than 90 min.)
  - This time has no remaining known conflicts

- If you have an unmovable conflict, please email me asap.
- Final project
  - Will be due on Thur., 12/3/2020
- First homework will be posted this Friday
- From now on, most reading assignments will be given in each homework

#### **Today's Lecture**

- Data notation
- Comment on definition of dataset D
  - ylx or y,x
- MLE Regression (part 2)
- Ridge regression

(2) 
$$\Delta = \{x_i, y_i\}_{i=1}^N$$
. Later:  $\Delta_{Tr}$  with  $N=N_{Tr}$ 

Later: 
$$D_{Tr}$$
 with  $N=N_{Tr}$  (training set)  
 $D_{Val}$  with  $N=N_{Val}$  (validation set)  
 $D_{Test}$  with  $N=N_{Test}$  (test set)

Design matrix: 
$$X = \begin{bmatrix} x_1^T \\ x_2^T \\ \vdots \\ x_N^T \end{bmatrix}$$
 Vector of  $y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$ 

$$\begin{bmatrix} x_1^T \\ abels \end{bmatrix}$$

$$\begin{bmatrix} x_1^T \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$$

$$\begin{bmatrix} x_1^T \\ x_2^T \\ \vdots \\ y_N \end{bmatrix}$$

We use  $\Delta$  for both set notation as in (2), and matrix-vector pair as in:  $\Delta = \underbrace{X}_{,y} \text{ or } \underbrace{X}_{,y}$ 

i. 
$$p(\Delta | \underline{\theta}) = p(\underline{y}, \underline{X} | \underline{\theta})$$
  
but what we often want is  $p(\underline{y} | \underline{X}, \underline{\theta})$  or  $p(\underline{X} | \underline{y}, \underline{\theta})$ .

Notes on 
$$p(\mathcal{D}|\underline{\theta}), p(\underline{y}, \underline{X}|\underline{\theta}), p(\underline{y}|\underline{X},\underline{\theta})$$

**Fall 2020** 

Using probability relations we have:

$$p(y,\underline{x}|\underline{\theta}) = p(y|\underline{x},\underline{\theta}) p(\underline{x}|\underline{\theta}) = p(y|\underline{x},\underline{\theta}) p(\underline{x})$$

where for the last step we have dropped the last condition on  $\underline{\theta}$  because it tells us nothing useful about  $p(\underline{x})$ . If we are interested in maximizing (or minimizing) the likelihood, we will take:

$$\arg \max_{\underline{\theta}} p(\mathcal{D}|\underline{\theta}) = \arg \max_{\underline{\theta}} \left\{ \prod_{i=1}^{N} p(y_{i}, \underline{x}_{i}|\underline{\theta}) \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \prod_{i=1}^{N} p(y_{i}|\underline{x}_{i}, \underline{\theta}) p(\underline{x}_{i}) \right\} = \arg \max_{\underline{\theta}} \left\{ \prod_{i=1}^{N} p(\underline{y}_{i}|\underline{x}_{i}, \underline{\theta}) \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \prod_{i=1}^{N} p(y_{i}|\underline{x}_{i}, \underline{\theta}) \right\}$$

and to obtain the last line,  $\prod_{i=1}^{N} p(\underline{x}_i)$  was dropped because it is a positive multiplicative term that

is a constant of  $\theta$ . This can equivalently be seen by using the log likelihood instead:

$$\arg \max_{\underline{\theta}} p(\mathcal{D}|\underline{\theta}) = \arg \max_{\underline{\theta}} \left\{ \ln \prod_{i=1}^{N} p(y_{i}, \underline{x}_{i}|\underline{\theta}) \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \ln \prod_{i=1}^{N} p(y_{i}|\underline{x}_{i}, \underline{\theta}) p(\underline{x}_{i}) \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \sum_{i=1}^{N} \ln \left[ p(y_{i}|\underline{x}_{i}, \underline{\theta}) p(\underline{x}_{i}) \right] \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \sum_{i=1}^{N} \left[ \ln p(y_{i}|\underline{x}_{i}, \underline{\theta}) + \ln p(\underline{x}_{i}) \right] \right\}$$

$$= \arg \max_{\underline{\theta}} \left\{ \sum_{i=1}^{N} \ln p(y_{i}|\underline{x}_{i}, \underline{\theta}) \right\}$$

and to obtain the last line, the additive terms that don't depend on  $\theta$  have been dropped.

So, when the goal of using the likelihood is to find its argmax or argmin w.r.t.  $\underline{\theta}$ , we can replace  $p(y_i,\underline{x}_i|\underline{\theta})$  directly with  $p(y_i|\underline{x}_i,\underline{\theta})$ .

2. Objective function

$$J_{1}(w, \delta) = ? = -\ln p(\delta|w) = NLL(w)$$

$$(or -p(\delta|w))$$

$$\ln p(\varpi|_{w}) = \sum_{i=1}^{N} \ln p(y_{i}|_{X_{i}}, \underline{w}_{i}) \qquad (i.d.)$$

$$= \sum_{i=1}^{N} \ln N(y_{i}|_{w}^{T}\underline{x}_{i}, \sigma^{2}) \qquad (Gaussian model)$$

Can re-write J, as: [M Eq. 7.5-7.9]

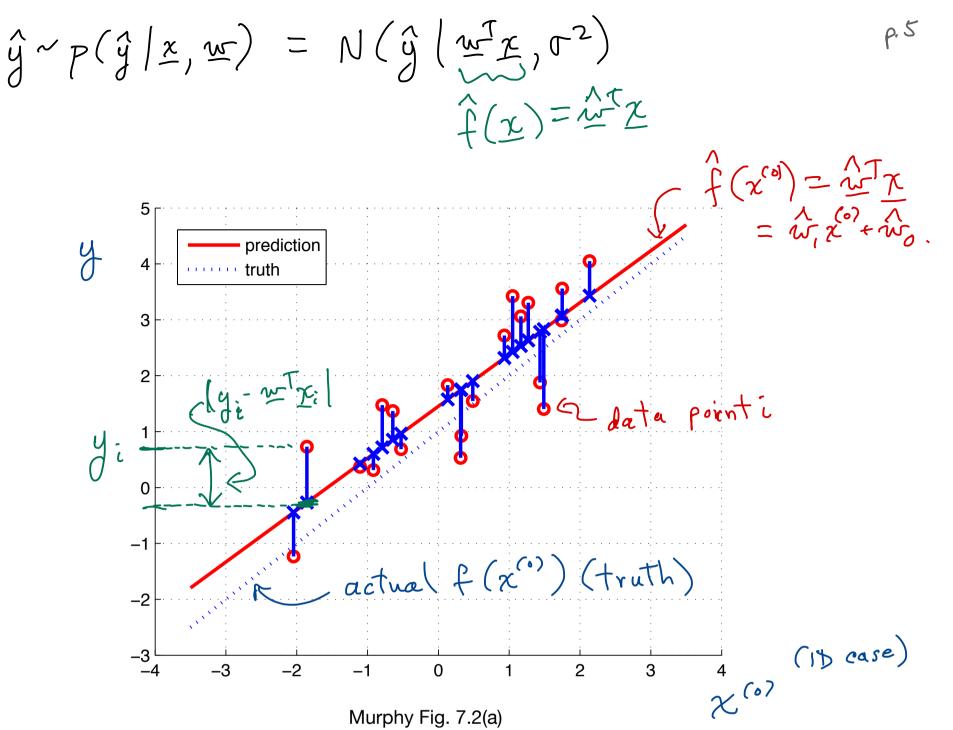
$$J_{i}(w, b) = \frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - w^{T}x_{i})^{2} + \frac{N}{2} ln(2\pi\sigma^{2})$$

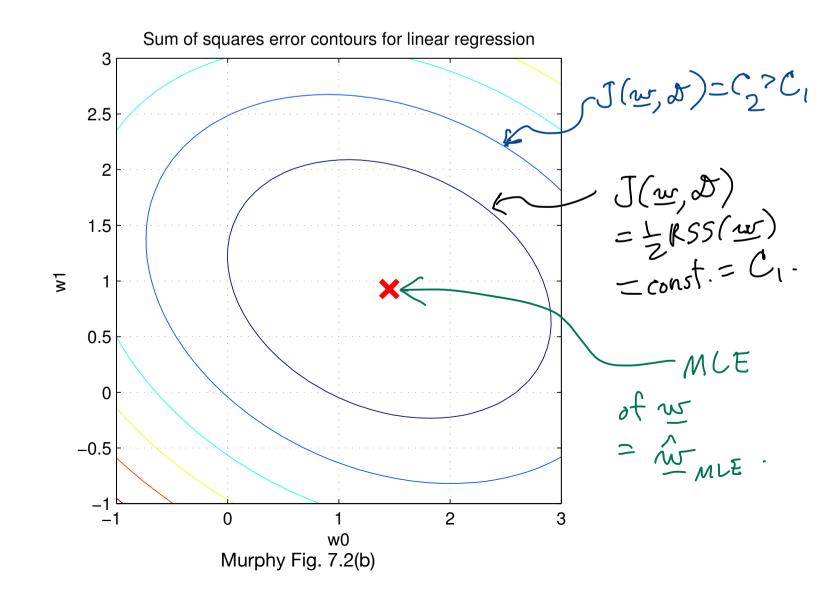
Simplify:

multiplicative constant > 0

constant of w

$$\Rightarrow \text{ Let } J(\underline{w}, \Delta) = \frac{1}{2} RSS(\underline{w}) = \frac{1}{2} \frac{N}{2} (y_i - \underline{w}^T x_i)^2 = \frac{1}{2} ||\underline{y} - \underline{X} \underline{w}||_2^2$$





# 3. Optimization method

### Which method ?

- · Gradient descent (stochastic or batch ...)
  - -> neural-network approach
    -> very large dataset
- · Solving Vw J(w, A) = 0 algebraically.

  - -> Pseudoinverse solution.
    -> Non-neural approaches
    - >> Solving gives w

$$X^TX = X^Ty$$

if (XTX) is invertable, then:

$$\hat{w}_{OLS} = \underbrace{X}_{OLS} = \underbrace{X}_{X} \underbrace{X}_{X}$$

= ordinary least squares solution. = pseudoiny. soln.

 $\frac{w}{m}$  E  $\frac{2}{m}$   $\frac{2}{m}$   $\frac{1}{m}$   $\frac{2}{m}$   $\frac{1}{m}$   $\frac{2}{m}$   $\frac{2}{m}$ 

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Ridge Regression [Murphy 7.5]
   (m = m_{(0)})
```

-> Use MAP (maximum a posteriori) estimation of w.

Which is the MAP est, of 
$$\Theta$$
?

(a)  $\hat{\theta} = \underset{\theta}{\text{argmax}} p(\hat{\sigma}|\underline{\theta})$ 

(b)  $\hat{\theta} = \underset{\theta}{\text{argmax}} p(\hat{\theta}|\underline{\theta})$ 

(b) 
$$\hat{\theta} = \underset{\hat{\theta}}{\operatorname{argmax}} p(\hat{\theta} | \hat{\theta}) \leftarrow$$

Model is same as MLE regression:

$$y \sim p(y|x, \theta)$$
  
 $= N(y|x - T^2) - Linear, Gaussian$   
 $= N(y|x - T^2) - Nonlinear, Gaussian$ 

Hypothesis set (linear, Gaussian case with  $\sigma^2$  given):  $Z = \frac{20}{2}$  set of  $Z = \frac{20}{2}$  integers  $Z = \frac{20}{2}$   $Z = \frac{20}{2}$  integers

Is It the same as for MLE regression (linear, Gaussian case, 52 given)? -> les.

What's different here? 
$$\rightarrow$$
 Objective function
$$\hat{\underline{\Theta}} = \underset{\underline{\Theta}}{\operatorname{argmax}} \quad p(\underline{\Theta} | \underline{B}) = \underset{\underline{\Theta}}{\operatorname{argmax}} \quad \frac{p(\underline{B}|\underline{\Theta})p(\underline{\Theta})}{p(\underline{B})}$$

$$= \underset{\underline{A}|_{\underline{W}}}{\operatorname{argmax}} \quad \frac{p(\underline{A}|\underline{\Theta})p(\underline{\Theta})}{p(\underline{\Theta})}$$

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$$= \underset{\underline{A}|_{\underline{W}}}{\operatorname{argmax}} \quad \frac{p(\underline{A}|\underline{\Theta})+lnp(\underline{\Theta})}{p(\underline{\Theta})}$$

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$$= \underset{\underline{A$$