EE 660

MACHINE LEARNING FROM SIGNALS: FOUNDATIONS AND METHODS

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Lecture 23

Lecture 23 EE 660 Nov 10, 2020

Announcements

- Homework 9 will be posted later this week
- End-of-semester quiz
 - Tues., 11/24/2020, 5:30-7:00 PM
 - Will be short-answer questions, taken online
 - Will be 60-90 minutes in length
 - Materials allowed to be announced

Today's topics

- Semi-supervised learning (part 3)
 - Expectation Maximization (EM)
- Unsupervised learning (USL) (part 1)
 - Introduction
 - Mixture models and EM → deferred

EM Algorithm

Initialize t=0 and $\theta^{(0)}$ Mstep E step Estimate parameters & (t+1) by: Compute best est. of Hasp(HD, O(t)) Halt when $p(D|D^{(t)})$ converges

1. Can be shown that p(D|D) increases at every iteration. 2. Converges to <u>(ocal optimum</u>. 3. Result depends on starting point θ . Common choice is: $\theta(0) = \frac{1}{2} \theta$ based on θ .

How to use it: For Estep

Let i index the data pts in Di; h index the data pts. in Du.

(3)
$$p(\mathcal{A}|\mathcal{D},\underline{\theta}) = \prod_{h=l+l} p(y_h | \underline{X}_{U}, \underline{Y}_{L}, \underline{X}_{L},\underline{\theta})$$

= TT p(yh | zh, e) (if know e), don't need other

En, \(\sum_{\cupsel, or \sum_{\cupsel}} \) to predict yn).

$$(4) P(y_h = c \mid \underline{x}_h, \underline{\theta}) = \frac{P(\underline{x}_h \mid y_h = c, \underline{\theta}) P(y_h = c \mid \underline{\theta})}{\sum_{y_v = 1}^{C} P(y_v = c \mid \underline{\theta}) P(\underline{x}_h \mid y_v, \underline{\theta})}$$

Let $f_h = p(y = c|x_h, \theta) = responsibility of y = c$ for data pt. x_h . latapt. It class index assin. = "soft label" for Ih.

p (H(D, D) gives soft labels of all un labeled data pts.

Mstep

max
$$\mathbb{E}_{\mathcal{H}}|_{\mathcal{S},\underline{B}^{(2)}} \left\{ \lim_{\rho \to 0} (\mathcal{S}, \mathcal{H} | \underline{\theta}) \right\}$$

= max $\left\{ \geq p(\mathcal{H} | \mathcal{S},\underline{\theta}^{(2)}) \ln p(\mathcal{S}, \mathcal{H} | \underline{\theta}) \right\}$
 $p(\mathcal{S}, \mathcal{H} | \underline{\theta}) = p(\mathcal{H} | \mathcal{S},\underline{\theta}) p(\mathcal{S} | \underline{\theta})$

given above $-(3),(u)$ like(inoof)

from \mathcal{E} step of all known data

$$p(\mathcal{B} | \underline{\theta}) = \prod_{i=1}^{n} p(\underline{x}_{i}, \underline{y}_{i} | \underline{\theta}) \prod_{h=l+1}^{n} p(\underline{x}_{h} | \underline{\theta})$$
 $p(\underline{x}_{i}, \underline{y}_{i} | \underline{\theta}) = p(\underline{x}_{i} | \underline{y}_{i}, \underline{\theta}) p(\underline{y}_{i} | \underline{\theta})$
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 $p(\underline{x}_{i}, \underline{y}_{i$

Comments: (EM w/ mixture dens. for SSL)

1. Works well when model is "correct. 2. Othewise might not work well.

[Fig. 3.2, 3.3 in Zhu SSL textbook]

Other topics in SSL (N.R.F.)

- cluster-then-label methods (end of Ch.3)
- Co-training (Ch-4)
 - Each instance I; has I views (feature sets): X (1), X (2)
 e.g.: words / letters in a phrase to classify: X (1)
 context (nearby words): Y
 - Use both for SSL
 - Graph-based methods
- SUM based methods
- Bounds on Eout [Intro. in Ch.8]



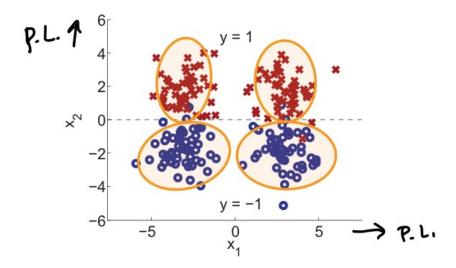


Figure 3.2: Two classes in four clusters (each a 2-dimensional Gaussian distribution).

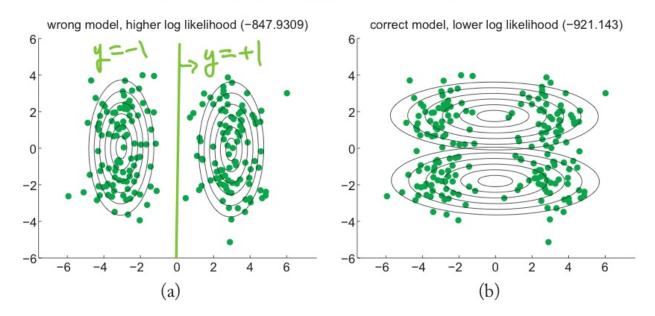


Figure 3.3: (a) Good fit under the wrong model assumption. The decision boundary is vertical, thus producing mass misclassification. (b) Worse fit under the wrong model assumption. However, the decision boundary is correct.

[From Zhu et al., Intro. to Semi-Supervised Learning.]

Unsupervised Learning (USL)

Data ets. in D have no class labels.

What can USL do for us?

- Learn structure in the data significance of clusters.
- Feature selection or feature discovery

e-g.: cluster data

find centroid of each cluster Uk

use distance d (x:, uk) to each ye as a feature value.

-> bag-of-words representation

- Adapt a classifier to changes over time by revising cluster/class boundaries as new data is observed.