## EE 660

# MACHINE LEARNING FROM SIGNALS: FOUNDATIONS AND METHODS

Prof. B. Keith Jenkins

Lecture 7

#### **Announcements**

- Homework 2 (Week 3) is due Friday 9/18.
- Starting this week, lecture topics are in the AML book.

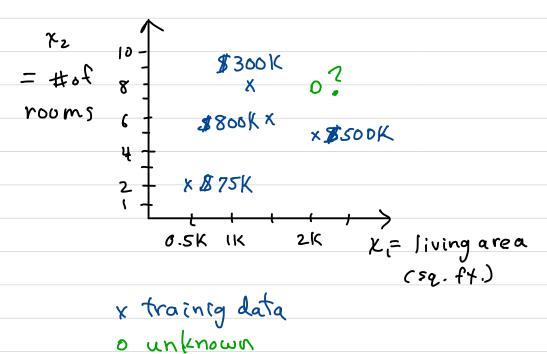
#### **Today's Lecture**

- Feasibility of learning (part 1)
  - Understanding ML and its feasibility
  - Generalization error
  - · Marbles and bins
  - Hoeffding inequality
    - Single hypothesis
    - *M* hypotheses

#### Feasibility of Learning

How or why can we expect a machine to generalize from training data of?

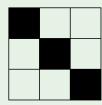
Housing price example;



#### A Learning puzzle

Training  $\begin{cases} datq \end{cases} \qquad f = -1 \end{cases} \begin{cases} class \\ y = -1 \end{cases}$   $f = +1 \end{cases} \begin{cases} class \\ y = +1 \end{cases}$ 

Unknown



$$f = ?$$

## What can make machine learning feasible?

Apparently the following can help:

- Assumptions
- Prior knowledge
- Appropriate hypothesis set (model)
- Enough data
- Appropriate features

Suggestions:

- Models

~ Larger N

For classification problems, let:

$$E_{\infty}(h) = \frac{1}{N} \sum_{n=1}^{N} \left[ h(x_n) \neq f(x_n) \right]$$

hypothesis prediction true target function

$$h(\Sigma_n) = \hat{f}(\Sigma_n) \text{ or } \hat{g}(\Sigma_n)$$
  $f(\Sigma_n) = y_n$ 

... Ex (h) = 70 of points in & that are misclassified by h.

Docan be DTr. Dva(, or DTe3 then N = NTr.) Nva(, NTe.

Let Eat (h) = out-of-sample error (probability of error over all x)

$$E_{out}(h) = P[h(x) \neq f(x)]$$
 (for classification problems)

We can measure Ep; we want to know Eout

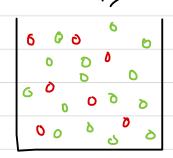
Fundamenta\
issue in ML

### Marbles and bins, mand v

We want to compare Ep (h) with Eat (h), when Ept (h) is unknown.

Measure Ex (h) from D:

La sample of data points drawn from input space X according to  $p(\underline{x})$ .



of then 
$$l-\mu = P(qreen)$$
 $\mu$  is deterministic but unknown to us.

How can we find or estimate m?

Draw N marbles independently (with replacement) z;, i=1,2, ..., N.

Estimate  $\hat{\mu} = \frac{\text{#red marbles}}{N} \stackrel{\triangle}{=} \nu$ 

How accurate is our estimate?

Hoeffding Inequality
$$P[|\nu-\mu|>\epsilon] \leq 2e^{-2\epsilon^{2}N} \quad \text{for any } \epsilon>0$$
our tolerance
$$\text{(sample size, #of marbles drawn)}$$

Note dependence of R.H.S. on E, N.

2-class classification problem

Hypothesis:  $h(\underline{x}) = [\widetilde{w}^T \underline{x} \ge 0]$ ,  $\widetilde{w}$  is given

Target fcn. is f(x) (true class label)

- 1. Pick a data point from X according to  $p(x) \rightarrow xi$ .
  - If  $h(x_i) = f(x_i)$ , then  $x_i$  is classified correctly by h
  - If  $h(x_i) \neq f(x_i)$ , then  $x_i$  is misclassied by h
- 2. Pick N data points, i.i.d. from X => dataset & (sample)

We can calculate Eg (h)

We want to know or bound E out (h)

1. Draw a marble from the bin

Marble is colored green (probability I-u)

Marble is colored red (probability M)

2. Draw N marbles from bin, with replacement

= v = 70 of drawn marbles that are red

 $= \mu = P[marble is red]$ 

=> Use Hoeffding Inequality

## Feasibility of Learning and Hoeffding Inequality (1) $P[|E_D(h)-E_{out}(h)|>\epsilon] \leq 2e^{-2\epsilon^2N}$ for any e > 0Note: D'must be drawn at random, i.i.d., according to p(x). Procedure for Hoeffding Inequality to be valid: 1. Specify h (determines color of marbles) 2. Draw & (draw N marbles from bin) 3. Calculate Ep(h); get bound on Eq (h) using (1). ML paradigm: L. Collect dataset D (and clean the data) 2. Construct hypothesis set 24. [ 3. Train to find hy (best hypothesis from 21) 4. Calculate ETr (hg) or ETest (hg) 5. Want to know E out (hg).

- Order is different,

-) Presolve by applying Hoeffding Ineq. before choosing hm. (one hypothesis) AML shows that:

$$P[|E_{so}(h_{g})-E_{out}(h_{g})|>\epsilon] \leq P[\bigcup_{m=1}^{M}(|E_{so}(h_{m})-E_{out}(h_{m})>\epsilon)]$$

$$\leq P[|E_{so}(h_{m})-E_{out}(h_{m})|>\epsilon]$$

$$\leq P[|E_{so}(h_{m})-E_{out}(h_{m})|>\epsilon]$$

So:

(2) 
$$P[IE_{so}(h_g) - E_{out}(h_g)] > \epsilon] \leq 2Me^{-2\epsilon^2N}$$
  
 $M = |\mathcal{H}| = \#of hypotheses in \mathcal{H}$ 

2 A loose bound. (but sometimes useful).

-) We will get a tighter bound later.