

Basics of Machine Learning

SD 210 - P3

Lecture 5 - Ensemble methods: bagging and random forests

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Ensemble methods for classification and regression

1. Remark:
 - Machine Learning not so "automatic": too many hyperparameters to tune
2. **meta-learning**: a procedure that learns to learn
3. **committee learning** or **wisdom of the crowd**: better results are obtained by combining the predictions of a set of **diverse** classifiers/regressors have a try in challenge
4. **ensemble learning**: Improve upon a single base predictive model by building an ensemble of predictive model (with no hyperparameter)

Ensemble methods for regression

Let $f_t, t = 1, \dots, T$ be T different regressors.

Notations:

$$\begin{aligned}\epsilon_t(x) &= y - f_t(x) \\ MSE(f_t) &= \mathbb{E}[\epsilon_t(x)^2] \\ f_{ens}(x) &= \frac{1}{T} \sum_t f_t(x) \\ &= y - \frac{1}{T} \sum_t \epsilon_t(x).\end{aligned}$$

Encourage the diversity of base models

$$MSE(f_{ens}) = \mathbb{E}[(y - f_{ens}(x))^2]$$

If ϵ_t are mutually independent with zero mean, then we have:

$$MSE(f_{ens}) = \frac{1}{T^2} \mathbb{E}[\sum_t \epsilon_t(x)^2]$$

The more diverse are the models, the more we reduce the mean square error !

Ensemble methods for supervised classification

Binary classification

$$h_{ens}(x) = \text{sign}\left(\sum_t h_t(x)\right)$$

Multiclass classification

$$h_{ens}(x) = \arg \max_c \text{vote}(c, h_1, \dots, h_T)$$

with : $\text{vote}(c, h_1, \dots, h_T) = \sum_t 1_{h_t(x)=c}(h_t(x))$

- **Encourage the diversity of base models by:**
 - using **bootstrap samples** (Bagging and Random forests)
 - using randomized models (ex: Random forests)
 - using weighted version of the current sample (**Boosting**) with weights dependent on the previous model (adaptive sampling) **we'll see that in next module SD207**

Ensemble methods at a glance

- 1995: Boosting, Freund and Schapire
- 1996: Bagging, Breiman
- 2001: Random forests, Breiman
- 2006: Extra-trees, Geurts, Ernst, Wehenkel

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Reminder: Decomposition bias/variance in regression

Given x ,

$$\mathbb{E}_S \mathbb{E}_{Y|x} (Y - f_S(x))^2 = \text{noise}(x) + \text{bias}^2(x) + \text{variance}(x) \quad (1)$$

noise(x): $\mathbb{E}_{Y|x} [(Y - \mathbb{E}_{Y|x}(Y))^2]$:

quantifies the error made by the Bayes model ($\mathbb{E}_{Y|x}(y)$)

$$\text{bias}^2(x) = (\mathbb{E}_{Y|x}(Y) - \mathbb{E}_S[f_S(x)])^2$$

measures the difference between minimal error (Bayes error) and the average model

$$\text{variance}(x) = \mathbb{E}_S [(f_S(x) - \mathbb{E}_S[f_S(x)])^2]$$

measures how much $h_S(x)$ varies from one training set to another

Introduction to bagging (regression) - 1

Assume we can generate several training independent samples $\mathcal{S}_1, \dots, \mathcal{S}_T$ from $P(x, y)$.

A first algorithm:

- draw T training independent samples $\{\mathcal{S}_1, \dots, \mathcal{S}_T\}$
- learn a model $f_t \in \mathcal{F}$ from each training sample \mathcal{S}_t ; $t = 1, \dots, T$
- compute the average model : $f_{ens}(x) = \frac{1}{T} \sum_{t=1}^T f_t(x)$

Introduction to bagging - 2

The bias ($E_{S_1, \dots, S_T}[f_{ens}(x)] - f_{target}(x)$) remains the same because :

$$E_{S_1, \dots, S_T}[f_{ens}(x)] = \frac{1}{T} \sum_t E_{S_t}[f_t(x)] = E_S[f_S(x)]$$

But the variance is divided by T:

$$E_{S_1, \dots, S_T}[(f_{ens}(x) - E_{S_1, \dots, S_T}[f_{ens}(x)])^2] = \frac{1}{T} E_S[(f_S(x) - E_S[f_S(x)])^2]$$

When is it useful? When the learning algorithm is unstable, producing high variance estimators such as trees !

Bagging (Breiman 1996)

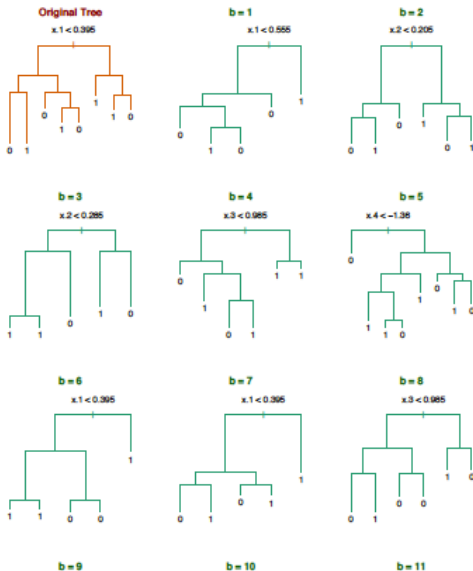
In practice, we do not know $P(X,Y)$ and we have only **one training sample** \mathcal{S} : we are going to use Bootstrap samples !

Bagging = Bootstrap Aggregating

- draw T bootstrap samples $\{1, \dots, T\}$ from \mathcal{S} (bootstrap: uniform sampling with replacement)
- Learn a model f_t for each t
- Build the average model: $f_{bag}(x) = \frac{1}{T} \sum_t f_t(x)$

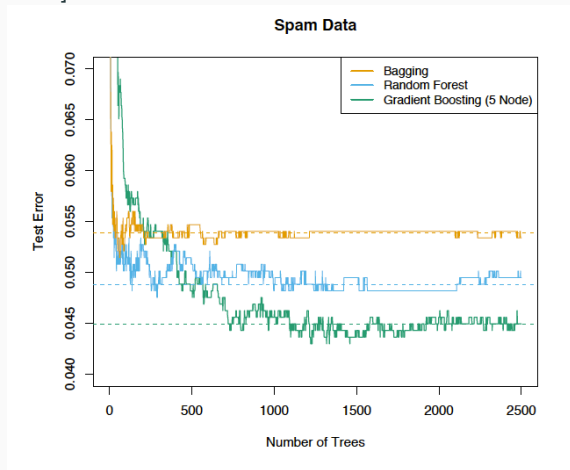
Example of bagged trees

[Book: The elements of statistical learning, Hastie, Tibshirani, Friedman,



Example of bagged trees

[Book: The elements of statistical learning, Hastie, Tibshirani, Friedman, 2001]



Bagging in practise

- Variance is reduced but the bias can increase a bit (the effective size of a bootstrap sample is 30% smaller than the original training set \mathcal{S})
- The obtained model is however more complex than a single model
- Bagging works for unstable predictors (neural nets, trees)
- In supervised classification, bagging a good classifier usually makes it better but bagging a bad classifier can make it worse

Motivation

Bagging

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References

Produce more diversity by building "more" de-correlated trees

- Perturbe and combine algorithms
 - Perturbe the base predictive model by bagging and variable randomization
 - Combine the perturbed predictive model

REFS: Random forests: Breiman 2001

Geurts, Ernst, Wehenkel, Extra-trees, 2006

Random forests algorithm

- INPUT: $F = p$ candidate feature splits, \mathcal{S}_{train}
- for $t=1$ to T
 - $\mathcal{S}_{train}^{(t)}$ m instance randomly drawn with replacement from \mathcal{S}_{train}
 - $h_{tree}^{(t)} \leftarrow$ randomized decision tree learned from $\mathcal{S}_{train}^{(t)}$
- OUTPUT: $H^T = \frac{1}{T} \sum_t h_{tree}^{(t)}$

Learning a single randomized tree

- To select a split at a node:
 - $R_f(F) \leftarrow$ randomly select (without replacement) f feature splits from F with $f \ll p$
 - Choose the best split in $R_f(F)$ (consider the different cut-points)
- Do not prune this tree
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Extra-trees

- INPUT: candidate feature splits $F = \{1, \dots, p\}, S_{train}$
- for $t=1$ to T
 - Always use S_{train}
 - $h_{tree}^{(t)} \rightarrow$: randomized decision tree learned from S_{train}
- OUTPUT: $H^T = \frac{1}{T} h_{tree}^{(t)}$

Learning a single randomized tree in extra-trees

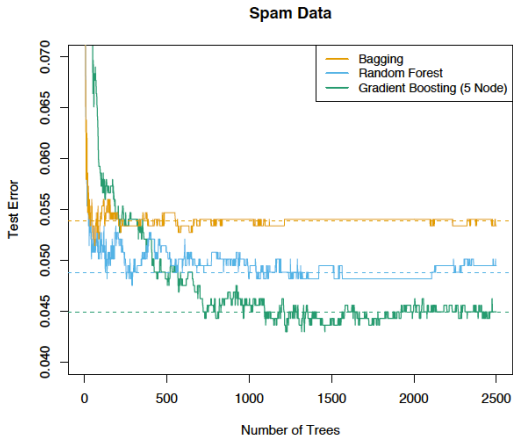
- To select a split at a node:
 - randomly select (without replacement) K feature splits from F with $K \ll |F|$
 - Draw K splits using the procedure $\text{Pick-a-random-split}(\mathcal{S}, i)$:
 - let a_{max}^i and a_{min}^i denote the maximal and minimal value of x_i in \mathcal{S}
 - Draw uniformly a cut-point a_c in $[a_{max}^i, a_{min}^i]$
 - Choose the best split among the K previous splits

Do not prune this tree

- Extra-trees faster (do not need to build bootstrap samples + shorter split selection procedure)
- Recent consistency results: for random forests (Scortnet et al. 2016)

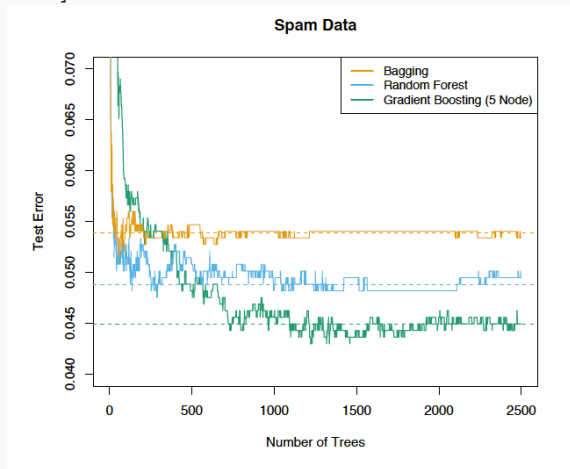
Random forest

Example of decision frontier:



Comparison (just an example)

[Book: The elements of statistical learning, Hastie, Tibshirani, Friedman, 2001]



Pros

- Fast, parallelizable and appropriate for a large number of features
- Relatively easy to tune
- Frequently the winner in challenges

Cons

- Overfitting if the size of the trees is too large
- Interpretability is lost (however importance of feature can be measured)

Definition

A variable X^j is important to predict Y if breaking the link between X^j and Y increase the prediction error

$\{\bar{\mathcal{S}}_n^t = \mathcal{S}_n - \mathcal{S}_n^t, t = 1, \dots, n_{tree}\}$ **out-of-bag samples**: contains the samples not selected by bootstrap

Variable importance

一种测试importance的方法

Let $\{\bar{S}_n^t = S_n - S_n^t, t = 1, \dots, n_{tree}\}$ **out-of-bag samples**

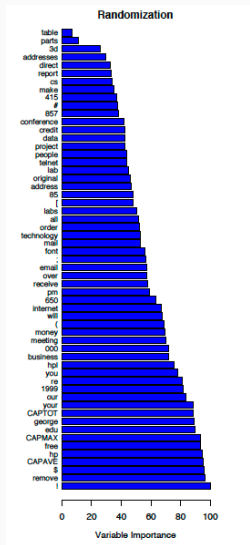
Let $\{\bar{S}_n^{t,j}, t = 1, \dots, n_{tree}\}$: permuted out-of-bag-samples (the values of the j th variable have been randomly permuted).

$$\hat{l}(X^j) = \frac{1}{n_{tree}} \sum_{t=1}^{n_{tree}} R_n(f_t, \bar{S}_n^{t,j}) - R_n(f_t, \bar{S}_n^t)$$

with $R_n(f, S)$: empirical loss of h measured on S

Variable importance: spam data

Spam dataset :



Outline

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References

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